# Foundations and Recent Trends in Multimodal Mobile Agents: A Survey

**Anonymous ACL submission** 

#### Abstract

Mobile agents are essential for automating tasks in complex and dynamic mobile environments. As foundation models evolve, they offer increasingly powerful capabilities for understanding and generating natural language, enabling real-time adaptation and processing of multimodal data. This survey provides a comprehensive review of mobile agent tech-009 nologies, with a focus on recent advancements in foundation models. Our analysis begins by 011 introducing the core components and exploring key representative works in mobile bench-012 013 marks and interactive environments, aiming to fully understand the research focuses and their limitations. We then categorize these advancements into two main approaches: prompt-based methods, which utilize large language models (LLMs) for instruction-based task execution, 018 and training-based methods, which fine-tune 019 multimodal models for mobile-specific applications. By discussing key challenges and outlining future research directions, this survey offers valuable insights for advancing mobile agent technologies.

# 1 Introduction

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Mobile agents have achieved notable success in handling complex mobile environments, enabling the automation of task execution across various applications with minimal human intervention (Zhang et al., 2023a; Li et al., 2024b; Bai et al., 2024). These agents are designed to perceive, plan, and execute in dynamic environments, making them highly suitable for mobile platforms that demand real-time adaptability. Over the years, research on mobile agents has evolved from simple rule-based systems to more sophisticated models capable of handling multimodal data and complex decision-making processes (Shi et al., 2017; Rawles et al., 2023). At the same time, foundation models, such as large language models (LLMs) and multimodal models, have become pivotal in enabling mobile agents to better understand, generate, and adapt to their environments, thus expanding their capabilities in mobile systems (Ma et al., 2024; Bai et al., 2024). 043

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The growing complexity of mobile environments and the increasing demand for automation highlight the importance of mobile agents (Deng et al., 2024a). They play a critical role in applications such as mobile interfaces, autonomous navigation, and intelligent assistance, allowing for more efficient and intelligent task execution (Yang et al., 2023). As mobile technologies advance, mobile agents are expected to operate in environments that require continuous adaptation to changing inputs, multimodal data processing, and interaction with various user interfaces (Zhang et al., 2023a). The ability to process and integrate diverse data sources in real-time makes mobile agents essential for enabling seamless user experiences and efficient operations in dynamic mobile platforms.

Despite their progress, mobile agents face several challenges. Traditional evaluation methods often fail to capture real-world mobile tasks' dynamic and interactive nature, limiting their assessment accuracy (Deng et al., 2024a). To address this, recent benchmarks such as AndroidEnv (Toyama et al., 2021) and Mobile-Env (Zhang et al., 2023a) have been developed to evaluate agents in more realistic, interactive mobile environments, focusing on adaptability and task performance. These benchmarks provide a more comprehensive assessment of mobile agents by measuring task completion and their ability to respond to changes in the environment.

Addressing complex tasks while ensuring mobile agents are multimodal, scalable, adaptable, and resource-efficient remains a significant challenge. Recent advancements in multimodal mobile agent research can be categorized into prompt-based and training-based methods. Prompt-based methods leverage large language models (LLMs), such as ChatGPT (OpenAI, 2023) and GPT-4 (OpenAI, 2023), to handle complex tasks by using instruction

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prompting and chain-of-thought (CoT) reasoning (Zhang et al., 2024c). Notable works such as AppAgent (Yang et al., 2023) and AutoDroid (Wen et al., 2024) have demonstrated the potential of promptbased systems in interactive mobile environments, although scalability and robustness remain ongoing challenges. On the other hand, training-based methods focus on fine-tuning multimodal models, such as LLaVA (Liu et al., 2023a) and Qwen-VL (Bai et al., 2023), specifically for mobile applications. These models can handle rich, multimodal data by integrating visual and textual inputs, improving their ability to perform tasks like interface navigation and task execution (Ma et al., 2024; Dorka et al., 2024).

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This survey provides a comprehensive review of multimodal mobile agent technologies, focusing on recent advancements and ongoing challenges. First, we explore the core components of mobile agents, including perception, planning, action, and memory, which collectively enable agents to operate effectively in dynamic environments. Furthermore, we explore the benchmarks and evaluation methods used to assess mobile agent performance. Next, we categorize mobile agents into promptbased and training-based approaches, discussing their strengths and limitations in improving agent adaptability, reasoning, and task execution. Finally, we discuss the future development directions of multimodal mobile agents. By providing a clear understanding of the current state of mobile agent research, this survey identifies key areas for future exploration and offers insights into the development of more adaptive, efficient, and capable mobile agents.

# 2 The Components of Mobile Agents

As shown in Fig. 1, this section outlines the four fundamental components of mobile agents: perception, planning, action, and memory. Together, these components enable agents to perceive, reason, and execute within dynamic mobile environments, adapting their behavior dynamically to improve task efficiency and robustness.

# 2.1 Perception

Perception is the process through which mobile agents gather and interpret multimodal information from their surroundings. In mobile agents, the perception component focuses on handling multimodal information from different environments, extracting relevant information to aid in planning and task execution.

Early research on mobile agents (Zhang et al., 2021; Sunkara et al., 2022; Song et al., 2023) primarily relied on simple models or tools to convert images or audio into text descriptions. However, these approaches often generate irrelevant and redundant information, hampering effective task planning and execution, especially in content-heavy interfaces. Additionally, the input length limitations of LLMs further amplified these challenges, making it difficult for agents to filter and prioritize information during task processing. Existing visual encoders, mostly pre-trained on general data, are not sensitive to interactive elements in mobile data. To address this, recent studies by Seeclick (Cheng et al., 2024) and CogAgent (Hong et al., 2024) have introduced mobile-specific datasets that enhance visual encoders' ability to detect and process key interactive elements, such as icons, within mobile environments.

In contexts where API calls are accessible, Mind2Web (Deng et al., 2024b) and AutoDroid (Wen et al., 2024) introduces a method for processing HTML-based information. This method ranks key elements of HTML data and filters crucial details to improve LLM perception of interactive components (Li et al., 2024b). Meanwhile, Octopus v2 (Chen and Li, 2024) leverages specialized functional tokens to streamline function calls, significantly enhancing on-device language model efficiency and reducing computational overhead.

### 2.2 Planning

Planning is central to mobile agents, enabling them to formulate action strategies based on task objectives and dynamic environments. Unlike agents in static settings, mobile agents must adapt to everchanging inputs while processing multimodal information.

Planning strategies can be categorized as dynamic or static. In static planning, agents break down tasks into sub-goals but do not re-plan if errors occur (Zhang et al., 2024c). In contrast, dynamic planning adjusts the plan based on realtime feedback, enabling agents to revert to earlier states and re-plan (Gao et al., 2023b; Wang et al., 2024a). Recent advances in prompt engineering have further enhanced mobile agent planning. OmniAct (Kapoor et al., 2024) employs prompt-based techniques to structure multimodal inputs and im-

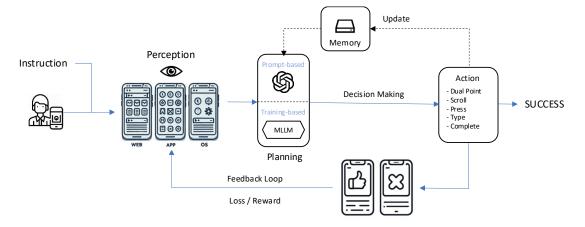


Figure 1: This pipeline shows the decision-making process of mobile agents: User instructions are processed through web, app, and OS interfaces, followed by planning with prompt-based or training-based methods. Actions are taken, and feedback is used to update memory, enabling continuous learning to achieve success.

prove reasoning capabilities. This approach allows agents to integrate external tools and adjust output formats dynamically and efficiently.

### 2.3 Action

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The action component demonstrates how agents execute tasks in a mobile environment by utilizing three key aspects: screen interactions, API calls, and agent interactions. Through screen interactions, agents tap, swipe, or type on GUIs, imitating human behavior to navigate apps. They also make API calls to access deeper system functions, such as issuing commands to automate tasks beyond the GUI (Chen and Li, 2024). Additionally, by collaborating with other agents, they enhance their ability to adapt to complex tasks, ensuring efficient task execution across diverse environments (Zhang et al., 2024c).

Screen Interactions In mobile environments, interactions often involve actions like tapping, swiping, or typing on virtual interfaces. Agents, such as those in AiTW, AITZ, and AMEX (Rawles et al., 203 2024b; Chai et al., 2024; Zhang et al., 2024c), perform GUI-based actions by mimicking human inter-206 actions, ensuring they work smoothly with native apps. These actions go beyond simple gestures, 207 including complex multi-step processes requiring agents to dynamically adapt to changes or new inputs (Lee et al., 2021; Wang et al., 2022). 210

**API Calls** Mobile agents rely on various methods 211 to interact with GUIs and perform tasks that require 212 deep integration with mobile operating systems, 213 with API calls serving as the foundation (Chen and 214 Li, 2024; Kapoor et al., 2024). Building on API 215

calls, mobile agents can further leverage HTML and XML data to access core functions, modify device settings, retrieve sensor data, and automate app navigation, extending their capabilities beyond GUI-based inputs (Chai et al., 2024; Chen and Li, 2024; Li et al., 2024b). By integrating these approaches, agents can efficiently complete tasks while gaining a more comprehensive understanding of their environment.

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#### 2.4 Memory

Memory mechanisms are crucial for mobile agents, allowing them to retain and use information across tasks. Current research maps in-context learning to short-term and long-term memory to external vector stores.

Short-term Memory Managing task continuity and adaptation effectively requires temporarily storing and reasoning about information, much like human working memory. Recent advancements have focused on improving the memory capabilities of mobile agents. For example, Auto-UI (Zhan and Zhang, 2023) incorporates historical text information to enhance decision-making by retaining past context, while UI-VLM (Dorka et al., 2024) uses image-based memory storage. Unlike singlemodality agents, multimodal agents must handle short-term memory across various data types, including text, images, and interactions, ensuring that crucial information from different sources is retained.

Long-term Memory Handling long-term com-246 plex information requires a more efficient memory system. While external vector stores can retrieve

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past experiences, they function differently from human long-term memory, which is highly structured and interconnected. A combination of parametric memory and vector databases is currently used to mimic human-like long-term memory. Parametric memory stores implicit and semantic information, while vector databases hold more recent semantic and episodic memories. To make querying easier, some approaches convert multimodal inputs into a unified text format for storage, simplifying retrieval and integration during task execution (Yang et al., 2023; Wang et al., 2024b; Wen et al., 2024).

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# **3** Mobile Datasets and Benchmarks

Benchmarks establish a standardized testing environment for evaluating and comparing the performance of mobile agents across both static and interactive settings, covering areas such as user interface automation, task completion, and real-world application scenarios.

Currently, as shown in Table 5, many benchmarks for GUI interaction rely on static datasets (Sun et al., 2022; Deng et al., 2024b; Niu et al., 2024; Roßner et al., 2020), which provide fixed ground-truth annotations and evaluate models by comparing their action sequences to predefined solutions. This method is problematic, as it penalizes alternative valid approaches, marking them as failures even if the task is successfully completed. Interactive benchmarks, such as AndroidArena (Xing et al., 2024), also use action sequence similarity as a primary evaluation metric, resulting in an inadequate assessment of agent performance. While recent studies on LLM-based GUI agents (Yang et al., 2023; Wang et al., 2024a; Zhang et al., 2024a) incorporate LLMs or human evaluations, these experiments are often conducted in uncontrolled open environments, leading to issues with reproducibility and comparability of results.

### 3.1 Static Datasets

Static datasets provide a controlled and predefined set of tasks with annotated ground-truth solutions, making them essential for evaluating the performance of mobile agents in fixed environments. These datasets are primarily used to assess task automation, where agents are required to follow predetermined actions or commands to complete specific tasks.

Early research links referring expressions to UI

elements on a screen, with each instance containing a screen, a low-level command, and the corresponding UI element. For example, the RicoSCA dataset (Deka et al., 2017) uses synthetic commands, while MiniWoB++ (Liu et al., 2018) includes sequences of low-level commands for multistep tasks.

Recent research has shifted towards taskoriented instructions, where each episode contains action-observation pairs, including screenshots and tree-structured representations like Android's View Hierarchy or the Document Object Model in web environments. For instance, the PixelHelp (Li et al., 2020a) dataset contains 187 high-level task goals with step-by-step instructions from Pixel Phone Help pages, while the UGIF (Venkatesh et al., 2022) dataset extends similar queries to multiple languages. Meanwhile, MoTIF(Burns et al., 2021), includes 4.7k task demonstrations, with an average of 6.5 steps per task and 276 unique task instructions. AITW (Rawles et al., 2024b) is much larger, featuring 715,142 episodes and 30,378 unique prompts, some inspired by other datasets.

### 3.2 Simulation Environments

Simulation environments provide dynamic platforms where agents engage with the environment in real time, receiving feedback and adjusting their actions accordingly. Unlike static datasets, these environments allow for continuous, adaptive interactions, making them critical for evaluating agents in more complex, evolving scenarios.

Before the rise of LLM-based agents, research primarily focused on reinforcement learning (RL)based agents. A prominent example is Android-Env (Toyama et al., 2021), which provided RL agents with an environment to interact with mobile applications via predefined actions and rewards. However, with advancements in LLMs, the focus has shifted towards agents that can use natural language understanding and generation to perform more flexible and adaptive tasks (Liu et al., 2024b; Sun et al., 2024b,a).

Simulation Environments are a key focus in current research on LLM-based agents, particularly in their ability to explore decision paths autonomously through interactions with the environment (Liu et al., 2024b; Sun et al., 2024b,a). In mobile settings, these agents are designed to handle complex, multi-step tasks and simulate human-like behav-

Dataset	Templates	Attach	Task	Reward	Platform
Static Dataset					
RICOSCA (Deka et al., 2017)	259k	VH	Grounding	-	Android
AndroidHowTo (Deka et al., 2017)	10k	-	Extraction	-	Android
PixelHelp (Li et al., 2020a)	187	VH	Apps	-	Android
Screen2Words (Wang et al., 2021)	112k	VH	Summarization	-	Android
META-GUI (Sun et al., 2022)	1,125	XML	Apps+Web	-	Android
MoTIF (Burns et al., 2021)	4,707	VH	Apps	-	Android
UGIF (Venkatesh et al., 2022)	4184	XML	Grounding	-	Android
AitW (Rawles et al., 2024b)	30k	Layout	Apps+Web	-	Android
AitZ (Zhang et al., 2024c)	2504	CoT	Apps+Web	-	Android
AMEX (Chai et al., 2024)	3k	Layout	Apps+Web	-	Android
Mobile3M (Chen et al., 2024a)	3M	XML	Apps	-	Android
Androidcontrol (Li et al., 2024a)	15283	VH	Apps+Web	-	Android
MobileViews-600K (Gao et al., 2024)	600k	VH	Apps	-	Android
Ferret-UI (You et al., 2024)	120k	VH	Apps	-	IOS
Odyssey (Lu et al., 2024)	7735	-	Apps+Web	-	Multi Platforms
ScreenSpot (Cheng et al., 2024)	1200	Layout	Apps+Web	-	Multi Platforms
GUI-World (Chen et al., 2024a)	12379	Video	Apps+Web	-	Multi Platforms
Interactive Environment					
MiniWoB++ (Liu et al., 2018)	114	-	Web (synthetic)	Sparse Rewards	-
AndroidEnv (Toyama et al., 2021)	100	-	Apps	Sparse Rewards	Android
AppBuddy (Shvo et al., 2021)	35	-	Apps	Sparse Rewards	Android
Mobile-Env (Zhang et al., 2023a)	224	VH	Apps+Web	Dense Rewards	Android
AndroidArena (Wang et al., 2024c)	221	XML	Apps+Web	Sparse Rewards	Android
AndroidWorld (Rawles et al., 2024a)	116	-	Apps+Web	Sparse Rewards	Android
DroidTask (Wen et al., 2024)	158	XML	Apps+Web	-	Android
B-MoCA (Lee et al., 2024)	60	XML	Apps+Web	-	Android
AppWorld (Trivedi et al., 2024)	750	API	Apps+Web	-	Android
Mobile-Bench (Deng et al., 2024a)	832	XML	Apps+Web	-	Android
MobileAgentBench (Wang et al., 2024c)	100	VH	Apps+Web	Dense Rewards	Android
LlamaTouch (Zhang et al., 2024d)	60	-	Apps+Web	-	Android
Spa-Bench (Chen et al., 2024b)	340	-	Apps+Web	Dense Rewards	Android
AndroidLab (Xu et al., 2024b)	138	XML	Apps+Web	Dense Rewards	Android
CRAB (Xu et al., 2024a)	23	XML	Apps+Web	Dense Rewards	Multi Platforms

Table 1: Comparison of various platforms based on parallelization, templates, tasks per template, rewards, and supported platforms. Layout refers to fine-grained annotation of the image content, such as the positional coordinates of elements. VH means View Hierarchy.

iors for app automation (Wen et al., 2023a,b; Liu et al., 2023c; Yao et al., 2022a; Shvo et al., 2021). A notable example is Mobile-Env (Zhang et al., 2023a), created to evaluate how well agents manage multi-step interactions in mobile environments. Ultimately, this research aims to improve the adaptability and flexibility of LLM-based agents, allowing them to function in dynamic, real-world environments with minimal reliance on predefined scripts or manual input.

#### 3.3 **Real-world Environments**

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Real-world Environments present a significant opportunity to address one of the main limitations of closed-reinforcement learning settings: their inability to fully capture the complexity and variability of real-world interactions. While controlled environments are useful for training and testing 365 agents, they often miss the dynamic elements of real-world scenarios, where factors like changing content, unpredictable user behavior, and diverse device configurations are crucial. To overcome

these challenges, researchers are increasingly exploring open, real-world environments for LLMbased GUI agents, enabling them to learn and adapt to the intricacies of live systems and evolving situations (Gao et al., 2023a; Wang et al., 2024b; Zhang et al., 2024a; Yang et al., 2023). However, deploying agents in open-world settings introduces several risks. These include safety concerns, irreproducible results, and the potential for unfair comparisons. To mitigate these issues and ensure fair, reproducible evaluations, researchers advocate for strategies such as fixing dynamic online content and employing replay mechanisms during evaluation (Liu et al., 2018; Shi et al., 2017; Zhou et al., 2023). These methods help create a more controlled testing environment, even within the broader scope of open-world deployments.

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#### 3.4 **Evaluation Methods**

In evaluating agent performance, trajectory evaluation, and outcome evaluation are two main methods. Trajectory evaluation focuses on how well agent

390actions align with predefined paths. In contrast,391outcome evaluation emphasizes whether the agent392achieves its final goals, focusing on results rather393than the specific process. The following sections394will explore recent research advancements in these395two areas, highlighting how more comprehensive396evaluation strategies can enhance our understand-397ing of agent performance in complex environments.

Trajectory Evaluation Recent improvements in GUI interaction benchmarks have focused on stepby-step assessments, comparing predicted actions 400 to reference action trajectories to evaluate agent 401 performance effectiveness (Rawles et al., 2024b; 402 Zhang et al., 2021). While this approach is ef-403 fective in many cases, task completion often has 404 multiple valid solutions, and agents might explore 405 different paths that do not necessarily follow the 406 predefined trajectories. To improve the flexibility 407 and robustness of these evaluations, Mobile-Env 408 evaluate a subset of signals from the environment 409 of an intermediate state, enabling reliable assess-410 ment across a wider range of tasks (Zhang et al., 411 2023a). 412

Outcome Evaluation An agent's success is deter-413 mined by assessing whether it reaches the desired 414 final state, treating task goals as subsets of hid-415 416 den states, regardless of the path taken to achieve them. These final states can be identified through 417 various system signals. Relying on a single signal 418 type may not capture all relevant state transitions, 419 as certain actions, such as form submissions, may 420 only be visible in the GUI and not in system logs 421 (Toyama et al., 2021) or databases (Rawles et al., 422 2024a). Shifting to outcome-based evaluation and 423 using multiple signals can make GUI interaction 424 benchmarks more reliable and adaptable, allowing 425 agents to show their full abilities in various scenar-426 ios (Wang et al., 2024c; Rawles et al., 2024a). 427

3.5 Performance Comparison

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Due to the limitations of current benchmarks, vari-429 ations in implementation methods, and changes in 430 platforms, comparing all methods within a unified 431 evaluation environment is challenging. Meanwhile, 432 both prompt-based and training-based approaches 433 suffer from inconsistent evaluation metrics, compli-434 cating cross-study comparisons. Methods such as 435 AppAgent (Li et al., 2024b) and AutoDroid (Wen 436 et al., 2024) introduce their own benchmarks and 437 metrics, but only test within these benchmarks and 438

compare against models like GPT-4. These disparities make direct experimental comparisons impractical at this stage. Therefore, after reviewing experimental results from different studies, we compared the AITW and MobileAgentbench benchmarks. AITW measures instruction accuracy (Rawles et al., 2024a), and MobileAgentbench measures Success Rate (Wang et al., 2024c). See tables 3 and 4 in the appendix for more details and the need for standardized benchmarks in future research. 439

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# 4 The Taxonomy of Mobile Agents

This section introduces a taxonomy of mobile agents, categorizing them into two primary types: prompt-based methods and training-based methods. As shown in Table 6, prompt-based agents take advantage of advancements in LLM to interpret and execute instructions through natural language processing, often focusing on tasks that require dynamic interaction with GUI. Training-based methods involve fine-tuning models or applying reinforcement learning to enhance agents' decisionmaking and adaptability over time.

### 4.1 Prompt-based Methods

Recent advancements in LLMs have demonstrated significant potential in developing autonomous GUI agents, particularly in tasks that require instruction following (Sanh et al., 2022; Taori et al., 2023; Chiang et al., 2023) and chain-of-thought (CoT) prompting (Nye et al., 2022; Wei et al., 2022). CoT prompting (Wei et al., 2022; Kojima et al., 2022; Zhang et al., 2023d), in particular, has proven effective in enabling LLMs to handle step-by-step processes, make decisions, and execute actions. These capabilities have shown to be highly beneficial in tasks involving GUI control (Rawles et al., 2023).

**GUI Tools** Enabling LLMs to interact with GUI is essential, as these models are primarily designed to process natural language rather than visual elements. GUI tools play a crucial role in bridging this gap by allowing LLMs to interpret and interact with visual elements through text-based commands, making it possible for the models to process and respond to graphical interface components. This multimodal integration significantly boosts the efficiency and flexibility of mobile agents in complex environments. Techniques like icon recognition and OCR (Zhang et al., 2021; Sunkara et al.,

Method	Input Type	Model	Training	Memory	Multi-agents
Prompt-based Methods					
DroidGPT (Wen et al., 2023b)	Text	ChatGPT	None	×	×
AppAgent (Yang et al., 2023)	Image&Text	GPT-4V	None	$\checkmark$	×
MobileAgent (Wang et al., 2024b)	Image&Text	GPT-4V & DINO & OCR	None	$\checkmark$	×
MobileAgent v2 (Wang et al., 2024a)	Image&Text	GPT-4V & DINO & OCR	None	$\checkmark$	$\checkmark$
AutoDroid (Wen et al., 2024)	Text	GPT-4 & Vicuna-7B	None	$\checkmark$	$\checkmark$
AppAgent V2 (Li et al., 2024b)	Image&Text	GPT-4V	None	$\checkmark$	×
VLUI (Lee et al., 2024)	Image&Text	GPT-4V	None	×	×
MobileExperts (Zhang et al., 2024b)	Image&Text	GPT-4V	None	×	$\checkmark$
Mobile-Agent-E (Wang et al., 2025)	Image&Text	GPT-40 & DINO & Qwen-VL-Plus	None	$\checkmark$	$\checkmark$
Training-based Methods					
MiniWob (Liu et al., 2018)	Image	DOMNET	RL-based	×	×
MetaGUI (Sun et al., 2022)	Image&Text	Faster-RCNN & Transformer	Pre-trained	×	×
CogAgent (Hong et al., 2023)	Image&Text	CogVLM	Pre-trained	×	×
SeeClick (Cheng et al., 2024)	Image&Text	Qwen-VL	Pre-trained	×	×
AutoGUI (Zhang and Zhang, 2023)	Image&Text	BLIP-2-ViT & FLAN-Alpaca	Finetune	$\checkmark$	×
ResponsibleTA (Zhang et al., 2023c)	Image&Text	Swin-ViT & BART	Finetune	$\checkmark$	×
UI-VLM (Dorka et al., 2024)	Image&Text	Qwen-VL	Finetune	$\checkmark$	×
Coco-Agent (Ma et al., 2024)	Image&Text	CLIP-ViT & LLama2-7B	Finetune	$\checkmark$	×
DigiRL (Bai et al., 2024)	Image&Text	BLIP-2-ViT & Flan-T5 & RoBerta	RL-based	×	×
SphAgent (Chai et al., 2024)	Image&Text	SPHINX-X	Finetune	×	×
Octopus v2 (Chen and Li, 2024)	Text	Gemma-2B	Finetune	×	×
Octo-planner (Chen et al., 2024d)	Text	Phi-3 Mini	Finetune	×	$\checkmark$
MobileVLM (Wu et al., 2024a)	Image&Text	Qwen-VL-Chat	Finetune	×	×
OdysseyAgent (Lu et al., 2024)	Image&Text	Qwen-VL	Finetune	$\checkmark$	×
AutoGLM (Liu et al., 2024a)	Image&Text	ChatGLM	RL-based	×	×
LiMAC (Christianos et al., 2024)	Image&Text	Qwen2-VL-2B & AcT	Finetune	×	×
DistRL (Wang et al., 2024e)	Image&Text	BLIP-2-ViT & Flan-T5	RL-based	×	×
ShowUI (Qinghong Lin et al., 2024)	Image&Text	Qwen2-VL-2B	Finetune	×	×
OmniParser (Wan et al., 2024)	Image&Text	BLIP-2 & OCR & YoloV8	Finetune	×	×
OS-Atlas (Wu et al., 2024b)	Image&Text	InternVL-2-4B \ Qwen2-VL-7B	Pre-trained	×	×
AppVLM (Papoudakis et al., 2025)	Image&Text	Paligemma-3B-896	RL-based	×	×
InfiGUIAgent (Liu et al., 2025)	Image&Text	Qwen2-VL-2B	Finetune	×	×

Table 2: Comparison of Mobile Agents: A Detailed Overview of Input Types, Models, Training Methods, Memory Capabilities, and Multi-agent Support.

2022; Song et al., 2023) are used to parse GUI elements, which then converts the parsed elements into HTML layouts. However, this method relies heavily on external tools (Rawles et al., 2023; Wen et al., 2023a) and app-specific APIs (Zhou et al., 2023; Gur et al., 2023), often resulting in inefficiencies and errors during inference. Although some research has investigated multimodal architectures to process different types of inputs (Sun et al., 2022; Yan et al., 2023), these approaches still depend on detailed environment parsing for optimal performance. Given the importance of accurate GUI grounding, newer studies (Cheng et al., 2024; Hong et al., 2023) have begun exploring pretraining methods to improve agent performance in GUI tasks.

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503Memory MechanismEffective task execution in504prompt-based methods relies on a strong memory505mechanism to retain and use relevant information.506In agents like AppAgent (Yang et al., 2023), the507agent employs an exploration phase for memory,

allowing it to learn and adapt to new applications by storing interactions from prior explorations. This approach enables the agent to retain knowledge without needing additional training data. Mobile-Agent (Wang et al., 2024b,a) automates mobile app operations by analyzing screenshots with visual tools, avoiding reliance on system code. 508

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**Complex Reasoning** In agent systems, complex reasoning refers to the ability of models to process, analyze, and integrate information from multiple sources to solve intricate tasks. This capability enhances decision-making, planning, and adaptability by enabling agents to draw connections between different data inputs, evaluate various outcomes, and execute informed actions in dynamic environments. CoAT (Zhang et al., 2024c) enhances GUI agent performance by integrating semantic information into action generation. It combines screen descriptions, action reasoning, next-action descriptions, and predicted outcomes to improve decision accuracy and consistency.

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4.2 Training-based Methods

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In contrast to prompt-based methods, trainingbased approaches involve explicit model optimization. These agents fine-tune large language models like LLama (Zhang et al., 2023b) or multimodal models such as LLaVA (Liu et al., 2023a) by collecting instruction-following data to obtain instruction information.

537 **Pre-trained VLMs** In mobile environments, pretrained VLMs have become powerful tools for 538 decision-making and interaction. Models like LLaVA (Liu et al., 2023a) and Qwen-VL (Bai et al., 2023), pre-trained on large-scale general datasets, 541 capture both visual and language information effectively. However, their applicability in mobile 543 settings is limited by the lack of sensitivity to interactive elements specific to mobile data. To improve 545 the responsiveness of pre-trained models to inter-546 active elements in mobile data, CogAgent (Hong et al., 2023) collected a large-scale mobile dataset 548 549 for pre-training representations. CogAgent (Hong et al., 2023) integrates visual and textual inputs for GUI agents, improving interaction with com-551 plex mobile UIs using VLMs. Spotlight (Li and 553 Li, 2022) is a vision-language model for mobile UI tasks, relying solely on screenshots and spe-554 cific regions, supporting multi-task and few-shot 555 learning, trained on a large-scale dataset. VUT (Li et al., 2021) employs a dual-tower Transformer 557 for multi-task UI modeling, achieving competitive performance with fewer models and reduced computational costs. 560

Fine-Tuning The process of fine-tuning pretrained VLMs with commonsense reasoning capabilities has been facilitated by large-scale mo-563 bile datasets, such as AitW (Rawles et al., 2024b), 564 through the Visual Instruction Tuning approach. Existing methods primarily involve two areas: 566 dataset enhancement, and training strategies improvement. ScreenAI (Baechler et al., 2024) and AMEX (Chai et al., 2024) focus on using synthetic data and multi-level annotations to precisely 570 identify and describe UI elements on mobile inter-571 faces, providing high-quality datasets for complex question-answering and navigation tasks. On the other hand, Auto-GUI (Zhan and Zhang, 2023), UI-574 VLM (Dorka et al., 2024), COCO-Agent (Ma et al., 575 2024), Octo-planner (Chen et al., 2024d), and Auto-576 Droid (Wen et al., 2024) achieve significant model 577 performance improvements through strategies such

as direct interface interaction, task instruction and element layout improvement, and separating planning from execution. These techniques not only optimize automation processes but also enhance the prediction accuracy and operational efficiency of models in practical applications.

**Reinforcement Learning** A dynamic approach to training mobile agents is offered by reinforcement learning, which enables them to learn from interactions with environments. This method is particularly effective in scenarios where the agent must adapt to sequential decision-making tasks or optimize its actions based on rewards. The WoB (Shi et al., 2017) platform enables reinforcement learning in real environments by allowing agents to interact with websites using human-like actions. Meanwhile (Shi et al., 2017) converts action prediction into question-answering, improving task generalization across different environments. MiniWoB++ (Liu et al., 2018) introduces workflowguided exploration, which integrates expert workflows with task-specific actions, accelerating learning and improving task efficiency in action prediction tasks. DigiRL (Bai et al., 2024) combines offline and online reinforcement learning to train device control agents. It scales online training using a VLM-based evaluator that supports real-time interaction with 64 Android emulators, enhancing the efficiency of RL-based agent training.

# 5 Conclusion

This survey provides a comprehensive overview of multimodal mobile agent technologies. Firstly, we discussed the core components-perception, planning, action, and memory-that enable mobile agents to adapt to their environments, forming the foundation of their functionality. Next, we reviewed advancements in mobile agents' benchmarks, which improve mobile agent assessments but still require more comprehensive methods to capture real-world dynamics. We then presented a taxonomy of mobile agents, differentiating between prompt-based and training-based methods, each with strengths and challenges in scalability and adaptability. Finally, we highlighted future research directions, focusing on security, adaptability, and multi-agent collaboration to advance mobile agent capabilities.

6

Limitations

ogy development.

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World Agents.

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This survey focuses on recent advancements in

LLM-based mobile agents but provides limited cov-

erage of traditional, non-LLM-based systems. The lack of discussion on older rule-based agents may

limit the broader context of mobile agent technol-

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# A Appendix

# A.1 Future Work

1205In this survey, we have presented the latest advance-1206ments in the field of mobile agents. While signif-1207icant progress has been made, several challenges1208remain unresolved. Based on the current state of1209research, we propose the following future research1210directions:

1211 Model Architecture Optimization : When optimizing mobile agent performance, it is crucial 1212 to consider the impact of grounding ability on the 1213 action prediction task. To achieve this, the model must enhance its grounding ability for accurate ele-1215 ment localization while effectively adapting to ac-1216 tion prediction tasks and making efficient decisions. 1217 The Mixture of Experts (MOE) architecture plays 1218 a key role in this process (Lin et al., 2024). By 1219 introducing multiple expert modules, MOE allows 1220 the model to dynamically select the most suitable 1221 expert based on the task, making it particularly 1222 effective in handling multi-domain tasks and im-1223 proving task adaptability and performance (Shu 1224 et al., 2024). Therefore, adopting the MOE archi-1225 tecture enhances grounding ability while ensuring 1226 strong decision-making capability in complex tasks, 1227 leading to improved performance across multiple 1228 domains (Wu et al., 2024c). 1229

Combine with Reinforcement Learning: Enhancing mobile agents' ability to adapt to dynamic and unpredictable environments is crucial. Mobile agent tasks are fundamentally decision-making tasks, not just prediction tasks (Liu et al., 2018). Training through instruction fine-tuning can improve predictions within the action space, but it struggles with decision data influenced by predicted outcomes that cause distribution changes, such as in virtual machines or simulators. These scenarios require the use of reinforcement learning to perform sequential decision-making tasks. However, research in this area is still in its early stages. Current explorations, such as Digirl (Bai et al., 2024), Distrl(Wang et al., 2024e) and RL4VLM (Zhai et al., 2024), have not yet achieved end-toend alignment in this field. Future research should explore how to utilize reinforcement learning better to integrate changing interactive environments with multimodal large language models for real-time behavior adjustment.

Security and Privacy: Mobile agents face se-1251 curity risks in open environments. Whether it in-1252 volves tasks that make decisions in latent spaces, 1253 such as those found in the AITW (Rawles et al., 1254 2024a) and AMEX (Chai et al., 2024) datasets, or 1255 tasks like AITZ (Zhang et al., 2024c) that complete 1256 decision-making through chains-of-thought, the 1257 security of the model and its ethical aspects can 1258 impact decision-making performance (Bai et al., 1259 2022). Future work should prioritize stronger secu-1260 rity mechanisms to prevent malicious behavior and 1261 data breaches. It's also necessary to develop pri-1262 vacy protection technologies and ethical improve-1263 ment mechanisms to ensure safe and ethical opera-1264 tions during agent interactions. 1265

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Multi-agent Collaboration: Collective intelligence simplifies complex problems through distributed control, enhances system robustness with redundant designs, and optimizes resource usage through coordinated operations, thereby demonstrating significant efficiency and adaptability in handling large-scale, complex tasks. Improving collaboration among multiple mobile agents remains a key challenge. Current methods exploring multi-agent systems are still limited to roleplaying(Li et al., 2024b), standard operating procedures (Zhang et al., 2024b), and collaboration with expert models (Chen et al., 2024d). The overall scale is small, lacking exploration into communication and organizational structures. Future research should focus on efficient communication and collaborative mechanisms that enable agents to dynamically form coalitions and complete tasks more effectively.

Model Lightweighting: The computational resources on mobile devices are limited, which imposes higher requirements for model deployment and inference. Therefore, quantization and accelerating inference are particularly important. Existing methods such as SphAgent (Chai et al., 2024), CogAgent (Hong et al., 2023), and SeeClick (Cheng et al., 2024) still have too large parameter sizes for deployment on mobile devices. The latest research, like LiMAC (Christianos et al., 2024), reduces finetuning costs without compressing model parameters. Future research should focus on optimizing the size of mobile agents and speeding up the inference process to ensure high performance under resource constraints. Additionally, refining the inference pipeline to enhance real-time decisionmaking capabilities is crucial, which involves better
computational algorithms and hardware accelerations to achieve faster responses and reduce energy
consumption.

# 05 A.2 Complementary Technologies

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Effective complementary technologies are vital for enhancing the performance and usability of mobile agents, in addition to key components like benchmarks, VLM models, fine-tuning methods, and advanced reasoning skills. These technologies facilitate seamless interactions with mobile environments, allowing agents to adapt, learn, and perform complex tasks efficiently.

UIED (Xie et al., 2020) detects and classifies GUI elements using computer vision and deep learning, supporting interactive editing. WebGPT (Nakano et al., 2021) fine-tunes GPT-3 for web-based question answering using imitation learning and human feedback. WebVLN (Chen et al., 2024c) trains AI agents to navigate websites with question-based instructions, incorporating HTML for deeper understanding.

### A.3 Available related technologies

Additionally, OmniACT (Kapoor et al., 2024) offers a comprehensive platform for evaluating task automation across various desktop applications and natural language tasks. WebVoyager (He et al., 2024) introduces an automated evaluation protocol using GPT-4V, capturing screenshots during navigation and achieving an 85.3% agreement with human judgments. Furthermore, Widget Captioning (Li et al., 2020b) sets a benchmark for improving UI accessibility and interaction by providing 162,859 human-annotated phrases that describe UI elements from multimodal inputs, paving the way for advancements in natural language generation tasks. Above all, leveraging a diverse set of system signals provides a more comprehensive and accurate assessment of an agent's performance (Xie et al., 2024).

On desktop platforms, research has focused on evaluating how well LLM-based agents utilize APIs and software tools to complete tasks such as file management and presentations (Qin et al., 2023; Guo et al., 2023). AgentBench (Liu et al., 2023b) offers a flexible, scalable framework for evaluating agent tasks, while PPTC Benchmark (Guo et al., 2023) targets the evaluation of LLM-based agents' performance in PowerPointrelated tasks.

Model	Overall	General	Install	GoogleApps	Single	WebShop.
ChatGPT-COT (Ding, 2024)	7.72	5.93	4.38	10.47	9.39	8.42
GPT-4V ZS+HTML (Ding, 2024)	50.54	41.66	42.64	49.82	72.83	45.73
GPT-4V ZS+History (Ding, 2024)	52.96	43.01	46.14	49.18	78.29	48.18
GPT-4o (Wu et al., 2024a)	55.02	47.06	49.12	52.30	80.28	46.42
MobileAgent (Wang et al., 2024b)	66.92	55.8	74.98	63.95	76.27	63.61
InternVL +History (Wu et al., 2024a)	2.63	1.95	2.88	2.94	3.03	2.71
Qwen-VL +History (Wu et al., 2024a)	3.23	2.71	4.11	4.02	3.89	2.58
PaLM-2 (Zhang and Zhang, 2023)	39.6	_	_	_	_	_
MM-Navigator (Yan et al., 2023)	50.54	41.66	42.64	49.82	72.83	45.73
MM-Navigator <sub>w/ text</sub> (Yan et al., 2023)	51.92	42.44	49.18	48.26	76.34	43.35
MM-Navigator <sub>w/ history</sub> (Yan et al., 2023)	52.96	43.01	46.14	49.18	78.29	48.18
OmniParser (Wan et al., 2024)	50.54	41.66	42.64	49.82	72.83	45.73
BC (Rawles et al., 2023)	68.7	_	_	_	_	_
BC <sub>w/history</sub> (Rawles et al., 2023)	73.1	63.7	77.5	75.7	80.3	68.5
Qwen-2-VL (Wang et al., 2024d)	67.20	61.40	71.80	62.60	73.70	66.70
Show-UI (Qinghong Lin et al., 2024)	70.00	63.90	72.50	69.70	77.50	66.60
Llama 2 (Zhang and Zhang, 2023)	28.40	28.56	35.18	30.99	27.35	19.92
Llama 2+Plan+Hist (Zhang and Zhang, 2023)	62.86	53.77	69.1	61.19	73.51	56.74
Auto-UI (Zhang and Zhang, 2023)	74.27	68.24	76.89	71.37	84.58	70.26
MobileVLM (Wu et al., 2024a)	74.94	69.58	79.87	74.72	81.24	71.70
SphAgent (Chai et al., 2024)	76.28	68.20	80.50	73.30	85.40	74.00
CoCo-LLAVA (Ma et al., 2024)	70.37	58.93	72.41	70.81	83.73	65.98
SeeClick (Cheng et al., 2024)	76.20	67.60	79.60	75.90	84.60	73.10
CogAgent (Hong et al., 2023)	76.88	65.38	78.86	74.95	93.49	71.73
CoCo-Agent (Ma et al., 2024) *	77.82	69.92	80.60	75.76	88.81	74.02

Table 3: Experimental results of different methods on static dataset AITW: Action accuracy across main setups, highlighting overall performance in decision-making tasks. The symbol \* indicates that CoCo-Agent incorporates layout information during training, while other models rely solely on image data.

Agent	<b>SR</b> ↑	$SE\downarrow$	Latency (s) $\downarrow$	Tokens $\downarrow$	FN Rate $\downarrow$	FP Rate ↓
AndroidArena (Xing et al., 2024)	0.22	1.13	18.61	750.47	0.09	0.33
AutoDroid (Wen et al., 2024)	0.27	3.10	4.85	963.48	0.93	0.01
AppAgent (Yang et al., 2023)	0.40	1.29	26.09	1505.09	0.17	0.40
CogAgent (Hong et al., 2023)	0.08	2.42	6.76	579.84	1.00	0.04
MobileAgent (Ding, 2024)	0.26	1.33	15.91	1236.88	0.19	0.31

Table 4: Experimental results of different methods on simulation environment MobileAgentBench. SR (Success Rate), SE (System Error), Latency, Tokens, FN Rate (False Negative Rate), and FP Rate (False Positive Rate) are the metrics used for comparison.

Dataset	Templates	Attach	Task	Reward	Platform
Static Dataset					
WebSRC (Chen et al., 2021)	400k	HTML	Web	-	Windows
WebUI (Wu et al., 2023)	400k	HTML	Web	-	Windows
Mind2Web (Deng et al., 2024b)	2,350	HTML	Web	-	Windows
Ferret-UI (You et al., 2024)	120k	-	Apps	-	IOS
OmniAct (Kapoor et al., 2024)	9802	Ocr/Seg	Web	-	Windows
WebLINX (Roßner et al., 2020)	2,337	HTML	Web	-	Windows
ScreenAgent (Niu et al., 2024)	3005	HTML	Web	-	Windows
Interactive Environment					
WebShop (Yao et al., 2022a)	12k	-	Web	Product Attrs Match	Windows
WebArena (Zhou et al., 2023)	241	HTML	Web	url/text-match	Windows
VisualWebArena (Koh et al., 2024)	314	HTML	Web	url/text/image-match	Windows
Ferret-UI (You et al., 2024)	314	HTML	Web	url/text/image-match	Windows
OSWorld (Xie et al., 2024)	369	-	Web	Device/Cloud state	Linux

Table 5: Comparison of various platforms based on parallelization, templates, tasks per template, rewards, and supported platforms.

Method	Input Type	Training	Memory	Task	Multi-agents
Prompt-based Methods					
ReAct (Yao et al., 2022b)	Text	None	$\checkmark$	Web	×
MM-Navigator (Yan et al., 2023)	Image&Text	None	X	Apps+Web	×
MindAct (Deng et al., 2024b)	Text	None	$\checkmark$	Apps+Web	×
OmniAct (Kapoor et al., 2024)	Text	None	×	Apps+Web	×
Training-based Methods					
VUT (Li et al., 2021)	Image&Text	Pre-trained	X	Web	×
Spotlight (Li and Li, 2022)	Image&Text	Pre-trained	X	Web	×
ScreenAI (Baechler et al., 2024)	Image&Text	Pre-trained	X	Web	×
ScreenAgent (Niu et al., 2024)	Image&Text	Pre-trained	$\checkmark$	Web	×
SeeClick (Cheng et al., 2024)	Image&Text	Pre-trained	×	Web	×

Table 6: Comparison of Mobile Agents: A Detailed Overview of Input Types, Models, Training Methods, Memory Capabilities, Tasks, and Multi-agent Support. Web\* means synthesized web data.