

Explainable Pathomics Feature Visualization via Correlation-aware Conditional Feature Editing

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Abstract

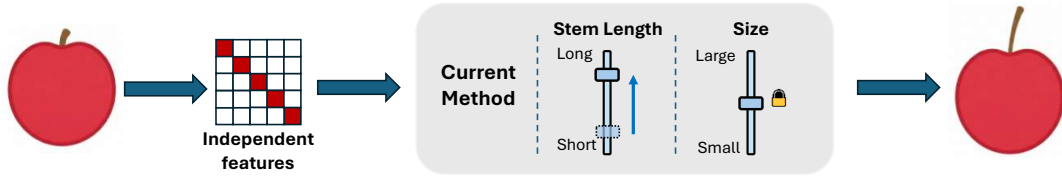
Pathomics is a recent approach that offers rich quantitative features beyond what black-box deep learning can provide, supporting more reproducible and explainable biomarkers in digital pathology. However, many derived features (e.g., “second-order moment”) remain difficult to interpret, especially across different clinical contexts, which limits their practical adoption. Conditional diffusion models show promise for explainability through feature editing, but they typically assume feature independence—an assumption violated by intrinsically correlated pathomics features. Consequently, editing one feature while fixing others can push the model off the biological manifold and produce unrealistic artifacts. To address this, we propose a Manifold-Aware Diffusion (MAD) framework for controllable and biologically plausible cell nuclei editing. Unlike existing approaches, our method regularizes feature trajectories within a disentangled latent space learned by a variational auto-encoder (VAE). This ensures that manipulating a target feature automatically adjusts correlated attributes to remain within the learned distribution of real cells. These optimized features then guide a conditional diffusion model to synthesize high-fidelity images. Experiments demonstrate that our approach is able to navigate the manifold of pathomics features when editing those features. The proposed method outperforms baseline methods in conditional feature editing while preserving structural coherence.

Keywords: Digital Pathology, diffusion models, pathomics, image generation, explainability.

1. Introduction

While deep learning models excel in predictive performance, pathomics remains valuable for its ability to decompose histological patterns into explicitly defined quantitative metrics such as shape, intensity, and texture. Tools like CellProfiler (McQuin et al., 2018; Stirling et al., 2021) and Pyspatial (Yang et al., 2025) allow researchers to extract hundreds of quantitative phenotypic features from pathology images. These high-dimensional signatures have supported clinical studies, for example in renal artery morphology (Yin et al., 2025b) and nephron-specific glomerular responses (Yin et al., 2025a). However, an interpretability gap remains. Statistical models can indicate which features are associated with an outcome, but clinicians still lack a clear picture of how a numerical change in a feature (for example, compactness increasing from 0.85 to 0.95) appears in the corresponding tissue object. Figure 1(a) sketches an ideal explanation system in which a user adjusts feature sliders and can immediately see how the object in pathology image changes.

(a) Ideally: An editing-based explanation AI could independently visualize features using conditional diffusion.



(b) In reality: Explaining pathomics features with such an AI is challenging because the features are often correlated, so editing a single feature may introduce conflicts.

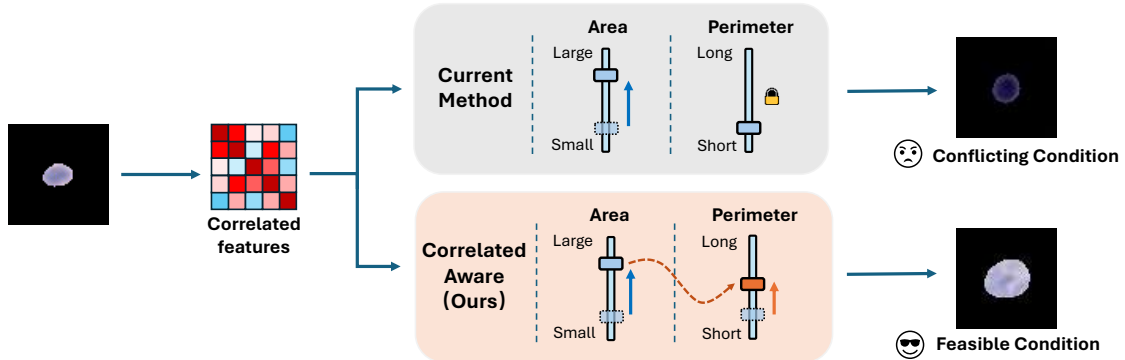


Figure 1: **Feature editing in pathomics.** (a) In generic object editing (e.g., an apple), attributes such as stem length and size operate independently. Modifying one feature does not impose constraints on others. (b) Pathomics features often exhibit intrinsic correlations (e.g., Area and Perimeter). The "Current Method" modifies the target feature (Area) while fixing the correlated feature (Perimeter), creating a geometric conflict and resulting in an infeasible edit. The proposed "Correlated-Aware" framework updates the correlated attribute alongside the target, ensuring the output remains within a feasible biological structure.

One way to approach such an explanation system is to use generative models that map features back to images. In this view, a generative model takes a feature vector as input, produces an image as output, and can act as a visual explanation tool. Recent work has explored this idea for pathomics. CP2Image (Ji et al., 2024) generates cell images directly from CellProfiler metrics, demonstrating that these hand-crafted features encode sufficient information for visual reconstruction. Continuous Conditional Diffusion Model (CCDM) (Ding et al., 2024) introduces mechanisms for conditioning diffusion models on continuous scalar values, enabling fine-grained control over attributes like cell counts or angles.

However, applying this idea to pathomics feature editing introduces a key difficulty. Many conditional pipelines implicitly rely on a feature independence assumption: when a target attribute such as area is modified, the remaining attributes are kept fixed. As noted in the CP2Image paper, current practices involve isolating a target feature for enhancement while keeping the remaining dimensions constant (Ji et al., 2024). Figure 1(b) illustrates why this is problematic for pathomics features. Attributes such as area and perimeter are intrinsically correlated and lie on a low-dimensional biological manifold. Increasing the area of a nucleus without adjusting its perimeter violates geometric laws and creates a conflicting condition for the generative model.

To address this, we propose Manifold-Aware Diffusion (MAD), a framework for controllable and correlation-aware pathomics feature editing. Instead of assuming that features can be edited independently, MAD performs feature editing on a learned manifold of pathomics features. The framework follows a two-stage design. First, a variational auto-encoder (VAE) (Kingma and Welling, 2013) learns the disentangled latent distribution of the features. Second, a conditional diffusion model synthesizes nucleus images conditioned on feature vectors. At inference time, when a user specifies a target feature value, MAD performs latent-guided optimization to obtain an edited feature vector that moves toward the target while adjusting correlated features so that the result stays on the learned manifold. We summarize our contributions as follows:

- **We propose MAD for explainable editing of correlated pathomics features.** MAD is a diffusion-based framework that edits continuous feature vectors and visualizes how changes in correlated features affect nucleus appearance.
- **MAD regularizes feature editing with a VAE-learned feature manifold.** The model performs edits within this manifold so that changes to a target feature are accompanied by correlated adjustments.
- **MAD scales to high-dimensional pathomics signatures.** A single model supports editing of 75-dimensional nuclear feature vectors and allows users to adjust each feature dimension individually.

2. Method

We propose MAD, a framework for editing correlated pathomics features with a conditional diffusion model. Figure 2 summarizes the overall idea of MAD. Edits are constrained

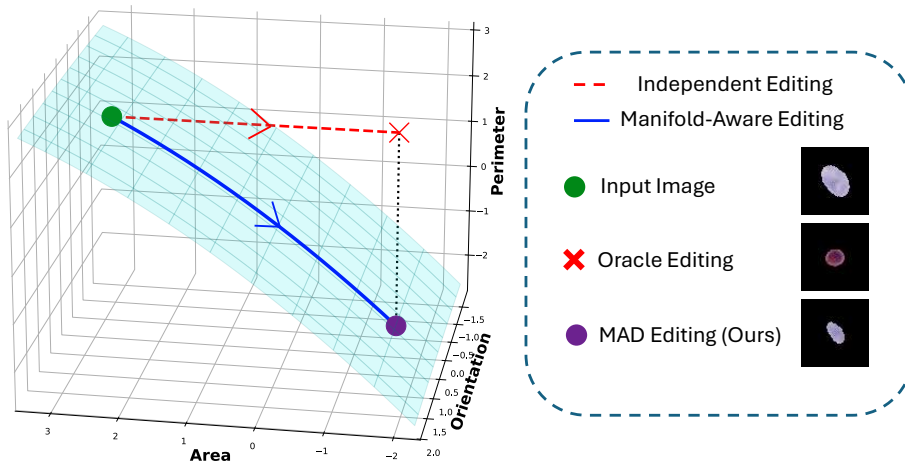


Figure 2: **Independent editing versus manifold-aware editing of correlated pathomics features.** The turquoise surface depicts the manifold of real nuclei in the feature space of area, perimeter, and orientation. The green point marks the input nucleus. To decrease area, independent editing (red dashed path) changes the area coordinate while keeping the other features fixed, reaching the oracle editing point (red cross), which lies off the manifold and leads to an out-of-distribution image. Manifold-aware editing (blue path) follows the manifold and jointly updates correlated features, reaching the MAD editing result (purple point) on the manifold. The images on the right show the input image, the image generated under the oracle editing condition, and the on-manifold result produced by our proposed model (MAD).

to follow a manifold of real nuclei features so that correlated attributes change together instead of moving off the manifold. To implement this idea, MAD decouples learning the image generator from learning the structure of the feature space, as shown in Figure 3. A conditional diffusion model learns to synthesize nucleus images from feature vectors, and a disentangled VAE learns a latent representation of valid feature combinations. At inference time, we perform latent-guided optimization in the VAE latent space to obtain an edited feature vector that moves toward a user-specified target while remaining on the learned manifold, and then use this feature vector as the condition for diffusion-based image editing.

2.1. Conditional Diffusion Model

We train a denoising diffusion probabilistic model (Ho et al., 2020) on single-nucleus images, which is illustrated in Figure 3(a). Each training sample consists of an image x_0 and its associated feature vector $y \in \mathbb{R}^N$ computed by a pathomics pipeline. This pairing ensures that the model learns to associate each image with the quantitative description that will be available in a downstream analysis pipeline. Following continuous conditional diffusion

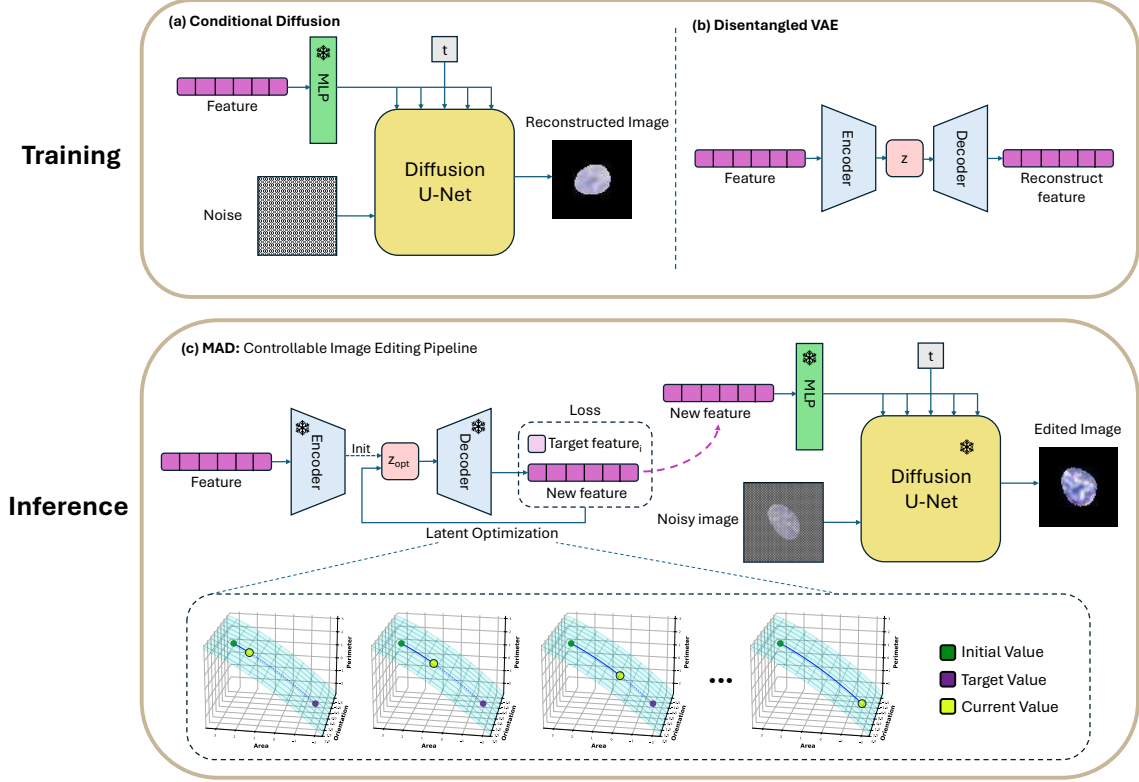


Figure 3: **Training and inference pipeline of MAD.** (a) A conditional diffusion model learns to use a feature vector to reconstruct the nucleus image. A pre-trained MLP encodes the feature vector into a conditioning embedding for the diffusion U-Net. (b) A disentangled VAE is trained on pathomics features. The encoder maps a feature vector to a latent variable z and the decoder reconstructs the feature vector. (c) Given an input nucleus and a target feature value, the encoder initializes a latent variable from the feature of the input image. Through latent optimization, the decoded feature moves toward the target feature along the learned feature manifold. The bottom plots illustrate this trajectory in the feature space. The optimized feature vector is then used as the condition for the diffusion U-Net to edit the input image.

models, we encode y with a multilayer perceptron (MLP) into a conditioning embedding $c(y)$ that is injected into each block of a U-Net denoiser (Ronneberger et al., 2015).

Let $q(x_t | x_0)$ denote the forward diffusion process that adds Gaussian noise to x_0 at time step t . The conditional U-Net ϵ_θ is trained to predict the added noise given the noisy image, the time step, and the feature embedding:

$$\mathcal{L}_{\text{diff}} = \mathbb{E}_{x_0, y, \epsilon, t} \left[\|\epsilon - \epsilon_\theta(x_t, t, c(y))\|_2^2 \right]. \quad (1)$$

At test time, we run the reverse diffusion process starting from Gaussian noise and repeatedly apply $\epsilon_\theta(\cdot, c(\tilde{y}))$ with a chosen conditioning feature vector \tilde{y} to obtain a synthetic or edited nucleus image.

2.2. Feature Manifold VAE

Pathomics feature vectors contain correlated measurements such as area, perimeter, and shape descriptors. To model these correlations, we learn a latent representation of valid feature combinations with a β -VAE (Higgins et al., 2017), which is shown in Figure 3(b). The VAE encoder \mathcal{E} maps a feature vector y to a latent code $z \in \mathbb{R}^d$, and the decoder \mathcal{D} reconstructs a feature vector \hat{y} from z .

We train the VAE on feature vectors using the following objective:

$$\mathcal{L}_{\text{vae}} = \mathbb{E}_y \left[\|y - \mathcal{D}(\mathcal{E}(y))\|_2^2 \right] + \beta D_{\text{KL}}(q(z | y) \| \mathcal{N}(0, I)), \quad (2)$$

where $q(z | y)$ is the approximate posterior produced by the encoder and β controls the strength of the Kullback–Leibler regularization. The latent space \mathcal{Z} learned by the VAE provides a continuous feature manifold on which nearby latent codes correspond to feature vectors that are close in the original attribute space.

2.3. Latent-Guided Feature Editing

Given a trained diffusion model and VAE, MAD performs feature editing at test time through latent-guided optimization, as shown in Figure 3(c). Suppose an input nucleus image x has measured feature vector y_{orig} and we wish to change the k -th feature to a target value v_{tgt} . Our goal is to obtain an edited feature vector y_{new} that reaches the target value on dimension k while remaining consistent with y_{orig} on other dimensions.

Initialization on the feature manifold. We first project y_{orig} onto the VAE latent space using the encoder

$$z_{\text{init}} = \mathcal{E}(y_{\text{orig}}). \quad (3)$$

This initialization places the optimization in a region of latent space that corresponds to observed nuclei features.

Latent optimization. We then optimize z by gradient descent while keeping the VAE parameters fixed. The optimization objective balances matching the target feature and regularizing changes to the remaining features and the latent code:

$$\mathcal{L}_{\text{opt}}(z) = \lambda_{\text{tgt}} (\mathcal{D}(z)_k - v_{\text{tgt}})^2 + \lambda_{\text{reg}} \sum_{j \neq k} w_j (\mathcal{D}(z)_j - y_{\text{orig},j})^2 + \lambda_{\text{prior}} \|z\|_2^2. \quad (4)$$

The first term encourages the decoded feature $\mathcal{D}(z)_k$ to match the target value on dimension k . The second term regularizes changes on non-target dimensions, where w_j are per-feature weights that control the strength of this regularization. The third term keeps z close to the origin of the Gaussian prior. During optimization we decode $\mathcal{D}(z)$ at each iteration; the bottom panel of Figure 3 illustrates the trajectory of the decoded features in a low-dimensional projection of the feature space.

Diffusion-based image editing. After optimization we obtain the edited feature vector

$$y_{\text{new}} = \mathcal{D}(z^*), \quad (5)$$

where z^* is the final latent code. We feed y_{new} into the same conditioning network $c(\cdot)$ used during diffusion training and run the reverse diffusion process to generate an edited image \tilde{x} . In all experiments, the diffusion parameters and the conditioning MLP are fixed during editing; only the latent code z is updated at test time.

3. Data and Experiments

3.1. Data

Dataset construction. We construct a nucleus image dataset from 1,556 whole-slide images (WSIs) of kidney tissue at $40\times$ magnification. The WSIs include human and rodent samples stained with H&E, PAS, and PASM, drawn from public repositories (NEPTUNE (Barisoni et al., 2013), HuBMAP (Howard et al., 2020)) and an internal collection at Vanderbilt University Medical Center (VUMC). This combination of species and staining protocols exposes the model to a broad range of nuclear morphologies and staining appearances. From each WSI we randomly extract five 512×512 image patches. Nucleus instance segmentation is performed with an ensemble of three published models, Cellpose (Stringer et al., 2021), StarDist (Weigert and Schmidt, 2022), and CellViT (Hörst et al., 2024). We select image patches for which all three cell foundation models generate high-quality nuclei segmentation outcomes, based on rating criteria defined by a renal pathologist with 20 years of experience at VUMC. The details of the dataset construction and curation pipelines can be found in (Guo et al., 2025b,a). Then, for computational convenience, each nucleus in the selected 512×512 patch is cropped and resized into a 64×64 nucleus-centered image. Patches containing fragmented nuclei or obvious artifacts are removed, yielding an initial pool of 93,643 nucleus-centered 64×64 image patches.

3.2. Pathomics Feature Extraction

For each nucleus patch, we compute a pathomics feature vector using Pyspatial (Yang et al., 2025). The feature set contains area- and shape-related descriptors derived from the nucleus mask. Starting from the full set of output features, we remove non-phenotypic identifiers and location-dependent quantities, and drop features that are constant or have very low variance across the dataset. This yields a 75-dimensional feature vector for each nucleus.

To reduce the impact of extreme values, we treat the top and bottom 2.5% of observations along each feature dimension as outliers. Nuclei that fall outside this range on any feature are excluded. After this filtering, the dataset used for model training and evaluation contains 28,809 nuclei, each associated with a 75-dimensional feature vector. All models are trained on this dataset, and quantitative evaluation of editing performance is conducted on a randomly sampled subset of 300 nuclei.

3.3. Metrics

We evaluate editing performance with two types of metrics. To assess control accuracy, we measure agreement between the target feature value and the feature measured from the

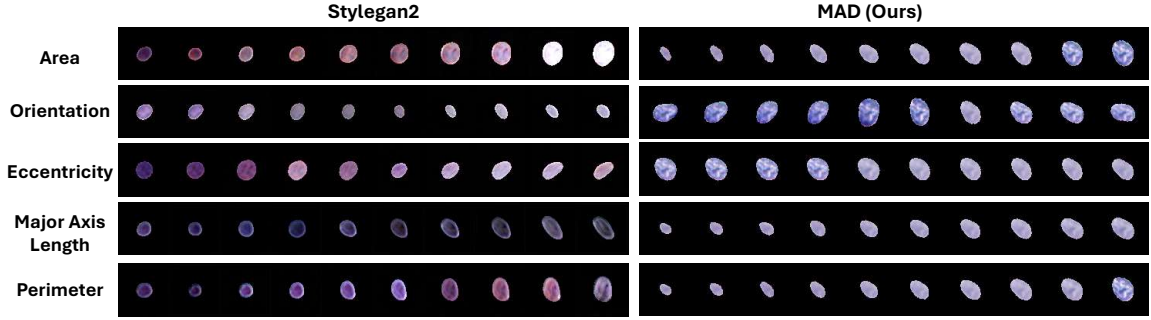


Figure 4: **Qualitative results between unconditional generation (StyleGAN2) and conditional generation (Ours).** Each row represents the traversal of a specific feature value from low to high. The left block shows StyleGAN2, which takes the target feature vector as input and generates a nucleus for each target value. The right block shows MAD, which edits a single input nucleus to match the same sequence of target values. StyleGAN2 samples follow the target feature but can introduce artifacts. MAD keeps the nuclei appearance close to the input image while changing the designated feature.

edited image using Mean Absolute Error (MAE) and coefficient of determination (R^2). Feature values on edited images are obtained from a pre-trained ResNet-based regressor. For identity preservation, we compute Learned Perceptual Image Patch Similarity (LPIPS) (Zhang et al., 2018) between the edited image and the input image. LPIPS computes distances in a deep feature space and is less sensitive than pixel-wise metrics such as SSIM to small spatial misalignments caused by shape changes.

3.4. Baselines

We compare MAD against two categories of baselines. As a generative model baseline, we use StyleGAN2-ADA (Karras et al., 2020) fine-tuned on nuclei images. At test time, we perform latent optimization in the StyleGAN w space guided by a frozen ResNet-based feature regressor so that the predicted feature value of the generated image moves towards the target value. As editing model baselines, we use Stable Diffusion v1.5 (Rombach et al., 2022) with LoRA (Hu et al., 2022) fine-tuning and a variant of our method without the VAE module (MAD w/o VAE), which uses the target feature vector directly as the diffusion condition. All models are trained and evaluated on the same dataset split and feature configuration.

4. Results

4.1. Qualitative Results

We first compare MAD with a StyleGAN2-based baseline that does not use an explicit feature manifold. Figure 4 shows StyleGAN2 and MAD along one-dimensional trajectories

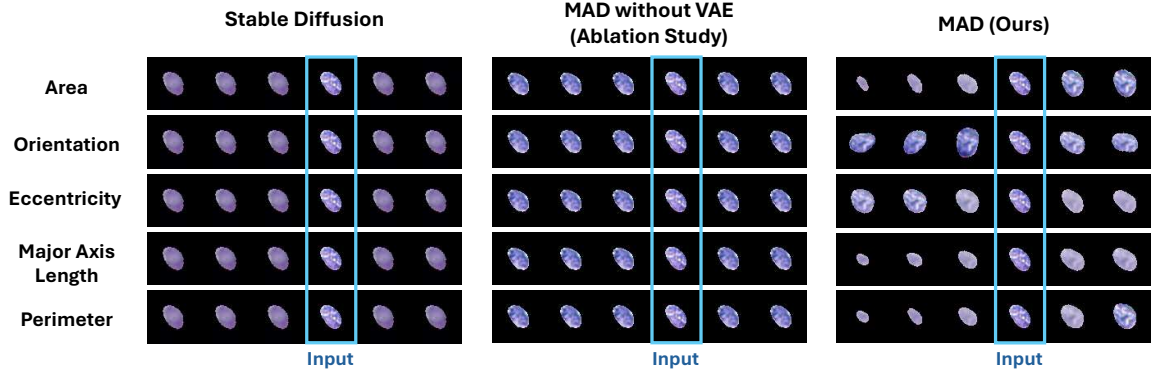


Figure 5: **Qualitative results for conditional editing.** Each row specifies a target trajectory for one nucleus feature. All three models take the same input nucleus (blue box) and the same sequence of target feature values. For Stable Diffusion and MAD without VAE, the edited nuclei stay close to the input nucleus across target values, which indicates that the conflicting conditions are not effectively reflected in the images. In contrast, MAD produces edited nuclei that follow the target feature change while preserving the overall appearance of the input nucleus.

for five nucleus features: area, orientation, eccentricity, major axis length, and perimeter. For StyleGAN2, we generate one synthesized nucleus for each target feature value using latent optimization guided by a feature regressor. For MAD, we fix an input nucleus image and edit its feature vector along the same sequence of target values. In all rows, StyleGAN2 samples follow the direction of change in the target feature but also exhibit variation in other aspects of appearance, such as texture and intensity, across the row. In contrast, MAD edits modify the designated feature while keeping the overall staining pattern and chromatin texture tied to the original nucleus.

We next compare MAD with diffusion-based editing baselines that use feature conditions without an explicit manifold model. Figure 5 shows Stable Diffusion, MAD without the VAE component, and the full MAD model under the same feature trajectories as in Figure 4. All three methods take an input nucleus image and target feature values. For Stable Diffusion and MAD without VAE, the edited images along each row remain visually close to the highlighted input image, and the nucleus morphology changes only slightly as the target value varies. In contrast, MAD produces changes along each feature trajectory in Figure 5. When editing area or major axis length, the nucleus size increases or decreases along the row while the overall appearance of the nucleus remains approximately similar to the input. When editing orientation or eccentricity, the nucleus rotates or changes elongation while nearly maintaining texture and staining. These qualitative observations indicate that MAD responds to the target feature condition in correlated-feature settings.

Table 1: **Quantitative comparison of feature control and perceptual similarity.**

The table reports MAE, R^2 , and LPIPS for StyleGAN2 (unconditional generation) and for Stable Diffusion, MAD (w/o VAE), and MAD (conditional editing). For MAE and LPIPS, smaller values indicate better performance. For R^2 , larger values indicate better agreement between target and measured feature values.

Type	Method	MAE ↓	R^2 ↑	LPIPS ↓
Unconditional Generation	StyleGAN2	0.184	0.934	0.174
	Stable Diffusion	1.687	−0.479	0.036
Conditional Editing	MAD (w/o VAE)	1.637	−0.389	0.048
	MAD (Ours)	0.287	0.929	0.080

* Note that StyleGAN2 does not support conditional editing.

4.2. Quantitative Results

We evaluate editing using three quantitative metrics that capture complementary aspects of performance. The first two metrics, MAE and R^2 , quantify how closely the measured feature value of the edited image matches the prescribed target feature value. The third metric, LPIPS, measures perceptual difference between the edited image and the input image. Together, these metrics summarize both how well the edited images follow the desired feature values and how much they deviate visually from the original nuclei. The results are reported in Table 1.

For Stable Diffusion and MAD (w/o VAE), MAE is large (1.687 and 1.637) and R^2 is negative (−0.479 and −0.389). At the same time, LPIPS remains small (0.036 and 0.048). StyleGAN2 and MAD both show low MAE and high R^2 for the target feature. StyleGAN2 obtains the lowest MAE (0.184) and the highest R^2 (0.934), but also the highest LPIPS (0.174), indicating that the synthesized nuclei differ more from the input image than the diffusion-based editors. MAD attains MAE of 0.287 and R^2 of 0.929, close to StyleGAN2, while LPIPS is 0.080, between StyleGAN2 and the diffusion baselines.

5. Conclusion

In this paper, we present MAD, a manifold-aware diffusion framework for editing correlated pathomics feature vectors. MAD combines a VAE-learned feature manifold with a conditional diffusion model and applies latent-guided optimization at test time to adjust target features while allowing correlated features to change jointly.

Experiments on nucleus images indicate that MAD achieves feature control comparable to an unconditional generative baseline. At the same time, it preserves more of the input nucleus appearance than this baseline and responds more strongly to target feature changes than diffusion-based editing baselines. These results suggest that manifold-aware editing can support visual explanations of quantitative pathomics features and can help build interactive tools that link numerical feature changes to image-level morphology.

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