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# Relational Out-of-Distribution Generalization

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## Abstract

1 In out-of-distribution (OOD) generalization, domain relation is an important factor.  
2 It can provide a global view on the functionality among domains, *e.g.*, the protein  
3 domain in the binding affinity task or the geographical location domain in the  
4 weather forecast task. Existing work lacks the utilization of the domain relation;  
5 yet in this work, we want to explore how to incorporate such rich information into  
6 solving the distribution shift problem. Therefore, we propose READ, a general  
7 multi-head deep learning framework that harnesses domain relation to generalize  
8 to unseen domains in a structured learning and inference manner. In READ, each  
9 training domain shares a common backbone but learns one separate head. Built  
10 on a proposed explicit regularization, READ simulates the generalization process  
11 among heads, where a weighted ensemble prediction from heads irrelevant to  
12 input domain is calculated via domain relation and aligned with the target. To  
13 improve the reliability of domain relation, READ further leverages similarity metric  
14 learning to update initial relation. Empirically, we evaluate READ on three domain  
15 generalization benchmarks. The results indicate that READ consistently improves  
16 upon existing state-of-the-art methods on datasets from various fields.

## 17 1 Introduction

18 Distribution shift is a universal problem in the real-world scenarios [10, 14], where the test distribution  
19 is different from the training distribution. Yet, recent evidence suggests that deep neural networks  
20 can be sensitive to distribution shifts, exhibiting a dramatic performance degradation within new  
21 environments [4, 21, 26]. Thus, distribution shift is a challenging but rewarding task.

22 In this paper, we refer to this problem as the out-of-distribution (OOD) generalization and specifically  
23 focus on domain shifts. In domain shifts, the test data is from unseen domains, and a well-trained  
24 model should be able to possess the good generalization ability to test domains without seeing the  
25 data from those domains at training time. For example, in AI-aided Drug Discovery (AIDD), we  
26 train a model on data from a fixed set of known target proteins, which is treated as domains. Then  
27 we deploy the model to new targets with unseen data distribution. Recent work [12] has proven that  
28 existing OOD algorithms fail to generalize in this specific setting.

29 To improve model robustness under domain shifts, recent studies align training domains and learn  
30 domain-invariant representations or predictors [3, 18, 27]. Unfortunately, most invariant learning  
31 approaches do not exhibit substantial improvements compared to standard ERM [30] training on  
32 various real-world datasets [12, 37]. One potential reason in such failure cases is that some test  
33 domains only correlate with a few training domains. For every test domain, involving uncorrelated  
34 training domains to train a model is useless or even hurts the performance. To generalize on such  
35 data with correlations between domains, we formulate a novel problem called relational OOD, and  
36 introduce another promising direction in utilizing the domain relation to solve this task.

37 Thus, we propose **READ**, a relation-aware algorithm to harness domain relation in a structured  
38 learning and inference manner and improve out-of-distribution robustness. Specifically, we first

39 extract pairwise domain relations from the data source. Then, READ aims to optimize the objective  
 40 function, which is composed of two parts: (1) the supervised loss, an empirical loss for each input and  
 41 target pair; (2) the domain alignment regularization, an attention loss weighted by a score function  
 42 based on both the ground-truth and learned domain relation. READ adds the second loss to mimic the  
 43 cases where the tasks are unknown and out-of-distribution. Lastly during the test time, when given  
 44 the new test domain, READ learns the relation between the new domain and all training domains, so  
 45 as to weigh the objective function.

46 To sum up, our **main contributions** are: we investigate and formalize an important yet underexplored  
 47 problem - OOD generalization with domain relation, and propose a effective multi-head deep learning  
 48 framework called READ, which leverages domain relation for ensemble and alignment over domains.  
 49 We empirically demonstrate the effectiveness of READ under domain shifts. By utilizing the domain  
 50 relation, we observe that READ outperforms prior state-of-the-art invariant learning methods.

## 51 2 Relational Out-of-Distribution Generalization

### 52 2.1 Problem Formulation

53 In this section, we present our formulation of relational OOD problem. We focus on the domain  
 54 shift setting, where the overall data distribution is drawn from a set of domains  $\mathcal{D}$ . Each domain  
 55  $d \in \mathcal{D}$  corresponds with a dataset  $(x_i, y_i, d)_{i=1}^{N_d}$  sampled from the domain-specific distribution  $p_d$ ,  
 56 where  $x_i \in \mathcal{X}$  is the input feature and  $y_i \in \mathcal{Y}$  is the prediction target. The relationship between  
 57 domains is described by a domain graph with the weighted adjacency matrix  $A = [A_{ij}]$ , where  $i, j$   
 58 index nodes (domains) in the graph and  $A_{ij}$  holds the weight between  $i$  and  $j$ . The detailed data  
 59 composition of relational OOD is shown in Appendix B. We split all domains into training domains  
 60  $\mathcal{D}^{tr}$  and test domains  $\mathcal{D}^{ts}$ , where  $\mathcal{D}^{tr} \cup \mathcal{D}^{ts} = \mathcal{D}$  and  $\mathcal{D}^{tr} \cap \mathcal{D}^{ts} = \emptyset$ . Our goal is to learn a robust  
 61 and generalizable predictive model  $f : \mathcal{X} \times \mathcal{D} \rightarrow \mathcal{Y}$  using data from the training domains  $\mathcal{D}^{tr}$  and  
 62 the given domain relation graph  $A$  to achieve a minimum prediction error on test domains  $\mathcal{D}^{ts}$ :

$$\min_{\theta} \mathbb{E}_{(x,y,d) \sim P^{ts}} [\ell(f_{\theta}(x, d, A), y)]. \quad (1)$$

### 63 2.2 Overall Pipeline

64 To better leverage the rich knowledge  
 65 in domain relation, we would like a  
 66 method that can build strong correla-  
 67 tion among domains. To accomplish  
 68 this, we introduce READ to ensemble  
 69 and align over domains. The key  
 70 idea motivating READ is to explicitly  
 71 learn a collection of diverse functions  
 72 that are consistent with training do-  
 73 main knowledge and link them with  
 74 test domains via domain relation. As  
 75 outlined in Figure 1, READ adopts  
 76 an encoder-decoder architecture to ex-  
 77 tract features. Then, we replace origi-  
 78 nal single-head predictor with a multi-  
 79 head one, where each domain is as-  
 80 signed with a separate head. To better  
 81 utilize the domain relation, we intro-  
 82 duce a domain-relational learner, which  
 is jointly trained with our prediction  
 model. In practice, READ generates  
 diverse results for each head, insert  
 domain relations across heads, and  
 leverage such relations for prediction.

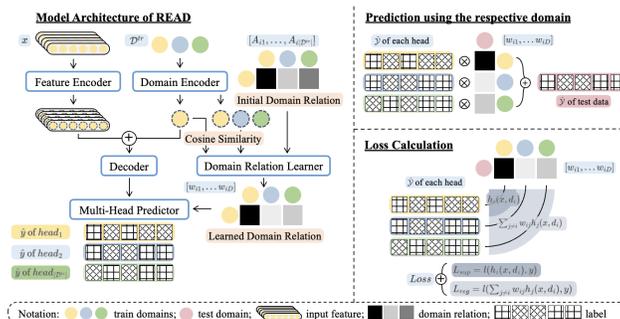


Figure 1: An illustration of READ. **Left:** Model architecture of READ, where  $x$  is data from domain  $d_i$ . **Right:** The behavior of READ during training and inference.

### 83 2.3 Relational Ensemble and Alignment among Domain-Specific Heads

84 As described above, we build a specific head  $h_i$  for each training domain (i.e.,  $d \in \mathcal{D}^{tr}$ ). Here  
 85 we denote the number of heads as  $n = |\mathcal{D}^{tr}|$ . To support our relational ensemble, two essential  
 86 components are the predictions from each head and learned domain relation. Therefore, we first  
 87 extract the features and estimate the outcomes with the encoder-decoder model  $f$  and prediction  
 88 heads  $h_i (i \in [n])$ . Simultaneously, we produce weight  $w_{ij}$  for each domain index pair using domain  
 89 relation learner. Next, we can ensemble and align over domains with these two components.

90 **Model Learning.** We train the model parameters  $\theta$  by optimizing the regular supervised loss and  
 91 additional regularization loss. For training data  $x$  from domain  $d_i$ , we first calculate the supervised  
 92 loss using the  $i$ -th head. Then, we ensemble results from other heads via learned relation and mimic  
 93 the generalization process with a domain alignment regularization forcing it to be consistent with  
 94 target.

95 Therefore, for a data point  $(x, y, d_i)$  and initial relation  $A$ , we have:

$$Loss(x, d_i, y, A) = \mathcal{L}_{sup} + \lambda \cdot \mathcal{L}_{reg} = \ell(h_i(x, d_i, A), y) + \lambda \cdot \ell\left(\frac{\sum_{j \neq i} w_{ij} h_j(x, d_j, A)}{\sum_{j \neq i} w_{ij}}, y\right), \quad (2)$$

96 where  $\lambda$  is the regularization weight and  $\ell$  is the loss function dedicated to a downstream task.

97 **Model Inference.** To infer outcomes on unseen test domain  $d_j$ , we would need to produce weighted  
 98 ensemble among all heads. Given the prediction from head  $h_i$  and learned relation  $w_{ij}$  for each  
 99 domain index pair  $(i, j)$ , it is straightforward to ensemble as follows:

$$\hat{y} = \frac{\sum_{i=1}^n w_{ij} h_i(f(x, d_j, A))}{\sum_{i=1}^n w_{ij}} \quad (3)$$

100 where  $x$  is a data point on  $d_j$ ,  $A$  is the initial domain relation, and  $f$  is the encoder-decoder model.  
 101 Furthermore, since the learned domain relation is fixed in test, we only parallel calculate relations for  
 102 all test domains once, indicating our domain relation learner brings little overhead during inference.

## 103 2.4 Similarity-based Domain Relation Learning

104 Following [17], we cast domain relation learning into a similarity metric function. As it takes domain  
 105 representations (denoted as  $Z$ ) and weighted adjacency matrix  $A$  as input and outputs a new relation  
 106 denoted by  $A'$ , we involve a two-step process. The first step follows the multi-head weighted cosine  
 107 similarity learning method previously used by [7], while the second step incorporates the information  
 108 of the original relation input.

109 We denote  $\{\mathbf{w}_i\}_{i=1}^m$  as  $m$  independent learnable weight vectors. Without loss of generality, we  
 110 compute the estimation for relation between domain index pair  $(u, v)$  as

$$a_{uv} = \frac{1}{m} \sum_{i=1}^m \cos(\mathbf{w}_i \odot \mathbf{z}_u, \mathbf{w}_i \odot \mathbf{z}_v), \quad (4)$$

111 where  $z_u$  and  $z_v$  are respectively the representations of domain  $d_u$  and  $d_v$ .

112 Next, to inherit the information from original domain relation, we combine the learned relation  $A_{tmp}$   
 113 and initial relation  $A$  with smoothing parameter  $\alpha$  to get output  $A'$ :

$$A' = \alpha \times A + (1 - \alpha) \times A_{tmp}. \quad (5)$$

114 We use  $A'$  to replace  $A$  in Eqn. (2) and (3).

## 115 3 Experiment

116 In this section, we conduct comprehensive experiments to evaluate the effectiveness of READ. More  
 117 experimental analysis can be find in Appendix G.

### 118 3.1 Datasets and Baselines

119 Following [19, 35] we evaluate READ on three benchmarks: (1) *DG-15*: 2D synthetic dataset, (2)  
 120 *TPT-48*: weather prediction dataset, (3) *ChEMBL-STRING* (ChEMBL 50 and ChEMBL 100): drug  
 121 discovery dataset. We present detailed descriptions of datasets in Appendix C.

122 Our main baselines are general-purpose methods with different learning strategies and categories  
 123 including (1) *vanilla*: ERM [30], (2) *distributionally robust optimization*: GroupDRO [24], (3) *data*  
 124 *augmentation*: Mixup [34], (4) *domain-invariant feature learning*: IRM [3], DANN [9], CORAL [27]  
 125 (See Appendix D for more detail). For fair comparison, we adopt the same model architectures and  
 126 same input  $x, y, d$  to the model (Eqn. (1)) for all approaches. All hyperparameters are selected via  
 127 cross-validation. We list all hyperparameters in Appendix in E.

128 **3.2 Experiment Results**

129 **DG-15.** The performance of READ and prior methods on DG-15 is reported in Table 1. READ has  
 130 an unparalleled advantage over all baselines with an outperformance of more than 30%. Moreover,  
 131 previous methods perform even worse than random guess (50% accuracy), indicating the necessity of  
 132 incorporating domain relation to transfer information among domains with high correlation.

Table 1: Results of domain shift on DG-15. Averaged accuracy is reported. See full table with standard deviation in Appendix F.1. We **bold** the best results and underline the second best results.

Algorithm	ERM	GroupDRO	Mixup	IRM	DANN	CORAL	<b>READ (ours)</b>
Accuracy	44.0%	<u>47.1%</u>	41.3%	43.9%	43.1%	43.5%	<b>77.5%</b>

133 For further understanding on how READ works on DG-15, Figure 2 visualizes data distribution on  
 134 DG-15 and the corresponding predictions from GroupDRO and READ. Train/test split is depicted  
 135 in Figure 2a. The comparison between Figure 2b with Figure 2c shows that GroupDRO learns a  
 136 linear decision boundary that overfits the training domains under domain shift. In contrast, READ  
 137 successfully generalize to test domains in Figure 2d except one without nearby training domain.

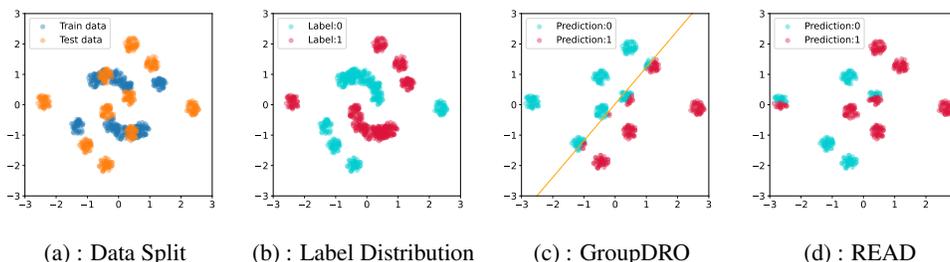


Figure 2: Visualization on DG-15. (a): Train/test split; (b): Label distribution; (c) Predictions from GroupDRO (our best baseline); (d) Predictions from READ.

138 **TPT-48.** Table 2 presents the MSE of our algorithm and previous methods on TPT-48. The results  
 139 shows that Mixup, IRM and DANN achieve negative performance, highlighting the difficulty of  
 140 tackling domain shift among geographic-related states. In comparison, READ achieves the lowest  
 MSE, indicating its suitability for regression tasks. We present the full results in Appendix F.2.

Table 2: Results of domain shift on TPT-48. We report the average MSE here.

Algorithm	ERM	GroupDRO	Mixup	IRM	DANN	CORAL	<b>READ (ours)</b>
MSE	0.108	<u>0.096</u>	0.179	0.135	0.122	0.103	<b>0.091</b>

141

142 **ChEMBL-STRING.** Figure 3 shows the results of  
 143 various methods on ChEMBL-STRING. READ out-  
 144 performs previous methods in both ROC-AUC score  
 145 and average accuracy, illustrating the effectiveness  
 146 of READ. Therefore, READ provides a fast way to  
 147 transfer knowledge to new proteins in drug discovery.  
 148 We also observe that in this task, all previous OOD  
 149 algorithms except CORAL exhibit no clear improve-  
 150 ment over the simple ERM algorithm.

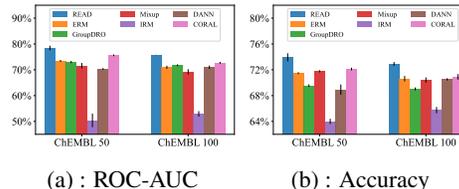


Figure 3: Results of domain shifts on ChEMBL 50 and ChEMBL 100. **Left:** ROC-AUC score; **Right:** Average accuracy.

151 **4 Conclusion**

152 In this paper, we investigate relational OOD, a natural extension of classical domain shift problem.  
 153 We propose an effective and efficient algorithm called READ to tackle this problem. READ aims  
 154 to leverage ensemble and alignment domain-specific heads via domain relation. We evaluate the  
 155 effectiveness of READ on three domain shift benchmarks from different fields, demonstrating its  
 156 promise. Besides, detailed analyses verify that the performance gains caused by READ result from  
 157 our proposed domain alignment regularization and relation learner.

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261 **A Related Work**

262 Here, we discuss related approaches that solve the OOD generalization from the following two categories:

263 **Learning Invariant Representations.** Inspired by unsupervised domain adaptation [5, 9], the first category of  
 264 works aligns representations across domains to learn invariant representations. The major research line of this  
 265 category aims to eliminate the domain dependency by minimizing the divergence of feature distributions with  
 266 different distance metrics, e.g., maximum mean discrepancy [20, 29], an adversarial loss [9, 18], Wassertein  
 267 distance [40]. Follow-up works applied data augmentation to (1) generate more domains and enhance the  
 268 consistency of representations during training [25, 33, 34, 36, 38, 41] or (2) generate new domains in an  
 269 adversarial way to imitate the challenging domains without using training domain information [23, 31, 39].  
 270 Instead of feature distributions, READ focuses on alignment among logits using domain relation, providing a  
 271 fresh perspective to the field of domain alignment.

272 **Learning Invariant Predictors.**

273 Beyond using domain alignment to learning invariant representations, recent work aims to further enhance  
 274 the correlations between the invariant representations and the labels [15], leading to invariant predictors.  
 275 Representatively, motivated by casual inference, invariant risk minimization (IRM) [3] and its variants [2, 11, 13]  
 276 aim to find a predictor that performs well across all domains through regularizations. Other follow-up works  
 277 leverage regularizers to penalize the variance of risks across all domains [16], to align the gradient across  
 278 domains [15], to smooth the cross-domain interpolation paths [8], or to involve game-theoretic invariant  
 279 rationalization criterion [6]. In contrast, READ encourages its prediction heads correlated to domains and  
 280 ensembles them with domain relation to generate a test-domain-related predictor.

281 **B Problem Formulation**

282 In Figure 4, we provide an illustration of our relation OOD. Let  $\mathcal{X}$  be the input (feature) space,  $\mathcal{Y}$  be the target  
 283 (label) space and  $\mathcal{D}$  be the domain space, the dataset can be decomposed into several samples  $(x, y, d)$  from  
 284  $\mathcal{X} \times \mathcal{Y} \times \mathcal{D}$ , and a weighted adjacency matrix  $A$  representing the domain relation graph.

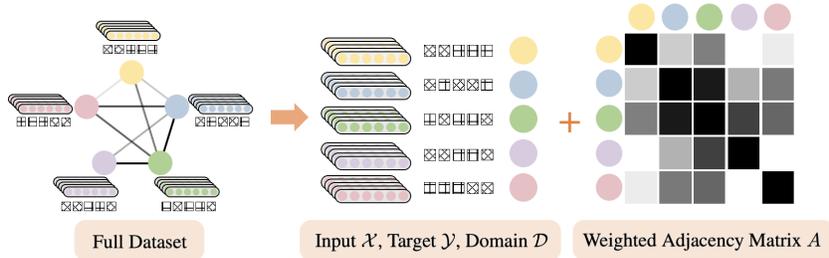


Figure 4: An illustration of our problem formulation. Each color represents one domain. The transparency of edges indicates domain relation, with low transparency meaning close relation and vice versa.

285 **C Detailed Description of Dataset**

286 **DG-15.** Following [35], We start with a synthetic 2D binary classification dataset with 15 domains called  
 287 DG-15. In each domain  $i$ , we randomly sample one point  $p_i = (x_i, y_i)$  in the 2-dimensional space. The domain  
 288 embedding is the angle of each point (i.e.,  $d_i = \arctan(\frac{y_i}{x_i})$ ). Next, 50 positive and 50 negative data points  
 289 are generated from two different 2-dimensional Gaussian distributions  $\mathcal{N}(p_i, \mathbf{I})$  and  $\mathcal{N}(-p_i, \mathbf{I})$  respectively.  
 290 In DG-15, we directly use the included angle of the two half-lines starting from the origin point and passing  
 291 through  $p_i, p_j$  to construct the relation between domain  $i$  and  $j$  (i.e.,  $A_{ij} = \arctan(\frac{y_j}{x_j}) - \arctan(\frac{y_i}{x_i})$ ). The  
 292 number of training, validation and test domains are 5, 5, 5 respectively.

293 **TPT-48.** TPT-48 is a real-world weather prediction dataset from the National Oceanic and Atmospheric  
 294 Administration’s Climate Divisional Database (nClimDiv) and Gridded 5km GHCN-Daily Temperature and  
 295 Precipitation Dataset (nClimGrid) [32], where the monthly average temperature for the 48 contiguous states in  
 296 the US from 2008 to 2019 is collected. We process the data following Washington Post [1] and focus on the  
 297 regression task that forecasts the next 6 months’ temperature based on previous first 6 months’ temperature. The  
 298 embedding of domain  $i$  is defined as the latitude and longitude of state  $i$ -th geographic center, which can be  
 299 denoted as  $d_i = (Lat_i, Lng_i)$ . In TPT-48, we use a 0/1 adjacency matrix as the domain relation, and domain

300  $i, j$  are connected (i.e.,  $A_{ij} = 1$ ) if they are adjacent states. We split all 48 states into 24 training, 12 validation  
 301 and 12 test domains.

302 **ChEMBL-STRING.** We also consider a scientific dataset from the chemistry field. ChEMBL [22] is a dataset  
 303 for the binding affinity task, which records the interaction between a small molecule and a target protein. Namely,  
 304 each data point is a molecule, and each task is to predict if the molecule can interact with the protein accordingly.  
 305 We cluster all tasks into several domains using their protein sequences. ChEMBL-STRING [19] was recently  
 306 proposed. It adds the domain relation (i.e., the protein relation) on ChEMBL by adopting the proteins using  
 307 protein-protein interaction (PPI) scores from STRING [28]. The intuition is that the PPI is able to provide a large  
 308 knowledge base that can be expected to connect the unseen proteins with the training proteins, enabling the fast  
 309 knowledge generalization/transfer. Due to the sparsity of the domain relation in ChEMBL (i.e., the PPI scores  
 310 of most protein pairs are 0), we densify the relation graph by iteratively filtering out proteins whose number  
 311 of nonzero PPI is lower than a certain threshold. By setting the threshold value to 50 and 100, we obtain two  
 312 relatively dense benchmark subsets called ChEMBL 50 and ChEMBL 100. The detailed statistics of ChEMBL  
 313 50 and 100 are listed in Table 3.

Table 3: Statistics about ChEMBL 50 and 100 datasets, where we use proteins as domains. Sparsity here is defined as the ratio of zero values in the relation graph.

Dataset	# Samples	# Proteins	Sparsity	# Train Proteins	# Valid Proteins	# Test Proteins
ChEMBL 50	87908	141	0.914	93	19	29
ChEMBL 100	58823	122	0.911	74	24	24

## 314 D Detailed Description of Baselines

315 In this work, we compare READ with several invariant learning approaches, i.e., ERM [30], GroupDRO [24],  
 316 Mixup [34], IRM [3], DANN [9], CORAL [27]. GroupDRO optimizes the worst-domain loss. Inter-domain  
 317 Mixup performs ERM on linear interpolations of examples from random pairs of domains and their labels. IRM  
 318 learns invariant predictors that perform well across different domains. DANN employs an adversarial network to  
 319 match feature distributions. CORAL matches the mean and covariance of feature distributions.

## 320 E Detailed Hyperparameters

Table 4: Hyperparameters for READ on all datasets.

Hyperparameters	DG-15	TRT-48	ChEMBL 50	ChEMBL 100
Learning Rate	1e-5	1e-4	1e-4	1e-4
Weight Decay	5e-4	5e-4	0	0
Batch Size	10	64	30	30
Epochs	30	40	100	100
Warm Start Epochs	5	10	10	10
Regularization Weight $\lambda$	0.5	0.5	0.5	0.5
Relation keep Ratio $\alpha$	0.8	0.8	0.5	0.5

## 321 F Additional Experiment Results

### 322 F.1 Full Results on DG-15

Table 5: Full results of domain shift on DG-15.

Algorithm	ERM	GroupDRO	Mixup	IRM	DANN	CORAL	<b>READ (ours)</b>
Accuracy	44.0 $\pm$ 4.6%	<u>47.1 <math>\pm</math> 9.0%</u>	41.3 $\pm$ 3.9%	43.9 $\pm$ 5.1%	43.1 $\pm$ 4.5%	43.5 $\pm$ 1.5%	<b>77.5 <math>\pm</math> 2.5%</b>

323 **F.2 Full Results on TPT-48**

Table 6: Full results of domain shift on TPT-48.

Algorithm	ERM	GroupDRO	Mixup	IRM	DANN	CORAL	READ (ours)
MSE	0.108 ± 0.002	<u>0.096 ± 0.001</u>	0.179 ± 0.012	0.135 ± 0.003	0.122 ± 0.019	0.103 ± 0.004	<b>0.091 ± 0.003</b>

324 **F.3 Full Results on ChEMBL-STRING**

Table 7: Full results of domain shifts on ChEMBL 50 and 100.

	ChEMBL 50		ChEMBL 100	
	ROC-AUC	Accuracy	ROC-AUC	Accuracy
ERM	73.43 ± 0.40%	71.47 ± 0.10%	70.99 ± 0.61%	70.62 ± 0.42%
GroupDRO	72.99 ± 0.43%	69.54 ± 0.20%	71.75 ± 0.37%	69.03 ± 0.23%
Mixup	71.57 ± 1.06%	71.77 ± 0.17%	69.20 ± 1.04%	70.41 ± 0.41%
IRM	50.39 ± 2.62%	64.01 ± 0.40%	52.91 ± 1.05%	65.76 ± 0.48%
DANN	70.31 ± 0.35%	68.93 ± 0.80%	71.00 ± 0.67%	70.51 ± 0.18%
CORAL	<u>75.60 ± 0.33%</u>	<u>72.11 ± 0.21%</u>	<u>72.69 ± 0.37%</u>	<u>70.91 ± 0.42%</u>
<b>READ (ours)</b>	<b>77.98 ± 0.30%</b>	<b>74.07 ± 0.27%</b>	<b>75.56 ± 0.11%</b>	<b>73.02 ± 0.16%</b>

325 **G Analysis**

326 Finally, we do analysis on ChEMBL-STRING to understand the effect of each module in READ.

327 **How do domain relation benefits ensemble inference?**

328 We compare our weighted ensemble using domain relation  
 329 with a simple uniform ensemble strategy during inference in  
 330 Table 8. The performance gap shows the effectiveness of our  
 331 strategy. In addition, we observe that the uniform ensemble  
 332 strategy also outperforms ERM, indicating the potential of  
 333 READ in scenarios that only relation between training domains is available.

Table 8: Comparison between ensemble strategies. ROC-AUC is reported.

	ChEMBL 50	ChEMBL 100
Uniform Ensemble	75.29 ± 0.21%	73.33 ± 0.12%
Weighted Ensemble	<b>78.42 ± 0.90%</b>	<b>75.85 ± 0.04%</b>

334 **Does regularization improve performance?**

335 By finetuning the regularization weight  $\lambda$  from 0 to 2,  
 336 we analyze the effect of domain alignment regulariza-  
 337 tion and test the model’s sensitivity. The correspond-  
 338 ing ROC-AUC and accuracy are respectively shown  
 339 in Figure 5. First, when  $\lambda = 0$  (i.e., no regulariza-  
 340 tion), READ’s performance is lower than those with  
 341 a positive  $\lambda$ , confirming the effectiveness of the rela-  
 342 tional alignment. Moreover, when we vary  $\lambda$  between  
 343 0.5 and 2,  $\lambda$  around 0.5 achieves the best results, indi-  
 344 cating that too large  $\lambda$  will result in weaker correlation  
 345 between each domain and its corresponding head.

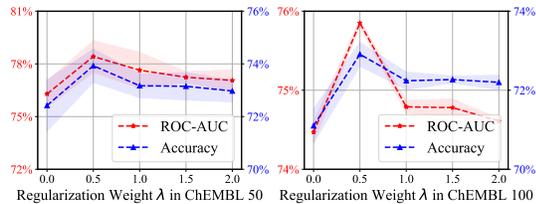


Figure 5: Sensitivity for regularization weight  $\lambda$ . ROC-AUC and Accuracy are reported.

346 **Why we need to learn domain relation?**

347 In Figure 6, we analyze the effect of domain relation  
 348 learner. By increasing the value of relation keep ratio  
 349  $\alpha$  from 0 to 1, we enforce our model to rely more  
 350 on initial relation. As we can see, the single usage  
 351 of either initial or learned domain relation leads to a  
 352 decrease in performance, proving the significance of a  
 353 combined relation. We conjecture that this is because  
 354 the original relation is relatively accurate while the  
 355 learned one is more task-related. Thus, combining  
 356 these two relations guarantees a more comprehensive  
 357 relation and improves the robustness of READ.

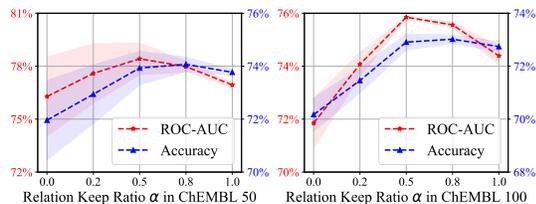


Figure 6: Analysis of relation keep ratio  $\alpha$  on ChEMBL-STRING. Here we report ROC-AUC and Accuracy.