GEOMETRY OF LONG-TAILED REPRESENTATION LEARNING: REBALANCING FEATURES FOR SKEWED DISTRIBUTIONS

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ABSTRACT

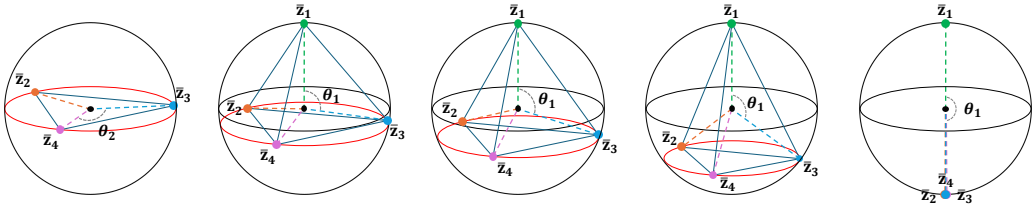
Deep learning has achieved significant success on balanced datasets. However, real-world data often exhibit a long-tailed distribution. Empirical results reveal that long-tailed data skew representations, where head classes dominate the feature space. Many methods have been proposed to empirically rectify the skewed representations. However, a clear understanding of the underlying cause and extent of this skew remains lacking. In this study, we provide a comprehensive theoretical analysis to elucidate how long-tailed data affect feature distributions, deriving the conditions under which centers of tail classes shrink together or even collapse into a single point. This results in overlapping feature distributions of tail classes, making features in the overlapping regions inseparable. Moreover, we demonstrate that merely empirically correcting the skewed representations of the training data is insufficient to separate the overlapping features due to distribution shifts between the training and real data. To address these challenges, we propose a novel long-tailed representation learning method, FeatRecon. It reconstructs the feature space to arrange features from different classes into symmetrical and linearly separable regions. This, in turn, enhances the model's robustness to long-tailed data. We validate the effectiveness of our method through extensive experiments on the CIFAR-10-LT, CIFAR-100-LT, ImageNet-LT, and iNaturalist 2018 datasets.

1 INTRODUCTION

Deep learning has achieved significant success on balanced datasets (Deng et al., 2009). However, in real-world scenarios, datasets often exhibit long-tailed distributions, characterized by highly imbalanced *class distribution* (i.e., the sample sizes of different classes). A few classes (called *head classes*) have a large number of samples, whereas many other classes (called *tail classes*) contain only a few samples. Training on such datasets distorts a model's feature representations and decision boundaries, limiting the model's generalization capability and performance on test data.

Our understanding of balanced data representation has advanced significantly. For example, using the powerful representation learning tool, *contrastive learning* (Khosla et al., 2020), it has been shown (Graf et al., 2021) that for balanced data, when the *supervised contrastive loss* (SC loss) reaches its minimum, the representations of each class converge at their respective class centers, and all class centers form a regular simplex (see Theorem 1 and Fig. 1a). This highly symmetrical configuration ensures separation among different classes, resulting in strong classification performance.

However, the optimal representation configuration for imbalanced data remains poorly understood. Empirical studies have revealed that, when data follow a long-tailed distribution, optimal representations form an asymmetrical configuration, with head classes dominating the feature space. Although several methods (Zhu et al., 2022; Kang et al., 2021; Li et al., 2022; Du et al., 2024) have attempted to correct this asymmetry, they primarily rely on empirical adjustments. Crucially, none of these methods provides a theoretical explanation of why and to what extent head classes dominate the feature space. Understanding this phenomenon could offer deeper insights into learning better representations of long-tailed data and inspire novel methods.



(a) $\rho = 0$ (b) $0 < \rho < 1$ (c) $\rho = 1$ (d) $1 < \rho < R$ (e) $\rho \geq R$

Figure 1: The geometry of the optimal representation configuration for four classes with different imbalance factors, ρ. Centers of the four classes ($\bar{z}_1, \ldots, \bar{z}_4$) are positioned on a unit hypersphere. Assume classes 2, 3 and 4 have the same size, $N_2 = N_3 = N_4$. Class 1's size is their size multiplied by ρ, $N_1 = \rho N_2$. **(a)**: when class 1 is empty ($N_1 = 0$), classes 2, 3 and 4 form a regular simplex. **(b) to (e)**: As ρ increases and N_1 increases, $\bar{z}_2$, $\bar{z}_3$ and $\bar{z}_4$ are pushed away from the equator and eventually collapse. **(c)**: when $\rho = 1$, all four classes form a regular simplex. R is the critical constant at which the collapse happens (see Sec. 3 for details). θ_1 is the angle between the head class center and tail class centers, and θ_2 is the angle between tail classes.

In this paper, we establish the first theoretical framework (in Theorem 2) to analyze the geometry of the optimal representation configuration, i.e., the arrangement of class centers when the SC loss is minimized, under various class distributions. In particular, we derive the analytical relationship between the imbalance factor, i.e., the ratio of sample sizes between head and tail classes, and the angles between different class centers at the optimal configuration. We show that as the imbalance factor increases, the head class increasingly dominates the feature space, pushing centers of the tail classes closer together. Beyond a certain critical threshold, centers of the tail classes collapse into a single point. Fig. 1 illustrates the optimal configuration of four classes. From Fig. 1a to Fig. 1e, as the imbalance factor continuously increases, the center of the head class ($\bar{z}_1$) pushes the other three tail classes' centers ($\bar{z}_2$, $\bar{z}_3$ and $\bar{z}_4$) closer and eventually collapse (Fig. 1e).[1]

Our theory provides insights into how long-tailed data hurts the representation learning. Without any mitigation strategy, tail classes are pushed close to one another or even collapse, resulting in overlapping distributions and poor separability between them. To address this issue, existing methods often readjust the empirical tail class centers to a symmetric configuration. However, due to the limited sample sizes of tail classes, these approaches may over-correct the issue, forcing the true centers of the tail classes to be too close to the head class, leading to overlapping distributions and poor separability between head and tail classes.

In this paper, we introduce **FeatRecon**, a novel method for long-tailed representation learning. It reconstructs the feature space such that features from different classes are arranged into symmetrical and linearly separable regions. Inspired by the theoretical analysis, our method addresses the center skewing issue by rebalancing the sample sizes of all classes. This is accomplished by generating synthetic features for tail classes and using both real and synthetic features for representation learning. To ensure linear separability, the synthetic features of each class are constrained within an estimated *confidence support*, i.e., the feature space region covering the majority of samples in that class. We derive the necessary conditions for the confidence supports to ensure they do not overlap at the optimal configuration.

The estimation of confidence support is crucial to our method. Direct estimation of the feature distribution is challenging due to the non-Euclidean geometry of the normalized feature space and the limited sample size of tail classes. Instead, we estimate the confidence support by using the center of each class and a single "central angle" parameter. Since the estimation for tail classes can be unreliable, the statistics of tail classes are regularized using those of head classes. By iteratively generating synthetic features to fill these confidence supports, adjusting representations, and re-estimating confidence supports, we can learn a feature space where both head and tail classes are equally separated, with no overlap between their confidence supports.

Our contributions are summarized as follows:

[1]For completeness, our analysis encompasses the cases when class 1's size, N_1, is smaller than the others'. Technically, class 1 is not the head class any more when $N_1 \leq N_2 = N_3 = N_3$.

- We study the geometry of long-tailed data representation and explain how long-tailed data skew representations and limit a model's generalization capability.
- We develop a novel algorithm to generate synthetic features to balance the sample sizes among all classes. The synthetic features are constrained within confidence supports which are estimated with head classes regularization.
- We propose an iterative approach to learn a symmetric and linearly separable feature space for long-tailed data. Our method iteratively generating synthetic features, adjusting representations, and re-estimating confidence support.

2 Related Work

2.1 Long-tailed Recognition

Resampling (Byrd & Lipton, 2019) and *re-weighting* (Cui et al., 2019; Jamal et al., 2020; Chen et al., 2023)are two classical methods in long-tailed learning. The former balances the number of training samples across different classes by either oversampling the tail classes or downsampling the head classes. The latter balances the per-class contributions to the loss function by assigning higher weights to classes with smaller gradients. Other methods adjust decision boundaries through either *post-hoc weight normalization* (Dang et al., 2024) or *margin adjustment* (Cao et al., 2019; Menon et al., 2021; Khan et al., 2019). The former adjusts the decision boundaries by modifying the weight norms of classifiers, while the latter increases the margins of the tail classes. Recent works also explore ideas in *data augmentation* (Ahn et al., 2023; Gao et al., 2024), which adjusts the strength of class-wise augmentation to help learn class-balanced representations, and *transfer learning* (Chen & Su, 2023; Zhang et al., 2023), which leverages information from the head classes to improve learning of the tail classes. A common way for transfer learning is to assume that data follow a multivariate Gaussian distribution and transfer distribution statistics. However, robust parameters estimation (i.e., the $K \times K$ covariance matrix) can be challenging given the small sample sizes of tail classes, and the distributional assumption does not hold for normalized features.

2.2 Contrastive Learning for Long-tailed Data

Contrastive learning (He et al., 2020; Chen et al., 2020; Caron et al., 2020; Chen & He, 2021; Grill et al., 2020; Wang & Isola, 2020) has made tremendous progress as a tool for representation learning. Supervised contrastive learning (SCL) (Khosla et al., 2020), by optimizing the supervised contrastive loss, learns a symmetrical feature space in which the representations of each class collapse to the vertices of a regular simplex. (Graf et al., 2021).

Recent studies in *long-tailed learning* (LTL) (Wang et al., 2021; Cui et al., 2021; Xuan & Zhang, 2024) incorporate an SCL module into the LTL framework, aiming to learn better representations and improve classifier training. However, directly using SCL is not ideal, as some (Li et al., 2022; Zhu et al., 2022) have demonstrated that SCL skews the feature space when training on long-tailed data. Many methods then focus on empirically readjusting these skewed representations. TCL (Li et al., 2022) addresses this by predefining well-separated empirical centers. Other methods rebalance the number of contrastive pairs in the SC loss, i.e, positive pairs (Kang et al., 2021), negative pairs (Zhu et al., 2022), or both positive and negative pairs (Du et al., 2024). Our method balances both positive and negative pairs by generating new features for the tail classes in hyperspherical caps. It involves estimating only two parameters, with tail class statistics regularized using those of the head classes.

3 Theoretical Analysis: Long-tailed Data Skew Contrastive Feature Representations

In this section, we study how long-tailed data skew the feature space. To understand how varying class distributions influence representations, we provide a theoretical framework (in Sec. 3.2) to investigate the optimal representation configuration when the SC loss is minimized (see Fig. 1).

We show (in Theorem 1), for balanced data, the optimal representations form a regular simplex. This reveals that representations of different classes are equally separated to the largest extent.

However, for imbalanced data, the optimal representation configuration becomes far more complex. Therefore, we focus on a one-vs-all scenario. We adjust the sample size of class 1, while assuming the remaining $K-1$ classes have equal and fixed sample size. In Theorem 2, we study the geometry of the optimal representation configuration when the imbalance factor changes.

3.1 Preliminaries

Suppose we have N training samples, $X=(x_1,\ldots,x_N)\in(\mathcal{X})^N$, randomly drawn from K distinct classes, with labels $Y=(y_1,\ldots,y_N)\in(\mathcal{Y})^N$ and $\mathcal{Y}=[K]=\{1,\ldots,K\}$. A unit hypersphere (in $\mathbb{R}^h$) is defined as $\mathbb{S}^{h-1}=\left\{z\in\mathbb{R}^h:\|z\|=1\right\}$. An encoder is a map $\varphi:\mathcal{X}\to\mathbb{R}^h$ that extracts representations from data, denoted as $Z=(\varphi(x_1),\ldots\varphi(x_N))$.

In practice, contrastive learning is conducted batch-wise due to memory limitations. To simplify our analysis, we assume unlimited memory to train on all samples in a single batch. We denote the set of indices of all samples as $B=[N]=\{1,\ldots,N\}$, and the set of indices of samples from the class k as $B_k=\{i:i\in B,y_i=k\}$. Let N_k be the number of samples from class k, $N_k=|B_k|$ and $N=\sum_{k=1}^K N_k$. The following definitions are necessary for the study.

Definition 1 (Supervised contrastive loss (SC loss))**.** *Let Z be an N point configuration (assuming all z's being normalized), $Z=(z_1,\ldots,z_N)\in(\mathbb{S}^{h-1})^N$, with labels $Y=(y_1,\ldots,y_N)\in([K])^N$, and $3\le K\le h+1$. The supervised contrastive loss $\mathcal{L}_{\mathrm{SC}}(\cdot;Y):(\mathbb{S}^{h-1})^N\to\mathbb{R}$ is defined as*

$$\mathcal{L}_{\mathrm{SC}}=\sum_{k=1}^{K}\sum_{i\in B_k}\mathcal{L}_{\mathrm{SC}}^{k,i},\ \textit{where}\ \mathcal{L}_{\mathrm{SC}}^{k,i}=-\frac{\mathbb{1}_{\{N_k>1\}}}{N_k-1}\sum_{j\in B_k\setminus\{i\}}\log\left(\frac{\exp\left(\langle z_i,z_j\rangle/\tau\right)}{\sum_{l\in B\setminus\{i\}}\exp\left(\langle z_i,z_l\rangle/\tau\right)}\right)\quad(1)$$

Definition 2 (Equidistant/regular simplex)**.** *Let $h,K\in\mathbb{N}$ with $K\le h+1$. An K point configuration $\zeta=(\zeta_1,\ldots,\zeta_K)\in(\mathbb{S}^{h-1})^N$ form the vertices of an equidistant simplex inscribed in the unit-hypersphere, if and only if the following conditions hold:*

(1) $\forall i\in[K],\|\zeta_i\|=1$

(2) $\exists d\in\mathbb{R},\forall i,j$ *and* $1\le i<j\le K$, $d=\langle\zeta_i,\zeta_j\rangle$

And ζ form the vertices of a regular simplex inscribed in the unit-hypersphere, if and only if (1), (2) and the following condition holds:

(3) $\sum_{i\in[K]}\zeta_i=0$

3.2 Optimal Representation Configuration

In this subsection, we assume a sufficiently powerful encoder capable of realizing any representation configuration, and set the temperature parameter (in Eq. (1)) to $\tau=1$.

Optimal Representation Configuration for Balanced Data. When data is balanced, Theorem 1 states that the SC loss attains its minimum if and only if the representations of each class converge at their respective class centers, and the centers of all classes form a regular simplex.

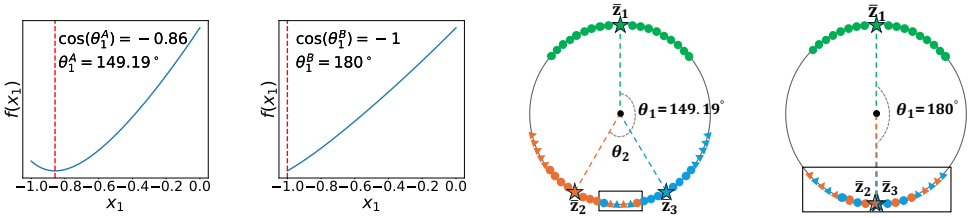
Theorem 1. *Let Z be an N point configuration (assuming all zs being normalized), $Z=(z_1,\ldots,z_N)\in(\mathbb{S}^{h-1})^N$, with labels $Y=(y_1,\ldots,y_N)\in([K])^N$, and $3\le K\le h+1$. When Y is balanced, hence $\forall i\in[K]$, $N_k=\frac{N}{K}$, it holds that:*

$$\mathcal{L}_{\mathrm{SC}}\ge N\log\left(\left(\frac{N}{K}-1\right)+\frac{N(K-1)}{K}\exp\left(-\frac{K}{K-1}\right)\right)\quad(2)$$

where equality is attained if and only if there exists a configuration of $\bar{Z}=(\bar{z}_1,\ldots,\bar{z}_K)\in(\mathbb{S}^{h-1})^K$ such that:

(A1) $i\in B_k$, $z_i=\bar{z}_k$.

(A2) $\bar{Z}$ *form a regular simplex inscribed in the unit-hypersphere.*



(a) (b) (c) (d)

Figure 2: Numerical example. The sample size ratio is **10:1:1** in Example A and **100:1:1** in Example B. (a) $f(x_1)$ of Example A. (b) $f(x_1)$ of Example B. (c) Representations of Example A. (d) Representations of Example B. Stars are empirical centers. Circles are available samples, triangles are missing samples. Black boxes are overlapping regions.

Remark 1. *This theorem has been previously established in Graf et al. (2021). In this paper, we provide a new proof (Appendix B.1) that dose not presume $\mathcal{L}_{\mathrm{SC}}^{k,i}$ (in Eq. (1)) to be the same when k varies, as was done in (S39) of Graf et al. (2021). This allows us to extend the analysis to more general center configurations, particularly laying the foundation for the imbalanced data case (Theorem 2).*

Optimal Representation Configuration for Imbalanced Data. When data is imbalanced, we first find the tight lower bound function f of $\mathcal{L}_{\mathrm{SC}}$, assuming all representations converging at their respective class centers. f only depends on the center configuration. We then determine the optimal representation configuration when f is minimized. In a one-vs-all scenario, Theorem 2 states the SC loss is minimized if and only if the representations of classes 2 to K converge to the vertices of an equidistant simplex while representations of class 1 converge to the point that is perpendicular to the equidistant simplex (more explanations in Appendix A.2)

Theorem 2. *Let Z be an N point configuration (assuming all zs being normalized), $Z = (z_1, \ldots, z_N) \in (\mathbb{S}^{h-1})^N$, with labels $Y = (y_1, \ldots, y_N) \in ([K])^N$, and $3 \leq K \leq h+1$. If $\forall k \in \{2, \ldots, K\}, N_k = a_2 \geq 4$, and $\exists \rho > 0$ such that $N_1 = a_1 = \rho a_2 > 1$, it holds that:*

$$\mathcal{L}_{\mathrm{SC}} \geq f(\cos(\theta_1), \cos(\theta_2)), \tag{3}$$

where $f(\cdot) : \mathbb{R} \times \mathbb{R} \to \mathbb{R}$ is defined as:

$$\begin{aligned} f(x_1, x_2) = \rho a_2 \log\left((\rho a_2 - 1) + e^{-1}(K-1)\, a_2 \exp(x_1)\right) \\ + (K-1) a_2 \log\left((a_2 - 1) + e^{-1}\left((K-2)\, a_2 \exp(x_2) + \rho a_2 \exp(x_1)\right)\right), \end{aligned} \tag{4}$$

and equality is attained if and only if there exists a configuration of $\bar{Z} = (\bar{z}_1, \ldots, \bar{z}_K) \in (\mathbb{S}^{h-1})^K$ such that:

(A3) $i \in B_k$, $z_i = \bar{z}_k$.

(A4) $\forall k, k' \in \{2, \ldots, K\}$ *and* $k \neq k'$, $\langle \bar{z}_1, \bar{z}_k \rangle = \cos(\theta_1)$, $\langle \bar{z}_k, \bar{z}_{k'} \rangle = \cos(\theta_2)$, *and* $\cos(\theta_2) = \frac{(K-1)\cos^2(\theta_1) - 1}{K-2}$.

(A5) (Case 1) $\rho < 1$: $\theta_1 \in \left(\cos^{-1}(-\frac{1}{K-1}), 0\right)$ *such that* $f'_{x_1}(\cos(\theta_1)) = 0$.

(Case 2) $\rho = 1$: $\theta_1 = \cos^{-1}(-\frac{1}{K-1})$.

(Case 3) $1 < \rho < R(K, a_2)$: $\theta_1 \in \left(-\pi, \cos^{-1}(-\frac{1}{K-1})\right)$ *such that* $f'_{x_1}(\cos(\theta_1)) = 0$.

(Case 4) $\rho \geq R(K, a_2)$: $\theta_1 = -\pi$.

Let $b_1 = (K-1)(1+e^{-2}-2e^2)a_2 - 2$, $b_2 = 8(1+e^{-2})(K-1)a_2((K-1)a_2 - e^2)$, then $R(K, a_2)$ defined as:

$$R(K, a_2) = \frac{-b_1 + \sqrt{b_1^2 + b_2}}{2(1+e^{-2})a_2}. \tag{5}$$

Detailed proof is provided in Appendix B.2. We show that x_2 is dependent on x_1 and f is a convex function of x_1. Therefore, f has one and only one minimal value within a given domain with

$f_{\text{min}} = f(\cos(\theta_1), \frac{(K-1)\cos^2(\theta_1)-1}{K-2})$. We also show that f'_{x_1} is an increasing function of ρ. So as ρ increases, θ_1 increases and θ_2 decreases. θ_1 measures the extent of dominance of the head class.

Remark 2. *$R(K, a_2)$ in Eq. (5) can be roughly simplified as a linear function only respect to K:*

$$R'(K) = (K-1)\frac{-(1+e^{-2}-2e^2)+\sqrt{(1+e^{-2}-2e^2)^2+8(1+e^{-2})}}{2(1+e^{-2})} \approx 12.16(K-1) \quad (6)$$

$R'(K)$ provides an approximate estimate to distinguish Case 3 and Case 4 in Theorem 2.

Numerical Examples. To quantify the extent that long-tailed data skew the feature space, we consider two examples with $K = 3$ classes. The tail-classes have $N_2 = N_3 = 50$ samples. In Example A, $\rho_A = 10$, and the head class has $N_1^A = 500$ samples. In Example B, $\rho_B = 100$, so $N_1^B = 5000$. $\rho_A < R'(3) < \rho_B$. All samples are mapped to a unit circle ($\mathbb{S}^1$). Then $\theta_1^A = 149.19°$, $\theta_2^A = 61.63°$, $\theta_1^B = 180°$ and $\theta_2^B = 0°$ can be found when f is minimized. Fig. 2 visualizes values of the lower bound function f and the empirical representations of both examples.

4 METHOD

4.1 CHALLENGES IN LONG-TAILED REPRESENTATION LEARNING

Skewed Center Configuration. Theorem 2 reveals that long-tailed data force tail classes' centers to shrink or even collapse. We refer to this phenomenon as the skewed center configuration. This leads to the feature distributions of the tail classes partially (Fig. 2c) or fully (Fig. 2d) overlapping. As a result, samples in the overlapping regions become inseparable and cannot be distinguished by a classifier.

Distribution Shift. One may consider rearranging the center configuration to symmetric one to separate the overlapping features. This approach implicitly assumes that the distribution of training data, $\mathcal{P}_{\text{train}}$, is the same with the true distribution of the underlying data, $\mathcal{P}_{\text{true}}$. However, due to the limited sample sizes of tail classes, a discrepancy often exists between $\mathcal{P}_{\text{train}}$ and $\mathcal{P}_{\text{true}}$. We refer to this phenomenon as distribution shift. When it occurs, rearranging the training center configuration can separate the training data but cannot ensure the separation of testing data and may even causes overlapping distributions between head and tail classes (as depicted in Fig. 3).

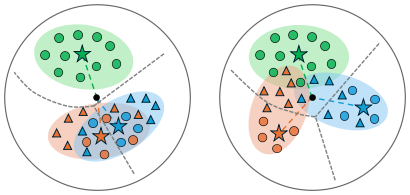


Figure 3: long-tailed data representations. Left: Before center correction. Right: After center correction with distribution shifts. To save space, we defer the legend to Fig. 4.

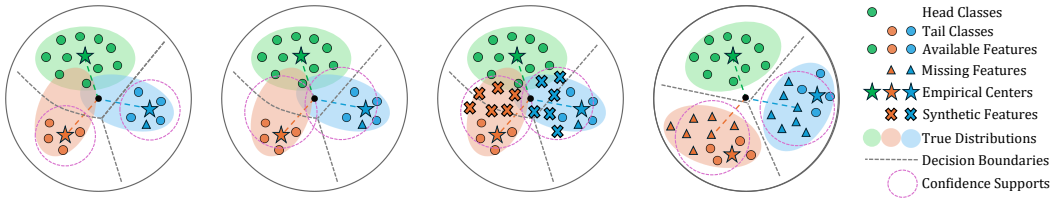
4.2 FEATRECON

To address the problems that are discussed above, we design our method to reconstruct the feature space of long-tailed data to be both symmetric and linearly separable.

Theorem 2 suggests that balancing sample size can correct the center configuration. To achieve this, we directly generate synthetic features in the feature space. Since all features are normalized (i.e, $Z \in \mathbb{S}^{h-1}$), it is reasonable to assume that the features of each class fall within a hyperspherical cap on $\mathbb{S}^{h-1}$, parameterized by a center and a "radius" – a fixed central angle. Thus, for each class, we estimate its confidence support as a hyperspherical cap that contains the majority of features. We then sample synthetic features from these supports. Each support is filled with real and synthetic features, and features from nearby classes are pushed away as training progresses.

However, since tail classes have limited sample sizes, their estimated supports are unreliable. To prevent missing features of tail classes from falling outside their respective supports and overlapping with the features of the head classes, we regularize tail classes' estimation with the statistics of neighboring head classes. Since the synthetic samples ensure the learnt representation configuration to be symmetric, as long as the central angle of any confidence support is sufficiently small (at the most $\frac{1}{2}\cos^{-1}(-\frac{1}{K-1})$), these confidence supports are guaranteed to be linearly separable.

The procedure is illustrated in Fig. 4. In Fig. 4a, we estimate the confidence support based on limited training samples. In Fig. 4b, the confidence supports of tail classes are regularized using the head



(a) (b) (c) (d)

Figure 4: One iteration of our algorithm. (a) Estimation of the confidence supports with training data. The supports are drawn in dashed magenta circles. (b) Regularization of the support by head class statistics. (c) Generating synthetic features to fill the supports (cross markers). (d) Optimization of the SC loss separates the tail classes and their supports.

class statistics. In Fig. 4c, we generate synthetic samples filling these confidence supports. Finally, by minimizing the SC loss, class centers are moved to equal distance from each other, and the supports are guaranteed to be linearly separable (Fig. 4d). In practice, we repeat the procedure iteratively.

Confidence Supports Estimation. A hyperspherical cap can be characterized by its center and a central angle. For class k, we estimate these parameters as follows:

$$\hat{\mu}_k = \frac{1}{N_k} \sum_{i \in B_k} z_i, \text{ and } \hat{\theta}_k = Q_\alpha\{\cos^{-1}(z_i \cdot \hat{\mu}_k) | y_i = k\}, \tag{7}$$

where Q_α denotes the α quantile. Normalization is applied wherever necessary to keep the center estimator a unit vector.

Head Class Regularization. For tail classes, the statistics are regularized using the statistics of $\mathcal{P}_{\text{true}}$ from head classes, which are estimated more accurately due to sufficient training samples. This improves the robustness of tail class parameter estimation. Specifically, for a tail class k, we select the top q head classes ($\mathcal{C}_h$) with the highest similarities to its class center $\hat{\mu}$:

$$\mathcal{C}_k^q = \left\{ i \mid \hat{\mu}_i \cdot \hat{\mu}_k \in \text{top}_q\left(\mathcal{S}_k\right) \right\}, \text{ where } \mathcal{S}_k = \left\{ \hat{\mu}_i \cdot \hat{\mu}_k \mid i \in \mathcal{C}_h \right\}, \tag{8}$$

and regularize its statistics using those from the selected head classes ($\mathcal{C}_k^q$) as follows:

$$\hat{\mu}'_k = (1-\gamma) \sum \omega_k^c \hat{\mu}_c + \gamma \hat{\mu}_k \text{ and } \hat{\theta}'_k \quad = (1-\gamma) \sum \omega_k^c \hat{\theta}_c + \gamma \hat{\theta}_k \tag{9}$$

where $\omega_k^c = \frac{\hat{\mu}_i \cdot \hat{\mu}_k}{\sum_{j \in \mathcal{C}_k^q} \hat{\mu}_i \cdot \hat{\mu}_j}$ is the regularization weight of class c, and γ is the regularization magnitude.

Feature Generation. The estimated confidence support of class k is defined as the set of points:

$$\tilde{\mathcal{Z}}_k = \left\{ \tilde{z} \in \mathbb{S}^{h-1} \mid \tilde{z}^\top \hat{\mu}'_k \geq \cos(\bar{\theta}_k) \right\}, \text{ where } \bar{\theta}_k = \min\{\hat{\theta}'_k, \frac{1}{2}\cos^{-1}(-\frac{1}{K-1})\}. \tag{10}$$

Let $N_{\text{max/min}} = \text{max/min}\{N_k : k \in [K]\}$, we sample $mN_{\text{max}} - N_k$ points from $\tilde{\mathcal{Z}}_k$ as the synthetic features for class k, where m controls the total number of synthetic features.

Temperature Adjustment. Previous works (Wang & Liu, 2021; Kukleva et al., 2023; Hou et al., 2023) have revealed temperature parameter τ controls the preference between intra-class and inter-class discrimination. A larger τ encourages more concentrical feature distributions and inter-class discrimination. And head classes benefit from a larger τ while tail classes benefit from a smaller one. Inspired by this, we adjust temperature for class k as:

$$\tau_k = \left(1 - 0.5\left(1 + \cos\left(\pi \frac{N_k - N_{\text{min}}}{N_{\text{max}} - N_{\text{min}}}\right)\right)\right) \times (\tau_+ - \tau_-) + \tau_- \tag{11}$$

where τ_+, τ_- denote the upper and lower bounds of τ, respectively.

Gradient analysis in Khosla et al. (2020) shows that τ also controls the gradient scale: the larger the τ, the smaller the gradient. Therefore, we re-balance the gradient scale of samples by class by adjusting the weight of $\mathcal{L}_{SC}^{k,i}$ with a scalar parameter $\frac{\tau_k}{\tau_-}$.

Table 1: Top-1 accuracy of ResNet-32 on CIFAR-10/100-LT datasets with different imbalance factors.

Dataset	CIFAR-10-LT			CIFAR-100-LT		
Imbalance Ratio (ρ)	100	50	10	100	50	10
CE	70.36	74.81	86.39	38.32	43.85	55.71
Focal Loss (Lin et al., 2017)	70.38	76.72	86.66	38.41	44.32	55.78
CB-Focal (Cui et al., 2019)	74.57	79.27	87.10	39.60	45.17	57.99
LDAM-DRW (Cao et al., 2019)	77.03	81.03	88.16	42.04	46.62	58.71
CB-DA-LDAM (Jamal et al., 2020)	80.00	82.23	87.40	44.08	49.16	58.00
CE-OTmix (Gao et al., 2024)	78.30	83.40	90.20	46.40	40.70	61.60
DWR-OTmix (Cao et al., 2019; Gao et al., 2024)	83.10	86.40	90.60	48.00	52.60	62.70
SCL (Khosla et al., 2020) -	-	-	-	42.10	45.20	54.80
Hybrid-SC (Wang et al., 2021)	81.40	85.36	91.12	46.72	51.87	63.05
Hybrid-PSC (Wang et al., 2021)	78.82	83.86	90.96	44.97	48.93	62.70
KCL (Kang et al., 2021)	77.60	81.70	88.00	42.80	46.30	57.60
TSC (Li et al., 2022)	79.70	82.90	88.70	43.80	47.40	59.00
BCL (Zhu et al., 2022)	84.32	87.24	91.12	51.93	56.59	64.87
SBCL (Hou et al., 2023) -	-	-	-	44.90	48.70	57.90
FeatRecon	**86.42**	**88.49**	**92.03**	**53.41**	**57.48**	**65.67**

Training Framework. Our training framework mainly follows (Zhu et al., 2022; Du et al., 2024). The model consists of: 1) a base encoder $f : X \to h$ that extracts latent embeddings; 2) a prediction head $l : h \to p$ that produces model predictions $p = l \circ f(\mathcal{X})$; 3) a projection head $g : h \to z$ that generates normalized representations $z = g \circ f(\mathcal{X})$.

The prediction head is optimized using the training data with the cross entropy loss and logit compensation (Menon et al., 2021). Let $\mathbb{P}(y)$ be class priors and $\delta_y = \log \mathbb{P}_y$. Then the $\mathcal{L}_x$ is:

$$\mathcal{L}_x(y, l \circ f(x)) = -\log \frac{\exp\left(p_y + \delta_y\right)}{\sum_{y' \in [\mathcal{Y}]} \exp\left(p_{y'} + \delta_{y'}\right)} \tag{12}$$

The projection head is optimized with both real and synthetic features with the supervised contrastive loss $\mathcal{L}_{SC}$. The final objective is:

$$\mathcal{L} = \lambda_x \mathcal{L}_x + \lambda_c \mathcal{L}_{SC} \tag{13}$$

where λ_x and λ_c are hyperparameters that control relative strength among different losses.

5 Experiments

5.1 Dataset and Implementation Details.

Dataset. CIFAR-10-LT and CIFAR-100-LT are the imbalanced subsets of the original CIFAR-10 and CIFAR-100 (Krizhevsky et al., 2009), following (Kang et al., 2021; Li et al., 2022; Zhu et al., 2022). We set the imbalance factor $\rho = N_{max}/N_{min}$ to be 100, 50, and 10.

ImageNet-LT (Liu et al., 2019) is the subset of the original ImageNet (Deng et al., 2009), with the training set sampled with a Pareto distribution with power value α = 0.6 and testing set unchanged. The imbalance factor is 256, with the most frequent class having 1280 samples and the least frequent one having 5 samples.

iNaturalist 2018 (Van Horn et al., 2018) is a large-scale long-tailed dataset that contains 437.5K images from 8,142 classes with an extremely imbalanced distribution.

Table 2: Top-1 accuracy of ResNet-32 on CIFAR-100-LT with imbalance factor equaling 100.

	Methods	Many	Medium	Few	All
200 epochs	Hybrid-SC (Wang et al., 2021)	-	-	-	46.7
	DRO-LT (Samuel & Chechik, 2021)	64.7	50.0	23.8	47.3
	RIDE(3 experts) (Wang et al., 2020)	68.1	49.2	23.9	48.0
	BCL (Zhu et al., 2022)	67.2	53.1	32.9	51.9
	FeatRecon (Ours)	**69.2**	**53.3**	**35.0**	**53.4**
400 epochs	Balanced Softmax (Ren et al., 2020)	-	-	-	50.8
	PaCo (Cui et al., 2021)	-	-	-	52.0
	GPaCo (Cui et al., 2023)	-	-	-	52.3
	BCL (Zhu et al., 2022)	69.7	53.8	35.5	53.9
	FeatRecon (Ours)	**70.6**	**54.1**	**36.9**	**54.8**

Table 3: Top-1 accuracy of ResNet-50 on ImageNet-LT dataset and iNaturalist 2018 dataset.

Method	ImageNet-LT				iNaturalist 2018			
	Many	Med	Few	All	Many	Med	Few	All
CE	64.0	33.8	5.8	41.6	72.2	63.0	57.2	61.7
Focal Loss (Lin et al., 2017)	51.0	40.8	20.8	43.7	-	-	-	61.3
LDAM-DRW (Cao et al., 2019)	60.4	46.9	30.7	49.8	-	-	-	64.6
cRT (Kang et al., 2020)	58.8	44.4	26.1	47.3	69.0	66.0	63.2	65.2
τ-norm (Kang et al., 2020)	56.6	44.2	27.4	46.7	65.6	65.3	65.9	65.6
LWS (Kang et al., 2020)	57.1	45.2	29.3	47.7	65.0	66.3	65.5	65.9
Area (Chen et al., 2023)	-	-	-	49.5	-	-	-	68.4
CE-OTmix (Gao et al., 2024)	**70.0**	45.9	22.3	52.0	69.3	70.5	68.4	69.5
DRW-OTmix (Cao et al., 2019; Gao et al., 2024)	67.0	49.0	30.4	53.4	70.6	71.9	70.4	71.1
IWB (Dang et al., 2024)	64.2	52.2	40.2	55.2	72.3	70.6	72.5	71.5
SCL (Khosla et al., 2020)	61.4	47.0	28.2	49.8	-	-	-	66.4
KCL (Kang et al., 2021)	61.8	49.4	30.9	51.5				68.6
TSC (Li et al., 2022)	63.5	49.7	30.4	52.4	72.6	70.6	67.8	69.7
BCL (Zhu et al., 2022)	-	-	-	56.0	-	-	-	71.8
BCL (Zhu et al., 2022)	67.2	53.9	36.5	56.7	-	-	-	-
SBCL (Hou et al., 2023)	63.8	51.3	31.2	53.4	**73.3**	71.9	68.6	70.8
DecoupledCL (Xuan & Zhang, 2024)	68.5	55.2	35.4	57.7	**74.2**	72.9	70.3	72.0
FeatRecon	68.1	**55.3**	**38.3**	**57.8**	72.0	**73.9**	**73.9**	**73.7**

Following previous works (Li et al., 2022; Zhu et al., 2022; Hou et al., 2023), we train our model on the long-tailed training sets and evaluate on the balanced testing sets. We divide the testing sets into three subsets: many (with more than 100 instances), medium (with 20 to 100 instances), and few (with less than 20 instances) splits.

Implementation Details. To ensure a fair comparison, our implementation follows (Zhu et al., 2022). For both CIFAR-10-LT and CIFAR-100-LT, we adopt the ResNet-32 as the backbone. The projection head is a 2-layer MLP that generates 128-dimensional embeddings. Dimension of the hidden layer is 512. Our model is trained for 200 epochs with a batch size of 256 and with a SGD optimizer. The momentum is 0.9 and the weight decay is $5e^{-4}$. The learning rate warms up 0.15 in the first 5 epochs and decay by 0.1 at the 160th and 180th epochs. For data augmentation, we adopt AutoAug (Cubuk et al., 2019) and Cutout (DeVries & Taylor, 2017) for the classification head, and adopt SimAug (Chen et al., 2020) for the projection head. For hyperparameters, we set $\lambda_x = 2.0$, $\lambda_c = 0.6$, $\alpha = 0.99$, and $\tau_- = 0.1$, $\tau_+ = 1$. We also train our model for 400 epochs for finer comparisons on CIFAR-100-LT. In this case, the learning rate warms up in the first 10 epochs and decay at the 360th and 380th epochs.

We adopt ResNet-50 (He et al., 2016) as the model backbone for both ImageNet-LT and iNaturalist 2018. The projection head is a 2-layer MLP that generates 1024-dimensional embeddings. Dimension of the hidden layer is 2048. For data augmentation, we switch the strategy for the projection head to RandAug (Cubuk et al., 2020). Our model is trained for 90 epochs for ImageNet-LT and 100 for iNaturalist 2018 epochs with a batch size of 256 and with a SGD optimizer. The momentum is 0.9 and the weight decay is $5e^{-4}$ for ImageNet-LT and $1e^{-4}$ for iNaturalist 2018. The learning rate is 0.1 for ImageNet-LT and 0.2 for iNaturalist 2018 with a cosine scheduler. Additionaly, we train our model for 90 epochs using ResNeXt-50-32x4d (Xie et al., 2017) as the backbone. For hyperparameters, we set $\lambda_x = 1$, $\lambda_c = 0.35$, $\alpha = 0.99$, and $\tau_- = 0.07$, $\tau_+ = 1$.

5.2 Results

CIFAR-LT Tab. 1 shows experiment results on CIFAR-10/100-LT datasets with imbalance factor varying among 10, 50, and 100. For baselines, we select methods that only work with classifiers (Lin et al., 2017; Cui et al., 2019; Cao et al., 2019; Jamal et al., 2020; Gao et al., 2024) and methods that work with both representations and classifiers (Khosla et al., 2020; Wang et al., 2021; Kang et al., 2021; Li et al., 2022; Zhu et al., 2022; Hou et al., 2023). We can see that FeatRecon outperforms baseline models in all settings. Moreover, our model achieves larger performance gain as the imbalance factor increases, proving the effectiveness of our method for long-tailed data. Additionally, in Tab. 2, we provide shot-wise results on CIFAR-100-LT data with imbalance factor of 100. The

model is trained for both 200 epochs and 400 epochs for fair comparisons with baselines that are trained under different settings. The results demonstrate the superiority of our approach, especially for the few-shot classes.

ImageNet-LT Tab. 3 shows experiment results on ImageNet-LT dataset using ResNet-50 as model backbone. Tab. 4 shows experiment results using ResNeXt-50 as model backbone. We report the overall Top-1 accuracy as well as the Top-1 accuracy on Many-shot, Medium-shot, and Few-shot classes. Similar to the experiments on CIFAR-LT, we select methods that only work with classifiers (Lin et al., 2017; Cao et al., 2019; Kang et al., 2020; Chen et al., 2023; Gao et al., 2024; Dang et al., 2024) and methods that work with both representations and classifiers (Khosla et al., 2020; Kang et al., 2021; Li et al., 2022; Zhu et al., 2022; Hou et al., 2023; Xuan & Zhang, 2024) for baselines. Results show that our method outperforms baselines on the accuracy of tail classes and overall accuracy, demonstrating the effectiveness of our approach for learning classes with missing samples.

Table 4: Top-1 accuracy of ResNeXt-50 on ImageNet-LT dataset.

Method	Many	Med	Few	All
Focal Loss (Lin et al., 2017)	64.3	37.1	8.2	43.7
τ-norm (Kang et al., 2020)	59.1	46.9	30.7	49.4
LWS (Kang et al., 2020)	60.2	47.2	30.3	49.9
IWB (Dang et al., 2024)	64.2	52.2	40.2	55.2
BCL (Zhu et al., 2022)	67.2	53.9	36.5	56.7
Ours	**68.7**	**55.6**	**38.6**	**58.3**

iNaturalist 2018 Tab. 3 also lists experiment results on iNaturalist 2018 dataset. Similar to results on ImageNet-LT, our method outperforms baselines on the accuracy of tail classes and overall accuracy, highlighting our model's capability of learning from few samples.

5.3 Ablation Study

We evaluate the design of FeatRecon through an ablation study on CIFAR-100-LT dataset, with an imbalance factor of 100. Each model runs for 400 epochs. Results are displayed in Tab. 5. Exp. 1 provides the baseline by training a classifier with logit compensation (LP) (Menon et al., 2021). Exp. 2 introduces an additional projection head and trains feature representations with the SC loss (Khosla et al., 2020). This design brings a 1.6% performance improvement, underscoring the benefit of representation learning. In Exp. 3, we balance the sample size across different classes by naively upsampling (Up Sam) the existing features for representation learning. However, this approach has no positive effect. It highlights the effectiveness of our synthetic feature generation method (Feat Gen), shown in Exp. 4, that brings a 3.1% performance gain. In Exp. 5, we validate the benefit of training with temperature adjustment (Temp Adj), which leads to an additional 1.1% performance increase.

Table 5: Ablating model components.

Exp	LC	SC	Up Sam	Feat Gen	Temp Adj	Accuracy	Δ
1	✓					50.8	
2	✓	✓				52.4	+1.6
3	✓	✓	✓			52.6	+1.8
4	✓	✓		✓		54.4	+3.6
5	✓	✓		✓	✓	**54.8**	**+4.0**

6 Conclusion

In this paper, we establish a theoretical framework to investigate the optimal representation configuration for long-tailed data. We prove that centers of tail classes either shrink or collapse. Building on this analysis, we explore the challenges associated with long-tailed representations, identifying two key issues: skewed center configurations and distribution shifts. Inspired by our findings, we introduce a novel method for long-tailed representation learning. Our method reconstructs the feature space for long-tailed data, arranging the representations of each class into symmetric and linearly separable regions. We demonstrate the effectiveness of our approach on several benchmark datasets, and the results show that our method achieves state-of-the-art performance.

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A Appendix A

A.1 Pseudo Algorithms

In this section, we first present the pseudo algorithms of FeatRecon. FeatRecon is a heuristic method that iteratively generates synthetic features, adjust representations, and re-estimate confidence supports at each step of the training process.

Algorithm 1: FeatRecon Algorithm

Input: Available training samples $\mathcal{D} = \{x_i, y_i\}_{i \in B_k}$ from K classes, the quantile parameter α, the regularization magnitude γ and m which controls the total number of synthetic features.

```
for t = 1, ..., T do
    Sample a mini-batch {x_i, y_i}_{i=1}^B from D ;
    for k = 1, ..., K do
        Estimate confident supports for class k as Eq. (7) with online update ;
        if class k is a tail class then
            Regularize its statistics as Eq. (8) and Eq. (9);
        end
        Generate mN_max − N_k synthetic features for class k ;
    end
    Compute the cross entropy loss L_x (Eq. (12)) with training data ;
    Compute the supervised contrastive loss L_SC with both real features and synthetic features ;
    Update model with loss L = λ_x L_x + λ_c L_SC ;
end
Return Trained model
```

For online update of confident support estimator, we adopt the method proposed in Du et al. (2024) to update the centers and use samples from previous batches to update angles. Also, for a given input, we take all estimated centers as additional samples for contrasting, and all generated samples from different classes as additional negatives.

A.2 More Explanation of Theorem 2

In this subsection, we provide more detailed mathematical explanation with respect to Theorem 2.

It states the necessary and sufficient conditions on the representation configuration for the SC loss attaining its minimal. (A3) states representations of each class converge to the respective class centers. (A4) states that the centers of class 2 to K form an $K-2$ equidistant simplex, the angles between whose vertices all equal θ_2. (A4) also states the vector between the spherical center and the center of class 1 is perpendicular to the equidistant simplex, and the angle between class 1's center and other classes' center all equal θ_1. And $\cos(\theta_2) = \frac{(K-1)\cos^2(\theta_1)-1}{K-2}$. (A5) depicts the whole dynamic of the configuration of all centers as ρ increases from 0 to $+\infty$.

More specifically, (A5) shows:

(Case 1) $0 < \rho < 1$: $\frac{\pi}{2} < \theta_1 < \cos^{-1}(-\frac{1}{K-1}) < \theta_2 < \cos^{-1}(-\frac{1}{K-2})$

(Case 2) $\rho = 1$: it becomes a data balance case where $\theta_1 = \theta_2 = \cos^{-1}(-\frac{1}{K-1})$. This indicates all class centers form a $K-1$ regular simplex.

(Case 3) $1 < \rho < R(K, a_2)$: as ρ continues to increase, it becomes a long-tailed problem. The head class (1st) increasingly dominates the feature space as $\pi > \theta_1 > \cos^{-1}(-\frac{1}{K-1}) > \theta_2 > 0$. At this stage, centers of the tail classes increasingly shrinks together.

(Case 4) $\rho > R(K, a_2)$: centers of the tail classes collapses with $\theta_2 = 0$ and $\theta_1 = \pi$

In both long-tailed cases, θ_1 measures the extent that a head class dominate the feature space. Also, Theorem 1 is a special case of Theorem 2 (Case 2).

A.3 More About the Connection Between Theorem 2 and the Proposed Method

Here, we provide a detailed explanation about the connection between theory and algorithm

Our theorem reveals that feature distributions of tail classes either overlap or at least not sufficiently separated, which adversely affect the discriminability of different classes. It not only suggests synthesizing tail class samples to balance class sizes, but also provide important quantitative and geometric guidance as to how the sampling should be done in the algorithm.

Our theorem analyzes the geometry of the optimal configuration, telling us the optimal angles between class centers is $\cos^{-1}(-\frac{1}{K-1})$. If distributions are well estimated, a model can learn symmetrical and linear separable true feature distributions of different classes, achieving good test time accuracy across all classes. However, due to the distribution shifts, confidence supports that are estimated with available training samples suffer sampling bias, resulting in estimation errors, and sacrificing tail class accuracy.

Our algorithm iteratively estimates confidence supports of all classes and fills the supports with synthetic samples so that supports of different classes are well separated at all time. To maximally grow the support, mitigating the sampling bias for tail classes, we regularize the support estimation using the nearby head class distribution. Our method achieves accurate estimation of distributions even for tail classes, with guaranteed inter class separation throughout the training, thus the superior test time accuracy across classes.

The theoretical insight is the key in designing our algorithm. Our algorithm explicitly restricts the estimated confidence support size to be below $\frac{1}{2}\cos^{-1}(-\frac{1}{K-1})$; it is half the optimal angle between classes according to the theorem. This constraint is crucial to guarantee estimated confidence supports of different classes, as well as their synthetic features, not to overlap.

A.4 Limitations

While our theoretical framework opens a door to study long-tailed representation, it's currently limited to the simple one vs. all case. The solution for more general cases remains unsolved.

To solve this problem, it is crucial to identify the numerical relationships among the angles between different class centers. As suggested in Lemma 5, if there are K classes with M distinct sample sizes, there will be $\binom{M}{2}$ distinct angles. Determining the numerical relationships among these angles poses a significant challenge.

However, while our theory primarily addresses the one-vs-all scenario, it unveils a crucial insight into how the head classes dominate the feature space, and provides guidance on algorithm design.

A.5 Representation Visualization

In Fig. 5, we visualize the learned representations of CIFAR-10 testing images with imbalance factor equaling 100 using t-SNE (Van Der Maaten & Hinton, 2008). Results show that, with the help of synthetic features generated by FeatRecon, the resulting testing distributions of different classes are more separated.

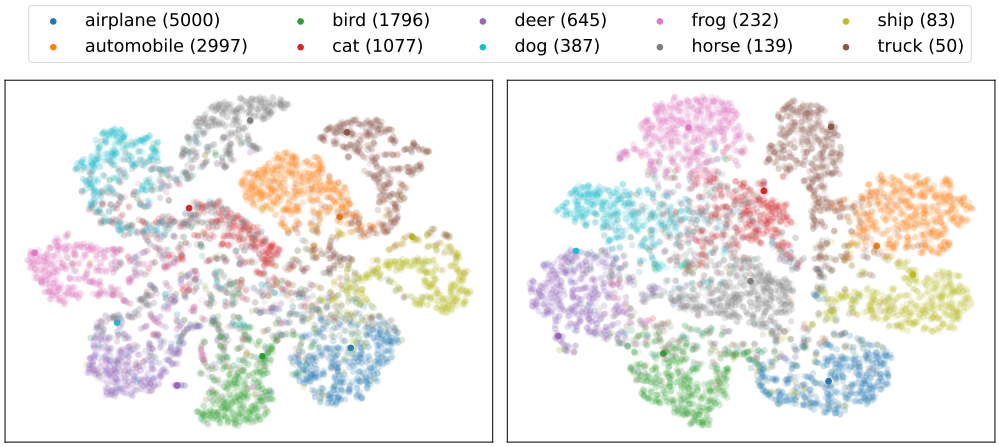

Figure 5: t-SNE visualization of CIFAR-10 testing set. (left) Learned representations without synthetic features. (Right) Learned representations with synthetic features generated by FeatRecon. Numbers in the legend after class names represents the numbers of training samples from this class.

B APPENDIX B

B.1 PROOF OF THEOREM 1

In this section, we provide proofs for Theorem 1 proposed in Sec. 3.2. Our proof is different from what's shown in (Graf et al., 2021; Zhu et al., 2022) in order to take long-tailed distribution into account. For the convenience of your reading, let's recall some related notions and definitions.

- $h, N, K \in \mathbb{N}$
- $\mathcal{Z} = \mathbb{R}^h$
- $\mathbb{S}^{h-1} = \left\{z \in \mathbb{R}^h : \|z\| = 1\right\}$
- $\mathcal{Y} = \{1, \ldots, K\} = [K]$
- $B = \{1, \ldots, N\} = [N]$
- $B_k = \{i : i \in B, y_i = k\}$
- $N_k = |B_k|$

Definition 1 (Supervised contrastive loss) Let Z be an N point configuration (assuming all zs being normalized), $Z = (z_1, \ldots, z_N) \in (\mathbb{S}^{h-1})^N$, with labels $Y = (y_1, \ldots, y_N) \in ([K])^N$, and $K \leq h+1$. Let $B = [N]$, $B_k = \{i : i \in B, y_i = k\}$ and $N_k = |B_k|$. The supervised contrastive loss $\mathcal{L}_{\mathrm{SC}}(\cdot; Y) : (\mathbb{S}^{h-1})^N \to \mathbb{R}$ is defined as:

$$\mathcal{L}_{\mathrm{SC}} = \sum_{k=1}^{K} \sum_{i \in B_k} \mathcal{L}_{\mathrm{SC}}^{k,i}, \text{ where } \mathcal{L}_{\mathrm{SC}}^{i} = -\frac{\mathbb{1}_{\{N_k > 1\}}}{N_k - 1} \sum_{j \in B_k \setminus \{i\}} \log \left(\frac{\exp\left(\langle z_i, z_j \rangle\right)}{\sum_{l \in B \setminus \{i\}} \exp\left(\langle z_i, z_l \rangle\right)} \right).$$

Definition 3 (Equidistant/regular Simplex) Let $h, K \in \mathbb{N}$ with $K \leq h+1$. An K point configuration $\zeta = (\zeta_1, \ldots, \zeta_K) \in (\mathbb{S}^{h-1})^N$ form the vertices of an equidistant simplex inscribed in the unit-hypersphere, if and only if all of the following conditions hold:

(1) $\forall i \in [K], \|\zeta_i\| = 1$

(2) $\exists d \in \mathbb{R}, \forall i, j$ and $1 \leq i < j \leq K$, $d = \langle \zeta_i, \zeta_j \rangle$

And ζ form the vertices of a regular simplex inscribed in the unit-hypersphere, if and only if (1), (2) and the following condition holds:

(3) $\sum_{i \in [K]} \zeta_i = 0$

Theorem 1 Let Z be an N point configuration (assuming all zs being normalized), $Z = (z_1, \ldots, z_N) \in (\mathbb{S}^{h-1})^N$, with labels $Y = (y_1, \ldots, y_N) \in ([K])^N$, and $K \leq h+1$. Let $B = [N]$, $B_k = \{i : i \in B, y_i = k\}$ and $N_k = |B_k|$. When Y is balanced, hence $\forall i \in [K]$, $N_k = \frac{N}{K}$, it holds that:

$$\mathcal{L}_{\mathrm{SC}} \geq N \log \left(\left(\frac{N}{K} - 1 \right) + \frac{N(K-1)}{K} \exp \left(-\frac{K}{K-1} \right) \right),$$

where equality is attained if and only if there exists a configuration of $\bar{Z} = (\bar{z}_1, \ldots, \bar{z}_K) \in (\mathbb{S}^{h-1})^K$ such that:

(A1) $i \in B_k$, $z_i = \bar{z}_k$.

(A2) $\bar{Z}$ form a regular simplex inscribed in the unit-hyperspher.

B.1.1 STEPS OF PROOF

First let's rewrite $\mathcal{L}_{\mathrm{SC}}^{k,i}$ and $\mathcal{L}_{\mathrm{SC}}$ (assuming $\forall k \in [K], N_k > 1$).

$$\begin{aligned}
\mathcal{L}_{\mathrm{SC}}^{k,i} &= -\frac{1}{N_k - 1} \sum_{j \in B_k \setminus \{i\}} \log \left(\frac{\exp\left(\langle z_i, z_j \rangle\right)}{\sum_{l \in B \setminus \{i\}} \exp\left(\langle z_i, z_l \rangle\right)} \right) \\
&= \frac{1}{N_k - 1} \sum_{j \in B_k \setminus \{i\}} \log \left(\frac{\sum_{l \in B \setminus \{i\}} \exp\left(\langle z_i, z_l \rangle\right)}{\exp\left(\langle z_i, z_j \rangle\right)} \right) \\
&= \frac{1}{N_k - 1} \log \left(\frac{\left(\sum_{l \in B \setminus \{i\}} \exp\left(\langle z_i, z_l \rangle\right)\right)^{N_k - 1}}{\prod_{j \in B_k \setminus \{i\}} \exp\left(\langle z_i, z_j \rangle\right)} \right) \\
&= \log \left(\frac{\sum_{l \in B \setminus \{i\}} \exp\left(\langle z_i, z_l \rangle\right)}{\exp\left(\sum_{j \in B_k \setminus \{i\}} \langle z_i, z_j \rangle\right)^{\frac{1}{N_k - 1}}} \right) \\
&= \log \left(\frac{\sum_{l \in B \setminus \{i\}} \exp\left(\langle z_i, z_l \rangle\right)}{\exp\left(\frac{1}{N_k - 1} \sum_{j \in B_k \setminus \{i\}} \langle z_i, z_j \rangle\right)} \right),
\end{aligned} \tag{14}$$

and hence

$$\begin{aligned}
\mathcal{L}_{\mathrm{SC}} &= \sum_{k=1}^{K} \sum_{i \in B_k} \mathcal{L}_{\mathrm{SC}}^{k,i} \\
&\overset{Lemma\ 2}{\geq} \sum_{k=1}^{K} N_k \log \left((N_k - 1) + e^{-1} \sum_{\substack{k' \in [K] \\ k' \neq k}} N_{k'} \exp\left(\langle \bar{z}_k, \bar{z}_{k'} \rangle\right) \right),
\end{aligned} \tag{15}$$

where $\bar{z}_k = \frac{1}{N_k} \sum_{i \in B_k} z_i$. When Y is balanced, $\forall i \in [K]$, $N_k = \frac{N}{K}$, then

$$\begin{aligned}
\mathcal{L}_{\mathrm{SC}} &\geq \sum_{k=1}^{K} \frac{N}{K} \log \left(\left(\frac{N}{K} - 1 \right) + e^{-1} \frac{N}{K} \sum_{\substack{k' \in [K] \\ k' \neq k}} \exp\left(\langle \bar{z}_k, \bar{z}_{k'} \rangle\right) \right) \\
&\overset{Lemma\ 3}{\geq} N \log \left(\left(\frac{N}{K} - 1 \right) + e^{-1} \frac{N(K-1)}{K} \exp\left(\beta\right) \right),
\end{aligned} \tag{16}$$

and equality is attained if and only if all of the following conditions hold:

(B1) $\forall i \in B_k$, $z_i = \bar{z}_k$.

(B2) $\forall k \in [K]$ and $k' \in [K] \setminus \{k\}$, $\langle \bar{z}_k, \bar{z}_{k'} \rangle = \beta$.

(B3) There exists a configuration of $\bar{Z} = (\bar{z}_1, \ldots, \bar{z}_K)$ such that (B2) holds.

- (Case 1) $K = h + 1$: $\beta = -\frac{1}{K-1}$ or $\beta = 1$
- (Case 2) $K < h + 1$: $-\frac{1}{K-1} \leq \beta \leq 1$

When $a, b > 0$, $f(x) = \log\left(a + be^x\right)$ is a strictly increasing function. And Eq. (16) suggests that the lower bound of $\mathcal{L}_{\mathrm{SC}}$ is a strictly increasing function of β. When β reaches its minimal value so does $\mathcal{L}_{\mathrm{SC}}$. When $K \leq h + 1$, $\beta_{\min} = -\frac{1}{K-1}$, then we have:

$$\begin{aligned}\mathcal{L}_{\mathrm{SC}} &\geq N \log\left(\left(\frac{N}{K}-1\right)+e^{-1}\frac{N(K-1)}{K}\exp\left(-\frac{1}{K-1}\right)\right)\\ &= N \log\left(\left(\frac{N}{K}-1\right)+\frac{N(K-1)}{K}\exp\left(-\frac{K}{K-1}\right)\right).\end{aligned} \tag{17}$$

When $\beta = -\frac{1}{K-1}$, Lemma 1 shows that (B2) and (B3) imply $\bar{Z} = (\bar{z}_1, \ldots, \bar{z}_K)$ form a regular simplex. Thus, the conditions for equality can be summarized as: there exists a configuration of $\bar{Z} = (\bar{z}_1, \ldots, \bar{z}_K) \in (\mathbb{S}^{h-1})^K$ such that:

(A1) $i \in B_k$, $z_i = \bar{z}_k$.

(A2) $\bar{Z}$ form a regular simplex inscribed in the unit-hyperspher.

B.1.2 Lemmas Part 1

In this section,we provide definitions and proofs of lemmas that are used for the proof of Theorem 1.

Lemma 1. *Let Z be an K point configuration (assuming all zs being normalized), $Z = (z_1, \ldots, z_K) \in (\mathbb{S}^{h-1})^K$. If $\exists \beta \in \mathbb{R}$, $\forall i, j \in [K]$ and $i \neq j$ such that all inner products $\langle z_i, z_j \rangle = \beta$ are equal, then one of the following cases holds:*

(Case 1) $K > h+1$*:* $\beta = 1$.

(Case 2) $K = h+1$*:* $\beta = -\frac{1}{N-1}$ *or* $\beta = 1$.

(Case 3) $K < h+1$*:* $-\frac{1}{N-1} \leq \beta \leq 1$.

And when $\beta = -\frac{1}{K-1}$, $Z = (z_1, \ldots, z_K)$ forms a regular simplex.

Proof. As explained in (Delsarte et al., 1977), there are at the most $h+1$ equidistant points on $\mathbb{S}^{h-1}$ (The size of a spherical 1-distance set $\leq h+1$ (Delsarte et al., 1977)). When $N > h+1$, all N points collapse into a single point and $\beta = 1$, which is the Case 1. When $N = h+1$, these points either form into a regular simplex or collapse into a single point, which is the Case 2. When $N < h+1$, these points form into a regular/non-regular equidistant simplex or collapse into a single point, which is the Case 3.

Next we will show why when $K < h+1$, $-\frac{1}{K-1} \leq \beta \leq 1$ (Case 3) and when $Z = (z_1, \ldots, z_K) \in (\mathbb{S}^{h-1})^K$ forms a regular simplex, $\beta = -\frac{1}{K-1}$ (Case 2). Given that

$$\begin{aligned}\left\|\sum_{k\in[K]} z_k\right\|^2 &= \left\langle \sum_{k\in[K]} z_k, \sum_{k\in[K]} z_k \right\rangle\\ &= \sum_{k\in[K]} \langle z_k, z_k\rangle + \sum_{\substack{n\in[K]\\ m\in[K]\setminus\{i\}}} \langle z_n, z_m\rangle\\ &= K + K(K-1)\beta\\ &\geq 0,\end{aligned} \tag{18}$$

this shows $-\frac{1}{K-1} \leq \beta$. Since β is the dot product of two unit vectors, $\beta \leq 1$. Then we have:

$$-\frac{1}{N-1} \leq \beta \leq 1. \tag{19}$$

When $Z = (z_1, \ldots, z_K) \in (\mathbb{S}^{h-1})^K$ forms a regular simplex, we have $\sum_{k\in[K]} z_k = 0$. Then $K + K(K-1)\beta = 0$ and $\beta = -\frac{1}{K-1}$.

Now we prove when $\beta = -\frac{1}{K-1}$, $Z = (z_1, \ldots, z_K)$ forms a regular simplex. Recall that $\forall i, j \in [K]$ and $i \neq j$, we have $\|z_i\| = 1$, and $\langle z_i, z_j \rangle = \beta$. When $\beta = -\frac{1}{K-1}$, Eq. (19) shows $\sum_{k\in[K]} z_k = 0$. Then Z forms a regular simplex. □

Lemma 2. *Let Z be an N point configuration (assuming all zs being normalized), $Z = (z_1, \ldots, z_N) \in (\mathbb{S}^{h-1})^N$, with labels $Y = (y_1, \ldots, y_N) \in ([K])^N$. Let $B = [N]$, $B_k = \{i : i \in B, y_i = k\}$. $\forall k \in [K]$, $\sum_{i\in B_k} \mathcal{L}_{\mathrm{SC}}^{k,i}$ is bounded below by:*

$$\sum_{i\in B_k} \mathcal{L}_{\mathrm{SC}}^{k,i} \geq N_k \log \left((N_k - 1) + e^{-1} \sum_{\substack{k'\in[K] \\ k'\neq k}} N_{k'} \exp\left(\langle \bar{z}_k, \bar{z}_{k'} \rangle\right) \right), \tag{20}$$

where $\bar{z}_k = \frac{1}{N_k} \sum_{i\in B_k} z_i$, and equality is attained if and only if the following condition holds:

(B1) $\forall i \in B_k$, $z_i = \bar{z}_k$.

Proof. According to Eq. (14):

$$\begin{aligned} \mathcal{L}_{\mathrm{SC}}^{k,i} &= \log \left(\frac{\sum_{l\in B\setminus\{i\}} \exp\left(\langle z_i, z_l \rangle\right)}{\exp\left(\frac{1}{N_k-1} \sum_{j\in B_k\setminus\{i\}} \langle z_i, z_j \rangle\right)} \right) \\ &= \log \left(\frac{\sum_{l\in B_k\setminus\{i\}} \exp\left(\langle z_i, z_l \rangle\right) + \sum_{\substack{k'\in[K] \\ k'\neq k}} \sum_{m\in B_{k'}} \exp\left(\langle z_i, z_m \rangle\right)}{\exp\left(\frac{1}{N_k-1} \sum_{j\in B_k\setminus\{i\}} \langle z_i, z_j \rangle\right)} \right). \end{aligned} \tag{21}$$

There are three terms in Eq. (21). Let's check their lower bounds one by one. Applying Jensen's inequity, the first term can be bounded below:

$$\sum_{l\in B_k\setminus\{i\}} \exp\left(\langle z_i, z_l \rangle\right) \geq (N_k - 1) \exp\left(\frac{1}{(N_k - 1)} \sum_{l\in B_k\setminus\{i\}} \langle z_i, z_l \rangle \right), \tag{22}$$

where equality is attained if and only if all of the following conditions hold:

(C1) $\forall k \in [K]$ and $\forall i \in B_k$, $\exists \alpha(k, i)$ such that $\forall j \in B_k\setminus\{i\}$, all inner products $\langle z_i, z_j \rangle = \alpha(k, i)$ are equal.

Let $\bar{z}_k = \frac{1}{N_k} \sum_{i\in B_k} z_i$. Similarly, the second term can be bounded below:

$$\begin{aligned} \sum_{m\in B_{k'}} \exp\left(\langle z_i, z_m \rangle\right) &\geq N_{k'} \exp\left(\frac{1}{N_{k'}} \sum_{m\in B_{k'}} \langle z_i, z_m \rangle \right) = N_{k'} \exp\left(\left\langle z_i, \frac{1}{N_{k'}} \sum_{m\in B_{k'}} z_m \right\rangle \right), \\ &= N_{k'} \exp\left(\langle z_i, \bar{z}_{k'} \rangle\right) \end{aligned} \tag{23}$$

where equality is attained if and only if all of the following conditions hold:

(C2) $\forall k \in [K]$ and $\forall i \in B_k$, $\exists \alpha(k, i, k')$ such that $k' \in [K]\setminus\{k\}$ and $m \in B_{k'}$, all inner products $\langle z_i, z_m \rangle = \alpha'(k, i, k')$ are equal. And $\alpha'(k, i, k') = \langle z_i, \bar{z}_{k'} \rangle$.

Using Cauchy-Schwarz inequality, the third term can be bounded below:

$$\frac{1}{\exp\left(\frac{1}{N_k-1}\sum_{j\in B_k\setminus\{i\}}\langle z_i, z_j\rangle\right)} \geq \frac{1}{\exp\left(\frac{1}{N_k-1}\sum_{j\in B_k\setminus\{i\}}\|z_i\|\,\|z_j\|\right)} = e^{-1}, \tag{24}$$

where equality is attained if and only if the following condition holds:

(C3) $\forall k \in [K]$ and $\forall i, j \in B_k$, $z_i = z_j = \bar{z}_k$.

It's obvious to see that when condition (C3) holds, all samples from the same class collapse into their class center (denoted by $\bar{z}_k$). In this case, and thus condition (C1) and (C2) hold as well where $\alpha(k,i) = 1$ and $\alpha'(k,i,k') = \langle z_k, \bar{z}_{k'}\rangle$. So (C3) is a sufficient condition for (C1) and (C2). Now we have:

$$\begin{aligned}
\sum_{i\in B_k}\mathcal{L}_{\mathrm{SC}}^{k,i} &= \sum_{i\in B_k}\log\left(\frac{\sum_{k\in B_k\setminus\{i\}\}}\exp\left(\langle z_i, z_l\rangle\right) + \sum_{\substack{k'\in[K]\\k'\neq k}}\sum_{l\in B_{k'}}\exp\left(\langle z_i, z_l\rangle\right)}{\exp\left(\frac{1}{N_k-1}\sum_{j\in B_k\setminus\{i\}}\langle z_i, z_j\rangle\right)}\right)\\
&\overset{Eq.\ (22)}{\geq} \sum_{i\in B_k}\log\left(\frac{(N_k-1)\exp\left(\frac{1}{(N_k-1)}\sum_{l\in B_k\setminus\{i\}}\langle z_i, z_l\rangle\right) + \sum_{\substack{k'\in[K]\\k'\neq k}}\sum_{l\in B_{k'}}\exp\left(\langle z_i, z_l\rangle\right)}{\exp\left(\frac{1}{N_k-1}\sum_{j\in B_k\setminus\{i\}}\langle z_i, z_j\rangle\right)}\right)\\
&= \sum_{i\in B_k}\log\left((N_k-1) + \frac{\sum_{\substack{k'\in[K]\\k'\neq k}}\sum_{l\in B_{k'}}\exp\left(\langle z_i, z_l\rangle\right)}{\exp\left(\frac{1}{N_k-1}\sum_{j\in B_k\setminus\{i\}}\langle z_i, z_j\rangle\right)}\right)\\
&\overset{Eq.\ (23)}{\geq} \sum_{i\in B_k}\log\left((N_k-1) + \frac{\sum_{\substack{k'\in[K]\\k'\neq k}}N_{k'}\exp\left(\langle z_i, \bar{z}_{k'}\rangle\right)}{\exp\left(\frac{1}{N_k-1}\sum_{j\in B_k\setminus\{i\}}\langle z_i, z_j\rangle\right)}\right)\\
&\overset{Eq.\ (24)}{\geq} \sum_{i\in B_k}\log\left((N_k-1) + e^{-1}\sum_{\substack{k'\in[K]\\k'\neq k}}N_{k'}\exp\left(\langle \bar{z}_k, \bar{z}_{k'}\rangle\right)\right)\\
&= N_k\log\left((N_k-1) + e^{-1}\sum_{\substack{k'\in[K]\\k'\neq k}}N_{k'}\exp\left(\langle \bar{z}_k, \bar{z}_{k'}\rangle\right)\right),
\end{aligned} \tag{25}$$

where equality is attained if and only if the following condition holds:

(B1) $\forall i \in B_k$, $z_i = \bar{z}_k$.

Here (B1) and (C3) express the same condition. □

Lemma 3. *Let $\bar{Z}$ be an K point configuration (assuming all $\bar{z}s$ being normalized), $\bar{Z} = (\bar{z}_1, \ldots, \bar{z}_K) \in (\mathbb{S}^{h-1})^K$, and $K \leq h+1$, it holds that:*

$$\sum_{k=1}^{K} a \log\left((a-1) + b\left(\sum_{\substack{k' \in [K] \\ k' \neq k}} \exp\left(\langle \bar{z}_k, \bar{z}_{k'} \rangle\right) + c\right)\right) \geq Ka \log\left((a-1) + b\left((K-1)\exp\left(\beta\right) + c\right)\right), \tag{26}$$

where $a > 1$, $b, c > 0$, and equality is attained if and only if all of the following conditions hold:

(B2) $\forall k \in [K]$ and $k' \in [K] \backslash \{k\}$, $\langle \bar{z}_k, \bar{z}_{k'} \rangle = \beta$.

(B3) There exists a configuration of $\bar{Z} = (\bar{z}_1, \ldots, \bar{z}_K)$ such that (B2) holds.

(Case 1) $K = h+1$: $\beta = -\frac{1}{N-1}$ or $\beta = 1$

(Case 2) $K < h+1$: $-\frac{1}{N-1} \leq \beta \leq 1$

Proof. Since $f(x) = \exp(x)$ is a convex function, applying Jensen's inequality, we have

$$\begin{aligned}
\sum_{\substack{k' \in [K] \\ k' \neq k}} \exp\left(\langle \bar{z}_k, \bar{z}_{k'} \rangle\right) &\geq (K-1)\exp\left(\frac{1}{K-1}\sum_{\substack{k' \in [K] \\ k' \neq k}} \langle \bar{z}_k, \bar{z}_{k'} \rangle\right) \\
&= (K-1)\exp\left(\frac{1}{K-1}\sum_{\substack{k' \in [K] \\ k' \neq k}} \beta_k\right) \\
&= (K-1)\exp\left(\beta_k\right),
\end{aligned} \tag{27}$$

where equality is attained if and only if all of the following conditions hold:

(C4) $\forall k \in [K]$ and $k' \in [K] \backslash \{k\}$, $\langle \bar{z}_k, \bar{z}_{k'} \rangle = \beta_k$.

(C5) There exists a configuration of $\bar{Z} = (\bar{z}_1, \ldots, \bar{z}_K)$ such that (C4) holds.

When $a > 1, b, c > 0$, $f(x) = \log\left((a-1) + b\left(\exp\left(x\right) + c\right)\right)$ is also a convex function. By Jensen's inequality, we have

$$\begin{aligned}
\sum_{k=1}^{K} a \log\left((a-1) + b\left(\exp\left(\beta_k\right) + c\right)\right) &\geq Ka \log\left((a-1) + b\left(\exp\left(\frac{1}{K}\sum_{k=1}^{K}\beta_k\right) + c\right)\right) \\
&= Ka \log\left((a-1) + b\left(\exp\left(\frac{1}{K}\sum_{k=1}^{K}\beta\right) + c\right)\right) \\
&= Ka \log\left((a-1) + b\left(\exp\left(\beta\right) + c\right)\right),
\end{aligned} \tag{28}$$

where equality is attained if and only if all of the following conditions hold:

(C6) $\forall k \in [K]$ and $k' \in [K] \backslash \{k\}$, $\beta_k = \beta_{k'} = \beta$.

(C7) There exists a configuration of $\bar{Z} = (\bar{z}_1, \ldots, \bar{z}_K)$ such that (C6) holds.

Note that when (C6) and (C7) hold, (C4) and (C5) hold too. And according to Lemma 1, when $K \leq h+1$, Case 2 and Case 3 in Lemma 1 satisfy (C7). And hence

$$\sum_{k=1}^{K} a \log \left((a-1) + b \left(\sum_{\substack{k' \in [K] \\ k' \neq k}} \exp\left(\langle \bar{z}_k, \bar{z}_{k'} \rangle\right) + c \right) \right) \geq Ka \log\left((a-1) + b\left((K-1)\exp(\beta) + c\right)\right), \tag{29}$$

where equality is attained if and only if all of the following conditions hold:

(B2) $\forall k \in [K]$ and $k' \in [K] \backslash \{k\}$, $\langle \bar{z}_k, \bar{z}_{k'} \rangle = \beta$.

(B3) There exists a configuration of $\bar{Z} = (\bar{z}_1, \ldots, \bar{z}_K)$ such that (B2) holds

(Case 1) $K = h+1$: $\beta = -\frac{1}{N-1}$ or $\beta = 1$

(Case 2) $K < h+1$: $-\frac{1}{N-1} \leq \beta \leq 1$

□

B.2 PROOF OF THEOREM 2

In this section, we provide proofs for Theorem 2 proposed in Sec. 3.2. For the convenience of your reading, let's recall some related notions and definitions.

- $h, N, K \in \mathbb{N}$
- $\mathcal{Z} = \mathbb{R}^h$
- $\mathbb{S}^{h-1} = \left\{z \in \mathbb{R}^h : \|z\| = 1\right\}$
- $\mathcal{Y} = \{1, \ldots, K\} = [K]$
- $B = \{1, \ldots, N\} = [N]$
- $B_k = \{i : i \in B, y_i = k\}$
- $N_k = |B_k|$

Definition 1 (Supervised contrastive loss) Let Z be an N point configuration (assuming all zs being normalized), $Z = (z_1, \ldots, z_N) \in (\mathbb{S}^{h-1})^N$, with labels $Y = (y_1, \ldots, y_N) \in ([K])^N$, and $K \leq h+1$. Let $B = [N]$, $B_k = \{i : i \in B, y_i = k\}$ and $N_k = |B_k|$. The supervised contrastive loss $\mathcal{L}_{\mathrm{SC}}(\cdot; Y) : (\mathbb{S}^{h-1})^N \to \mathbb{R}$ is defined as:

$$\mathcal{L}_{\mathrm{SC}} = \sum_{k=1}^{K} \sum_{i \in B_k} \mathcal{L}_{\mathrm{SC}}^{k,i}, \text{ where } \mathcal{L}_{\mathrm{SC}}^{i} = -\frac{\mathbb{1}_{\{N_k > 1\}}}{N_k - 1} \sum_{j \in B_k \setminus \{i\}} \log\left(\frac{\exp\left(\langle z_i, z_j \rangle\right)}{\sum_{l \in B \setminus \{i\}} \exp\left(\langle z_i, z_l \rangle\right)}\right).$$

Theorem 2 Let Z be an N point configuration (assuming all zs being normalized), $Z = (z_1, \ldots, z_N) \in (\mathbb{S}^{h-1})^N$, with labels $Y = (y_1, \ldots, y_N) \in ([K])^N$, and $3 \leq K \leq h+1$. If $\forall k \in \{2, \ldots, K\}, N_k = a_2 \geq 4$, and $\exists \rho > 0$ such that $N_1 = a_1 = \rho a_2 > 1$, it holds that:

$$\mathcal{L}_{\mathrm{SC}} \geq f(\cos(\theta_1), \cos(\theta_2)),$$

where $f(\cdot) : \mathbb{R} \times \mathbb{R} \to \mathbb{R}$ is defined as:

$$\begin{aligned} f(x_1, x_2) = {} & \rho a_2 \log\left((\rho a_2 - 1) + e^{-1}(K-1) a_2 \exp(x_1)\right) \\ & + (K-1) a_2 \log\left((a_2 - 1) + e^{-1}\left((K-2) a_2 \exp(x_2) + \rho a_2 \exp(x_1)\right)\right), \end{aligned}$$

and equality is attained if and only if there exists a configuration of $\bar{Z} = (\bar{z}_1, \ldots, \bar{z}_K) \in (\mathbb{S}^{h-1})^K$ such that:

(A3) $i \in B_k$, $z_i = \bar{z}_k$.

(A4) $\forall k, k' \in \{2, \ldots, K\}$ and $k \neq k'$, $\langle \bar{z}_1, \bar{z}_k \rangle = \cos(\theta_1)$, $\langle \bar{z}_k, \bar{z}_{k'} \rangle = \cos(\theta_2), and \cos(\theta_2) = \frac{(K-1)\cos^2(\theta_1) - 1}{K-2}$.

(A5) (Case 1) $\rho < 1$: $\theta_1 \in \left(\cos^{-1}(-\frac{1}{K-1}), 0\right)$ such that $f'_{x_1}(\cos(\theta_1)) = 0$.

(Case 2) $\rho = 1$: $\theta_1 = \cos^{-1}(-\frac{1}{K-1})$.

(Case 3) $1 < \rho < R(K, a_2)$: $\theta_1 \in \left(-\pi, \cos^{-1}(-\frac{1}{K-1})\right)$ such that $f'_{x_1}(\cos(\theta_1)) = 0$.

(Case 4) $\rho \geq R(K, a_2)$: $\theta_1 = -\pi$.

Let $b_1 = (K-1)(1+e^{-2}-2e^2)a_2 - 2$, $b_2 = 8(1+e^{-2})(K-1)a_2((K-1)a_2 - e^2)$, then $R(K, a_2)$ defined as:

$$R(K, a_2) = \frac{-b_1 + \sqrt{b_1^2 + b_2}}{2(1+e^{-2})a_2}.$$

B.2.1 STEPS OF PROOF

Following Eq. (14), Eq. (15) and Lemma 2 in Appendix B.1.1, we have

$$\mathcal{L}_{\mathrm{SC}} \overset{Lemma\ 2}{\geq} \sum_{k=1}^{K} N_k \log \left((N_k - 1) + e^{-1} \sum_{\substack{k' \in [K] \\ k' \neq k}} N_{k'} \exp\left(\langle \bar{z}_k, \bar{z}_{k'} \rangle\right) \right). \tag{30}$$

where equality is attained if and only if there exists a configuration of $\bar{Z} = (\bar{z}_1, \ldots, \bar{z}_K) \in (\mathbb{S}^{h-1})^K$ such that:

(A3) $i \in B_k$, $z_i = \bar{z}_k$.

When $3 \leq K \leq h+1$, $\forall k \in \{2, \ldots, K\}$, $N_k = a_2 \geq 4$, and $\exists \rho > 0$ such that $N_1 = a_1 = \rho a_2 > 1$, following Lemma 5, we have:

$$\begin{aligned} \mathcal{L}_{\mathrm{SC}} &\geq \sum_{k=1}^{K} N_k \log \left((N_k - 1) + e^{-1} \sum_{\substack{k' \in [K] \\ k' \neq k}} N_{k'} \exp\left(\langle \bar{z}_k, \bar{z}_{k'} \rangle\right) \right) \\ &\overset{Lemma\ 5}{\geq} f(\beta_1), \end{aligned} \tag{31}$$

where $f(x)$ is:

$$\begin{aligned} f(x) = {} & \rho a_2 \log\left((\rho a_2 - 1) + e^{-1} (K-1) a_2 \exp(x) \right) \\ & + (K-1) a_2 \log\left((a_2 - 1) + e^{-1} \left((K-2) a_2 \exp\left(\frac{(K-1)x^2 - 1}{K-2} \right) + \rho a_2 \exp(x) \right) \right), \end{aligned} \tag{32}$$

and equality is attained if and only if all of the following conditions hold:

(A4) $\forall k, k' \in \{2, \ldots, K\}$ and $k \neq k'$, $\langle \bar{z}_1, \bar{z}_k \rangle = \cos(\theta_1)$, $\langle \bar{z}_k, \bar{z}_{k'} \rangle = \cos(\theta_2), and \cos(\theta_2) = \frac{(K-1)\cos^2(\theta_1) - 1}{K-2}$.

(A5) (Case 1) $\rho < 1$: $\theta_1 \in \left(\cos^{-1}(-\frac{1}{K-1}), 0 \right)$ such that $f'_{x_1}(\cos(\theta_1)) = 0$.

(Case 2) $\rho = 1$: $\theta_1 = \cos^{-1}(-\frac{1}{K-1})$.

(Case 3) $1 < \rho < R(K, a_2)$: $\theta_1 \in \left(-\pi, \cos^{-1}(-\frac{1}{K-1}) \right)$ such that $f'_{x_1}(\cos(\theta_1)) = 0$.

(Case 4) $\rho \geq R(K, a_2)$: $\theta_1 = -\pi$.

Here $b_1 = (K-1)(1+e^{-2}-2e^2)a_2 - 2$ and $b_2 = 8(1+e^{-2})(K-1)a_2((K-1)a_2 - e^2)$. $R(K, a_2)$ is given by:

$$R(K, a_2) = \frac{-b_1 + \sqrt{b_1^2 + b_2}}{2(1+e^{-2})a_2}. \tag{33}$$

B.2.2 LEMMAS PART 2

In this section,we provide definitions and proofs of lemmas that are used for the proof of Theorem 2.

Lemma 4. *Let $\bar{Z}$ be an K point configuration (assuming all $\bar{z}s$ being normalized), $\bar{Z} = (\bar{z}_1, \dots, \bar{z}_K) \in (\mathbb{S}^{h-1})^K$, and $3 \leq K \leq h+1$. If $\forall k, k' \in \{2, \dots, K\}$ and $k \neq k'$ such that $\langle \bar{z}_k, \bar{z}_{k'} \rangle = \beta_2$ and $\beta_1 = min_c\{c : \langle \bar{z}_1, \bar{z}_k \rangle = c\}$, it holds that:*

$$\beta_2 = \frac{(K-1)\,\beta_1^2 - 1}{K-2}, \text{ where } -1 \leq \beta_1 \leq 0 \text{ and } -\frac{1}{K-2} \leq \beta_2 < 1. \tag{34}$$

Proof. Without loss of generality, we assume $(\bar{z}_2, \dots, \bar{z}_K)$ form an equidistant simplex in the southern hemisphere of $\mathbb{S}^{h-1}$ and then $\bar{z}_1$ is at the north pole. Let $l = \|\frac{1}{K-1}\sum_{k=2}^{K} z_k\|$, we have $l = |\beta_1|$, then

$$\begin{aligned}
\|l\|^2 &= \left\| \frac{1}{K-1} \sum_{k=2}^{K} z_k \right\|^2 = \left\langle \frac{1}{K-1} \sum_{k=2}^{K} z_k, \frac{1}{K-1} \sum_{k=2}^{K} z_k \right\rangle \\
&= \frac{1}{(K-1)^2} \left(\sum_{k=2}^{K} z_k \langle z_k, z_k \rangle + \sum_{\substack{k,k'=2 \\ k \neq k'}}^{K} \langle z_k, z_{k'} \rangle \right) \\
&= \frac{1}{(K-1)^2} \left((K-1) + (K-1)(K-2)\,\beta_2 \right) \\
&= |\beta_1|^2,
\end{aligned} \tag{35}$$

so we have

$$\beta_2 = \frac{(K-1)\,\beta_1^2 - 1}{K-2}. \tag{36}$$

According to Lemma 1, $-\frac{1}{K-2} \leq \beta_2 < 1$ and so $-1 \leq \beta_1 \leq 0$. □

Lemma 5. *Let $\bar{Z}$ be an K point configuration (assuming all $\bar{z}s$ being normalized), $\bar{Z} = (\bar{z}_1, \dots, \bar{z}_K) \in (\mathbb{S}^{h-1})^K$, and $3 \leq K \leq h+1$. Let $B = [N]$, $B_k = \{i : i \in B, y_i = k\}$ and $N_k = |B_k|$. Let $\mathcal{J}(\cdot) : (\mathbb{S}^{h-1})^K \to \mathbb{R}$ is defined as:*

$$\mathcal{J}(\bar{Z}) = \sum_{k=1}^{K} N_k \log \left((N_k - 1) + e^{-1} \sum_{\substack{k' \in [K] \\ k' \neq k}} N_{k'} \exp\left(\langle \bar{z}_k, \bar{z}_{k'} \rangle \right) \right), \tag{37}$$

If $\forall k \in \{2, \dots, K\}, N_k = a_2 \geq 4$, and $\exists \rho > 0$ such that $N_1 = a_1 = \rho a_2 > 1$, it holds that:

$$\mathcal{J}(\bar{Z}) \geq f(\beta_1), \tag{38}$$

where $f(\cdot) : \mathbb{R} \to \mathbb{R}$ is defined as:

$$\begin{aligned}
f(x) = {} & \rho a_2 \log\left((\rho a_2 - 1) + e^{-1} (K-1)\, a_2 \exp(x) \right) \\
& + (K-1) a_2 \log\left((a_2 - 1) + e^{-1} \left((K-2)\, a_2 \exp\left(\frac{(K-1)\,x^2 - 1}{K-2} \right) + \rho a_2 \exp(x) \right) \right),
\end{aligned} \tag{39}$$

and equality is attained if and only if all of the following conditions hold:

(B4) $\forall k, k' \in \{2, \ldots, K\}$ *and* $k \neq k'$, $\langle \bar{z}_1, \bar{z}_k \rangle = \beta_1$ *and* $\langle \bar{z}_k, \bar{z}_{k'} \rangle = \beta_2 = \frac{(K-1)\beta_1^2 - 1}{K-2}$.

(B5) (Case 1) $\rho < 1$*:* $\hat{x} \in (-\frac{1}{K-1}, 0)$.
(Case 2) $\rho = 1$*:* $\hat{x} = -\frac{1}{K-1}$.
(Case 3) $1 < \rho < R(K, a_2)$*:* $\hat{x} \in (-1, -\frac{1}{K-1})$.
(Case 4) $\rho \geq R(K, a_2)$*:* $\hat{x} = -1$.

Here $b_1 = (K-1)(1+e^{-2}-2e^2)a_2 - 2$ *and* $b_2 = 8(1+e^{-2})(K-1)a_2((K-1)a_2 - e^2)$. $R(K, a_2)$ *is given by:*

$$R(K, a_2) = \frac{-b_1 + \sqrt{b_1^2 + b_2}}{2(1+e^{-2})a_2}. \tag{40}$$

Proof. When $N_1 = a_1, \forall k \in \{2, \ldots, K\}, N_k = a_2$, $a_1 = \rho a_2$, then

$$\begin{aligned}
\mathcal{J}(\bar{Z}) &= \sum_{k=1}^{K} N_k \log \left((N_k - 1) + e^{-1} \sum_{\substack{k' \in [K] \\ k' \neq k}} N_{k'} \exp\left(\langle \bar{z}_k, \bar{z}_{k'} \rangle\right) \right) \\
&= a_1 \log \left((a_1 - 1) + e^{-1} \sum_{k'=2}^{K} a_2 \exp\left(\langle \bar{z}_1, \bar{z}_{k'} \rangle\right) \right) \\
&+ \sum_{k=2}^{K} a_2 \log \left((a_2 - 1) + e^{-1} \left(\sum_{\substack{k'=2 \\ k' \neq k}}^{K} a_2 \exp\left(\langle \bar{z}_k, \bar{z}_{k'} \rangle\right) + a_1 \exp\left(\langle \bar{z}_k, \bar{z}_1 \rangle\right) \right) \right).
\end{aligned} \tag{41}$$

According to Eq. (27) in the Lemma 3, the first term can be bounded low:

$$\begin{aligned}
& a_1 \log \left((a_1 - 1) + e^{-1} \sum_{k'=2}^{K} a_2 \exp\left(\langle \bar{z}_1, \bar{z}_{k'} \rangle\right) \right) \\
& \geq a_1 \log \left((a_1 - 1) + e^{-1} (K-1) a_2 \exp(\beta_1) \right) \\
& = f_1(\beta_1).
\end{aligned} \tag{42}$$

Similarly, the second term can be bounded low:

$$\begin{aligned}
& \sum_{k=2}^{K} a_2 \log \left((a_2 - 1) + e^{-1} \left(\sum_{\substack{k'=2 \\ k' \neq k}}^{K} a_2 \exp\left(\langle \bar{z}_k, \bar{z}_{k'} \rangle\right) + a_1 \exp\left(\langle \bar{z}_k, \bar{z}_1 \rangle\right) \right) \right) \\
& \geq (K-1) a_2 \log \left((a_2 - 1) + e^{-1} \left((K-2) a_2 \exp(\beta_2) + a_1 \exp(\beta_1) \right) \right) \\
& = f_2(\beta_1).
\end{aligned} \tag{43}$$

Combining Eq. (42), Eq. (43) and Lemma 4, we have

$$\begin{aligned}
\mathcal{J}(\bar{Z}) &\geq \rho a_2 \log \left((\rho a_2 - 1) + e^{-1} (K-1) a_2 \exp(\beta_1) \right) \\
&+ (K-1) a_2 \log \left((a_2 - 1) + e^{-1} \left((K-2) a_2 \exp\left(\frac{(K-1)\beta_1^2 - 1}{K-2} \right) + \rho a_2 \exp(\beta_1) \right) \right) \\
&= f_1(\beta_1) + f_2(\beta_1) = f(\beta_1),
\end{aligned} \tag{44}$$

where $-1 \leq \beta_1 \leq 0$ and equality is attained if and only if the following condition holds:

(C8) $\forall k, k' \in \{2, \ldots, K\}$ and $k \neq k'$, $\langle \bar{z}_1, \bar{z}_k \rangle = \beta_1$ and $\langle \bar{z}_k, \bar{z}_{k'} \rangle = \beta_2 = \frac{(K-1)\beta_1^2 - 1}{K-2}$.

To find the minimal value of $f(x)$ when $-1 \leq x \leq 0$, we need to find the critical value of $f'(x) = 0$ and the sign of $f'(x)$. Direct computation of these value is difficult but can be found with scientific computation software once we know all parameters in a specific case. For analytical purpose, we investigate the general form. Let $3 \leq K \leq h+1, \rho > 0, a_1 = \rho a_2 > 1, a_2 \geq 4$ and $-1 \leq x \leq 0$.

We first study key properties of $f(x)$.

(P1) We start by analyzing the derivatives of $f(x)$. The first and the second derivative of $f_1(x)$ are:

$$f_1'(x) = e^{-1}(K-1)a_2^2 \frac{\rho e^x}{(\rho a_2 - 1) + e^{-1}(K-1)a_2 e^x} > 0, \tag{45}$$

and

$$f_1''(x) = e^{-1}(K-1)a_2^2 \frac{(\rho a_2 - 1)\, \rho e^x}{((\rho a_2 - 1) + e^{-1}(K-1)a_2 e^x)^2} > 0. \tag{46}$$

Here $f_1'(x)$ and $f_1''(x)$ are strictly positive because every term of them is positive. The First derivative of $f_2(x)$ is:

$$f_2'(x) = e^{-1}(K-1)a_2^2 \frac{2(K-1)x \exp\left(\frac{(K-1)x^2-1}{K-2}\right) + \rho e^x}{(a_2 - 1) + e^{-1}\left((K-2)a_2 \exp\left(\frac{(K-1)x^2-1}{K-2}\right) + \rho a_2 e^x\right)}. \tag{47}$$

The second derivative of $f_2(x)$ is difficult to calculate directly. We instead do it in another way. If we take $y(x) = \exp(\frac{(K-1)x^2-1}{K-2})$ as a variable, we have:

$$\frac{dy(x)}{dx} = \frac{2(K-1)x}{K-2} \exp(\frac{(K-1)x^2 - 1}{K-2}) < 0. \tag{48}$$

It holds because every term but x (negative) in $\frac{dy(x)}{dx}$ is positive. And $f_2'(x)$ can be written as:

$$\begin{aligned} f_2'(x) = G(x,y) &= e^{-1}(K-1)a_2^2 \frac{\rho e^x + 2(K-1)xy}{(a_2 - 1) + e^{-1}\rho a_2 e^x + e^{-1}(K-2)a_2 y} \\ &= c_1 \frac{c_2 + c_3 y}{c_4 + c_5 y}, \end{aligned} \tag{49}$$

where $c_1 = e^{-1}(K-1)a_2^2 > 0$, $c_2 = \rho e^x$, $c_3 = 2(K-1)x$, $c_4 = (a_2 - 1) + e^{-1}\rho a_2 e^x$, $c_5 = e^{-1}(K-2)a_2$ and $-1 \leq x \leq 0$. Then the partial derivative of G to y is:

$$\begin{aligned} \frac{\partial G(x,y)}{\partial y} &= \frac{c_1}{(c_4 + c_5 y)^2} (c_3 c_4 - c_2 c_5) \\ &= \frac{c_1}{(c_4 + c_5 y)^2} \left((2(K-1)x - (K-2))\, e^{-1}\rho a_2 e^x + (a_2 - 1)2(K-1)x\right) \\ &< 0. \end{aligned} \tag{50}$$

Here $\frac{\partial G}{\partial y}$ is strictly negative because $(2(K-1)x - (K-2))$ and x are negative while all other terms are positive. Similarly, $f_2'(x)$ can be written as:

$$
\begin{aligned}
f_2'(x) = G(x,y) &= e^{-1}(K-1)a_2^2 \frac{2(K-1)yx + \rho e^x}{(a_2-1) + e^{-1}(K-2)a_2 y + e^{-1}\rho a_2 e^x} \\
&= c_1 \frac{c_6 x + c_7 e^x}{c_8 + c_9 e^x},
\end{aligned} \tag{51}
$$

where $c_1 = e^{-1}(K-1)a_2^2$, $c_6 = 2(K-1)y$, $c_7 = \rho$, $c_8 = (a_2-1)+e^{-1}(K-2)a_2 y$, $c_9 = e^{-1}\rho a_2$ and $-1 \le x \le 0$. Here $c_1, c_6, c_7, c_8, c_9 > 0$. Then the partial derivative of G to x is:

$$
\frac{\partial G(x,y)}{\partial x} = \frac{c_1}{(c_8 + c_9 e^x)^2}\left((1-x)c_6 c_9 e^x + c_7 c_8 e^x + c_6 c_8\right) > 0. \tag{52}
$$

Here $\frac{\partial G}{\partial x}$ is strictly positive because every term of it is positive. Combining Eq. (48), Eq. (50) and Eq. (52), we have:

$$
f_2''(x) = \frac{\partial G(x,y)}{\partial x} + \frac{\partial G(x,y)}{\partial y} \cdot \frac{dy(x)}{x} > 0. \tag{53}
$$

Thus, according to Eq. (46) and Eq. (53), the second derivative of $f(x)$ is:

$$
f''(x) = f_1''(x) + f_2''(x) > 0. \tag{54}
$$

This reveals that $f(x)$ is a convex function.

(P2) Next, we analyze how ρ affects $f'(x)$. If we view ρ as a variable instead of a constant, we have

$$
\begin{aligned}
f_1'(x) = H_1(x,\rho) &= e^{-1}(K-1)a_2^2 e^x \frac{\rho}{a_2\rho + e^{-1}(K-1)a_2 e^x - 1} \\
&= c_1 \frac{\rho}{a_2\rho + c_2},
\end{aligned} \tag{55}
$$

where $c_1 = e^{-1}(K-1)a_2^2 e^x > 0$, $c_2 = e^{-1}(K-1)a_2 e^x - 1$. Then the partial derivative of H_1 to ρ is given by:

$$
\begin{aligned}
\frac{\partial H_1(x,\rho)}{\partial \rho} &= c_1 \frac{c_2}{(a_2\rho + c_2)^2} = c_1 \frac{e^{-1}(K-1)a_2 e^x - 1}{(a_2\rho + c_2)^2} \\
&> c_1 \frac{e^{-1}(3-1)a_2 e^{-1} - 1}{(a_2\rho + c_2)^2} = c_1 \frac{2e^{-2}a_2 - 1}{(a_2\rho + c_2)^2} \\
&> 0.
\end{aligned} \tag{56}
$$

When $K \ge 3$ and $-1 \le x \le 0$, $e^{-1}(K-1)a_2 e^x > 2e^{-2}a_2$. So as long as $a_2 \ge 4 > \frac{e^2}{2}$ holds, $c_2 > 0$ holds. Similarly, we also have:

$$
\begin{aligned}
f_2'(x) = H_2(x,\rho) &= e^{-1}(K-1)a_2^2 e^x \frac{\rho + 2(K-1)xe^{-x}\exp\left(\frac{(K-1)x^2-1}{K-2}\right)}{e^{-1}a_2 e^x \rho + (a_2-1) + e^{-1}(K-2)a_2 \exp\left(\frac{(K-1)x^2-1}{K-2}\right)} \\
&= c_1 \frac{\rho + c_3}{c_4\rho + c_5},
\end{aligned} \tag{57}
$$

where $c_1 = e^{-1}(K-1)a_2^2 e^x$ ¿ 0, $c_3 = 2(K-1)xe^{-x}\exp\left(\frac{(K-1)x^2-1}{K-2}\right)$, $c_4 = e^{-1}a_2 e^x$ and $c_5 = (a_2-1) + e^{-1}(K-2)a_2 \exp\left(\frac{(K-1)x^2-1}{K-2}\right)$. Then the partial derivative of H_2 to ρ is:

$$\begin{aligned}\frac{\partial H_2(x,\rho)}{\partial \rho} &= c_1 \frac{c_5 - c_3 c_4}{(c_4\rho + c_5)^2} = c_1 \frac{(a_2 - 1) + e^{-1} a_2 \left(-Kx\right) \exp\left(\frac{(K-1)x^2 - 1}{K-2}\right)}{(c_4\rho + c_5)^2} \\ &> 0.\end{aligned} \tag{58}$$

It holds because every term in $\frac{\partial H_2}{\partial \rho}$ is positive. Combining Eq. (55) to Eq. (58), we have

$$\begin{aligned} f'(x) &= f_1'(x) + f_2'(x) \\ &= H_1(x,\rho) + H_2(x,\rho) = H(x,\rho), \end{aligned} \tag{59}$$

and

$$\frac{\partial H(x,\rho)}{\partial \rho} = \frac{\partial H_1(x,\rho)}{\partial \rho} + \frac{\partial H_2(x,\rho)}{\partial \rho} > 0. \tag{60}$$

So $f'(x) = H(x,\rho)$ is an increasing function with respect to ρ.

With the above 2 key properties of $f(x)$ in hand. Now, let's check some important values.

(V1). When $x = 0$, we have:

$$\begin{aligned} f'(0) &= \frac{e^{-1}(K-1)\rho a_2^2}{(\rho a_2 - 1) + e^{-1}(K-1)a_2} + \frac{e^{-1}(K-1)\rho a_2^2}{(a_2 - 1) + e^{-1}\left((K-2)a_2 \exp\left(-\frac{1}{K-2}\right) + \rho a_2\right)} \\ &> 0. \end{aligned} \tag{61}$$

It holds because every term in $f'(0)$ is positive. This case shows that, when samples from $K-1$ equal-sized classes are well-trained, they form a $K-2$ regular simplex ($\beta_1 = 0$ and $\beta_2 = -\frac{1}{K-2}$). Once there comes samples from the Kth class, the original $K-2$ simplex starts to shrink as the loss goes down when β_1 decreases and β_2 increases.

(V2). When $x = -\frac{1}{K-1}$, we have:

$$\begin{aligned} f'(-\frac{1}{K-1}) &= H(-\frac{1}{K-1}, \rho) \\ &= \frac{e^{-1}(K-1)a_2^2 e^{-\frac{1}{K-1}}\rho}{(\rho a_2 - 1) + e^{-1}(K-1)a_2 e^{-\frac{1}{K-1}}} + \frac{e^{-1}(K-1)a_2^2 e^{-\frac{1}{K-1}}(\rho - 2)}{(a_2 - 1) + e^{-1}a_2 e^{-\frac{1}{K-1}}\left((K-2+\rho\right)}, \end{aligned} \tag{62}$$

and

$$H(-\frac{1}{K-1}, 1) = 0. \tag{63}$$

According to Eq. (59) and Eq. (60), $H(-\frac{1}{K-1}, \rho)$ is an increasing function with respect to ρ. Recalling that $f(x)$ is a convex function, with Eq. (62) and Eq. (63), we can conclude that:

(C9) When $\rho < 1$: $f'(-\frac{1}{K-1}) < H(-\frac{1}{K-1}, 1) = 0$. Since $f'(0) > 0$, according to the intermediate value theorem, there exists a critical point $\hat{x} \in (-\frac{1}{K-1}, 0)$, such that $f'(\hat{x}) = 0$, and $f(x)$ attains its minimal value at $x = \hat{x}$. If ρ increases, $f'(\hat{x})$ increases too. It leads to $f'(\hat{x}) > 0$, then there comes a new critical point $\tilde{x} \in (-\frac{1}{K-1}, \hat{x})$ where $f'(\tilde{x}) = 0$.

(C10) When $\rho = 1$: $f'(-\frac{1}{K-1}) = H(-\frac{1}{K-1}, 1) = 0$. So $\hat{x} = -\frac{1}{K-1}$ is the critical point and $f(x)$ attains its minimal value at $x = -\frac{1}{K-1}$.

(C11) When $\rho > 1$: $f'(-\frac{1}{K-1}) > H(-\frac{1}{K-1}, 1) = 0$. And $\forall x \in [-\frac{1}{K-1}, 0]$, $f'(x) > 0$ and $f(x) \geq f(-\frac{1}{K-1})$.

(V3). When $x = -1$, from (C7) and (C8) we know that $f'(-1) < 0$ if $\rho \leq 1$. Now let's only consider the case when $\rho > 1$.

$$\begin{aligned} f'(-1) &= \frac{e^{-2}(K-1)a_2^2\rho}{(\rho a_2 - 1) + e^{-2}(K-1)a_2} + (K-1)a_2^2 \frac{-2(K-1) + e^{-2}\rho}{(a_2 - 1) + (K-2)\,a_2 + e^{-2}\rho a_2} \\ &= e^{-2}(K-1)a_2^2 \left(\frac{\rho}{a_2\rho + e^{-2}(K-1)a_2 - 1} + \frac{\rho - 2(K-1)e^2}{e^{-2}a_2\rho + (K-1)\,a_2 - 1} \right) \\ &= e^{-2}(K-1)a_2^2 \left(\frac{\rho}{a_2\rho + c_1} + \frac{\rho + c_2}{e^{-2}a_2\rho + c_3} \right) \\ &= \frac{e^{-2}(K-1)a_2^2}{(a_2\rho + c_1)(e^{-2}a_2\rho + c_3)} \left((1 + e^{-2})a_2\rho^2 + (c_1 + c_3 + a_2c_2)\rho + c_1c_2 \right) \\ &= \frac{(K-1)e^{-2}a_2^2}{(a_2\rho + c_1)(e^{-2}a_2\rho + c_3)} \cdot L(\rho), \end{aligned} \tag{64}$$

where $c_1 = e^{-2}(K-1)a_2 - 1$, $c_2 = -2(K-1)e^2$, $c_3 = (K-1)\,a_2 - 1$ and:

$$\begin{aligned} L(\rho) &= (1 + e^{-2})a_2\rho^2 + (c_1 + c_3 + a_2c_2)\rho + c_1c_2 \\ &= (1 + e^{-2})a_2\rho^2 + ((K-1)(1 + e^{-2} - 2e^2)a_2 - 2)\rho - 2(K-1)((K-1)a_2 - e^2). \end{aligned} \tag{65}$$

When $K \geq 3$, as long as $a_2 \geq 4 > \frac{e^2}{2}$ holds, $c_1 > 2e^{-2}a_2 - 1 > 0$. Also $c_3 > 0$, so we have $\frac{(K-1)e^{-2}a_2^2}{(a_2\rho + c_1)(e^{-2}a_2\rho + c_3)} > 0$, then $f'(-1) \geq 0 \Leftrightarrow L(\rho) \geq 0$. To solve this inequality, let's first take a look the value:

$$\begin{aligned} M &= (c_1 + c_3 + a_2c_2)^2 - 4(1 + e^{-2})a_2c_1c_2 \\ &> -4(1 + e^{-2})a_2c_1c_2 \\ &= 8(1 + e^{-2})a_2(K-1)e^2c_1 \\ &> c_1 > 0. \end{aligned} \tag{66}$$

Let $b_1 = c_1 + c_3 + a_2c_2 = (K-1)(1 + e^{-2} - 2e^2)a_2 - 2 < 0$, $b_2 = -4(1 + e^{-2})a_2c_1c_2 = 8(1 + e^{-2})(K-1)a_2((K-1)a_2 - e^2) > 0$ and $M = b_1^2 + b_2 > 0$. Then the solution for $L(\rho) > 0$ and also $f'(-1) > 0$ is:

$$\rho \leq \frac{-b_1 - \sqrt{b_1^2 + b_2}}{2(1 + e^{-2})a_2} \text{or } \rho \geq \frac{-b_1 + \sqrt{b_1^2 + b_2}}{2(1 + e^{-2})a_2}. \tag{67}$$

Since $b_2 > 0$, then $\sqrt{b_1^2 + b_2} > -b_1$ and so $-b_1 - \sqrt{b_1^2 + b_2}$ ¡ 0. As we only consider the case where $\rho > 1$. We retain the right part of Eq. (67).

Combined with (C11), now we can conclude that: when $K \geq 3$ and $a_2 \geq 4$, let

$$R(K, a_2) = \frac{-b_1 + \sqrt{b_1^2 + b_2}}{2(1 + e^{-2})a_2}, \tag{68}$$

where $b_1 = (K-1)(1 + e^{-2} - 2e^2)a_2 - 2 < 0$ and $b_2 = 8(1 + e^{-2})(K-1)a_2((K-1)a_2 - e^2) > 0$

(C12) When $1 < \rho < R(K, a_2)$: $f'(-1) < 0$. Since $\forall x \in [-\frac{1}{K-1}, 0]$, $f'(x) > 0$, according to the intermediate value theorem, there exists a critical point $\hat{x} \in (-1, -\frac{1}{K-1})$, such that $f'(\hat{x}) = 0$ and $f(x)$ attains its minimal value when $x = \hat{x}$. If ρ increases, $f'(\hat{x})$ increases too. It leads to $f'(\hat{x}) > 0$, then there comes a new critical point $\tilde{x} \in (-1, \hat{x})$ where $f'(\tilde{x}) = 0$.

(C13) When $\rho \geq R(K, a_2)$: $f'(-1) \geq 0$. Then $\forall x \in [-1, 0]$, $f'(x) \geq 0$. $f(x)$ attains its minimal value when $x = -1$

Combining (C8) to (C13), we conclude that: $\mathcal{J}(\bar{Z})$ reach its minimal if and only if all of the following conditions hold:

(B4) $\forall k, k' \in \{2, \ldots, K\}$ and $k \neq k'$, $\langle \bar{z}_1, \bar{z}_k \rangle = \beta_1$ and $\langle \bar{z}_k, \bar{z}_{k'} \rangle = \beta_2 = \frac{(K-1)\beta_1^2 - 1}{K-2}$.

(B5) (Case 1) $\rho < 1$: $\hat{x} \in (-\frac{1}{K-1}, 0)$.
(Case 2) $\rho = 1$: $\hat{x} = -\frac{1}{K-1}$.
(Case 3) $1 < \rho < R(K, a_2)$: $\hat{x} \in (-1, -\frac{1}{K-1})$.
(Case 4) $\rho \geq R(K, a_2)$: $\hat{x} = -1$.

□

B.3 PROOF OF REMARK 2

Proof. Recall that:

$$R(K, a_2) = \frac{-b_1 + \sqrt{b_1^2 + b_2}}{2(1+e^{-2})a_2}. \tag{69}$$

where $b_1 = (K-1)(1+e^{-2}-2e^2)a_2 - 2$, $b_2 = 8(1+e^{-2})(K-1)a_2((K-1)a_2 - e^2)$. b_1 and b_2 in Eq. (69) can be roughly simplified as

$$\begin{aligned} \frac{b_1}{a_2} &= (K-1)(1+e^{-2}-2e^2) - \frac{2}{a_2} \approx (K-1)(1+e^{-2}-2e^2) = (K-1)b_1' \\ \frac{b_2}{a_2^2} &= 8(1+e^{-2})(K-1)((K-1) - \frac{e^2}{a_2}) \approx 8(1+e^{-2})(K-1)^2 = (K-1)^2 b_2', \end{aligned} \tag{70}$$

where $b_1' = (1+e^{-2}-2e^2)$ and $b_2' = 8(1+e^{-2})$. Then we can roughly simplifies $R(K, a_2)$ as a function only respect to K as:

$$\begin{aligned} R(K, a_2) &= \frac{-b_1 + \sqrt{b_1^2 + b_2}}{2(1+e^{-2})a_2} = \frac{-\frac{b_1}{a_2} + \sqrt{(\frac{b_1}{a_2})^2 + \frac{b_2}{a_2^2}}}{2(1+e^{-2})} \\ &\approx (K-1)\frac{-b_1' + \sqrt{{b_1'}^2 + b_2'}}{2(1+e^{-2})} \\ &= (K-1)\frac{-(1+e^{-2}-2e^2) + \sqrt{(1+e^{-2}-2e^2)^2 + 8(1+e^{-2})}}{2(1+e^{-2})} \\ &= R'(K) \\ &\approx 12.16(K-1) \end{aligned} \tag{71}$$

□