Identifying Structure in the MIMIC ICU Dataset

Abstract

The MIMIC-III dataset, containing trajectories of 40,000 ICU patients, is one of the most popular datasets in machine learning for health space. However, there has been very little systematic exploration to understand what is the *natural* structure of these data—most analyses enforce some type of top-down clustering or embedding. We take a bottom-up approach, identifying consistent structures that are robust across a range of embedding choices. We identified two dominant structures sorted by either fraction-inspired oxygen or creatinine — both of which were validated as the key features by our clinical co-author. Our bottom-up approach in studying the macro-structure of a dataset can also be adapted for other datasets.

1 Introduction

Understanding the structure of clinical data can help us identify important insights in disease subtypes and process variation. Within medicine, clustering techniques have been applied to the diagnosis of breast cancer (Chen [2014]), Parkinson's disease (Polat [2012];Nilashi et al. [2016]), mental health and psychiatric disorders (Trevithick et al. [2015]), heart and diabetes diseases (Yilmaz et al. [2014]), among many others.

In this paper, we focus on understanding the natural structure of the MIMIC-III Intensive Care Units (ICU) electronic health record data set (Johnson et al. [2016]) via projection-based clustering methods. MIMIC-III contains timeseries of measures of 40,000 patients in the ICU. With 4,417 citations, it is one of the most commonly used data sets in machine learning and health. Thus, its structure is of inherent interest. However, to date, most works have imposed a top-down approach to finding structure—e.g. imposing a particular clustering method (Shea [2020]; Sharafoddini et al. [2021];Zhang et al. [2021]; Fang et al. [2020]) or creating a task-specific embedding (Beaulieu-Jones et al. [2018]; Galozy [2018]; Chaudhary et al. [2020]). They are heavily engineered in the sense that they often presume certain statistics (e.g. a mean, median, extreme values) and certain standardizations (e.g. based on laboratory reference ranges) are the right pre-processing. These studies often provide insights for their specific task but do not necessarily provide insight into the structure of the data overall.

In our work, we take the opposite approach: What structure in the MIMIC-III data is persistent across a range of processing choices? Specifically, we identify patterns that persist across a range of data standardizations and projection parameters (in the context of tSNE, UMAP). Within the range of our exploration, we find that the dominant structures found either by fraction inspired oxygen (Fi02) or by creatinine levels—both of which were validated as key patient features by our clinical co-author and are known to be relevant for mortality and readmission predictions. More generally, we found a much greater sensitivity to standardization approaches than projection parameters. Our work provides both important insights about the MIMIC-III data set and suggests ways to identify robust structure in other clinical data sets.

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2 Methods

Our MIMIC-III cohort is the first 48 hours of seven commonly measured features of each of 10,184 patients: The features are heart rate, respiratory rate, creatinine, hematocrit, fraction inspired oxygen, sodium and mean blood pressure. When seeking structure, we explored the effect of (a) different ways to standardize the data and (b) different projection parameters. We identified commonalities between the induced embeddings for further inspection.

2.1 Description of Different Standardization Methods

Different features have different natural ranges and variation. For example, heart rate normally varies between 60 and 100; respiratory rate varies between 12 and 18. Thus, decisions have to be made regarding how to standardize the data. For each feature d, we consider standardizations of the form:

$$z_d = f((x_d - x_{d,\min})/(x_{d,\max} - x_{d,\min})), \tag{1}$$

For the values of $x_{d,\min}$ and $x_{d,\max}$, we randomly sample values between *valid* values—a range that feasibly exists in the human physiology—and *normal* values—a range that that is normal for healthy outpatients, but not necessarily normal or safe for ICU patients. These values are in Table 1. We consider two forms for f: *continuous*, that is, $f(x) = x$, or *discrete*, that is $f(x) = -1$ if $x < 0$; $f(x) = 1$ if $x \in [0, 1]$, and $f(x) = 1$ if $x > 0$. Finally, we include the "standard" standardization $z_d = (x_d - \bar{x}_d)/\sigma_{x,d}$ based on the feature's mean and variance.

2.2 Description of Different Projection Parameters

We consider two types of projections, t-Stochastic Neighbor Embedding, t-SNE, (Van der Maaten and Hinton [2008]) and Uniform manifold approximation and projection, UMAP, (McInnes et al. [2018]). For t-SNE, the different parameter we explored was perplexity, where we tested `perplexity =` $\{5, 30, 50, 80\}$. For UMAP, the different parameters we explored were `min_dist` and `n_neighbors`, where we tested `n_neighbors =` $\{5, 15, 50, 100\}$ and `min_dist =` $\{0.1, 0.25, 0.5, 0.99\}$. (Note: we also explored using PCA, but the linear projection did not reveal substructure in the data—see Appendix Figure 5.)

2.3 Embedding Similarity Metric

Each standardization and choice of parameters in projection resulted in an embedding of the data set in a two dimensional space. To compare the similarities between the embeddings, we tested a total of 42 different parameters: 5 discrete randomized ranges and 5 continuous randomized range for both t-SNE and UMAP, where randomized clinical range is scaled with $e \sim \text{Unif}(0,1)$ from valid range and normal range, with the detailed formula in Appendix A, UMAP `n_neighbors = 5, 30, 50, 80` UMAP `min_dist = 0.1, 0.25, 0.5, 0.99` and t-SNE `perplexity = 5, 15, 50, 100` for both continuous and discrete range, resulted in a total of $10 + 10 + 3 \times (16) = 42$ different methods tested. For each of the methods, we compare the labeling that we get for each method of standardization and metrics, and compute a similarity matrix between them (put simply: How many points stay at the same clusters comparing two different methods). We visualize the similarity matrix with a heat map for clarity.

3 Results

Across the different standardization and projection parameters, we find two major structures.

Figure 7 shows the similarities between the embeddings across the different standardization and projection approaches. We see that embeddings cluster into two main groups, distinguished by

- Fraction Inspired Oxygen, for the data that are continuously standardized with valid range or randomized continuous range
- Creatinine, for the data that is only discretely standardized against the normal range

(a) Continuous-Normal   (b) Continuous-Valid   (c) Discrete-Normal   (d) Discrete-Valid   (e) Standard Scaling

Figure 1: UMAP Projections for different standardization schemes. The Continuous-Valid and Discrete-Normal schemes have separable clusters (colored in red and blue). The Continuous-Normal and Continuous-Standard Scaled schemes have interesting substructures but no clear clustering. The choice of feature range for standardization has important effects on the structure of the resulting projections.

(a) FiO2 Timeseries   (b) Creatinine Timeseries

Figure 2: Timeseries for different clusters for UMAP

Examples of projections from each group are given in Figures 1b and 1c, as well as the associated timeseries. For embedding that shows interesting structures and visually identifiable clusters, we aim to uncover the important features that result in the particular structure. Statistically, we observed that for the Continuous-Normal scheme, we observe that cluster 1 (the small blue cluster identified in Figure 1b and 6b) has a mean and median Fi02 = 0.21 across 24 hours while the other clusters have FiO2 values maintained at a mean of 0.8 and a median of 0.6 for the first 5 hours at maintained at a mean and median of 0.5 after the 5th hour, as shown in the Figure 2a. For the Discrete-Normal scheme, we observe that cluster 1 (the small blue cluster identified in Figures 1c and 6c) a mean and median creatinine≈ 0.8mg/dL across 48 hours while cluster 2 has creatinine > 0.8mg/dL across 48 hours, as shown in the Figure 2b.

Separation Based on Features We further validated our result using the simple Decision Tree Classifier to probe whether there are simple human-understandable rules that can be inferred from this structure that may reliably predict whether a datapoint may lie in a particular cluster. We observe that a single-layer decision tree is sufficient to find a distinguishing feature between the cluster that cleanly separates more than 97% of the points inside a cluster.

The decision tree result can be found in Figure 3. For both cases where we observe identifiable clusters, we find a decisive feature that separates the clusters and is consistent with the statistical analysis. For the Continuous-Valid scheme, the most important feature for cluster separation is Fraction-Inspired Oxygen at hour 10, the decisive value being 0.24 and for the Discrete-Normal scheme, it is Creatinine at hours 20, with the decisive value being 1.35 mg/dL. For the Continuous-Valid scheme, it is clear that patients with lower values of FiO2 are in the one small cluster, with the other cluster having larger values.

```
|--- fraction_inspired_oxygen10 <= 0.24          |--- creatinine21 <= 0.50
|   |--- class: 1                                |   |--- creatinine17 <= 0.50
|--- fraction_inspired_oxygen10 >  0.24          |   |   |--- class: 2
|   |--- fraction_inspired_oxygen16 <= 0.27      |   |--- creatinine17 >  0.50
|   |   |--- heart_rate8 <= 91.50                |   |   |--- class: 1
|   |   |   |--- class: 2                        |--- creatinine21 >  0.50
|   |   |--- heart_rate8 >  91.50                |   |--- creatinine30 <= 0.50
|   |   |   |--- class: 1                        |   |   |--- class: 1
|   |--- fraction_inspired_oxygen16 >  0.27      |   |--- creatinine30 >  0.50
|   |   |--- class: 2                            |   |   |--- class: 1
```

Figure 3: Decision Tree Output: The first level features important for separating clusters are clinically relevant in early stages of treatment

Effect of Standardization Methods on Distribution We further investigated why different standardization methods give rise to different clustering and strucutre by investigating the distribution plot for the identified feature. From Figure 4, we observed that the standardization methods that produce meaningful result are those capture the distribution of the original data closely.

(a) Fraction Inspired Oxygen at hour 10   (b) Creatinine at hour 20

Figure 4: Effect of Standardization on Distribution of important features: methods that closely capture the distribution of the original data produce meaningful results

Clinical Relevance of Features In the critical care setting, Fraction Inspire Oxygen (Fi02) describes the population of patients that are on/off respirators, with patients on respirators having higher FiO2. Creatinine, an important feature about kidney function, has been identified by the medical domain expert to be crucial for physicians' clinical decisions in the early stages of patients' treatment outcomes.

The "Typical" Ways To Standardize Lead to Very Different Projections. Critically ill patients have numerous laboratory abnormalities. The laboratory reference intervals that define normal values established by sampling healthy outpatients might not provide insights. While we checked for robust patterns across a different range of choices as well as across different models, we found out that the typical ways of standardizing, which is based on feature's mean-variance, as well as standardizing against normal ranges, resulted in the loss of structure in the projection, as shown in figure 1e, 1a, 6e, 6a. Hence, future research should be more careful in selecting a clinical range to standardize against.

4 Conclusion

In this work, we identified that across seven different combinations of ways to standardize and project the MIMIC-III data, two key structures emerged, one dependent on fraction-inspired oxygen and one dependent on creatinine. While we explored the effect of standardizations in depth, there are additional directions one could explore to identify if other key structures exist. In particular, we always assumed that timesteps aligned in the 48-hour timeseries. Future work could more closely relate outcomes to the topologies we discovered, further explore the substructures in our projections, and explore ways beyond standardization to compare different patient timeseries.

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A Appendix

A.1 Data

In this study, we used data from the Medical Information Mart for Intensive Care (MIMIC-III)
database, which is a large, freely available database comprising de-identified health-related data
associated with over forty thousand patients who stayed in critical care units at Beth Israel Deaconess
Medical Center in Boston, Massachusetts between 2001 and 2012. (Johnson et al. [2016]). For our
study, we sample from the MIMIC-III dataset based on the following criteria:

- Patients with minimum 48 hours of records;
- Patients with age over 18 years old;
- Patients with complete age, gender, ethnicity group, insurance, readmission, and mortality
  record

A total of 10,184 patients fit the criteria and are considered. For each of the patients in the selected
cohort, we have further selected seven laboratory test measurements for their first 48 hours in the ICU.
These 7 clinical features are a key indicator of important organ functions and have been commonly
mentioned in previous research in the ICU. These clinical features are respiratory rate, heart rate,
mean blood pressure, sodium, creatinine, fraction inspired oxygen, and hematocrit (Fialho et al.
[2012]Curto et al. [2016]Desautels et al. [2017]).

For each feature, we record its value at each hour at the patients' first 48 hours admission to the ICU.
If a value is not found, we carry forward the value from the hour before. To minimize model variance
in our study, we also remove the patients with outliers values, which are values that are physically
impossible to achieve by human standards, as shown in Table 1. All in all, we get a data-frame that
has a dimension of $10,184 \times 322$.

Vitals	Valid Low	Valid High	Normal Low	Normal High	Ourlier Low	Outlier High
Heart Rate	0	350	60	100	0.0	390.0
Respiratory Rate	0	300	12	18	0.0	330.0
Creatinine	0.10	60	0.59	1.35	0.0	66.0
Hematocrit	0	75	37	52	0.0	100.0
Fraction Inspired Oxygen	0.21	1.00	0.21	0.5	0.2	1.1
Mean Blood Pressure	14	330	70	100	0.0	375.0
Sodium	50	225	135	145	0.0	250.0

Table 1: Valid and Normal clinical laboratory values for different features.

A.2 An Deeper view on Methodology

Projection Based Dimensionality Reduction Algorithm

For high-dimensional datasets, finding global structure directly is difficult as in high-dimensional, the
curse of dimensionality applies, where there is a loss of meaningful differentiation between similar
and dissimilar objects observed. Dimension reduction techniques reduce the dimension of the input
space to facilitate finding structures in the data. A novel method for improving structure finding in
the high-dimensional dataset is using projection-based clustering. A projection is used as a method
for visualizing high-dimensional data in 2D space such that the distance and the density of the data
are captured. One approach is to use projections as conventional methods of dimensionality reduction
for information visualization in order to transform high-dimensional data into low-dimensional
space (Venna et al. [2010]). Thus, in our paper, we experimented with 3 unsupervised dimension

reduction techniques, namely Principal Component Analysis (PCA), t-distributed stochastic neighbor embedding (t-SNE), and Uniform Manifold Approximation and Projection (UMAP). We projected our data to two-dimensional, which resulted in a scatter plot that we can analyze. Scatter plots generated by a projection method remain the state-of-the-art approach in cluster analysis to visualize data structures. (e.g., Mirkin [2005]; Ritter [2014]; Hennig et al. [2015]). We will discuss each of the dimension reduction techniques mentioned above below.

PCA is the oldest and most commonly used linear projection technique that reduces the dimensions of the data. PCA works by dropping the least important variables and preserving the most valuable variables, projecting them onto a two-dimensional space. However, for very high dimensional data, PCA may fail to find interesting structures and patterns. This is because since all linear projections are orthonormal rotations of the data coordinates, clusters that are linear nonseparable entanglements, such as the Chainlink data (Ultsch [1995]) or overlapping convex hulls, cannot be separated. With this type of projection, it is unavoidable that at some locations remote data are erroneously superimposed in the output space.

In such cases, non-linear stochastic methods like t-SNE and UMAP are particularly beneficial. t-SNE uses points in high-dimensional space to find a faithful representation of those points in a lower-dimensional space. The algorithm is non-linear and adapts to the underlying data, performing different transformations on different regions. t-SNE however suffers from limitations such as loss of large-scale information (the inter-cluster relationships), slow computation time and inability to meaningfully represent very large datasets (van Unen et al. [2016]). UMAP, created by McInnes and Healy (McInnes et al. [2018]), uses the data to construct the initial high-dimensional weighted graph with the nearest neighboring points in a local region. Compared to t-SNE it preserves as much of the local and more of the global data structure, with a shorter runtime.

A.3 Testing Persistency of Clustering

Once clusters are identified, we want to know how persistent the clusterings identified are across different methods and parameters. Borrowing ideas from persistent homology, we test how sensitive are these clusters toward the clinical range identified in Table 1, as well as towards different model hyperparameters.

Randomized Clinical Range

To test how the role that the predefined clinical range in Table 1, we defined a randomized clinical range, where we scale the clinical range with $e \sim Unif(0,1)$ as follows:

$$x_{\text{min-random}} = x_{\text{min-valid}} + e(x_{\text{min-normal}} - x_{\text{min-valid}}) \tag{2}$$

$$x_{\text{max-random}} = x_{\text{max-normal}} + e(x_{\text{max-valid}} - x_{\text{max-normal}}), \tag{3}$$

where the values for min-normal, max-normal, min-valid and max-valid can be found in 1 above. With the above range, we redefine continuous and discrete standardization methods with the randomized clinical range as follows:

- **Continuous Randomized:** Continuously standardized against randomized range, defined in equation (1) & (2) in a continuous manner where

$$z = (x - x_{\text{min-random}})/(x_{\text{max-random}} - x_{\text{min-random}}),$$

- **Discrete Randomized:** Discretely standardized against randomized range, defined in equation (1) & (2):

$$f(x) = \begin{cases} -1, & \text{for } x < x_{\text{min-random}} \\ 0, & \text{for } x_{\text{min-random}} \leq x \leq x_{\text{max-random}} \\ 1, & \text{for } x > x_{\text{max-random}} \end{cases}$$

Model Parameters

Previous works on projections using nonlinear and stochastic methods show that they are sensitive to the hyperparameters of the techniques (Wattenberg et al. [2016]). Therefore, we tested against different model hyperparameters across different ranges to check how they affect the projections. Namely,

- UMAP `n_neighbors`: UMAP `n_neighbors` parameters investigate local versus global structure in the data. A small `n_neighbors` will force the algorithm to concentrate on very local structure, and a larger `n_neighbors` will cover broader structure of the data. In our case, we tested `n_neighbors` = $\{5, 15, 50, 100\}$
- UMAP `min_dist`: UMAP `min_dist` affects how tightly points are allow to pack together. A lower `min_dist` will allow us to have clumpier embeddings, which lead us to discover finer topological structure, whereas a higher `min_dist` provides a global view. In our case, we tested `min_dist` = $\{0.1, 0.25, 0.5, 0.99\}$
- TSNE `perplexity`: TSNE `perplexity` balance attention between local and global structure, and different in `perplexity` values have found to produce different clusterings (Wattenberg et al. [2016]). In our paper, we tested `perplexity` = $\{5, 30, 50, 80\}$

Once we identified the standardization methods and model parameters to test against to ensure the consistency of the structure identified, we combine them to test the consistency. Namely, we tested a total of 42 different parameters: 5 discrete randomized ranges and 5 continuous randomized range for both t-SNE and UMAP, UMAP `n_neighbors` = 5, 30, 50, 80 UMAP `min_dist` = 0.1, 0.25, 0.5, 0.99 and t-SNE `perplexity` = 5, 15, 50, 100 for both continuous and discrete range, resulted in a total of $10 + 10 + 3 * (16) = 42$ different methods tested. For each of the methods, we compare the labeling that we get for each method of standardization and metrics, and compute a similarity matrix between them (put simply: How many points stay at the same clusters comparing two different methods). We visualize the similarity matrix with a heat map.

A.4 Additional Results

Figure 5: PCA Projections for Continuous Valid Scheme,
other schemes result in qualitatively similar plots

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(a) Continuous-Normal	(b) Continuous-Valid	(c) Discrete-Normal	(d) Discrete-Valid	(e) Continuous Standard Scaled

Figure 6: TSNE Projections for different standardization schemes

Figure 7: Heatmap: Continuous ranges are more robust tha discrete raanges