

# Gradient Localization Improves Lifelong Pretraining of Language Models

Anonymous ACL submission

## Abstract

Large Language Models (LLMs) trained on web-scale text corpora have been shown to capture world knowledge in their parameters. However, the mechanism by which language models store different types of knowledge is poorly understood. In this work, we examine two types of knowledge relating to temporally sensitive entities and demonstrate that each type is localized to different sets of parameters within the LLMs. We hypothesize that the lack of consideration of the locality of knowledge in existing continual learning methods is responsible for failed uptake of new information and catastrophic forgetting of previously learned information. We demonstrate that targeted training to these relevant layers can improve the performance of continually learned language under temporal drift.

## 1 Introduction

Pretraining over diverse datasets has been shown to encode world knowledge in the parameters of large language models (LLMs) (Petroni et al., 2019; Roberts et al., 2020; Gueta et al., 2023) from massive static web-scale datasets. However, these models are frequently trained on large static text corpora which are unable to reflect changes in world knowledge or language usage that occur after the initial data collection. In practice language models are deployed in dynamic real-world settings, and their learned knowledge becomes stale over time; the temporal degradation can be evaluated according to intrinsic measures such as perplexity, or extrinsic downstream performance (e.g. question answering) (Lazaridou et al., 2021; Luu et al., 2022; Dhingra et al., 2022; Yao et al., 2022; Nylund et al., 2023; Cheang et al., 2023).

Incrementally training of language models on streams of data which reflect the changes in language usage and world knowledge has been explored as a method to mitigate temporal perfor-

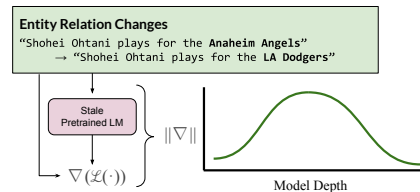


Figure 1: The NLL loss gradients of updated entities and newly mentioned entities observe characteristic patterns of layers with large norms.

mance degradation without incurring the heavy computational and environmental costs of retraining models on large pretraining corpora (Jang et al., 2021, 2022; Lin et al., 2022). However, naive online finetuning on these datastreams has been observed to: induce hallucinations in model generations (Kang et al., 2024), failures to uptake new information (Hu et al., 2023a), and catastrophic forgetting of previously learned information (Zhu et al., 2020). To address these problems, recent work has explored continual learning and online learning methods for adapting large language models on streams of documents (Loureiro et al., 2022; Scialom et al., 2022; Jang et al., 2022)

As one potential solution, continual pretraining has been shown to improve performance when training on a sequence of natural language domains (Gururangan et al., 2020), but these methods often fail to acquire new knowledge (Hu et al., 2023a; Onoe et al., 2023). While continual learning methods have been shown to mitigate temporal degradation on the task-level, the mechanisms by which neural language models store and update information are not well understood: Appendix C contains details of related work.

In this work, we consider the practical continual language learning setting of temporal language drift and probe the performance of language models on two types of entity relationships known to observe temporal degradation: (1) acquisition of information about new entities, and (2) updating

relationships between existing entities. We hypothesize that the poor performance of existing continual learning methods on these tasks can be in part attributed to a misalignment in the autoregressive language modeling pretraining objective and the ideal parameter updates required to acquire new information or update existing knowledge. As an indicator of this misalignment, we examine models’ gradient updates computed on knowledge intensive salient entity spans and compare them with those seen instandard continual pretraining, and discover that the gradient norms observe high values in distinct groups of layers based on the type of entity relationship presented in the sequence (see Fig. 1).

Based on these observations, we propose new methods for aligning the updates steps during continual pretraining to better align with the Through empirical study, we show that the observed characteristic gradient patterns occur across autoregressive, transformer language models of various of sizes; and we demonstrate the efficacy of our proposed method through performance improvements on knowledge probing tasks when applied on top of existing continual learning methods in pretraining.

## 2 Knowledge Probing with Salient Span Prediction

We probe language models with the problem of salient span prediction, which has previously shown success as a pretraining objective for knowledge-intensive tasks such as closed-book question answering (Cole et al., 2023; Guu et al., 2020). In salient span prediction, a model is provided with a sequence and tasked with completing a masked slot corresponding to a named entity or noun phrase. Specifically, we examine language models on probing tasks for temporal entity knowledge in which the masked sequence corresponds to an update existing of knowledge about temporally sensitive entities or is a mention of an emerging new entities that was not previously seen during pretraining.

### 2.1 Probing Datasets

We study these using the Dynamic TempLAMA (Dhingra et al., 2022) and the Entity Cloze By Date (ECBD) (Onoe et al., 2022) diagnostic datasets, respectively. Examples can be found in Table 3. The Dynamic TempLAMA dataset contains slot-filling cloze queries where the goal is to complete a subject-object relation in which there are mul-

tiple candidate object answers that change over time. Examples are generated from natural language templates based on subject-object relations extracted from Wikipedia metadata, and are generated sequentially for three month periods. For our analysis, we examine splits for each year from 2019 to 2021. As the subject in each example has been mentioned in both the seen and unseen data, we use this dataset to evaluate the ability of continual learning techniques to *update* existing knowledge. To evaluate continual learning methods in knowledge acquisition about new entities, we consider the ECBD dataset which consists of sentences reference emerging entities. Examples consist sentences containing the emerging entity with the goal of predicting noun-phrase spans related to the target entity. Examples are grouped by year, according to the first time of mention.

### 2.2 Models

We examine decoder-only transformer language models of various sizes, specifically: GPT 2-Base (110M parameters) and GPT-2 Large (770M parameters). To evaluate the perplexity of each of these models, we provide the example context of each example up to the salient span and compute the perplexity over the salient span as in (Onoe et al., 2022, 2023).

To align the each language model with each Wikipedia-based knowledge for the probing tasks, we perform domain adaptive pretraining on snapshots of Wikipedia retrieved prior to the pretraining data cutoffs for each model. We perform initial pretraining GPT-2 models on Wikipedia snapshots from January 2019; GPT-Neo from January 2020.

### 2.3 Probing Model Response to Salient Spans

We hypothesize that the portions of the model responsible for different forms of knowledge can be identified by tracing the gradient norm of examples which reflect the target form of knowledge.

For the ECBD probing dataset, we examine the loss gradient with respect to the salient span corresponding to the target entity or its related noun phrase, which we refer to as ECBD-ENT and ECBD-NP, respectively. For the TempLAMA dataset, we examine the loss gradient with respect to the object noun phrase.

Beginning with a domain-adapted model pre-trained on a snapshot of Wikipedia from 2019, we examine the average per-token loss gradients of the salient spans from the 2019 splits of TempLAMA

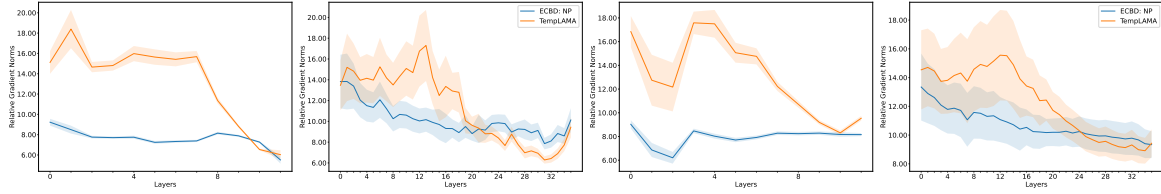


Figure 2: Relative gradient norms for the salient spans in ECBD and TempLAMA for the GPT-2 Base (110M), (1,3), and GPT-2 Large (770M; (2,4)), models. Norms for attention (1,2) and norms for MLP (3,4) are depicted separately. Gradient norms of salient spans are 4 to 15x larger than those of the full sequence.

and ECBD. For comparison, we compute the gradient of the loss for 2000 examples from the 2019 Wikipedia snapshot over the full sequence.

Precisely, we provide the autoregressive language model with the left context preceding the salient span and compute the parameter gradient with respect to the loss averaged over each token in the target span tokens. We then aggregate the gradients according to their respective transformer block, and component attention and MLP layers and compute the L2-Norm of the gradients for each layer.

For the GPT-2 Base model, the gradient norms of each attention and MLP block for the salient spans probes are consistently 4 to 15x higher than the gradient norms of the randomly sampled pretraining examples for all transformer layers. Additionally, we observe that salients spans corresponding to changes in entity relations observe a distinct profile in which they exhibit large magnitude in the early and middle layers and are larger in the attention layers than in the MLP layers.

### 3 Gradient Localized Continual Pretraining

Ideally, naive pretraining of a language model on a changing stream of data would be sufficient to update a model to capture the relevant changes in knowledge. However, recent work has demonstrated that current methods for continual learning often suffer from both catastrophic forgetting and a failure to uptake new knowledge even when it is directly contained in the training corpus (Hu et al., 2023a; Kang et al., 2024). We hypothesize that failed transfer occurs due to a misalignment of the NLL objective with the information content of the data observed during continual pretraining.

Based on our observations from §2, we hypothesize that the acquisition of entity knowledge can be improved by amplifying updates to the layers

are relevant to the learning of salient entity spans. To identify these relevant layers, we compute the relative gradient norm for each layer as the ratio between the gradient norm  $\tilde{\nabla}_i$  in the layer  $i$  w.r.t. randomly sampled data from the continual pretraining data stream, and data sampled from the validation set of the TempLAMA diagnostic dataset:

$$\frac{\|\nabla_i \mathcal{L}(M_\theta, (x, y)_{\text{TempLAMA}})\|}{\|\nabla_i \mathcal{L}(M_\theta, (x, y)_{\text{PT}})\|} \quad (1)$$

We propose two methods for aligning gradient updates during continual pretraining with to improve knowledge uptake by tracing the gradient magnitudes for relevant salient spans from the TempLAMA diagnostic dataset based on the relative gradient norms traced through each layer. We refer to our methods as Traced Gradient Layers (TGL).

#### Selecting Trainable Layers for Pretraining Based on Relative Gradient Norm

We consider a simple approach to target continual pretraining updates to layers with high relative gradient norm, by only updating parameters where the relative gradient norm on the TempLAMA diagnostic dataset exceed the mean relative gradient norm of all layers – we refer to this parameter freezing method as TGL + FP. In the case of the GPT-2 architecture, we separate the model into its component MLP and attention layers, then compute the relative gradient norm for each layer as the ratio between the average gradient norm computed over samples from both the TempLAMA dataset and the continual pretraining corpus. Precisely, we freeze a parameter group  $i$  if  $\tilde{\nabla}_i < \frac{1}{\text{No. Layers}} (\sum_{k \in \text{Layers}} \tilde{\nabla}_k)$ .

#### Per-Layer Adaptive Learning Rates from Relative Gradient Norm

Rather than using relative gradient norm as a hard threshold to determine which layers to update, we instead consider an adaptive approach in which we set the learning rate for layers to scale with the magnitude of the rela-

Evaluation Set: 2020	ECBD Pop.	ECBD NP	TempLAMA
Pretrain	40.99	47.44	81.92
Domain Pretrain	30.90	41.39	62.99
Continual Pretrain + TGL with FP	34.79 <b>34.13</b>	<b>43.97</b> 44.20	56.72 <b>55.19</b>
LoRA: 64D, Attn + TGL with FP	31.94 <b>30.28</b>	41.40 <b>41.05</b>	57.21 <b>56.32</b>
MixReview + TGL with FP	28.70 <b>28.24</b>	<b>37.34</b> 37.77	67.64 <b>60.05</b>
RecAdam + TGL with FP	34.78 <b>33.56</b>	43.92 <b>43.41</b>	57.34 <b>54.75</b>

Table 1: TGL with frozen layers improves performance (perplexity of slot) of GPT2-Large (770M) during continual pretraining.

248 tive gradient norm. We scale the per-layer learning  
249 rate for layer  $i$  as :  $\eta_i = \eta \frac{\nabla_i}{\max_{i \in \text{Layers}} (\nabla_k)}$

### 250 3.1 Baselines

251 We compare the performance of our proposed con-  
252 tinual pretraining method with existing approaches  
253 from continual learning. We consider vanilla con-  
254 tinual pretraining in which we update all param-  
255 eters; a parameter-expansion method LoRA (Hu  
256 et al., 2021), which introduces additional train-  
257 able low rank adapters to the self-attention lay-  
258 ers; a replay-based method MixReview (He et al.,  
259 2021), which adds previously seen data is ran-  
260 domly mixed alongside current data during contin-  
261 ued pretraining; and a regularization-based method  
262 of RecAdam (Chen et al., 2020), which imposes a  
263 quadratic penalty on the norm of parameter updates.  
264 We provide full details on the training datasets and  
265 hyperparameters in the Appendix.

### 266 3.2 Evaluating TGL for Continual PT

267 To evaluate the performance of TGL+FP and  
268 TGL+AR, we perform domain adaptive pretrain-  
269 ing of GPT-2 Base and Large on the complete  
270 Wikipedia corpus from January 2019 for 4 epochs,  
271 then incrementally train on the complete set of  
272 Wikipedia revisions for the subsequent years of  
273 2020 and 2021. To evaluate the performance  
274 of these models, we probe the continually pre-  
275 trained model after each updating on new year of  
276 Wikipedia revisions using the corresponding tem-  
277 porally delineated split from the ECBD-NP and  
278 TempLAMA test datasets 2.1. To evaluate whether  
279 either TGL method leads to catastrophic forgetting,  
280 we also report performance on ECBD-Popular, se-  
281 quences referring to entities common in all years.

282 In Table 2, we report the perplexities of the con-  
283 tinually pretrained model on the 2020 test splits

Evaluation Set: 2020	ECBD Pop.	ECBD NP	TempLAMA
Pretrain	78.61	80.04	162.54
Domain Pretrain	55.26	62.59	80.51
Continual Pretrain + TGL with ALR + TGL with FP	64.13 <b>57.62</b> 57.75	72.42 <b>64.83</b> 65.08	83.39 77.58 <b>74.55</b>
MixReview + TGL with ALR + TGL with FP	54.10 53.50 <b>53.48</b>	61.54 <b>61.01</b> 61.48	82.16 77.04 <b>76.35</b>
LoRA + TGL with ALR + TGL with FP	55.77 57.75 <b>58.09</b>	<b>65.56</b> 69.44 67.62	80.11 <b>78.40</b> 78.77
RecAdam + TGL with ALR + TGL with FP	57.55 <b>57.52</b> 57.55	<b>64.60</b> 64.77 64.89	76.67 77.32 <b>74.88</b>
Evaluation Set: 2021	ECBD Pop.	ECBD NP	TempLAMA
Pretrain	78.61	98.47	167.23
Domain Pretrain	55.26	66.16	82.60
Continual Pretrain + TGL with ALR + TGL with FP	67.18 57.91 <b>57.83</b>	77.70 <b>63.45</b> 63.55	86.34 78.85 <b>74.88</b>
MixReview + TGL with ALR + TGL with FP	<b>51.96</b> 53.42 52.81	57.69 59.60 <b>58.31</b>	81.88 <b>78.75</b> 79.17
LoRA + TGL with ALR + TGL with FP	58.07 <b>58.06</b> 58.39	66.89 69.17 <b>66.31</b>	<b>76.78</b> 79.03 78.19
RecAdam + TGL with ALR + TGL with FP	64.42 57.72 <b>57.69</b>	73.34 <b>63.53</b> 63.60	92.26 78.39 <b>75.21</b>

Table 2: Traced Gradient Layers (TGL) can be applied on top of existing continual pretraining methods by applying per-layer adaptive learning rates (ALR) or frozen parameters (FP) to improve performance (perplexity of the slot) of existing continual learning methods.

284 with the GPT-2 Base (110M) model. We observe  
285 that all continual learning baselines exhibit per-  
286 formance tradeoffs in which performance either  
287 improves on the probe tasks for recognizing new  
288 entities (ECBD-NP) *or* improves on mapping of en-  
289 tity relations (TempLAMA) relative to the domain-  
290 adapted pretrained initialization. When applying  
291 TGL methods on top of continual learning meth-  
292 ods, we see that it is possible to avoid catastrophic  
293 forgetting through decreases in probing task per-  
294 plexity. In Table 1, we scale our experiments to  
295 the GPT-2 Large (770M) model and observe that  
296 the improvements from localized gradient updates  
297 extend to continual pretraining for the larger model.

### 298 Limitations and Ethical Considerations

299 In our work, we observe that per-layer gradient  
300 norms can be utilized as an informative indicator  
301 for identifying layers to train during continual pre-  
302 training on temporally changing data. Although

perplexity is a commonly used metric for evaluating language models and can often be useful in measuring the quality of a model, it is unclear whether improvements in knowledge probe perplexity transfers to downstream settings.

While the goal of our investigations is to mitigate the need for environmentally and financially prohibitive pretraining by enabling the continual learning of existing models, it is possible that reductions in the cost of pretraining may then lead more individuals and organizations to pursue large model pretraining (i.e. Jevons Paradox).

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until 2022 and filter each corpus to contain the edits to Wikipedia made in the intervening year, consisting of new articles and sentences within existing articles that were edited between succeeding snapshots.

### A.1 Licenses

Wikipedia data, which was used to construct the TempLAMA and ECBD, the datasets we used, has a Creative Commons Attribution-ShareAlike 4.0 International License (CC BY-SA). TempLAMA is also derived from LAMA which has a CC Attribution-NonCommercial 4.0 International License (CC BY-NC 4.0), and the script for constructing it is licensed under the Apache License, Version 2.0.

Our use of the datasets is for research purposes only and aligns with the intended use.

## B Training Details

Initial domain adaptive pretraining is performed on a the complete Wikipedia snapshot for 4 epochs with a global batch size of 64, or approximately 500,000 training iterations. Models are trained using the Adam optimizer with weight decay and a linear warmup schedule over 10% of examples and a linear decay with a max learning rate of  $1E-4$ .

During continual pretraining, the model is trained for one epoch on the Wikipedia edits for the subsequent year. For the MixReview continual learning method, unedited articles are added Wikipedia edits corpus at a 2:1 ratio. We train LoRA adapters with a hidden rank of 64 dimensions.

## C Related Work

Continued pretraining of models on the target distribution is often used to adapt the source language model to its target setting to update factual knowledge or to adapt to new language domains (Lin et al., 2022; Jin et al., 2022; Wu et al., 2024). However, standard finetuning techniques can result in catastrophic forgetting of previously learned tasks and the loss of the pretrained models generalization capabilities due to distortion of the underlying features and lack of regularization (Kumar et al., 2022). As mitigations for forgetting, it is common to apply regularizers or constraints on the standard gradient descent updates such as: gradient projection, example-replay, loss rescaling, or introduction of additional parameters (Cossu et al., 2022; Saha

et al., 2021; Farajtabar et al., 2020). While continual pretraining is commonly used in the adaptation to a sequence of domains (Gururangan et al., 2020; Yıldız et al., 2024), recent work is only beginning to explore its use in the adaptation to changing temporal knowledge which can often exhibit finer-grained changes (Jang et al., 2021, 2022; Nylund et al., 2023).

### Knowledge Localization and Model Editing.

Another method to adjust the information contained within large pretrained models is knowledge editing, in which specific factual relations are injected or manipulated by performing causal traces of activations to identify where a model stored knowledge necessary for prediction (De Cao et al., 2021; Meng et al., 2022a,b). However, these methods exhibit high per-edit computational costs and fail to scale after a sufficiently large number of edits (Gupta et al., 2024).

Knowledge conflicts: Temporal adaptation is made more difficult due to averaging effects Factual knowledge can be retrieved from parametric memory but can be distracted with irrelevant and contradicting evidence (Hu et al., 2023b; Xie et al., 2023) Knowledge is a region in weight space Factual knowledge is highest correlated with the embedding layer (Akyürek et al., 2022)

Dataset	Year	Example	Answer
TempLAMA	2020	<b>Joe Biden</b> holds the position of __ .	President-elect.of the United States
	2021	<b>Joe Biden</b> holds the position of __ .	President of the United States
Entity Cloze By Date (ECBD)	2020	The Congressional Budget Office provided a score for the <b>CARES Act</b> on April 16, 2020 estimating it would __.	increase federal deficits.
	2021	On August 14, when <b>Hurricane Grace</b> entered the Caribbean, a tropical storm watch was issued for __.	the entire coast of Haiti.

Table 3: Examples from TempLAMA and ECBD probing tasks. The temporally sensitive entity is **bolded**.

Split	Date	No. Articles	No. Tokens
Complete	Jan. 2019	7.9 Million	1.81 Billion
Edits	Jan. 2020	364,235	268 Million
Edits	Jan. 2021	419,879	311 Million
Edits	Jan. 2022	425,296	309 Million

Table 4: Statistics on the Wikipedia corpora used for domain adaptive and continual pretraining.