COLLAPSE BY CONDITIONING: TRAINING CLASS-CONDITIONAL GANS WITH LIMITED DATA

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ABSTRACT

Class-conditioning offers a direct means of controlling a Generative Adversarial Network (GAN) based on a discrete input variable. While necessary in many applications, the additional information provided by the class labels could even be expected to benefit the training of the GAN itself. Contrary to this belief, we observe that class-conditioning causes mode collapse in limited data settings, where unconditional learning leads to satisfactory generative ability. Motivated by this observation, we propose a training strategy for conditional GANs (cGANs) that effectively prevents the observed mode-collapse by leveraging unconditional learning. Our training strategy starts with an unconditional GAN and gradually injects conditional information into the generator and the objective function. The proposed method for training cGANs with limited data results not only in stable training but also in generating high-quality images, thanks to the early-stage exploitation of the shared information across classes. We analyze the aforementioned mode collapse problem in comprehensive experiments on four datasets. Our approach demonstrates outstanding results compared with state-of-the-art methods and established baselines.

1 INTRODUCTION

Since the introduction of generative adversarial networks (GANs) by Goodfellow et al. (2014), there has been a substantial progress in realistic image and video generations. The contents of such generations are often controlled by conditioning the process by means of conditional GANs (cGANS) (Mirza & Osindero, 2014). In practice, cGANs are of high interest, as they can generate and control a wide variety of outputs using a single model. Some example applications of cGANs include; category-conditioned generation (Brock et al., 2018), image manipulation (Yu et al., 2018), image-to-image translation (Zhu et al., 2017), and text-to-image generation (Xu et al., 2018).

Despite the remarkable success, training cGANs requires large training data, including conditioning labels, for realistic generation and stable training behavior (Tseng et al., 2021). Collecting large enough data is challenging in many frequent scenarios, due to the privacy, the quality and the diversity required, among other reasons. This difficulty is often worsened further for datasets for conditional training, where also labels need to be collected. The case of fine-grained conditioning adds an additional challenge for data collection, since the availability of the data samples and their variability are expected to deteriorate with the increasingly fine-grained details (Gupta et al., 2019).

While training GANs with limited data has recently received some attention (Karras et al., 2020a; Wang et al., 2018; Tseng et al., 2021), the influence of conditioning in this setting remains unexplored. Compared to the unconditional case, the conditional information provides additional supervision and input to the generator. Intuitively, this additional information can guide the generation process better and ensure the success of cGANs whenever its unconditional counterpart succeeds. In fact, one may even argue that the additional supervision by conditioning can even alleviate the problem of limited data, to an extent. Surprisingly however, we observe an opposite effect (to our preliminary intuition) in our experiments for class-conditional GANs. As visualized in Fig. 1, the conditional GAN trained on limited data suffers from severe mode collapse. Its unconditional counterpart, on the other hand, trained on the same data, is able to generate diverse images of high fidelity with stable training process. To our knowledge, these counter-intuitive observations of cGANs have not been observed or reported in previous works.

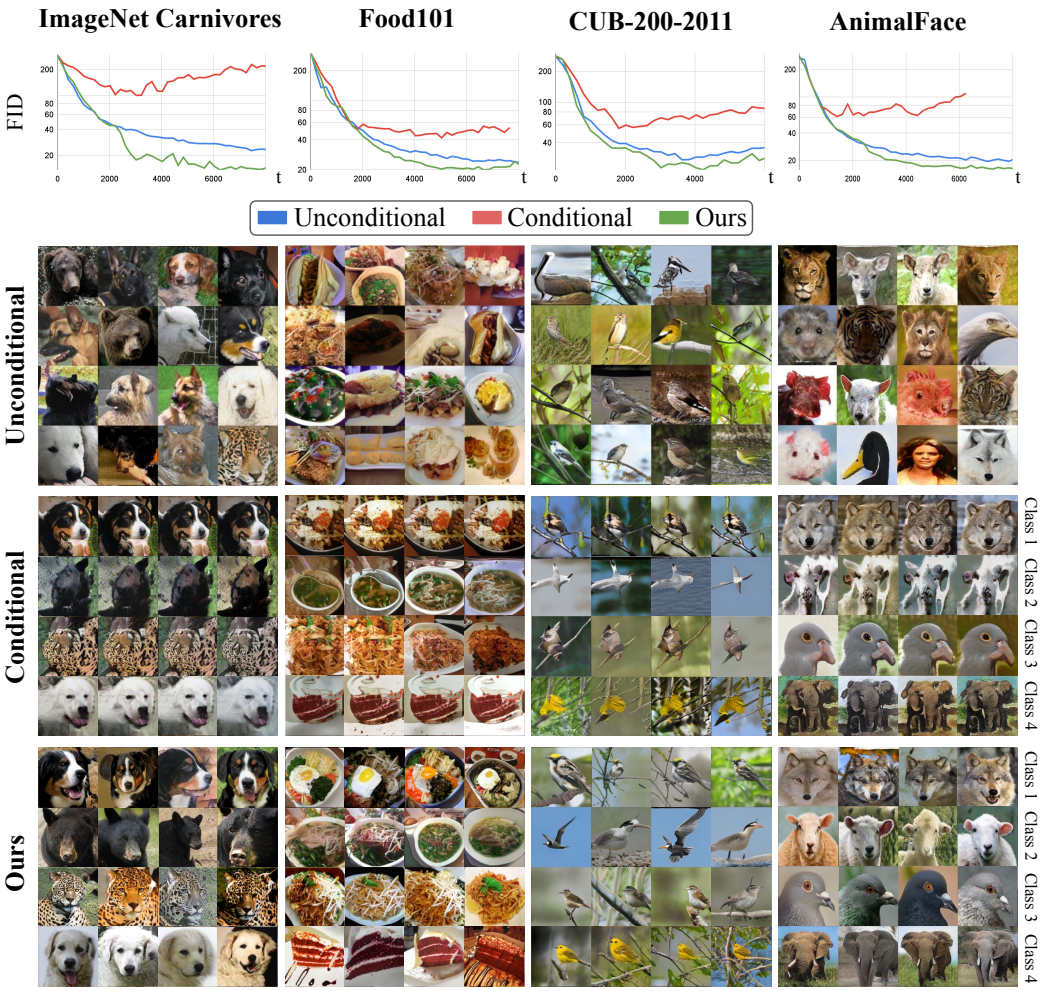


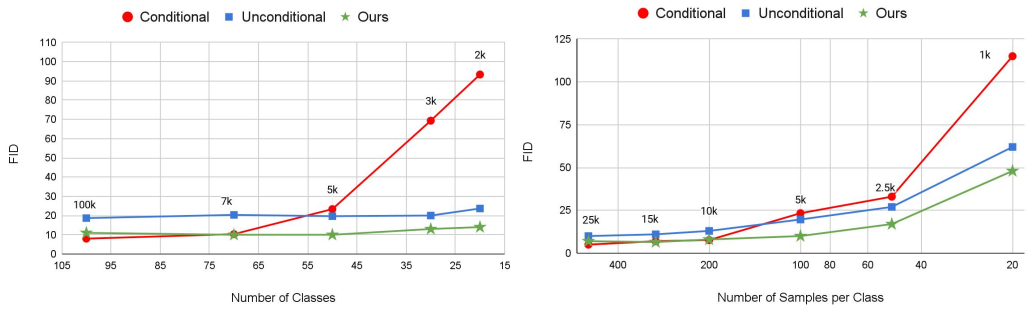
Figure 1: FID curves (first row) and sample images for training StyleGAN2+ADA unconditionally (second row), conditionally (third row), and using our method (fourth row) on four datasets under the limited-data setup (from left to right: ImageNet Carnivores, Food101, CUB-200-2011, and AnimalFace). The vertical axis of FID plots is in log scale for better visualization.

In this paper, we first study the behaviour of a state-of-the-art class-conditional GAN with varying number of classes and image samples per class, and contrast it to the unconditional case. Our study in the limited data regime reveals that the unconditional GANs compare favorable with conditional ones, in terms of generated image quality. We, however, are interested in the conditional case, so as to be able to control the image generation process using a single generative model. In this work, we therefore set out to mitigate the aforementioned mode collapse problem.

Motivated by our experimental observations, we propose a method for training cGANs that leverages the stable training of the unconditional GANs. During the training process, we integrate a gradual transition from unconditional to conditional generative learning. The early stage of the proposed training method favours the unconditional objective for the sake of stability, whereas the later stage favours the conditional objective for the desired control over the output by conditioning. Our transitional training procedure only requires minimal changes in existing state-of-the-art generator and discriminator architectures.

We demonstrate the advantage of the proposed method over the existing ones, by evaluating our method on four benchmark datasets under the limited data setups. The major contributions of this study are summarized as follows:

- We identify and characterize the problem of conditioning-induced mode collapse when training class-conditional GANs under limited data setups.
- We propose a training method for cGANs that exploits the training stability of unconditional GANs to mitigate the observed conditioning collapse.
- The effectiveness of the proposed method is demonstrated on four benchmark datasets. The method is shown to significantly outperform the state-of-the art and the compared baselines.



(a) (b)

Figure 2: The FID scores for different experiments on ImageNet Carnivores using unconditional, conditional, and our proposed training of StyleGAN2+ADA by varying (a) the number of classes (number of samples per class is fixed at 100) and (b) the number of images per class (the number of classes is fixed at 50). The total number of images of the experiments are shown on the data points. The horizontal axis in Fig. (b) is in log scale for better visualization.

2 Class-conditioning Mode Collapse

Learning conditional image generation networks is becoming an increasingly important task. The ability to control the generator is a fundamental feature in many applications. However, even in the context of unconditional GANs, previous studies suggest that class information as extra supervision can be used to improve the generated image quality (Salimans et al., 2016; Zhou et al., 2018; Kavalerov et al., 2020). This, in turn, may set an expectation that, the extra supervision by conditioning must not lead to the mode collapse of cGANs in setups where the unconditional GANs succeed. Furthermore, one may also expect to resolve the issue of training cGANs on limited data, to an extent, due to the availability of the additional conditional labels.

As the first part of our study, we investigate the effect of conditioning on GANs under the limited data setup. We base our experiments on StyleGAN2 with adaptive data augmentation (ADA), which is a recent state-of-the-art method for unconditional and class conditional image generation under limited-data setup (Karras et al., 2020a). Both unconditional and conditional versions of StyleGAN2 are trained on four benchmark datasets (more details in Section 4.1), with the setup of this paper. The selected datasets are somewhat of fine-grained in nature, where the problem of limited data, concerning their availability and labelling difficulty, is often expected to be encountered.

In Fig. 1, we analyze the training of conditional and unconditional GANs by plotting the Fréchet inception distance (FID) (Heusel et al., 2017) during training. The analysis is performed on four different datasets, each containing between 1170 and 2410 images for training. Contrary to our initial expectation, the conditional version obtains consistently worse FID during training, compared to the unconditional training. To analyze its cause, in Fig. 1 we also visualize samples from the best model attained during training in terms of FID. For each dataset, the unconditional model learns to generate diverse and realistic images, while lacking the ability to perform class-conditional generation. On the other hand, the conditional model suffers from severe mode collapse. Specifically, the intra-class variations are very small and mainly limited to color changes, while retaining the same structure and pose. Moreover, the images lack realism and contain pronounced artifacts.

Next, we further characterize the mode collapse problem observed in Fig. 1 by analyzing its dependence on the size of the training dataset. To this end, we employ the ImageNet Carnivores

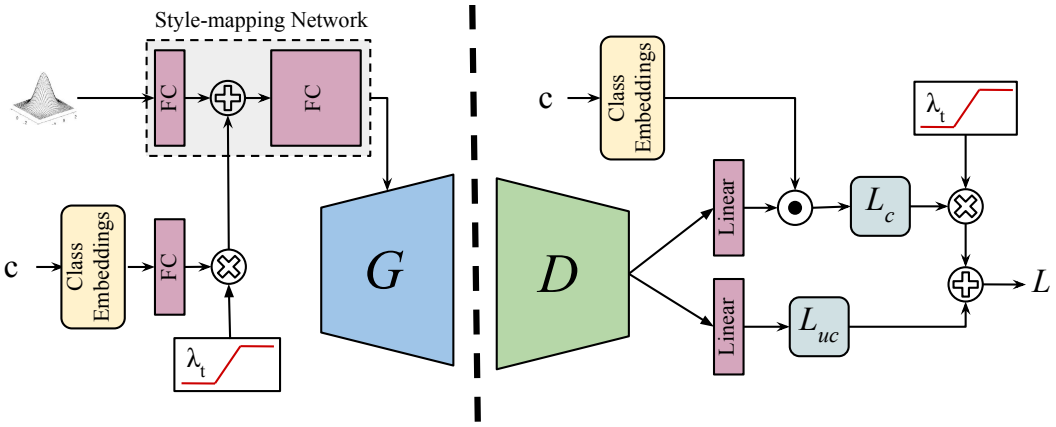


Figure 3: The proposed modified training objective and architecture of StyleGAN2 allows for transitioning from the unconditional to the conditional model during the training.

dataset (Liu et al., 2019), which includes a larger number of classes and images. We perform the analysis by gradually reducing the size of the training set in two ways. In Fig. 2a, we reduce the number of classes while keeping a number of 100 training images per class. In Fig. 2b, we reduce the number of images per class while using a 50 classes in all cases. In both cases, the conditional GAN achieves a better FID for larger datasets, here above 5k images. This observation is in line with previous work (Salimans et al., 2016; Zhou et al., 2018; Kavalerov et al., 2020). However, when reducing the dataset size, the order is inverted. Instead, the unconditional model achieves consistently better FID, while the conditional model degrades rapidly.

Inspired by these observations, we set out to design a training strategy for conditional GANs that eliminates the mode collapse induced by the conditioning itself. Our proposed approach, presented next, achieves stable training that attains low FID, as visualized in Fig. 1. The images generated from our model exhibit natural intra-class variations with substantial changes in pose, appearance, and color. Furthermore, our training strategy outperforms both the conditional and unconditional models in terms of FID in a wide range of dataset sizes, as shown in Fig. 2.

3 Method

3.1 From Unconditional to Conditional GANs

As the analysis in Section 2 reveals, conditional GAN training leads to mode collapse when training data is limited, while the unconditional counterpart achieves good performance for the same number of training samples. This discovery motivates us to design an approach capable of leveraging the advantages of unconditional training in order to prevent mode-collapse in conditional GANs. Our initial inspections of the generated images during conditional training indicated that the mode collapse appears from the very early stages of the training. On the contrary, the corresponding unconditional GAN learns to generate diverse images with gradually improved photo-realism during training. In order to avoid mode-collapse, we aim to exploit unconditional learning in the beginning of the training process. Unconditional training in early stages allows the GAN model to learn the distribution of the real images without the complications caused by conditioning. We then introduce the conditioning in the later stages of the training. This allows the network to adapt to conditional generation in a more stable way, by exploiting the partially learned data manifold.

In general, we control the transition between unconditional and conditional generative learning during the training process with a function $\lambda_t \geq 0$. The subscript t denotes the iteration number during training. Specifically, a zero value $\lambda_t = 0$ implies a purely unconditional learning, i.e. the conditional information does not affect the generator or discriminator networks. Our goal is to design a training strategy capable of gradually incorporating conditioning during training by increasing the value of λ_t. While any monotonically increasing function λ_t may be chosen, we only consider a

simple linear transition from 0 to 1 as,

$$\lambda_t = \min\left(\max\left(\frac{t - T_s}{T_e - T_s}, 0\right), 1\right) . \tag{1}$$

Here, T_s and T_e denote the start and end time steps of the transition, respectively.

We achieve the desired transition during training by introducing a method for controlling the behavior of the generator and discriminator using the function λ_t. An overview of our approach, detailed in next sections, is illustrated in Fig. 3.

3.2 Transition in the Generator

The generator $G(z)$ of a GAN is trained to map the latent vector z, drawn from a prior distribution $p(z)$, to a generated image $I_g = G(z)$ belonging to the distribution of the training data. A conditional generator $G(z, c)$ additionally receives the conditioning variable c as input, aiming to learn the image distribution of the training data conditioned on c.

The transition from an unconditional $G(z)$ to a conditional $G(z, c)$ generator seemingly requires a discrete architectural change during the training process. We circumvent this by additionally conditioning our generator on the transition function λ_t as $G(z, c, \lambda_t)$. More specifically, we gradually incorporate conditional information during training by using a generator of the form,

$$G(z, c, \lambda_t) = G(S(z) + \lambda_t \cdot E(c)) . \tag{2}$$

Here, S and E are neural network modules that transform the latent and conditional vector respectively. In case of $\lambda_t = 0$, the conditional information is masked out, leading to a purely unconditional generator $G(S(z))$. During the transition step $T_s < t < T_e$, the importance of the conditional information is gradually increased during training.

To achieve the generator in equation 2, we perform a minimal modification to the class-conditional StyleGAN2 (Karras et al., 2020b) baseline. The generator consist of a style-mapping network and an image synthesis network. The style-mapping network maps the input latent vector z and the embedding of the condition c to the intermediate representation w, known as style code. The image synthesis network, then generates images from the style codes. As illustrated in Fig. 3, we modify the conditioning in the generator by feeding the class embeddings to a fully-connected layer, which is then weighted by λ_t before adding to the output of the style-mapping network's first layer.

3.3 Transition in the Training Objective

The unconditional and conditional GAN frameworks also differ in their training objectives. The latter objective assesses the realism of an image based on its conditioning variable. We propose using both unconditional and conditional objectives and follow the same transition as in the generator. Our proposed loss function includes the unconditional objective during the whole training. The conditional term, on the other hand, is weighted by the transition function λ_t. Our total objective is thus given by,

$$\begin{aligned} L^D &= L^D_{uc} + \lambda_t \cdot L^D_c , \\ L^G &= L^G_{uc} + \lambda_t \cdot L^G_c . \end{aligned} \tag{3}$$

Here, L^D_{uc}, L^D_c, and L^D are the unconditional, conditional, and the proposed losses for the discriminator respectively. Similarly, L^G_{uc}, L^G_c, and L^G represent the unconditional, conditional, and the proposed losses for the generator.

As the discriminator is responsible to predict the scores needed for calculating the loss, the proposed training objective requires also modifying the discriminator's architecture. In this regard, the necessary modification must provide both conditional and unconditional scores. We propose using two prediction branches, separately dedicated to conditional and unconditional cases, in the last layer of the discriminator, as shown in Fig. 3.

The proposed training objective and discriminator for StyleGAN2 are also visualized in Fig. 3. In the discriminator of StyleGAN2, conditioning is performed by matching the features of the input images with the target class embedding. In other words, the conditional discriminator assigns scores

to the input images by calculating the dot-product between the features of the input images and the embedding of the target class c. The proposed discriminator architecture bears some resemblance to the architecture of projection discriminators (Miyato & Koyama (2018)). In contrast to our approach, the projection discriminator aggregates the unconditional and conditional scores inside the discriminator before the loss function. Additionally, the projection discriminator does not perform any transition between the two scores.

4 EXPERIMENTS

In this section, we first provide the details of our experimental setup. Then, we present the quantitative and qualitative results of the proposed method, as well as the comparison with existing methods. Finally, we provide more ablation and analysis of different components of our method.

4.1 EXPERIMENT SETUP

Datasets: We use four datasets to evaluate our method: ImageNet Carnivores (Liu et al., 2019), CUB-200-2011 (Wah et al., 2011), Food101 (Bossard et al., 2014), and AnimalFace (Si & Zhu, 2011). To keep our experiments in the limited-data regime, we decrease the number of classes and images per class in some of these datasets using random sampling.

- *ImageNet Carnivores* is a subset of the ImageNet dataset (Deng et al., 2009), which contains 149 classes of carnivore animals. The images were processed by the authors to only contain the faces of the animals. We use a subset of the dataset with 20 classes and 100 images per class.
- *Food101* contains 101 different food categories, having a total amount of 101k images. We use a subset of the dataset with 20 classes and 100 images per class.
- *CUB-200-2011* contains 200 categories of different bird spices with only around 60 images per class. We use a subset of this dataset with 20 classes with all the images in each class.
- *AnimalFace*, similar to ImageNet Carnivores, is a dataset that contains images of animal faces. However, the animal in AnimalFace are not limited to carnivores. AnimalFace contains 20 classes with 2432 images in total. Since AnimalFace is already a small dataset, we do not further reduce its size.

Implementation details: We base our method on the official PyTorch implementation of StyleGAN2+ADA. The hyper-parameter selection for the base unconditional and conditional StyleGAN2 is performed automatically as provided in the official implementation. Training is done with a batch size of 64 spread over 4 GPUs. For the transition function we use $T_s = 2k$ and $T_e = 4k$.

Evaluation Metrics: We evaluate our method using Fréchet inception distance (FID) as the most-commonly used metric for measuring the similarity between the distribution of real and generated images. As FID can be biased when real data is small (Karras et al., 2020a), we also include kernel inception distance (KID) (Bińkowski et al., 2018) as a metric which is unbiased by design.

4.2 RESULTS AND COMPARISONS

To assess the efficacy of the proposed method, we provide a quantitative comparison with the well-established baselines and existing methods:

- *BigGAN+ADA (Brock et al., 2018)*: Achieving outstanding results on ImageNet, BigGAN has been widely used for class-conditional image generation (more details in Section 5). We use the implementation with ADA provided by (Kang & Park, 2020).
- *ContraGAN+ADA (Kang & Park, 2020)*: A class-conditional model based on BigGAN that ouperforms BigGAN in many setups using self-supervision in the discriminator (more details in Section 5). We use the implementation provided by the authors.
- *U-StyleGAN+ADA:* Unconditional training of StyleGAN2+ADA using the original unconditional architecture.
- *C-StyleGAN+ADA:* Conditional training of StyleGAN2+ADA using the original conditional architecture.
- *C-StyleGAN+ADA+projD:* Modified Conditional StyleGAN2+ADA by replacing the discriminator with projection discriminator (Miyato & Koyama, 2018).

- *C-StyleGAN+ADA+Lecam:* Regularizing C-StyleGAN2+ADA using Lecam regularizer, recently proposed by Tseng et al. (2021) for limited-data setup (more details in Section 5). The authors have suggested a hyper-parameter in the range of $[0.1, 0.5]$. As we did not observe a noticeable difference between different values in the suggested range, we set the hyper-parameter to 0.3 for all experiments.

Results are reported in Table 1. BigGAN and ContraGAN, even though coupled with ADA, struggle to achieve any good generation quality in our experiments. Conditional StyleGAN2 shows better results on three of the datasets compared to that of the other two conditional competitors. However, the FID and KID scores are still very high. As discussed before, C-StyleGAN is consistently outperformed by its unconditional counterpart. Replacing the StyleGAN2's discriminator with projection discriminator does not yield a noticeable advantage over the original architecture, as it brings improvements on two of the datasets, but degrades the performance on the other two. Adding Lecam regularization to the C-StyleGAN2 shows promising results, achieving good FID and KID scores on Food101 and AnimalFace. However, it still fails to achieve as good generation quality as the unconditional StyleGAN2. The FID and KID scores for the proposed method indicate significant and consistent advantage over all the compared methods in all four datasets. Our method is able to maintain a stable training and achieve better generation quality than both unconditional and conditional StyleGAN2. The FID curves during training along with example generated images using the

Table 1: Comparison of the proposed method with baselines and existing methods on four datasets in terms of FID and KID metrics.

Method	**Carnivores**		**Food101**		**CUB-200-2011**		**AnimalFace**	
	FID	KID	FID	KID	FID	KID	FID	KID
BigGAN+ADA	97	0.0665	111	0.0794	136	0.0860	90	0.0587
ContraGAN+ADA	97	0.0629	124	0.0961	137	0.0934	89	0.645
UC-StyleGAN2+ADA	23	0.0093	24	0.0071	27	0.0059	20	0.0048
C-StyleGAN2+ADA	100	0.0493	42	0.0135	55	0.0197	61	0.0107
C-StyleGAN2+ADA+ProjD	103	0.0503	32	0.0108	54	0.0182	71	0.0186
C-StyleGAN2+ADA+Lecam	62	0.0211	27	0.0086	37	0.0179	26	0.0042
Ours	**14**	**0.0021**	**20**	**0.0045**	**22**	**0.0032**	**16**	**0.0018**

proposed method are visualized in Fig. 1. FID curves indicate training dynamics as stable as the unconditional training, while achieving better FID. In addition, the generated images of our method are clearly of more diversity and quality compared to those of the standard conditional model, showing the advantage of the proposed method. The results in Fig. 2 further demonstrate a clear advantage of our method over a wide range of dataset sizes. Our approach maintains the performance of cGANs for larger datasets, while significantly outperforming the unconditional counterpart when data is more scarce. This shows that our method enables cGANs to use the additional information provided by the labels to achieve better generation quality without falling into any mode collapse induced by the conditioning.

4.3 Ablation and Analysis

In this section, we provide further ablation and analysis over different components of our method. First, we provide an ablation study containing four different variants:

- *No transition:* Training the modified architecture with the new objective, without any transition in the objective or the generator (equivalent to using an auxiliary unconditional loss term to train a conditional model).
- *Transition only in G:* Performing the transition only in the generator (Sec. 3.2), while the training objective is the summation of the unconditional and conditional term.
- *Transition only in Loss:* Performing the transition only in the training objective (Sec. 3.3), while the generator is fully conditional from the beginning.
- *Final method:* The final method with all the proposed components.

Table 2 presents the results of the ablation study on Food101 and ImageNet Carnivores. The *No transition* version yields poor results, showing that the mode collapse is not alleviated by only adding an auxiliary unconditional training objective. Adding the transition to the generator already brings significant improvement to the model. Having the transition only in the objective, on the other, does not lead to good results. To our initial surprise, this reveals that transitioning in the generator is a crucial part of the method. However, also having the transition in the objective in addition to that in the generator, corresponding to our final method, achieves the best results.

Table 2: Ablation study over different components of the proposed method, including the proposed architecture and objectives, as well as the transition in the generator and in the objective.

	Food101		ImageNet Carniv.	
Experiment	**FID**	**KID**	**FID**	**KID**
No transition	79	0.0300	110	0.0436
Transition only in G	25	0.0064	17	**0.0019**
Transition only in loss	80	0.0297	107	0.0539
Final method	**20**	**0.0045**	**14**	0.0021

Next, we analyze the impact of *when* the transition between unconditional and conditional learning is applied. The total transition time is fixed to $T_e - T_s = 2$k time steps. We then report the results on the Food101 and ImageNet Carnivores datasets for different starting times T_s in Table 3. Importantly, we notice a significantly worse results if the transition is started in the beginning of the training $T_s = 0$. This further supports the hypothesis that conditioning leads to mode collapse in the early stages of the training. By introducing conditional information in a later stage, good FID and KID numbers are obtained without being sensitive to the specific choice of T_s. In Table 4, we further independently analyze the transition end time T_e, while keeping $T_s = 2$k fixed. Again, our approach is not sensitive to its value. Our method does thus not require extensive hyper-parameter tuning.

Table 3: Analysing the importance of the transition starting time (T_s). The transition period is constant at $2k$ for all the experiments.

	Food101		ImageNet Carnivores	
Experiment	**FID**	**KID**	**FID**	**KID**
$T_s = 0$	24	0.0068	27	0.0075
$T_s = 1k$	22	0.0057	15	0.0023
$T_s = 2k$	20	0.0045	14	0.0021
$T_s = 4k$	21	0.0056	14	0.0021
$T_s = 6k$	23	0.0056	15	0.0028

Lastly, we visualize on evolution of the generated images and formation of classes during our training process. Fig 4 shows how different images generated from the unconditional phase of training on AnimalFace all start to evolve into different images of the class Panda. In addition to the formation of the classes, Fig. 4 also shows how the image quality continues to improve during and after the transition. In the Appendix, randomly generated images from all classes of all datasets are provided for more detailed assessment of the ability of the proposed method in conditional high-quality image generation.

Table 4: Analysing the importance of the transition ending time (T_e). The starting time (T_s) is constant at $2k$ for all the experiments.

	Food101		ImageNet Carnivores	
Experiment	**FID**	**KID**	**FID**	**KID**
$T_e = 3k$	21	0.0053	16	0.0032
$T_e = 4k$	20	0.0045	14	0.0021
$T_e = 5k$	23	0.0062	15	0.0029

5 Related Work

Class-conditional GANs: The first conditional GAN architecture, introduced by Mirza & Osindero (2014), incorporated conditioning by concatenating the condition variable to the input of the generator and the discriminator. AC-GAN (Odena et al., 2017) equipped the discriminator with an auxiliary classification task to ensure the conditional generation. cGAN with projection discriminator (Miyato & Koyama, 2018) replaced the two-headed discriminator of AC-GAN with a single-output discriminator that outputs the sum of the realism score and class score. The class score is calculated using the dot-product of the discriminator features and the target class embedding. The conditioning in the generator, on the other hand, is performed through the conditional batch normalization layers. Improving over cGAN with projection discriminator, BigGAN (Brock et al., 2018) was able to become the state-of-the-art cGAN on ImageNet dataset (Deng et al., 2009). Inspired by the recent progress in self-supervised learning, ContraGAN (Kang & Park, 2020) improved over BigGAN by exploiting an auxiliary self-supervised task in the discriminator for better image representation learning. StyleGAN (Karras et al., 2019), mainly known for unconditional image generation, was extended to

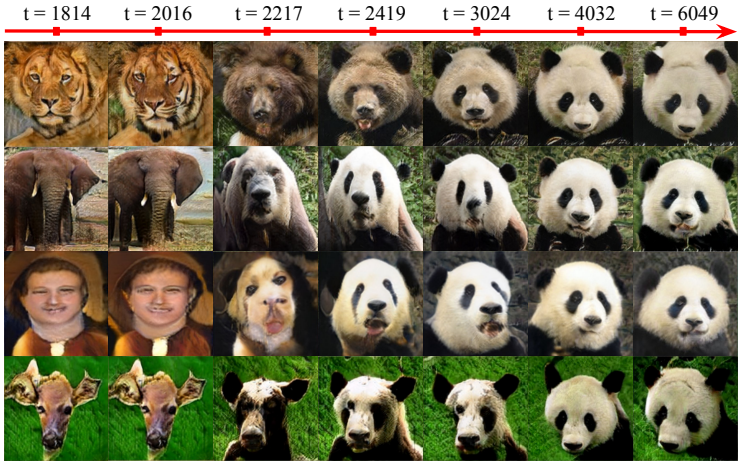


Figure 4: Visualization on the formation of the class "Panda" in AnimalFace during the transition from unconditional to conditional training. The transition starts at $t = 2k$.

class conditioning in the improved version, and coupled with adaptive differentiable augmentation, outperformed the state-of-the-art cGANs in small data setup (Karras et al., 2020a).

cGANs in small data regime: There are several directions for addressing the problem of training GANs on small datasets. Transfer learning is one of these directions that exploits a large pretraining dataset to provide a better initialization for learning the target data. In recent years several works have studied the best practices for performing transfer learning in GANs (Wang et al., 2018; 2020; Mo et al., 2020; Zhao et al., 2020a; Noguchi & Harada, 2019)). As an example of transfer learning in the context of conditional GANs, cGANTransfer (Shahbazi et al., 2021) proposed class-specific knowledge transfer from source dataset to the target by learning to combine the source class representations, which embedded as the parameters of the batch normalization layers. Although transfer learning is an effective technique for training GANs on small datasets, it usually requires access to a large pretraining dataset with sufficient domain relevance to the target data. Data augmentation is another technique for tackling the problem of small data. In order to avoid augmentations from leaking to the generated images, recent concurrent works proposed differentiable data augmentation Zhao et al. (2020b); Karras et al. (2020a). Including adaptive differentiable augmentation (ADA) as a part of StyleGAN2 resulted in a significant improvement in conditional image generation quality and training stability on small datasets, outperforming previous conditional GANs on cifar10 dataset (Karras et al., 2020a). In addition to the aforementioned techniques, there are other studies on GANs in small data regime focusing on better architecture or loss function design. Liu et al. (2021) proposed a lighter unconditional architecture for StyleGAN for faster training, as well as a self-supervised discriminator to increase the stability on fewer samples. As another approach, Tseng et al. (2021) proposed a regularization to prevent the discriminator from over-fitting in small-data setup by penalizing the difference between the predictions of the discriminator for current real images and those of previous generated images, as well as the difference between the predictions for current generated images and those of previous real images.

6 Conclusions

In this work, we studied the problem of training class-conditional Generative Adversarial Networks (cGANs) with limited data. Our empirical study demonstrated that class-conditioning can lead the training of GANs to mode-collapse within the investigated setup. To prevent from such collapse, we presented a method of injecting the class conditioning by transitioning from unconditional to conditional case, in an incremental manner. To enable such transition, we have proposed architectural modifications and training objects, which can be easily adapted by any existing GAN models. The proposed method achieves outstanding results when compared with the state-of-the-art methods and established baselines, for the limited data setup of four benchmark datasets. In future, we will test and study our method for the cases of conditioning beyond object classes (e.g. semantics).

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A APPENDIX

In the following, we provide more experiments and visualizations on the discovered observation and the proposed method.

A.1 STYLEGAN2 WITHOUT ADA

To investigate whether the appearance of the conditional collapse and efficacy of the proposed method in solving it is related to the adaptive differentiable augmentation (ADA), we perform an experiment on a subset of ImageNet carnivores (50 classes, 500 mages per class), without using ADA in the training. As the experiments show, the same observation happens in this setup in the absence of ADA, and our method is able to stabilize the training.

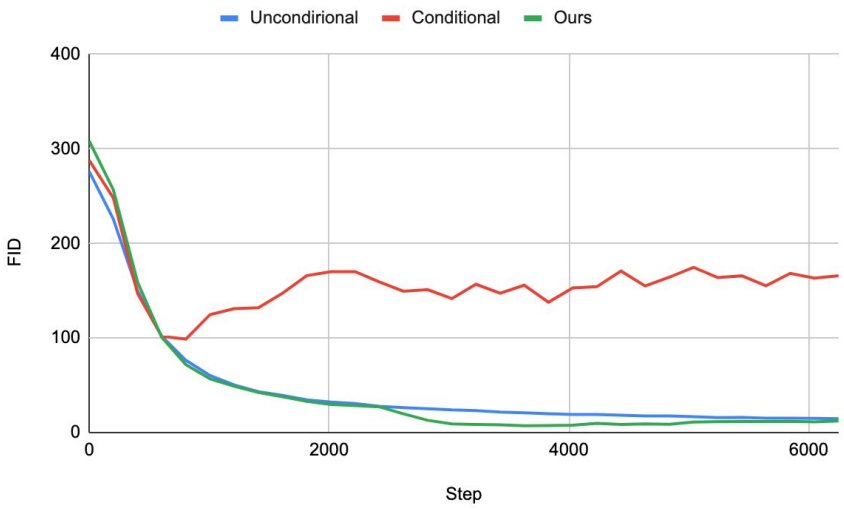

Figure 5: FID curves for training unconditional and conditional StyleGAN2, as well as our method, on ImageNet Carnivores with 50 classes and 500 images per class.

Table 5: The FID and KID scores for training unconditional and conditional StyleGAN2, as well as our method, without using ADA, on ImageNet Carnivores with 50 classes and 500 images per class.

Method	FID	KID
U-StyleGAN2	99	0.0795
C-StyleGAN2	13	0.0067
Ours	**8**	**0.0020**

A.2 EXPERIMENTS ON CIFAR100

In addition to the experiments on the four datasets presented in the paper, we provide the results of training unconditional and conditional StyleGAN2+ADA as well as our method on four different subsets of CIFAR100 (Krizhevsky (2009)) in Table 6. In Fig. 6, as an example, the FID curves of training the three methods on a subset of CIFAR100 with 100 classes and 300 images per class is visualized. We observe a similar behavior on CIFAR100, where our approach outperforms the conditional baseline, achieving FID and KID better or on-par with the unconditional baseline. .

Table 6: Quantitative results for examples of unconditional and conditional training of StyleGAN2+ADA, as well as our method, on different subsets of CIFAR100. In the name of the columns, C indicates the number of classes and S shows the number of images per class

Method	**C20, S500**		**C50, S50**		**C50, S300**		**C100, S300**	
	FID	KID	FID	KID	FID	KID	FID	KID
UC-StyleGAN+ADA	**7**	**0.0006**	**20**	0.0022	**6**	**0.0008**	**6**	0.0021
C-StyleGAN+ADA	12	0.0033	23	0.0036	9	0.0025	13	0.0053
Ours	**7**	**0.0006**	**20**	**0.0014**	**6**	**0.0008**	**6**	**0.0012**

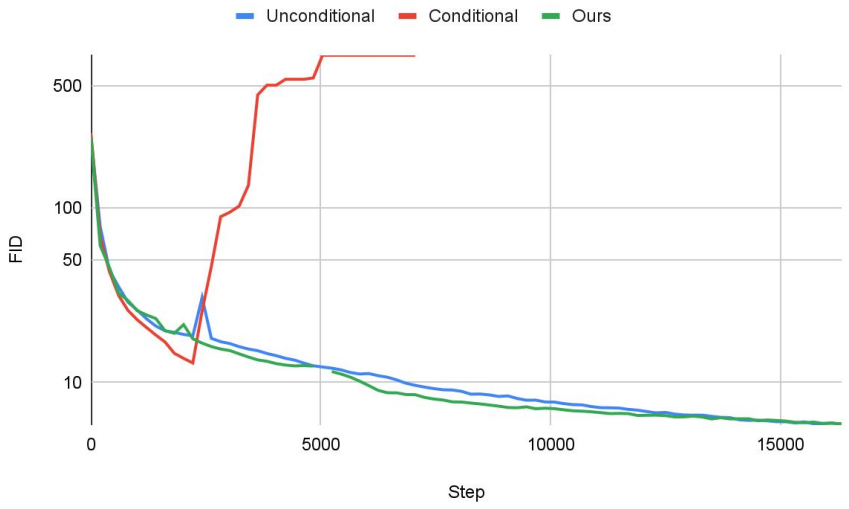

Figure 6: FID curves for training unconditional and conditional StyleGAN2, as well as our method, on CIFAR100 with 100 classes and 300 images per class. The vertical axis is in the log scale.

A.3 Class-wise FID and KID

Here, we provide the class-wise FID and KID for ImageNet Carnivores and Food101 datasets, using the full number of sample per class in calculating the metrics.

Table 7: The class-wise FID and KID for Imagenet Carnivores and Food101 using the full number of real samples per class in the evaluation.

Loss Formulation	**Carnivores**		**Food101**	
	FID	KID	FID	KID
C-StyleGAN+ADA	139	0.179	100	0.079
C-StyleGAN2+ADA+ProjD	151	0.199	97	0.0815
C-StyleGAN2+ADA+Lecam	90	0.096	56	0.027
Ours	**30**	**0.011**	**44**	**0.019**

A.4 Precision and Recall

In tables 8 and 9, we provide the unconditional and class-wise precision and recall metrics calculated for the compared methods

A.5 The Transition Function

In Fig. 7, we provide a detailed visualization of the proposed transition function.

Table 8: The unconditional precision and recall for the compared methods in the paper.

Method	**Carnivores**		**Food101**		**CUB-200-2011**		**AnimalFace**	
	Pr	Rl	Pr	Rl	Pr	Rl	Pr	Rl
UC-StyleGAN2+ADA	0.77	0.300	0.71	0.187	0.70	0.232	0.76	0.430
C-StyleGAN2+ADA	0.80	0.0008	0.74	0.004	**0.79**	0.002	0.78	0.032
C-StyleGAN2+ADA+ProjD	0.81	0.0	0.74	0.002	0.76	0.067	**0.83**	0.0
C-StyleGAN2+ADA+Lecam	0.81	0.046	0.73	0.004	0.76	0.097	**0.83**	0.0005
Ours	**0.82**	**0.263**	**0.82**	**0.068**	0.77	**0.229**	**0.83**	**0.314**

Table 9: The class-wise precision and recall for the compared methods on Imagenet Carnivores and Food101 using the full number of real samples per class in the evaluation..

Method	**Carnivores**		**Food101**	
	Pr	Rl	Pr	Rl
C-StyleGAN2+ADA	**0.75**	0.0	0.75	0
C-StyleGAN2+ADA+ProjD	0.68	0.0	**0.78**	0.00005
C-StyleGAN2+ADA+Lecam	0.67	0.0001	0.70	0.0148
Ours	0.73	**0.1205**	0.64	**0.1049**

A.6 Ablation on the transition in the loss function

In table 10, we provide the ablation over two choices for transition in the proposed loss function.

A.7 Visual Results

We provide more visual results for comparison of our method and the baselines in Fig. 8. Moreover, more generated images using our method on the four datasets are visualized in Figs. 9-12.

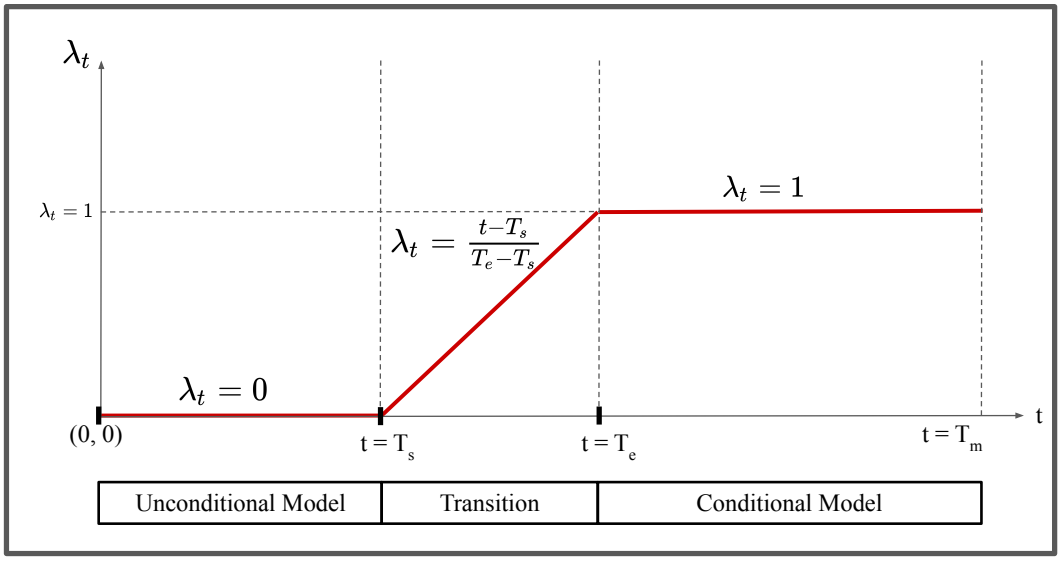

Figure 7: Visualization of the transition function λ_t. T_s, T_e, and T_m denote the start of the transition, the end time of the transition, and the end of training, respectively.

Table 10: The FID and KID results for two different loss formulations.

Loss Formulation	**Carnivores**		**Food101**		**CUB-200-2011**		**AnimalFace**	
	FID	KID	FID	KID	FID	KID	FID	KID
$L = (1 - \lambda_t) \cdot L_{uc} + \lambda_t \cdot L_c$	18	0.0047	25	0.0088	25	0.0064	20	0.0035
$L = L_{uc} + \lambda_t \cdot L_c$ (Ours)	**14**	**0.0021**	**20**	**0.0045**	**22**	**0.0032**	**16**	**0.0018**

Figure 8: Visual results for the compared methods on four datasets.

Figure 9: Generated images using the proposed method trained on ImageNet Carnivores dataset. Each row represents a different class. FID score is 14.

Figure 10: Generated images using the proposed method trained on Food101 dataset. Each row represents a different class. The FID score score is 20.

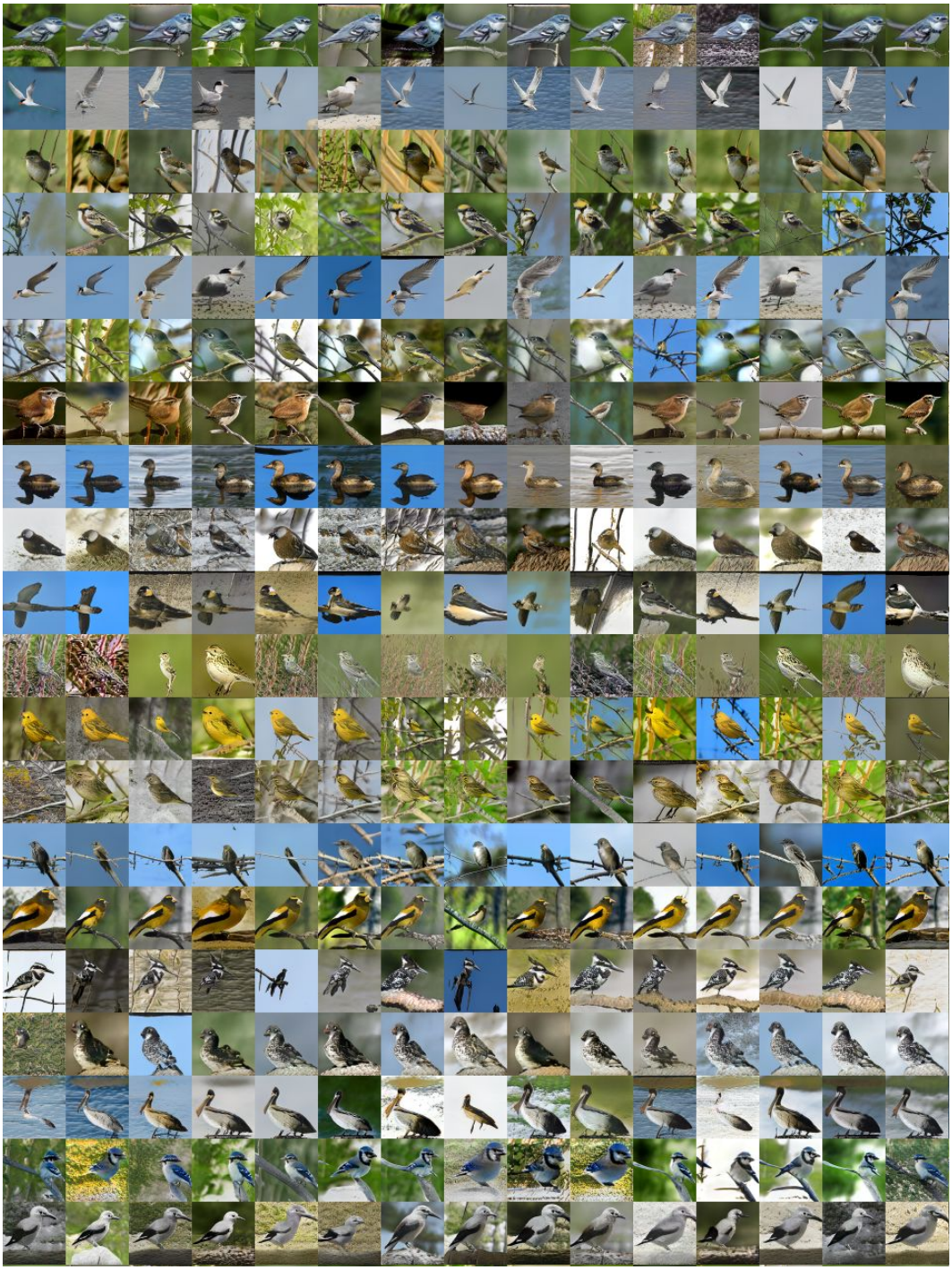

Figure 11: Generated images using the proposed method trained on CUB-200-2011 dataset. Each row represents a different class. The FID score is 22.

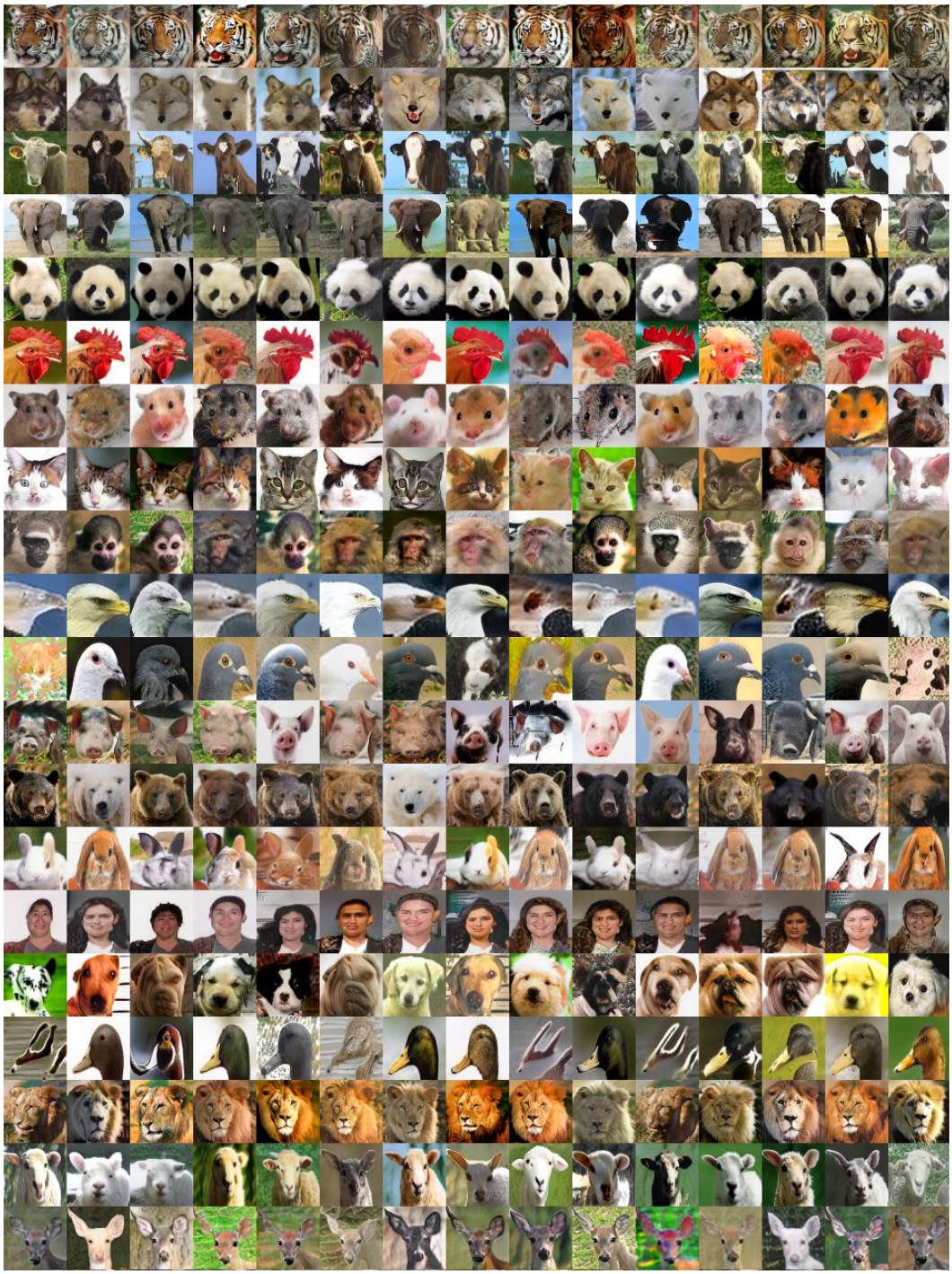

Figure 12: Generated images using the proposed method trained on AnimalFace dataset. Each row represents a different class. The FID score is 16.