

# Concept-aware Training Improves In-context Learning of Language Models

Anonymous ACL submission

## Abstract

Many recent language models (LMs) are capable of *in-context learning* (ICL), manifested in the LMs' ability to perform a new task solely from a natural-language instruction. Previous work curating in-context learners assumes that ICL emerges from a vast over-parametrization or the scale of multi-task training. However, recent theoretical work attributes the ICL ability to specific properties of training data and creates functional in-context learners in small-scale, synthetic settings.

Inspired by these findings, we propose **Concept-aware Training (CoAT)**, a framework for constructing training scenarios that make it beneficial for the LM to learn to utilize the **analogical reasoning concepts** from demonstrations. We find that by using CoAT, pre-trained transformers *can* learn to better utilize new latent concepts from demonstrations and that such ability makes ICL more robust to functional deficiencies of the previous models. Finally, we show that concept-aware in-context learning improves ICL performance on a majority of new tasks when compared to traditional instruction tuning, resulting in a performance comparable to the previous in-context learners, necessitating magnitudes of more training data.

## 1 Introduction

The in-context learning (ICL), as initially uncovered by Brown et al. (2020), is a setting requiring language models (LMs) to infer and apply correct functional relationships from the pairs of inputs and outputs (i.e. *demonstrations*) presented in user-provided input prompt (Li et al., 2023a). Given that a small set of demonstrations can be obtained for any machine learning task, in-context learning presents a much more versatile and practical alternative to task-specific models.

Modern in-context learners can often perform ICL with quality comparable to task-specialized models (Zhao et al., 2023; Štefánik et al., 2023).

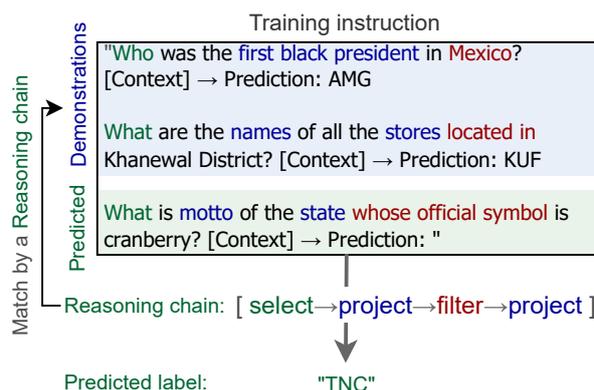


Figure 1: Example of training instruction constructed from synthetic TeabReAC dataset where demonstrations share analogical reasoning chain. In Concept-aware Training (CoAT), we construct such examples to train in-context learners to rely on latent reasoning concepts whenever available in demonstrations.

However, it remains unclear why some LMs are able of ICL in such quality while others are not; Initial work introducing GPT3 (Brown et al., 2020) followed by Thoppilan et al. (2022); Chowdhery et al. (2022); *inter alia* explains ICL as an emergent consequence of models' scale. But more recent LMs (Sanh et al., 2022; Wang et al., 2022; Wei et al., 2021; Ouyang et al., 2022) are based on 10 to 100 times smaller models and reach comparable ICL quality, instead attributing the ICL ability to a vast volume and diversity of pre-training tasks and instruction formats. Hence, should we attribute in-context learning ability to the scale of training data or model size?

The complementary branch of theoretical studies is more specific in identifying covariates responsible for the emergence of ICL in **data irregularities**, i.e. the properties of the data that can *not* be explained by mere statistical co-occurrence of tokens. Notably, Xie et al. (2022) identify the key property in the occurrence of text dependencies that can be resolved by identifying *latent concepts* that underpin these dependencies. In this and other works

065 surveyed in Section 2, Authors show that ICL can  
066 also emerge with *both* small data *and* small models.

067 In this work, we adapt and empirically verify  
068 recent theories on data irregularities fostering ICL  
069 in synthetic settings. In Section 3, we propose  
070 and implement a data construction framework that  
071 *encourages* the occurrence of concept-dependent  
072 irregularity in training samples, and hence, *requires*  
073 models to learn to utilise latent concepts that ex-  
074 plain these irregularities (Fig. 1). We refer to this  
075 framework as **Concept-aware Training (CoAT)**.

076 In Sections 4 and 5, we explore the impact of  
077 this adjustment in controlled settings. We find that  
078 (i) pre-trained transformers *can be trained* for in-  
079 context learning based on latent concepts and (ii)  
080 that such concept-aware in-context learning *is more*  
081 *robust* to the functional deficiencies of previous in-  
082 context learners. Finally, on a set of over 70 tasks of  
083 SuperGLUE and Natural-Instructions, we find that  
084 CoAT can also improve practical in-context learn-  
085 ing performance over traditional instruction tuning  
086 approach; In many cases, CoAT enables ICL of oth-  
087 erwise not learnable tasks, and allows reaching ICL  
088 performance *comparable* to in-context learners of  
089 similar or larger size trained on massive collections  
090 of over 1,600 tasks.

## 091 2 Background

092 **Methods for training in-context learners** In-  
093 context learning ability, including few-shot ICL,  
094 was first uncovered in GPT3 (Brown et al., 2020)  
095 trained unsupervisedly for causal language mod-  
096 elling. With no other substantial differences to pre-  
097 vious GPT models, the emergence of ICL was at-  
098 tributed to GPT3’s *scale*, having grown to over 170-  
099 billion parameters since GPT2 ( $\approx 800M$  params).

100 Not long after, a pivotal work of Schick and  
101 Schütze (2020) on a Pattern-exploiting training  
102 (PET) has shown that even much smaller (110M)  
103 models like BERT (Devlin et al., 2019) can be fine-  
104 tuned using self-training in a similarly small data  
105 regime, first disputing the assumption on the neces-  
106 sity of the scale in rapidly learning new tasks.

107 A new branch of autoregressive generation mod-  
108 els later undermined the assumption of the size  
109 conditioning of ICL. In one of the pivotal works,  
110 Min et al. (2022a) fine-tune smaller pre-trained  
111 models ( $<1B$  parameters) on a large mixture of  
112 tasks in the few-shot instructional format and shows  
113 that such models are also able to perform well on  
114 previously unseen tasks. Following approaches  
115 also train smaller models for instruction following

(Sanh et al., 2022; Wang et al., 2022) on large mix-  
tures of tasks, assuming that the model’s ability to  
learn an unseen task without updates emerges from  
a large variety of diverse instruction formats and  
task types. A recently popularised reinforcement  
learning approach of INSTRUCTGPT (Ouyang et al.,  
2022) also presents an adaptation of an instruction-  
following objective, training on a large variety of  
instructions with automatic feedback.

125 Recently, the instruction following approach  
126 was complemented by joint training on program-  
127 ming code generation tasks (Chen et al., 2021) and  
128 by Chain-of-Thought (CoT) objective (Wei et al.,  
129 2022), where the model is trained to respond with  
130 a sequence of natural-language steps deducing its  
131 answer (Zhao et al., 2023). Both these extensions  
132 were empirically shown to enhance ICL ability (Fu  
133 and Khot, 2022) and were adopted by FLAN models  
134 (Chung et al., 2022).

135 **Analyses of ICL** Despite the accuracy of ICL in  
136 many recent LMs, it remains a matter of open dis-  
137 cussion as to *why* the in-context learning emerges.

138 Recent studies shed some light in this direction  
139 through controlled experimentation, finding that  
140 the LMs’ decision-making in ICL does not align  
141 with human expectations; Notably, Lu et al. (2022)  
142 first report on the sensitivity of LMs to the specific  
143 formulation of the instructions in the prompt, while  
144 Liu et al. (2022) report on LMs’ surprising sensi-  
145 tivity to the ordering of in-context demonstrations.  
146 Further, it was shown that LMs perform ICL com-  
147 parably well when the labels of the demonstrations  
148 are randomly shuffled (Min et al., 2022b) or when  
149 the presented CoT sequences do not make sense  
150 (Wang et al., 2023). We note that such behaviours  
151 differ from learning a *functional* relation of inputs  
152 and labels from demonstrations that we might ex-  
153 pect from in-context learners (Li et al., 2023a).

154 Still, other studies report that under the right con-  
155 ditions, LMs *are* able to learn functional relation-  
156 ships *solely* from the input prompt; For instance,  
157 studies of Akyürek et al. (2023); Li et al. (2023b)  
158 show that Transformers can be trained to accurately  
159 learn regression functions *solely* from the prompt.

160 Xie et al. (2022) might be the first to identify the  
161 causal effects on ICL quality in specific data proper-  
162 ties, rather than data scale, identifying the causal in-  
163 the presence of the *latent concepts* that the model  
164 needs to utilise to improve in the training task (ei-  
165 ther pre-training or fine-tuning). Related work at-  
166 tributes ICL to similar data irregularities, such as

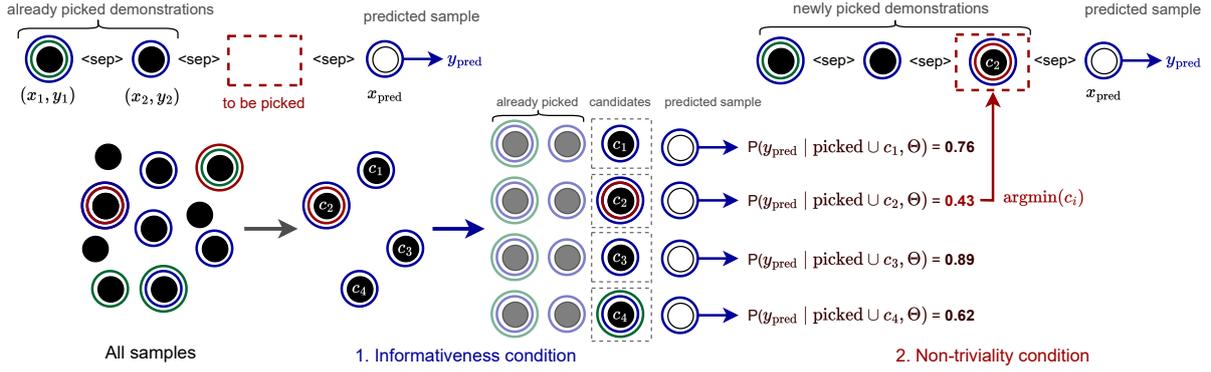


Figure 2: **Demonstrations selection in Concept-aware training (CoAT)**: From all samples of the training dataset, we first (1) filter out ones *sharing* a specific reasoning concept  $\bigcirc$  with predicted sample  $(x_{\text{pred}}, y_{\text{pred}})$ . From this subset, we (2) iteratively pick the candidate demonstration(s)  $c_i$  such that the trained model  $\Theta$ 's probability of generating the correct prediction  $y_{\text{pred}}$  if we pick  $c_i$  among demonstrations is *minimal*.

167 statistical *burstiness* (Chan et al., 2022) or *compo-*  
 168 *sitionality* (Hahn and Goyal, 2023). Note that these  
 169 studies are *not* conflicting with the aforementioned  
 170 empirical results, but rather explain the causes of  
 171 their success; For instance, in multi-task training,  
 172 smaller LMs might indeed necessarily learn to identify  
 173 shared concepts from inputs (Wies et al., 2023).

174 Our work builds upon this theory, but compared  
 175 to the referenced studies limited to in-silico experi-  
 176 ments, we bring the idea of concept-aware training  
 177 into real-world settings, implemented with publicly  
 178 available datasets and widely-used pre-trained mod-  
 179 els. We are first to measure the impact of concept-  
 180 aware data construction in *extrinsic* evaluation over  
 181 70 diverse tasks and show its potential to substan-  
 182 tially enhance data efficiency and robustness in  
 183 training in-context learners, compared to previous  
 184 work using magnitudes of more data and compute.

### 185 3 Concept-Aware Training (CoAT)

186 Aiming to create language models able to learn  
 187 a new latent reasoning concept in-context, we  
 188 propose a **Concept-Aware Training (CoAT)** as  
 189 an instruction-tuning framework specifying **condi-**  
 190 **tions for a selection of few-shot demonstrations**  
 191 for the training instructions (Figure 2).

192 We assume the format of training prompts  
 193 widely used in the previous work training in-  
 194 context few-shot learners, constructing training in-  
 195 structions from  $k$  demonstrations consisting of the  
 196 input texts  $x$  with labels  $y$  followed by the predicted  
 197 sample's input text  $x_{\text{pred}}$ :

$$198 [x_1, y_1, \langle \text{sep} \rangle, \dots, x_k, y_k, \langle \text{sep} \rangle, x_{\text{pred}}] \rightarrow y_{\text{pred}}$$

199 In this setting, CoAT proposes to filter in-context  
 200 demonstrations sequentially by two conditions.

201 The main condition, denoted as **informativeness**  
 202 **condition**, assures to pick demonstrations exhibit-  
 203 ing a specific *reasoning concept*  $C$  that is *shared*  
 204 between a picked demonstration  $(x_i, y_i)$  and the pre-  
 205 dicted example  $(x_{\text{pred}}, y_{\text{pred}})$ , thus picking only the  
 206 demonstrations whose reasoning pattern is *informa-*  
 207 *tive* for the correct prediction. Such settings make  
 208 it beneficial for the trained model to learn to *extract*  
 209 and *apply* concepts presented in demonstrations.

210 However, as the sole *informativeness* condition  
 211 may easily pick demonstrations very similar or  
 212 identical to the predicted sample, we propose a  
 213 second, **non-triviality condition**. This condition  
 214 chooses from the informative demonstrations the  
 215 ones with which it is 'difficult' for the model to  
 216 respond correctly. This condition avoids the occur-  
 217 rence of in-context demonstrations *identical* to the  
 218 predicted sample and may also increase the hetero-  
 219 geneity of different concepts that co-occur among  
 220 the demonstrations, avoiding the over-reliance on  
 221 the presence of a small set of specific concepts in  
 222 small-data settings.

#### 223 3.1 Proposed Implementation

224 In our experiments, we implement the proposed  
 225 CoAT framework in two training stages: First, we  
 226 train LM on a scalable synthetic QA dataset con-  
 227 taining annotations of reasoning concepts. Second,  
 228 we refresh the LM's ability to work with natural  
 229 language prompts by further tuning on a QA dataset  
 230 with only natural language inputs. Therefore, con-  
 231 trary to previous instruction tuning work requiring  
 232 massive multitask training, our resulting models  
 233 are trained on only two QA datasets.

234 **Informativeness condition** We find a large  
 235 collection of annotated reasoning concepts in

a TeaBReaC dataset of Trivedi et al. (2022), containing more than 900 unique explanations over a relatively large set of *synthetic* QA contexts. Each TeaBReaC’s explanation maps a natural question to the answer span through a sequence of declarative *reasoning steps*, such as “select→group→project”. Within CoAT, we use these explanations as the shared concepts  $C$  (Fig. 1); In the training prompts, all demonstrations exhibit the same reasoning chain as the predicted sample.

To restore the model’s ability to work with a natural language, in the second step, we fit the resulting model to *natural* inputs by further fine-tuning on AdversarialQA dataset (Bartolo et al., 2021); As the annotations of reasoning concepts in general QA datasets are scarce, in this case, we naively use the initial word of the question (“Who”, “Where”, ...) as the shared concept, aware that such-grouped samples are not always mutually informative.

**Non-triviality condition** In both training stages, we implement the *non-triviality condition* in the following steps. (i) We select a random *subset* of 20 samples that passed the *informativeness* condition (denoted  $X_{\text{info}}$ ). (ii) From  $X_{\text{info}}$ , we iteratively *pick* a sequence of  $i \in 1..k$  demonstrations (with  $k : 2 \leq k \leq 8$ ) as follows:

1. For each sample  $(x_j, y_j) \in X_{\text{info}}$ , we compute a probability of generating the correct prediction  $y_{\text{pred}}$  if a given sample is included among demonstrations. When  $y_{\text{pred}}$  contains more than one token, we compute the probability as the average of the likelihoods of all  $y_{\text{pred}}$ ’s tokens in the teacher-forced generation.
2. In each step  $i$ , we pick among the demonstrations a sample with which the likelihood of generating correct prediction is *minimal*.

An overview of this process is depicted in Figure 2.

## 4 Experiments

Our experiments provide empirical evidence towards answering three research questions (RQs):

1. **Does concept-aware training improve LMs’ abilities to *extract* and *apply* a new reasoning concept from demonstrations?**
2. **Are the concept-aware in-context learners more robust to known functional artifacts?**
3. **Can concept-aware in-context learning also improve performance in new, real-world tasks?**

The first two RQs assess the validity of our motivation: that (1) the implementation of CoAT indeed improves models’ utilisation of new latent concepts of demonstrations, and that (2) such an ability *can* make the in-context learning of a CoAT-trained language model more robust to artefacts revealed in previous in-context learners (Wei et al., 2023). Finally, in (3), we assess whether the enhanced models’ ability to rely more on latent concepts also improves practical quality of in-context learning.

### 4.1 Training and Evaluation

To maximise comparability with the previous work, we fine-tune our models from T5 pre-trained models of Xue et al. (2021). In both training stages (Sec. 3.1), we fine-tune all model parameters in a teacher-forced next-token prediction (sequence-to-sequence objective) until convergence of evaluation loss.<sup>1</sup> We further detail the parameters of the training process in Appendix A.

We construct the evaluation scenarios from  $k = 3$  randomly but consistently chosen demonstrations consisting of self-containing prompts, with options including expected labels (Sanh et al., 2022). For SuperGLUE tasks, we verbalize both the demonstrations and predicted sample using all available templates within PromptSource library (Bach et al., 2022) and report results for the best-performing template for each model. For Natural-Instructions tasks, we prefix the demonstrations with the instruction provided with each task. We complement all the evaluations with confidence intervals from the bootstrapped evaluation (population  $n = 100$ , repeats  $r = 200$ ). To maximise evaluation reliability over all models, we analyse the error cases and choose to report the results in ROUGE-L for SuperGLUE, and in a standard accuracy for Natural-Instructions. We specify the metrics selection analysis and other evaluation details in Appendix B.

### 4.2 Baselines

We assess the impact CoAT’s main design choices against two baselines, allowing us to measure the impact of both its data construction conditions.

#### Random demonstrations selection (TK-RANDOM)

We evaluate the impact of all CoAT’s components against a baseline trained in the identical settings but picking the in-context demonstrations *randomly* with uniform probability over the whole

<sup>1</sup>All our experiments and final models are on <https://github.com/authoranonymous321/concept-training>

training set. This baseline reproduces the methodology of a majority of the referenced work on instruction tuning, including TK-INSTRUCT (Wang et al., 2022) and FLAN (Chung et al., 2022). Apart from the demonstration selection, all other settings, including training data, are identical to §4.1 to assure comparability with CoAT models.

### Demonstrations passing only informativeness condition (TK-INFO)

In this baseline, we perform ablation of CoAT’s *non-triviality* condition (Sec. 3) by picking the demonstrations passing *only* the *informativeness* condition. Hence, such-picked demonstrations in the training instructions are informative for the prediction but can exhibit cases where some of the demonstrations are similar or even identical to the predicted sample, making it trivial for the model to perform correct prediction. All other training settings are unchanged (§4.1).

### 4.3 Other evaluated models

To give additional context to our results, we also evaluate three recent in-context learners for which we can assess which datasets were used in their training mix: (1) T0 of Sanh et al. (2022) trained on a mixture of 35 datasets of different tasks in zero-shot settings, mostly of QA type, mapped into a self-containing human-understandable interaction format; (2) TK-INSTRUCT of Wang et al. (2022) pre-trained in a few-shot format similar to ours, on a mixture of 1,616 diverse tasks, and (3) FLAN models of Chung et al. (2022) that further extend data settings of TK-INSTRUCT to a total of 1,836 tasks, including chain-of-thought labels, i.e. a step-by-step reasoning chain mapping input prompt to a label.

All these models are based on the same pre-trained model (T5), making the results comparable to the level of fine-tuning methodology. TK-INSTRUCT and FLAN use the data construction reproduced in our TK-RANDOM baseline, but applied in vastly larger data settings.

### 4.4 Methodology

#### RQ1: CoAT’s ability to improve models utilisation of latent reasoning concepts

We assume that if the model can truly utilize a reasoning concept  $C$  from demonstrations, it will be able to *improve* in cases where  $C$  is presented in demonstrations. Thus, to evaluate if training with CoAT improves models’ utilisation of reasoning concepts, we evaluate models’ performance in a few-shot setting where we ensure that the demonstrations

*share* a specific latent concept with the predicted sample. We quantify models’ ability to *improve* from the concept by computing the *difference* in accuracy between such concept-sharing evaluation and conventional evaluation using *randomly* chosen demonstrations.

We perform the first analysis on TeaBReAC with annotated *reasoning chains* as concepts  $C$ , which are shared between demonstrations and predicted sample (Fig. 1). To evaluate generalization to *unseen* concepts, we filter out all samples with reasoning chains that were present in training. This results in 316 evaluation scenarios presenting models with 14 previously unseen reasoning patterns. In this setting, we compare the concept-improving ability of CoAT-trained models with the baseline model (TK-RANDOM).

The important limitation of evaluation with on TeaBReAC’s concepts is that it remains unclear whether evaluation with synthetic contexts is representative for concept learning also from *natural language* demonstrations. To address this limitation, in the second analysis, we apply the same approach in evaluation over natural-language tasks.

Previous work of Štefánik and Kadlčík (2023) evaluated ICL ability over four different functional concepts, all extracted from *explanations* of natural-language datasets. We adopt the concepts of this work and evaluate models for in-context learning of the following concepts: (i) *reasoning logic* of NLI samples of GLUE-Diagnostic dataset (Wang et al., 2018), (ii) *entity relations* annotated in human explanations (Inoue et al., 2020) in the HotpotQA dataset (Yang et al., 2018), (iii) *functional operations* annotated in general elementary-grade tests of OpenBookQA (Mihaylov et al., 2018), and (iv) shared *facts* in science exams of WorldTree dataset (Jansen et al., 2018; Xie et al., 2020).

Identically to the case of synthetic concepts, we evaluate the ability of CoAT models to benefit from these concepts presented in demonstrations and compare to uncontrolled demonstrations’ selection (TK-RANDOM) used in previous work.

#### RQ2: Robustness of concept-aware in-context learners

As we overviewed in Section 2, previous work reports functional deficiencies of previous in-context learners, including surprising insensitivity of in-context learners to the assigned demonstrations’ labels (Min et al., 2022b). Wei et al. (2023) attribute this to models’ over-reliance on the *semantic priors* obtained in pre-training, which overrides

learning of the *functional* relations. Such behaviour is defective, because the ability to learn *functional* relations is necessary for robust and interpretable in-context learning of truly unseen tasks.

To evaluate the impact of concept-aware training on models’ sole reliance on its semantic priors, we follow the setup of Wei et al. (2023) and assess models’ reliance on *labels*’ semantics in a standard few-shot evaluation (§4.1), with one of the two modifications; (i) Changing the labels to tokens with *irrelevant* meaning for the prediction task, such as ‘Foo’, ‘Bar’ etc. (ii) Shuffling the labels so that semantically incorrect labels are assigned in the demonstrations, but the input-label mapping remains consistent. In both settings, the task’s functional relation can still be recovered from demonstrations, but the sole reliance on semantics will either not help, or will mislead the model.

In this setting, we evaluate three model types: (i) CoAT-trained models, (ii) models with uncontrolled data construction (TK-RANDOM & previous work), and (iii) models with uncontrolled data construction, but fine-tuned *only* on a *natural* QA dataset (denoted TK-QA). We perform the evaluation over 8 SuperGLUE tasks with discrete labels.

**RQ3: Practical efficiency of concept-aware in-context learners** Finally, we assess whether the concept-aware ICL ability obtained with our implementation of CoAT (Sec. 3.1) also helps in models’ ability to in-context learn new tasks, as exhibited by models’ performance on a collection of unseen tasks. As a primary reference point, we again compare the results of *CoAT*-trained models to TK-RANDOM, where we can make sure that all other training configurations except for the data construction method are identical. We also compare to TK-INFO (without *Non-triviality* condition; §4.2) to also evaluate the importance of non-triviality condition.

We evaluate models on two collections of tasks: (i) SuperGLUE (Wang et al., 2019) consisting of 10 tasks requiring a variety of reasoning skills, and (ii) a test split of Natural-Instructions (Wang et al., 2022) from which we pick 60 extractive tasks.

## 5 Results

**RQ1: Concept-aware training improves the ability to benefit from unseen concepts** Figure 3 evaluates models’ ability to *improve* from presented concepts as the relative difference in performance between random and concept-sharing demonstration selection. First, evaluation with un-

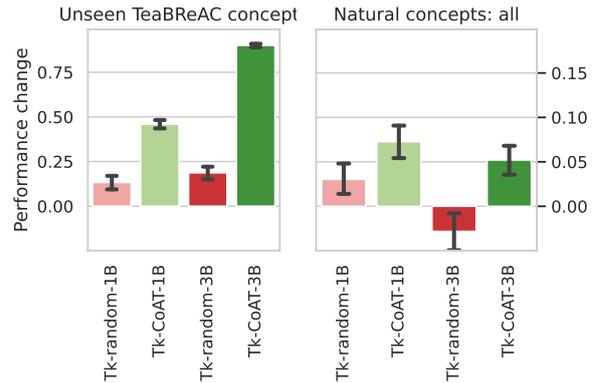


Figure 3: **In-context learning of new concepts:** Relative change of performance of models when presented with demonstrations exhibiting an a reasoning concept informative for prediction. Evaluation with (left) synthetic TeaBReAC samples, and (right) diverse concepts of *natural* datasets (§4.4).

seen TeaBReAC concepts (left) assesses models’ ability to extrapolate the utilisation of latent concepts to 14 previously unseen reasoning chains.

Both CoAT and random-demonstration models (§4.2) can improve from concepts presented in demonstrations. However, the improvement of CoAT-trained models is significantly larger and exceeds gains of TK-RANDOM by 2-fold and 4-fold with the smaller and larger model, respectively. This comparison verifies that CoAT’s data construction really improves our targeted skill of utilizing latent concepts when presented in demonstrations.

**RQ1: CoAT applied with synthetic data also improves the use of natural concepts** Evaluation of improvements on selected natural concepts (Figure 3; right) shows that concept-learning ability obtained with synthetic TeaBReAC concepts also transfers to natural-language settings, as the CoAT-trained models can benefit from concepts significantly *more* than models trained without concept-aware data construction (TK-RANDOM).

Despite that, evaluations over the individual reasoning concepts (Figure 7 in Appendix C.3) reveal that even CoAT models can not benefit robustly from *all* concepts. Nevertheless, we note that in the cases where CoAT models do not improve, also *none* of the baselines benefit from presented concepts. This might be attributed to several reasons: (i) the presented concepts are not really *informative* for prediction, (ii) our training data allowed the models to *memorize* relevant knowledge and, hence, do not *need* (and *benefit from*) the concepts’ exposure, or (iii) our training concepts were simply not sufficient to generalize over these new concepts.

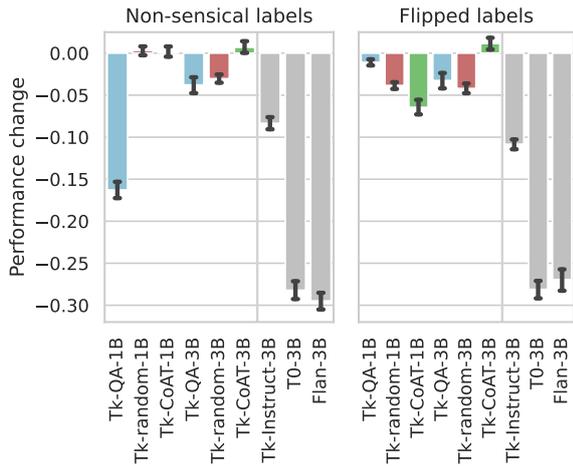


Figure 4: **Models’ reliance on semantic priors:** Relative change of models’ performance when we (left) replace labels with ‘non-sensical’ tokens with no correspondence to the semantics of the task, such as ‘foo’, ‘bar’, etc.; and (right) flip the original labels, so that e.g. ‘negative’ label corresponds to a positive-sentiment sample. CoAT models can in-context learn the input-output mapping similarly well with non-sensical labels and rely on the labels’ semantics significantly less than previous in-context learners.

**RQ2: CoAT mitigates over-reliance on labels’ semantic priors** Evaluation with non-sensical labels (Figure 4) shows that all models pre-trained on a synthetic TeaBReAC dataset (TK-RANDOM, and TK-CoAT) are more robust to the labels’ semantics than our natural-language baseline (TK-QA). However, a comparison of TK-RANDOM and TK-CoAT suggests that TK-CoAT’s preference for learning functional relations is a composition of both using a synthetic dataset in pre-training and CoAT’s data construction mechanism.

A comparison to previous models reveals that all multitask models experience substantially larger decay in performance than our models. We suspect this feature could be a bias specific to massive multi-task learning emerging when label semantics can explain a large portion of training data. This result is consistent with Wei et al. (2023), but contrary to their conclusions, we show that ICL robust to semantic distractions does not emerge exclusively with very large ( $\geq 100B$ ) model scale.

Nevertheless, we note that the smaller CoAT model still relies on labels’ semantics when recognizable (*Flipped labels* case), less significantly than previous work, but comparable to our baselines.

**RQ3: Impact of Concept-aware training on ICL performance** Figure 5 compares the accuracy of

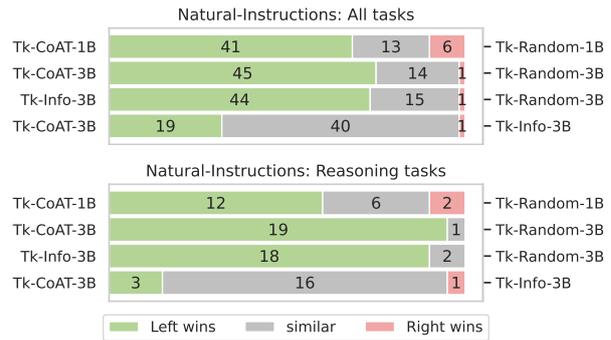


Figure 5: **Efficiency of Concept-aware training: Natural-Instructions:** Win rate of models utilising Concept-aware training (CoAT; §3) and traditional instruction tuning (TK-RANDOM; §4.2) evaluated on (top) all and (bottom) reasoning tasks of Natural-Instructions collection. Values indicate the number of tasks where the referenced model reaches significantly higher accuracy than the other. For the tasks denoted as *similar*, the difference in models’ performance is not statistically significant.

CoAT-trained models to our baselines (i) without systematic demonstrations selection (TK-RANDOM) and (ii) without the *non-triviality* condition (TK-INFO), over 60 tasks of NaturalInstructions collection. In comparison to TK-RANDOM, CoAT models reach significantly higher accuracy on 41 and 45 of 60 tasks, with comparable performance on a majority (13 and 14) of other tasks. The difference is further magnified on reasoning tasks, which we argue might better evaluate models’ ability to in-context learn a *functional* relation of the new task. A comparison of TK-INFO with TK-RANDOM shows that the performance on reasoning tasks is mainly fostered by the CoAT’s *informativeness* condition, but in a full task collection, TK-CoAT still outperforms TK-INFO in 19 out of 60 tasks. Evaluations by other task segments can be found in Appendix C.2.

In the evaluation over the tasks of SuperGLUE collection (Table 1), we additionally report the specific values of ROUGE-L that our baselines and CoAT models achieve. With a single exception, models utilising a concept-based selection of demonstrations (TK-CoAT and TK-INFO) consistently reach higher scores than TK-RANDOM. Our analyses of models’ predictions reveal that in 7 out of 20 evaluations, TK-RANDOM models fail to follow the task’s instruction, consequentially responding out of valid label space. TK-CoAT shows to mitigate this issue in all cases except for a smaller CoAT-trained model on MultiRC. A comparison of TK-CoAT with TK-INFO shows that *informative-*

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	AxG	Ax-b	WSC	CB	RTE	WiC	ReCoRD	BoolQ	COPA	MultiRC
Tk-RANDOM-1B	49.4±5.2	43.6±4.8	52.7±5.1	21.8±3.9	29.3±4.6	18.0±4.0	15.3±3.8	34.0±5.0	74.7±3.4	5.1±2.4
Tk-RANDOM-3B	50.2±5.4	<u>57.5±4.8</u>	52.0±5.5	47.8±5.1	48.9±4.8	50.1±4.4	16.3±7.3	62.8±4.6	75.5±2.8	2.1±1.5
Tk-INFO-1B	50.0±4.2	42.6±5.7	52.0±4.3	<u>47.2±3.9</u>	49.2±4.8	53.2±4.5	15.5±4.0	19.6±2.3	61.5±2.3	3.2±1.2
Tk-INFO-3B	50.8±4.6	57.2±4.9	53.5±4.8	47.3±5.4	<u>54.7±4.9</u>	53.6±4.7	22.6±4.5	<u>64.4±4.8</u>	76.3±3.0	2.7±2.1
Tk-CoAT-1B	<u>50.4±5.3</u>	<u>52.7±4.6</u>	<u>53.6±5.2</u>	46.9±4.9	<u>53.7±4.9</u>	<u>53.5±5.3</u>	<u>17.0±3.5</u>	<u>63.8±5.4</u>	<u>76.1±3.2</u>	<u>11.4±2.6</u>
Tk-CoAT-3B	<u>57.9±4.9</u>	57.2±4.8	<u>53.6±4.5</u>	<u>60.4±4.8</u>	52.0±5.4	<u>56.9±5.0</u>	<u>23.1±3.8</u>	63.6±4.3	<u>81.3±3.3</u>	<u>56.9±3.6</u>

Table 1: **Efficiency of concept-aware training: SuperGLUE:** ROUGE-L scores of ICL models evaluated in few-shot setting on SuperGLUE tasks (Wang et al., 2019), trained using (i) *random* demonstrations sampling used in previous work, (ii) *informative* demonstrations sampling (§4.2) and (iii) *informative+non-trivial* sampling (CoAT; §3). Underlined are the best results per each task and model size. See Table 2 for a comparison to previous models.

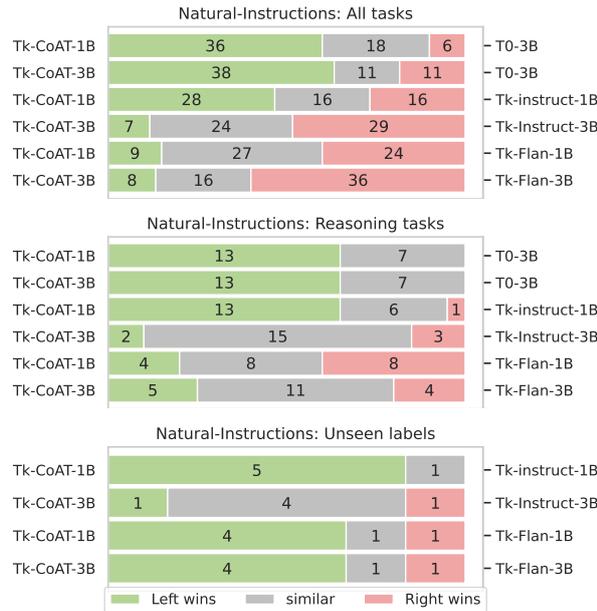


Figure 6: **Performance comparison to previous work: Natural-Instructions:** : Win rate of CoAT models trained using two (2) tasks and existing models trained on mixtures of 35 (T0), 1,616 (Tk-INSTRUCT) and 1,836 tasks (Tk-FLAN). Values denote the number of tasks where the model reaches significantly better accuracy. Evaluations over (top) all tasks, (middle) reasoning tasks, (bottom) tasks with labels not present in the training mix of Tk-Instruct and Tk-Flan.

ness condition is more substantial for a smaller model, but the models of both sizes benefit from the concept-based selection of demonstrations.

**Comparison to multitask learners** Figure 6 compares the performance of CoAT models with the models of previous work, trained on large mixtures of 35–1,836 tasks. In the comparison over all the NI tasks (Fig. 6; top), the performance of CoAT models is better or comparable for the majority of the tasks in 5 out of 6 competitions. The evaluation on reasoning tasks (Fig. 6; middle) supports our hypothesis that CoAT particularly promotes improvements in in-context learning of new reasoning

ability, winning on reasoning tasks over FLAN and Tk-INSTRUCT in a comparable number of cases than the opponents. Finally, we look at a few tasks where Tk-INSTRUCT and FLAN can not rely on the semantics of labels presented in their training mix (Fig. 6; bottom). In this segment, CoAT models perform best, reaching significantly better accuracy on the majority of tasks in 3 out of 4 comparisons.

Table 2 in Appendix C details models’ scores on SuperGLUE tasks, providing further evidence on a comparability of CoAT models to multitask learners. For instance, a comparison with Tk-Instruct reveals that CoAT’s 1B and 3B models reach higher absolute results on 3 and 5 out of the 7 Tk-INSTRUCT’s unseen tasks.

## 6 Conclusion

Inspired by the theory on data properties conditioning the emergence of in-context learning (ICL), we propose Concept-aware Training (CoAT), a framework specifying how to construct training samples that make it beneficial for a language model to learn to extract and apply latent reasoning concepts from demonstrations. We implement CoAT and show that language models *can* learn to perform a concept-based ICL (RQ1), and that concept-based ICL is more robust in learning *functional* relations of a new task from demonstrations (RQ2). Finally, we find that concept-based ICL also *brings* performance gains in the ICL of a majority of unseen tasks (RQ3), performing comparably to models trained on over 1,600 tasks with only two QA tasks.

In a broader perspective, our work explores an alternative axis for scaling the quality of in-context learning, complementing the known *model* and *data scale* axes. We wish to inspire future work to a more proactive approach to refining train data properties so that fitting such data *necessitates* the emergence of the specific, robust abilities of the models, such as the concept modelling ability.

## 625 Limitations

626 Although our main objective is to assess the effi- 676  
627 ciency of concept-aware training, we acknowledge 677  
628 the limitations of our comparison to the previous 678  
629 work, where several aspects convolute the represen- 679  
630 tative comparison of different in-context learners: 680  
631 (i) each of the multitask learners was trained on a 681  
632 different, yet massive set of tasks, making it dif- 682  
633 ficult to find a broader collection that is *new* for 683  
634 multiple models; For this purpose, we surveyed 684  
635 three standard collections used for few-shot eval- 685  
636 uation: CLUES (Mukherjee et al., 2021), RAFT 686  
637 (Alex et al., 2021) and FLEX (Bragg et al., 2021), 687  
638 but found in total only three tasks unseen by the 688  
639 multitask learners of previous work, all of the same 689  
640 type (classification). Therefore, we use in our eval- 690  
641 uations (a) Tk-Instruct’s own evaluation set and 691  
642 (b) SuperGLUE with a significant overlay with the 692  
643 training tasks of previous work. (ii) many aspects 693  
644 make it “easier” for the model to improve, includ- 694  
645 ing the domain of labels or prompt format matching 695  
646 the training distribution (relevant to TK-INSTRUCT  
647 and FLAN evaluated on Natural-Instructions).

648 Another aspect that we neglect in our experi- 696  
649 ments in favour of more in-depth analyses is the 697  
650 *impact of pretraining* projected into the properties 698  
651 of the foundation model that we use. We pick T5 699  
652 as a base model for our experiments to maximise 700  
653 comparability with previous methods. While we 701  
654 do not identify any concrete reason to assume that 702  
655 CoAT would perform worse with other base mod- 703  
656 els, one should note that our results do not provide 704  
657 any evidence in this respect. 705

658 Finally, we note that the applicability of CoAT 706  
659 is conditioned by the availability of the annotated 707  
660 *concepts C* in the training datasets, which might 708  
661 be difficult to obtain for natural-language datasets. 709  
662 Our implementation circumvents this issue by us- 710  
663 ing a synthetically curated dataset. Hence, we 711  
664 simultaneously show that concept-aware abilities 712  
665 can also be obtained in the restrictive settings of 713  
666 synthetic-dataset pre-training, where we note that 714  
667 the volume and variability of the synthetic dataset 715  
668 can be scaled further much easier than the natural 716  
669 dataset(s) (Trivedi et al., 2022). Nevertheless, our 717  
670 experiments do not provide any empirical evidence 718  
671 for answering *to what extend* could further exten- 719  
672 sion of synthetically-generated datasets, possibly 720  
673 covering even more complex concepts, *scale* to 721  
674 further performance gains. 722

## Ethical Considerations & Broader Impact

675 The primary motivation of our work is to minimise 676  
677 the computing demands for the creation of accurate 678  
679 in-context learners by deepening our understand- 680  
681 ing of the covariates of the resulting quality. We 682  
683 believe that our presented method, as well as the 684  
685 future data-efficient methods improving our under- 686  
687 standing of in-context learning, will enable the de- 688  
689 mocratization of the creation of robust and accurate 690  
691 in-context learning models for both research and 692  
693 industry. 694  
695

696 Finally, we note that data-efficient methods for 697  
698 training ICLs (as opposed to *multitask training*) 699  
699 might open possibilities for creating more accu- 700  
700 rate ICLs specialized to languages outside English, 701  
701 where training datasets are scarce. We look forward 702  
702 for the future work that will explore the potential of 703  
703 data-efficient instruction tuning specifically on the 704  
704 target-language datasets, creating in-context learn- 705  
705 ers specially tailored for target languages outside 706  
706 English. 707

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## A Training details

In all our training setups, we fine-tune all model parameters for teacher-forced next-token prediction, conventionally used in training sequence-to-sequence language models. In the two training stages (TeaBReAC and AdversarialQA), we use a **learning rate** of  $5e^{-5}$  and  $2e^{-5}$ , respectively. Other parameters remain identical between stages: effective **batch size** = 30 samples and **early stopping** with the patience of 2,000 updates based on evaluation loss on a standardized validation set of each dataset. We do not report the absolute values of evaluation loss as these are not directly comparable. In CoAT training, we use a random subsample of 20 informative examples as a candidate set for a selection of non-trivial demonstrations.

Other parameters of training configuration default to Training Arguments of Transformers library (Wolf et al., 2020) in version 4.19.1. For readability, we implement the relatively complex demonstrations’ selection as a new objective of the Adaptor library (Štefánik et al., 2022). The picked demonstrations are encoded into a format consistent with the evaluation.

## B Evaluation details

**SuperGLUE Evaluation format** As mentioned in Section 4.1, we verbalize both the demonstrations and predicted sample using all available templates of PromptSource library (Bach et al., 2022), obtaining prompts for each demonstration prompt  $x_i$  and its label  $y_i$  in a free-text form. The prompts commonly contain the full-text match of the possible labels as options for the model.

Following the example of Wang et al. (2022), we additionally prepend the demonstrations and labels with keywords “Input” and “Prediction” and separate demonstrations with new lines. Thus, the resulting input→output pairs in evaluation take this format:

```
“Input:  $x_1$  Prediction:  $y_1$  <newline>
Input:  $x_2$  Prediction:  $y_2$  <newline>
Input:  $x_3$  Prediction:  $y_3$  <newline>
Input:  $x_{pred}$  Prediction: ” → “ $y_{pred}$ ”
```

where demonstrations  $(x_i, y_i)$  are picked randomly but consistently between all evaluated models.

**Natural-Instructions Evaluation format** In the evaluations on Natural-Instructions, we closely follow the example of Wang et al. (2022) and additionally prepend the sequence of demonstrations with an instruction provided for each task:

```
“<task instruction> <newline>
Input:  $x_1$  Prediction:  $y_1$  <newline>
Input:  $x_2$  Prediction:  $y_2$  <newline>
Input:  $x_3$  Prediction:  $y_3$  <newline>
Input:  $x_{pred}$  Prediction: ” → “ $y_{pred}$ ”
```

where the *<task instruction>* contains the instruction as would be given to the annotators of the evaluation task, usually spanning between 3–6 longer sentences. The demonstrations are again picked randomly but consistently between models.

**Evaluation metrics selection** Previous work training in-context few-shot learners is not consistent in the use of evaluation metrics, and the choice usually boils down to either using the exact-match accuracy (Sanh et al., 2022; Chung et al., 2022) or ROUGE-L of Lin (2004) (Wang et al., 2022), evaluating the longest common sequence of tokens. We investigate these two options with the aim of not penalising the models for minor discrepancies in the output format (in the accuracy case) but avoiding false positive evaluations in predictions that are obviously incorrect (in the ROUGE case).

Investigation of the models’ predictions reveals that the selection of the metric makes a large difference only in the case of Tk-INSTRUCT models, where the situation differs between SuperGLUE and Natural-Instructions, likely due to the character of the evaluation prompts.

(1) On **SuperGlue**, e.g. on MultiRC task, for the evaluation prompt: "Does answer sound like a valid answer to the question: question", Tk-INSTRUCT-3B in our evaluation predicts "Yes." or "Yes it is" (instead of "Yes"), or "No not at all" (instead of "No"), likely due to the resemblance with the format of training outputs. As we do not wish to penalize these cases, we use ROUGE-L over all SuperGLUE evaluations.

(2) In **Natural-Instructions** evaluation, we find that Tk-INSTRUCT often predicts longer extracts from the input prompt. This is problematic with ROUGE-L in the cases where the extract contains

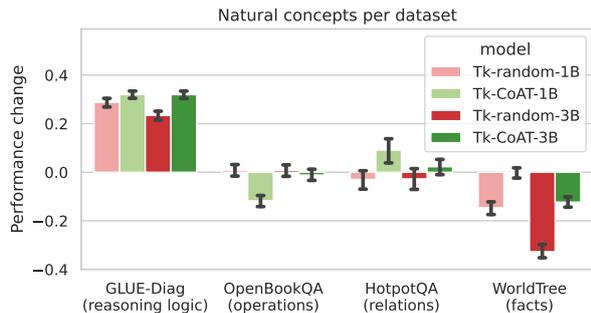


Figure 7: **In-context learning of specific natural concepts:** While CoAT improves the ability to benefit from reasoning concepts on average (Fig. 3), per-concept evaluation reveals that this ability is not consistently robust.

all possible answers, such as in the TK-INSTRUCT-1B’s prediction: “yes or no” to the prompt whose instruction ends with “Please answer in the form of yes or no.”. As we encounter this behaviour in a large portion of Natural-Instructions tasks, we evaluate all models on Natural-Instructions for exact-match accuracy after the normalization of the casing and the removal of non-alphabetic symbols. To make sure that the model is presented with the exact-matching answer option, we exclude from evaluation the tasks where the correct answer is not presented in the task’s instruction. The reference to the list of Natural-Instructions evaluation tasks can be found in Appendix C.4.

For the reported evaluations of the Reasoning tasks, we pick from the list of evaluation tasks the ones concerned with the reasoning task by simply matching the tasks with ‘reasoning’ in their name, resulting in the collection of 20 evaluation tasks.

## C Further evaluations

### C.1 SuperGLUE evaluations of other models

Table 2 compares the performance over the tasks of SuperGLUE collection (Wang et al., 2019) for CoAT models trained on two tasks of the same (QA) type with in-context learners trained on 35–1,836 tasks of the comparable size. Despite the significantly smaller volumes and complexity of the training dataset, CoAT-trained models show competitive results to similar-size or even larger in-context learners of previous work. For instance, the 1-billion-parameter TK-CoAT performs better than the 3-billion T0 in 3 cases (Ax-b, RTE, COPA) and comparably in another 3 cases (WSC, CB, WiC). In comparison with TK-INSTRUCT of the same size, TK-CoAT-1B outperforms TK-INSTRUCT in 3 out of

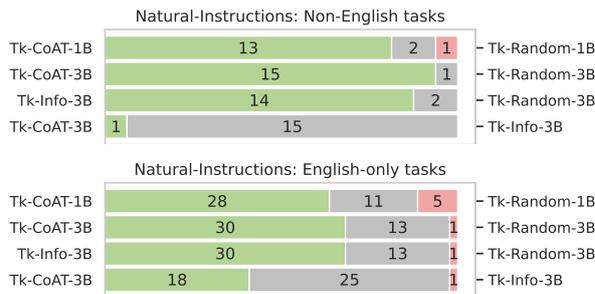


Figure 8: **Impact of Concept-aware training per different language settings:** Pairwise comparison of models trained using selected training configurations (§4.2) on (top) *Non-English* tasks and (bottom) *English-only* tasks of Natural-Instructions collection. Values in green and red bars indicate a number of tasks where the referenced model reaches significantly higher accuracy than the other. For the tasks denoted as *similar*, the difference in performance falls within the evaluation’s confidence intervals.

7 unseen tasks (WSC, CB, ReCoRD), and reaches similar scores in most other cases, even in 2 out of 3 tasks that were included in TK-INSTRUCT’s training mix. Similarly, larger TK-CoAT-3B outperforms TK-INSTRUCT on 4 of 7 new tasks (Ax-b, WSC, WiC, ReCoRD), but with larger gaps on the others.

### C.2 Natural-Instructions: other task types

Figure 8 evaluates the impact of CoAT’s mechanism on the quality of in-context learning separately on the English and non-English tasks. The figure reveals that CoAT works particularly well for non-English tasks. Our analyses found this is mainly due to the low performance of the baseline on the non-English tasks. We speculate that this can be a consequence of the higher reliance of the baseline on token semantics (Section 4.4, RQ2); As our models are fine-tuned on an English-only QA model, such learnt reliance is not applicable in multilingual settings.

Figure 9 compares the performance of CoAT models against the models of previous work, separately on the English and non-English tasks. We can see that CoAT is slightly better at the multilingual portion of Natural-Instructions, but the difference is not principal.

### C.3 Per-concept evaluations

Figure 7 evaluates the performance gains of the baseline models (§4.2) and CoAT-trained models individually per each of the concepts of the natural datasets. While the CoAT models are able to bene-

	# train tasks	AxG	Ax-b	WSC	CB	RTE	WiC	ReCoRD	BoolQ	COPA	MultiRC
FLAN-1B	1,836	84.8±3.9	21.9±4.0	70.7±4.8	92.5±2.8*	92.1±3.0*	69.9±5.1*	38.9±5.2*	92.3±2.7*	97.8±1.5*	88.3±3.2*
FLAN-3B	1,836	95.3±3.7	22.0±8.0	80.2±9.2	92.7±6.7*	96.0±4.0*	79.7±8.3*	62.2±9.7*	92.1±5.1*	99.3±1.6*	90.4±6.4*
Tk-INSTRUCT-1B	1,616	51.9±4.9	57.2±5.8	49.8±4.9	46.0±5.5	55.5±4.8	53.5±5.3	13.1±3.7	63.4±3.4*	76.9±3.2*	62.2±5.1*
Tk-INSTRUCT-3B	1,616	53.5±4.7	49.9±4.9	51.2±4.9	66.3±4.6	62.7±4.6	50.4±4.8	18.6±4.2	68.8±4.4*	73.8±3.5*	59.9±4.9*
T0-3B	35	65.0±4.5	36.1±4.6	53.5±5.2	48.0±5.4	51.3±5.2	54.0±5.0	20.5±4.0	60.1±4.9	56.8±3.6	56.2±4.4
Tk-CoAT-1B	2	50.4±5.3	52.7±4.6	53.6±5.2	46.9±4.9	53.7±4.9	53.5±5.3	17.0±3.5	63.8±5.4	76.1±3.2	11.4±2.6
Tk-CoAT-3B	2	57.9±4.9	57.2±4.8	53.6±4.5	60.4±4.8	52.0±5.4	56.9±5.0	23.1±3.8	63.6±4.3	81.3±3.3	56.9±3.6

Table 2: **ICL performance: comparison to previous ICL models** ROUGE-L of CoAT-trained ICL models and models of comparable size in previous work. Evaluation setup is consistent with Table 1. In cases marked with \*, the task was used in the model’s training; Underlined are the best results per unseen task and model size.

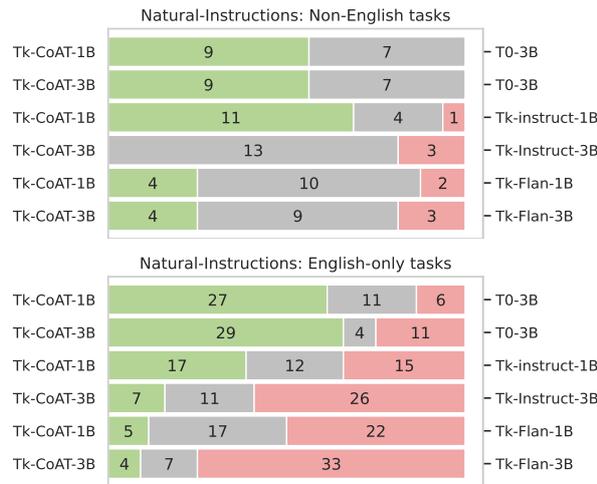


Figure 9: **Comparison to previous work per different language settings:** Pairwise comparison of CoAT models vs. the models of previous work on (top) *Non-English* tasks and (bottom) *English-only* tasks of Natural-Instructions collection. Values denote the number of tasks where the model reaches significantly better accuracy. For the tasks denoted as *similar*, the difference in performance falls within the evaluation’s confidence intervals.

fit from concepts the largest in the relative change of quality, they are also not consistent in the ability to benefit from all the concepts. However, as discussed in Section 5, this does not imply that CoAT is unable to utilize these concepts.

#### C.4 Evaluation tasks and other configurations

SuperGLUE (Wang et al., 2019) consists of the following tasks (as ordered in our Results, §5): Winogender Schema Diagnostics (AxG) (Rudinger et al., 2018), Broadcoverage Diagnostics (CB), The Winograd Schema Challenge, Commitment-Bank (CB), Recognizing Textual Entailment (RTE), ContextWords in Context (WiC) (Pilehvar and Camacho-Collados, 2019), Reading Comprehen-

sion with Commonsense Reasoning (ReCoRD) (Zhang et al., 2018), BoolQ (Clark et al., 2019), Choice of Plausible Alternatives (COPA), Multi-Sentence Reading Comprehension (MultiRC).

Natural-Instructions consists of a larger mixture of tasks, which we do not enumerate here to maintain readability; the full list of evaluation tasks can be found in the original work of Wang et al. (2022) in Figures 11 and 12.

To maintain comparability of evaluations among models, we deterministically fix the demonstration selection procedure so that only the full prediction prompts for all the models are the same. In the analyses comparing the differences in performance (§4.4; RQ1+2), we fixed the prediction samples ( $x_{\text{pred}}$ ) between different demonstrations’ sampling strategies to avoid perplexing our comparison with possible data selection biases. Further details can be found in the referenced implementation.

#### D Computational Requirements

We run both training and evaluation experiments on a machine with dedicated single NVIDIA A100-SXM-80GB, 40GB of RAM and a single CPU core. Hence, all our reproduction scripts can run on this or a similar configuration. Two stages of training in total take at most 6,600 updates and at most 117h of training for Tk-CoAT to converge.