
Learning 3D Anisotropic Noise Distributions Improves Molecular Force Field Modeling

Xixian Liu^{1*}, Rui Jiao^{2*}, Zhiyuan Liu^{3†}, Yurou Liu⁴, Yang Liu²,
Ziheng Lu⁵, Wenbing Huang^{4†}, Yang Zhang³, Yixin Cao⁶

¹Fudan University, ²Tsinghua University, ³National University of Singapore

⁴Renmin University of China, ⁵Microsoft Research

⁶Institute of Trustworthy Embodied AI, Fudan University

xixian.liu@mila.quebec, jiaor21@mails.tsinghua.edu.cn

zhiyuan@nus.edu.sg, hwenbing@ruc.edu.cn

Abstract

Coordinate denoising has emerged as a promising method for 3D molecular pre-training due to its theoretical connection to learning a molecular force field. However, existing denoising methods rely on oversimplified molecular dynamics that assume atomic motions to be isotropic and homoscedastic. To address these limitations, we propose a novel denoising framework **AniDS**: Anisotropic Variational Autoencoder for 3D Molecular Denoising. AniDS introduces a structure-aware anisotropic noise generator that can produce atom-specific, full covariance matrices for Gaussian noise distributions to better reflect directional and structural variability in molecular systems. These covariances are derived from pairwise atomic interactions as anisotropic corrections to an isotropic base. Our design ensures that the resulting covariance matrices are symmetric, positive semi-definite, and SO(3)-equivariant, while providing greater capacity to model complex molecular dynamics. Extensive experiments show that AniDS outperforms prior isotropic and homoscedastic denoising models and other leading methods on the MD17 and OC22 benchmarks, achieving average relative improvements of **8.9%** and **6.2%** in force prediction accuracy. Our case study on a crystal and molecule structure shows that AniDS adaptively suppresses noise along the bonding direction, consistent with physicochemical principles. Our code is available at <https://github.com/ZeroKnighting/AniDS>

1 Introduction

Accurately and efficiently predicting atomic properties of molecules and materials is fundamental to a wide range of downstream applications, including drug discovery [1, 2], material design [3], catalyst design [4, 5], and molecular dynamics simulations [6, 7]. *Ab initio* methods such as Density Functional Theory (DFT) [8] are widely regarded as the standard for atomic property prediction, but their high computational cost significantly limits scalability to large systems or datasets. To overcome this challenge, machine learning potentials [9] have been developed to accelerate atomic simulations by orders of magnitude, with recent advances of graph neural networks (GNNs) [10, 11] further improving prediction accuracy. Among these methods, coordinate denoising [12, 13] has emerged as a promising training objective, due to its theoretical grounding in learning molecular force fields.

Classical coordinate denoising [12] involves recovering the original atomic coordinates \mathbf{X} from the perturbed version $\mathbf{X} + \epsilon$, where the noise $\epsilon \sim \mathcal{N}(\mathbf{0}, \sigma^2 \mathbf{I})$ is drawn from an isotropic Gaussian. This objective corresponds to learning the molecular force fields when the data distribution $p(\tilde{\mathbf{X}})$

*Equal contribution. † Correspondence.

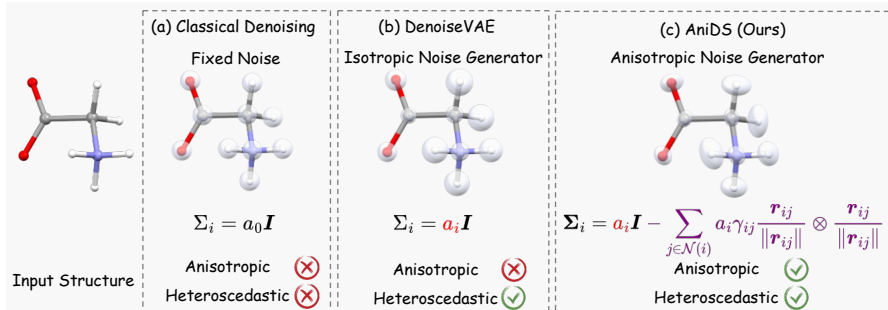


Figure 1: Comparison between different denoising approaches. The opaque spheres represent noise distributions. Our approach captures noise distribution that is both anisotropic and heteroscedastic.

is approximated as a mixture of isotropic Gaussians centered at each data point [13], *i.e.*, $p(\tilde{\mathbf{X}}) \approx \frac{1}{n} \sum_{i=1}^n \mathcal{N}(\tilde{\mathbf{X}} | \mathbf{X}_i, \sigma^2 \mathbf{I})$. A closer examination of this formulation reveals two implicit assumptions: (1) atomic motions are assumed to be **isotropic**, with identical variance along all axes ($\sigma_x^2 = \sigma_y^2 = \sigma_z^2$), ignoring direction-dependent stiffness such as bond stretching [14]; and (2) atomic motions are assumed to be **homoscedastic** [15], with all atoms sharing the same noise scale σ^2 , ignoring variability in energy potentials across distinct structures. While these assumptions make the implementation easier, they oversimplify the molecular dynamics, potentially leading to inaccurate force field learning.

Relaxing these assumptions demands a new noise distribution that is theoretically consistent with the assumed atomic motion. DenoiseVAE [16] learns adaptive noise scale σ^2 for different atoms, lifting the assumption of homoscedasticity, although the isotropic assumption remains less explored. On the other hand, earlier works [17, 18] move beyond isotropic Gaussian noises by introducing handcrafted noises, *e.g.*, perturbing bonds and dihedrals. However, these noises are applied independently at fixed scales, thus failing to address the assumption of homoscedasticity.

In this work, we propose a novel denoising framework: **Anisotropic Variational Autoencoder for 3D Molecular Denoising (AniDS)**, aiming to improve molecular force field learning by adaptively generating anisotropic Gaussian noises for coordinate denoising, thereby lifting all three assumptions discussed above. AniDS achieves this by adaptively generating a “full covariance matrix” (*i.e.*, without the diagonal constraint) for each atom’s Gaussian noise distribution, enabling it to capture directional variability and different molecular structures. However, generating such full covariance matrix introduces two major challenges that have hindered prior efforts: (1) Ensuring the covariance matrices are symmetric, positive semi-definite, and equivariant, which are fundamental properties of covariance matrices and molecules. While these properties are trivially satisfied in isotropic settings, they require explicit modeling and constraint in the anisotropic case. (2) Guiding the covariance learning process with proper physicochemical priors. The space of full covariance matrices is high-dimensional and susceptible to trivial or degenerated solutions if not properly regularized, which often leads to unstable or failed pretraining.

To address these challenges, AniDS introduces a **structure-aware anisotropic noise generator** that leverages 3D molecular structures to produce atom-specific full covariance matrices for anisotropic noise distributions. Specifically, the generator first constructs an isotropic base term and then applies anisotropic corrections derived from the learned pairwise atomic interactions. These anisotropic corrections enable the model to capture local rigidity and directional variability across different molecular structures, acting as a physicochemical prior. Additionally, our design ensures the covariance matrices are symmetric, positive semi-definite, and SO(3)-equivariant. Equipped with this expressive noise generator, AniDS supervises a molecular denoising autoencoder using our theoretically grounded denoising loss that approximates learning the molecular force field.

AniDS achieves an average relative improvement of **8.9%** on MD17 and **6.2%** on OC22 in force prediction. Ablation studies confirm the effectiveness of each component. Our case study further shows that AniDS adaptively adjusts the direction and scale of the noise according to the atomic interactions’ strength in $\text{H}_3\text{In}_{12}\text{O}_{48}\text{Pd}_{12}$ and SNPH_4 structures, aligning with physicochemical principles.

2 Preliminary: Coordinate Denoising and DenoiseVAE

We begin by introducing the coordinate denoising [13] objective and the subsequent study DenoiseVAE [16] that addresses the homoscedastic assumption.

Notation of Molecules. In this work, we develop a framework to learn force fields for both small molecules and crystal materials. For clarity, we present the methodology using the notation of small molecules; the extension to crystals is straightforward and involves revising the denoising autoencoder to reflect crystals’ periodicity. Details of this adaptation are provided in Appendix [B](#).

A 3D molecule $\mathbf{M} = (\mathbf{Z}, \mathbf{X}, \mathbf{E})$ is represented by: (1) $\mathbf{Z} \in \mathbb{N}^N$, with $Z_i \in \mathbb{N}$ denotes the atomic number of the i -th atom; (2) $\mathbf{X} \in \mathbb{R}^{N \times 3}$, where $\mathbf{X}_i \in \mathbb{R}^3$ specifies the 3D coordinates of the i -th atom; and (3) $\mathbf{E} \in \mathbb{R}^{N \times N \times d}$, where $\mathbf{E}_{ij} \in \mathbb{R}^d$ denotes the bond existence and bond type between atoms i and j . Here, N denotes the number of atoms in the molecule.

Coordinate Denoising. Given a molecule \mathbf{M} in equilibrium, in which the atom-wise forces are near zero, a corrupted version is generated as $\tilde{\mathbf{M}} = (\mathbf{Z}, \tilde{\mathbf{X}}, \mathbf{O})$, where the atomic coordinates are perturbed by Gaussian noise: $\tilde{\mathbf{X}} = \mathbf{X} + \sigma\epsilon$ with $\epsilon \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$. Here σ is a hyperparameter controlling the added noise scale, which is usually around 0.1 to generate a small perturbation. Then, a denoising autoencoder [\[19-21\]](#) $\phi(\cdot)$ is trained to predict the added noise by minimizing the following loss: $\mathbb{E}_{p(\tilde{\mathbf{M}}, \mathbf{M})} \|\phi(\tilde{\mathbf{M}}) - (\tilde{\mathbf{X}} - \mathbf{X})/\sigma^2\|^2$. Theoretically, this denoising objective is shown to approximate learning a molecular force field [\[13\]](#), therefore improving its performance.

DenoiseVAE [\[16\]](#). The standard coordinate denoising operates under the homoscedasticity assumption, treating all atoms equally. Specifically, a fixed noise scale σ is used to simulate minor thermal fluctuations for all atoms, but fails to capture the energy variations across different molecular structures. For example, in a rigid structure like a benzene ring, a minor coordinate perturbation can lead to a disproportionately large energy change, whereas similar perturbations in more flexible regions may have negligible energetic impact. Resolving this issue, DenoiseVAE trains a noise generator $\psi(\cdot)$ to adaptively assign a distinct noise scale σ_i to each atom based on the molecular structure:

$$\{\sigma_i \in \mathbb{R}^+ \mid i \in \mathbf{M}\} = \psi(\mathbf{M}), \quad (1) \quad \tilde{\mathbf{X}}_i = \mathbf{X}_i + \sigma_i \epsilon_i, \quad \epsilon_i \sim \mathcal{N}(\mathbf{0}, \mathbf{I}). \quad (2)$$

We then obtain the perturbed molecule $\tilde{\mathbf{M}} = (\mathbf{Z}, \tilde{\mathbf{X}}, \mathbf{L})$, and perform denoise training as follows:

$$\mathcal{L}_{\text{Denoise}} = \frac{1}{|\mathbf{M}|} \mathbb{E}_{p(\tilde{\mathbf{X}}, \mathbf{X})} \sum_{i \in \mathbf{M}} \sigma_i^2 \|\phi(\tilde{\mathbf{M}}) - \frac{(\tilde{\mathbf{X}} - \mathbf{X})}{\sigma_i^2}\|^2, \quad (3)$$

$$\mathcal{L}_{\text{KL}} = \frac{1}{|\mathbf{M}|} \sum_{i \in \mathbf{M}} \mathbf{D}_{\text{KL}}(\mathcal{N}(\mathbf{0}, \sigma_i^2 \mathbf{I}) \parallel p_i), \quad (4)$$

where p_i is the prior distribution, set to $\mathcal{N}(\mathbf{0}, \sigma_p^2 \mathbf{I})$, and σ_p is a hyperparameter. The KL divergence term \mathcal{L}_{KL} acts as a regularizer to prevent the noise generator $\psi(\cdot)$ from collapsing to trivial solutions where $\sigma_i \rightarrow 0$. This ensures meaningful denoise training. The final training objective combines both losses $\mathcal{L}_{\text{DenoiseVAE}} = \lambda_{\text{Denoise}} \mathcal{L}_{\text{Denoise}} + \lambda_{\text{KL}} \mathcal{L}_{\text{KL}}$ with balancing coefficients λ_{Denoise} and λ_{KL} .

3 Methodology

In this section, we start by overviewing the AniDS framework. We then present the motivations and detailed formulations of its key components in Sections [3.2](#) and Section [3.3](#), respectively. Finally, we describe how AniDS can be adapted to different training schemes in Section [3.4](#).

3.1 Overview of the AniDS Framework

AniDS consists of three key components: (1) a structure-aware anisotropic noise generator $\psi(\cdot)$ that generates per-atom noise distribution conditioned on the molecule structure \mathbf{M} ; (2) a denoising autoencoder $\phi(\cdot)$ that is trained for coordinate denoising; and (3) a denoising objective $\mathcal{L}_{\text{AniDS}}$ that approximates learning molecular force field.

Structure-aware Anisotropic Noise Generator. Given a molecule \mathbf{M} , AniDS employs a noise generator $\psi(\cdot)$ to generate a full covariance matrix $\Sigma_i \in \mathbb{R}^{3 \times 3}$ for each atom $i \in \mathbf{M}$, defining an anisotropic Gaussian noise distribution $\mathcal{N}(\mathbf{0}, \Sigma_i)$. Unlike prior works that assume diagonal Σ_i for theoretical and computational convenience [\[22, 13\]](#), AniDS models Σ_i as a dense matrix to capture directional variability. To ensure that the generated noise reflects the underlying molecular structure, $\psi(\cdot)$ should be implemented with structure-aware molecular encoders [\[23, 24\]](#). This enables the generated covariance matrices to reflect local and global molecular structural contexts. Given this generator $\psi(\cdot)$, the perturbed molecule $\tilde{\mathbf{M}}$ can be obtained as:

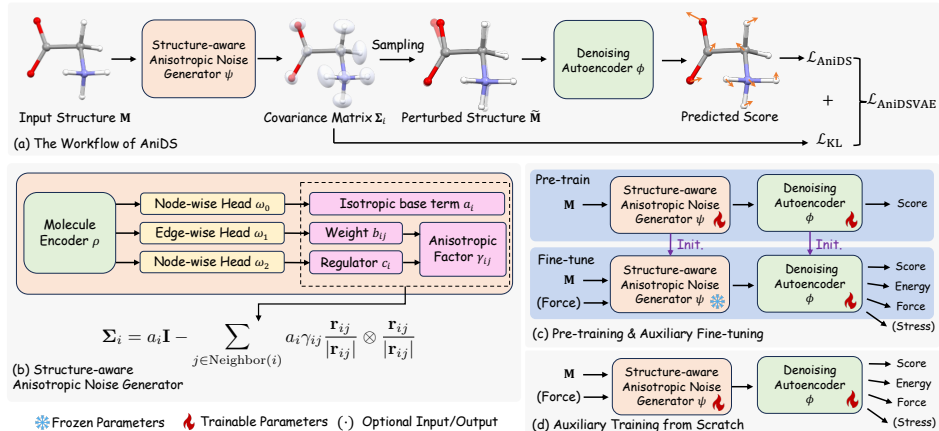


Figure 2: Overview of the AniDS framework.

$$\{\Sigma_i \in \mathbb{R}^{3 \times 3} | i \in \mathbf{M}\} = \psi(\mathbf{M}), \quad (5) \quad \mathbf{L}_i = \text{Cholesky}(\Sigma_i), \quad (6)$$

$$\tilde{\mathbf{X}}_i = \mathbf{X}_i + \mathbf{L}_i \epsilon_i, \epsilon_i \sim \mathcal{N}(\mathbf{0}, \mathbf{I}), \quad (7) \quad \tilde{\mathbf{M}} = (\mathbf{Z}, \tilde{\mathbf{X}}, \mathbf{E}), \quad (8)$$

where $\tilde{\mathbf{X}}_i$ is the perturbed coordinate of the i -th atom, sampled via Cholesky decomposition [25] of the learned covariance Σ_i . While the noise generator can be any neural network capable of producing symmetric, positive semi-definite, and 3D-equivariant covariance matrices, we introduce our implementation in Section 3.2.

Denoising Autoencoder. The denoising autoencoder ϕ takes the perturbed structure $\tilde{\mathbf{M}}$ as input and predicts atom-wise vectors intended to recover the original coordinates: $\phi(\tilde{\mathbf{M}}) \in \mathbb{R}^{N \times 3}$. AniDS is a model-agnostic framework that can be integrated into a wide range of molecular backbones. In this work, we implement ϕ with EquiformerV2 [24] and Geoformer [26], which have demonstrated strong performance on molecular benchmarks. To enable coordinate denoising on non-equilibrium structures, we follow [27] to include **force encoding** as the additional features for the corrupted atoms. Unlike equilibrium structures, which are uniquely defined by local energy minima, multiple non-equilibrium structures may share the same energy level, introducing ambiguity into the denoising targets. Including force information helps disambiguate these cases by anchoring the target to a specific molecular state. Our detailed implementations of the denoising autoencoders and the force encoding are introduced in Appendix B.1.

AniDS’s Denoising Objective. AniDS’s denoising loss jointly trains the noise generator and the denoising autoencoder to recover the noise vector scaled by the inverse covariance:

$$\mathcal{L}_{\text{AniDS}} = \frac{1}{|\mathbf{M}|} \mathbb{E}_{q_{\Sigma}(\tilde{\mathbf{X}}, \mathbf{X})} \sum_{i \in \mathbf{M}} \left\| \phi(\tilde{\mathbf{M}})_i - [\Sigma_i]^{-1} (\tilde{\mathbf{X}}_i - \mathbf{X}_i) \right\|^2. \quad (9)$$

We show in Section 3.3 that the objective above approximates learning the molecular force field. Additionally, we compute a KL divergence loss between the learned anisotropic noise distribution and an isotropic Gaussian prior $\mathcal{N}(0, \sigma_p^2 \mathbf{I})$:

$$\mathcal{L}_{\text{KL}} = \frac{1}{2|\mathbf{M}|} \sum_{i \in \mathbf{M}} \left(\text{tr}(\sigma_p^{-2} \Sigma_i) - d + \ln \frac{|\sigma_p^2 \mathbf{I}|}{|\Sigma_i|} \right), \quad (10)$$

which prevents the learned covariance from collapsing into trivial solutions like zeros. Recall that the normalized anisotropic weights $\{\gamma_{ij}\}$ on Eq. 15 satisfy $\sum_j \gamma_{ij} < 1$ by construction. To avoid degenerate covariances that become overly isotropic in flexible regions, we regularize the total anisotropic mass $\Gamma_i := \sum_j \gamma_{ij}$ towards a target level $\kappa \in (0, 1)$ via a one-sided hinge-squared penalty:

$$\mathcal{L}_{\gamma} = \frac{1}{|\mathcal{M}|} \sum_{i \in \mathcal{M}} [\max(0, \kappa - \Gamma_i)]^2. \quad (11)$$

Intuitively, Eq. (11) discourages vanishing anisotropic corrections (i.e., Γ_i too small), while preserving the PSD guarantee $\Gamma_i < 1$ from [15]. The final loss $\mathcal{L}_{\text{AniDSVAE}}$ is a weighted sum of the denoising and regularization terms:

$$\mathcal{L}_{\text{AniDS-VAE}} = \lambda_{\text{AniDS}} \mathcal{L}_{\text{AniDS}} + \lambda_{\text{KL}} \mathcal{L}_{\text{KL}} + \lambda_{\gamma} \mathcal{L}_{\gamma}. \quad (12)$$

3.2 Structure-Aware Anisotropic Noise Generation

The noise generator $\psi(\cdot)$ constructs symmetric, positive semi-definite, and SO(3)-equivariant covariance matrices $\{\Sigma_i | i \in \mathbf{M}\}$. These matrices encode both isotropic and anisotropic uncertainty in atomic positions, reflecting each atom’s structural context. The generation consists of two main steps:

Atom-wise Structural Representation. A molecular structure encoder $\rho(\cdot)$ is used to extract structural representations, to guide the covariance generation process. This work shares the architecture as the denoising autoencoder. Formally, we have:

$$\{\mathbf{h}_i \in \mathbb{R}^d | i \in \mathbf{M}\} = \rho(\mathbf{M}), \quad (13)$$

where \mathbf{h}_i encodes the structural and chemical contexts of atom i .

Covariance Matrix. Given the structural representation above, we parameterize the covariance matrix Σ_i for atom i as the sum of a isotropic base term and an anisotropic term, motivated by our physicochemical prior of pairwise atomic interactions:

$$\Sigma_i = \underbrace{a_i \mathbf{I}}_{\text{Isotropic Base}} - \underbrace{\sum_{j \in \text{Neighbor}(i)} a_i \gamma_{ij} \frac{\mathbf{r}_{ij}}{|\mathbf{r}_{ij}|} \otimes \frac{\mathbf{r}_{ij}}{|\mathbf{r}_{ij}|}}_{\text{Anisotropic Corrections}}, \quad (14)$$

$$\gamma_{ij} = \frac{\exp(b_{ij})}{\sum_{l \in \text{Neighbor}(i)} \exp(b_{il}) + c_i} \quad (\text{Normalized anisotropic weight}), \quad (15)$$

where $\mathbf{r}_{ij} = \mathbf{X}_i - \mathbf{X}_j \in \mathbb{R}^3$ is the relative position vector. The parameters a_i , b_{ij} , and c_i are adaptively derived from the atomic structural representations $\{\mathbf{h}_i | i \in \mathbf{M}\}$ using MLPs (*i.e.*, ω_0 , ω_1 , and ω_2) and a radial basis function [28] $\eta(\cdot)$, respectively:

- **Isotropic base term** $a_i = \exp(\omega_0(\mathbf{h}_i)) \in \mathbb{R}^+$. It controls the baseline noise level for atom i , reflecting its intrinsic flexibility. Larger a_i values indicate greater isotropic flexibility.
- **Anisotropic weight** $b_{ij} = \omega_1([\mathbf{h}_i; \mathbf{h}_j; \eta(|\mathbf{r}_{ij}|)]) \in \mathbb{R}$. It controls the weights of anisotropic corrections, which determines the directional stiffness between atoms i and j . For example, along covalent bonds, high b_{ij} produces high γ_{ij} that suppresses motion along \mathbf{r}_{ij} . Conversely, $b_{ij} \ll 0$ for distant atom pairs eliminates the corresponding directional influence of stiffness.
- **Anisotropic regulator** $c_i = \exp(\omega_2(\mathbf{h}_i)) \in \mathbb{R}^+$. It regulates the influence of anisotropic corrections. In symmetric or rigid environments, such as aromatic rings, larger c_i values suppress individual directional components, resulting in a more isotropic noise distribution. In contrast, smaller c_i allows stronger anisotropic corrections to reflect local uncertainty in flexible regions.

Our noise generator is designed to ensure three essential properties of the covariance matrix:

- **Symmetry:** $\Sigma_i = \Sigma_i^\top$ is satisfied due to the symmetry of the isotropic base and the outer product.
- **Positive Semi-Definiteness:** The covariance matrix is positive definite ($\Sigma_i \succ 0$) if $\sum_j \gamma_{ij} < 1$, enforced via the softmax in Equation (15). This condition guarantees the anisotropic correction term does not overpower the isotropic base $a_i \mathbf{I}$. A detailed proof is in Appendix B.
- **SO(3)-Equivariance and T(3)-Invariance:** Given SE(3) transformation $g = (\mathbf{R}, \mathbf{t})$ of rotation $\mathbf{R} \in \text{SO}(3)$ and translation $\mathbf{t} \in \mathbb{R}^3$ applied on the molecule \mathbf{M} , the transformed covariance matrix satisfies $g \circ \Sigma_i = \mathbf{R} \Sigma_i \mathbf{R}^\top$: the covariance matrix is equivariant to the rotation but invariant to the translation. This is because the translation is canceled out when computing $\mathbf{r}_{ij} = \mathbf{X}_i - \mathbf{X}_j$.

3.3 AniDS Learns Molecular Force Fields

Here, we show that AniDS’s denoising objective approximates learning molecular force field.

Step 1: Boltzmann Distribution and Gaussian Mixture Approximation. The distribution of molecular structures follows the Boltzmann distribution: $p_{\text{physical}}(\tilde{\mathbf{X}}) \propto \exp(-\frac{E(\tilde{\mathbf{X}})}{k_B T})$, where $E(\tilde{\mathbf{X}})$ is the potential energy. Following prior works [13, 29], we approximate p_{physical} as a mixture of Gaussians centered at the known structures, typically selected as the equilibrium conformations [13]. Subsequent study [17] demonstrates that learning this Gaussian mixture over non-equilibrium structures is theoretically equivalent to modeling a hybrid noise distribution over equilibrium ones (See

Proposition 3.4 in [17]). In their work, non-equilibrium structures are generated by applying small torsional perturbations to equilibrium conformations. Further studies show that intermediate states from molecular dynamics simulations can also serve as effective non-equilibrium samples for denoising [22, 27], which are also adopted in our work. Specifically, we have:

$$p_{\text{physical}}(\tilde{\mathbf{X}}) \approx q_{\Sigma}(\tilde{\mathbf{X}}) = \frac{1}{|\mathcal{D}|} \sum_{k=1}^{|\mathcal{D}|} q_{\Sigma}(\tilde{\mathbf{X}}|\mathbf{X}^{(k)}), \quad (16)$$

where $\mathbf{X}^{(k)}$ is the k -th structure in dataset \mathcal{D} . We define $q_{\Sigma}(\tilde{\mathbf{X}}|\mathbf{X}^{(k)}) = \prod_{i=1}^N \mathcal{N}(\tilde{\mathbf{X}}_i; \mathbf{X}_i^{(k)}, \Sigma_i^{(k)})$. Here $\mathbf{X}_i^{(k)} \in \mathbb{R}^3$ denotes the coordinate of the i -th atom in the k -th structure, and $\Sigma_i^{(k)} \in \mathbb{R}^{3 \times 3}$ is the covariance matrix of the i -th atom in the k -th structure.

Step 2: Score Function of the Gaussian Mixture. The score (gradient of the log-density) is:

$$\nabla_{\tilde{\mathbf{X}}} \log q_{\Sigma}(\tilde{\mathbf{X}}) = \frac{\sum_{k=1}^{|\mathcal{D}|} q_{\Sigma}(\tilde{\mathbf{X}}|\mathbf{X}^{(k)}) \nabla_{\tilde{\mathbf{X}}} \log q_{\Sigma}(\tilde{\mathbf{X}}|\mathbf{X}^{(k)})}{\sum_{k=1}^{|\mathcal{D}|} q_{\Sigma}(\tilde{\mathbf{X}}|\mathbf{X}^{(k)})} \quad (17)$$

Step 3: Link to Molecular Force Field. Under the Boltzmann distribution, the force field is proportional to the score:

$$\mathbf{F}(\tilde{\mathbf{X}}) = -\nabla_{\tilde{\mathbf{X}}} E(\tilde{\mathbf{X}}) = k_B T \cdot \nabla_{\tilde{\mathbf{X}}} \log p_{\text{physical}}(\tilde{\mathbf{X}}). \quad (18)$$

For small perturbation ($\tilde{\mathbf{X}} \approx \mathbf{X}^{(k)}$), the Gaussian mixture is dominated by the nearest structure $\mathbf{X}^{(k)}$, simplifying the score (cf. Equation (17)) to:

$$\nabla_{\tilde{\mathbf{X}}} \log q_{\Sigma}(\tilde{\mathbf{X}}) \approx \nabla_{\tilde{\mathbf{X}}} \log q_{\Sigma}(\tilde{\mathbf{X}}|\mathbf{X}^{(k)}) = -\sum_{j=1}^N [\Sigma_j^{(k)}]^{-1} (\tilde{\mathbf{X}}_j - \mathbf{X}_j^{(k)}). \quad (19)$$

Substituting this into the force field expression (cf. Equation (18)), we identify:

$$\mathbf{F}(\tilde{\mathbf{X}}) \propto \sum_{i=1}^N [\Sigma_i^{(k)}]^{-1} (\tilde{\mathbf{X}}_i - \mathbf{X}_i^{(k)}). \quad (20)$$

Step 4: Denoising as Learning Force Field. AniDS trains a denoise autoencoder $\phi(\tilde{\mathbf{M}})$ to predict the noise scaled by the inverse covariance (cf. Equation (9)). By Vincent’s theorem [30], this is equivalent to score matching:

$$\mathcal{L}_{\text{AniDS}} \propto \mathbb{E}_{q_{\Sigma}(\tilde{\mathbf{X}})} \|\phi(\tilde{\mathbf{M}}) - \nabla_{\tilde{\mathbf{X}}} \log q_{\Sigma}(\tilde{\mathbf{X}})\|^2 \quad (21)$$

At convergence, $\phi^*(\tilde{\mathbf{M}}) = \nabla_{\tilde{\mathbf{X}}} \log q_{\Sigma}(\tilde{\mathbf{X}}) \approx \nabla_{\tilde{\mathbf{X}}} \log p_{\text{physical}}(\tilde{\mathbf{X}})$, recovering the force field: $\phi^*(\tilde{\mathbf{M}}) \propto -\mathbf{F}(\tilde{\mathbf{X}})$. Prior works of Coordinate Denoising [27] and DenoiseVAE [16] can be seen as special cases of our approach, with detailed derivations provided in Appendix B.

3.4 Adapting AniDS to Different Training Schemes

Consistent with prior works, we adopt AniDS under two training schemes: (1) as a pretraining objective followed by task-specific fine-tuning [13, 31], and (2) as an auxiliary task jointly optimized with supervised force field learning when training from scratch [27, 12].

Pre-training and Fine-tuning. Following [12, 31], we can apply AniDS (cf. Equation (12)) to pretrain the denoising autoencoder ϕ and the structure-aware noise generator ψ altogether on a large pretraining dataset. The pretrained encoder ϕ is then fine-tuned on downstream datasets for supervised force field learning, with the AniDS objective retained as an auxiliary loss, as described in the following paragraph. During fine-tuning, the parameters of the noise generator ψ are kept frozen.

Supervised Learning with Partial Corruption and Auxiliary Denoising. We use AniDS as an auxiliary loss for supervised force field learning. Inspired by [27], we adopt a partially corrupted denoising strategy. Specifically, only a subset of a molecule’s atom coordinates is corrupted using the noise generator. The model is trained with the weighted sum of supervised force field loss on the uncorrupted atoms and AniDS loss (cf. Equation (12)) on the corrupted atoms. This design ensures that the model learns from clean ground truth coordinates for supervised force field learning, while still benefiting from denoising regularization. Compared to corrupting all the atoms, this method mitigates the mismatch between the the ground truth force field label and the perturbed structure. Implementation details are provided in Appendix B.3.

Table 1: MAE for force prediction on MD17’s test sets. Forces are reported in units of kcal/mol. Bold numbers indicate the best performance. Green denotes relative improvement to the baseline.

Model	Aspirin	Benzene	Ethanol	Malonaldehyde	Naphthalene	Salicylic Acid	Toluene	Uracil	Avg
SchNet [37]	1.35	0.31	0.39	0.66	0.58	0.85	0.57	0.56	0.66
DimeNet [38]	0.499	0.187	0.230	0.383	0.215	0.374	0.216	0.301	0.300
PaiNN [39]	0.338	-	0.224	0.319	0.077	0.195	0.094	0.139	-
TorchMD-NET [40]	0.253	0.196	0.109	0.169	0.061	0.129	0.067	0.095	0.135
NequIP (Lmax=3) [10]	0.184	-	0.071	0.129	0.039	0.090	0.046	0.076	-
SE(3)-DDM [41]	0.453	-	0.166	0.288	0.129	0.266	0.122	0.122	-
Coord [13]	0.211	0.169	0.096	0.139	0.053	0.109	0.058	0.074	0.114
Frad [17]	0.209	0.199	0.091	0.1415	0.053	0.108	0.054	0.076	0.116
Slide [18]	0.174	0.169	0.088	0.153	0.048	0.100	0.054	0.082	0.109
DeNS [27] (Lmax=2)	0.131	0.141	0.060	0.101	0.039	0.085	0.044	0.076	0.085
DeNS [27] (Lmax=3)	0.120	0.141	0.055	0.095	0.037	0.074	0.042	0.067	0.079
AniDS (Lmax=2)	0.102 ^{+15.0%}	0.139 ^{+1.4%}	0.050 ^{+9.1%}	0.084 ^{+11.6%}	0.036 ^{+2.7%}	0.064 ^{+13.5%}	0.038 ^{+9.5%}	0.062 ^{+7.5%}	0.072 ^{+8.9%}

Table 2: Performance comparison on OC22’s S2EF-Total validation set.

Model	Params	Energy E-MAE (meV)			Force F-MAE (meV/Å)		
		ID	OOD	Avg	ID	OOD	Avg
GemNet-OC [42]	39M	545	1011	778	30.0	40.0	35.0
GemNet-OC (OC20+OC22) [42]	39M	464	859	661.5	27.0	34.0	30.5
E2former [43]	67M	491	724	607.5	25.98	36.45	31.22
EquiformerV2 [24]	122M	433.0	629.0	531	22.88	30.70	26.79
EquiformerV2 + DeNS [27]	127M	391.6	533.0	462.3	20.66	27.11	23.89
EquiformerV2 + AniDS (ours)	129M	370.0 ^{+5.5%}	525.4 ^{+1.4%}	447.7 ^{+3.2%}	19.53 ^{+5.5%}	25.27 ^{+6.8%}	22.4 ^{+6.2%}

4 Experiments

Datasets. We briefly describe the datasets in our experiments, and leave additional setup details in Appendix C.2. Our experiments involve four datasets: (1) **PCQM4Mv2** [32] contains 3,746,619 molecules along with their Density Functional Theory (DFT) calculated 3D equilibrium structures. (2) **OC22** [33] is a large-scale dataset of DFT calculated structures designed to advance machine learning for oxide electrocatalysts. (3) **MD17** [34] provides molecular dynamics trajectories of small organic molecules, with both energy and force labels. (4) **MPTraj** [35] includes 1.58 million structures obtained from DFT relaxation trajectories of over 146,000 materials in the Materials Project [36].

4.1 Results of pre-training and Fine-tuning

Setup. We pre-train our model on PCQM4Mv2 and subsequently fine-tune it exclusively on MD17. We adopt the Equiformer-V2 backbone [24]. Note, we use only the 3D structures without the property values in PCQM4Mv2. During the fine-tuning, given that the pre-trained AniDS has already learned a decent distribution for adding noise, we freeze the noise generator and only train the denoising autoencoder, using AniDS as an auxiliary task along with supervised learning. Following [27], we use 950 molecules for training and 50 for testing. No noise is added during validation and testing.

MD17. Table 1 presents the results on MD17. Our method achieves the best across all evaluated tasks. Compared to the previous results, we observe an average improvement of approximately **8.9%** across the tasks. We attribute this significant improvement to our structure-aware noise generator, which produces anisotropic noise, enabling our model to learn the molecular potential energy surface more effectively. Furthermore, while DeNS ($L_{max} = 3$) enhances input features by increasing the degree of irreducible representations in EquiformerV2, AniDS ($L_{max} = 2$) outperforms it while using a lower dimensional irreducible representation. This demonstrates the efficacy of our adaptive structure-driven noise sampling strategy, suggesting that well-informed noise learning can lead to a more generalizable force field prediction.

4.2 Results of Supervised Learning with Partial Corruption and Auxiliary Denoising

Setup. Here AniDS is used as an auxiliary task when conducting supervised learning on OC22. Due to resource constraints, we adopt the pre-trained models from [27]. This pre-trained model utilizes the EquiformerV2 architecture, and its training process incorporated DeNS as an auxiliary task. Given its architectural similarity to the model used for MD17, we can easily extend its training by integrating our AniDS framework. Following [27], we conduct training on OC22’s S2EF-Total task, which contains 8.2 million structures. We further evaluate performance on the provided validation split [33]. Additionally, our results on MPTraj are provided in Appendix C.

Table 3: Ablation Studies on the Aspirin dataset of MD17. **(a)** Comparison of different denoising methods under the pre-train-fine-tune scheme. **(b)** Comparison of different denoising methods under the pre-train-fine-tune scheme. Standard supervised fine-tuning is used without AniDS as an auxiliary task. **(c)** Hyperparameter analysis under the pre-train and fine-tune scheme.

(a) Pre-train and Fine-tune		(b) w/o Auxiliary Fine-tuning		(c) Hyperparameters	
Model	F(MAE)	Model	F(MAE)	EqV2	F(MAE)
–	–	–	–	$\sigma_p = 0.5$	0.13018
EqV2-No pre-train	0.1929	EqV2-No pre-train	0.1929	$\sigma_p = 0.1$	0.11180
EqV2-DeNS	0.1178	EqV2-DeNS	0.1424	$\sigma_p = 0.05$	0.11594
EqV2-DenoiseVAE	0.1143	EqV2-DenoiseVAE	0.1400	$\lambda_{\text{KL}} = 1.5$	0.11714
EqV2-AniDS-add	0.1128	EqV2-AniDS-add	0.1389	$\lambda_{\text{KL}} = 1.0$	0.11180
EqV2-AniDS	0.1118	EqV2-AniDS	0.1369	$\lambda_{\text{KL}} = 0.5$	0.11461

OC22. Table 2 presents the results. Compared to baselines, AniDS achieves state-of-the-art performance across all tasks. This is because AniDS can more accurately generate noise that aligns with the atomic vibration modes, thereby better assisting the model to learn molecular force fields. Notably, our model demonstrates an improvement of $\sim 3.2\%$ in energy prediction for both the in-distribution (ID) and out-of-distribution (OOD) datasets, and an improvement of $\sim 6.2\%$ in force prediction for both ID and OOD datasets. These superior results underscore the effectiveness of our method.

4.3 Ablation Study and Hyperparameter Analysis

Impact of Different Denoising Methods. We evaluate various denoising strategies with the same Equiformer-v2 backbone [24], pre-trained on the PCQM4Mv2 dataset. The methods include: (1) no pre-training; (2) denoise training with fixed-scale isotropic Gaussian Noise (EqV2-DeNS [27]); (3) DenoiseVAE [16]; (4) AniDS with additive anisotropic correction instead of subtractive correction (cf. Equation 14; EqV2-AniDS-add); and (5) our method AniDS.

Table 3 compares two fine-tuning settings following denoising pre-training: (a) fine-tuning with denoising as an auxiliary task, and (b) fine-tuning without denoising. In both settings, our model consistently outperforms all baselines. All denoising-based pre-training methods substantially outperform the baseline without pre-training, supporting the benefit of learning molecular noise distributions. Notably, models using anisotropic noise (EqV2-AniDS and EqV2-AniDS-add) consistently outperform those using isotropic noise (EqV2-DeNS and EqV2-DenoiseVAE), confirming that isotropic assumptions oversimplify molecular dynamics. Moreover, the subtractive correction in EqV2-AniDS yields slightly better results than the additive correction in EqV2-AniDS-add, suggesting that incorporating directional stiffness from physicochemical priors improves the model’s structural understanding.

Impact of Different σ_p and λ_{KL} . The choice of prior distribution σ_p and the strength of the KL loss λ_{KL} both affect model performance. As shown in Table 3(c) (top), varying σ_p influences how effectively the model learns from the noise prior, with the best performance achieved at $\sigma = 0.1$. In addition, Table 3(c) (bottom) shows the effect of different λ_{KL} values. The KL loss helps prevent trivial solutions (e.g., collapsing to zero noise) by regularizing the learned noise distribution. Our results indicate that setting $\lambda_{\text{KL}} = 1.0$ yields the best performance. Larger values overly bias the model toward the prior, ignoring structure-specific features, while smaller values lead to under-regularized, uninformative noise distributions. Together, these results highlight the importance of carefully balancing prior assumptions and regularization strength when modeling physically meaningful noise.

4.4 Case Study: Validating Anisotropic Noise Behavior on Crystal and Molecular Structures

To verify whether the learned noise captures the physical anisotropy of the energy landscape, we design an experiment to probe how directional perturbations influence energy changes. To quantitatively evaluate this effect, we first perform eigenvalue decomposition on the learned covariance matrices and apply small random perturbations along the resulting eigenvectors. The corresponding changes in energy are then measured using the Symmetric Mean Absolute Percentage Error (sMAPE).

Crystal Validation. The resulting energy changes, along with the associated eigenvectors and eigenvalues, are visualized in Figure 3(c).

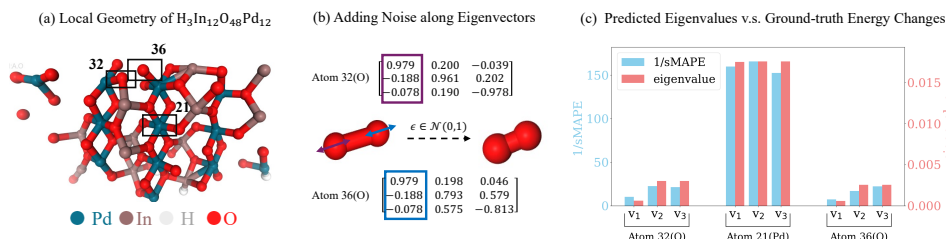


Figure 3: Visualization of the $\text{H}_3\text{In}_{12}\text{O}_{48}\text{Pd}_{12}$ crystal. We select oxygen atoms at indices $\{32, 36\}$, and a palladium atom at index 21. Figure (b) presents the eigenvectors of the oxygens. Figure (c) shows the relationship between the structural energy and applied noise.

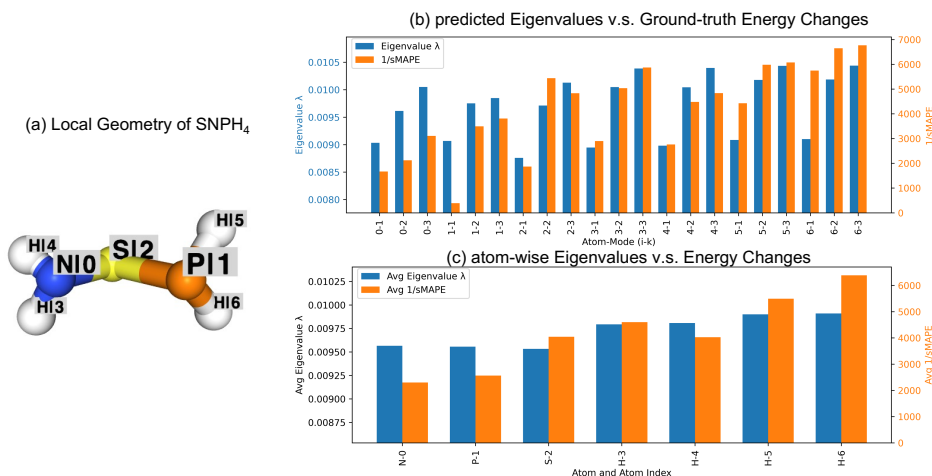


Figure 4: Analysis on the SNPH_4 molecule. (a) Local geometry showing atom indices. (b) Per-atom directional alignment between predicted eigenvalues and ground-truth energy sensitivities ($1/\text{sMAPE}$). (c) Atom-wise comparison of averaged eigenvalues and energy sensitivities.

For example, atoms $\{32, 36\}$ are spatially close, identical oxygen atoms with strong repulsive interaction. **The eigenvector corresponding to the smallest eigenvalue for both atoms aligns with the bond direction between them (Figure 3b).** Due to the short distance and strong repulsion, perturbations along this axis lead to significant energy changes, and AniDS accordingly reduces noise in this direction. In contrast, atom 21 resides in a more symmetric environment. The model thus produces larger and more isotropic noise for this atom. This strongly supports our main idea: AniDS allows for structure-aware noise generation, reducing excessive disruption.

Molecular Validation. To further confirm the generality of the anisotropic noise modeling, we conduct an additional analysis on the SNPH_4 molecule.

Figure 4(b) shows that the predicted eigenvalues exhibit a consistent trend with the ground-truth energy changes measured by $1/\text{sMAPE}$, demonstrating that AniDS effectively captures direction-dependent energy stiffness. Notably, for atoms H6-1 and H5-1, the smallest eigenvalues correspond to eigenvectors aligned with the two P-H bonds, matching the physically stiff directions of the molecule. Figure 4(c) further summarizes the per-atom averaged behavior. Hydrogen atoms display larger eigenvalues and higher $1/\text{sMAPE}$ values, indicating that their displacements have relatively minor effects on total energy. In contrast, the N, P, and S atoms situated at the core of the molecular structure and show smaller eigenvalues, signifying greater energy sensitivity to positional perturbations. The results show that perturbations along different directions affect the potential energy surface to varying degrees, validating the rationale behind the anisotropic noise design: **AniDS suppresses perturbations in energy-sensitive directions while allowing more noise along flexible axes, closely aligning with the ground-truth energy changes.**

5 Related Works

Coordinate Denoising for 3D Atomistic Systems. Coordinate denoising has been widely explored for pretraining on 3D atomistic systems [12, 13, 31, 17, 22], showing strong performance in predicting

quantum chemical properties, force fields, and energies [44, 45, 18]. While the method was originally proposed to equilibrium molecular structures, it is later extended to non-equilibrium systems by incorporating atomic force information into the model [27]. Coordinate denoising’s effectiveness stems from its theoretical connection to learning molecular force fields [13], under the assumption that the noise distribution is isotropic Gaussian and the data distribution is a mixture of such Gaussians. To overcome the limitations of the isotropic assumption, Frad [17] combines torsional and coordinate noise, while Slide [18] applies independent Gaussian noise on bond lengths, angles, and torsion angles. However, these methods use fixed noise scales, ignoring the variability of energy potentials across distinct structures. Addressing this, DenoiseVAE [16] leverages a Variational Autoencoder [46] to learn atom-wise adaptive noise variances. In contrast, AniDS learns a full covariance matrix for each atom’s noise distribution, enabling the modeling of anisotropic and structure-aware noise.

Other 3D Molecular Pretraining Methods. A representative approach involves directly pretraining on large-scale molecular dynamics simulation datasets. For example, MatterSim [47] and JMP [48] are trained on large-scale molecular dynamics trajectories and achieve strong performance on downstream property prediction tasks. However, these methods rely heavily on high-quality large-scale simulation datasets, which are often expensive to obtain and limited in scalability. Another line of work focuses on integrating multiple structural representations to improve model expressiveness. For instance, MoleculeSDE [49] and Transformer-M [50] combine 2D topological graphs with 3D geometric point clouds, using complementary perspectives to enhance molecular representations. UniCorn [51] unifies three mainstream self-supervised strategies into a multi-view contrastive learning framework to construct more comprehensive molecular representations. MoleBlend [52] fuses 2D and 3D structural information at the atomic relation level, enabling fine-grained structural modeling. Recent advances further explore cross-modal and language-grounded representations for molecular systems. 3D-MoLM [53] and MolCA [54] align molecular graphs and textual descriptions through multimodal pretraining, while NEXT-MOL [55] and ReactXT [56] integrate 3D diffusion or reaction-context modeling with language understanding. SIMSGT [57] revisits tokenization and decoding for masked graph modeling, and ProfT3 [58] extends text-based pretraining to proteins. Beyond molecule-text alignment, UAE-3D [59] propose a unified latent space for 3D molecular diffusion, and scMMGPT [60] leverage language models for single-cell representation learning. At a broader scale, NatureLM [61] envisions a general language of natural sciences, and deep-learning frameworks such as [62] highlight the potential of AI to uncover physical principles in crystalline materials.

6 Conclusion and Future Work

We present AniDS, a denoising framework that learns anisotropic, structure-aware noise distributions to enhance molecular force field modeling. By generating atom-specific full covariance matrices conditioned on molecular geometry, AniDS lifts the isotropic and homoscedastic assumptions inherent in prior denoising methods. Grounded in theoretical connections to force field learning, AniDS supports both pretraining and auxiliary fine-tuning. Extensive experiments on MD17 and OC22 show that AniDS achieves leading performance. Looking forward, we aim to extend AniDS to larger and more complex systems, such as proteins and RNAs, and apply it for molecular simulations.

7 Acknowledgement

This work was supported in part by the Ministry of Education (MOE T1251RES2309 and MOE T2EP20125-0039) and the Agency for Science, Technology and Research (A*STAR H25J6a0034).

References

- [1] Alexandre Blanco-Gonzalez, Alfonso Cabezon, Alejandro Seco-Gonzalez, Daniel Conde-Torres, Paula Antelo-Riveiro, Angel Pineiro, and Rebeca Garcia-Fandino. The role of ai in drug discovery: challenges, opportunities, and strategies. *Pharmaceuticals*, 16(6):891, 2023.
- [2] Kit-Kay Mak, Yi-Hang Wong, and Mallikarjuna Rao Pichika. Artificial intelligence in drug discovery and development. *Drug discovery and evaluation: safety and pharmacokinetic assays*, pages 1461–1498, 2024.
- [3] Dana Bishara, Yuxi Xie, Wing Kam Liu, and Shaofan Li. A state-of-the-art review on machine learning-based multiscale modeling, simulation, homogenization and design of materials. *Archives of computational methods in engineering*, 30(1):191–222, 2023.

- [4] Lowik Chanussot, Abhishek Das, Siddharth Goyal, Thibaut Lavril, Muhammed Shuaibi, Morgane Riviere, Kevin Tran, Javier Heras-Domingo, Caleb Ho, Weihua Hu, et al. Open catalyst 2020 (oc20) dataset and community challenges. *Acs Catalysis*, 11(10):6059–6072, 2021.
- [5] Janice Lan, Aini Palizhati, Muhammed Shuaibi, Brandon M Wood, Brook Wander, Abhishek Das, Matt Uyttendaele, C Lawrence Zitnick, and Zachary W Ulissi. Adsorbml: a leap in efficiency for adsorption energy calculations using generalizable machine learning potentials. *npj Computational Materials*, 9(1):172, 2023.
- [6] Boris Kozinsky, Albert Musaelian, Anders Johansson, and Simon Batzner. Scaling the leading accuracy of deep equivariant models to biomolecular simulations of realistic size. In *Proceedings of the International Conference for High Performance Computing, Networking, Storage and Analysis*, pages 1–12, 2023.
- [7] Stefan Chmiela, Alexandre Tkatchenko, Huziel E Sauceda, Igor Poltavsky, Kristof T Schütt, and Klaus-Robert Müller. Machine learning of accurate energy-conserving molecular force fields. *Science advances*, 3(5):e1603015, 2017.
- [8] Robert G. Parr and Weitao Yang. *Density-Functional Theory of Atoms and Molecules*. Oxford University Press, USA, 1994.
- [9] Jörg Behler. Perspective: Machine learning potentials for atomistic simulations. *The Journal of chemical physics*, 145(17), 2016.
- [10] Simon Batzner, Albert Musaelian, Lixin Sun, Mario Geiger, Jonathan P Mailoa, Mordechai Kornbluth, Nicola Molinari, Tess E Smidt, and Boris Kozinsky. E(3)-equivariant graph neural networks for data-efficient and accurate interatomic potentials. *Nature communications*, 13(1):2453, 2022.
- [11] Oliver Unke, Mihail Bogojeski, Michael Gastegger, Mario Geiger, Tess Smidt, and Klaus-Robert Müller. Se(3)-equivariant prediction of molecular wavefunctions and electronic densities. *Advances in Neural Information Processing Systems*, 34:14434–14447, 2021.
- [12] Jonathan Godwin, Michael Schaarschmidt, Alexander Gaunt, Alvaro Sanchez-Gonzalez, Yulia Rubanova, Petar Veličković, James Kirkpatrick, and Peter Battaglia. Simple gnn regularisation for 3d molecular property prediction & beyond. *arXiv preprint arXiv:2106.07971*, 2021.
- [13] Sheheryar Zaidi, Michael Schaarschmidt, James Martens, Hyunjik Kim, Yee Whye Teh, Alvaro Sanchez-Gonzalez, Peter Battaglia, Razvan Pascanu, and Jonathan Godwin. Pre-training via denoising for molecular property prediction. *arXiv preprint arXiv:2206.00133*, 2022.
- [14] Andrew R Leach. *Molecular modelling: principles and applications*. Pearson education, 2001.
- [15] Trevor Hastie, Robert Tibshirani, Jerome H Friedman, and Jerome H Friedman. *The elements of statistical learning: data mining, inference, and prediction*, volume 2. Springer, 2009.
- [16] Yurou Liu, Jiahao Chen, Rui Jiao, Jiangmeng Li, Wenbing Huang, and Bing Su. Denoisevae: Learning molecule-adaptive noise distributions for denoising-based 3d molecular pre-training. In *The Thirteenth International Conference on Learning Representations*, 2025.
- [17] Shikun Feng, Yuyan Ni, Yanyan Lan, Zhi-Ming Ma, and Wei-Ying Ma. Fractional denoising for 3d molecular pre-training. In *International Conference on Machine Learning*, pages 9938–9961. PMLR, 2023.
- [18] Yuyan Ni, Shikun Feng, Wei-Ying Ma, Zhi-Ming Ma, and Yanyan Lan. Sliced denoising: A physics-informed molecular pre-training method. *arXiv preprint arXiv:2311.02124*, 2023.
- [19] Kaiming He, Xinlei Chen, Saining Xie, Yanghao Li, Piotr Dollár, and Ross Girshick. Masked autoencoders are scalable vision learners. In *Proceedings of the IEEE/CVF conference on computer vision and pattern recognition*, pages 16000–16009, 2022.

- [20] Jacob Devlin, Ming-Wei Chang, Kenton Lee, and Kristina Toutanova. Bert: Pre-training of deep bidirectional transformers for language understanding. In *Proceedings of the 2019 conference of the North American chapter of the association for computational linguistics: human language technologies, volume 1 (long and short papers)*, pages 4171–4186, 2019.
- [21] Zhiyuan Liu, Yaorui Shi, An Zhang, Enzhi Zhang, Kenji Kawaguchi, Xiang Wang, and Tat-Seng Chua. Rethinking tokenizer and decoder in masked graph modeling for molecules. *Advances in Neural Information Processing Systems*, 36:25854–25875, 2023.
- [22] Yuyang Wang, Changwen Xu, Zijie Li, and Amir Barati Farimani. Denoise pretraining on nonequilibrium molecules for accurate and transferable neural potentials. *Journal of Chemical Theory and Computation*, 19(15):5077–5087, 2023.
- [23] Tianlang Chen, Shengjie Luo, Di He, Shuxin Zheng, Tie-Yan Liu, and Liwei Wang. Geomformer: A general architecture for geometric molecular representation learning. *arXiv preprint arXiv:2406.16853*, 2024.
- [24] Yi-Lun Liao, Brandon Wood, Abhishek Das, and Tess Smidt. Equiformerv2: Improved equivariant transformer for scaling to higher-degree representations. In *ICLR*, 2024.
- [25] Gene H Golub and Charles F Van Loan. *Matrix computations*. JHU press, 2013.
- [26] Yusong Wang, Shaoning Li, Tong Wang, Bin Shao, Nanning Zheng, and Tie-Yan Liu. Geometric transformer with interatomic positional encoding. *Advances in Neural Information Processing Systems*, 36:55981–55994, 2023.
- [27] Yi-Lun Liao, Tess Smidt, Muhammed Shuaibi, and Abhishek Das. Generalizing denoising to non-equilibrium structures improves equivariant force fields. *arXiv preprint arXiv:2403.09549*, 2024.
- [28] Johannes Gasteiger, Janek Groß, and Stephan Günnemann. Directional message passing for molecular graphs. *arXiv preprint arXiv:2003.03123*, 2020.
- [29] Yang Song and Stefano Ermon. Generative modeling by estimating gradients of the data distribution. *Advances in neural information processing systems*, 32, 2019.
- [30] Pascal Vincent. A connection between score matching and denoising autoencoders. *Neural computation*, 23(7):1661–1674, 2011.
- [31] Shengchao Liu, Hongyu Guo, and Jian Tang. Molecular geometry pretraining with se (3)-invariant denoising distance matching. *arXiv preprint arXiv:2206.13602*, 2022.
- [32] Maho Nakata and Tomomi Shimazaki. Pubchemqc project: a large-scale first-principles electronic structure database for data-driven chemistry. *Journal of chemical information and modeling*, 57(6):1300–1308, 2017.
- [33] Richard Tran, Janice Lan, Muhammed Shuaibi, Brandon M Wood, Siddharth Goyal, Abhishek Das, Javier Heras-Domingo, Adeesh Kolluru, Ammar Rizvi, Nima Shoghi, et al. The open catalyst 2022 (oc22) dataset and challenges for oxide electrocatalysts. *ACS Catalysis*, 13(5):3066–3084, 2023.
- [34] Stefan Chmiela, Alexandre Tkatchenko, Huziel E Sauceda, Igor Poltavsky, Kristof T Schütt, and Klaus-Robert Müller. Machine learning of accurate energy-conserving molecular force fields. *Science advances*, 3(5):e1603015, 2017.
- [35] Bowen Deng, Peichen Zhong, KyuJung Jun, Janosh Riebesell, Kevin Han, Christopher J Bartel, and Gerbrand Ceder. Chgnet as a pretrained universal neural network potential for charge-informed atomistic modelling. *Nature Machine Intelligence*, 5(9):1031–1041, 2023.
- [36] Anubhav Jain, Shyue Ping Ong, Geoffroy Hautier, Wei Chen, William Davidson Richards, Stephen Dacek, Shreyas Cholia, Dan Gunter, David Skinner, Gerbrand Ceder, and Kristin A. Persson. Commentary: The materials project: A materials genome approach to accelerating materials innovation. *APL Materials*, 1(1):011002, 07 2013.

- [37] Kristof T Schütt, Huziel E Saucedo, P-J Kindermans, Alexandre Tkatchenko, and K-R Müller. SchNet—a deep learning architecture for molecules and materials. *The Journal of Chemical Physics*, 148(24), 2018.
- [38] Johannes Gasteiger, Shankari Giri, Johannes T Margraf, and Stephan Günnemann. Fast and uncertainty-aware directional message passing for non-equilibrium molecules. *arXiv preprint arXiv:2011.14115*, 2020.
- [39] Kristof Schütt, Oliver Unke, and Michael Gastegger. Equivariant message passing for the prediction of tensorial properties and molecular spectra. In *International Conference on Machine Learning*, pages 9377–9388. PMLR, 2021.
- [40] Philipp Thölke and Gianni De Fabritiis. Torchmd-net: equivariant transformers for neural network based molecular potentials. *arXiv preprint arXiv:2202.02541*, 2022.
- [41] Shengchao Liu, Hongyu Guo, and Jian Tang. Molecular geometry pretraining with SE(3)-invariant denoising distance matching. In *The Eleventh International Conference on Learning Representations*, 2023.
- [42] Johannes Gasteiger, Muhammed Shuaibi, Anuroop Sriram, Stephan Günnemann, Zachary Ulissi, C Lawrence Zitnick, and Abhishek Das. Gemnet-oc: developing graph neural networks for large and diverse molecular simulation datasets. *arXiv preprint arXiv:2204.02782*, 2022.
- [43] Yunyang Li, Lin Huang, Zhihao Ding, Chu Wang, Xinran Wei, Han Yang, Zun Wang, Chang Liu, Yu Shi, Peiran Jin, et al. E2former: A linear-time efficient and equivariant transformer for scalable molecular modeling. *arXiv e-prints*, pages arXiv–2501, 2025.
- [44] Rui Jiao, Jiaqi Han, Wenbing Huang, Yu Rong, and Yang Liu. Energy-motivated equivariant pretraining for 3d molecular graphs. In *Proceedings of the AAAI Conference on Artificial Intelligence*, volume 37, pages 8096–8104, 2023.
- [45] Gengmo Zhou, Zhifeng Gao, Qiankun Ding, Hang Zheng, Hongteng Xu, Zhewei Wei, Linfeng Zhang, and Guolin Ke. Uni-mol: A universal 3d molecular representation learning framework. 2023.
- [46] Diederik P. Kingma and Max Welling. Auto-encoding variational bayes. In *ICLR*, 2014.
- [47] Han Yang, Chenxi Hu, Yichi Zhou, Xixian Liu, Yu Shi, Jielan Li, Guanzhi Li, Zekun Chen, Shuizhou Chen, Claudio Zeni, et al. Mattersim: A deep learning atomistic model across elements, temperatures and pressures. *arXiv preprint arXiv:2405.04967*, 2024.
- [48] Nima Shoghi, Adeesh Kolluru, John R Kitchin, Zachary W Ulissi, C Lawrence Zitnick, and Brandon M Wood. From molecules to materials: Pre-training large generalizable models for atomic property prediction. *arXiv preprint arXiv:2310.16802*, 2023.
- [49] Shengchao Liu, Weitao Du, Zhi-Ming Ma, Hongyu Guo, and Jian Tang. A group symmetric stochastic differential equation model for molecule multi-modal pretraining. In *International Conference on Machine Learning*, pages 21497–21526. PMLR, 2023.
- [50] Shengjie Luo, Tianlang Chen, Yixian Xu, Shuxin Zheng, Tie-Yan Liu, Liwei Wang, and Di He. One transformer can understand both 2d & 3d molecular data. *arXiv preprint arXiv:2210.01765*, 2022.
- [51] Shikun Feng, Yuyan Ni, Minghao Li, Yanwen Huang, Zhi-Ming Ma, Wei-Ying Ma, and Yanyan Lan. Unicorn: A unified contrastive learning approach for multi-view molecular representation learning. *arXiv preprint arXiv:2405.10343*, 2024.
- [52] Qiyang Yu, Yudi Zhang, Yuyan Ni, Shikun Feng, Yanyan Lan, Hao Zhou, and Jingjing Liu. Multimodal molecular pretraining via modality blending. *arXiv preprint arXiv:2307.06235*, 2023.

- [53] Sihang Li, Zhiyuan Liu, Yanchen Luo, Xiang Wang, Xiangnan He, Kenji Kawaguchi, Tat-Seng Chua, and Qi Tian. 3d-molm: Towards 3d molecule-text interpretation in language models. In *ICLR*, 2024.
- [54] Zhiyuan Liu, Sihang Li, Yanchen Luo, Hao Fei, Yixin Cao, Kenji Kawaguchi, Xiang Wang, and Tat-Seng Chua. Molca: Molecular graph-language modeling with cross-modal projector and uni-modal adapter. In *EMNLP*, 2023.
- [55] Zhiyuan Liu, Yanchen Luo, Han Huang, Enzhi Zhang, Sihang Li, Junfeng Fang, Yaorui Shi, Xiang Wang, Kenji Kawaguchi, and Tat-Seng Chua. NEXT-MOL: 3d diffusion meets 1d language modeling for 3d molecule generation. In *The Thirteenth International Conference on Learning Representations*, 2025.
- [56] Zhiyuan Liu, Yaorui Shi, An Zhang, Sihang Li, Enzhi Zhang, Xiang Wang, Kenji Kawaguchi, and Tat-Seng Chua. Reactxt: Understanding molecular “reaction-ship” via reaction-contextualized molecule-text pretraining. In *Findings of the Association for Computational Linguistics: ACL 2024*. Association for Computational Linguistics, 2024.
- [57] Zhiyuan Liu, Yaorui Shi, An Zhang, Enzhi Zhang, Kenji Kawaguchi, Xiang Wang, and Tat-Seng Chua. Rethinking tokenizer and decoder in masked graph modeling for molecules. In *NeurIPS*, 2023.
- [58] Zhiyuan Liu, An Zhang, Hao Fei, Enzhi Zhang, Xiang Wang, Kenji Kawaguchi, and Tat-Seng Chua. Prott3: Protein-to-text generation for text-based protein understanding. In *ACL*. Association for Computational Linguistics, 2024.
- [59] Yanchen Luo, Zhiyuan Liu, Yi Zhao, Sihang Li, Hengxing Cai, Kenji Kawaguchi, Tat-Seng Chua, Yang Zhang, and Xiang Wang. Towards unified and lossless latent space for 3d molecular latent diffusion modeling. *arXiv preprint arXiv:2503.15567*, 2025.
- [60] Yaorui Shi, Jiaqi Yang, Changhao Nai, Sihang Li, Junfeng Fang, Xiang Wang, Zhiyuan Liu, and Yang Zhang. Language-enhanced representation learning for single-cell transcriptomics. *arXiv preprint arXiv:2503.09427*, 2025.
- [61] Yingce Xia, Peiran Jin, Shufang Xie, Liang He, Chuan Cao, Renqian Luo, Guoqing Liu, Yue Wang, Zequn Liu, Yuan-Jyue Chen, et al. Naturelm: Deciphering the language of nature for scientific discovery. *arXiv e-prints*, pages arXiv–2502, 2025.
- [62] Jielan Li, Zekun Chen, Qian Wang, Han Yang, Ziheng Lu, Guanzhi Li, Shuizhou Chen, Yu Zhu, Xixian Liu, Junfu Tan, et al. Probing the limit of heat transfer in inorganic crystals with deep learning. *arXiv preprint arXiv:2503.11568*, 2025.
- [63] Jonathan Schmidt, Tiago FT Cerqueira, Aldo H Romero, Antoine Loew, Fabian Jäger, Hai-Chen Wang, Silvana Botti, and Miguel AL Marques. Improving machine-learning models in materials science through large datasets. *Materials Today Physics*, 48:101560, 2024.
- [64] Jinzhe Zeng, Duo Zhang, Anyang Peng, Xiangyu Zhang, Sensen He, Yan Wang, Xinzijian Liu, Hangrui Bi, Yifan Li, Chun Cai, et al. Deepmd-kit v3: A multiple-backend framework for machine learning potentials. *Journal of Chemical Theory and Computation*, 2025.
- [65] Ilyes Batatia, David P Kovacs, Gregor Simm, Christoph Ortner, and Gábor Csányi. Mace: Higher order equivariant message passing neural networks for fast and accurate force fields. *Advances in neural information processing systems*, 35:11423–11436, 2022.
- [66] Luis Barroso-Luque, Muhammed Shuaibi, Xiang Fu, Brandon M Wood, Misko Dzamba, Meng Gao, Ammar Rizvi, C Lawrence Zitnick, and Zachary W Ulissi. Open materials 2024 (omat24) inorganic materials dataset and models. *arXiv preprint arXiv:2410.12771*, 2024.
- [67] Viktor Zaverkin, Francesco Alesiani, Takashi Maruyama, Federico Errica, Henrik Christiansen, Makoto Takamoto, Nicolas Weber, and Mathias Niepert. Higher-rank irreducible cartesian tensors for equivariant message passing. *Advances in Neural Information Processing Systems*, 37:124025–124068, 2024.

- [68] Anders S Christensen and O Anatole Von Lilienfeld. On the role of gradients for machine learning of molecular energies and forces. *Machine Learning: Science and Technology*, 1(4):045018, 2020.
- [69] Stefan Chmiela, Valentin Vassilev-Galindo, Oliver T Unke, Adil Kabylda, Huziel E Saucedo, Alexandre Tkatchenko, and Klaus-Robert Müller. Accurate global machine learning force fields for molecules with hundreds of atoms. *Science Advances*, 9(2):eadf0873, 2023.
- [70] Yunyang Li, Yusong Wang, Lin Huang, Han Yang, Xinran Wei, Jia Zhang, Tong Wang, Zun Wang, Bin Shao, and Tie-Yan Liu. Long-short-range message-passing: A physics-informed framework to capture non-local interaction for scalable molecular dynamics simulation. *arXiv preprint arXiv:2304.13542*, 2023.

NeurIPS Paper Checklist

1. Claims

Question: Do the main claims made in the abstract and introduction accurately reflect the paper's contributions and scope?

Answer: [Yes]

Justification: We assure that the main claims made in the abstract and introduction accurately reflect the paper's contributions and scope.

Guidelines:

- The answer NA means that the abstract and introduction do not include the claims made in the paper.
- The abstract and/or introduction should clearly state the claims made, including the contributions made in the paper and important assumptions and limitations. A No or NA answer to this question will not be perceived well by the reviewers.
- The claims made should match theoretical and experimental results, and reflect how much the results can be expected to generalize to other settings.
- It is fine to include aspirational goals as motivation as long as it is clear that these goals are not attained by the paper.

2. Limitations

Question: Does the paper discuss the limitations of the work performed by the authors?

Answer: [Yes]

Justification: The limitations are in Appendix [A](#)

Guidelines:

- The answer NA means that the paper has no limitation while the answer No means that the paper has limitations, but those are not discussed in the paper.
- The authors are encouraged to create a separate "Limitations" section in their paper.
- The paper should point out any strong assumptions and how robust the results are to violations of these assumptions (e.g., independence assumptions, noiseless settings, model well-specification, asymptotic approximations only holding locally). The authors should reflect on how these assumptions might be violated in practice and what the implications would be.
- The authors should reflect on the scope of the claims made, e.g., if the approach was only tested on a few datasets or with a few runs. In general, empirical results often depend on implicit assumptions, which should be articulated.
- The authors should reflect on the factors that influence the performance of the approach. For example, a facial recognition algorithm may perform poorly when image resolution is low or images are taken in low lighting. Or a speech-to-text system might not be used reliably to provide closed captions for online lectures because it fails to handle technical jargon.
- The authors should discuss the computational efficiency of the proposed algorithms and how they scale with dataset size.
- If applicable, the authors should discuss possible limitations of their approach to address problems of privacy and fairness.
- While the authors might fear that complete honesty about limitations might be used by reviewers as grounds for rejection, a worse outcome might be that reviewers discover limitations that aren't acknowledged in the paper. The authors should use their best judgment and recognize that individual actions in favor of transparency play an important role in developing norms that preserve the integrity of the community. Reviewers will be specifically instructed to not penalize honesty concerning limitations.

3. Theory assumptions and proofs

Question: For each theoretical result, does the paper provide the full set of assumptions and a complete (and correct) proof?

Answer: [Yes]

Justification: We include the full assumptions and complete proof in Section 3 and Appendix B.

Guidelines:

- The answer NA means that the paper does not include theoretical results.
- All the theorems, formulas, and proofs in the paper should be numbered and cross-referenced.
- All assumptions should be clearly stated or referenced in the statement of any theorems.
- The proofs can either appear in the main paper or the supplemental material, but if they appear in the supplemental material, the authors are encouraged to provide a short proof sketch to provide intuition.
- Inversely, any informal proof provided in the core of the paper should be complemented by formal proofs provided in appendix or supplemental material.
- Theorems and Lemmas that the proof relies upon should be properly referenced.

4. Experimental result reproducibility

Question: Does the paper fully disclose all the information needed to reproduce the main experimental results of the paper to the extent that it affects the main claims and/or conclusions of the paper (regardless of whether the code and data are provided or not)?

Answer: [Yes]

Justification: We provide details for reproduction in Section 4 and Appendix C.2.

Guidelines:

- The answer NA means that the paper does not include experiments.
- If the paper includes experiments, a No answer to this question will not be perceived well by the reviewers: Making the paper reproducible is important, regardless of whether the code and data are provided or not.
- If the contribution is a dataset and/or model, the authors should describe the steps taken to make their results reproducible or verifiable.
- Depending on the contribution, reproducibility can be accomplished in various ways. For example, if the contribution is a novel architecture, describing the architecture fully might suffice, or if the contribution is a specific model and empirical evaluation, it may be necessary to either make it possible for others to replicate the model with the same dataset, or provide access to the model. In general, releasing code and data is often one good way to accomplish this, but reproducibility can also be provided via detailed instructions for how to replicate the results, access to a hosted model (e.g., in the case of a large language model), releasing of a model checkpoint, or other means that are appropriate to the research performed.
- While NeurIPS does not require releasing code, the conference does require all submissions to provide some reasonable avenue for reproducibility, which may depend on the nature of the contribution. For example
 - (a) If the contribution is primarily a new algorithm, the paper should make it clear how to reproduce that algorithm.
 - (b) If the contribution is primarily a new model architecture, the paper should describe the architecture clearly and fully.
 - (c) If the contribution is a new model (e.g., a large language model), then there should either be a way to access this model for reproducing the results or a way to reproduce the model (e.g., with an open-source dataset or instructions for how to construct the dataset).
 - (d) We recognize that reproducibility may be tricky in some cases, in which case authors are welcome to describe the particular way they provide for reproducibility. In the case of closed-source models, it may be that access to the model is limited in some way (e.g., to registered users), but it should be possible for other researchers to have some path to reproducing or verifying the results.

5. Open access to data and code

Question: Does the paper provide open access to the data and code, with sufficient instructions to faithfully reproduce the main experimental results, as described in supplemental material?

Answer: [Yes]

Justification: Our code is released at <https://anonymous.4open.science/r/AnIDS>.

Guidelines:

- The answer NA means that paper does not include experiments requiring code.
- Please see the NeurIPS code and data submission guidelines (<https://nips.cc/public/guides/CodeSubmissionPolicy>) for more details.
- While we encourage the release of code and data, we understand that this might not be possible, so “No” is an acceptable answer. Papers cannot be rejected simply for not including code, unless this is central to the contribution (e.g., for a new open-source benchmark).
- The instructions should contain the exact command and environment needed to run to reproduce the results. See the NeurIPS code and data submission guidelines (<https://nips.cc/public/guides/CodeSubmissionPolicy>) for more details.
- The authors should provide instructions on data access and preparation, including how to access the raw data, preprocessed data, intermediate data, and generated data, etc.
- The authors should provide scripts to reproduce all experimental results for the new proposed method and baselines. If only a subset of experiments are reproducible, they should state which ones are omitted from the script and why.
- At submission time, to preserve anonymity, the authors should release anonymized versions (if applicable).
- Providing as much information as possible in supplemental material (appended to the paper) is recommended, but including URLs to data and code is permitted.

6. Experimental setting/details

Question: Does the paper specify all the training and test details (e.g., data splits, hyper-parameters, how they were chosen, type of optimizer, etc.) necessary to understand the results?

Answer: [Yes]

Justification: The details are provided in Section 4 and Appendix C.2

Guidelines:

- The answer NA means that the paper does not include experiments.
- The experimental setting should be presented in the core of the paper to a level of detail that is necessary to appreciate the results and make sense of them.
- The full details can be provided either with the code, in appendix, or as supplemental material.

7. Experiment statistical significance

Question: Does the paper report error bars suitably and correctly defined or other appropriate information about the statistical significance of the experiments?

Answer: [No]

Justification: Our experiments are mostly computational expensive. Therefore, we run only one group of experiment for each setting, following previous works.

Guidelines:

- The answer NA means that the paper does not include experiments.
- The authors should answer "Yes" if the results are accompanied by error bars, confidence intervals, or statistical significance tests, at least for the experiments that support the main claims of the paper.
- The factors of variability that the error bars are capturing should be clearly stated (for example, train/test split, initialization, random drawing of some parameter, or overall run with given experimental conditions).
- The method for calculating the error bars should be explained (closed form formula, call to a library function, bootstrap, etc.)
- The assumptions made should be given (e.g., Normally distributed errors).

- It should be clear whether the error bar is the standard deviation or the standard error of the mean.
- It is OK to report 1-sigma error bars, but one should state it. The authors should preferably report a 2-sigma error bar than state that they have a 96% CI, if the hypothesis of Normality of errors is not verified.
- For asymmetric distributions, the authors should be careful not to show in tables or figures symmetric error bars that would yield results that are out of range (e.g. negative error rates).
- If error bars are reported in tables or plots, The authors should explain in the text how they were calculated and reference the corresponding figures or tables in the text.

8. Experiments compute resources

Question: For each experiment, does the paper provide sufficient information on the computer resources (type of compute workers, memory, time of execution) needed to reproduce the experiments?

Answer: [Yes]

Justification: These details are provided in Appendix [C.2](#)

Guidelines:

- The answer NA means that the paper does not include experiments.
- The paper should indicate the type of compute workers CPU or GPU, internal cluster, or cloud provider, including relevant memory and storage.
- The paper should provide the amount of compute required for each of the individual experimental runs as well as estimate the total compute.
- The paper should disclose whether the full research project required more compute than the experiments reported in the paper (e.g., preliminary or failed experiments that didn't make it into the paper).

9. Code of ethics

Question: Does the research conducted in the paper conform, in every respect, with the NeurIPS Code of Ethics <https://neurips.cc/public/EthicsGuidelines>?

Answer: [Yes]

Justification: We respect the NeurIPS code of ethics.

Guidelines:

- The answer NA means that the authors have not reviewed the NeurIPS Code of Ethics.
- If the authors answer No, they should explain the special circumstances that require a deviation from the Code of Ethics.
- The authors should make sure to preserve anonymity (e.g., if there is a special consideration due to laws or regulations in their jurisdiction).

10. Broader impacts

Question: Does the paper discuss both potential positive societal impacts and negative societal impacts of the work performed?

Answer: [NA]

Justification: This work is about small molecules and materials, which does not involve societal impact.

Guidelines:

- The answer NA means that there is no societal impact of the work performed.
- If the authors answer NA or No, they should explain why their work has no societal impact or why the paper does not address societal impact.
- Examples of negative societal impacts include potential malicious or unintended uses (e.g., disinformation, generating fake profiles, surveillance), fairness considerations (e.g., deployment of technologies that could make decisions that unfairly impact specific groups), privacy considerations, and security considerations.

- The conference expects that many papers will be foundational research and not tied to particular applications, let alone deployments. However, if there is a direct path to any negative applications, the authors should point it out. For example, it is legitimate to point out that an improvement in the quality of generative models could be used to generate deepfakes for disinformation. On the other hand, it is not needed to point out that a generic algorithm for optimizing neural networks could enable people to train models that generate Deepfakes faster.
- The authors should consider possible harms that could arise when the technology is being used as intended and functioning correctly, harms that could arise when the technology is being used as intended but gives incorrect results, and harms following from (intentional or unintentional) misuse of the technology.
- If there are negative societal impacts, the authors could also discuss possible mitigation strategies (e.g., gated release of models, providing defenses in addition to attacks, mechanisms for monitoring misuse, mechanisms to monitor how a system learns from feedback over time, improving the efficiency and accessibility of ML).

11. Safeguards

Question: Does the paper describe safeguards that have been put in place for responsible release of data or models that have a high risk for misuse (e.g., pretrained language models, image generators, or scraped datasets)?

Answer: [NA]

Justification: Our research are about small molecules and materials that dose not have such risks.

Guidelines:

- The answer NA means that the paper poses no such risks.
- Released models that have a high risk for misuse or dual-use should be released with necessary safeguards to allow for controlled use of the model, for example by requiring that users adhere to usage guidelines or restrictions to access the model or implementing safety filters.
- Datasets that have been scraped from the Internet could pose safety risks. The authors should describe how they avoided releasing unsafe images.
- We recognize that providing effective safeguards is challenging, and many papers do not require this, but we encourage authors to take this into account and make a best faith effort.

12. Licenses for existing assets

Question: Are the creators or original owners of assets (e.g., code, data, models), used in the paper, properly credited and are the license and terms of use explicitly mentioned and properly respected?

Answer: [Yes]

Justification: The discussion is in Appendix [C.2.2](#)

Guidelines:

- The answer NA means that the paper does not use existing assets.
- The authors should cite the original paper that produced the code package or dataset.
- The authors should state which version of the asset is used and, if possible, include a URL.
- The name of the license (e.g., CC-BY 4.0) should be included for each asset.
- For scraped data from a particular source (e.g., website), the copyright and terms of service of that source should be provided.
- If assets are released, the license, copyright information, and terms of use in the package should be provided. For popular datasets, paperswithcode.com/datasets has curated licenses for some datasets. Their licensing guide can help determine the license of a dataset.
- For existing datasets that are re-packaged, both the original license and the license of the derived asset (if it has changed) should be provided.

- If this information is not available online, the authors are encouraged to reach out to the asset’s creators.

13. New assets

Question: Are new assets introduced in the paper well documented and is the documentation provided alongside the assets?

Answer: [Yes]

Justification: Our released code at <https://anonymous.4open.science/r/AniDS> is accompanied with a README as the documentation.

Guidelines:

- The answer NA means that the paper does not release new assets.
- Researchers should communicate the details of the dataset/code/model as part of their submissions via structured templates. This includes details about training, license, limitations, etc.
- The paper should discuss whether and how consent was obtained from people whose asset is used.
- At submission time, remember to anonymize your assets (if applicable). You can either create an anonymized URL or include an anonymized zip file.

14. Crowdsourcing and research with human subjects

Question: For crowdsourcing experiments and research with human subjects, does the paper include the full text of instructions given to participants and screenshots, if applicable, as well as details about compensation (if any)?

Answer: [NA]

Justification: We do not include these resources.

Guidelines:

- The answer NA means that the paper does not involve crowdsourcing nor research with human subjects.
- Including this information in the supplemental material is fine, but if the main contribution of the paper involves human subjects, then as much detail as possible should be included in the main paper.
- According to the NeurIPS Code of Ethics, workers involved in data collection, curation, or other labor should be paid at least the minimum wage in the country of the data collector.

15. Institutional review board (IRB) approvals or equivalent for research with human subjects

Question: Does the paper describe potential risks incurred by study participants, whether such risks were disclosed to the subjects, and whether Institutional Review Board (IRB) approvals (or an equivalent approval/review based on the requirements of your country or institution) were obtained?

Answer: [NA]

Justification: We do not include such risks.

Guidelines:

- The answer NA means that the paper does not involve crowdsourcing nor research with human subjects.
- Depending on the country in which research is conducted, IRB approval (or equivalent) may be required for any human subjects research. If you obtained IRB approval, you should clearly state this in the paper.
- We recognize that the procedures for this may vary significantly between institutions and locations, and we expect authors to adhere to the NeurIPS Code of Ethics and the guidelines for their institution.
- For initial submissions, do not include any information that would break anonymity (if applicable), such as the institution conducting the review.

16. Declaration of LLM usage

Question: Does the paper describe the usage of LLMs if it is an important, original, or non-standard component of the core methods in this research? Note that if the LLM is used only for writing, editing, or formatting purposes and does not impact the core methodology, scientific rigorousness, or originality of the research, declaration is not required.

Answer: [NA]

Justification: The core method development in this research does not involve LLMs as any important, original, or non-standard components.

Guidelines:

- The answer NA means that the core method development in this research does not involve LLMs as any important, original, or non-standard components.
- Please refer to our LLM policy (<https://neurips.cc/Conferences/2025/LLM>) for what should or should not be described.