

Can Computer Vision Help Relativistic Physics? ML-JET dataset for relativistic heavy ion collisions

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Abstract

Understanding relativistic heavy ion collision is important to study universe evolution. Traditional methods to simulate the collision reliant on Bayesian analysis which is costly and non-scalable, and deep learning has the potential to overcome it. We present a benchmark on relativistic heavy ion collisions, which simulates the relativistic heavy ion collision for about 3700 hours on a combination of GPUs and CPUs to compute many events, producing a total of 10.8 million jet event images for benchmarking relativistic heavy ion collisions. We release it to the vision community to push forward. Our dataset converts complex physics simulations into physics images, which can be compatible with standard vision classifiers. Using the standard Convolutional Neural Networks (CNN), our initial results attain a 92% accuracy in energy loss module classification, while concurrently accelerating the simulation process by an order of magnitude and saving millions of CPU/GPU hours. Our results suggest the potential of applying computer vision algorithms to physics in particle collisions discovery and beyond.

1. Introduction

In the realm of high-energy heavy-ion collisions, our research addresses a crucial need — to unravel the intricacies of the quark-gluon plasma and, specifically, to decode the elusive energy loss module within jet events. This pursuit isn't driven by mere curiosity but by the profound importance of advancing our comprehension of fundamental physics.

In the realm of relativistic heavy-ion collisions, researchers aim to investigate the Quark-Gluon Plasma (QGP) by studying jets. This pursuit involves extracting various parameters, transitioning from the abstract concept of QGP to a tangible exploration. Physicists navigate uncertainties by making assumptions about different stages, blending well-understood aspects with ambiguous segments as

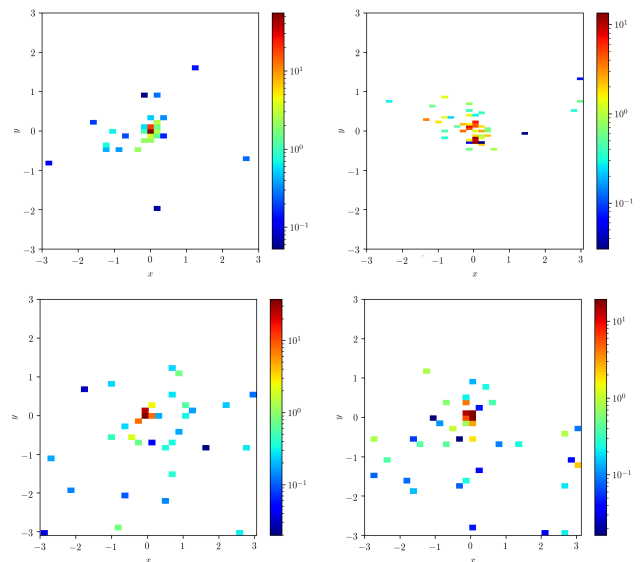


Figure 1. Representative example of Pb-Pb collision events with $Q_0 = 1.5$ and $\alpha_s = 0.2$ that show the scattering and energy of the subatomic particles, depicted as a 2D histogram. Top two figures are Matter events; bottom two figures are MATTER-LBT events. We will show how to predict the energy loss module, which is crucial for particle physics, from those events images.

signed specific parameters. The ultimate goal is to precisely extract these parameters, navigating the blurred boundaries between the known and unknown in the quest to unravel the mysteries of relativistic heavy-ion collisions. Figure 2 illustrates collisions evolution in one glance.

Addressing the challenges of high-energy collisions and quark-gluon plasma intricacies [18, 28], our project takes a departure from conventional Bayesian analysis approach. Unlike the iterative simulation approach of Bayesian analysis [8], our focus is on pioneering computer vision and pattern recognition methods. Despite the success of Bayesian [12–14, 19, 36, 37], our central inquiry revolves around efficiency – can computer vision expedite the process? This

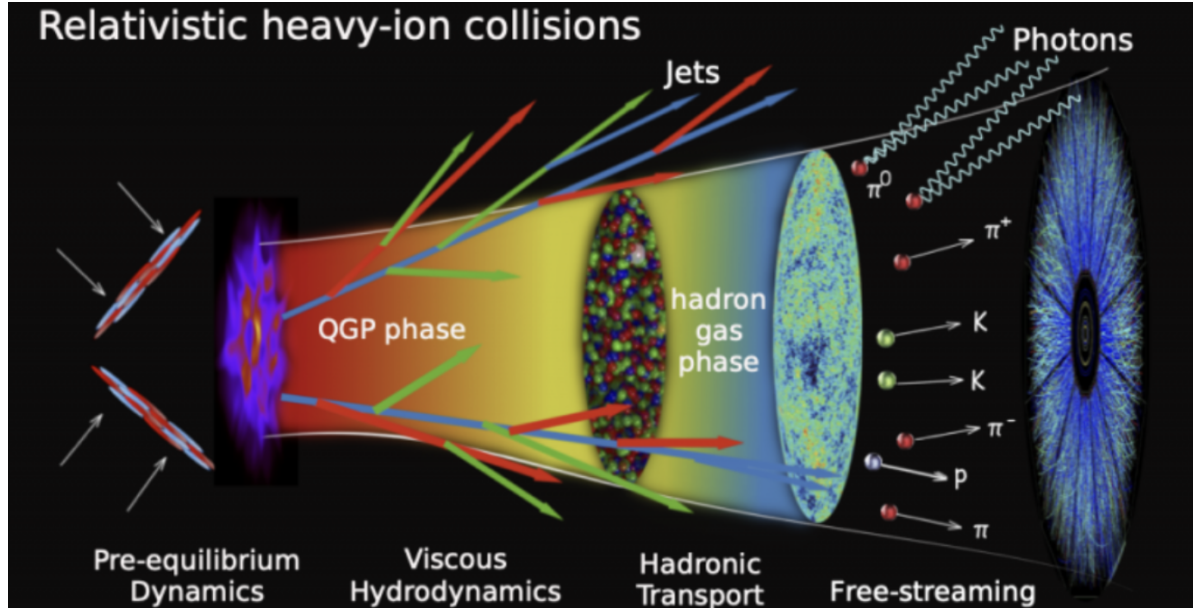


Figure 2. Relativistic heavy-ion collisions, credit to Chun Shen et. al. from JETSCAPE collaboration.

049 leads to our defined problem: using pattern recognition, can
050 a ML model discern jet parameters from a set of event images?
051 The necessity for a set of events arises due to the
052 inadequacy of information in a single event image for com-
053 prehensive parameter analysis.

054 Our innovative approach centers around the ML-JET
055 dataset, a colossal compilation of 10.8 million images ex-
056 clusively designed for deep learning. Each image encapsu-
057 lates crucial information, depicting three parameters: en-
058 ergy loss module, virtuality separation scale (Q_0), and
059 strong coupling constant (α_s). Figure 1 illustrates for sam-
060 ple event collisions. The dataset’s creation required an ex-
061 tensive 3700 hours of computational effort, utilizing signif-
062 icant resources — 512 GB of memory and up to 16 CPU
063 cores. Notably, our emphasis on energy loss module binary
064 classification, akin to cat vs. dog classification, is crucial.
065 This task, determining MATTER or LBT categorization,
066 which lie at the extremes of the energy loss values, offers
067 insights into predicting nuanced parameters. This classi-
068 fication initiative, our inaugural feasibility study, acts as a
069 proof of concept for broader predictive endeavors in our re-
070 search.

071 Utilizing state-of-art deep learning techniques, notably
072 the VGG16 and PointNet model, we achieve unprecedented
073 precision in classifying and analyzing energy loss modules.
074 Rooted in a comprehensive dataset, this approach not only
075 expands our understanding of high-energy heavy-ion colli-
076 sions and the mysterious quark-gluon plasma but also rep-
077 resents the first in-depth examination of jet evolution within
078 a medium. The groundbreaking result stems from the inter-
079 section of the ML-JET dataset and cutting-edge deep learn-

ing techniques, advancing our knowledge and establishing
a solid foundation for a nuanced grasp of energy loss mod-
ules. Our work, with its exceptional precision, addresses
gaps in prior methodologies, signifying a substantial ad-
vance in the study of high-energy collisions. The trained
classifier demonstrated remarkable efficacy, boasting a 92%
accuracy — an impressive feat compared to the conven-
tional Bayesian analysis, which is both computationally and
time-consuming, lacking simultaneous consideration of all
jet shower data. We will release our data, model, and code.

2. Related Work

Analyzing heavy ion collisions presents distinctive chal-
lenges, with datasets reaching gigabytes or terabytes for
a limited number of design points. Unlike conventional
datasets, each heavy ion collision dataset is specific to its
task, creating varied samples based on governing param-
eters. Recent research in heavy ion collisions has addressed
known issues by providing standardized datasets. While
AI has been employed for jet and hydro studies, there’s a
notable gap in energy loss module binary classification re-
search. Prior work focused on vacuum jets, neglecting those
traversing a medium. Our research pioneers machine learn-
ing applications in examining jets within a medium, mark-
ing a significant and novel contribution to the field. [12–
14, 19, 36, 37]. [9] focuses on hadron showers using ML
and is specialized for specific types of hadron showers. Of
these, the excellent work of [11] is most closely related, but
with only four physical systems, it still lacks sufficient scale
and diversity of data to challenge emerging ML algorithms.

By offering a wider, more varied problem selection and scale than these prior initiatives (18 design points with various parametrizations leading to 9 datasets), we increase the number of benchmarks available in this field. For these design aspects, we also take into account the energy loss module classification problem [7, 27] with the intention of employing ML to find latent factors that are not observable. Despite growing in prominence throughout the community, this has not yet been addressed.

One may find a summary and taxonomy of developments in heavy ion collisions in [18, 28]. Given data produced by the JETSCAPE framework [28], which itself tries to directly incorporate the tuning of parameters by Bayesian analysis, we concentrate on applying CNN models to approximate the outputs of the ground truth for creating our baselines. A range of techniques to deal with heavy ion collisions is discussed in [11, 27]. Methods include Bayesian analysis [8], principle component analysis [21], and CNN [11]. Each of these methods makes use of various presumptions, applicability domains, and data processing needs. The JETSCAPE framework is basically designed to try/understand jets moving through the medium, i.e., the Quark Gluon Plasma (QGP). Jets are localized regions of high energy traveling through the QGP. [28]

Bayesian Analysis: Although computationally expensive, Bayesian analysis is a relatively efficient means of extracting parameter values so the simulation results approximate experimental data. That’s how physicists convert the problem from an abstract model to something more concrete. To make this computationally feasible, the analysis requires some assumptions about different stages/phases and considers only a subset of the available data. Some parameter values are better determined than others, and most parameter values are not independent of each other, so Bayesian analysis is used to tune the system by finding suitable parameter values. [12, 14, 19]

The Bayesian analysis research field operates by systematically varying parameters in simulations and comparing the results with real data to isolate specific parameter values. Utilizing maximum a posteriori probability (MAP), Bayesian analysis seeks the parameter space’s maximum probability, reporting this as its parameter predictions. Unlike our current approach, which can determine one specific parameter at a time, Bayesian analysis aims to concurrently determine all parameter values, and its predictions depend on the interrelation of all values. [13, 36, 37]

What we are doing in the big picture and the whole idea of our research is to find a different path to determine those parameters with computer vision/pattern recognition perspective as an alternate method to Bayesian analysis.

Physicists have achieved success in utilizing Bayesian analysis to ascertain parameter values. The inquiry arises: can we enhance efficiency and speed through a computer

Table 1. Design point parameters leading to nine configurations that comprise the dataset

Config.	Matter Matter-LBT		α_s	# events (in Millions)
	Q_0	Q_0		
1	1	1.5	0.2	1.2
2	1	1.5	0.3	1.2
3	1	1.5	0.4	1.2
4	1	2	0.2	1.2
5	1	2	0.3	1.2
6	1	2	0.4	1.2
7	1	2.5	0.2	1.2
8	1	2.5	0.3	1.2
9	1	2.5	0.4	1.2
				Total = 10.8

vision approach using pattern recognition techniques? This frames the problem as follows: can a pattern recognition routine, when presented with a set of jet experimental events as images, discern the associated jet parameters? The necessity for a set of events arises from the inadequacy of information in a single event image to determine parameter values; hence, a collection of events becomes essential. In this study, as a feasibility study, we started with something simple instead of going to the last version of the problem. We started by simulating many events with some discrete values of parameters, which are determining values from the physics point of view. We then tried to see if we could train a machine to just look at the output data (event images) and recognize the original event parameters e.g., energy loss module on the predefined discrete values.

As another aspect of the big picture of the study, with Bayesian analysis, one can define parameter values and ask for a random event generator to produce events. An advantage that the machine learning-based approach would have is that it can produce these events faster, the latter methods are not highly computational/time-consuming. At the moment, with the current computational power, jet event generators e.g., JETSCAPE, take 15 minutes to generate one event, therefore it is worthwhile to explore other solutions [12, 28]. But before attempting an alternate model for jet generator, we need to make sure that we can predict the values of the parameters with pattern recognition techniques. If the outcome shows its prediction matches with real experimental data and the physics behind it with a reasonable level of uncertainty, it’s proof we are on the right path toward event generators powered by AI.

We should mention that this study is just the beginning of a vast research that combines relativistic heavy ion energy physics with the pattern recognition field, and we just tried

196 to scratch the surface. On the other hand, the Bayesian anal-
197 ysis approach has been a dominant approach in this field
198 for a decade and has been well-studied already. We ex-
199 pect that by taking such a different approach and applying
200 all the cutting-edge techniques in pattern recognition now
201 available, we can develop an alternate/faster solution for the
202 problem.

203 2.1. JETSCAPE

204 High-energy nuclear physics, specifically the study of
205 Quark Gluon Plasma (QGP), underwent a significant shift
206 with the introduction of heavy ion collisions at the Large
207 Hadron Collider (LHC) [2, 3, 5, 6], marking the onset of
208 systematic inquiry.

209 To cover the wide energy range from 100 GeV at the Rel-
210 ativistic Heavy Ion Collider (RHIC) to several TeV at the
211 LHC, only moderate enhancements were necessary com-
212 pared to existing relativistic fluid dynamical simulations of
213 QGP evolution developed over a decade before the LHC
214 program [15, 22, 35]. However, it became evident that an
215 event-by-event approach was essential to compare theoret-
216 ical predictions with experimental results due to the incorpo-
217 ration of various new physics components, including fluc-
218 tuating initial states, pre-equilibrium phases, and hadronic
219 afterburners, as depicted in Figure 5. This necessitated a
220 sophisticated statistical framework to identify or accurately
221 estimate numerous unknown parameters (approximately 15
222 for a 3+1D simulation with bulk and shear viscosity), de-
223 manding a more comprehensive simulator than previous it-
224 erations [26].

225 A shift in approach occurred concerning how various
226 emissions are treated in different systems and how the
227 medium affects jet quenching calculations. The Gyulassy-
228 Levai-Vitev (GLV) and higher-twist methods were devised
229 for situations with higher virtuality, where medium scat-
230 tering corrected the vacuum shower, leading to a medium
231 modified DGLAP evolution for the leading hadron’s frag-
232 mentation function [17, 23, 40]. MATTER, a vacuum-like
233 shower generator, emerged from this approach [25]. In con-
234 trast, the Baier-Dokshitzer-Mueller-Peigne-Schif (BDMPS)
235 and Arnold-Moore-Yaffe (AMY) formalisms employ a dif-
236 ferent emission strategy.

237 Methods like BDMPS and AMY were designed for jets
238 with virtuality comparable to that from multiple scatter-
239 ing in the medium, using Poisson emission probability or
240 rate equation to simulate uncommon gluon releases [16, 30,
241 31, 38]. Approaches like Linearized Boltzmann transport
242 (LBT)-based simulators and Q-PYTHIA incorporate mixed
243 Monte Carlo methods at the event generator level [4, 33,
244 41]. JEWEL utilizes bottom-up approaches for energy loss
245 simulation [44, 45].

246 Jet Energyloss Tomography with a Statistically
247 and Computationally Advanced Program Envelope

(JETSCAPE) software offers a modular architecture 248
for event generation, advanced modules for simulating 249
heavy ion collisions, and Bayesian statistical routines for 250
calibration and comparison with experimental data.

Algorithm 1 ML-JET Dataset Builder Algorithm

- 1: Simulate nine configurations, each resulting in two final
state hadron files containing 600K jet events.
 - 2: Define jet observables: p_T, ϕ, η .
 - 3: Define cone with radius $R = \pi$.
 - 4: **for** each event **do**
 - 5: Select particles satisfying $|\phi| < R$ and $|\eta| < R$.
 - 6: Split events into 2D array.
 - 7: Create 2D histogram with 32 bins.
 - 8: Split plane $-\pi$ to π for $|\phi|$ and $|\eta|$ into 32×32 mesh.
 - 9: Calculate sum of transverse momentum in each cell,
 $P_T = \sum_{\phi_i, \eta_i} p_{t_i}$.
 - 10: **end for**
 - 11: Assign energy loss module, Q_0 , and α_s value as labels.
 - 12: Divide labeled events into 90% train and 10% test data.
 - 13: Shuffle train set for better training performance.
 - 14: Package train and test sets into nine separate datasets.
-

251

3. ML-JET: A benchmark for relativistic heavy 252 ion collisions 253

254 The benchmark’s general learning problem is discussed in
255 the sections that follow, along with its currently covered de-
256 sign points, implemented baselines (all created using Ten-
257 sorflow [1]), and compliance with FAIR data standards [42].
258

3.1. Energy Loss in JETSCAPE 259

260 Initial parton virtuality is limited by a preset distribution
261 and fed into the MATTER event generator. A hard parton
262 with light-cone momentum $p^+ = (p^0 + \hat{n} \cdot \vec{p}/\sqrt{2})$ starts
263 a virtuality-ordered shower at point r . Virtuality ($t = Q^2$)
264 is determined using a Sudakov form factor, where α_s de-
265 notes the strong coupling constant, influencing parton scat-
266 tering rates. The transport coefficient \hat{q} , evaluated at the
267 scattering location, influences the splitting time of partons.
268 Splitting functions and invariant mass differences are used
269 to estimate daughter pair transverse momenta until parton
270 Q^2 reaches Q_0^2 .

271 Below Q_0^2 , alternative energy loss modules like LBT
272 may characterize the jet. Q_0 serves as the virtuality sep-
273 aration scale. The medium-induced gluon spectrum Γ^{inel}
274 is calculated using the differential spectrum of radiated glu-
275 ons from higher-twist energy loss formalism. Monte Carlo

Table 2. MNIST model accuracy & loss diagrams.

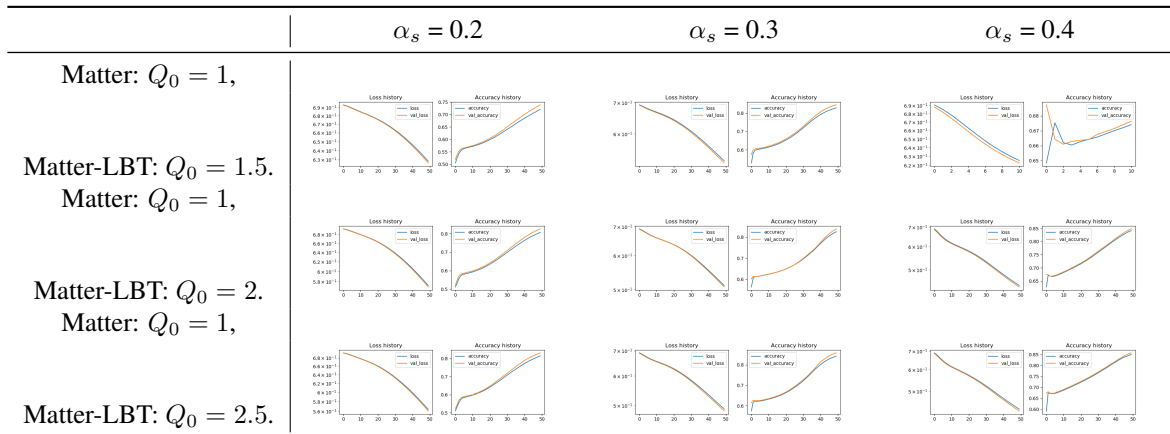


Table 3. MNIST model evaluation: accuracy

	Accuracy (%)		
	Train	Validation	Test
Config No. 1	74.12	73.87	79.58
Config No. 2	84.46	84.51	85.88
Config No. 3	68.59	68.73	68.71
Config No. 4	82.77	82.61	82.61
Config No. 5	84.04	83.93	83.95
Config No. 6	84.77	84.78	84.80
Config No. 7	83.36	83.11	83.16
Config No. 8	85.85	85.88	85.81
Config No. 9	85.64	85.68	85.61

276 methods determine scattering rates within a time step. This
 277 work focuses on developing a machine learning model to
 278 predict energy loss models for different Q_0 and α_s values.
 279 We explained the energy loss and its relation with α_s
 280 and Q_0 with more quantum physics formalism details in
 281 Appendix 9

282 4. Data collection and pre-processing

283 The ML-JET dataset comprises 10.8 million 32×32 resolu-
 284 tion images, each labeled with MATTER or MATTER-LBT
 285 associated with JET energy loss. These images are gener-
 286 ated from simulations within the JETSCAPE framework.

287 To construct the dataset, jet events are generated using
 288 preset parameters in the JETSCAPE framework. Each event
 289 is pre-processed by aggregating data, clipping outliers, re-
 290 sizing to a standard size, converting to a 2-dimensional his-
 291 togram, and normalizing pixel values. Data augmentation
 292 techniques like rotation, flipping, and cropping were unnec-
 293 essary due to the dataset’s ample size and variability.

294 **Jet events simulation configuration:** To construct the

dataset, Pb-Pb (lead-lead) events were simulated using the
 JETSCAPE framework on a distributed computing Grid
 system. All events utilize either *Matter* or *Matter-LBT*
 as their energy loss module with a static medium.

The dataset comprises nine parts, each corresponding
 to different combinations of α_s and Q_0 across 18 design
 points. Parts with the same α_s and varying Q_0 are grouped
 together, resulting in nine distinct parts (see Table 1).

4.1. Matching/Filtering procedure

The algorithm 1 describes the preprocessing steps for the
 ML-JET dataset, including simulation, selection of rele-
 vant jet observables, creation of 2D histograms, visual-
 ization, labeling, dataset splitting, and packaging. These
 steps are essential for building/preparing the data for a
 benchmark dataset and training models in subsequent sec-
 tions. Followings are jet observable used in our dataset
 building process:

- p_T : transverse momentum
- ϕ : azimuthal angle
- η : pseudorapidity of the emitted thermal particles

In the next section, we introduce a methodology to train
 models from nine datasets with 1080K training records,
 compile the model, and classify 120K test records and cal-
 culate the accuracy as their validation method.

5. Methodology

To predict the energy loss module, we segregate our events
 into either *Matter* or *Matter-LBT* labels on the basis of the
 features, so we are solving a binary classification problem.

We refined the predictor model’s general category based
 on our data structure. We examined state-of-the-art pat-
 tern recognition techniques in machine learning, to solve
 the problem first and because jet events exhibit discernible
 topological structures resembling images, we opted for

Table 4. VGG16 model with 50 epochs: accuracy & loss diagrams.

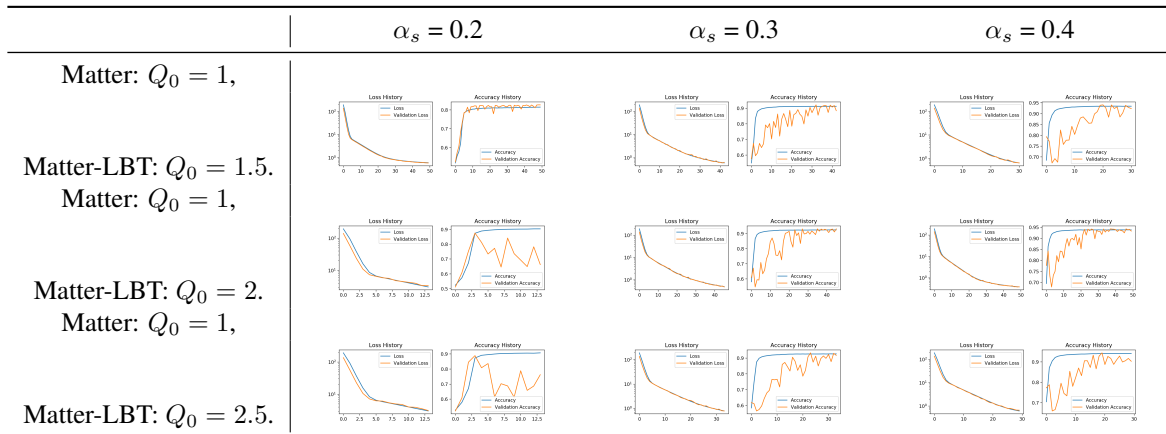


Table 5. VGG16 model with 50 epochs: accuracy.

	Accuracy (%)		
	Train	Validation	Test
Config. 1	82.58	82.65	89.98
Config. 2	92.12	92.17	92.89
Config. 3	94	94.07	93.87
Config. 4	87.45	87.54	87.26
Config. 5	93.15	93.15	93.06
Config. 6	94.34	94.3	94.29
Config. 7	88.99	88.9	88.91
Config. 8	93.24	93.3	93.24
Config. 9	94.38	94.4	94.29

328 computer vision and pattern recognition leading us Con-
 329 volutional Neural Networks (CNN) as our next approach.
 330 Initiating our baseline models with piece-wise linear units,
 331 such as Rectified Linear Units (ReLU), we employed Adam
 332 as the optimizer.

333 The incorporation of Adam Batch Normalization yielded
 334 a marked improvement in optimization performance, particu-
 335 larly beneficial for convolutional networks and networks
 336 featuring sigmoidal nonlinearities, as evidenced by previ-
 337 ous applications. To enhance regularization and curb over-
 338 fitting, we universally implemented Early Stopping and ap-
 339 plied Dropout as a regularizer. Furthermore, Batch Nor-
 340 malization was employed to minimize regularization errors
 341 effectively.

342 We carefully selected hyperparameters to optimize the
 343 performance of our approach. The learning rate, a critical
 344 parameter influencing the convergence of our model, was
 345 set to $[1e - 1, 1e - 7]$. Additionally, the architecture of
 346 our neural network was fine-tuned by specifying 4-16 hid-
 347 den layers, each designed to capture intricate features rele-

vant to our task. These hyperparameter choices were made
 through an iterative process of experimentation and valida-
 tion, ensuring the robustness and effectiveness of our model
 across various scenarios. In the context of binary classi-
 fication, each model employs a loss function, specifically
binary cross entropy, consistently applied throughout our
 comprehensive study.

5.1. Baseline Pre-trained Models

In this section, we introduce a range of baseline mod-
 els encompassing both pre-trained deep learning architec-
 tures and traditional machine learning algorithms for the
 energy loss module classification task. **MNIST Net** [20]
 and **VGG16Net** [34] serve as representatives of pre-trained
 deep neural network architectures. MNIST Net, initially
 devised for handwritten digit recognition, leverages in-
 sights into 2D shape invariances through local connection
 patterns and weight constraints. With 4 layers, includ-
 ing convolutional and fully connected layers, MNIST Net
 boasts 96,445 trainable parameters. On the other hand,
 VGG16Net, renowned for its remarkable performance in
 image recognition tasks, comprises 16 layers, with 4 con-
 volutional and fully connected blocks, totaling 15,676,673
 trainable parameters. **PointNet** [29] introduces a novel ap-
 proach to processing point cloud data, making it uniquely
 suited for our jet event image classification task. Unlike
 conventional convolutional neural networks that operate on
 structured grid-like data, PointNet directly consumes un-
 ordered point sets. To ensure consistency across all mod-
 els, we kept the key features of the networks such as activa-
 tion function, dropout layer, optimization algorithms, loss func-
 tions, validation process, and early stopping standardized
 across architectures. Additionally, we include a selection of
 traditional machine learning algorithms:

- **Logistic Regression** serves as a fundamental binary clas-
 sification algorithm that models the probability of an in-

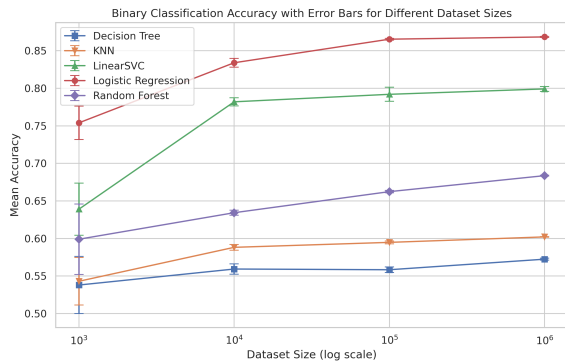


Figure 3. Trained logistic regression, decision trees, KNN, Linear SVC, and Random Forest models accuracy mean and error bar.

stance belonging to a particular class. It provides a simple yet effective baseline for comparison.

- **K-Nearest Neighbor (KNN)** is a non-parametric classification algorithm that assigns labels to instances based on the majority vote of its k-nearest neighbors in the feature space.
- **Support Vector Machine (SVM)** offers a powerful method for classification by finding the hyperplane that best separates the classes while maximizing the margin.
- **Decision Tree** constructs a tree-like model by recursively partitioning the feature space based on the feature values, making it intuitive and interpretable.
- **Random Forest** is an ensemble learning method that constructs multiple decision trees during training and outputs the mode of the classes as the prediction.

By incorporating both deep learning architectures and traditional machine learning algorithms, we facilitate a comprehensive evaluation of various models for the energy loss module classification task.

5.2. Data Format, Benchmark Access, Maintenance, and Extensibility

The benchmark consists of different data files, one for each configuration from table 1, consisting of Q_0 , α_s , energy loss module label, and the event matrices, using the pickle binary data format. Each such file contains four arrays, which contain X_{train} , Y_{train} , X_{test} and Y_{test} , where each array has the dimensions N_{train} , M_{test} . N_{train} is the number of events and energy loss module labels in X_{train} and Y_{train} and M_{test} is the number events and energy loss module labels in X_{test} and Y_{test} . The scientist can leverage the predefined classes included in our benchmark code to load a particular dataset as a Tensorflow [1] dataset class. These can then be applied to create standard DataLoader instances for training unique ML models. We make use of the Hydra [43] package, which facilitates the data management

and the generation of additional datasets. For the latter, we make many simulation settings available and accessible for the user to modify. As a result, users have a low entry hurdle to benchmark with fresh experiments or standard configurations.

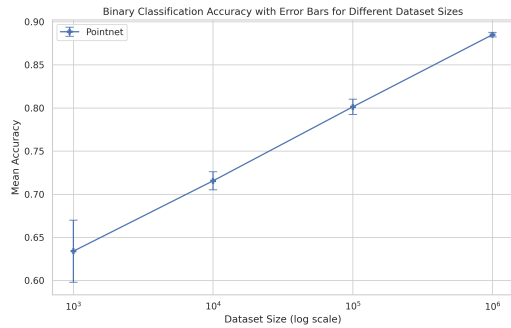
6. Dataset analysis and evaluation

In this section, we present the outcomes of our experiments aimed at assessing the efficacy and suitability of various machine learning and deep learning methodologies on the ML-JET dataset for the task of energy loss module classification. We conducted a comprehensive analysis employing logistic regression, decision trees, K-Nearest Neighbor (KNN), Support Vector Machine (SVM), Random Forest, MNISTNet, VGG16Net, and PointNet models. Our evaluation encompasses performance metrics such as binary classification accuracy, training time, stability, and scalability across different dataset sizes. We leverage our university grid by using GPUs. We allocated 128GB memory and 32-core CPU with a GPU V100 Nvidia Tesla for training each model.

6.1. Results of Deep Learning Models

We initiated our investigation by training deep learning models, specifically Convolutional Neural Networks (CNNs), on the ML-JET dataset. Various CNN architectures, including MNIST and VGG16, were utilized with distinct configurations. Notably, the VGG16 model achieved an average accuracy of 92% on the held-out test set, showcasing its effectiveness in energy loss module classification tasks. Extensive experimentation revealed the robustness of deep learning approaches in handling complex classification problems within heavy ion physics.

We trained the MNIST model for 30 epochs, resulting in an average accuracy of 82.23% on the test data over all nine configurations. Furthermore, the VGG16 model achieved an accuracy of 88.95% for 30 epochs and 91.98% for 50 epochs. A detailed analysis of the VGG16 training on 50 epochs and MNIST, focusing on accuracy and loss diagrams for 9 different dataset configurations, is presented in Table 2 and Table 4. Respectively, we reported their detailed accuracy results in Table 3 and Table 4. The MNIST model exhibited a mean accuracy of approximately 82.78%, with error bars indicating a 95% confidence interval of $\pm 5.27\%$. This suggests a moderate level of consistency in performance. The VGG16 model trained for 30 epochs achieved a mean accuracy of 89.11%, with relatively small error bars ($\pm 2.97\%$), indicating a high degree of stability in the model's accuracy across different runs. Moreover, we explored the efficacy of PointNet models, a cutting-edge methodology tailored for point cloud data. Figure 4 demonstrates the training results of PointNet models and one sample accuracy and loss diagram for it. Our findings



(a) Accuracy mean and error bar of trained PointNet models.

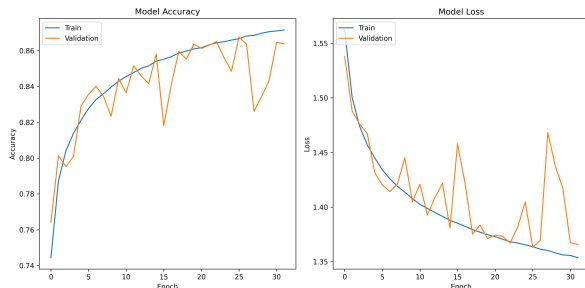
(b) Accuracy and loss of PointNet models for training and validation on a dataset size of 10^6 .

Figure 4. Performance evaluation of PointNet models.

469 demonstrated remarkable performance, with point clouds
 470 achieving an average accuracy of approximately 88% with
 471 a dataset size of 10^6 , outperforming traditional machine
 472 learning models such as logistic regression on significantly
 473 larger datasets. The trajectory of training loss across epochs
 474 exhibited consistent decrease, indicating effective learning,
 475 although vigilance against overfitting was warranted.

476 6.2. Results of Machine Learning Models

477 In parallel, we evaluated traditional machine learning mod-
 478 els including logistic regression, decision trees, KNN, Lin-
 479 ear SVC, and Random Forest. Logistic regression emerged
 480 as a strong contender, achieving an average accuracy of ap-
 481 proximately 87%, surpassing other traditional models in the
 482 context of energy loss module classification. However, the
 483 accuracy plateaued around 87% even with increased dataset
 484 sizes, suggesting the necessity for alternative approaches,
 485 particularly in scenarios demanding higher accuracy.

486 Linear SVC, Random Forest, KNN, and Decision Tree
 487 techniques followed, demonstrating varying degrees of per-
 488 formance. While Linear SVC exhibited a plateauing trend
 489 in accuracy around 80%, Random Forest showcased a lin-
 490 ear increase with dataset size expansion. Nevertheless, ex-
 491 trapolation indicated substantial dataset size requirements
 492 to match logistic regression accuracy levels. KNN and Ran-
 493 dom Forest displayed incremental accuracy improvements

up to a certain dataset size, indicating their efficacy for
 moderate-scale datasets.

7. Conclusion

497 In this paper, we presented a new dataset named ML-JET
 498 that is specifically designed for deep learning applications.
 499 The dataset consists of 10.8 million images with a reso-
 500 lution of 32×32 , each associated with energy loss mod-
 501 ule labels (Matter and Matter-LBT). We believe that this
 502 dataset is valuable to researchers and practitioners in the
 503 field of deep learning and phenomenal physics, enabling
 504 them to develop and test new models for various tasks
 505 such as medium parameter classification and event param-
 506 eter prediction. We will release the dataset publicly to
 507 allow others to replicate our experiments and build upon
 508 our findings. Furthermore, our study underscores the effi-
 509 cacy of both deep learning and traditional machine learn-
 510 ing methodologies in addressing energy loss module clas-
 511 sification tasks. While deep learning models, particularly
 512 VGG16 and PointNet, demonstrated superior accuracy and
 513 scalability, traditional machine learning approaches, espe-
 514 cially logistic regression, remain viable options, particularly
 515 in resource-constrained environments. For the specific re-
 516 quirements of the application and the available computa-
 517 tional resources, we recommend pattern recognition tech-
 518 niques using deep neural networks.

8. Discussion and Future Studies

520 After successfully building a novel dataset of jet events and
 521 using it to classify the energy loss module in this study, we
 522 plan to extend the study by leveraging the dataset for more
 523 machine learning and deep learning tasks. Some possible
 524 future studies include the following:

- Develop and train deep models individually for classify-
 ing and predicting the α_s and Q_0 values.
- Construct a synthesis deep model to simultaneously pre-
 dict the energy loss module, α_s , and Q_0 values.
- Create an application capable of extracting all environ-
 mental parameters associated with each event from event
 images.
- Expand the dataset from a static medium to a hydro-
 dynamic medium, generate/simulate events, and build a
 dataset with the hydrodynamic profile.
- Develop and train deep models for the expanded dataset.
- Conduct a comparative analysis between the resulting
 models.

538 We encourage fellow scientists in the field to utilize the
 539 ML-JET dataset to explore additional mysteries of the uni-
 540 verse.

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Can Computer Vision Help Relativistic Physics?

ML-JET dataset for relativistic heavy ion collisions

Supplementary Material

725 9. Energy Loss Module Physics Formalism

726 The initial virtuality of the partons will have a maximum
727 limit set by the preset distribution. These will then be intro-
728 duced into the MATTER event generator. In MATTER, a
729 single hard parton created at a point r with a forward light-
730 cone momentum $p^+ = (p^0 + \hat{n} \cdot \vec{p}/\sqrt{2})$ where $\hat{n} = \vec{p}/|\vec{p}|$
731 starts a virtuality-ordered shower.

732 To ascertain the real virtuality ($t = Q^2$) of the given parton,
733 one may sample a Sudakov form factor,

$$734 \Delta(t, t_0) = \exp \left[- \int_{t_0}^t \frac{dQ^2}{Q^2} \frac{\alpha_s(Q^2)}{2\pi} \int_{t_0/t}^{1-t_0/t} dz P(z) \right. \\ \left. \times \left\{ 1 + \int_0^{\zeta+MAX^+} d\zeta^+ \frac{\hat{q}(r+\zeta)}{Q^2(1-z)} \Phi(Q^2, p^+, \zeta^+) \right\} \right], \quad (1)$$

735 where Φ represents a sum over phase factors that depends
736 on ζ^+, p^+ , and Q . The transport coefficient \hat{q} is evalu-
737 ated at the location of scattering $\vec{r} + \hat{n}\zeta^+$, $P(z)$ is the vac-
738 uum splitting function, and ζ_{MAX^+} is the maximum length
739 ($1.2\tau_f^+$), which is used to sample the actual splitting time of
740 the given parton with τ_f^+ as the mean light-cone formation
741 time $\tau_f^+ = 2p^+/Q^2$ [10]. After determining Q^2 , z can be
742 sampled using the splitting function $P(z)$. The transverse
743 momentum of the created daughter pair can be estimated using
744 the difference in invariant mass between the parent and
745 daughters. This method is repeated until a given parton's
746 Q^2 reaches a specific value for Q_0^2 .

747 Below Q_0^2 the jet might be better characterized by another
748 energy loss module such as LBT, which can evolve accord-
749 ing to the linear Boltzmann equation. Q_0 is the virtual-
750 ity separation scale. For our dataset, the medium-induced
751 gluon spectrum

$$752 \Gamma^{inel} = \int dx dk_{\perp}^2 \frac{dN_g}{dx dk_{\perp}^2 dt}, \quad (2)$$

753 where the differential spectrum of radiated gluon is taken
754 from the higher-twist energy loss formalism [24, 32, 39]:

$$755 \frac{dN_g}{dx dk_{\perp}^2 dt} = \frac{2\alpha_s C_A \hat{q} P(x) k_{\perp}^4}{\pi(k_{\perp}^2 + x^2 m^2)^4} \sin^2 \left(\frac{t - t_i}{2\tau_f} \right), \quad (3)$$

756 where x and k_{\perp} are the fractional energy and transverse
757 momentum of the emitted gluon with respect to its parent
758 parton, α_s is the strong coupling constant, $C_A = N_c$ is the
759 gluon color factor, $P(x)$ is the splitting function, \hat{q} is the

transport coefficient, t_i denotes the production time of the
760 given parton, and $\tau_f = 2Ex(1-x)/k_{\perp}^2 + x^2 m^2$ is the
761 formation time of the radiated gluon with E and m as the
762 parton energy and mass, respectively. With these scatter-
763 ing rates, the Monte Carlo method is applied to determine
764 whether scattering happens within a given time step. In this
765 work, we develop a ML model to determine the energy loss
766 model for different values of Q_0 and α_s .
767

10. Heavy Ion Collisions

In this section, we show a visualization that depicts the
769 multi-stage approach that is leveraged in the JETSCAPE for
770 jet evolution in Figure 5.
771

11. Sample events

In this appendix, we provide sample events for configura-
773 tions two through nine of the dataset, depicted in Figures 6
774 through 23.
775

12. Calculating Accuracy for VGG16 Training for 50 epoch Config. #9 - Test Data

One of the methods for assessing classification models is
778 accuracy, which is simply the percentage of correct predic-
779 tions. For binary classification, accuracy can also be cal-
780 culated in terms of positives and negatives as in equation
781 (4).
782

$$783 Accuracy = \frac{TP + TN}{TP + TN + FP + FN}, \quad (4)$$

784 where $TP = True\ Positives$, $TN = True\ Negatives$, $FP =$
785 $False\ Positives$, and $FN = False\ Negatives$. Table 6 shows
786 an example confusion matrix (VGG16 Model – 50 epoch -
787 Config. #9 – Test data) to calculate model's accuracy. The
788 accuracy is 0.9429, or 94.29% (94 out of 100 instances
789 yielded correct predictions) regarding equation 4. That indi-
790 cates that our energy loss module classifier is very effective
791 in detecting between *Matter* and *Matter-LBT*.

Table 6. Confusion Matrix for VGG16 Model – 50 epoch - Config. #9 – Test data

	Predicted	
	MATTER	MATTER-LBT
MATTER	TP: 56192	FP: 3039
MATTER-LBT	FN: 3808	TN: 56961

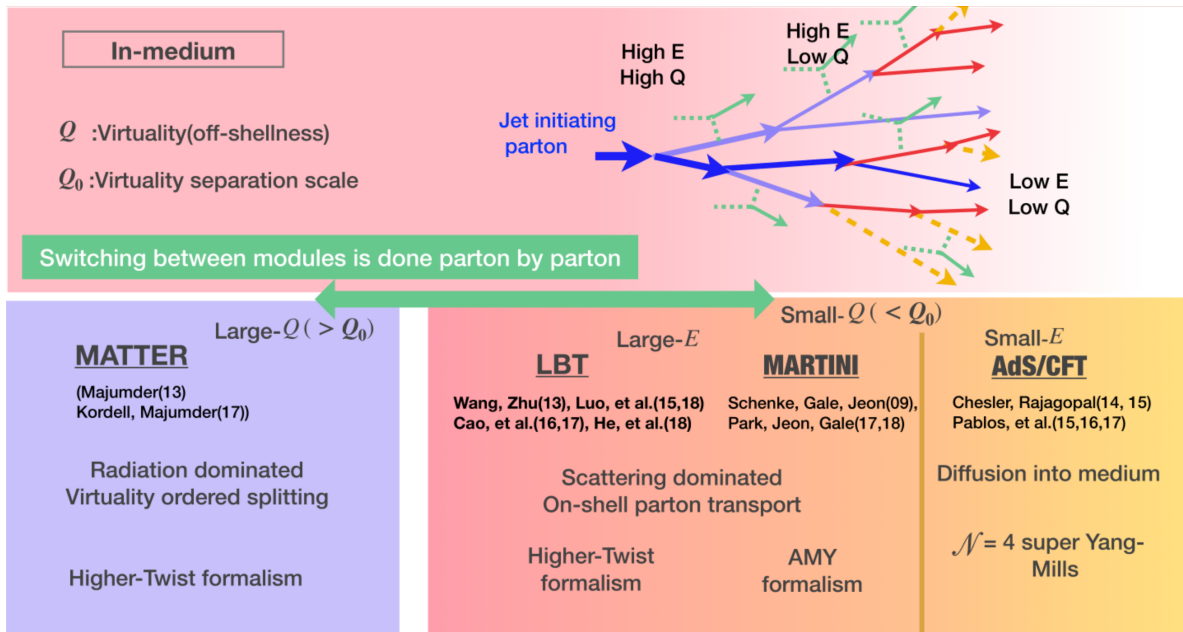


Figure 5. Multi-stage approach in heavy-ion collisions, credit to Y. Tachibana et. al. from JETSCAPE collaboration.

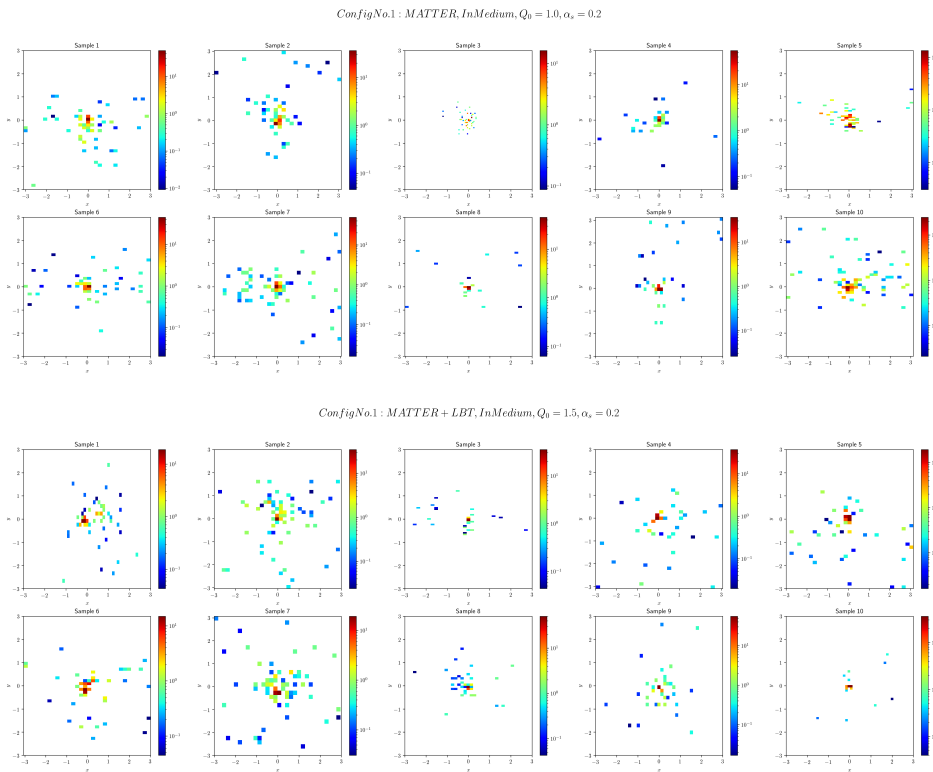


Figure 6. Dataset: Sample events: Config No. 1 Matter and Matter-LBT.

13. VGG16 Training for 30 epochs

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In this appendix, we provide the detailed analysis for VGG16 training for 30 epochs. Table 7 demonstrates the

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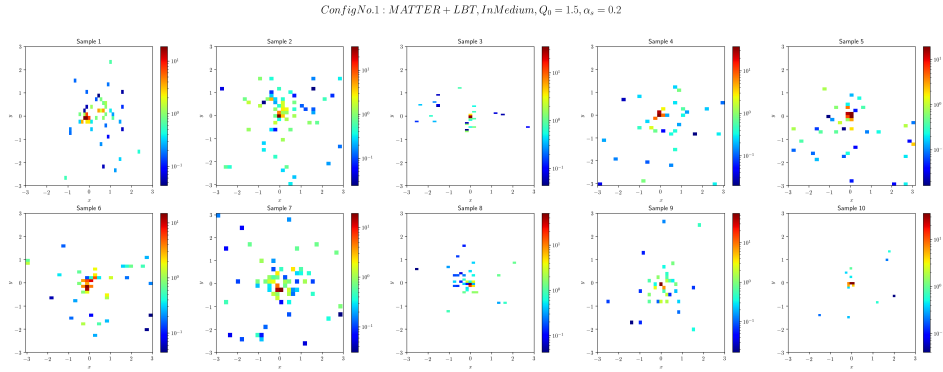


Figure 7. dataset: Sample events: Config No. 1 Matter-LBT.

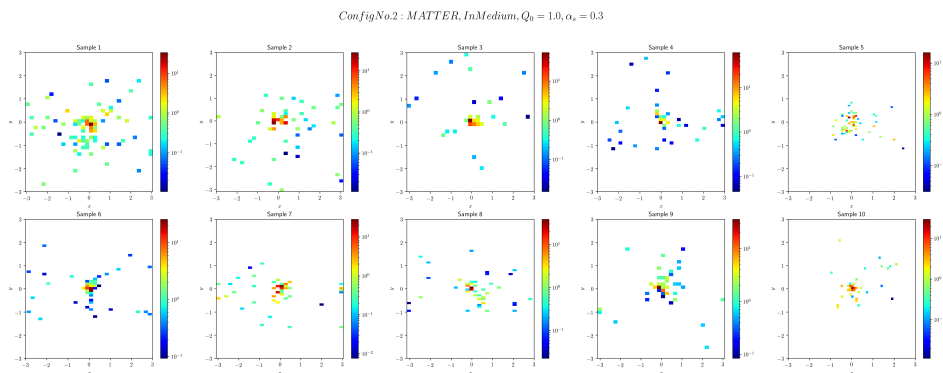


Figure 8. dataset: Sample events: Config No. 2 Matter.

Table 7. VGG16 model with 30 epochs: accuracy.

	Accuracy (%)		
	Train	Validation	Test
Config No. 1	89.395	89.4242	89.1383
Config No. 2	91.031	91.0596	91.5408
Config No. 3	84.5407	84.6833	84.4558
Config No. 4	76.0095	76.1054	75.9908
Config No. 5	91.7856	91.8829	91.6892
Config No. 6	94.367	94.3083	94.3483
Config No. 7	86.5311	86.41	86.2825
Config No. 8	93.029	93.0608	93.0133
Config No. 9	94.1714	94.1717	94.0925

795 loss and accuracy diagrams and table 8 demonstrates the
796 accuracy for nine configurations.

797 14. Early stopping on VGG15 models

798 To prevent overfitting early stopping techniques has been
799 applied on the training models. Table 9 shows a detailed ac-

curacy report on each model when it confronted early stop-
ping on VGG16 for 50 epochs.

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15. Accuracy central tendency and variation for MNIST and VGG16 models

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In this section, models' accuracy results with central ten-
dency (mean) and their variation (error bars) in Figure 24.

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15.1. Analysis of Machine Learning Models

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In the pursuit of evaluating the efficacy and applicability
of the ML-JET dataset, a series of experiments were con-
ducted employing diverse machine learning methodologies.
These encompassed logistic regression, decision trees, K-
Nearest Neighbor (KNN), Support Vector Machine (SVM)
including its linear variant (Linear SVC), and Random For-
est, each deployed with various architectures and configu-
rations. Training these models on the ML-JET dataset, we
gauged their performance against a held-out test set.

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Figure 3 illustrates the binary classification accuracy
along with error bars for five distinct machine learning mod-
els trained over 5-fold cross-validation and employing four

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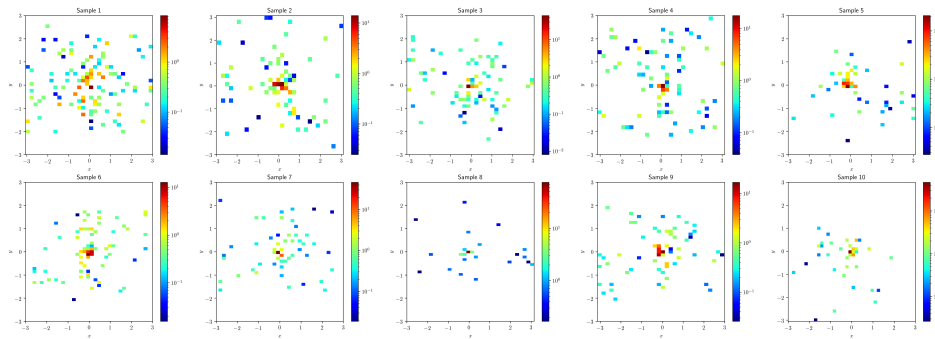
ConfigNo.2: MATTER+LBT, InMedium, $Q_0 = 1.5, \alpha_x = 0.3$ 

Figure 9. dataset: Sample events: Config No. 2 Matter-LBT.

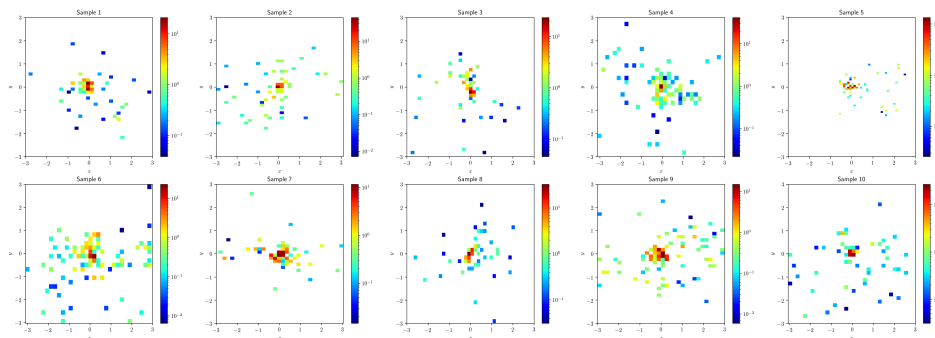
ConfigNo.3: MATTER, InMedium, $Q_0 = 1.0, \alpha_x = 0.4$ 

Figure 10. dataset: Sample events: Config No. 3 Matter.

819 variations in dataset size ranging from 1K to 1000K instances. Our findings underscore the ML-JET dataset’s proficiency, particularly in logistic regression models for tasks pertaining to energy loss module classification. These models achieved an average accuracy of approximately 87%, surpassing the performance of other models. However, it’s noteworthy that the accuracy of logistic regression models plateaued at around 87% even with an increase in dataset size from 10^5 to 10^6 , prompting consideration for alternative approaches within deep learning paradigms.

829 Linear SVC, Random Forest, KNN, and Decision Tree techniques followed in rankings from 2 to 5 respectively, in terms of their accuracy performance. Similar to logistic regression, Linear SVC exhibited a plateauing trend in accuracy, albeit at around 80% on average. Random Forest displayed a linear increase in accuracy with the expansion of the dataset size. However, extrapolating this trend suggests an immense dataset size requirement of 10^{10} instances to merely attain logistic regression accuracy levels with a dataset size of 10^6 . KNN and Random Forest exhibited analogous accuracy trends, showing improvements between 10^3 to 10^4 instances, with marginal gains thereafter,

boasting approximately 2-3% better performance.

16. Analysis of Point Cloud Models

Upon scrutinizing the limitations of contemporary machine learning models in terms of computational capacity and accuracy, our focus shifted towards exploring cutting-edge deep neural network methodologies. Specifically, we delved into training PointNet [29] models for addressing the energy loss binary classification problem, employing various settings and configurations.

Figure 4a presents a comprehensive overview of the binary classification accuracy along with error bars for five distinct machine learning models, trained over 10 folds, 32 epochs, and with dataset sizes ranging from 1K to 1000K instances. The results obtained are highly encouraging. Notably, a linear correlation is observed between dataset size and average accuracy. Furthermore, as the dataset size increases, the standard deviation of accuracy diminishes, indicating improved stability in accuracy metrics. Notably, point clouds achieve an average accuracy of approximately 88% with a dataset size of 10^5 . Remarkably, this outperforms logistic regression on a dataset size of 10^6 , showcas-

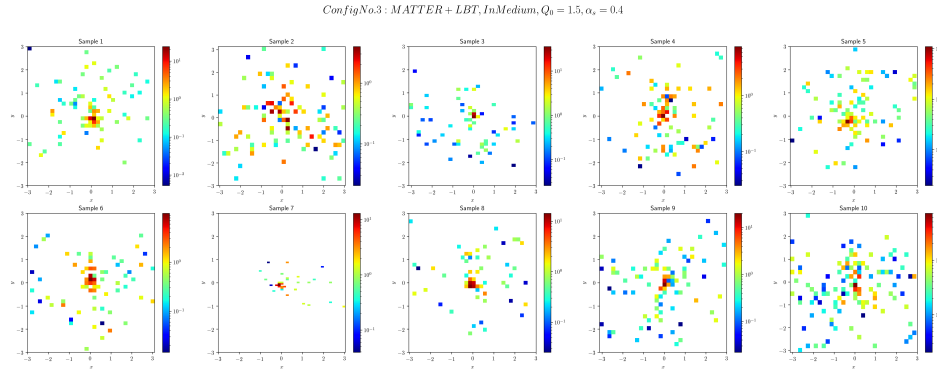


Figure 11. dataset: Sample events: Config No. 3 Matter-LBT.

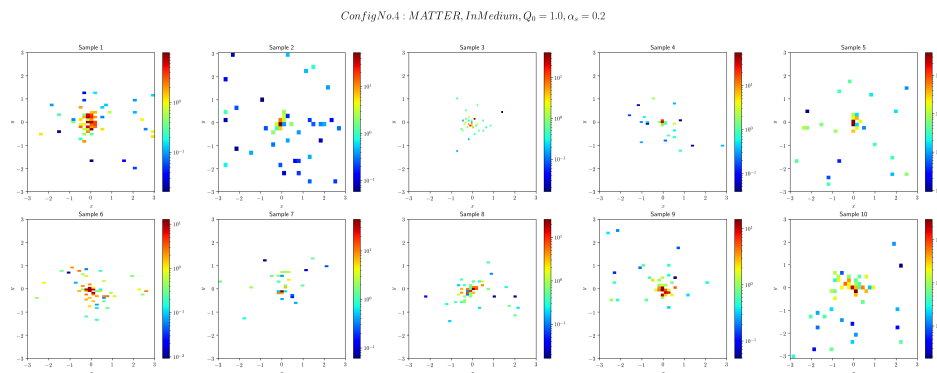


Figure 12. dataset: Sample events: Config No. 4 Matter.

862 ing the consistent and linear progress achieved by PointNet
863 models.

864 Additionally, Figure 4b illustrates the trajectory of train-
865 ing loss across epochs, demonstrating a consistent decrease,
866 indicating effective learning from the training data. Con-
867 versely, the validation loss exhibits an initial decrease but
868 later manifests fluctuations, suggestive of potential overfit-
869 ting as the training progresses. Towards the latter stages of
870 training, a slight increase in validation loss further corrobo-
871 rates the presence of overfitting tendencies.

872 The training accuracy steadily ascends with each epoch,
873 as anticipated due to the model's learning process. How-
874 ever, the validation accuracy showcases a plateauing trend
875 after a certain epoch, indicating limited improvement in per-
876 formance on unseen data beyond a certain point.

877 The widening chasm between training and validation
878 loss serves as a telltale sign of overfitting, wherein the
879 model excels on the training data but struggles to general-
880 ize to unseen instances. Despite these challenges, the final
881 validation accuracy hovers around 86-87%, a commendable
882 achievement within the realm of heavy ion physics and its
883 specific requirements.

ConfigNo.4: *MATTER+LBT, InMedium, $Q_0 = 2.0, \alpha_s = 0.2$*

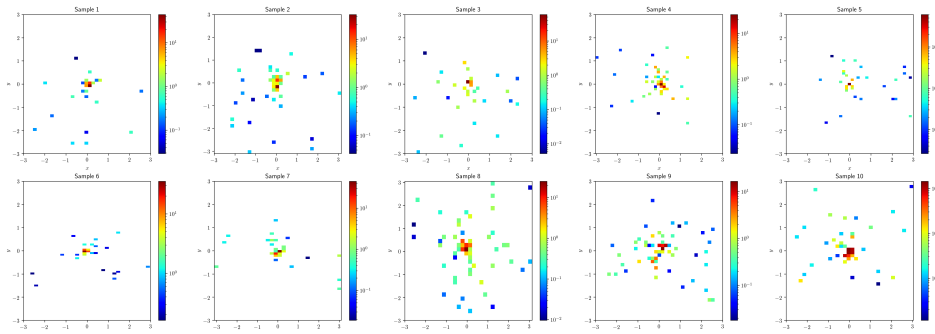


Figure 13. dataset: Sample events: Config No. 4 Matter-LBT.

ConfigNo.5: *MATTER, InMedium, $Q_0 = 1.0, \alpha_s = 0.3$*

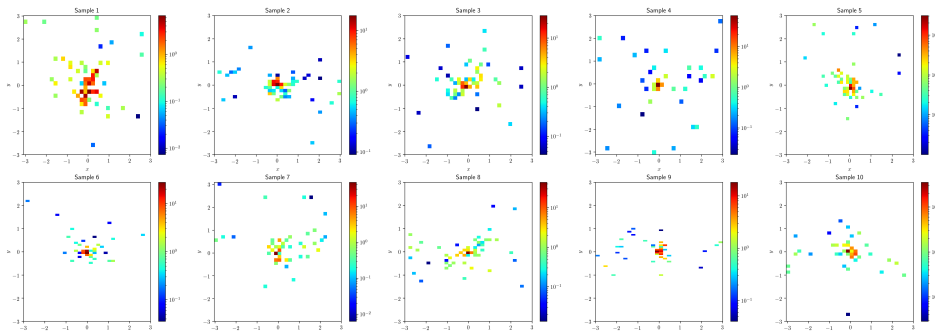


Figure 14. dataset: Sample events: Config No. 5 Matter.

ConfigNo.5: *MATTER+LBT, InMedium, $Q_0 = 2.0, \alpha_s = 0.3$*

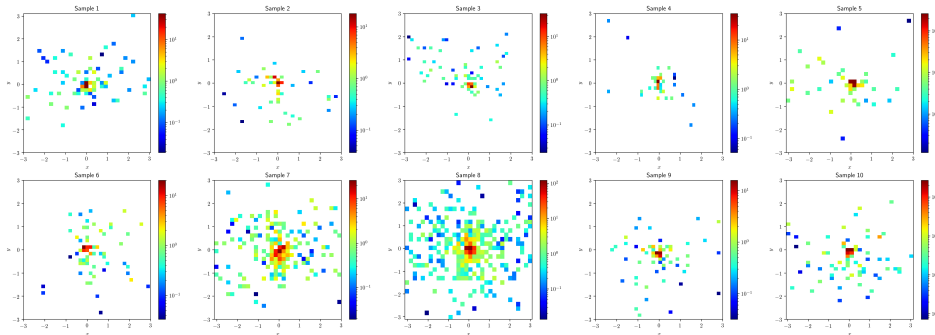


Figure 15. dataset: Sample events: Config No. 5 Matter-LBT.

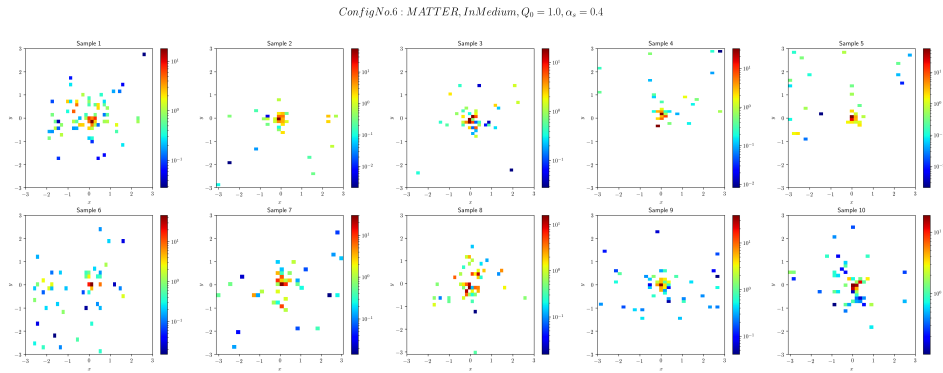


Figure 16. dataset: Sample events: Config No. 6 Matter.

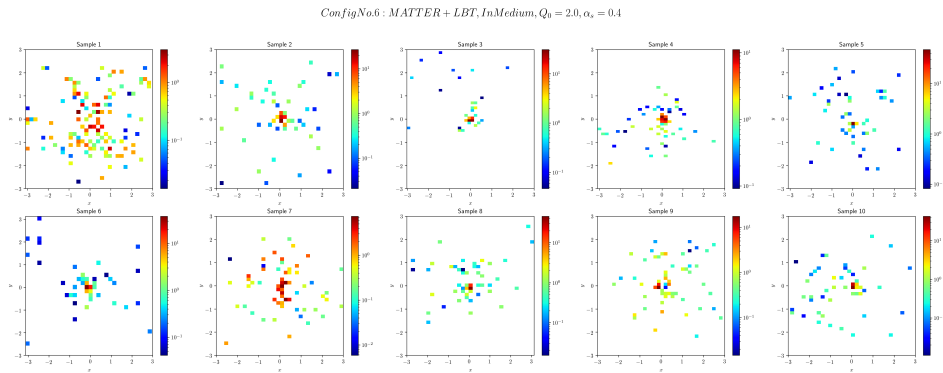


Figure 17. dataset: Sample events: Config No. 6 Matter-LBT.

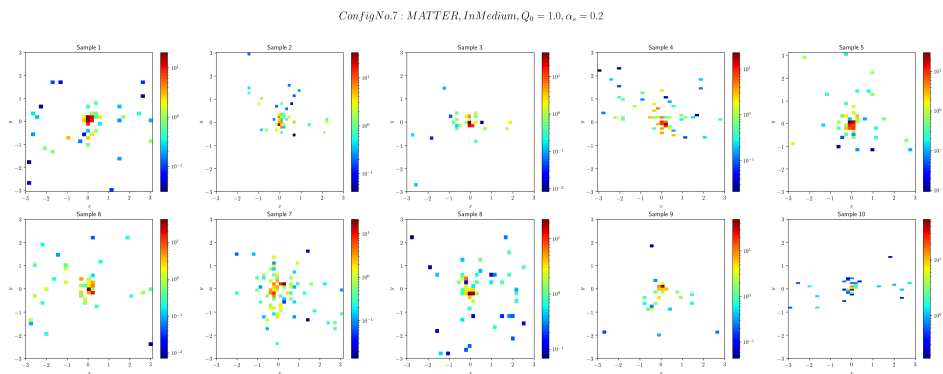


Figure 18. dataset: Sample events: Config No. 7 Matter.

ConfigNo.7: MATTER+LBT, InMedium, $Q_0 = 2.5, \alpha_x = 0.2$

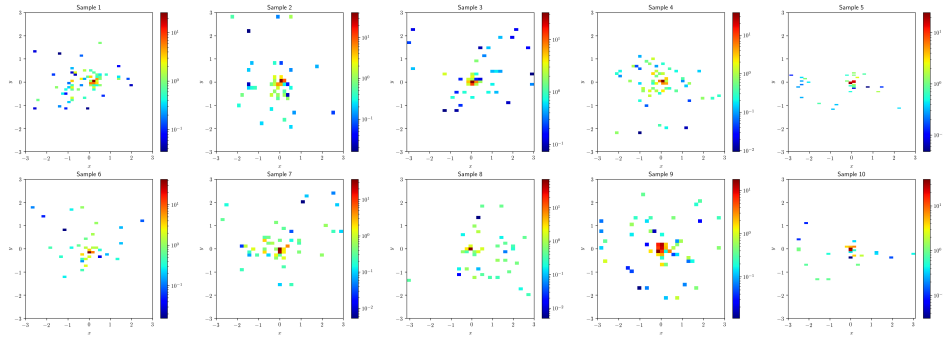


Figure 19. dataset: Sample events: Config No. 7 Matter-LBT.

ConfigNo.8: MATTER, InMedium, $Q_0 = 1.0, \alpha_x = 0.3$

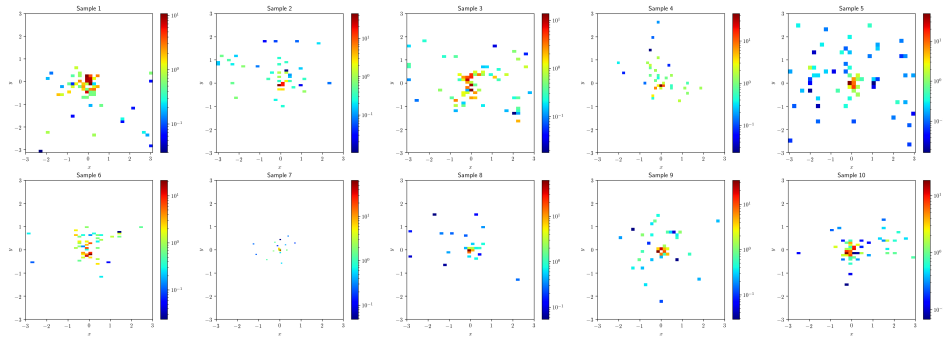


Figure 20. dataset: Sample events: Config No. 8 Matter.

ConfigNo.8: MATTER+LBT, InMedium, $Q_0 = 2.5, \alpha_x = 0.3$

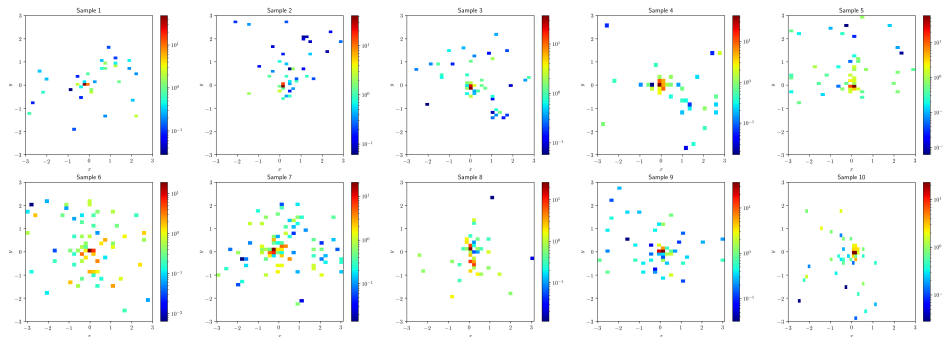


Figure 21. dataset: Sample events: Config No. 8 Matter-LBT.

ConfigNo.9 : MATTER, InMedium, $Q_0 = 1.0, \alpha_s = 0.4$

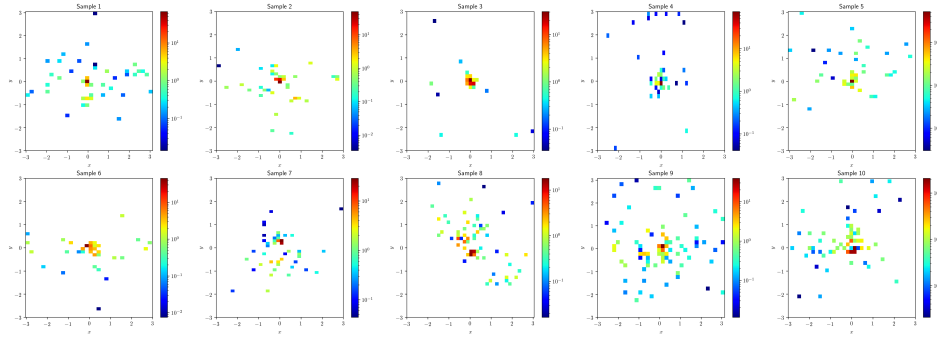


Figure 22. dataset: Sample events: Config No. 9 Matter.

ConfigNo.9 : MATTER + LBT, InMedium, $Q_0 = 2.5, \alpha_s = 0.4$

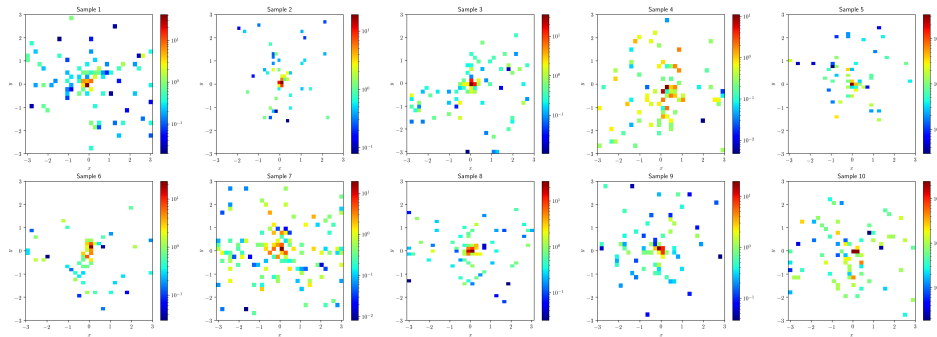


Figure 23. dataset: Sample events: Config No. 9 Matter-LBT.

Table 8. VGG16 model with 30 epochs: accuracy & loss diagrams.

	$\alpha_s = 0.2$	$\alpha_s = 0.3$	$\alpha_s = 0.4$
Matter: $q_0 = 1,$			
Matter-LBT: $q_0 = 1.5,$			
Matter: $q_0 = 1,$			
Matter-LBT: $q_0 = 2,$			
Matter: $q_0 = 1,$			
Matter-LBT: $q_0 = 2.5,$			

Table 9. VGG16 trained models for 50 epochs early stopping and their converged accuracy

Configuration No.	2	3	4	5	7	8
Accuracy (%)	92	93	90	93	89	93

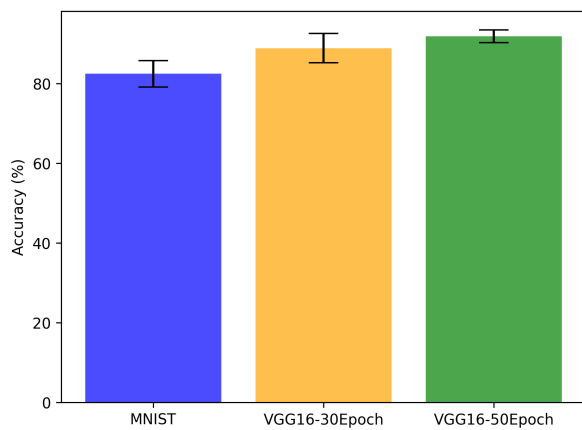


Figure 24. trained models accuracy mean and error bar.