

CLOSED-FORM ℓ_r NORM SCALING WITH DATA FOR OVERPARAMETERIZED LINEAR REGRESSION AND DIAGONAL LINEAR NETWORKS UNDER ℓ_p BIAS

Anonymous authors

Paper under double-blind review

ABSTRACT

For overparameterized linear regression with isotropic Gaussian design and minimum- ℓ_p interpolator with $p \in (1, 2]$, we give a unified, high-probability characterization for the scaling of the family of parameter norms $\{\|\widehat{w}_p\|_r\}_{r \in [1, p]}$ with sample size. We solve this basic, but unresolved question through a simple dual-ray analysis, which reveals a competition between a signal *spike* and a *bulk* of null coordinates in $X^\top Y$, yielding closed-form predictions for (i) a data-dependent transition n_* (the “elbow”), and (ii) a universal threshold $r_* = 2(p - 1)$ that separates $\|\widehat{w}_p\|_r$ ’s which plateau from those that continue to grow with an explicit exponent. This unified solution resolves the scaling of *all* ℓ_r norms within the family $r \in [1, p]$ under ℓ_p -biased interpolation, and explains in one picture which norms saturate and which increase as n grows. We then study diagonal linear networks (DLNs) trained by gradient descent. By calibrating the initialization scale α to an effective $p_{\text{eff}}(\alpha)$ via the DLN separable potential, we show empirically that DLNs inherit the same elbow/threshold laws, providing a predictive bridge between explicit and implicit bias. Given that many generalization proxies depend on $\|\widehat{w}_p\|_r$, our results suggest that their predictive power will be highly sensitive to which ℓ_r norm is used.

1 INTRODUCTION

Many modern generalization measures for machine learning tasks are anchored on the parameter norm instead of parameter count (Neyshabur et al., 2015c;a; Yoshida & Miyato, 2017; Miyato et al., 2018; Cisse et al., 2017). Yet, most analyses of overparameterized regression still treat “the norm” monolithically—typically defaulting to ℓ_2 . If one is going to use a parameter norm, *which* ℓ_r should be used, and how does that choice interact with the inductive bias that selects the interpolator (e.g., minimum- ℓ_p)? This question has been comparatively less studied. We address this question first in a simpler but core setting—linear regression—and then connect the picture to diagonal linear networks (DLNs). Our experiments reveal that sweeping (r, p) produces non-trivial behavior: even for the *same* interpolating predictor, some ℓ_r norms plateau while others keep growing with distinct slopes; in mixed cases, the elbow’s location shifts with p , and *which* r ’s plateau depends on the setting.

In linear regression it is well understood that the value of p *shapes* the inductive bias (sparser as $p \downarrow 1$, denser as $p \uparrow 2$), making the r - p interaction concrete. Beyond explicit ℓ_p penalties, first-order optimization can *implicitly* select a geometry: in overparameterized linear regression, gradient methods recover the minimum- ℓ_2 interpolant; in separable classification, gradient descent converges to a max-margin solution; and in diagonal/deep linear parameterizations, the separable potentials governing the dynamics interpolate between sparse- and dense-leaning behaviors depending on initialization and parameterization (Tibshirani, 1996; Frank & Friedman, 1993; Hoerl & Kennard, 1970; Chen et al., 2001; Zou & Hastie, 2005; Hastie et al., 2015; 2022a; Soudry et al., 2018; Gunasekar et al., 2018a; Ji & Telgarsky, 2019b; Chizat et al., 2019; Woodworth et al., 2020). This variety of explicit/implicit pathways for p -like biases motivates our unified treatment of the *family* $\{\|\widehat{w}\|_r\}$ and explains why different ℓ_r proxies can exhibit qualitatively different n -dependence under a fixed training pipeline.

054 Concretely, we study the minimum- ℓ_p interpolator in high-dimensional linear regression with isotropic
 055 Gaussian design ($d > n, p \in (1, 2]$), and we characterize—in closed form and with high probability—
 056 how the entire family $\{\|\widehat{w}_p\|_r\}_{r \in [1, p]}$ scales with n . A one-dimensional dual-ray analysis exposes
 057 a competition between a signal *spike* and a high-dimensional *bulk* in $X^\top Y$, yielding: (i) a data-
 058 dependent transition size n_* (an elbow in n), and (ii) a universal threshold $r_* = 2(p - 1)$ that
 059 separates norms that ultimately plateau ($r > r_*$) from those that continue to grow with explicit
 060 exponents ($r \leq r_*$). We also extend the picture to DLNs trained by gradient descent: calibrating the
 061 initialization scale α via the network’s separable potential that gives an *effective* exponent $p_{\text{eff}}(\alpha)$,
 062 and with this calibration the observed ℓ_r -vs- n curves inherit the same elbow/threshold structure as
 063 explicit minimum- ℓ_p interpolation. *When the inductive bias is unknown a priori*—e.g., the operative
 064 p of the training pipeline is unclear—our results imply that choosing the “right” r for norm-based
 065 generalization measures can be delicate, since different (r, p) pairs can produce opposite scaling
 066 behaviors (plateau vs. growth) as n increases.

067 *Our contributions:*

- 069 1. **Strong sensitivity of the parameter norm as a function of the pair (r, p)** We find a strong
 070 *qualitative* effect for the scaling of the parameter norm with data: for fixed p , certain ℓ_r norms
 071 plateau while others grow with different slopes; varying p moves the elbow and reassigns which
 072 r ’s plateau.
- 073 2. **Closed-form scaling laws for parameter norms.** We derive the first unified closed-form scaling
 074 laws for this problem. For $p \in (1, 2]$ and all $r \in [1, p]$, we identify the universal threshold
 075 $r_* = 2(p - 1)$, give an explicit expression for the transition size n_* , and provide plateau levels and
 076 growth exponents in both spike- and bulk-dominated regimes via a compact dual-ray argument.
- 077 3. **Extension of our theory to DLNs.** We map the DLN initialization scale to geometry: $\alpha \mapsto p_{\text{eff}}(\alpha)$.
 078 Using this map, we transfer the theory to DLNs and verify the predicted elbow/threshold behavior
 079 of the parameter norm empirically.

081 **Implications for practice.** Because many norm-based generalization measures and diagnostics
 082 depend on $\|\widehat{w}\|_r$, our results imply that practitioners using norm-based bounds or proxies—especially
 083 in more complex models such as DNNs—should be cautious: conclusions can be *highly sensitive* to
 084 the choice of r , and the sensitivity depends on the underlying ℓ_p bias that selects the interpolator.

087 2 RELATED WORK

088
 089 The focus of this paper is a basic question: for overparameterized linear regression and related
 090 diagonal linear networks (DLNs), how do the *parameter norms* $\{\|\widehat{w}\|_r\}_{r \in [1, p]}$ scale with sample size
 091 when the interpolator is selected by an ℓ_p bias? The links to generalization are therefore indirect:
 092 norm quantities often appear as proxies in modern generalization measures (Neyshabur et al., 2015b;
 093 Bartlett et al., 2017; Dziugaite & Roy, 2017), so understanding their n -scaling is informative, but we
 094 do not develop new generalization bounds here. Relatedly, recent analyses derive explicit norm upper
 095 bounds as intermediate steps toward generalization—often via Gaussian min-max techniques—for
 096 interpolators and max-margin procedures (Koehler et al., 2021; Donhauser et al., 2022).

097
 098 **The ℓ_r family of linear-regression interpolators.** A large body of work characterizes how explicit
 099 ℓ_p penalties shape linear estimators: ridge/Tikhonov (ℓ_2) (Hoerl & Kennard, 1970), lasso (ℓ_1)
 100 (Tibshirani, 1996; Efron et al., 2004; Knight & Fu, 2000; Zou, 2006), elastic net (mixtures of ℓ_1
 101 and ℓ_2) (Zou & Hastie, 2005), and the bridge family (ℓ_p for $0 < p \leq 2$) (Frank & Friedman, 1993);
 102 basis pursuit gives the sparse interpolating extreme under equality constraints (Chen et al., 2001;
 103 Candès & Tao, 2007; Donoho, 2006; Bickel et al., 2009). High-dimensional convex-geometric
 104 analyses explain when these programs select structured solutions and how their solutions move
 105 with the data geometry (Chandrasekaran et al., 2012; Amelunxen et al., 2014; Bühlmann & van de
 106 Geer, 2011; Wainwright, 2019), and recent developments give precise characterizations for ridgeless
 107 (minimum- ℓ_2) interpolation and its risk (Hastie et al., 2022a;b). Our contribution complements this
 literature by treating the *entire* norm family $\{\|\widehat{w}_p\|_r\}_{r \in [1, p]}$ for minimum- ℓ_p *interpolators* (with
 $p \in (1, 2]$) and deriving closed-form, high-probability scaling laws in n across r . In this sense we

108 move from “which p shapes which estimator?” to “given p , how do all ℓ_r diagnostics behave as data
109 grow?”
110

111 **Overparameterization in regression and deep networks.** The deep-learning era stimulated a
112 re-examination of overparameterized regression, revealing phenomena such as double descent (Belkin
113 et al., 2019; Nakkiran et al., 2021; Zhang et al., 2017; Nakkiran et al., 2020a; Adlam & Pennington,
114 2020) and benign overfitting for minimum-norm interpolators (Bartlett et al., 2020; Hastie et al.,
115 2022b; Muthukumar et al., 2021). These results show that linear regression can capture qualitative
116 behaviors seen in deep learning models and that the *selected* interpolator’s norm matters for risk.
117 Our work leverages this bridge as motivation only: by explaining, in closed form, which ℓ_r norms
118 plateau and which grow (and at what rates) under an ℓ_p bias, we clarify what one should expect
119 from norm-based proxies commonly used in deep-net analyses. Because practical pipelines for deep
120 models rarely specify the effective p , our finding that $\|\widehat{w}_p\|_r$ depends sensitively on the *pair* (r, p)
121 suggests caution when interpreting norm-based generalization diagnostics.
122

123 **Explicit/implicit regularization and DLNs.** Beyond explicit penalties, optimization can select
124 solutions with an *implicit* geometry (Soudry et al., 2018; Lyu & Li, 2020; Gunasekar et al., 2018b;
125 2017a). In overparameterized linear regression, gradient methods recover the minimum- ℓ_2 interpolant;
126 in factorized or deep-linear parameterizations, the training dynamics induce separable potentials that
127 interpolate between sparse- and dense-leaning behaviors depending on initialization and parame-
128 terization (Saxe et al., 2014b; Gunasekar et al., 2018a; Ji & Telgarsky, 2019b; Chizat et al., 2019;
129 Woodworth et al., 2020). We build on this perspective for DLNs: by calibrating the initialization
130 scale to an effective p_{eff} , we show empirically that DLNs inherit the same elbow/threshold laws for
131 $\{\|\widehat{w}\|_r\}$ as explicit minimum- ℓ_p interpolation.
132

133 **Proof techniques.** Our analysis borrows standard high-dimensional tools used throughout the
134 modern regression literature—Gaussian concentration, blockwise (signal-vs-bulk) decompositions,
135 and dual certificates in convex programs (Vershynin, 2018; Tropp, 2015)—and combines them with a
136 one-dimensional “dual-ray” reduction tailored to the ℓ_p penalty. Two closely related works derive
137 norm *upper* bounds as an intermediate step toward generalization, using the Gaussian Min–Max
138 Theorem (GMT) and its convex analogue (CGMT): Koehler et al. (2021); Donhauser et al. (2022).
139 Their GMT/CGMT-based proofs are conceptually similar in spirit; by contrast, our argument proceeds
140 from first principles via a simple dual-ray balance and yields closed-form n -scaling laws without
141 invoking GMT/CGMT (see also Gordon (1985); Thrampoulidis et al. (2015) for the GMT and CGMT
142 statements).
143

144 3 FAMILY OF NORM MEASURES OF MINIMUM ℓ_p -NORM INTERPOLATOR IN 145 LINEAR MODELS 146

147 We now formalize the object introduced in the overview: for $p \in (1, 2]$ in overparameterized linear
148 regression, we study the family $\{\|\widehat{w}_p\|_r\}_{r \in [1, p]}$ where \widehat{w}_p is the minimum- ℓ_p interpolator. Our goal
149 is to characterize how these norms scale with sample size n . Our results identify (i) a data-dependent
150 elbow n_* and (ii) a universal threshold $r_* = 2(p - 1)$ that separates plateauing from growing ℓ_r ’s.
151

152 **Data and settings.** We consider overparameterized linear models with $X \in \mathbb{R}^{n \times d}$, $d > n$, rows
153 i.i.d. $\mathcal{N}(0, I_d)$, and

$$154 Y = Xw^* + \xi, \quad \xi \sim \mathcal{N}(0, \sigma^2 I_n).$$

155 The minimum- ℓ_p interpolator is

$$156 \widehat{w}_p \in \arg \min_{w \in \mathbb{R}^d} \|w\|_p \quad \text{s.t.} \quad Xw = Y, \quad p \in (1, 2].$$

157
158 Let $s = \|w^*\|_0$ denote the support size and $\tau_s^2 := \|w^*\|_2^2 + \sigma^2$. In contrast to interesting recent
160 work by Donhauser et al. (2022), our theory is *not* restricted to the $w^* = e_1$ limit of extreme sparse
161 regression.

3.1 MAIN THEOREM

Theorem 3.1 (ℓ_r scaling of minimum- ℓ_p interpolators). Fix $p \in (1, 2]$, set $q = \frac{p}{p-1}$, and take $r \in [1, p]$. Assume

$$\frac{d}{n} \rightarrow \kappa \in (1, \infty) \quad \text{and} \quad \liminf_{n \rightarrow \infty} \frac{d-s}{n} = \kappa_{\text{bulk}} > 0.$$

Let w^* have support S with $|S| = s$, and let

$$\hat{w}_p \in \arg \min_{w \in \mathbb{R}^d} \|w\|_p \quad \text{s.t.} \quad Xw = Y.$$

Write $W_q := \|w^*\|_q^q$ and $m_t := \mathbb{E}|Z|^t$ for $Z \sim \mathcal{N}(0, 1)$. Define the ray scale t_* via

$$t_*^{q-1} \asymp \frac{\|Y\|_2^2}{\|X^\top Y\|_q^q} \asymp \frac{\tau_s^2 n}{\underbrace{n^q W_q}_{\text{spike}} + \underbrace{(d-s)m_q \tau_s^q n^{q/2}}_{\text{bulk}} + \underbrace{O(\tau_s^q (s n^{q/2} + s^{1+q/2}))}_{\text{remainder}}} \quad \text{w.h.p.} \quad (1)$$

Then, w.h.p. (see Remark A.1),

$$\|\hat{w}_p\|_r \asymp \max \left\{ t_*^{q-1} n^{q-1} \|w^*\|_{(q-1)r}^{q-1}, (d-s)^{1/r} (t_* \tau_s \sqrt{n})^{q-1}, s^{\max\{1/r, (q-1)/2\}} (t_* \tau_s \sqrt{n})^{q-1} \right\}. \quad (2)$$

Introduce the transition scale

$$n_* \asymp \left(\kappa_{\text{bulk}} \frac{\tau_s^q}{W_q} \right)^{\frac{2}{q-2}}. \quad (3)$$

In the two extremes, we obtain:

Spike-dominated ($n \gg n_*$):

$$\|\hat{w}_p\|_r \asymp \begin{cases} \frac{\tau_s^{q+1}}{W_q} n^{\frac{1}{r} - \frac{1}{2(p-1)}}, & r \leq 2(p-1), \\ \frac{\tau_s^2}{W_q} \|w^*\|_{(q-1)r}^{q-1}, & r > 2(p-1). \end{cases} \quad (4)$$

Bulk-dominated ($n \ll n_*$):

$$\|\hat{w}_p\|_r \asymp \max \left\{ \kappa_{\text{bulk}}^{\frac{1}{r}-1} \tau_s n^{\frac{1}{r}-\frac{1}{2}}, \kappa_{\text{bulk}}^{-1} \tau_s^{2-q} \|w^*\|_{(q-1)r}^{q-1} n^{\frac{q}{2}-1}, \kappa_{\text{bulk}}^{-1} \tau_s s^{\max\{1/r, (q-1)/2\}} n^{-1/2} \right\}. \quad (5)$$

Since $d-s \asymp \kappa_{\text{bulk}} n$, the last term equals $\frac{\tau_s}{d-s} s^{\max\{1/r, (q-1)/2\}} \sqrt{n}$. All \asymp hide absolute constants depending only on $(p, \kappa_{\text{bulk}}, r)$.

Remark 3.2 (Dual viewpoint). The constrained problem $\min_w \frac{1}{p} \|w\|_p^p$ s.t. $Xw = Y$ has unconstrained dual $\max_\lambda \lambda^\top Y - \frac{1}{q} \|X^\top \lambda\|_q^q$, with KKT conditions $Xw = Y$ and $X^\top \lambda = \nabla f(w)$. Restricting to the ray $\lambda = tY$ yields $t_*^{q-1} = \|Y\|_2^2 / \|X^\top Y\|_q^q$. The ‘‘spike’’ vs. ‘‘bulk’’ terminology refers to which part of $\|X^\top Y\|_q$ controls t_* .

Proof sketch. The behavior of the minimum- ℓ_p interpolator can be read through a simple dual lens: rather than track the optimizer directly, we examine a dual certificate that both fits the labels and respects a norm budget after passing through the design; pushing the dual along the label direction (a one-dimensional ‘‘ray’’) reveals a single diagnostic scale where the budget tightens, and this scale is controlled by two competing sources in the correlations $X^\top Y$: a ‘‘spike’’ part (true signal coordinates) that coherently accumulates with n , and a ‘‘bulk’’ part (many null coordinates) that aggregates small, mostly noisy effects. Balancing these two contributions defines a data-dependent transition sample size n_* : for $n \ll n_*$ the bulk dominates, the solution’s mass is effectively spread over many coordinates, and the family $\{\|\hat{w}_p\|_r\}$ grows with n in the way our bulk formulas predict

(including the usual cross- r ordering and an $n^{1/2}$ -type trend visible in the plots); for $n \gg n_*$ the spike dominates, mass concentrates on the support, and a clean threshold—determined by p at $r = 2(p - 1)$ —splits the outcomes: ℓ_r plateaus for r above the threshold and grows with a gentler, explicit slope for r below it. Standard concentration for Gaussian designs justifies the spike/bulk decomposition and the stability of the ray scale, and the KKT linkage between the dual certificate and the primal coordinates turns these ingredients into the unified bound, the expression for n_* , and the two regime descriptions stated in the theorem. Full details are deferred to Appendix A. \square

4 COROLLARIES FOR CANONICAL TARGETS

To make the unified laws in Theorem 3.1 concrete, we specialize them to two canonical targets: (i) a single spike $w^* = e_1$, and (ii) a flat s -sparse vector with equal magnitude a on its support. Substituting the problem-specific scales $W_q = \|w^*\|_q^q$ and $\tau_s^2 = \|w^*\|_2^2 + \sigma^2$ into the elbow formula equation 8 and the spike/bulk-dominated expressions equation 9–equation 10 yields closed-form, high-probability predictions for $\|\widehat{w}_p\|_r$ and the transition size n_* . We record these specializations below as Corollaries 4.1 and 4.2, and use them as reference overlays in our experiments.

4.1 SINGLE SPIKE

Corollary 4.1 (Single spike). *Under Theorem 3.1 with $w^* = e_1$ and $\tau^2 = 1 + \sigma^2$, for any $r \in [1, p]$:*

$$\text{Bulk-dominated } (n \ll n_*): \quad \|\widehat{w}_p\|_r \asymp \tau (d - 1)^{\frac{1}{r} - 1} n^{1/2},$$

$$\text{Spike-dominated } (n \gg n_*): \quad \|\widehat{w}_p\|_r \asymp \begin{cases} \tau^{q+1} n^{\frac{1}{r} - \frac{1}{2(p-1)}} & \text{if } r \leq 2(p-1), \\ \tau^2 & \text{if } r > 2(p-1). \end{cases}$$

Interpretation. Here $W_q=1$ and $n_* \asymp (\kappa_{\text{bulk}} \tau^q)^{2/(q-2)}$ from equation 8. For $r > 2(p-1)$ the ℓ_r curves plateau at level $\asymp \tau^2$ once $n \gg n_*$; for $r \leq 2(p-1)$ they continue to grow with slope $\frac{1}{r} - \frac{1}{2(p-1)}$.

4.2 FLAT SUPPORT

Corollary 4.2 (Flat support). *Under Theorem 3.1 and a flat w^* on S with $|S| = s$ and $w_j^* = a s_j$ for $j \in S$ ($|s_j| = 1$), for any $r \in [1, p]$, w.h.p.:*

$$\text{Spike-dominated } (n \geq Cn_*): \quad \|\widehat{w}_p\|_r \asymp \begin{cases} \frac{(sa^2 + \sigma^2)^{\frac{q+1}{2}}}{s|a|^q} n^{\frac{1}{r} - \frac{1}{2(p-1)}} & r \leq 2(p-1), \\ s^{\frac{1}{r} - 1} \frac{sa^2 + \sigma^2}{|a|} & 2(p-1) < r \leq p, \end{cases}$$

$$\text{Bulk-dominated } (n \leq cn_*): \quad \|\widehat{w}_p\|_r \asymp \max \left\{ \kappa_{\text{bulk}}^{\frac{1}{r} - 1} \tau_s n^{\frac{1}{r} - \frac{1}{2}}, \kappa_{\text{bulk}}^{-1} \tau_s^{2-q} s^{1/r} |a|^{q-1} n^{\frac{q}{2} - 1}, \kappa_{\text{bulk}}^{-1} \tau_s s^{\max\{1/r, (q-1)/2\}} n^{-1/2} \right\}.$$

Interpretation. Here $W_q = s|a|^q$ and $\tau_s^2 = sa^2 + \sigma^2$, so equation 8 gives $n_* \asymp (\kappa_{\text{bulk}} \tau_s^q / (s|a|^q))^{2/(q-2)}$, which grows with s (the elbow shifts to larger n). In the spike-dominated plateau branch ($r > 2(p-1)$) the level scales as $s^{\frac{1}{r} - 1} (sa^2 + \sigma^2) / |a|$, which is typically of the same order as the single-spike plateau for moderate s .

Comparison across targets. The threshold $r = 2(p - 1)$ and the n -exponents in both regimes are *unchanged* between Corollaries 4.1 and 4.2. The differences lie in the *scales*: (i) the transition size moves from $n_* \asymp (\kappa_{\text{bulk}} \tau^q / W_q)^{2/(q-2)}$ with $W_q=1$, $\tau^2=1+\sigma^2$ (single spike) to $n_* \asymp (\kappa_{\text{bulk}} \tau_s^q / W_q)^{2/(q-2)}$ with $W_q=s|a|^q$, $\tau_s^2=sa^2+\sigma^2$ (flat), which scales roughly linearly in s (cf. equation 8). Hence the elbow for regime change shifts to *larger* n when we move from e_1 to a flat w^* with $s=50$. (ii) In the spike-dominated plateau branch ($r > 2(p - 1)$), the level changes from

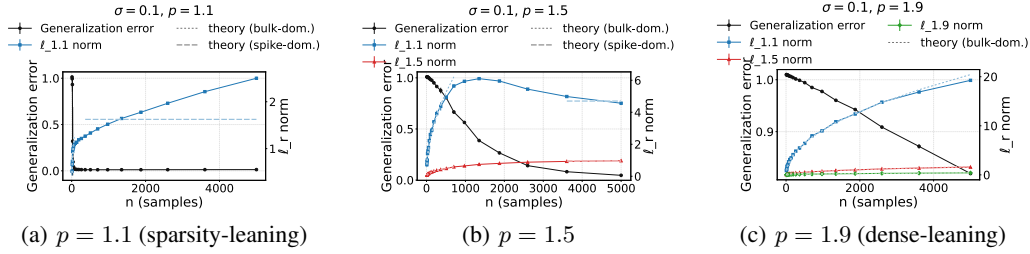


Figure 1: **Single spike** $w^* = e_1$; **explicit minimum- ℓ_p interpolation**. Ordering across r and the presence/absence of elbows follow Corollary 4.1; the bulk panels rise like $n^{1/2}$ and the spike-side panels plateau for $r > 2(p-1)$, consistent with equation 9-equation 10.

$\asymp \tau^2$ (single spike) to $\asymp s^{\frac{1}{r}-1} (sa^2 + \sigma^2)/|a|$ (flat) [cf. equation 9 and Corollary 4.2]; for moderate s this produces *comparable* numerical magnitudes, which is why the vertical ranges in our figures are similar. The regime labels (bulk vs. spike) and their slopes/plateaus therefore provide the informative contrast.

4.3 LINEAR REGRESSION WITH EXPLICIT MINIMUM- ℓ_p BIAS

Here the inductive bias is explicit: for a chosen p , the interpolator is the minimum- ℓ_p element among all w with $Xw = Y$. Sweeping p slides the solution from a more sparse-leaning geometry as $p \downarrow 1$ toward a more dense-leaning geometry as $p \uparrow 2$, revealing how the objective itself shapes the family $\{\|\hat{w}_p\|_r\}_r$.

Experimental protocol. We set $\sigma = 0.1$, sweep $p \in \{1.1, 1.5, 1.9\}$, and vary n . Each plot overlays test MSE (left axis) and representative ℓ_r curves (right axis). For flat w^* experiments, we kept $\|w^*\|_2 = 1$, i.e. $a = \frac{1}{\sqrt{s}}$. Additional noise sweeps are reported in Appendix C.

What the figures show and why. In Fig. 1 (single spike), the left/middle/right panels follow the corollary’s regime rules. In the left panel, for $r > 2(p-1)$ the curves flatten after the transition, while for smaller r they retain the predicted growth; thin reference overlays (where present) trace these slopes. The middle panel exhibits a clear elbow near the predicted n_* ; beyond it, the $r > 2(p-1)$ curves plateau in line with equation 9, while the others keep their slope. The right panel stays bulk-dominated across the range, with the ℓ_r traces growing approximately as $n^{1/2}$ and ordered across r as the bulk formula prescribes.

In Fig. 2 (flat w^* with $s=50$), the *same* slope/plateau rules apply, but the transition scale is larger: the elbow for $p=1.5$ appears at a later n (or just off-range), consistent with n_* increasing roughly linearly with s in equation 8. Across panels, the absolute ℓ_r values are numerically similar to Fig. 1; this matches the flat-support plateau level in Corollary 4.2, which for moderate s is close to the single-spike level. The informative distinction is thus *where* the curves switch from bulk growth to spike plateaus and the persistence of the $n^{1/2}$ slope in regimes that remain bulk-dominated.

Experiments with larger sparsity. We repeat the explicit minimum- ℓ_p runs at larger supports, $s \in \{500, 5000\}$, with the same $\|w^*\|_2=1$ and noise level ($\sigma = 0.1$); see Appendix E, Figs. S13-S14. The qualitative picture from $s=50$ reappears but shifts to larger n , consistent with the transition size n_* in equation 8 growing with s . For small p ($p=1.1$), the prolonged bulk-dominated window makes the *double-descent* pattern visible—generalization error first *increases* and then drops (most clearly at $s=5000$)—while the blue $\ell_{1.1}$ curve keeps rising along the bulk guide across the plotted range (Belkin et al., 2019; Nakkiran et al., 2020b; Hastie et al., 2022a). For larger p ($p=1.5, 1.9$), the curves remain monotonically decreasing; the minimized ℓ_p traces drift only mildly upward (no flattening within the range), reflecting the rounder geometry that avoids early over-reliance on noisy bulk directions. In all panels, the dashed overlays track the bulk/spike trends and the expected r -ordering of the ℓ_r diagnostics, matching the regime structure highlighted in the theory.

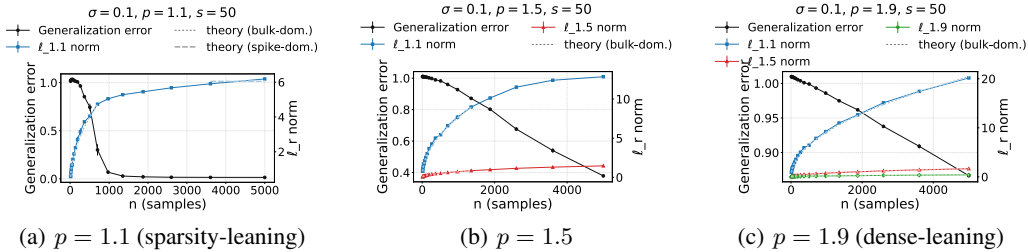


Figure 2: **Flat w^* ($s = 50$); explicit minimum- ℓ_p interpolation.** The scaling rules mirror the flat-support corollary: bulk growth persists until a larger transition scale, while spike-side r values plateau; absolute levels are comparable to the single-spike case, as predicted by the plateau formulas.

4.4 DIAGONAL LINEAR NETWORK WITH IMPLICIT BIAS

Diagonal linear networks (DLNs) - deep linear models whose weight matrices are diagonal so that the effective predictor is the coordinatewise product of layer parameters—provide a tractable testbed for understanding optimization-induced geometry and implicit bias in overparameterized systems. They connect classical analyses of linear nets and factorized parameterizations (Saxe et al., 2014a; Ji & Telgarsky, 2019a; Arora et al., 2019; Gunasekar et al., 2017b) with recent perspectives on how initialization and parameterization interpolate between “rich” and “kernel” behaviors (Chizat et al., 2019; Woodworth et al., 2020). A particularly useful feature—formalized for DLNs via a separable gradient-flow potential—is that the *scale of the initialization*, denoted α , *continuously tunes* the implicit bias: small α yields a sparse-leaning geometry (an ℓ_1 -like penalty up to logarithmic factors), while large α approaches an ℓ_2^2 -type geometry; see the potential Q_α and its limits (Theorem 1 in Woodworth et al. (2020)) and related characterizations in Gunasekar et al. (2017b); Arora et al. (2019).

Calibrating α via an effective p . To compare DLN runs with our explicit minimum- ℓ_p experiments, we convert α into an *effective p* by a data-free calibration. Following the separable potential view, we evaluate Q_α on k -sparse, unit- ℓ_2 probes and fit the log-log slope of its k -dependence; matching that slope to the exact $k^{1-p/2}$ law of $\|\cdot\|_p^p$ yields a monotone map $\alpha \mapsto p_{\text{eff}}(\alpha)$ with limits $p_{\text{eff}}(\alpha) \rightarrow 1$ as $\alpha \rightarrow 0$ and $p_{\text{eff}}(\alpha) \rightarrow 2$ as $\alpha \rightarrow \infty$. This calibration is independent of (n, σ) and lets us select α values that span a sparse-to-dense range comparable to $p \in \{1.1, 1.5, 1.9\}$. A full derivation and a visualization of $\alpha \mapsto p_{\text{eff}}(\alpha)$ are provided in Appendix B.

Finite learning rate. With a single-spike target ($w^* = e_1$, sparsity $s=1$) and small initialization ($\alpha = 0.00102$, so $p_{\text{eff}} \approx 1.10$), we find that the learning rate lr can materially change the ℓ_r -vs- n scaling once label noise is present. When $\sigma=0$, the $\ell_{1.1}$ curve rapidly plateaus and is essentially insensitive to lr (see Appendix D for more details). In contrast, for $\sigma \in \{0.1, 0.5\}$ increasing lr produces a steadily rising $\ell_{1.1}$ and shifts the elbow to larger n ; at the highest noise the effect is strongest- $\text{lr}=10^{-1}$ yields monotone growth across our range, whereas $\text{lr}=10^{-3}$ exhibits a transient rise followed by relaxation toward a plateau, indicating a rightward-moving elbow. We observe qualitatively similar trends for larger sparsity ($s=50$). A natural explanation is that finite step size together with noisy gradients turns (stochastic) gradient descent into a noisy dynamical system with an *effective temperature* that scales with lr and the noise level. The resulting diffusion broadens the stationary distribution and biases the predictor toward rounder (less sparse) geometries-effectively increasing p_{eff} -so mass leaks into bulk coordinates, delaying spike dominance and inflating ℓ_r before the eventual plateau (Mandt et al., 2017; Smith et al., 2018; Yaida, 2018; Jastrzebski et al., 2017).

Experimental protocol. We set $\sigma = 0.1$, sweep $\alpha \in \{0.00102, 0.0664, 0.229\}$ (which according to our α to p calibration $\approx p \in \{1.1, 1.5, 1.9\}$), and vary n . Each plot overlays test MSE (left axis) and representative ℓ_r curves (right axis). For flat w^* again $a = \frac{1}{\sqrt{s}}$. Additional noise sweeps are reported in Appendix C.

Because α has been empirically calibrated to $p_{\text{eff}}(\alpha)$, the DLN panels mirror the *scaling* behavior seen with explicit minimum- ℓ_p : for $w^* = e_1$ (Fig. 3), smaller α (smaller p_{eff}) enters the spike-dominated

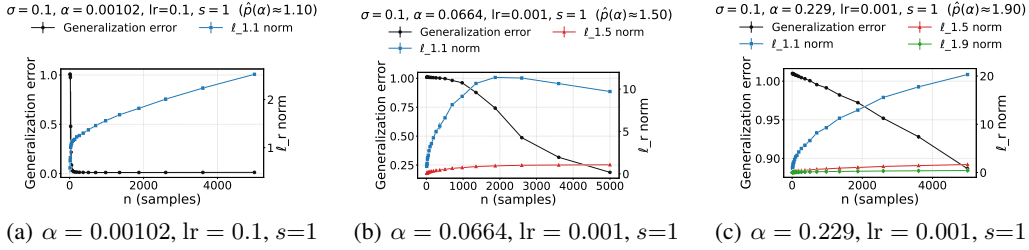


Figure 3: **Single spike** $w^* = e_1$; **diagonal linear network (DLN)**. After calibrating α to $p_{\text{eff}}(\alpha)$, the regime structure matches the explicit p case: smaller α exhibits earlier spike dominance and plateaus for $r > 2(p-1)$; larger α remains bulk-dominated with $n^{1/2}$ -like growth.

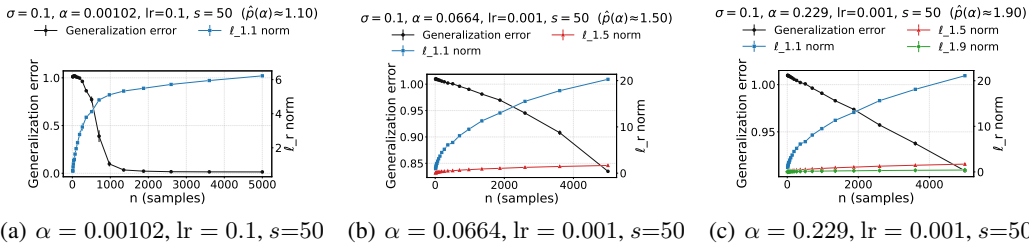


Figure 4: **Flat** $w^* (s = 50)$; **diagonal linear network (DLN)**. The same scaling rules hold, but the elbow appears at larger n —in line with the flat-support transition scale—while absolute ℓ_r magnitudes remain comparable to the single-spike case.

regime earlier so that, for $r > 2(p-1)$, the ℓ_r curves flatten after the transition; larger α remains bulk-dominated longer and the traces grow with the characteristic $n^{1/2}$ trend. For the flat target with $s=50$ (Fig. 4), the same rules apply but the elbow shifts to larger n , consistent with the s -dependent transition scale in the flat-support corollary. The absolute magnitudes of $\|\hat{w}\|_r$ are similar across the two targets, as predicted by the plateau formulas, so the informative contrast again lies in the *location* of the elbow and the presence/absence of plateaus vs. bulk growth. We do not overlay theory on the DLN plots: our guarantees are stated in terms of the explicit parameter p , and deriving a closed-form α -indexed analogue (especially under finite learning rates) is outside the scope of this work; the $\alpha \mapsto p_{\text{eff}}$ calibration serves precisely to make the scaling correspondence visible. In Appendix F we discuss how can we extend our main theorem to DLNs with explicit α .

5 CONCLUSION AND DISCUSSION

We provided the first unified, closed-form characterization of how the entire family of norms $\{\|\hat{w}_p\|_r\}_{r \in [1, p]}$ scales with sample size in overparameterized linear regression under minimum- ℓ_p interpolation ($p \in (1, 2]$). A one-dimensional dual-ray argument exposes a competition between a signal *spike* and a *bulk* of null coordinates in $X^\top Y$ and yields, with high probability: (i) a data-dependent elbow n_\star at which bulk and spike balance [Eq. 8], and (ii) a universal threshold

$$r_\star = 2(p-1),$$

which separates ℓ_r 's that ultimately plateau ($r > r_\star$) from those that continue to grow with an explicit exponent ($r \leq r_\star$) in the spike-dominated regime (Theorem 3.1). The formulas give plateau levels and slopes in both bulk- and spike-dominated regimes, and specialize cleanly for canonical targets (single spike and flat support). Empirically, diagonal linear networks (DLNs) trained by gradient descent inherit the same elbow/threshold laws once the initialization scale α is calibrated to an effective $p_{\text{eff}}(\alpha)$ via the separable potential. Together, these results show that which ℓ_r one tracks matters: for a fixed ℓ_p bias, different ℓ_r 's can exhibit qualitatively different n -laws.

Intuition behind the regime transition. The dual-ray lens reduces the interpolation geometry to a single scale t_\star controlled by $\|X^\top Y\|_q$ ($q = p/(p-1)$). The *bulk* contributes $\asymp (d-s) m_q \tau_s^q n^{q/2}$

while the *spike* contributes $\asymp n^q W_q$, and their balance sets the elbow n_* . Above the elbow, the KKT map raises correlations to the $(q - 1)$ power; the sign of $\frac{1}{r} - \frac{1}{2(p-1)}$ dictates whether the bulk-type term decays (plateau) or grows (slope). This is the origin of the sharp threshold $r_* = 2(p - 1)$. Geometrically, smaller p (sparser inductive bias) lowers r_* , so more ℓ_r 's plateau once the spike dominates; as $p \uparrow 2$, r_* approaches 2 and spike-side plateaus recede, consistent with the special role of $p = 2$ where there is no n -driven transition in the proportional limit.

Implications for generalization proxies. Many diagnostics and bounds in modern learning scale with a parameter norm (or a reparameterization-aware surrogate). Our results indicate that the predictive power of such proxies is *norm-choice sensitive*. For a given ℓ_p bias, ℓ_r 's above r_* stabilize (after n_*) and can serve as geometry-aligned capacity proxies, while ℓ_r 's below r_* continue to reflect data growth through explicit exponents. In practice, the pair (n_*, r_*) acts as a *norm-scaling signature*. Reporting only one norm—often ℓ_2 —risks conflating bulk vs. spike effects and can obscure regime changes that are visible in the ℓ_r family.

From explicit to implicit bias. By calibrating DLN initialization via a simple slope-matching map $\alpha \mapsto p_{\text{eff}}(\alpha)$, the empirical DLN curves line up with the explicit minimum- ℓ_p predictions under $p \leftarrow p_{\text{eff}}(\alpha)$. This provides a quantitative bridge between explicit and implicit bias: initialization steers the effective geometry, and the (n_*, r_*) structure is inherited. Finite learning rates in the presence of label noise act like an effective temperature, increasing p_{eff} and shifting elbows rightward—consistent with recent views of SGD as a noisy dynamical system.

Relation to double descent and benign overfitting. The bulk-side growth ($\propto n^{1/2}$ in prominent terms) and its eventual handoff to spike control rationalize when increasing n first harms and then helps: early fits draw from many noisy bulk directions (large norms and higher variance), while beyond n_* the spike dominates and the relevant ℓ_r 's plateau. Our explicit exponents and thresholds sharpen this picture and make precise which ℓ_r will display which trend at a given (p, n) .

Scope and limitations. Our guarantees assume isotropic Gaussian design, $p \in (1, 2]$, squared loss, and exact interpolation. At $p = 2$ the proportional regime admits no n -driven elbow. The DLN extension uses a data-free calibration to $p_{\text{eff}}(\alpha)$ rather than a fully rigorous, learning-rate-aware theory. Finally, classification losses and non-linear features (beyond DLNs) are outside our formal scope.

Actionable guidance. (i) When using norm-based capacity control, *choose the norm with the geometry*: if training is ℓ_p -biased (explicitly or implicitly), track ℓ_r with $r > 2(p-1)$ to obtain a stable, post-elbow proxy; use $r \leq 2(p-1)$ when one *wants* a readout that continues to reflect data growth. (ii) Empirically estimate (n_*, r_*) by fitting the predicted slopes to a small ℓ_r grid; this gives a compact fingerprint of model-data geometry and a practical meter for bulk vs. spike dominance.

Future directions:

Beyond isotropy and Gaussianity. Extend the dual-ray analysis to anisotropic/sub-Gaussian designs (via whitening) and to heavy-tailed covariates; characterize how n_* and possibly r_* deform with the spectrum and tails of X . **From DLNs to nonlinear nets.** Replace the power link by depth-dependent implicit links in deep (nonlinear) architectures (e.g., path-norm or neural tangent/feature-learning regimes) and test whether an r_* -type threshold persists. **Algorithmic knobs as geometry.** Develop a theory of p_{eff} that accounts for step size, batch size, momentum, and label noise (Langevin/SGD limits), turning these knobs into quantitative geometric parameters with predictions for (n_*, r_*) . **Classification and margins.** Generalize the scaling laws to separable classification with cross-entropy/hinge losses, relating r_* to margin exponents and the growth/saturation of norm families along max-margin flows. **Tighter, r -aware bounds.** Build generalization bounds that track the family $\{\|\hat{w}\|_r\}$ and explicitly incorporate the elbow/threshold structure, connecting to PAC-Bayes and margin-based analyses. **Practical diagnostics.** On modern deep models, measure several ℓ_r -style surrogates (e.g., path norms) across data scale to estimate (n_*, r_*) and evaluate which norms are reliable predictors of test error across regimes.

Overall, our results advocate replacing the monolithic notion of “the norm” by a *family* view. The elbow n_* and the threshold r_* provide simple, interpretable invariants that tie together explicit/implicit bias, data growth, and norm-based generalization measures, and they offer a compact vocabulary for describing—and ultimately controlling—interpolation in high dimensions.

486 **Reproducibility Statement** All experiments in this work are fully reproducible with minimum
487 hardware requirements. The anonymized code can be found at [https://anonymous.4open.
488 science/r/minlp_codebase-880B/](https://anonymous.4open.science/r/minlp_codebase-880B/).
489

490 **LLM usage** General-purpose LLMs are used in this paper to aid or polish writing, e.g., checking
491 typo/grammar slips.
492

493 REFERENCES 494

- 495 Ben Adlam and Jeffrey Pennington. The double descent risk curve in linear regression. *Proceedings
496 of the National Academy of Sciences (PNAS)*, 117(9):5249–5255, 2020.
- 497 Dennis Amelunxen, Miroslav Lotz, Michael B. McCoy, and Joel A. Tropp. Living on the edge: Phase
498 transitions in convex programs with random data. *Information and Inference: A Journal of the
499 IMA*, 3(3):224–294, 2014.
- 500 Sanjeev Arora, Nadav Cohen, Wei Hu, and Yuping Luo. Implicit regularization in deep matrix
501 factorization. In *Advances in Neural Information Processing Systems (NeurIPS)*, volume 32, 2019.
- 502 Peter L. Bartlett, Dylan J. Foster, and Matus Telgarsky. Spectrally-normalized margin bounds for
503 neural networks. In *Advances in Neural Information Processing Systems (NeurIPS)*, 2017.
- 504 Peter L. Bartlett, Philip M Long, Gábor Lugosi, and Alexander Tsigler. Benign overfitting in linear
505 regression. *Proceedings of the National Academy of Sciences*, 117(48):30063–30070, 2020.
- 506 Mikhail Belkin, Daniel Hsu, Siyuan Ma, and Soumik Mandal. Reconciling modern machine-learning
507 practice and the classical bias–variance trade-off. *Proceedings of the National Academy of Sciences*,
508 116(32):15849–15854, 2019.
- 509 Peter J. Bickel, Ya’acov Ritov, and Alexandre B. Tsybakov. Simultaneous analysis of lasso and
510 dantzig selector. *The Annals of Statistics*, 37(4):1705–1732, 2009.
- 511 Peter Bühlmann and Sara van de Geer. *Statistics for High-Dimensional Data: Methods, Theory and
512 Applications*. Springer, 2011.
- 513 Emmanuel J. Candès and Terence Tao. The dantzig selector: Statistical estimation when p is much
514 larger than n . *The Annals of Statistics*, 35(6):2313–2351, 2007.
- 515 Venkat Chandrasekaran, Benjamin Recht, Pablo A. Parrilo, and Alan S. Willsky. The convex geometry
516 of linear inverse problems. *Foundations of Computational Mathematics*, 12(6):805–849, 2012.
- 517 Scott Shaobing Chen, David L. Donoho, and Michael A. Saunders. Atomic decomposition by basis
518 pursuit. *SIAM Review*, 43(1):129–159, 2001.
- 519 Lénaïc Chizat, Edouard Oyallon, and Francis Bach. On lazy training in differentiable programming.
520 In *Advances in Neural Information Processing Systems (NeurIPS)*, volume 32, pp. 2933–2943,
521 2019. arXiv:1812.07956.
- 522 Moustapha Cisse, Piotr Bojanowski, Edouard Grave, Yann Dauphin, and Nicolas Usunier. Parseval
523 networks: Improving robustness to adversarial examples. In *Proceedings of the 34th International
524 Conference on Machine Learning (ICML)*, volume 70 of *Proceedings of Machine Learning
525 Research*. PMLR, 2017.
- 526 Konstantin Donhauser, Nicolo Ruggeri, Stefan Stojanovic, and Fanny Yang. Fast rates for noisy
527 interpolation require rethinking the effect of inductive bias. In *International Conference on
528 Machine Learning*, pp. 5397–5428. PMLR, 2022.
- 529 David L. Donoho. Compressed sensing. *IEEE Transactions on Information Theory*, 52(4):1289–1306,
530 2006.
- 531 Gintare Karolina Dziugaite and Daniel M. Roy. Computing nonvacuous generalization bounds
532 with PAC-bayes. In *International Conference on Learning Representations (ICLR)*, 2017.
533 arXiv:1703.11008.
534
535
536
537
538
539

- 540 Bradley Efron, Trevor Hastie, Iain Johnstone, and Robert Tibshirani. Least angle regression. *The*
541 *Annals of Statistics*, 32(2):407–499, 2004.
- 542
- 543 IE Frank and JH Friedman. A statistical view of some chemometrics regression tools. *Technometrics*,
544 35(2):109–135, 1993.
- 545
- 546 Yehoram Gordon. Some inequalities for gaussian processes and applications. *Israel Journal of*
547 *Mathematics*, 50(4):265–289, 1985. doi: 10.1007/BF02764726.
- 548 Suriya Gunasekar, Prateek Jain, Daniel Soudry, Sham M. Kakade, and Nathan Srebro. Implicit
549 regularization in matrix factorization. In *Advances in Neural Information Processing Systems*
550 *(NeurIPS)*, 2017a.
- 551
- 552 Suriya Gunasekar, Blake E. Woodworth, Srinadh Bhojanapalli, Behnam Neyshabur, and Nathan
553 Srebro. Implicit regularization in matrix factorization. In *Advances in Neural Information*
554 *Processing Systems (NIPS)*, volume 30, 2017b.
- 555
- 556 Suriya Gunasekar, Daniel Soudry, Mor Nacson, and Nathan Srebro. Implicit bias of gradient
557 descent on linear convolutional networks. In *Advances in Neural Information Processing Systems*,
558 volume 31, 2018a.
- 559
- 559 Suriya Gunasekar, Blake E. Woodworth, Sham Kakade, and Nathan Srebro. Implicit bias of gradient
560 descent on linear convolutional networks. In *Advances in Neural Information Processing Systems*
561 *(NeurIPS)*, 2018b.
- 562
- 563 Trevor Hastie, Robert Tibshirani, and Martin Wainwright. *Statistical Learning with Sparsity: The*
564 *Lasso and Generalizations*. CRC Press, 2015.
- 565
- 565 Trevor Hastie, Andrea Montanari, Saharon Rosset, and Ryan J. Tibshirani. Surprises in high-
566 dimensional ridgeless least squares interpolation. *The Annals of Statistics*, 50(2):949–986, 2022a.
567 Earlier version: arXiv:1903.08560 (2019).
- 568
- 569 Trevor Hastie, Andrea Montanari, Saharon Rosset, and Ryan J Tibshirani. Surprises in high-
570 dimensional ridgeless least squares interpolation. *Proceedings of the National Academy of Sciences*,
571 119(28):e2101426119, 2022b.
- 572
- 572 Arthur E. Hoerl and Robert W. Kennard. Ridge regression: Biased estimation for nonorthogonal
573 problems. *Technometrics*, 12(1):55–67, 1970. doi: 10.1080/00401706.1970.10488634.
- 574
- 575 Stanisław Jastrzebski, Zachary Kenton, Devansh Arpit, Nicolas Ballas, Asja Fischer, Yoshua Bengio,
576 and Amos Storkey. Three factors influencing minima in SGD. *arXiv preprint arXiv:1711.04623*,
577 2017. URL <https://arxiv.org/abs/1711.04623>.
- 578
- 578 Ziwei Ji and Matus Telgarsky. Gradient descent aligns the layers of deep linear networks. In
579 *International Conference on Learning Representations (ICLR)*, 2019a. arXiv:1810.02032.
- 580
- 581 Ziwei Ji and Matus Telgarsky. Gradient descent aligns the layers of deep linear networks. In
582 *International Conference on Learning Representations (ICLR)*, 2019b.
- 583
- 583 Keith Knight and Wenjiang Fu. Asymptotics for lasso-type estimators. *The Annals of Statistics*, 28
584 (5):1356–1378, 2000.
- 585
- 586 Frederic Koehler, Lijia Zhou, Danica J. Sutherland, and Nathan Srebro. Uniform convergence
587 of interpolators: Gaussian width, norm bounds and benign overfitting. In *Advances in Neural*
588 *Information Processing Systems (NeurIPS)*, 2021. arXiv:2106.09276.
- 589
- 590 Kaifeng Lyu and Jian Li. Gradient descent maximizes the margin of homogeneous neural networks.
591 In *International Conference on Learning Representations (ICLR)*, 2020. arXiv:1906.05890.
- 592
- 592 Stephan Mandt, Matthew D. Hoffman, and David M. Blei. Stochastic gradient descent as approximate
593 bayesian inference. *Journal of Machine Learning Research*, 18(134):1–35, 2017. URL <https://www.jmlr.org/papers/volume18/17-214/17-214.pdf>.

- 594 Takeru Miyato, Toshiki Kataoka, Masanori Koyama, and Yuichi Yoshida. Spectral normalization for
595 generative adversarial networks. In *International Conference on Learning Representations (ICLR)*,
596 2018.
- 597
- 598 Vidya Muthukumar, Kai Roth, Yuxin Chen, Anders Rørddam Jensen, Aditya Guntuboyina, Kannan
599 Ramchandran, and Peter L. Bartlett. Harmless interpolation of noisy data in regression. *Proceedings*
600 *of the National Academy of Sciences (PNAS)*, 118(44):e2102421118, 2021.
- 601
- 602 Preetum Nakkiran, Gal Kaplun, Yamini Bansal, Tristan Yang, Boaz Barak, and Ilya Sutskever. Deep
603 double descent: Where bigger models and more data hurt. *arXiv preprint arXiv:1912.02292*,
604 2020a.
- 605
- 606 Preetum Nakkiran, Gal Kaplun, Yamini Bansal, Tristan Yang, Boaz Barak, and Ilya Sutskever. Deep
607 double descent: Where bigger models and more data hurt. *arXiv preprint arXiv:1912.02292*,
608 2020b. ICLR 2020 version available.
- 609
- 610 Preetum Nakkiran, Gal Kaplun, Yamini Bansal, Tristan Yang, Boaz Barak, and Ilya Sutskever. Deep
611 double descent: Where bigger models and more data still hurt. *Journal of Statistical Mechanics:
Theory and Experiment*, (12):124003, 2021.
- 612
- 613 Behnam Neyshabur, Ruslan Salakhutdinov, and Nathan Srebro. Path-sgd: Path-normalized optimiza-
614 tion in deep neural networks. In *Advances in Neural Information Processing Systems*, volume 28,
615 2015a.
- 616
- 617 Behnam Neyshabur, Ryota Tomioka, and Nathan Srebro. Norm-based capacity control in neural
618 networks. In *Proceedings of the 28th Annual Conference on Learning Theory (COLT)*, 2015b.
- 619
- 620 Behnam Neyshabur, Ryota Tomioka, and Nathan Srebro. Norm-based capacity control in neural
621 networks. In *Proceedings of the 28th Conference on Learning Theory (COLT)*, volume 40 of
622 *Proceedings of Machine Learning Research*, pp. 1–26. PMLR, 2015c.
- 623
- 624 Andrew M. Saxe, James L. McClelland, and Surya Ganguli. Exact solutions to the nonlinear
625 dynamics of learning in deep linear neural networks. In *International Conference on Learning
626 Representations (ICLR)*, 2014a. arXiv:1312.6120.
- 627
- 628 Andrew M Saxe, James L McClelland, and Surya Ganguli. Exact solutions to the nonlinear dy-
629 namics of learning in deep linear neural networks. In *International Conference on Learning
630 Representations (ICLR)*, 2014b.
- 631
- 632 Samuel L. Smith, Pieter-Jan Kindermans, Chris Ying, and Quoc V. Le. Don’t decay the learning rate,
633 increase the batch size. In *International Conference on Learning Representations (ICLR)*, 2018.
634 URL <https://openreview.net/forum?id=B1Yy1BxCZ>.
- 635
- 636 Daniel Soudry, Elad Hoffer, Mor Shpigel Nacson, Suriya Gunasekar, and Nathan Srebro. The implicit
637 bias of gradient descent on separable data. *Journal of Machine Learning Research*, 19(70):1–57,
638 2018. URL <https://www.jmlr.org/papers/volume19/18-188/18-188.pdf>.
- 639
- 640 Kyrill Thrampoulidis, Emre Oymak, and Babak Hassibi. The convex gaussian min–max theorem,
641 2015. URL <https://arxiv.org/abs/1506.07868>.
- 642
- 643 Robert Tibshirani. Regression shrinkage and selection via the lasso. *Journal of the Royal Statistical
644 Society: Series B*, 58(1):267–288, 1996.
- 645
- 646 Joel A. Tropp. An introduction to matrix concentration inequalities. *Foundations and Trends in
647 Machine Learning*, 8(1-2):1–230, 2015.
- 648
- 649 Roman Vershynin. *High-Dimensional Probability: An Introduction with Applications in Data Science*.
650 Cambridge University Press, 2018.
- 651
- 652 Martin J. Wainwright. *High-Dimensional Statistics: A Non-Asymptotic Viewpoint*. Cambridge
653 University Press, 2019.

648 Blake Woodworth, Suriya Gunasekar, Jason D. Lee, Edward Moroshko, Pedro Savarese, Itay Golan,
649 Daniel Soudry, and Nathan Srebro. Kernel and rich regimes in overparametrized models. In
650 *Proceedings of the 33rd Conference on Learning Theory (COLT)*, volume 125 of *Proceedings of*
651 *Machine Learning Research*, pp. 3635–3673. PMLR, 2020.

652
653 Sho Yaida. Fluctuation–dissipation relations for stochastic gradient descent. *arXiv preprint*
654 *arXiv:1810.00004*, 2018. URL <https://arxiv.org/abs/1810.00004>.

655
656 Yuichi Yoshida and Takeru Miyato. Spectral norm regularization for improving the generalizability
657 of deep learning. *arXiv preprint arXiv:1705.10941*, 2017.

658 Chiyuan Zhang, Samy Bengio, Moritz Hardt, Benjamin Recht, and Oriol Vinyals. Understand-
659 ing deep learning requires rethinking generalization. In *International Conference on Learning*
660 *Representations (ICLR)*, 2017.

661
662 Hui Zou. The adaptive lasso and its oracle properties. *Journal of the American Statistical Association*,
663 101(476):1418–1429, 2006.

664
665 Hui Zou and Trevor Hastie. Regularization and variable selection via the elastic net. *Journal of the*
666 *Royal Statistical Society: Series B*, 67(2):301–320, 2005.

667 668 A MINIMUM- ℓ_p INTERPOLATOR WITH s -SPARSE GROUND TRUTH

669
670 For completeness, we first introduce again the mathematical settings and restate our main theorem.
671 We study $p \in (1, 2]$, set $q = \frac{p}{p-1} \in [2, \infty)$, and let $r \in [1, p]$. Dimensions $n, d \in \mathbb{N}$ with $d \geq n$. All
672 $X \in \mathbb{R}^{n \times d}$ have i.i.d. $\mathcal{N}(0, 1)$ entries; columns are $X_{:,j}$. Noise $\xi \sim \mathcal{N}(0, \sigma^2 I_n)$, independent of X .
673 The signal $w^* \in \mathbb{R}^d$ is s -sparse with support $S \subset [d]$, $|S| = s$; we write w_S^* for its nonzeros. The
674 response is $Y := Xw^* + \xi$. The min- ℓ_p interpolator

$$675 \hat{w}_p \in \arg \min \{ \|w\|_p : Xw = Y \} \quad (p > 1 \text{ ensures uniqueness})$$

676
677 is our object of interest. Shorthands:

$$678 \tau_s^2 := \|w^*\|_2^2 + \sigma^2, \quad W_q := \|w^*\|_q^q = \sum_{j \in S} |w_j^*|^q.$$

679
680 *Remark A.1* (Standing assumptions and probability shorthand). We work in the proportional regime

$$681 \frac{d}{n} \rightarrow \kappa \in (1, \infty), \quad \kappa_{\text{bulk}} := \liminf_{n \rightarrow \infty} \frac{d-s}{n} \in (0, \infty),$$

682
683 so $d-s = \Theta(n)$ and $s = O(n)$ (we do not require $s \leq n$). Unless stated otherwise, all hidden
684 constants depend only on $(p, \kappa_{\text{bulk}})$ (and on r when relevant), and “w.h.p.” means probability at
685 least $1 - Ce^{-cn} - 2d^{-\gamma}$. When we simplify remainders using $s \leq n$ (e.g., $\sqrt{sn} + s \rightsquigarrow \sqrt{sn}$), the
686 corresponding $s > n$ form is always available and does not affect any \asymp conclusions in Theorem A.2.

687
688 *On proportionality.* The assumption $d/n \rightarrow \kappa$ is only for cleanliness of exposition and to keep
689 constants tidy; it is not essential to the argument. All places where it enters (e.g., the bulk ℓ_t
690 embedding and the uniform column–norm control) can be run under the weaker—and often more
691 realistic—conditions

$$692 \liminf_{n \rightarrow \infty} \frac{d-s}{n} = \kappa_{\text{bulk}} > 0, \quad \log d = o(n), \quad s = O(n).$$

693
694 In particular, our proofs and conclusions (same exponents in n , the threshold $r_* = 2(p-1)$, and the
695 high-probability events) remain valid even in “larger” aspect-ratio regimes (including $d/n \rightarrow \infty$)
696 as long as $\log d = o(n)$ and the bulk density is bounded below. Under these weaker assumptions
697 the hidden constants are uniform in (n, d, s) and depend only on $(p, r, \kappa_{\text{bulk}})$ (and on a fixed upper
698 bound for s/n if desired), so no changes to the proofs are needed.

A.1 MAIN THEOREM

Theorem A.2 (Theorem 3.1 restated). *Fix $p \in (1, 2]$, $q = \frac{p}{p-1}$, $r \in [1, p]$, and suppose $\liminf(d - s)/n = \kappa_{\text{bulk}} > 0$ while $d/n \rightarrow \kappa \in (1, \infty)$. Then, w.h.p.,*

$$\|\widehat{w}_p\|_r \asymp \max \left\{ \underbrace{t_*^{q-1} n^{q-1} \|w^*\|_{(q-1)r}^{q-1}}_{\text{spike main } (S)}, \underbrace{(d-s)^{1/r} (t_* \tau_s \sqrt{n})^{q-1}}_{\text{bulk } (S^c)}, \underbrace{s^{\max\{1/r, (q-1)/2\}} (t_* \tau_s \sqrt{n})^{q-1}}_{\text{spike remainder}} \right\}. \quad (6)$$

where the ray scale t_* satisfies

$$t_*^{q-1} \asymp \frac{\|Y\|_2^2}{\|X^\top Y\|_q^q} \asymp \frac{\tau_s^2 n}{n^q W_q + (d-s) m_q \tau_s^q n^{q/2} + O(\tau_s^q (s n^{q/2} + s^{1+q/2}))} \quad \text{w.h.p.} \quad (7)$$

with $m_t := \mathbb{E}|Z|^t$ and $Z \sim \mathcal{N}(0, 1)$. Define the dual-transition scale

$$n_* \asymp \left(\kappa_{\text{bulk}} \frac{\tau_s^q}{W_q} \right)^{\frac{2}{q-2}}. \quad (8)$$

Then, w.h.p., the following asymptotic simplifications hold:

Dual spike-dominated $n \gg n_*$.

$$\|\widehat{w}_p\|_r \asymp \begin{cases} \frac{\tau_s^{q+1}}{W_q} n^{\frac{1}{r} - \frac{1}{2(p-1)}}, & r \leq 2(p-1), \\ \frac{\tau_s^2}{W_q} \|w^*\|_{(q-1)r}^{q-1}, & r > 2(p-1). \end{cases} \quad (9)$$

Dual bulk-dominated $n \ll n_*$.

$$\|\widehat{w}_p\|_r \asymp \max \left\{ \kappa_{\text{bulk}}^{\frac{1}{r}-1} \tau_s n^{\frac{1}{r}-\frac{1}{2}}, \kappa_{\text{bulk}}^{-1} \tau_s^{2-q} \|w^*\|_{(q-1)r}^{q-1} n^{\frac{q}{2}-1}, \kappa_{\text{bulk}}^{-1} \tau_s s^{\max\{1/r, (q-1)/2\}} n^{-1/2} \right\}. \quad (10)$$

(Equivalently, using $d-s \asymp \kappa_{\text{bulk}} n$, the third term can be written as $\frac{\tau_s}{d-s} s^{\max\{1/r, (q-1)/2\}} \sqrt{n}$.)

Remark A.3 (When the third term is absorbed). If $r \leq 2(p-1)$ and $s \leq C(d-s)$ for an absolute constant C , then the third term in equation 10 is dominated by the first term (their ratio is $\lesssim (s/(d-s))^{1/r}$). In that case, equation 10 reduces to the two-term maximum

$$\|\widehat{w}_p\|_r \asymp \max \left\{ \kappa_{\text{bulk}}^{\frac{1}{r}-1} \tau_s n^{\frac{1}{r}-\frac{1}{2}}, \kappa_{\text{bulk}}^{-1} \tau_s^{2-q} \|w^*\|_{(q-1)r}^{q-1} n^{\frac{q}{2}-1} \right\}.$$

For $r > 2(p-1)$, no uniform absorption holds in general; the third term can dominate when $\|w^*\|_{(q-1)r}$ is small relative to τ_s .

Remark A.4 (Boundary $p = 2$). At $p = 2$ (so $q = 2$) the exponent in equation 8 diverges. In the proportional- d regime ($d/n \rightarrow \kappa$) there is no n -driven transition; the relative sizes of the spike and bulk are constant-level. In the finite- d regime (below) a concrete n -threshold does exist because $(d-s)$ does not scale with n .

A.2 KEY LEMMAS AND PROOF OUTLINE

Roadmap. We prove Theorem 3.1 by (i) reducing the min- ℓ_p interpolator to a dual maximization and restricting the dual to the one-dimensional ray $\lambda = tY$, (ii) decomposing $\|X^\top Y\|_q^q$ into a spike term ($j \in S$) and a bulk term ($j \notin S$), and (iii) converting back to the primal via the KKT map, which raises correlations to the power $(q-1)$ and produces the three-term maximum in equation 6. The elbow at $r = 2(p-1)$ comes from the sign of $1/r - 1/(2(p-1))$, i.e., exactly whether the bulk-type contribution grows or plateaus in the spike-dominated regime. We work on a single high-probability event \mathcal{E} (defined below) on which all concentration facts hold simultaneously.

Global event. Let \mathcal{E} be the intersection of the column-norm, spectral, and bulk ℓ_t events from Lemmas A.5, A.8, and A.11. Then $\mathbb{P}(\mathcal{E}) \geq 1 - Ce^{-cn} - 2d^{-\gamma}$. All bounds below hold on \mathcal{E} .

756 A.2.1 DUAL PROBLEM AND KKT

757 We briefly review Lagrangian duality for convex programs with equality constraints and then apply it
758 to the minimum- ℓ_p interpolator.

759 **Primal problem and feasibility.** We consider

$$760 \min_{w \in \mathbb{R}^d} f(w) \quad \text{subject to} \quad Xw = Y, \quad \text{with} \quad f(w) := \frac{1}{p} \|w\|_p^p,$$

761 where $p \in (1, 2]$. Since $X \in \mathbb{R}^{n \times d}$ has full row rank n a.s. (for $d \geq n$ with i.i.d. $\mathcal{N}(0, 1)$ entries),
762 the affine constraint set $\{w : Xw = Y\}$ is nonempty for every $Y \in \mathbb{R}^n$. The objective f is proper,
763 closed, and *strictly convex* for $p > 1$ (indeed uniformly convex). Therefore, the primal minimizer \hat{w}_p
764 exists and is unique. Introduce a Lagrange multiplier $\lambda \in \mathbb{R}^n$ for the equality constraint, and form
765 the Lagrangian

$$766 \mathcal{L}(w, \lambda) := f(w) + \langle \lambda, Y - Xw \rangle.$$

767 The *dual function* is obtained by minimizing the Lagrangian over w :

$$768 g(\lambda) := \inf_{w \in \mathbb{R}^d} \left\{ f(w) - \langle X^\top \lambda, w \rangle \right\} + \langle Y, \lambda \rangle = -f^*(X^\top \lambda) + \langle Y, \lambda \rangle,$$

769 where f^* is the convex conjugate of f :

$$770 f^*(z) := \sup_{w \in \mathbb{R}^d} \left\{ \langle z, w \rangle - f(w) \right\}.$$

771 Since $f(w) = \sum_{i=1}^d |w_i|^p/p$ is separable, its conjugate is $f^*(z) = \sum_{i=1}^d |z_i|^q/q = (1/q) \|z\|_q^q$,
772 where $q = p/(p-1)$ is the Hölder conjugate of p . Indeed, for each coordinate

$$773 \sup_{t \in \mathbb{R}} \{ zt - |t|^p/p \}$$

774 is achieved at $t = \text{sgn}(z)|z|^{q-1}$, with optimal value $|z|^q/q$. Therefore the dual function is

$$775 g(\lambda) = \langle Y, \lambda \rangle - \frac{1}{q} \|X^\top \lambda\|_q^q.$$

776 **Dual problem and strong duality.** The *dual problem* is $\max_{\lambda \in \mathbb{R}^n} g(\lambda)$, i.e.

$$777 \max_{\lambda \in \mathbb{R}^n} D(\lambda), \quad D(\lambda) := \langle Y, \lambda \rangle - \frac{1}{q} \|X^\top \lambda\|_q^q.$$

778 This is a concave maximization problem (a smooth concave objective with no constraints). Strong
779 duality holds in our setting by standard convex duality: the primal is convex, the constraint is affine,
780 and feasibility holds (Slater's condition for equalities reduces to existence of a feasible point). Hence

$$781 \min_{w: Xw=Y} f(w) = \max_{\lambda \in \mathbb{R}^n} D(\lambda).$$

782 For convex programs with equality constraints, the Karush-Kuhn-Tucker (KKT) conditions are
783 necessary and sufficient for optimality under strong duality. They read:

$$784 \text{(primal feasibility)} \quad Xw = Y, \quad \text{(stationarity)} \quad 0 \in \partial f(w) - X^\top \lambda.$$

785 Because $p > 1$, f is differentiable on \mathbb{R}^d with gradient

$$786 \nabla f(w) = |w|^{p-2} \odot w = \text{sgn}(w) \odot |w|^{p-1},$$

787 so the subdifferential collapses to the singleton $\{\nabla f(w)\}$ and stationarity is

$$788 \nabla f(w) = X^\top \lambda.$$

789 At any primal-dual optimum (\hat{w}_p, λ^*) we therefore have

$$790 X\hat{w}_p = Y, \quad X^\top \lambda^* = \nabla f(\hat{w}_p) = |\hat{w}_p|^{p-2} \odot \hat{w}_p. \quad (11)$$

The conjugate f^* is differentiable with $\nabla f^*(z) = |z|^{q-2} \odot z = \text{sgn}(z) \odot |z|^{q-1}$, and the gradients are mutual inverses: $\nabla f^* = (\nabla f)^{-1}$. Applying ∇f^* to both sides of $X^\top \lambda^* = \nabla f(\widehat{w}_p)$ gives the *coordinatewise KKT map*:

$$\widehat{w}_{p,i} = (\nabla f^*(X^\top \lambda^*))_i = \text{sgn}((X^\top \lambda^*)_i) |(X^\top \lambda^*)_i|^{q-1}. \quad (12)$$

Equivalently, $\widehat{w}_p = \nabla f^*(X^\top \lambda^*)$ and $X^\top \lambda^* = \nabla f(\widehat{w}_p)$.

At optimality, Fenchel–Young gives $f(\widehat{w}_p) + f^*(X^\top \lambda^*) = \langle \widehat{w}_p, X^\top \lambda^* \rangle$. Using $X \widehat{w}_p = Y$ and the expressions for f and f^* yields the identities

$$\|X^\top \lambda^*\|_q^q = \|\widehat{w}_p\|_p^p = \langle Y, \lambda^* \rangle. \quad (13)$$

These will be used repeatedly to pass between the primal and dual scales.

The affine set $\{w : Xw = Y\}$ is a translate of $\ker(X)$, and minimizing $\|w\|_p$ over it finds the point where a scaled ℓ_p ball first touches this affine subspace. The *outer normal* to the ℓ_p ball at the touching point is $\nabla f(\widehat{w}_p) = |\widehat{w}_p|^{p-2} \odot \widehat{w}_p$, and the KKT condition $X^\top \lambda^* = \nabla f(\widehat{w}_p)$ says that this normal lies in the row space of X . In coordinates, equation 12 shows that each coefficient of \widehat{w}_p is a $(q-1)$ -power of the correlation between the corresponding feature column $X_{:,i}$ and the dual multiplier λ^* .

Specialization at $p = 2$. When $p = q = 2$, $\nabla f(w) = w$ and $\nabla f^*(z) = z$. Then equation 11 reads $X^\top \lambda^* = \widehat{w}_2$ and $X \widehat{w}_2 = Y$, which implies $XX^\top \lambda^* = Y$ and hence $\lambda^* = (XX^\top)^{-1}Y$. Therefore

$$\widehat{w}_2 = X^\top (XX^\top)^{-1}Y = X^+Y,$$

the minimum- ℓ_2 (Moore–Penrose) interpolator. For $p \neq 2$ the same structure persists but the map $z \mapsto \nabla f^*(z) = \text{sgn}(z)|z|^{q-1}$ is nonlinear, which is exactly what introduces the $(q-1)$ -power in the subsequent spike/bulk analysis.

Why duality helps here. The dual objective

$$D(\lambda) = \langle Y, \lambda \rangle - \frac{1}{q} \|X^\top \lambda\|_q^q$$

separates the *data dependence* (linear in Y) from the *feature geometry* through $\|X^\top \lambda\|_q^q$. In our Gaussian design, the d coordinates of $X^\top \lambda$ split naturally into the s *spikes* (indices in S) and the $(d-s)$ *bulk*, for which we have precise ℓ_t concentration (Lemmas A.8 and A.11). Because D is homogeneous in a simple way along the *ray* $\lambda = tY$,

$$D(t) = t\|Y\|_2^2 - \frac{t^q}{q} \|X^\top Y\|_q^q,$$

we will use the *ray scale* t_* (the maximizer of $D(tY)$) as a canonical scale for λ^* ; Lemma A.12 shows $\|\lambda^*\|_2 \asymp t_* \|Y\|_2$ and provides blockwise controls on $X^\top \lambda^*$. The KKT map equation 12 then converts $\|X^\top \lambda^*\|_{(q-1)r}^{q-1}$ into $\|\widehat{w}_p\|_r$, via $\| |u|^{\odot(q-1)} \|_r = \|u\|_{(q-1)r}^{q-1}$, which is the backbone of the unified bound equation 6.

A.2.2 CONCENTRATION FOR Y AND $X^\top Y$.

Let $m_t := \mathbb{E}|Z|^t$ for $Z \sim \mathcal{N}(0, 1)$.

Lemma A.5 (norm of Y). *With $Y := Xw^* + \xi$ and $\tau_s^2 := \|w^*\|_2^2 + \sigma^2$, we have*

$$\|Y\|_2^2 = \tau_s^2 n (1 + o(1)) \quad \text{w.h.p.}$$

More quantitatively, for every $t > 0$,

$$\Pr\left(\left|\|Y\|_2^2 - \tau_s^2 n\right| \geq 2\tau_s^2 \sqrt{nt} + 2\tau_s^2 t\right) \leq e^{-t}.$$

Proof. For each row $i \in [n]$, $(Xw^*)_i = \sum_{j=1}^d w_j^* X_{i,j}$ is $\mathcal{N}(0, \|w^*\|_2^2)$ since the $X_{i,j}$ are i.i.d. $\mathcal{N}(0, 1)$ and independent in j ; the rows are independent. The noise $\xi_i \sim \mathcal{N}(0, \sigma^2)$ is independent of X , hence

$$Y \sim \mathcal{N}(0, \tau_s^2 I_n), \quad \frac{\|Y\|_2^2}{\tau_s^2} \sim \chi_n^2.$$

The standard Laurent–Massart inequality for χ_n^2 variables (see e.g. *Ann. Statist.* 2000) yields, for all $t > 0$,

$$\Pr\left(\|Y\|_2^2 - \tau_s^2 n \geq 2\tau_s^2 \sqrt{nt} + 2\tau_s^2 t\right) \leq e^{-t}, \quad \Pr\left(\tau_s^2 n - \|Y\|_2^2 \geq 2\tau_s^2 \sqrt{nt}\right) \leq e^{-t}.$$

Taking $t = cn$ gives $\|Y\|_2^2 = \tau_s^2 n(1 + o(1))$ with probability at least $1 - e^{-cn}$. \square

Lemma A.6 (bulk coordinates of $X^\top Y$). *Conditional on Y , for each $j \notin S$,*

$$\langle X_{:,j}, Y \rangle \sim \mathcal{N}(0, \|Y\|_2^2),$$

and the variables $\{\langle X_{:,j}, Y \rangle\}_{j \notin S}$ are i.i.d. given Y . Consequently, with $m_q := \mathbb{E}|Z|^q$ for $Z \sim \mathcal{N}(0, 1)$,

$$\sum_{j \notin S} |\langle X_{:,j}, Y \rangle|^q = (d-s) m_q \|Y\|_2^q (1 + o(1)) \asymp (d-s) \tau_s^q n^{q/2} \quad \text{w.h.p.}$$

Quantitatively, for any fixed $q \geq 2$ and any $u \in (0, 1)$,

$$\Pr\left(\left|\frac{1}{d-s} \sum_{j \notin S} \frac{|\langle X_{:,j}, Y \rangle|^q}{\|Y\|_2^q} - m_q\right| > u \mid Y\right) \leq 2 \exp(-c_q (d-s) \min\{u^2, u\}).$$

Proof. Fix $j \notin S$. The vector $X_{:,j} \sim \mathcal{N}(0, I_n)$ is independent of $(X_{:,k})_{k \in S}$ and ξ , hence independent of $Y = Xw^* + \xi$, which depends only on the columns indexed by S and on ξ . Conditional on Y , by rotational invariance,

$$\langle X_{:,j}, Y \rangle \stackrel{d}{=} \|Y\|_2 Z_j, \quad Z_j \sim \mathcal{N}(0, 1),$$

and independence across $j \notin S$ follows from the independence of the columns $\{X_{:,j}\}_{j \notin S}$.

Let $W_j := |Z_j|^q - m_q$. Then W_j are i.i.d. mean-zero and sub-exponential with $\|W_j\|_{\psi_1} \leq C_q$ (a standard fact for polynomial functions of a standard Gaussian, see, e.g., Vershynin’s *High-Dimensional Probability*). Bernstein’s inequality for sub-exponential variables gives, for any $u > 0$,

$$\Pr\left(\left|\frac{1}{d-s} \sum_{j \notin S} W_j\right| > u \mid Y\right) \leq 2 \exp(-c_q (d-s) \min\{u^2, u\}).$$

Multiplying back by $\|Y\|_2^q$ proves the conditional concentration display. Since $(d-s) \asymp n$ by assumption, taking $u \rightarrow 0$ slowly (e.g. $u = \sqrt{(\log n)/(d-s)}$) yields

$$\sum_{j \notin S} |\langle X_{:,j}, Y \rangle|^q = (d-s) m_q \|Y\|_2^q (1 + o(1))$$

with probability at least $1 - Ce^{-c(d-s)} \geq 1 - Ce^{-cn}$ (unconditionally). Finally, Lemma A.5 implies $\|Y\|_2^q \asymp \tau_s^q n^{q/2}$ w.h.p., completing the proof. \square

Lemma A.7 (Signal block with integrated uniform column-norm control). *Let $X \in \mathbb{R}^{n \times d}$ have i.i.d. $\mathcal{N}(0, 1)$ entries, $S \subset [d]$ with $|S| = s$, and $Y := Xw^* + \xi$ where $\xi \sim \mathcal{N}(0, \sigma^2 I_n)$ is independent of X . Write $\tau_s^2 := \|w^*\|_2^2 + \sigma^2$ and $W_q := \sum_{j \in S} |w_j^*|^q$ for $q \geq 2$.*

(i) **Uniform column-norm concentration (over all d columns).** *There exists a universal $c \in (0, 1)$ such that, for every $u > 0$,*

$$\Pr\left(\max_{1 \leq j \leq d} \left|\frac{\|X_{:,j}\|_2^2}{n} - 1\right| > u\right) \leq 2d \exp(-cn \min\{u^2, u\}). \quad (14)$$

In particular, for any fixed $\gamma > 0$,

$$u_n := \sqrt{\frac{(1+\gamma) \log d}{cn}} \in (0, 1] \text{ for } n \text{ large, and } \Pr\left(\max_{j \leq d} \left|\frac{\|X_{:,j}\|_2^2}{n} - 1\right| > u_n\right) \leq 2d^{-\gamma}.$$

(ii) **Spike decomposition, explicit definition of ζ_j , and q -moment bound.** For each $j \in S$, define

$$\zeta_j := \left\langle X_{:,j}, \sum_{k \in S \setminus \{j\}} w_k^* X_{:,k} + \xi \right\rangle. \quad (15)$$

Then

$$\langle X_{:,j}, Y \rangle = w_j^* \|X_{:,j}\|_2^2 + \zeta_j. \quad (16)$$

Moreover, for each fixed $j \in S$,

$$\mathbb{E}[\zeta_j | X_{:,j}] = 0, \quad \text{Var}(\zeta_j | X_{:,j}) = (\tau_s^2 - (w_j^*)^2) \|X_{:,j}\|_2^2, \quad (17)$$

and, conditional on $X_{:,j}$,

$$\zeta_j \sim \mathcal{N}\left(0, (\tau_s^2 - (w_j^*)^2) \|X_{:,j}\|_2^2\right). \quad (18)$$

(We do not assume or use independence between the collection $\{\zeta_j\}_{j \in S}$; the proof below controls their aggregate via operator-norm bounds.) Consequently, with probability at least $1 - 2d^{-\gamma} - Ce^{-c\sqrt{ns}}$,

$$\sum_{j \in S} |\langle X_{:,j}, Y \rangle|^q = n^q W_q (1 + o(1)) + O\left(\tau_s^q (s n^{q/2} + s^{1+q/2})\right), \quad (19)$$

where the $o(1)$ (as $n \rightarrow \infty$) and the hidden constants depend only on q (hence on p). The mixed term $\sum_{j \in S} |a_j|^{q-1} |b_j|$ is absorbed by Young's inequality into the $n^q W_q$ leading term and the $\sum_{j \in S} |b_j|^q$ remainder, with a harmless change in constants.

Proof. Part (i): For a fixed j , $Z_j := \|X_{:,j}\|_2^2 \stackrel{d}{=} \chi_n^2$. By Laurent–Massart, for all $x \geq 0$,

$$\Pr(Z_j - n \geq 2\sqrt{nx} + 2x) \leq e^{-x}, \quad \Pr(n - Z_j \geq 2\sqrt{nx}) \leq e^{-x}.$$

A standard choice of x (see derivation below) yields the Bernstein-type bound

$$\Pr\left(\left|\frac{Z_j}{n} - 1\right| > u\right) \leq 2 \exp(-cn \min\{u^2, u\}) \quad (\forall u > 0), \quad (20)$$

for some universal $c \in (0, 1)$. Summing over $j = 1, \dots, d$ gives equation 14. For the explicit choice $u_n = \sqrt{(1 + \gamma) \log d / (cn)} \leq 1$ (for n large),

$$2d \exp(-cnu_n^2) = 2d \exp(-(1 + \gamma) \log d) = 2d^{-\gamma}.$$

(Derivation of the Bernstein form): If $u \in (0, 1]$, choose $x = \frac{u^2 n}{8}$ to get $\Pr(Z_j - n \geq un) \leq e^{-\frac{u^2 n}{8}}$ and $x = \frac{u^2 n}{4}$ to get $\Pr(n - Z_j \geq un) \leq e^{-\frac{u^2 n}{4}}$. If $u \geq 1$, choose $x = c_0 un$ (e.g. $c_0 = 1/16$) so that $2\sqrt{nx} + 2x \leq un$, hence $\Pr(Z_j - n \geq un) \leq e^{-c_0 un}$. Combine and absorb constants into c .

Part (ii): The decomposition equation 16 is immediate from

$$Y = w_j^* X_{:,j} + \sum_{k \in S \setminus \{j\}} w_k^* X_{:,k} + \xi,$$

and independence/rotational invariance: conditional on $X_{:,j}$, $\langle X_{:,j}, X_{:,k} \rangle \sim \mathcal{N}(0, \|X_{:,j}\|_2^2)$ for $k \neq j$ and $\langle X_{:,j}, \xi \rangle \sim \mathcal{N}(0, \sigma^2 \|X_{:,j}\|_2^2)$, all independent. Let $a_j := w_j^* \|X_{:,j}\|_2^2$ and $b_j := \zeta_j$ so that $\langle X_{:,j}, Y \rangle = a_j + b_j$. We show:

$$\sum_{j \in S} |a_j|^q = n^q W_q (1 + o(1)) \quad \text{and} \quad \sum_{j \in S} |b_j|^q \lesssim s \tau_s^q n^{q/2},$$

with the stated probability. Conditioned on the event from (i) with $u = u_n = o(1)$,

$$\max_{1 \leq j \leq d} \left| \frac{\|X_{:,j}\|_2^2}{n} - 1 \right| \leq u_n,$$

and by a mean-value bound, $\|X_{:,j}\|_2^{2q} = n^q (1 + O(u_n))$ uniformly in j . Hence

$$\sum_{j \in S} |a_j|^q = \sum_{j \in S} |w_j^*|^q \|X_{:,j}\|_2^{2q} = n^q \sum_{j \in S} |w_j^*|^q (1 + O(u_n)) = n^q W_q (1 + o(1)).$$

For any index set $T \subset [d]$, we write $X_{:,T} \in \mathbb{R}^{n \times |T|}$ for the submatrix formed by the columns $\{X_{:,j} : j \in T\}$. When convenient we abbreviate $X_{:,T}$ as X_T . For a vector $w \in \mathbb{R}^d$, w_T denotes its restriction to T , and T^c the complement of T in $[d]$. Let $G := X_S^\top X_S$ and $D := \text{diag}(\|X_{:,j}\|_2^2)_{j \in S}$. Then

$$b = (b_j)_{j \in S} = (G - D)w_S^* + X_S^\top \xi.$$

We bound $\|b\|_2$ and then pass to ℓ_q . Recall $b = (G - D)w_S^* + X_S^\top \xi$, where $G := X_S^\top X_S \in \mathbb{R}^{s \times s}$ and $D := \text{diag}(\|X_{:,j}\|_2^2)_{j \in S}$.

Bound on $\|(G - D)w_S^*\|_2$. We have

$$\|(G - D)w_S^*\|_2 \leq \|G - D\|_{\text{op}} \|w^*\|_2 \leq (\|G - nI_s\|_{\text{op}} + \|D - nI_s\|_{\text{op}}) \|w^*\|_2. \quad (21)$$

Singular-value bound for $G - nI_s$. Let $s_{\max}(X_S)$ and $s_{\min}(X_S)$ denote the largest and smallest singular values of X_S . By the standard Gaussian singular-value concentration (see Vershynin, *High-Dimensional Probability*, Thm. 4.6.1), for any $t \geq 0$,

$$\mathbb{P}\left(s_{\max}(X_S) \leq \sqrt{n} + \sqrt{s} + t, \quad s_{\min}(X_S) \geq \sqrt{n} - \sqrt{s} - t\right) \geq 1 - 2e^{-t^2/2}. \quad (22)$$

Conditioned on this event,

$$\begin{aligned} \|G - nI_s\|_{\text{op}} &= \max\{s_{\max}(X_S)^2 - n, n - s_{\min}(X_S)^2\} \\ &\leq (\sqrt{n} + \sqrt{s} + t)^2 - n \vee n - (\sqrt{n} - \sqrt{s} - t)^2 \\ &\leq s + 2\sqrt{ns} + 2t(\sqrt{n} + \sqrt{s}) + t^2. \end{aligned} \quad (23)$$

Choosing $t = \sqrt{s}$ in equation 22–equation 23 yields, with probability at least $1 - 2e^{-s/2}$,

$$\|G - nI_s\|_{\text{op}} \leq s + 2\sqrt{ns} + 2\sqrt{s}(\sqrt{n} + \sqrt{s}) + s \leq 4\sqrt{ns} + 4s. \quad (24)$$

Diagonal bound for $D - nI_s$. By the single-column deviation bound equation 20, for any $u > 0$ and any $j \in S$,

$$\Pr\left(\left|\frac{\|X_{:,j}\|_2^2}{n} - 1\right| > u\right) \leq 2\exp(-cn \min\{u^2, u\}).$$

Union-bounding this over the s indices $j \in S$ and taking

$$u_S := \sqrt{\frac{s}{n}}, \quad (25)$$

we obtain

$$\mathbb{P}\left(\max_{j \in S} \left|\frac{\|X_{:,j}\|_2^2}{n} - 1\right| > u_S\right) \leq \begin{cases} C e^{-cs}, & s \leq n, \\ C e^{-c'\sqrt{ns}}, & s > n. \end{cases} \quad (26)$$

hence, on this event,

$$\|D - nI_s\|_{\text{op}} = \max_{j \in S} |\|X_{:,j}\|_2^2 - n| \leq nu_S = \sqrt{ns}. \quad (27)$$

Combining equation 21, equation 24, and equation 27, we arrive at

$$\|(G - D)w_S^*\|_2 \leq (4\sqrt{ns} + 4s + \sqrt{ns}) \|w^*\|_2 \leq (5\sqrt{ns} + 4s) \|w^*\|_2, \quad (28)$$

with probability at least $1 - 2e^{-s/2} - Ce^{-c'\sqrt{ns}}$.

Now we bound $\|X_S^\top \xi\|_2$. Conditionally on X_S , the vector $X_S^\top \xi$ is Gaussian with covariance

$$\Sigma := \text{Var}(X_S^\top \xi | X_S) = \sigma^2 G.$$

Write the eigenvalues of G as $\mu_1, \dots, \mu_s \geq 0$. Then

$$\|X_S^\top \xi\|_2^2 \stackrel{d}{=} \sum_{i=1}^s \lambda_i Z_i^2, \quad \lambda_i := \sigma^2 \mu_i, \quad Z_i \stackrel{\text{i.i.d.}}{\sim} \mathcal{N}(0, 1).$$

The weighted χ^2 tail of Laurent–Massart (2000, Lemma 1) states that for all $x \geq 0$,

$$\mathbb{P}\left(\sum_{i=1}^s \lambda_i Z_i^2 \geq \sum_{i=1}^s \lambda_i + 2\sqrt{\left(\sum_{i=1}^s \lambda_i^2\right)x} + 2(\max_i \lambda_i)x \mid X_S\right) \leq e^{-x}. \quad (29)$$

Since $\sum_i \lambda_i = \sigma^2 \text{tr}(G)$, $\sum_i \lambda_i^2 = \sigma^4 \text{tr}(G^2) \leq \sigma^4 s \|G\|_{\text{op}}^2$, and $\max_i \lambda_i = \sigma^2 \|G\|_{\text{op}}$, inserting these into equation 29 and choosing $x = s$ gives, with conditional probability $\geq 1 - e^{-s}$,

$$\|X_S^\top \xi\|_2^2 \leq \sigma^2 (\text{tr}(G) + 4s \|G\|_{\text{op}}). \quad (30)$$

We now bound $\text{tr}(G)$ and $\|G\|_{\text{op}}$ on the events already used in Step A. First, by equation 25–equation 26,

$$\text{tr}(G) = \sum_{j \in S} \|X_{:,j}\|_2^2 \leq sn(1 + u_S) = sn + s\sqrt{ns}. \quad (31)$$

Second, from equation 22 with $t = \sqrt{s}$,

$$\|G\|_{\text{op}} = s_{\max}(X_S)^2 \leq (\sqrt{n} + \sqrt{s} + \sqrt{s})^2 \leq n + 4\sqrt{ns} + 4s. \quad (32)$$

Plugging equation 31–equation 32 into equation 30 and taking square roots, we obtain

$$\begin{aligned} \|X_S^\top \xi\|_2 &\leq \sigma \sqrt{sn + s\sqrt{ns} + 4s(n + 4\sqrt{ns} + 4s)} \\ &\leq \sigma (\sqrt{sn} + \sqrt{s\sqrt{ns}} + 2\sqrt{sn} + 4s) \\ &\leq C\sigma(\sqrt{sn} + s), \end{aligned} \quad (33)$$

where in the last step we used $\sqrt{s\sqrt{ns}} = s^{3/4}n^{1/4} \leq \frac{1}{2}(\sqrt{sn} + s)$.

ℓ_2 and ℓ_q bounds for b . Combining equation 28 and equation 33,

$$\|b\|_2 \leq \|(G - D)w_S^*\|_2 + \|X_S^\top \xi\|_2 \leq C(\sqrt{ns} \|w^*\|_2 + s \|w^*\|_2 + \sigma\sqrt{sn} + \sigma s). \quad (34)$$

In particular, when $s \leq n$ the s terms are dominated by \sqrt{ns} and

$$\|b\|_2 \leq C\tau_s \sqrt{sn} \quad (\text{since } \tau_s^2 = \|w^*\|_2^2 + \sigma^2). \quad (35)$$

(*Refined q -moment bound via decoupling*). Introduce i.i.d. “ghost” columns $\{X'_{:,j}\}_{j \in S}$ independent of (X, ξ) and set

$$\zeta'_j := \langle X'_{:,j}, u_j \rangle, \quad u_j := X_{:,S \setminus \{j\}} w_{S \setminus \{j\}}^* + \xi.$$

By a standard decoupling inequality for Gaussian chaos of order two (de la Peña and Giné, *Decoupling: From Dependence to Independence*, 1999, Thm. 3.5.3), there exists $C_q < \infty$ (depending only on q) such that for all $t > 0$,

$$\mathbb{P}\left(\sum_{j \in S} |\zeta_j|^q > t\right) \leq C_q \mathbb{P}\left(\sum_{j \in S} |\zeta'_j|^q > t/C_q\right).$$

Conditional on $\{u_j\}$, the variables $\{\zeta'_j\}_{j \in S}$ are independent centered Gaussians with variances $\|u_j\|_2^2$. On the singular-value and column-norm events used above (cf. equation 22 with $t = \sqrt{s}$ and equation 14), uniformly in j ,

$$\|u_j\|_2^2 \leq \|X_{:,S}\|_{\text{op}}^2 \|w^*\|_2^2 + \|\xi\|_2^2 \leq C(n + 4\sqrt{ns} + 4s) \|w^*\|_2^2 + C\sigma^2 n \leq C\tau_s^2 (n + s).$$

Hence, conditionally on $\{u_j\}$, each $|\zeta'_j|^q$ is sub-exponential with ψ_1 -norm $\leq C\tau_s^q (n + s)^{q/2}$. Bernstein’s inequality then yields

$$\sum_{j \in S} |\zeta'_j|^q \leq C\tau_s^q (sn^{q/2} + s^{1+q/2}) \quad \text{with conditional probability at least } 1 - Ce^{-cs}.$$

Unconditioning and applying decoupling gives, with probability at least $1 - 2d^{-\gamma} - Ce^{-cs}$,

$$\sum_{j \in S} |b_j|^q = \sum_{j \in S} |\zeta_j|^q \leq C \tau_s^q (s n^{q/2} + s^{1+q/2}). \quad (36)$$

In particular, if $s \leq n$ this simplifies to $\sum_{j \in S} |b_j|^q \leq C s \tau_s^q n^{q/2}$.

For the cross term, for $q \geq 2$ and any $a, b \in \mathbb{R}$ we have the elementary inequality

$$||a + b|^q - |a|^q| \leq C_q (|a|^{q-1}|b| + |b|^q) \leq C_q (|a|^{q-2}b^2 + |b|^q), \quad (37)$$

for a constant C_q depending only on q . Summing equation 37 over $j \in S$ with $a_j = w_j^* \|X_{:,j}\|_2^2$ and $b_j = \zeta_j$, and applying Hölder,

$$\begin{aligned} \sum_{j \in S} ||a_j + b_j|^q - |a_j|^q| &\leq C_q \sum_{j \in S} |a_j|^{q-1} |b_j| + C_q \sum_{j \in S} |b_j|^q \\ &\leq C_q \left(\sum_{j \in S} |a_j|^q \right)^{\frac{q-1}{q}} \left(\sum_{j \in S} |b_j|^q \right)^{\frac{1}{q}} + C_q \sum_{j \in S} |b_j|^q. \end{aligned} \quad (38)$$

Set

$$A := \sum_{j \in S} |a_j|^q, \quad B := \sum_{j \in S} |b_j|^q.$$

Apply Young's inequality with conjugate exponents $r = \frac{q}{q-1}$ and $s = q$: for any $\varepsilon > 0$,

$$A^{\frac{q-1}{q}} B^{\frac{1}{q}} \leq \frac{\varepsilon}{r} A + \frac{\varepsilon^{-(q-1)}}{s} B = \frac{q-1}{q} \varepsilon A + \frac{1}{q} \varepsilon^{-(q-1)} B. \quad (39)$$

With $A = n^q W_q (1 + O(u_n))$ and the bound $B \leq C \tau_s^q (s n^{q/2} + s^{1+q/2})$ from equation 36, choosing a fixed $\varepsilon \in (0, 1)$ (e.g. $\varepsilon = \frac{1}{2}$) absorbs the mixed term into the leading A and the B -remainder (with a harmless change of constants). Consequently,

$$\sum_{j \in S} ||a_j + b_j|^q - |a_j|^q| = O\left(\tau_s^q (s n^{q/2} + s^{1+q/2})\right),$$

which yields equation 19. When $s \leq n$ the remainder simplifies to $O(s \tau_s^q n^{q/2})$. \square

Combining Lemmas A.6–A.7 yields the decomposition

$$\|X^\top Y\|_q^q = n^q W_q (1 + o(1)) + (d-s) m_q \tau_s^q n^{q/2} (1 + o(1)) + O\left(\tau_s^q (s n^{q/2} + s^{1+q/2})\right) \quad \text{w.h.p.} \quad (40)$$

A.2.3 BULK ℓ_q -EMBEDDING AND GAUSSIAN ℓ_t RELATIONS.

Lemma A.8 (uniform ℓ_q control on the bulk operator). *Let $q \in [2, \infty)$ and assume $\kappa_{\text{bulk}} := \liminf_{n \rightarrow \infty} \frac{d-s}{n} > 0$. There exist constants $0 < c_q \leq C_q < \infty$, depending only on $(q, \kappa_{\text{bulk}})$, such that, with probability at least $1 - Ce^{-cn}$, simultaneously for all $\lambda \in \mathbb{R}^n$,*

$$c_q (d-s) \|\lambda\|_2^q \leq \sum_{j \notin S} |\langle X_{:,j}, \lambda \rangle|^q \leq C_q (d-s) \|\lambda\|_2^q. \quad (41)$$

(Here we absorb the Gaussian absolute moment $m_q = \mathbb{E}|Z|^q$ into the constants c_q, C_q ; in equation 42 we keep m_t explicit.) *Moreover, for every $t \in [1, q]$, there exist constants $0 < c_t \leq C_t < \infty$, depending only on $(t, \kappa_{\text{bulk}})$, such that, w.h.p., uniformly in $\lambda \in \mathbb{R}^n$,*

$$c_t^{1/t} (d-s)^{1/t} m_t^{1/t} \|\lambda\|_2 \leq \left\| \left(|\langle X_{:,j}, \lambda \rangle| \right)_{j \notin S} \right\|_t \leq C_t^{1/t} (d-s)^{1/t} m_t^{1/t} \|\lambda\|_2, \quad (42)$$

where $m_t := \mathbb{E}|Z|^t$ for $Z \sim \mathcal{N}(0, 1)$.

1134 *Proof.* Fix $\lambda \in \mathbb{R}^n$, and if $\lambda \neq 0$ write $u := \lambda/\|\lambda\|_2 \in \mathbb{S}^{n-1}$. By homogeneity,

$$1135 \sum_{j \notin S} |\langle X_{:,j}, \lambda \rangle|^q = \|\lambda\|_2^q \sum_{j \notin S} |\langle X_{:,j}, u \rangle|^q, \quad (43)$$

1137 and similarly for any $t \in [1, q]$,

$$1138 \left\| (\langle X_{:,j}, \lambda \rangle)_{j \notin S} \right\|_t = \|\lambda\|_2 \left(\sum_{j \notin S} |\langle X_{:,j}, u \rangle|^t \right)^{1/t}. \quad (44)$$

1140 Thus it suffices to prove the bounds for unit u .

1141 Let $T := S^c$ and $m := |T| = d - s$. Fix $u \in \mathbb{S}^{n-1}$ and $t \in [1, q]$. Define

$$1142 Y_j^{(t)}(u) := |\langle X_{:,j}, u \rangle|^t, \quad j \in T.$$

1143 Since the columns $\{X_{:,j}\}_{j \in T}$ are i.i.d. $\mathcal{N}(0, I_n)$ and independent of u , the random variables $\{Y_j^{(t)}(u)\}_{j \in T}$ are i.i.d.

1144 **Definition A.9** (Orlicz ψ_ν norm and sub-Weibull class). For $\nu \in (0, 2]$ and a real random variable Z , the Orlicz norm

$$1145 \|Z\|_{\psi_\nu} := \inf \left\{ K > 0 : \mathbb{E} \exp\left(\frac{|Z|^\nu}{K^\nu}\right) \leq 2 \right\}.$$

1146 If $\|Z\|_{\psi_\nu} < \infty$, we say Z is *sub-Weibull of order ν* . Special cases: $\nu = 2$ (sub-Gaussian) and $\nu = 1$ (sub-Exponential). Two basic properties we use are

$$1147 \mathbb{P}(|Z| > x) \leq 2 \exp\left(-c(x/\|Z\|_{\psi_\nu})^\nu\right) \quad (\forall x \geq 0), \quad (45)$$

$$1148 \|Z - \mathbb{E}Z\|_{\psi_\nu} \leq 2 \|Z\|_{\psi_\nu}. \quad (46)$$

1149 **Definition A.10** (Gaussian absolute moment). For $t > 0$, let $Z \sim \mathcal{N}(0, 1)$ and define

$$1150 m_t := \mathbb{E}|Z|^t = 2^{t/2} \frac{\Gamma(\frac{t+1}{2})}{\sqrt{\pi}}.$$

1151 *Classification of $Y_j^{(t)}(u)$ in ψ_ν (with explicit mgf computation).* Since $\langle X_{:,j}, u \rangle \sim \mathcal{N}(0, 1)$, write $Z \sim \mathcal{N}(0, 1)$ and set $W := |Z|^t$. For any $K > 0$,

$$1152 \left(\frac{W}{K}\right)^{2/t} = \left(\frac{|Z|^t}{K}\right)^{2/t} = \frac{|Z|^2}{K^{2/t}}.$$

1153 Let

$$1154 \theta := \frac{1}{K^{2/t}}.$$

1155 Then

$$1156 \mathbb{E} \exp\left(\left(\frac{W}{K}\right)^{2/t}\right) = \mathbb{E} \exp(\theta Z^2).$$

1157 Compute this expectation explicitly: using the standard normal density $\varphi(z) = (2\pi)^{-1/2} e^{-z^2/2}$,

$$1158 \mathbb{E}[e^{\theta Z^2}] = \int_{\mathbb{R}} e^{\theta z^2} \varphi(z) dz = \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} e^{\theta z^2} e^{-z^2/2} dz$$

$$1159 = \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} e^{-(\frac{1}{2}-\theta)z^2} dz = \frac{1}{\sqrt{2\pi}} \cdot \sqrt{\frac{\pi}{\frac{1}{2}-\theta}} = \frac{1}{\sqrt{1-2\theta}}, \quad \text{for } \theta < \frac{1}{2}. \quad (47)$$

1160 Equivalently, since $Z^2 \sim \chi_1^2$, the mgf of χ_1^2 is $(1-2\theta)^{-1/2}$ for $\theta < 1/2$, which matches equation 47.

1161 We now choose K so that $\theta < 1/2$ and the expectation is uniformly bounded by a constant ≤ 2 . Take

$$1162 K_t := (4t)^{t/2} \implies \theta = \frac{1}{K_t^{2/t}} = \frac{1}{4t} < \frac{1}{2} \quad (t \geq 1). \quad (48)$$

Then, by equation 47,

$$\mathbb{E} \exp\left(\left(W/K_t\right)^{2/t}\right) = \frac{1}{\sqrt{1 - \frac{2}{K_t^{2/t}}}} = \frac{1}{\sqrt{1 - \frac{1}{2t}}} \leq \frac{1}{\sqrt{1 - \frac{1}{2}}} = \sqrt{2} < 2, \quad (49)$$

where we used $t \in [1, q]$ (hence $t \geq 1$). By the definition of the Orlicz norm,

$$\| |Z|^t \|_{\psi_{2/t}} \leq K_t = (4t)^{t/2}. \quad (50)$$

Centering preserves the class up to a factor 2 (by equation 46), hence

$$\| |Z|^t - m_t \|_{\psi_{2/t}} \leq 2K_t = 2(4t)^{t/2}. \quad (51)$$

Finally, define

$$\nu(t) := \min\{1, 2/t\}. \quad (52)$$

Since $2/t \geq 1$ for $t \leq 2$ and $2/t < 1$ for $t > 2$, combining equation 51 with equation 52 yields the uniform (in u) classification

$$\| Y_j^{(t)}(u) - m_t \|_{\psi_{\nu(t)}} \leq K'_t \quad \text{with } K'_t := 2(4t)^{t/2}. \quad (53)$$

This bound is uniform in u because $\langle X_{:,j}, u \rangle \stackrel{d}{=} \mathcal{N}(0, 1)$ for every fixed $u \in \mathbb{S}^{n-1}$.

Empirical-mean concentration at fixed u . From equation 53 and independence across $j \in T$, a Bernstein-type inequality for sums of i.i.d. sub-Weibull(ν) variables (e.g. Theorem 3.1 in Kuchibhotla-Basu, 2018) yields, for any $\varepsilon > 0$,

$$\mathbb{P}\left(\left|\frac{1}{m} \sum_{j \in T} (Y_j^{(t)}(u) - m_t)\right| > \varepsilon\right) \leq 2 \exp\left\{-c_{\nu(t)} m \min\left(\frac{\varepsilon^2}{K_t'^2}, \left(\frac{\varepsilon}{K_t'}\right)^{\nu(t)}\right)\right\}. \quad (54)$$

Taking $\varepsilon = \delta m_t$ with $\delta \in (0, 1)$, and absorbing the fixed ratio m_t/K_t' (which depends only on t) into the constant, we obtain

$$\mathbb{P}\left(\left|\frac{1}{m} \sum_{j \in T} Y_j^{(t)}(u) - m_t\right| > \delta m_t\right) \leq 2 \exp\left(-c_t m \min\{\delta^2, \delta^{\nu(t)}\}\right), \quad (55)$$

where $c_t > 0$ depends only on t (hence only on p). In the sub-Exponential range $t \in [1, 2]$, $\nu(t) = 1$ and equation 55 simplifies to

$$\mathbb{P}\left(\left|\frac{1}{m} \sum_{j \in T} Y_j^{(t)}(u) - m_t\right| > \delta m_t\right) \leq 2 \exp(-c_t m \min\{\delta^2, \delta\}). \quad (56)$$

Finally, note that

$$\mathbb{E} Y_j^{(t)}(u) = m_t, \quad (57)$$

by Definition A.10, completing Step 1.

Now we can construct a net on the sphere and a uniform bound on that net. Let $\varepsilon \in (0, 1/8]$ be a fixed absolute constant (to be chosen below). There exists an ε -net $\mathcal{N}_\varepsilon \subset \mathbb{S}^{n-1}$ with

$$|\mathcal{N}_\varepsilon| \leq \left(1 + \frac{2}{\varepsilon}\right)^n \leq C_\varepsilon^m. \quad (58)$$

Applying equation 55 with $\delta = \delta_t \in (0, 1/4]$ (a small absolute constant depending only on t) and union-bounding over \mathcal{N}_ε yields

$$\begin{aligned} \mathbb{P}\left(\exists v \in \mathcal{N}_\varepsilon : \left|\frac{1}{m} \sum_{j \in T} Y_j^{(t)}(v) - m_t\right| > \delta_t m_t\right) &\leq 2 |\mathcal{N}_\varepsilon| \exp(-c_t m \min\{\delta_t^2, \delta_t\}) \\ &\leq 2 \exp\left(n \log C_\varepsilon - c'_t m\right). \end{aligned} \quad (59)$$

Because $m \geq \kappa_{\text{bulk}} n$ and $\kappa_{\text{bulk}} > 0$, by taking δ_t fixed (e.g. $\delta_t = 1/4$) and ε fixed (e.g. $\varepsilon = 1/8$), the right-hand side of equation 59 is $\leq Ce^{-cn}$. Therefore, with probability at least $1 - Ce^{-cn}$, simultaneously for all $v \in \mathcal{N}_\varepsilon$,

$$(1 - \delta_t) m_t \leq \frac{1}{m} \sum_{j \in T} |\langle X_{:,j}, v \rangle|^t \leq (1 + \delta_t) m_t. \quad (60)$$

We are ready to extend from the net to the whole sphere. Fix arbitrary $u \in \mathbb{S}^{n-1}$ and pick $v \in \mathcal{N}_\varepsilon$ with $\|u - v\|_2 \leq \varepsilon$. For any $a, b \in \mathbb{R}$ and any $t \geq 1$, the elementary inequalities

$$|a + b|^t \leq 2^{t-1}(|a|^t + |b|^t), \quad |a|^t \leq 2^{t-1}(|a + b|^t + |b|^t) \quad (61)$$

hold. Applying equation 61 with $a = \langle X_{:,j}, v \rangle$ and $b = \langle X_{:,j}, u - v \rangle$, we get

$$|\langle X_{:,j}, u \rangle|^t \leq 2^{t-1} \left(|\langle X_{:,j}, v \rangle|^t + |\langle X_{:,j}, u - v \rangle|^t \right), \quad (62)$$

$$|\langle X_{:,j}, u \rangle|^t \geq 2^{1-t} |\langle X_{:,j}, v \rangle|^t - |\langle X_{:,j}, u - v \rangle|^t. \quad (63)$$

Average equation 62 and equation 63 over $j \in T$ and divide by m to obtain

$$\frac{1}{m} \sum_{j \in T} |\langle X_{:,j}, u \rangle|^t \leq 2^{t-1} \left(\frac{1}{m} \sum_{j \in T} |\langle X_{:,j}, v \rangle|^t + \frac{1}{m} \sum_{j \in T} |\langle X_{:,j}, u - v \rangle|^t \right), \quad (64)$$

$$\frac{1}{m} \sum_{j \in T} |\langle X_{:,j}, u \rangle|^t \geq 2^{1-t} \frac{1}{m} \sum_{j \in T} |\langle X_{:,j}, v \rangle|^t - \frac{1}{m} \sum_{j \in T} |\langle X_{:,j}, u - v \rangle|^t. \quad (65)$$

For any $w \in \mathbb{R}^n$,

$$\frac{1}{m} \sum_{j \in T} |\langle X_{:,j}, w \rangle|^t = \|w\|_2^t \cdot \frac{1}{m} \sum_{j \in T} |\langle X_{:,j}, \widehat{w} \rangle|^t, \quad \widehat{w} := \frac{w}{\|w\|_2} \text{ (if } w \neq 0). \quad (66)$$

Define the functional and its extremal values

$$A(u) := \frac{1}{m} \sum_{j \in T} |\langle X_{:,j}, u \rangle|^t, \quad S := \sup_{u \in \mathbb{S}^{n-1}} A(u), \quad I := \inf_{u \in \mathbb{S}^{n-1}} A(u).$$

By equation 66 and $\|u - v\|_2 \leq \varepsilon$,

$$\frac{1}{m} \sum_{j \in T} |\langle X_{:,j}, u - v \rangle|^t = \|u - v\|_2^t \cdot \frac{1}{m} \sum_{j \in T} |\langle X_{:,j}, \widehat{u - v} \rangle|^t \leq \varepsilon^t S,$$

where we used the definition of S in the last inequality. On the event equation 60 (from Step 2), $A(v) \in [(1 - \delta_t)m_t, (1 + \delta_t)m_t]$ for every $v \in \mathcal{N}_\varepsilon$. Plugging these into equation 64-equation 65 yields

$$A(u) \leq 2^{t-1} (A(v) + \varepsilon^t S),$$

$$A(u) \geq 2^{1-t} A(v) - \varepsilon^t S.$$

Taking the supremum over $u \in \mathbb{S}^{n-1}$ in the upper bound:

$$S \leq 2^{t-1} ((1 + \delta_t)m_t + \varepsilon^t S) \implies S \leq \frac{2^{t-1}}{1 - 2^{t-1}\varepsilon^t} (1 + \delta_t) m_t.$$

Taking the infimum over $u \in \mathbb{S}^{n-1}$ in the lower bound:

$$I \geq 2^{1-t} (1 - \delta_t) m_t - \varepsilon^t S.$$

Choose fixed $\delta_t \leq \frac{1}{4}$ and $\varepsilon \leq \frac{1}{8}$; then

$$2^{t-1}\varepsilon^t = \frac{(2\varepsilon)^t}{2} \leq \frac{(1/4)^t}{2} \leq \frac{1}{8},$$

so $1 - 2^{t-1}\varepsilon^t \geq 7/8$ and thus

$$S \leq \frac{2^{t-1}}{7/8} (1 + \delta_t) m_t \leq C_t m_t,$$

for a constant $C_t < \infty$ depending only on t . Substituting this bound for S back into the inequality for I gives

$$I \geq 2^{1-t}(1 - \delta_t)m_t - \varepsilon^t C_t m_t \geq c_t m_t,$$

for some $c_t > 0$ (depending only on t). Therefore, with probability at least $1 - Ce^{-cn}$,

$$c_t m_t \leq \frac{1}{m} \sum_{j \in T} |\langle X_{:,j}, u \rangle|^t \leq C_t m_t \quad \text{simultaneously for all } u \in \mathbb{S}^{n-1}. \quad (67)$$

Multiplying equation 67 by $m = d - s$ and using equation 43 with $t = q$ yields

$$c_q (d - s) \|\lambda\|_2^q \leq \sum_{j \notin S} |\langle X_{:,j}, \lambda \rangle|^q \leq C_q (d - s) \|\lambda\|_2^q,$$

which is equation 41. Likewise, combining equation 67 with equation 44 gives

$$c_t^{1/t} (d - s)^{1/t} m_t^{1/t} \|\lambda\|_2 \leq \|(|\langle X_{:,j}, \lambda \rangle|)_{j \notin S}\|_t \leq C_t^{1/t} (d - s)^{1/t} m_t^{1/t} \|\lambda\|_2,$$

which is equation 42. \square

A.2.4 SPIKE ℓ_t CONTROL FOR $X^\top Y$

Lemma A.11 (spike ℓ_t control for $X^\top Y$). *Fix any $t \in [1, q]$ and $\gamma > 0$. With probability at least $1 - 2d^{-\gamma} - Ce^{-cs}$,*

$$\left\| (|\langle X_{:,j}, Y \rangle|)_{j \in S} \right\|_t = n \|w^*\|_t (1 + O(u_n)) \pm C \tau_s \left(\sqrt{n} s^{\max\{1/t, 1/2\}} + s^{1+(1/t-1/2)_+} \right), \quad (68)$$

where $u_n := \sqrt{(1 + \gamma) \log d / (cn)} = o(1)$ and $(x)_+ := \max\{x, 0\}$. In particular, if $s \leq n$ then the error simplifies to

$$\left\| (|\langle X_{:,j}, Y \rangle|)_{j \in S} \right\|_t = n \|w^*\|_t (1 + O(u_n)) \pm C \tau_s \sqrt{n} s^{\max\{1/t, 1/2\}}. \quad (69)$$

All constants may depend on t (hence on p) but not on (n, d, s) .

Proof. For each $j \in S$,

$$\langle X_{:,j}, Y \rangle = w_j^* \|X_{:,j}\|_2^2 + \zeta_j, \quad \zeta_j := \left\langle X_{:,j}, \sum_{k \in S \setminus \{j\}} w_k^* X_{:,k} + \xi \right\rangle. \quad (70)$$

Conditional on $X_{:,j}$,

$$\mathbb{E}[\zeta_j | X_{:,j}] = 0, \quad \text{Var}(\zeta_j | X_{:,j}) = (\tau_s^2 - (w_j^*)^2) \|X_{:,j}\|_2^2, \quad (71)$$

and $\zeta_j | X_{:,j} \sim \mathcal{N}(0, (\tau_s^2 - (w_j^*)^2) \|X_{:,j}\|_2^2)$ by independence and rotational invariance. Define

$$a_j := w_j^* \|X_{:,j}\|_2^2, \quad b_j := \zeta_j, \quad a := (a_j)_{j \in S}, \quad b := (b_j)_{j \in S}.$$

By the uniform column-norm bound equation 14 with $u = u_n = o(1)$, we have

$$\max_{1 \leq j \leq d} \left| \frac{\|X_{:,j}\|_2^2}{n} - 1 \right| \leq u_n \quad \text{with probability at least } 1 - 2d^{-\gamma}. \quad (72)$$

On this event,

$$\begin{aligned} \left\| (|a_j|)_{j \in S} \right\|_{\ell_t} &= \left(\sum_{j \in S} |w_j^*|^t \|X_{:,j}\|_2^{2t} \right)^{1/t} = n \left(\sum_{j \in S} |w_j^*|^t (1 + O(u_n))^t \right)^{1/t} \\ &= n \|w^*\|_t (1 + O(u_n)). \end{aligned} \quad (73)$$

Let X_S be the $n \times s$ submatrix with columns $\{X_{:,j}\}_{j \in S}$, and set

$$G := X_S^\top X_S, \quad D := \text{diag}(\|X_{:,j}\|_2^2)_{j \in S}.$$

From equation 70, in vector form

$$b = (G - D)w_S^* + X_S^\top \xi. \quad (74)$$

We bound the two terms separately.

(i) *Control of $(G - D)w_S^*$.* By the triangle inequality and operator norm submultiplicativity,

$$\|(G - D)w_S^*\|_2 \leq \|G - D\|_{\text{op}} \|w^*\|_2 \leq (\|G - nI_s\|_{\text{op}} + \|D - nI_s\|_{\text{op}}) \|w^*\|_2. \quad (75)$$

Gaussian singular-value concentration (Vershynin, HDP, Thm. 4.6.1) gives, for any $t \geq 0$,

$$\mathbb{P}\left(s_{\max}(X_S) \leq \sqrt{n} + \sqrt{s} + t, \quad s_{\min}(X_S) \geq \sqrt{n} - \sqrt{s} - t\right) \geq 1 - 2e^{-t^2/2}. \quad (76)$$

On this event,

$$\begin{aligned} \|G - nI_s\|_{\text{op}} &= \max\{s_{\max}(X_S)^2 - n, n - s_{\min}(X_S)^2\} \\ &\leq (\sqrt{n} + \sqrt{s} + t)^2 - n \vee n - (\sqrt{n} - \sqrt{s} - t)^2 \\ &\leq s + 2\sqrt{ns} + 2t(\sqrt{n} + \sqrt{s}) + t^2. \end{aligned} \quad (77)$$

Taking $t = \sqrt{s}$ yields, with probability $\geq 1 - 2e^{-s/2}$,

$$\|G - nI_s\|_{\text{op}} \leq 4\sqrt{ns} + 4s. \quad (78)$$

By the S -only column-norm event equation 26 (with $u_S = \sqrt{s/n}$),

$$\|D - nI_s\|_{\text{op}} = \max_{j \in S} |\|X_{:,j}\|_2^2 - n| \leq nu_S = \sqrt{ns}.$$

Combining this with equation 75 and equation 78 yields

$$\|(G - D)w_S^*\|_2 \leq C(\sqrt{ns} + s) \|w^*\|_2 \quad \text{with probability at least } 1 - 2e^{-s/2} - Ce^{-c\sqrt{ns}}. \quad (79)$$

(ii) *Control of $X_S^\top \xi$.* Conditionally on X_S , one has $X_S^\top \xi \sim \mathcal{N}(0, \sigma^2 G)$. Writing $\{\mu_i\}_{i=1}^s$ for the eigenvalues of G and $\lambda_i := \sigma^2 \mu_i$, Laurent–Massart’s weighted χ^2 tail (2000, Lemma 1) yields, for all $x \geq 0$,

$$\mathbb{P}\left(\sum_{i=1}^s \lambda_i Z_i^2 \geq \sum_i \lambda_i + 2\sqrt{\left(\sum_i \lambda_i^2\right)x} + 2(\max_i \lambda_i)x \mid X_S\right) \leq e^{-x}. \quad (80)$$

Using $\sum_i \lambda_i = \sigma^2 \text{tr}(G)$, $\sum_i \lambda_i^2 \leq \sigma^4 s \|G\|_{\text{op}}^2$, and $\max_i \lambda_i = \sigma^2 \|G\|_{\text{op}}$, and taking $x = s$ gives, with conditional probability $\geq 1 - e^{-s}$,

$$\|X_S^\top \xi\|_2^2 \leq \sigma^2 (\text{tr}(G) + 4s \|G\|_{\text{op}}). \quad (81)$$

On the event equation 76 with $t = \sqrt{s}$ and equation 72,

$$\text{tr}(G) = \sum_{j \in S} \|X_{:,j}\|_2^2 \leq sn(1 + u_n) = sn + o(sn), \quad \|G\|_{\text{op}} = s_{\max}(X_S)^2 \leq n + 4\sqrt{ns} + 4s. \quad (82)$$

Plugging equation 82 into equation 81 and taking square roots,

$$\|X_S^\top \xi\|_2 \leq C\sigma(\sqrt{sn} + s) \quad \text{with prob. } \geq 1 - 2e^{-s/2} - e^{-s}. \quad (83)$$

Combining equation 79, equation 83, and equation 74,

$$\|b\|_2 \leq C\tau_s(\sqrt{sn} + s) \quad \text{with prob. } \geq 1 - 2d^{-\gamma} - Ce^{-cs}. \quad (84)$$

For $t \in [1, 2]$, the norm monotonicity in \mathbb{R}^s gives

$$\|b\|_{\ell_t} \leq s^{1/t-1/2} \|b\|_2. \quad (85)$$

For $t \geq 2$, $\|b\|_{\ell_t} \leq \|b\|_2$. Hence, for all $t \in [1, q]$,

$$\|b\|_{\ell_t} \leq s^{(1/t-1/2)+} \|b\|_2 \leq C \tau_s \left(\sqrt{n} s^{\max\{1/t, 1/2\}} + s^{1+(1/t-1/2)+} \right), \quad (86)$$

where we used equation 84. In particular, if $s \leq n$ then $s^{1+(1/t-1/2)+} \leq \sqrt{n} s^{\max\{1/t, 1/2\}}$ and equation 86 reduces to

$$\|b\|_{\ell_t} \leq C \tau_s \sqrt{n} s^{\max\{1/t, 1/2\}}. \quad (87)$$

Finally, by the triangle inequality,

$$\|(|a_j + b_j|)_{j \in S}\|_{\ell_t} \leq \|(|a_j|)_{j \in S}\|_{\ell_t} + \|(|b_j|)_{j \in S}\|_{\ell_t}, \quad (88)$$

$$\|(|a_j + b_j|)_{j \in S}\|_{\ell_t} \geq \|(|a_j|)_{j \in S}\|_{\ell_t} - \|(|b_j|)_{j \in S}\|_{\ell_t}, \quad (89)$$

and combining with equation 73 and equation 86 (or equation 87 when $s \leq n$) yields equation 68 (and equation 69). \square

A.2.5 RAY CONTROLS: MINIMAL COMPARISON AND BLOCKWISE BOUNDS

For the ray $\lambda = tY$ we have the one-dimensional dual objective

$$D(t) := \langle Y, tY \rangle - \frac{1}{q} \|X^\top(tY)\|_q^q = t \|Y\|_2^2 - \frac{t^q}{q} \|X^\top Y\|_q^q. \quad (90)$$

Since $D''(t) = -(q-1)t^{q-2} \|X^\top Y\|_q^q < 0$ for all $t > 0$, D is strictly concave on $[0, \infty)$ and admits a unique maximizer t_* given by the first-order condition $D'(t_*) = 0$:

$$t_*^{q-1} = \frac{\|Y\|_2^2}{\|X^\top Y\|_q^q}. \quad (91)$$

At this maximizer,

$$D(t_*) = t_* \|Y\|_2^2 - \frac{t_*^q}{q} \|X^\top Y\|_q^q = \left(1 - \frac{1}{q}\right) t_*^q \|X^\top Y\|_q^q = \left(1 - \frac{1}{q}\right) \|X^\top(t_* Y)\|_q^q. \quad (92)$$

Lemma A.12 (Ray controls). *Let $p \in (1, 2]$, $q = \frac{p}{p-1} \in [2, \infty)$, and define t_* by equation 91. With probability at least $1 - Ce^{-c(d-s)} - Ce^{-c\sqrt{ns}}$ (constants depend only on $(q, \kappa_{\text{bulk}})$), the following hold simultaneously.*

(One-sided value comparison).

$$D(\lambda^*) \geq D(t_*) \quad \text{and} \quad \|X^\top \lambda^*\|_q^q \geq \|X^\top(t_* Y)\|_q^q. \quad (93)$$

(Dual-norm scale). *There exist $0 < c_1 \leq C_1 < \infty$ depending only on $(q, \kappa_{\text{bulk}})$ such that*

$$c_1 t_* \|Y\|_2 \leq \|\lambda^*\|_2 \leq C_1 t_* \|Y\|_2. \quad (94)$$

(Bulk block at level $t \in [1, q]$). *For each $t \in [1, q]$ there exist $0 < c_t \leq C_t < \infty$ (depending only on $(t, \kappa_{\text{bulk}})$) such that*

$$c_t^{1/t} (d-s)^{1/t} m_t^{1/t} t_* \|Y\|_2 \leq \left\| (|\langle X_{:,j}, \lambda^* \rangle|)_{j \notin S} \right\|_t \leq C_t^{1/t} (d-s)^{1/t} m_t^{1/t} t_* \|Y\|_2, \quad (95)$$

where $m_t = \mathbb{E}|Z|^t$ for $Z \sim \mathcal{N}(0, 1)$.

(Spike block: two-sided t -level perturbation). *For every $t \in [1, q]$,*

$$\left\| (|\langle X_{:,j}, \lambda^* \rangle|)_{j \in S} \right\|_t = t_* \left\| (|\langle X_{:,j}, Y \rangle|)_{j \in S} \right\|_t \pm C_2 t_* \|Y\|_2 s^{(1/t-1/2)+} (\sqrt{n} + \sqrt{s}), \quad (96)$$

for a constant $C_2 = C_2(q, \kappa_{\text{bulk}})$. *In particular, if $s \leq n$ then*

$$\left\| (|\langle X_{:,j}, \lambda^* \rangle|)_{j \in S} \right\|_t = t_* \left\| (|\langle X_{:,j}, Y \rangle|)_{j \in S} \right\|_t \pm C_3 t_* \tau_s \sqrt{n} s^{\max\{1/t, 1/2\}}. \quad (97)$$

In the last display we used $\|Y\|_2 = \tau_s \sqrt{n} (1 + o(1))$ from Lemma A.5.

1458 *Proof.* We work on the intersection of the high-probability events supplied by Lemma A.8 (both
1459 equation 41 and equation 42), Lemma A.6, and the singular-value bound equation 22; this intersection
1460 has probability at least $1 - Ce^{-cn}$.

1461
1462 (*One-sided value comparison equation 93*). By optimality of λ^* and the definition of t_* ,

$$D(\lambda^*) \geq D(t_*).$$

1463
1464 Using the Fenchel-Young identity at the optimum (see equation 13) and equation 92,

$$D(\lambda^*) = \left(1 - \frac{1}{q}\right) \|X^\top \lambda^*\|_q^q, \quad D(t_*) = \left(1 - \frac{1}{q}\right) \|X^\top (t_* Y)\|_q^q,$$

1465 hence equation 93.

1466
1467 (*Dual-norm scale equation 94*). **Lower bound.** From $D(\lambda^*) \geq D(t_*)$ and equation 92,

$$D(\lambda^*) \geq \left(1 - \frac{1}{q}\right) t_* \|Y\|_2^2.$$

1470 Since $D(\lambda^*) \leq \langle Y, \lambda^* \rangle \leq \|Y\|_2 \|\lambda^*\|_2$, we get

$$\|\lambda^*\|_2 \geq \left(1 - \frac{1}{q}\right) t_* \|Y\|_2.$$

1471
1472 **Upper bound.** Let

$$S(\lambda) := \sum_{j \in S} |\langle X_{:,j}, \lambda \rangle|^q, \quad B(\lambda) := \sum_{j \notin S} |\langle X_{:,j}, \lambda \rangle|^q.$$

1473
1474 From equation 13,

$$D(\lambda^*) = \left(1 - \frac{1}{q}\right) (S(\lambda^*) + B(\lambda^*)).$$

1475 By Lemma A.8 (left inequality in equation 41),

$$B(\lambda^*) \geq c_q (d - s) \|\lambda^*\|_2^q.$$

1476 Combining with $D(\lambda^*) \leq \|Y\|_2 \|\lambda^*\|_2$ gives

$$\left(1 - \frac{1}{q}\right) c_q (d - s) \|\lambda^*\|_2^{q-1} \leq \|Y\|_2. \quad (98)$$

1477 Next, Lemma A.6 yields

$$\sum_{j \notin S} |\langle X_{:,j}, Y \rangle|^q = (d - s) m_q \|Y\|_2^q (1 + o(1)),$$

1478 so $\|X^\top Y\|_q^q \geq c(d - s) \|Y\|_2^q$. From equation 91,

$$(t_* \|Y\|_2)^{q-1} = \frac{\|Y\|_2^{q+1}}{\|X^\top Y\|_q^q} \leq \frac{1}{c} \cdot \frac{\|Y\|_2}{(d - s)}.$$

1479 Comparing with equation 98 gives $\|\lambda^*\|_2^{q-1} \leq C (t_* \|Y\|_2)^{q-1}$ and hence $\|\lambda^*\|_2 \leq C_1 t_* \|Y\|_2$.

1480 (*Bulk block equation 95*). Apply Lemma A.8 at level t (two-sided inequality equation 42) with
1481 $\lambda = \lambda^*$:

$$c_t^{1/t} (d - s)^{1/t} m_t^{1/t} \|\lambda^*\|_2 \leq \left\| \left(|\langle X_{:,j}, \lambda^* \rangle| \right)_{j \notin S} \right\|_t \leq C_t^{1/t} (d - s)^{1/t} m_t^{1/t} \|\lambda^*\|_2.$$

1482 Substitute $\|\lambda^*\|_2 \asymp t_* \|Y\|_2$ from equation 94.

1483 (*Spike block equation 96-equation 97*). Set $h := \lambda^* - t_* Y$. Then

$$X_{:,S}^\top \lambda^* = t_* X_{:,S}^\top Y + X_{:,S}^\top h.$$

1484 For any $t \geq 1$, the triangle inequality gives

$$\left\| \left(|\langle X_{:,j}, \lambda^* \rangle| \right)_{j \in S} \right\|_t \leq t_* \left\| \left(|\langle X_{:,j}, Y \rangle| \right)_{j \in S} \right\|_t + \|X_{:,S}^\top h\|_{\ell_t},$$

and the analogous lower bound with a minus sign. By norm monotonicity in \mathbb{R}^s and operator norm submultiplicativity,

$$\|X_{:,S}^\top h\|_{\ell_t} \leq s^{(1/t-1/2)+} \|X_{:,S}^\top h\|_2 \leq s^{(1/t-1/2)+} s_{\max}(X_{:,S}) \|h\|_2.$$

From equation 22 with $t = \sqrt{s}$, $s_{\max}(X_{:,S}) \leq C(\sqrt{n} + \sqrt{s})$ w.h.p., and from equation 94,

$$\|h\|_2 = \|\lambda^* - t_* Y\|_2 \leq \|\lambda^*\|_2 + t_* \|Y\|_2 \leq (C_1 + 1) t_* \|Y\|_2.$$

Putting these together yields equation 96. If $s \leq n$, Lemma A.5 gives $\|Y\|_2 = \tau_s \sqrt{n}(1 + o(1))$ and

$$s^{(1/t-1/2)+} (\sqrt{n} + \sqrt{s}) \leq 2\sqrt{n} s^{\max\{1/t, 1/2\}},$$

which implies equation 97. \square

A.3 PROOF OF THEOREM A.2

With these lemmas in place, we are ready to prove Theorem A.2.

Proof of Theorem A.2. We work on the intersection of the high-probability events provided by Lemmas A.5, A.6, A.7, A.8, A.11, and A.12; this event has probability at least $1 - Ce^{-c(d-s)} - Ce^{-c\sqrt{ns}} - 2d^{-\gamma}$, consistent with Remark A.1. All constants implicit in \asymp depend only on $(q, \kappa_{\text{bulk}})$.

Along the ray $\lambda = tY$, the one-dimensional dual objective

$$D(t) = t \|Y\|_2^2 - \frac{t^q}{q} \|X^\top Y\|_q^q$$

is strictly concave with unique maximizer given by the first-order condition (see equation 91)

$$t_*^{q-1} = \frac{\|Y\|_2^2}{\|X^\top Y\|_q^q}. \quad (99)$$

By Lemma A.5, $\|Y\|_2^2 = \tau_s^2 n(1 + o(1))$, and by the decomposition equation 40,

$$\|X^\top Y\|_q^q = n^q W_q (1 + o(1)) + (d-s) m_q \tau_s^q n^{q/2} (1 + o(1)) + O(s \tau_s^q n^{q/2}).$$

Substituting into equation 99 yields

$$t_*^{q-1} \asymp \frac{\tau_s^2 n}{n^q W_q + ((d-s) m_q + O(s)) \tau_s^q n^{q/2}} \quad \text{w.h.p.} \quad (100)$$

By strong duality and Fenchel-Young (see equation 13),

$$\sup_\lambda D(\lambda) = \left(1 - \frac{1}{q}\right) \|X^\top \lambda^*\|_q^q = \left(1 - \frac{1}{q}\right) \|\hat{w}_p\|_p^p. \quad (101)$$

Evaluating D on the ray at t_* and using $D(\lambda^*) \geq D(t_*)$ gives

$$\|\hat{w}_p\|_p^p = \|X^\top \lambda^*\|_q^q \geq \|X^\top (t_* Y)\|_q^q = t_*^q \|X^\top Y\|_q^q = \frac{\|Y\|_2^{\frac{2q}{q-1}}}{\|X^\top Y\|_q^{\frac{q}{q-1}}}. \quad (102)$$

Moreover, by Cauchy-Schwarz and equation 94,

$$\|X^\top \lambda^*\|_q^q = \langle Y, \lambda^* \rangle \leq \|Y\|_2 \|\lambda^*\|_2 \lesssim t_* \|Y\|_2^2 = t_*^q \|X^\top Y\|_q^q.$$

Combining with equation 102 we obtain the two-sided scale

$$\|\hat{w}_p\|_p^p = \|X^\top \lambda^*\|_q^q \asymp t_*^q \|X^\top Y\|_q^q.$$

Using the coordinatewise KKT map equation 12,

$$\hat{w}_p = \nabla f^*(X^\top \lambda^*) = \text{sgn}(X^\top \lambda^*) \odot |X^\top \lambda^*|^{q-1}.$$

Hence, for any $r \in [1, p]$,

$$\|\hat{w}_p\|_r = \|X^\top \lambda^*\|_{(q-1)r}^{q-1}. \quad (103)$$

Split the $(q-1)r$ -norm over the spike block S and the bulk block S^c and note that $\|u\|_t^t = \|u_S\|_t^t + \|u_{S^c}\|_t^t$ implies $\|u\|_t \asymp \max\{\|u_S\|_t, \|u_{S^c}\|_t\}$:

$$\|\widehat{w}_p\|_r \asymp \max \left\{ \|(|\langle X_{:,j}, \lambda^* \rangle|)_{j \in S}\|_{(q-1)r}^{q-1}, \|(|\langle X_{:,j}, \lambda^* \rangle|)_{j \notin S}\|_{(q-1)r}^{q-1} \right\}. \quad (104)$$

(We used $\max\{a, b\} \leq (a^t + b^t)^{1/t} \leq 2^{1/t} \max\{a, b\}$ for $t \geq 1$.)

Set $t := (q-1)r \leq q$. By the spike-ray perturbation from Lemma A.12 (see equation 97 when $s \leq n$),

$$\|(|\langle X_{:,j}, \lambda^* \rangle|)_{j \in S}\|_{\ell_t} = t_* \|(|\langle X_{:,j}, Y \rangle|)_{j \in S}\|_{\ell_t} \pm C t_* \tau_s \sqrt{n} s^{\max\{1/t, 1/2\}}. \quad (105)$$

(If $s > n$, use the general form equation 96; the conclusion below is unchanged up to constants since $(\sqrt{n} + \sqrt{s}) s^{(1/t-1/2)+} \leq 2\sqrt{n} s^{\max\{1/t, 1/2\}} + s^{1+(1/t-1/2)+}$, which is captured by the final ‘‘spike remainder’’ term.) By Lemma A.11 at level t ,

$$\|(|\langle X_{:,j}, Y \rangle|)_{j \in S}\|_{\ell_t} = n \|w^*\|_t (1 + o(1)) \pm C \tau_s \sqrt{n} s^{\max\{1/t, 1/2\}}. \quad (106)$$

Combining equation 105-equation 106 and using $(a+b)^{q-1} \leq 2^{q-2}(a^{q-1} + b^{q-1})$ for $a, b \geq 0$, we obtain the following uniform two-sided bounds (recall $t = (q-1)r \leq q$):

$$\|(|\langle X_{:,j}, \lambda^* \rangle|)_{j \in S}\|_{\ell_t}^{q-1} \leq C \left\{ t_*^{q-1} n^{q-1} \|w^*\|_t^{q-1} + (t_* \tau_s \sqrt{n})^{q-1} s^{(q-1) \max\{1/t, 1/2\}} \right\}, \quad (107)$$

$$\|(|\langle X_{:,j}, \lambda^* \rangle|)_{j \in S}\|_{\ell_t}^{q-1} \geq c \left(t_* n \|w^*\|_t - C t_* \tau_s \sqrt{n} s^{\max\{1/t, 1/2\}} \right)_+^{q-1}. \quad (108)$$

Applying the mean-value inequality to the map $z \mapsto z^{q-1}$,

$$|(x \pm y)^{q-1} - x^{q-1}| \leq C (x^{q-2} y + y^{q-1}),$$

with $x = t_* n \|w^*\|_t$ and $y = C t_* \tau_s \sqrt{n} s^{\max\{1/t, 1/2\}}$, we obtain

$$\|(|\langle X_{:,j}, \lambda^* \rangle|)_{j \in S}\|_{\ell_t}^{q-1} = t_*^{q-1} n^{q-1} \|w^*\|_t^{q-1} (1 + o(1)) \pm C (t_* \tau_s \sqrt{n})^{q-1} s^{\max\{(q-1)/2, (q-1)/t\}}. \quad (109)$$

Recalling $t = (q-1)r$ and $\|w^*\|_t \asymp \|w^*\|_{(q-1)r}$, we obtain the spike contribution stated in equation 6. (For completeness: specializing equation 96 to $t = q$ together with Lemma A.11 at $t = q$ yields the same rate and remainder exponent as in equation 109.)

By Lemma A.12 (bulk control equation 95) together with equation 94,

$$\|(|\langle X_{:,j}, \lambda^* \rangle|)_{j \notin S}\|_{(q-1)r} \asymp (d-s)^{1/((q-1)r)} t_* \|Y\|_2.$$

Raising to the $(q-1)$ -th power and using $\|Y\|_2 \asymp \tau_s \sqrt{n}$ (Lemma A.5),

$$\|(|\langle X_{:,j}, \lambda^* \rangle|)_{j \notin S}\|_{(q-1)r}^{q-1} \asymp (d-s)^{1/r} (t_* \tau_s \sqrt{n})^{q-1}. \quad (110)$$

Plug equation 109 and equation 110 into equation 104. This yields

$$\|\widehat{w}_p\|_r \asymp \max \left\{ t_*^{q-1} n^{q-1} \|w^*\|_{(q-1)r}^{q-1}, (d-s)^{1/r} (t_* \tau_s \sqrt{n})^{q-1}, s^{\max\{1/r, (q-1)/2\}} (t_* \tau_s \sqrt{n})^{q-1} \right\},$$

which is exactly the three-term unified bound in equation 6. When $r < 2(p-1)$ and $(d-s) \gtrsim s$, the third term is absorbed by the bulk term, recovering the two-term maximum.

In the proportional regime $(d-s) \asymp \kappa_{\text{bulk}} n$, balance the two leading terms in $\|X^\top Y\|_q^q$ (cf. equation 40) to define

$$n^q W_q \asymp (d-s) \tau_s^q n^{q/2} \iff n^{q/2} \asymp \kappa_{\text{bulk}} \frac{\tau_s^q}{W_q} \iff n_* \asymp \left(\kappa_{\text{bulk}} \frac{\tau_s^q}{W_q} \right)^{\frac{2}{q-2}},$$

which matches equation 8.

(i) *Dual spike-dominated regime* $n \gg n_*$. Then $\|X^\top Y\|_q^q \asymp n^q W_q$ and equation 100 gives

$$t_*^{q-1} \asymp \frac{\tau_s^2 n}{n^q W_q} = \frac{\tau_s^2}{W_q} n^{-(q-1)}. \quad (111)$$

Consequently

$$(d-s)^{1/r} (t_* \tau_s \sqrt{n})^{q-1} \asymp \frac{\tau_s^{q+1}}{W_q} n^{\frac{1}{r} - \frac{1}{2(p-1)}}, \quad (112a)$$

$$s^{\max\{1/r, (q-1)/2\}} (t_* \tau_s \sqrt{n})^{q-1} \asymp \frac{\tau_s^{q+1}}{W_q} s^{\max\{1/r, (q-1)/2\}} n^{-\frac{1}{2(p-1)}}. \quad (112b)$$

In particular, when $r \leq 2(p-1)$ the two ‘‘bulk-type’’ terms are of the same order (and are dominated by the spike main when $r \geq 2(p-1)$); this recovers equation 9.

(ii) *Dual bulk-dominated regime* $n \ll n_*$. Then $\|X^\top Y\|_q^q \asymp (d-s)\tau_s^q n^{q/2}$ and

$$t_*^{q-1} \asymp \frac{\tau_s^2 n}{(d-s)\tau_s^q n^{q/2}} = \frac{\tau_s^{2-q}}{(d-s)} n^{1-\frac{q}{2}}. \quad (113)$$

Therefore

$$(d-s)^{1/r} (t_* \tau_s \sqrt{n})^{q-1} \asymp \kappa_{\text{bulk}}^{\frac{1}{r}-1} \tau_s n^{\frac{1}{r}-\frac{1}{2}}, \quad (114a)$$

$$s^{\max\{1/r, (q-1)/2\}} (t_* \tau_s \sqrt{n})^{q-1} \asymp \kappa_{\text{bulk}}^{-1} \tau_s s^{\max\{1/r, (q-1)/2\}} n^{-1/2}. \quad (114b)$$

Taking the maximum together with the spike main term gives equation 10 whenever the third term is absorbed; otherwise the third term with exponent $\max\{1/r, (q-1)/2\} - 1/2$ may dominate.

This completes the proof of equation 6 (three-term form), the energy scale equation 102, hence the proof of Theorem A.2. \square

A.4 TWO CONCRETE COROLLARIES: SINGLE SPIKE AND FLAT SUPPORT

We keep $p \in (1, 2]$, $q = \frac{p}{p-1} \in [2, \infty)$, $r \in [1, p]$, and $\kappa_{\text{bulk}} = \liminf (d-s)/n > 0$. Recall the unified bound from Theorem A.2. We will repeatedly use the identity

$$\|\widehat{w}_p\|_r \asymp \max \left\{ t_*^{q-1} n^{q-1} \|w^*\|_{(q-1)r}^{q-1}, (d-s)^{1/r} (t_* \tau_s \sqrt{n})^{q-1}, \right. \quad (115)$$

$$\left. s^{\max\{1/r, (q-1)/2\}} (t_* \tau_s \sqrt{n})^{q-1} \right\}, \quad (116)$$

together with

$$t_*^{q-1} = \frac{\|Y\|_2^2}{\|X^\top Y\|_q^q}, \quad n_* \asymp \left(\kappa_{\text{bulk}} \frac{\tau_s^q}{W_q} \right)^{\frac{2}{q-2}}, \quad W_q = \sum_{j \in S} |w_j^*|^q, \quad \tau_s^2 = \|w^*\|_2^2 + \sigma^2. \quad (117)$$

Case (i): single spike ($s = 1$). Let the support be $\{j_0\}$ and write $a := |w_{j_0}^*| > 0$. Then

$$W_q = a^q, \quad \|w^*\|_{(q-1)r} = a, \quad \tau_s^2 = a^2 + \sigma^2. \quad (118)$$

The transition scale simplifies to

$$n_* \asymp \left(\kappa_{\text{bulk}} \frac{(a^2 + \sigma^2)^{q/2}}{a^q} \right)^{\frac{2}{q-2}}. \quad (119)$$

In equation 115, the spike remainder is dominated by the bulk term since

$$\frac{\text{spike remainder}}{\text{bulk}} = (d-1)^{-1/r} \ll 1 \quad \text{for large } d. \quad (120)$$

Dual spike-dominated ($n \gg n_*$). Using the phase form equation 9, we obtain

$$\|\widehat{w}_p\|_r \asymp \begin{cases} \frac{(a^2 + \sigma^2)^{\frac{q+1}{2}}}{a^q} n^{\frac{1}{r} - \frac{1}{2(p-1)}}, & r \leq 2(p-1), \\ \frac{a^2 + \sigma^2}{a}, & r > 2(p-1). \end{cases} \quad (121)$$

Dual bulk-dominated ($n \ll n_*$). Using equation 10,

$$\|\widehat{w}_p\|_r \asymp \max \left\{ \kappa_{\text{bulk}}^{\frac{1}{r}-1} (a^2 + \sigma^2)^{1/2} n^{\frac{1}{r}-\frac{1}{2}}, \kappa_{\text{bulk}}^{-1} (a^2 + \sigma^2)^{\frac{2-q}{2}} a^{q-1} n^{\frac{q}{2}-1} \right\}. \quad (122)$$

(The third term in equation 10 equals $\kappa_{\text{bulk}}^{-1} \tau_s n^{-1/2}$ and is dominated by the first term for large n .)

Case (ii): flat signal on its support. Assume $w_j^* = a s_j$ for all $j \in S$ with $|s_j| = 1$ and $|S| = s$. Then

$$\|w^*\|_2 = \sqrt{s} |a|, \quad W_q = s |a|^q, \quad \|w^*\|_{(q-1)r} = s^{\frac{1}{(q-1)r}} |a|, \quad \tau_s^2 = s a^2 + \sigma^2. \quad (123)$$

The transition scale grows linearly in s :

$$n_* \asymp \left(\kappa_{\text{bulk}} \frac{(s a^2 + \sigma^2)^{q/2}}{s |a|^q} \right)^{\frac{2}{q-2}} = \kappa_{\text{bulk}}^{\frac{2}{q-2}} s \left(1 + \frac{\sigma^2}{s a^2} \right)^{\frac{q}{q-2}}. \quad (124)$$

Dual spike-dominated ($n \gg n_*$). From equation 9,

$$\|\widehat{w}_p\|_r \asymp \begin{cases} \frac{(s a^2 + \sigma^2)^{\frac{q+1}{2}}}{s |a|^q} n^{\frac{1}{r} - \frac{1}{2(p-1)}}, & r \leq 2(p-1), \\ s^{\frac{1}{r}-1} \frac{s a^2 + \sigma^2}{|a|}, & r > 2(p-1). \end{cases} \quad (125)$$

In the noiseless case ($\sigma = 0$),

$$r > 2(p-1) : \|\widehat{w}_p\|_r \asymp s^{1/r} |a|, \quad r \leq 2(p-1) : \|\widehat{w}_p\|_r \asymp s^{\frac{q-1}{2}} |a| n^{\frac{1}{r} - \frac{1}{2(p-1)}}. \quad (126)$$

Dual bulk-dominated ($n \ll n_*$). From equation 10,

$$\|\widehat{w}_p\|_r \asymp \max \left\{ \kappa_{\text{bulk}}^{\frac{1}{r}-1} (s a^2 + \sigma^2)^{1/2} n^{\frac{1}{r}-\frac{1}{2}}, \kappa_{\text{bulk}}^{-1} (s a^2 + \sigma^2)^{\frac{2-q}{2}} s^{1/r} |a|^{q-1} n^{\frac{q}{2}-1}, \right. \quad (127)$$

$$\left. \kappa_{\text{bulk}}^{-1} (s a^2 + \sigma^2)^{1/2} s^{\max\{1/r, (q-1)/2\}} n^{-1/2} \right\}. \quad (128)$$

When $r \leq 2(p-1)$ and $s \lesssim (d-s)$, the third term is absorbed by the first (Remark A.3).

B FROM INITIALIZATION SCALE TO AN EFFECTIVE ℓ_p : A SLOPE-MATCHING VIEW

Figure S1 visualizes the mapping $\alpha \mapsto p_{\text{eff}}(\alpha)$ we use throughout. The construction is data-free (independent of n and σ) and relies only on the gradient-flow potential that characterizes the two-layer DLN implicit bias. Pseudocode can be found in Algorithm 1.

We start from the separable potential

$$Q_\alpha(\beta) = \alpha^2 \sum_{i=1}^d q\left(\frac{\beta_i}{\alpha^2}\right), \quad (129)$$

$$q(z) = \int_0^z \operatorname{arcsinh}\left(\frac{u}{2}\right) du = 2 - \sqrt{4+z^2} + z \operatorname{arcsinh}\left(\frac{z}{2}\right). \quad (130)$$

At the coordinate level, letting $\psi_\alpha(t) \equiv \alpha^2 q(t/\alpha^2)$ gives

$$\psi'_\alpha(t) = \operatorname{arcsinh}\left(\frac{t}{2\alpha^2}\right), \quad (131)$$

$$\psi''_\alpha(t) = \frac{1}{\alpha^2 \sqrt{4 + (t/\alpha^2)^2}} = \frac{1}{\sqrt{4\alpha^4 + t^2}}. \quad (132)$$

Asymptotics for q control the limiting geometry (all logs are natural):

$$q(z) = \frac{z^2}{4} - \frac{z^4}{192} + O(z^6), \quad z \rightarrow 0, \quad (133)$$

$$q(z) = z(\log z - 1) + 2 - \frac{1}{z} + O\left(\frac{1}{z^3}\right), \quad z \rightarrow \infty. \quad (134)$$

Hence Q_α behaves like ℓ_2^2 as $\alpha \rightarrow \infty$ and like an ℓ_1 -type penalty (up to a log) as $\alpha \rightarrow 0$.

To turn this into a quantitative $\alpha \mapsto p$ mapping, we evaluate Q_α on the k -sparse, unit- ℓ_2 probes

$$\beta^{(k)} \in \mathbb{R}^d, \quad \beta_i^{(k)} \in \{0, k^{-1/2}\}, \quad \|\beta^{(k)}\|_2 = 1, \quad \#\{i : \beta_i^{(k)} \neq 0\} = k. \quad (135)$$

For this family,

$$Q_\alpha(\beta^{(k)}) = \alpha^2 k q\left(\frac{1}{\alpha^2 \sqrt{k}}\right), \quad (136)$$

while ℓ_p (calibrated via $\|\beta\|_p^p$) has the exact scaling

$$\|\beta^{(k)}\|_p^p = k \left(\frac{1}{\sqrt{k}}\right)^p = k^{1-\frac{p}{2}}. \quad (137)$$

We now fit a log-log slope to the k -dependence of Q_α and match exponents. Fix $\alpha > 0$, choose a logarithmic grid $\mathcal{K} \subset \{1, 2, \dots, d\}$ (e.g., up to 10^4), and solve

$$\log Q_\alpha(\beta^{(k)}) \approx c(\alpha) + s(\alpha) \log k, \quad k \in \mathcal{K}. \quad (138)$$

Comparing with equation 137 (which grows as $k^{1-p/2}$) yields

$$s(\alpha) = 1 - \frac{p_{\text{eff}}(\alpha)}{2} \implies p_{\text{eff}}(\alpha) = 2(1 - s(\alpha)). \quad (139)$$

The limits in equation 133–equation 134 imply

$$\alpha \rightarrow \infty : Q_\alpha(\beta^{(k)}) = \frac{1}{4\alpha^2} + O\left(\frac{1}{\alpha^6 k}\right), \quad s(\alpha) \rightarrow 0, \quad p_{\text{eff}}(\alpha) \rightarrow 2, \quad (140)$$

$$\alpha \rightarrow 0 : Q_\alpha(\beta^{(k)}) = \sqrt{k} \left(\log\left(\frac{1}{\alpha^2 \sqrt{k}}\right) - 1\right) + 2\alpha^2 k - \alpha^4 k \sqrt{k} + O(\alpha^8 k^2 \sqrt{k}), \quad (141)$$

$$s(\alpha) \rightarrow \frac{1}{2},$$

$$p_{\text{eff}}(\alpha) \rightarrow 1.$$

Thus $p_{\text{eff}}(\alpha)$ increases smoothly and monotonically from 1 to 2 as α grows, exactly as depicted in Figure S1. The inverse problem—choosing α for a target $p^* \in [1, 2]$ —is the scalar root

$$p_{\text{eff}}(\alpha) = p^*, \quad (142)$$

which we solve by bisection using the monotonicity in α (Algorithm 2).

C ADDITIONAL NOISE SWEEPS: $\sigma \in \{0, 0.5\}$

Experimental protocol. We replicate the experiments of §4.3 and §4.4 at two additional noise levels, $\sigma = 0$ and $\sigma = 0.5$, keeping everything else fixed (same $p \in \{1.1, 1.5, 1.9\}$ for explicit minimum- ℓ_p runs; same $\alpha \in \{0.00102, 0.0664, 0.229\}$ for DLNs with the same $\alpha \mapsto p_{\text{eff}}$ calibration

Algorithm 1 Slope-matching map $\alpha \mapsto p_{\text{eff}}(\alpha)$

Require: Log-grid \mathcal{A} of α values; log-grid $\mathcal{K} \subset \{1, \dots, d\}$ of k values
Ensure: $\{(\alpha, p_{\text{eff}}(\alpha)) : \alpha \in \mathcal{A}\}$

- 1: **for all** $\alpha \in \mathcal{A}$ **do**
- 2: Initialize lists $X \leftarrow [], Y \leftarrow []$ $\triangleright X = \{\log k\}, Y = \{\log Q_\alpha(\beta^{(k)})\}$
- 3: **for all** $k \in \mathcal{K}$ **do**
- 4: $z_k \leftarrow 1/(\alpha^2 \sqrt{k})$
- 5: Compute $q(z_k)$ using the closed form in equation 130; if $|z_k|$ is small, use the series
- 6: $q(z) = z^2/4 - z^4/192 + z^6/2560 + \dots$ for stability
- 7: $Q_k \leftarrow \alpha^2 k q(z_k)$
- 8: Append $\log k$ to X ; append $\log Q_k$ to Y
- 9: **end for**
- 10: Fit $Y \approx c(\alpha) + s(\alpha) X$ by least squares \triangleright by equation 139
- 11: $p_{\text{eff}}(\alpha) \leftarrow 2(1 - s(\alpha))$
- 12: **end for**
- 13: **return** $\{(\alpha, p_{\text{eff}}(\alpha)) : \alpha \in \mathcal{A}\}$

Algorithm 2 Inverse map $p^* \mapsto \alpha^*$ by bisection in $\log \alpha$

Require: Target $p^* \in [1, 2]$; grid \mathcal{K} ; bracket $0 < \alpha_{\min} < \alpha_{\max}$ with $p_{\text{eff}}(\alpha_{\min}) \leq p^* \leq p_{\text{eff}}(\alpha_{\max})$;
tolerance $\varepsilon > 0$

Ensure: α^* with $|p_{\text{eff}}(\alpha^*) - p^*| \leq \varepsilon$

- 1: $u_{\min} \leftarrow \log \alpha_{\min}, u_{\max} \leftarrow \log \alpha_{\max}$
- 2: **while** $u_{\max} - u_{\min} > \varepsilon$ **do**
- 3: $u_{\text{mid}} \leftarrow \frac{1}{2}(u_{\min} + u_{\max}), \alpha_{\text{mid}} \leftarrow e^{u_{\text{mid}}}$
- 4: Compute $p_{\text{eff}}(\alpha_{\text{mid}})$ via Algorithm 1 restricted to this single α
- 5: **if** $p_{\text{eff}}(\alpha_{\text{mid}}) < p^*$ **then**
- 6: $u_{\min} \leftarrow u_{\text{mid}}$
- 7: **else**
- 8: $u_{\max} \leftarrow u_{\text{mid}}$
- 9: **end if**
- 10: **end while**
- 11: **return** $\alpha^* \leftarrow e^{(u_{\min} + u_{\max})/2}$

as in Appendix B; same seeds and learning rates as indicated in the panel captions). Each plot overlays test MSE (left axis) and representative ℓ_r curves (right axis).

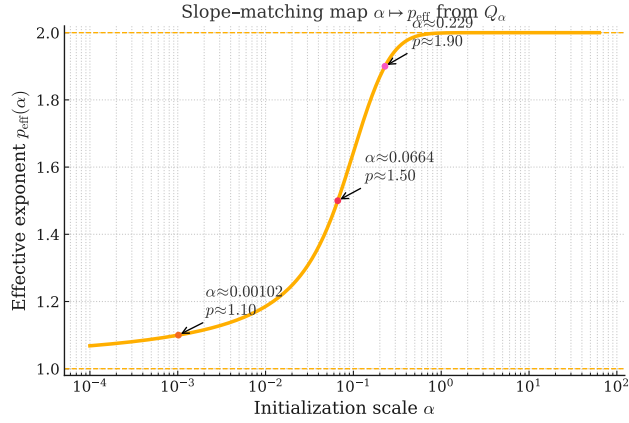
What the figures show and why. In Fig. S2-Fig. S9, the slopes and regime rules from Theorem 3.1 and Corollaries 4.1-4.2 are unchanged across σ ; noise only rescales τ_s and thereby shifts the transition size $n_* \asymp (\kappa_{\text{bulk}} \tau_s^q / W_q)^{2/(q-2)}$ [equation 8] and the spike-side plateau levels [equation 9]. Thus, compared to $\sigma=0.1$ in the main text: (i) at $\sigma=0$ elbows appear earlier and plateaus (for $r > 2(p-1)$) occur sooner and at lower levels; (ii) at $\sigma=0.5$ elbows are delayed and spike-side plateaus are higher. Bulk-dominated panels retain the $n^{1/2}$ growth and the r -ordering in equation 10.

D FINITE LEARNING RATE EFFECTS

We consider the single-spike case $w^* = e_1$ and a small shape parameter $\alpha = 0.00102$ (so the calibrated $p_{\text{eff}}(\alpha) \approx 1.10$). We vary the learning rate $\text{lr} \in \{10^{-1}, 10^{-2}, 10^{-3}\}$ and the label-noise level $\sigma \in \{0, 0.1, 0.5\}$. All panels plot generalization error (left axis) and $\ell_{1.1}$ norm (right axis) versus sample size n .

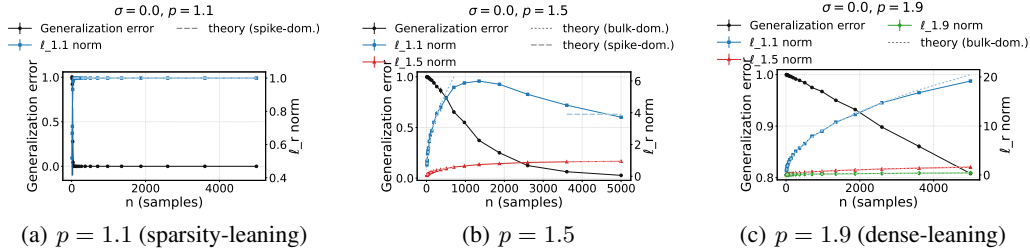
Observed effect. With **clean labels** ($\sigma = 0$), the $\ell_{1.1}$ norm is essentially flat across n and insensitive to lr (Fig. S10), consistent with a low- p_{eff} (sparse) implicit bias at small α . When **label noise is present** ($\sigma \in \{0.1, 0.5\}$), increasing the learning rate makes $\ell_{1.1}$ *increase with n* (Figs. S11, S12); the transition point (the ‘‘elbow’’) beyond which the norm would plateau shifts to larger n as lr grows. Within the accessible sample sizes this rightward shift makes the curve look bulk-dominated and rising—as if the effective exponent p_{eff} were larger.

1836
1837
1838
1839
1840
1841
1842
1843
1844
1845
1846
1847
1848
1849
1850



1851 Figure S1: Slope-matching map $\alpha \mapsto p_{\text{eff}}(\alpha)$ (Algorithm 1), obtained by fitting the k -sparse scaling
1852 of $Q_\alpha(\beta^{(k)})$ against the exact $k^{1-p/2}$ scaling of $\|\beta^{(k)}\|_p^p$. Target points ($p \in \{1.1, 1.5, 1.9\}$) are
1853 annotated; their corresponding α are solved by Algorithm 2.

1854
1855
1856
1857
1858
1859
1860
1861
1862
1863



1864 Figure S2: **Single spike** $w^* = e_1$; **explicit minimum- ℓ_p interpolation** ($\sigma = 0$). Earlier elbows
1865 and lower spike-side plateaus than at $\sigma=0.1$; bulk-side traces keep the $n^{1/2}$ slope, consistent with
1866 equation 9-equation 10.

1867
1868
1869
1870
1871
1872
1873
1874
1875
1876
1877
1878

Why this happens. Finite step size together with label/gradient noise injects additional stochasticity into the discrete dynamics. A useful approximation views (stochastic) gradient descent as a Langevin-type process with an *effective temperature* controlled by the learning rate and the noise level; this broadens the stationary distribution and leads to wider, less sparse solutions (Mandt et al., 2017; Smith et al., 2018; Yaida, 2018; Jastrzebski et al., 2017). For a single-spike target, that diffusion leaks mass into off-signal coordinates during early training, nudging the geometry away from “ ℓ_1 -like” toward a higher- p regime and delaying when the spike dominates—hence the elbow shifts right. With **clean labels**, the gradient remains aligned with the spike and the small-step implicit bias toward path/diagonal-norm solutions is recovered (Neyshabur et al., 2015a; Gunasekar et al., 2018a). The same qualitative phenomenon also appears for the denser case $s=50$ with a smaller magnitude.

1879 E LARGER SPARSITY s FOR EXPLICIT $\min \|w\|_p$ LINEAR REGRESSION

1880
1881
1882
1883
1884
1885

We revisit the explicit $\min \|w\|_p$ experiments at larger sparsities $s \in \{500, 5000\}$ for $p \in \{1.1, 1.5, 1.9\}$ under the same Gaussian design and noise $\sigma = 0.1$ as in the main text. Each panel reports generalization error (left axis) and several ℓ_r -norms of the *same* interpolating w (right axis); gray dashed curves are the bulk/spike theory overlays used earlier.

1886
1887
1888
1889

Comparison to $s=50$. Across all three p values, the larger- s experiments reprise the main-text regime structure at larger sample sizes. For $p \approx 1$, lengthening the bulk-dominated segment makes the initial *increase* in generalization error clearly visible (especially at $s=5000$), after which the curve turns downward as alignment improves. For $p \in \{1.5, 1.9\}$, the same right-shift occurs yet the curves remain monotone; the rounder objectives keep the estimator from over-relying on noisy directions

1890
1891
1892
1893
1894
1895
1896
1897
1898
1899
1900
1901
1902
1903
1904
1905
1906
1907
1908
1909
1910
1911
1912
1913
1914
1915
1916
1917
1918
1919
1920
1921
1922
1923
1924
1925
1926
1927
1928
1929
1930
1931
1932
1933
1934
1935
1936
1937
1938
1939
1940
1941
1942
1943

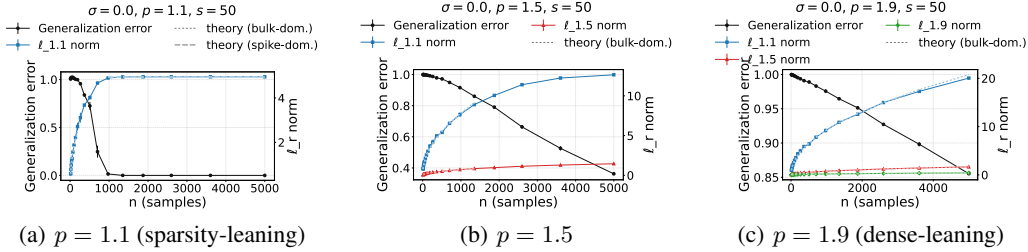


Figure S3: **Flat w^* ($s = 50$); explicit minimum- ℓ_p interpolation ($\sigma = 0$).** Same slope/plateau rules as Corollary 4.2, with a reduced transition scale and lower absolute ℓ_r levels compared to $\sigma=0.1$.

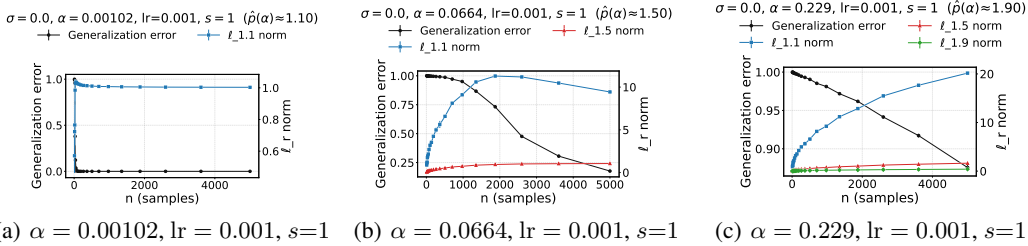


Figure S4: **Single spike $w^* = e_1$; DLN ($\sigma = 0$).** With α calibrated to $p_{\text{eff}}(\alpha)$, the regime structure mirrors the explicit p case: smaller p_{eff} exhibits earlier spike dominance and plateaus for $r > 2(p-1)$; larger p_{eff} stays bulk-dominated longer.

early on. In every panel, the blue $\ell_{1.1}$ curve remains a useful “regime meter”: rapid growth signals bulk influence, and gradual approach toward the spike guide signals improving alignment—even though none of the ℓ_r curves truly flatten within our plotted range.

Small p (here $p=1.1$). Relative to the $s=50$ panels in the main text, both larger- s slices preserve the same two-phase story but the handoff happens later in n . At $s=500$ (Fig. S13a), generalization error is flat-to-slightly higher at small n while $\|w\|_{1.1}$ rises rapidly; as n grows, generalization error begins to fall and the blue curve bends toward (but, in our range, does not meet) the spike overlay. At $s=5000$ (Fig. S14a), the shape is unmistakable: generalization error *first increases* to a visible peak at intermediate n and then drops. The $\ell_{1.1}$ curve keeps climbing throughout the displayed range, tracking the bulk-dominated guide before gradually approaching the spike prediction (without flattening). This “up-then-down” with more samples matches the double-descent picture for interpolating estimators—early fits lean on high-variance bulk directions; only later does the solution align with signal—well documented in linear and deep settings (Belkin et al., 2019; Nakkiran et al., 2020b; Hastie et al., 2022a).

Larger p (here $p=1.5$ and $p=1.9$). Compared to $s=50$, the curves again shift rightward in n , but the qualitative picture is unchanged: generalization error decreases *monotonically* over the whole range for both sparsities (Figs. S13b-c and S14b-c). The minimized ℓ_p -norms (red for $p=1.5$, green for $p=1.9$) drift only slightly upward rather than plateauing, while the auxiliary $\ell_{1.1}$ diagnostic continues its steady growth along the bulk guide. The absence of an initial increase in generalization error is consistent with the rounder geometry of larger- p balls: the interpolating solution spreads weight more evenly and avoids the brittle, variance-heavy fits that create the small- p bump, echoing analyses of benign overfitting/ridgeless least squares and convex-geometric shrinkage of descent cones (Bartlett et al., 2020; Hastie et al., 2022a; Chandrasekaran et al., 2012; Amelunxen et al., 2014).

F EXTENDING THE ℓ_r -SCALING THEOREM TO DIAGONAL LINEAR NETWORKS

This section is a blueprint for porting our main ℓ_r -scaling theorem from the minimum- ℓ_p interpolator to predictors selected by training *diagonal linear networks* (DLNs) with arbitrary depth. The goal

1944

1945

1946

1947

1948

1949

1950

1951

1952

1953

1954

1955

1956

1957

1958

1959

1960

1961

1962

1963

1964

1965

1966

1967

1968

1969

1970

1971

1972

1973

1974

1975

1976

1977

1978

1979

1980

1981

1982

1983

1984

1985

1986

1987

1988

1989

1990

1991

1992

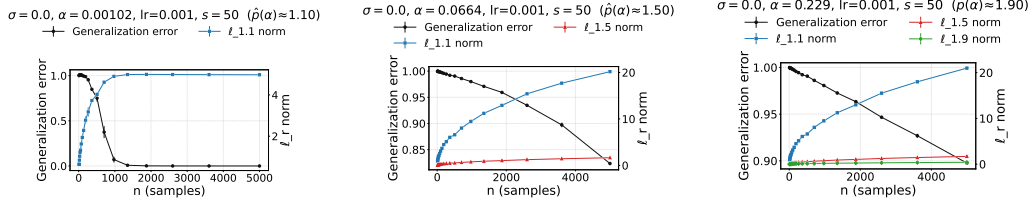
1993

1994

1995

1996

1997



(a) $\alpha = 0.00102$, $lr = 0.001$, (b) $\alpha = 0.0664$, $lr = 0.001$, $s=50$ (c) $\alpha = 0.229$, $lr = 0.001$, $s=50$

Figure S5: **Flat w^* ($s = 50$); DLN ($\sigma = 0$)**. The elbow shifts with support size as in the flat-support corollary; plateaus for $r > 2(p-1)$ occur earlier and at lower levels than at $\sigma=0.1$, while bulk-side $n^{1/2}$ growth persists where predicted.

1959

1960

1961

1962

1963

1964

1965

1966

1967

1968

1969

1970

1971

1972

1973

1974

1975

1976

1977

1978

1979

1980

1981

1982

1983

1984

1985

1986

1987

1988

1989

1990

1991

1992

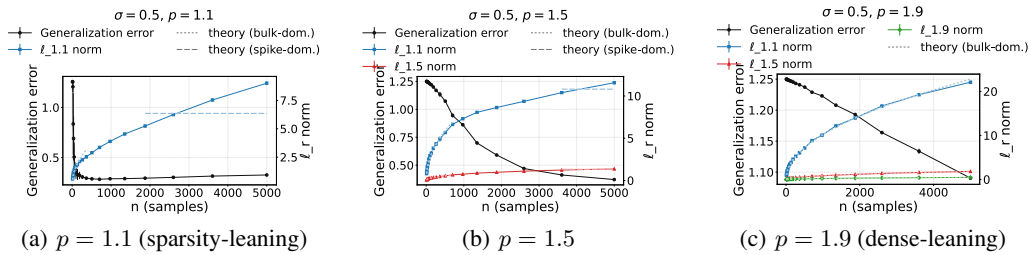
1993

1994

1995

1996

1997



(a) $p = 1.1$ (sparsity-learning)

(b) $p = 1.5$

(c) $p = 1.9$ (dense-learning)

Figure S6: **Single spike $w^* = e_1$; explicit minimum- ℓ_p interpolation ($\sigma = 0.5$)**. Larger τ increases both n_* and plateau heights relative to $\sigma=0.1$. Bulk-dominated panels retain the $n^{1/2}$ trend; $r > 2(p-1)$ traces flatten only after the later transition, in line with equation 9-equation 10.

is to reuse the entire spike+bulk argument with minimal surgery by swapping in the right implicit regularizer and the right one-dimensional balance. The guidance below covers both the two-layer case and the general depth- D case, aligning with the characterization of implicit bias in DLNs proved by Woodworth et al. (2020).

In our $\min \ell_p$ analysis, the predictor among all interpolators is selected by a separable power potential, and the proof runs through a dual “link” that maps the ray variable back to primal coordinates. DLNs fit exactly the same template:

- For two layers, the implicit regularizer is the hypentropy-type separable potential, and the link is the corresponding odd, strictly increasing map (Woodworth et al., Thm. 1). Non-uniform initialization simply reweights coordinates multiplicatively throughout.
- For depth $D \geq 3$, the implicit regularizer is again separable but with a depth-dependent link; Woodworth et al. (Thm. 3) identify the unique depth- D link and its inverse. Practically, you can treat it as “the D -link” playing the role occupied by the power map in $\min \ell_p$ and by the hypentropy link at $D = 2$.

No other structural change is needed: once the link is fixed, every step of our proof goes through with the same spike/bulk decomposition and the same ray reduction.

As in the $\min \ell_p$ proof, restrict the dual variable to the ray spanned by the labels and determine a single scale t from a strictly monotone one-dimensional balance. Conceptually:

- In the *kernel-like window* (small arguments of the link on both spike and bulk), the link linearizes and the entire analysis collapses to the $p = 2$ case *verbatim*. This is the “lazy” regime.
- In the *rich-like window* (arguments large on the bulk and/or a dominant spike), the nonlinearity of the link controls the transition. For two layers, the balance yields a Lambert- W controlled scale; for $D \geq 3$, the depth- D link gives a faster, polynomial-in-initialization tran-

1998

1999

2000

2001

2002

2003

2004

2005

2006

2007

2008

2009

2010

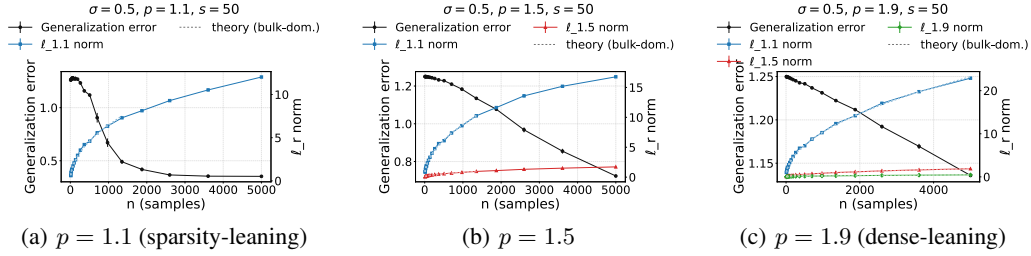


Figure S7: **Flat w^* ($s = 50$); explicit minimum- ℓ_p interpolation ($\sigma = 0.5$).** The same slope/plateau rules apply, but both the elbow and plateau heights shift upward with σ via τ_s and equation 8.

2011

2012

2013

2014

2015

2016

2017

2018

2019

2020

2021

2022

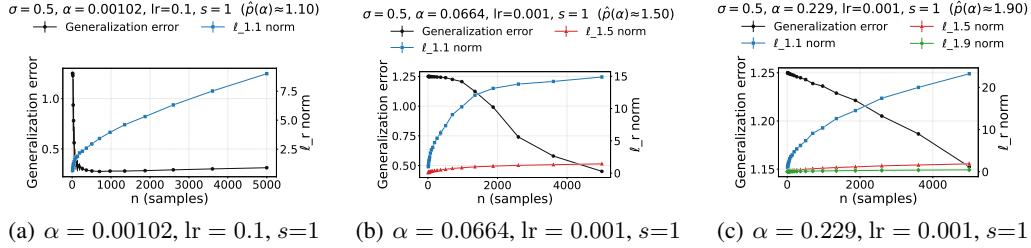


Figure S8: **Single spike $w^* = e_1$; DLN ($\sigma = 0.5$).** After calibrating $\alpha \mapsto p_{\text{eff}}$, bulk growth persists to larger n (larger n_*), and spike-side plateaus for $r > 2(p-1)$ emerge later and at higher levels.

2023

2024

2025

2026

2027

2028

2029

2030

2031

2032

2033

2034

2035

2036

2037

2038

2039

2040

2041

2042

2043

2044

2045

2046

2047

2048

2049

2050

2051

sition. You do not need a closed form—just the monotonicity and the small/large-argument asymptotics.

Bulk block. Replace the power moment used in the min ℓ_p bulk bound by the depth-appropriate scalar functional that averages the link across a standard Gaussian coordinate. Operationally:

- Define a *bulk scalar* by applying the DLN link at the ray scale to a single Gaussian coordinate and taking its ℓ_r moment (to the $1/r$). This plays the exact role of $m_t^{1/t}$ in the min ℓ_p proof.
- Use the same Gaussian embedding for the bulk design to lift this scalar to the full bulk contribution. In the kernel-like window you recover the $p = 2$ scaling exactly; in the rich-like window you get the accelerated depth- D growth predicted by the link's large-argument behavior.
- Keep track of the global scaling coming from the link's overall prefactor (this carries the initialization scale); it multiplies both bulk and spike-remainder terms.

Spike block. On the spike coordinates, keep the original two-part structure:

- *Spike-main*: apply the link to the mean shift determined by the signal; if a single coordinate dominates the one-dimensional balance, the selected predictor saturates at the spike scale and becomes essentially independent of the initialization (up to lower-order logarithmic or depth-dependent corrections).
- *Spike-remainder*: control the residual Gaussian fluctuation by the same operator-norm and concentration events as in the min ℓ_p proof; its ℓ_r size is the bulk scalar (at the ray scale) times $s^{\max\{1/r, 1/2\}}$, again multiplied by the link's global prefactor.

When spikes are *meek* relative to the bulk (no dominant coordinate), the spike block linearizes and you are back in the $p = 2$ laws.

Unified bound. After these replacements, the final display has the identical three-term structure:

$$\text{DLN predictor's } \ell_r \text{ size} = \text{maximum of (spike-main, bulk, spike-remainder),}$$

2052

2053

2054

2055

2056

2057

2058

2059

2060

2061

2062

2063

2064

2065

2066

2067

2068

2069

2070

2071

2072

2073

2074

2075

2076

2077

2078

2079

2080

2081

2082

2083

2084

2085

2086

2087

2088

2089

2090

2091

2092

2093

2094

2095

2096

2097

2098

2099

2100

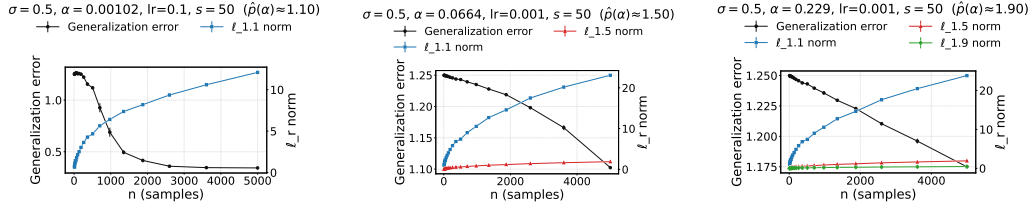
2101

2102

2103

2104

2105



(a) $\alpha = 0.00102$, $lr = 0.1$, $s = 50$ (b) $\alpha = 0.0664$, $lr = 0.001$, $s = 50$ (c) $\alpha = 0.229$, $lr = 0.001$, $s = 50$

Figure S9: **Flat w^* ($s = 50$); DLN ($\sigma = 0.5$).** The σ -driven increase in τ_s shifts n_* to larger n ; otherwise the bulk vs. spike regime behavior matches the theory and the explicit p experiments.

2064

2065

2066

2067

2068

2069

2070

2071

2072

2073

2074

2075

2076

2077

2078

2079

2080

2081

2082

2083

2084

2085

2086

2087

2088

2089

2090

2091

2092

2093

2094

2095

2096

2097

2098

2099

2100

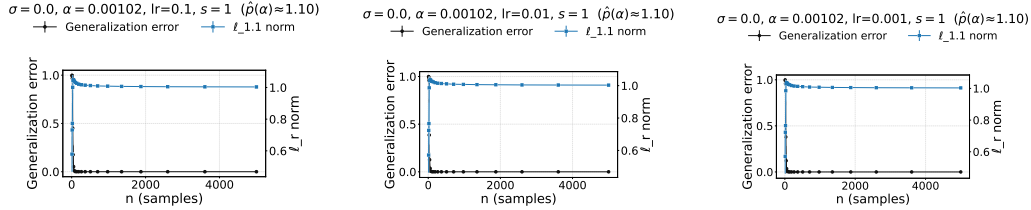
2101

2102

2103

2104

2105



(a) $\sigma = 0$, $\alpha = 0.00102$, $lr = 0.1$, $s = 1$ (b) $\sigma = 0$, $\alpha = 0.00102$, $lr = 0.01$, $s = 1$ (c) $\sigma = 0$, $\alpha = 0.00102$, $lr = 0.001$, $s = 1$

Figure S10: $w^* = e_1$ (**sparsity $s=1$, clean labels**). $\ell_{1,1}$ rapidly plateaus and is insensitive to learning rate, consistent with a low- p_{eff} implicit bias at small α .

with each term obtained from the min ℓ_p counterpart by: (i) replacing the power link with the DLN link; (ii) inserting the link’s global prefactor; and (iii) using the DLN bulk scalar in place of the power moment. In the kernel-like window this reproduces the $p = 2$ version *exactly*; in the rich-like window you get either bulk-controlled growth (Lambert- W for two layers; depth-accelerated for $D \geq 3$) or spike saturation.

Depth and initialization intricacy.

- **Depth $D \geq 3$.** The depth- D link is odd, strictly increasing, and has a simple linearization at the origin and an explicit rational form away from it (Woodworth et al., Thm. 3). This yields the same kernel-like reduction and a sharper rich-like transition than at $D = 2$. You never need its closed form—only its monotonicity and asymptotics.
- **Non-uniform initialization.** The per-coordinate *shape* of the initialization simply reweights the separable potential and carries multiplicatively through the link. Every bound inherits these weights in a purely multiplicative way (Woodworth et al., Thm. 1).
- **Limits.** Large initialization recovers the minimum- ℓ_2 norm predictor; vanishing initialization recovers the minimum- ℓ_1 predictor (with the usual caveats on how small “small” must be). These are the DLN analogues of the kernel and rich limits and hold for all depths covered above.

A handy dictionary for porting the proof. To translate any display or lemma from the min ℓ_p analysis to DLNs, we can make the following substitutions:

1. **Power link** \rightarrow **DLN link**: replace the power map by the depth-appropriate link (hypentropy at two layers; the depth- D link from Woodworth et al. otherwise), including its global prefactor.
2. **Ray scale** \rightarrow **DLN balance**: keep the same one-dimensional, strictly monotone balance along the label ray; solve it numerically or via asymptotics (linear in the kernel-like window; Lambert- W at two layers and power-law at depth $D \geq 3$ in the rich-like window).

2106

2107

2108

2109

2110

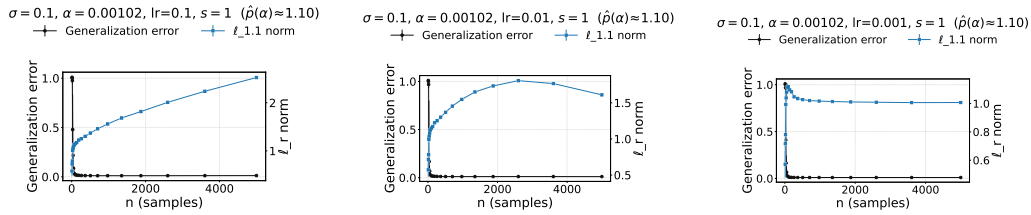
2111

2112

2113

2114

2115



(a) $\sigma = 0.1, \alpha = 0.00102, \text{lr} = 0.1, s = 1$ (b) $\sigma = 0.1, \alpha = 0.00102, \text{lr} = 0.01, s = 1$ (c) $\sigma = 0.1, \alpha = 0.00102, \text{lr} = 0.001, s = 1$

Figure S11: $w^* = e_1$ (sparsity $s=1$), moderate noise. Larger learning rates produce a steadily rising $\ell_{1.1}$ and shift the elbow to larger n ; decreasing lr suppresses the rise and restores a near-plateau.

2116

2117

2118

2119

2120

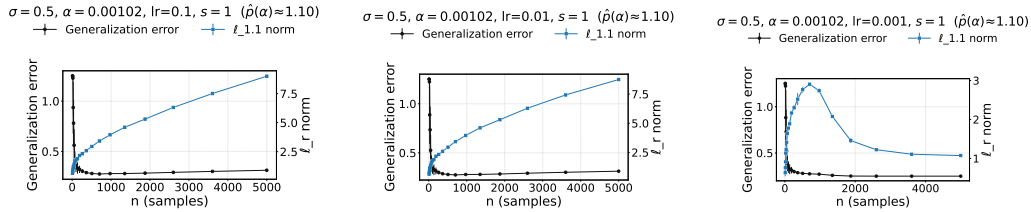
2121

2122

2123

2124

2125



(a) $\sigma = 0.5, \alpha = 0.00102, \text{lr} = 0.1, s = 1$ (b) $\sigma = 0.5, \alpha = 0.00102, \text{lr} = 0.01, s = 1$ (c) $\sigma = 0.5, \alpha = 0.00102, \text{lr} = 0.001, s = 1$

2126

2127

2128

2129

2130

2131

2132

2133

2134

2135

2136

2137

2138

2139

2140

2141

2142

2143

2144

2145

2146

2147

2148

2149

2150

2151

2152

2153

2154

2155

2156

2157

2158

2159

Figure S12: $w^* = e_1$ (sparsity $s=1$), heavy noise. The learning-rate-induced increase in $\ell_{1.1}$ is strongest at high noise: $\text{lr}=0.1$ (and to a lesser extent 0.01) yields monotone growth with n , whereas $\text{lr}=0.001$ shows a transient bump and then relaxes toward a plateau—evidence that the elbow shifts right under larger lr.

3. **Bulk scalar:** replace the power moment by the ℓ_r moment of the DLN link applied to a single Gaussian coordinate at the ray scale; lift via the Gaussian embedding exactly as before.
4. **Spike block:** reuse the deterministic-plus-Gaussian decomposition, the operator-norm and concentration events, and the same ℓ_r geometry; only the link and its global prefactor change.

With the substitutions above, the ℓ_r -scaling analysis for the minimum- ℓ_p interpolator transfers directly to DLNs of any depth. The proof structure, the spike/bulk decomposition, and the final three-term form remain identical; only the link and its scalar balance change. Two layers inherit a Lambert- W bulk scale; deeper networks transition faster with initialization due to their depth- D link. In the kernel-like window, everything collapses to the $p = 2$ bounds almost word-for-word.

2160
2161
2162
2163
2164
2165
2166
2167
2168
2169
2170
2171
2172
2173
2174
2175
2176
2177
2178
2179
2180
2181
2182
2183
2184
2185
2186
2187
2188
2189
2190
2191
2192
2193
2194
2195
2196
2197
2198
2199
2200
2201
2202
2203
2204
2205
2206
2207
2208
2209
2210
2211
2212
2213

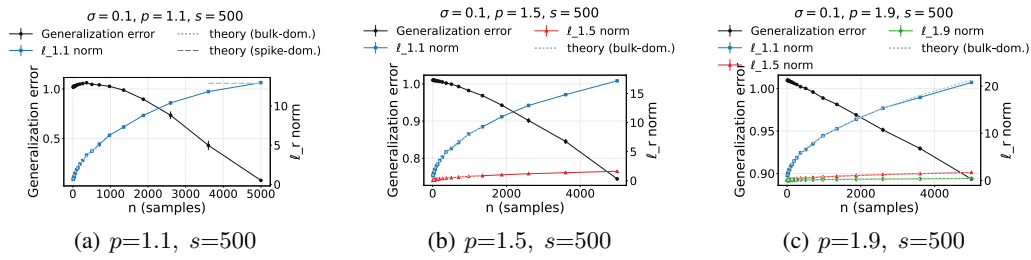


Figure S13: **Large sparsity**, $s=500$. Black—generalization error; colored— ℓ_r -norms of the same interpolator (blue: $\ell_{1.1}$, red: $\ell_{1.5}$, green: $\ell_{1.9}$); gray dashed—bulk/spike overlays.

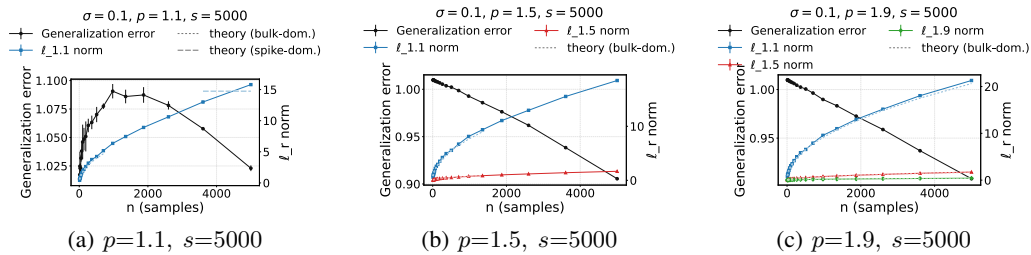


Figure S14: **Even larger sparsity**, $s=5000$. Same conventions as Fig. S13. Increasing s shifts the bulk→spike crossover to larger n .