THE LIMITATIONS OF ADVERSARIAL TRAINING AND THE BLIND-SPOT ATTACK

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ABSTRACT

The adversarial training procedure proposed by Madry et al. (2018) is one of the most effective methods to defend against adversarial examples on deep neural networks (DNNs). Despite being very effective on MNIST, adversarial training on larger datasets like CIFAR and ImageNet achieves much worse results. In our paper, we shed some lights on the practicality and hardness of adversarial training by first showing that the effectiveness of adversarial training procedure on test set has a strong correlation with the distance between the test point and the manifold of training data. The test examples that are relatively far away from the manifold of training dataset are more likely to be vulnerable to adversarial attacks. Consequentially, adversarial training based defense is susceptible to a new class of attacks (*"blind-spot attack"*) where the input image resides in a "blind-spot" in the empirical distribution of training data but is still on the ground-truth data manifold. For MNIST, we found that these blind-spots can be easily found by simply scaling and shifting image pixel values. Most importantly, for large datasets with high dimensional and complex data manifold (CIFAR, ImageNet, etc), the existence of blind-spots in adversarial training makes the defense on any valid test examples almost impossible due to the curse of dimensionality.

1 INTRODUCTION

Since the discovery of adversarial examples in deep neural networks (DNNs) (Szegedy et al., 2013), adversarial training with the robustness optimization framework (Madry et al., 2018; Sinha et al., 2018) has become one of the most effective methods to defend against adversarial examples. A recent study by Athalye et al. (2018) showed that adversarial training does not cause obfuscated gradient and delivers promising results for defending adversarial examples on small datasets. Adversarial training approximately solves the following min-max optimization problem:

$$\min_{\theta} \mathop{\mathbb{E}}_{(x,y)\in\mathcal{X}} \left[\max_{\delta\in S} L(x+\delta; y; \theta) \right], \tag{1}$$

where $\mathcal{X}$ is the set of training data, L is the loss function, θ is the parameter of the network, and S is usually a norm constrained ℓ_p ball centered at 0. Madry et al. (2018) propose to use projected gradient descent (PGD) to approximately solve the maximization problem within $S = \{\delta \mid \|\delta\|_\infty \leq \epsilon\}$, where $\epsilon = 0.3$ for MNIST dataset on a 0-1 pixel scale, and $\epsilon = 8$ for CIFAR-10 dataset on a 0-255 pixel scale. This approach achieves impressive defending results on the MNIST test set: so far the best available white-box attacks by Zheng et al. (2018) can only decrease the test accuracy from approximately 98% to 88%[1]. However, on CIFAR-10 dataset, a simple 20-step PGD can decrease the test accuracy from 87% to less than 50%[2].

Currently, the effectiveness of adversarial training is measured on the test dataset. However, the adversarial training process itself is done on the training set. Suppose we can optimize (1) perfectly, then certified robustness may be obtained on those training data points. However, if the empirical distribution of training dataset differs from the true data distribution, drawing a test point from the true data distribution might be far away from the empirical distribution of training dataset and is not "covered" by the adversarial training procedure. For datasets that are relatively simple and has low intrinsic dimensions (MNIST, Fashion MNIST, etc), we can obtain enough training examples

[1] https://github.com/MadryLab/mnist_challenge [2] https://github.com/MadryLab/cifar10_challenge

to make sure adversarial training covers most part of the data distribution. For high dimensional datasets (CIFAR, ImageNet), adversarial training have been shown difficult (Kurakin et al., 2016; Tramèr et al., 2018) and only limited success was obtained.

A recent attack proposed by Song et al. (2018) shows that adversarial training can be defeated when the input image is produced by a generative model (for example, a generative adversarial network) rather than selected directly from the test examples. The generated images are well recognized by humans and thus valid images in the ground-truth data distribution. In our interpretation, this attack effective finds the "blind-spots" in the input space that the training data do not well cover.

For higher dimensional datasets, we hypothesize that many test images already fall into these blind-spots of training data and thus adversarial training only obtains a moderate level of robustness. It is interesting to see that for those test images that adversarial training fails to defend, if their distances (in some metrics) to the training dataset are indeed larger. In our paper, we try to explain the success of robust optimization based adversarial training and show the limitations of this approach when the test points are slightly off the empirical distribution of training data. Our main contributions are:

- We show that on the original set of test images, the effectiveness of adversarial training is highly correlated with the distance (in different distance metrics) from the test image to the distribution of training images. For MNIST and Fashion MNIST dataset, most test images are close the training data and very good robustness is observed on these points. For CIFAR, there is a clear trend that the adversarially trained network gradually loses its robustness property when the test images are further away from training data.
- We propose a method to estimate the distance between training set and test set using the K-L divergence, which is a good indicator of the success of adversarial training. On datasets where adversarial training does not perform well, this divergence tends to be larger.
- We identify a new class of attacks, "*blind-spot attacks*", where the input image resides in a "blind-spot" in the empirical distribution of training data (far enough from any training examples) but is still in the ground-truth data distribution (well recognized by humans and correctly classified by the model). Adversarial training cannot provide good robustness on these blind-spots. GAN based attacks by Song et al. (2018) is a successful attack in this class.
- We show that blind-spots can be easily found without using an more involved procedure like GAN. We propose a few simple transformations (changing contrast and background), that do not significantly affect MNIST and Fashion MNIST model's accuracy but make the adversarially trained models model vulnerable to adversarial attacks on these sets of transformed input images. These transformations effectively move the test images slightly out of the domain of training images, which does not affect generalization but poses a challenge for robust learning.
- Our results imply that current adversarial training procedures cannot scale to datasets with a large (intrinsic) dimension, where any practical amount of training data cannot cover all the blind-spots. This explains the limited success for applying adversarial training on ImageNet dataset, where many test images can be sufficiently far away from the empirical distribution of training dataset.

2 Related Works

2.1 Defending Against Adversarial Examples

Adversarial examples in DNNs have brought great threats to the deep learning-based AI applications such as autonomous driving and face recognition. Therefore, defending against adversarial examples is an urgent task before we can safely deploy deep learning models to a wider range of applications. Following the emergence of adversarial examples, various defense methods have been proposed recently, such as defensive distillation in Papernot et al. (2016) and feature squeezing in Xu et al. (2017). Some of these defense methods have been proven vulnerable or ineffective under strong attack methods such as C&W in Carlini & Wagner (2017). Another category of recent defense is gradient masking or obfuscated gradient (Buckman et al. (2018); Ma et al. (2018); Guo et al. (2017); Song et al. (2017); Samangouei et al. (2018)), but these methods are also successfully evaded by the stronger BPDA attack (Athalye et al. (2018)). Randomization in DNNs (Dhillon et al., 2018; Xie et al., 2017; Liu et al., 2018) is also used to reduce the success rate of adversarial attacks, however, it usually incurs additional computational costs and still cannot fully defend against an adaptive attacker (Athalye et al., 2018; Athalye & Sutskever, 2017).

Another effective defense method is adversarial training, which trains the model with adversarial examples freshly generated during the entire training process. First introduced by Goodfellow et al., adversarial training demonstrates the state-of-the-art defending performance. Madry et al. (2018) formulated the adversarial training procedure into a min-max robust optimization problem and has achieved state-of-the-art defending performance on MNIST and CIFAR datasets. Several attacks have been proposed to attack the model release by Madry et al. (2018). On the MNIST testset, so far the best attack by Zheng et al. (2018) can only reduce the test accuracy from 98% to 88%. Analysis by Athalye et al. (2018) shows that this adversarial training framework does not obfuscate gradient and truly increases model robustness; gradient based attacks with random starts can only achieve less than 10% success rate with given distortion constraints and are unable to penetrate this defense. On the other hand, attacking adversarial training using generative models have also been investigated; both Xiao et al. (2018) and Song et al. (2018) propose to use GANs to produce adversarial examples in black-box and white-box settings, respectively.

Finally, certified defense methods were proposed. Certified defenses are able to provably increase model robustness, achieve good performance (i.e., test accuracy on natural images does not drop significantly and training is computationally feasible), and can be applied to medium-sized networks with multiple layers. Notably, Sinha et al. (2018) analyzes adversarial training using distributional robust optimization techniques. Kolter & Wong (2018); Wong et al. (2018) proposed a robustness certificate based on the dual of a convex relaxation for ReLU networks, and used it for training to provably increase robustness. During training, certified defense methods can provably guarantee that the model is robust on most (if not all) training examples

2.2 Analyzing Adversarial Examples

Along with the attack-defense arms race, some insightful findings have been discovered to understand the natural of adversarial examples, both theoretically and experimentally. Schmidt et al. (2018) show that even for a simple data distribution of two class-conditional Gaussians, robust generalization requires significantly larger number of samples than standard generalization. Cullina et al. (2018) extend the well-known PAC learning theory to the case with adversaries, and derive the adversarial VC-dimension which can be either larger or smaller than the standard VC-dimension. Bubeck et al. (2018) conjecture that a robust classifier can be computationally intractable to find, and proved the computation hardness under statistical query (SQ) model. Additionally, finding the safe area approximately is computationally hard according to Katz et al. (2017) and Weng et al. (2018). Mahloujifar et al. (2018) explain the prevalence of adversarial examples by making a connection to the "concentration of measure" phenomenon in metric measure spaces. Tsipras et al. (2018) discover that data examples consist of robust and non-robust features and adversarial training tends to find robust features that have strongly-correlations with the labels. Su et al. (2018) conduct large scale experiments on ImageNet and find a negative correlation between robustness and accuracy.

Both adversarial training and certified defence achieve state-of-the-art robustness performance on training data, but it is still unknown if the trained model has good *robust generalization* property. Typically, we evaluate the robustness of a model by computing a upper bound of error on the test set; specifically, given a norm bounded distortion ϵ, we verify if each image in test set has a robustness certificate. There might exist test images that are still within the capability of standard generalization (i.e., correctly classified by DNNs with high confidence, and well recognized by humans), but behaves badly in robust generalization (i.e., adversarial examples can be easily found). Our paper complements those existing findings by showing the strong correlation between the effectiveness of adversarial defenses (both adversarial training and certified defenses) and the distance between training data and test points. Additionally, we show that a tiny shift in input domain (which may or may not be detectable in embedding space) can easily destroy the robustness property of an robust model.

3 Methodology

3.1 Measuring the distance between training dataset and a test data point

To verify the correlation between the effectiveness of adversarial training and how close a test point is to the training dataset, we need to propose a reasonable distance metric between a test example

and a set of training examples. However, defining a meaningful distance metric for high dimensional image data is a challenging problem. Naively using an Euclidean distance metric in the input space of images works poorly as it does not reflect the true distance between the images on their ground-truth manifold. One strategy is to use (kernel-)PCA, t-SNE (Maaten & Hinton, 2008), or UMAP (McInnes & Healy, 2018) to reduce the dimension of training data to a low dimensional space, and then define distance in that space. These methods are sufficient for small and simple datasets like MNIST, but for more general and complicated dataset like CIFAR, extracting a meaningful low-dimensional manifold directly on the input space can be really challenging.

On the other hand, using a DNN to extract features of input images and measuring the distance in the deep feature embedding space has demonstrated better performance in many applications (Hu et al., 2014; 2015), since DNN models can capture the manifold of image data much better than simple methods such as PCA or t-SNE. Although we can form an empirical distribution using kernel density estimation (KDE) on the deep feature embedding space and then obtain probability densities for test points, our experiments showed that KDE work poorly because the features extracted by DNNs are still high dimensional (hundreds or thousands dimensions).

Taking the above considerations into account, we propose a simple and intuitive distance metric using deep feature embeddings and k-nearest neighbour. Given a feature extraction neural network $h(x)$, a set of n training data points $\mathcal{X}_{\text{train}} = \{x^1_{\text{train}}, x^2_{\text{train}}, \cdots, x^n_{\text{train}}\}$, and a set of m test data points $\mathcal{X}_{\text{test}} = \{x^1_{\text{test}}, x^2_{\text{test}}, \cdots, x^m_{\text{test}}\}$ from the true data distribution, for each $j \in [m]$, we define the following distance between x^j_{test} and $\mathcal{X}_{\text{train}}$:

$$D(x^j_{\text{test}}, \mathcal{X}_{\text{train}}) := \frac{1}{k} \sum_{i=1}^{k} \|h(x^j_{\text{test}}) - h(x^{\pi_j(i)}_{\text{train}})\|_p \tag{2}$$

where $\pi_j : [n] \to [n]$ is a permutation that $\{\pi_j(1), \pi_j(2), \cdots, \pi_j(n)\}$ is an ascending ordering of training data based on the ℓ_p distance between x^j_{test} and x^i_{train} in the deep embedding space, i.e.,

$$\forall i < i', \|h(x^j_{\text{test}}) - h(x^{\pi_j(i)}_{\text{train}})\|_p \leq \|h(x^j_{\text{test}}) - h(x^{\pi_j(i')}_{\text{train}})\|_p.$$

In other words, we average the embedding space distance of k nearest neighbors of x_j in the training dataset. This simple metric is non-parametric and we found that the results are not sensitive to the selection of k; also, for naturally trained and adversarially trained feature extractors, the distance metric obtained by them have the same correlation with the effectiveness of adversarial training.

3.2 Measuring the distance between training and test datasets

We are also interested to investigate the "distance" between the training dataset and the test dataset, as it will become a good indicator for how adversarial training performs on the test set. Unlike the setting in Section 3.1, this requires to compute a divergence between two data distributions.

Given n training data points $\mathcal{X}_{\text{train}} = \{x^1_{\text{train}}, x^2_{\text{train}}, \cdots, x^n_{\text{train}}\}$ and m test data points $\mathcal{X}_{\text{test}} = \{x^1_{\text{test}}, x^2_{\text{test}}, \cdots, x^m_{\text{test}}\}$, we first apply a neural feature extractor h to them, which is the same as in Section 3.1. Then, we apply a non-linear projection (in our case, we use t-SNE) to project both $h(x^i_{\text{train}})$ and $h(x^j_{\text{test}})$ to a low dimensional space, and obtain $\bar{x}^i_{\text{train}} = \text{proj}(h(x^i_{\text{train}}))$ and $\bar{x}^j_{\text{test}} = \text{proj}(h(x^j_{\text{test}}))$. The dataset after feature extraction and projection is denoted as $\bar{\mathcal{X}}_{\text{train}}$ and $\bar{\mathcal{X}}_{\text{test}}$. Because $\bar{x}^i_{\text{train}}$ and $\bar{x}^j_{\text{test}}$ are low dimensional, we can use kernel density estimation (KDE) to form empirical distributions $\bar{p}_{\text{train}}$ and $\bar{p}_{\text{test}}$ for them. We use p_{train} and p_{test} to denote the true distributions. Then, we approximate the K-L divergence between p_{train} and p_{test} via a numerical integration of Eq.(3):

$$D_{\text{KL}}(p_{\text{train}} || p_{\text{test}}) \approx \int_V \bar{p}_{\text{train}}(x) \log \frac{\bar{p}_{\text{train}}(x)}{\bar{p}_{\text{test}}(x)} \mathrm{d}x, \tag{3}$$

where $\bar{p}_{\text{train}}(x) = \frac{1}{n} \sum_{i=1}^{n} K(x - \bar{x}^i_{\text{train}}; H)$ and $\bar{p}_{\text{test}}(x) = \frac{1}{m} \sum_{j=1}^{m} K(x - \bar{x}^j_{\text{test}}; H)$ are the KDE density functions. K is the kernel function (specifically, we use the Gaussian kernel) and H is the bandwidth parameter automatically selected by Scott's rule (Scott, 2015). V is chosen as a box bounding all training and test data points. For a multi-class dataset, we compute the aforementioned KDE and K-L divergence *for each class separately*.

As we will show in experiments, this K-L divergence is a good indicator on the effectiveness of adversarial training – a large divergence between training and test data points is a strong indication that adversarial training is likely to fail on many test points.

3.3 THE BLIND-SPOT ATTACK: A NEW CLASS OF ADVERSARIAL ATTACKS

Inspired by our findings of the negative correlation between the effectiveness of adversarial training and the distance between a test image and training dataset, we identify a new class of adversarial attacks called "blind-spot attacks", where we find input images that are far enough from any existing training examples such that:

- They are still drawn from the ground-truth data distribution (i.e. well recognized by humans) and *classified correctly* by the model (within the generalization capability of the model);
- Adversarial training cannot provide good robustness properties on these images, and we can easily find their adversarial examples using a simple gradient based attack.

We find that these blind-spots are prevalent and can be easily found without resorting to complex generative models like in Song et al. (2018). For the MNIST dataset which Madry et al. (2018) demonstrate the strongest defense results so far, we propose a simple transformation to find the blind-spots in this model. We simply scale and shift each pixel value. Suppose the input image $x \in [-0.5, 0.5]^d$, we scale and shift each test data example x to form a new example x':

$$x' = \alpha x + \beta, \text{ s.t. } x' \in [-0.5, 0.5]^d$$

where α is a constant close to 1 and β is a constant close to 0. We make sure that the selection of α and β will result in a x' that is still in the valid input range $[-0.5, 0.5]^d$. This transformation effectively adjusts the contrast of the image, and/or adds a gray background to the image. It is important that the blind-spot images are still valid images; for example, a digit that is slightly darker than the one in test set is still considered as a valid digit and can be well recognized by humans. Also, we found that with appropriate α and β the accuracy of MNIST and Fashion-MNIST models barely decreases; the model has enough generalization capability for this set of slightly transformed images, yet their adversarial examples can be easily found.

Although the blind-spot attack is beyond the threat model considered in adversarial training (e.g. ℓ_∞ norm constrained perturbations), our argument is that adversarial training (and probably other defense methods with certifications only on training examples such as Kolter & Wong (2018)) are unlikely to scale well to datasets that lie in a high dimensional manifold, as the limited training data only guarantees robustness near these training examples. The blind-spots are almost inevitable in high dimensional case. For example, in CIFAR-10, about 50% of test images are already in blind-spots and their adversarial examples can be trivially found by projected gradient descent despite adversarial training. Using data augmentation may eliminate some blind-spots, however for high dimensional data it is impossible to enumerate all possible inputs due to the curse of dimensionality.

4 EXPERIMENTS

In this section we present our experimental results on adversarially trained models by Madry et al. (2018). Experimental results on models by Kolter & Wong (2018), Wong et al. (2018) and Sinha et al. (2018) will be demonstrated in Section 6.4 in the Appendix.

4.1 SETUP

We conduct experiments on adversarially trained models by Madry et al. (2018) on four datasets: MNIST, Fashion MNIST, and CIFAR-10. For MNIST, we use the "secret" model release for the MNIST attack challenge[3]. For CIFAR-10, we use the public "adversarially trained" model[4]. For Fashion MNIST, we train our own model with the same model structure and parameters as the robust MNIST model, except that the iterative adversary is allowed to perturb each pixel by at most $\epsilon = 0.1$ as a larger ϵ will significantly reduce model accuracy.

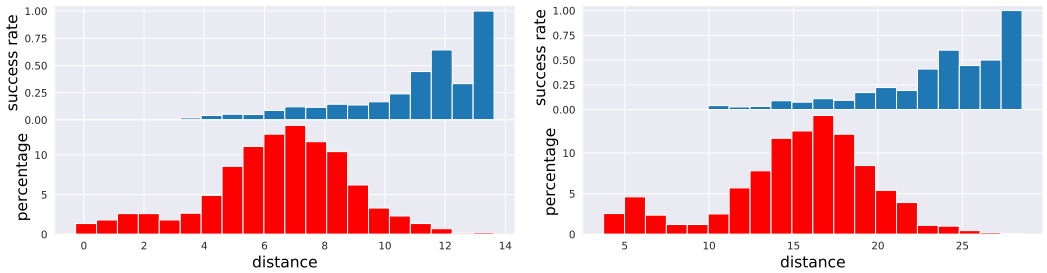
We attack each model with Carlini & Wagner's ℓ_∞ attack (Carlini & Wagner (2017)). We found that this method generally finds adversarial examples with smaller perturbations than projected gradient descent (PGD). To avoid gradient masking, we initial our attacks using two schemes: (1) from the original image plus a random Gaussian noise with a standard deviation of 0.2; (2) from a blank gray image where all pixels are initialized as 0. A successful attack is defined as finding an perturbed

[3] https://github.com/MadryLab/mnist_challenge [4] https://github.com/MadryLab/cifar10_challenge

example that changes the model's classification and the ℓ_∞ distortion is less than a given ϵ used for robust training. For MNIST, $\epsilon = 0.3$; for Fashion-MNIST, $\epsilon = 0.1$; and for CIFAR, $\epsilon = 8/255$. All input images are normalized to $[-0.5, 0.5]$.

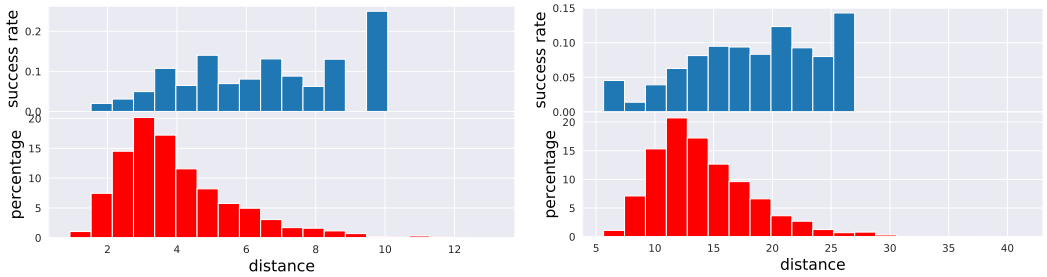
4.2 EFFECTIVENESS OF ADVERSARIAL TRAINING AND THE DISTANCE TO TRAINING SET

In this set of experiments, we build a connection between attack success rate on adversarially trained models and the distance between a test example and the whole training set. We use the metric defined in Section 3.1 to measure this distance. For MNIST and Fashion-MNIST, the outputs of the first fully connected layer are used as the neural feature extractor $h(x)$; for CIFAR, we use the outputs of the last average pooling layer. We consider both naturally and adversarially trained networks as the neural feature extractor. p is set as 2 and k is set as 5. The results are shown in Figure 1, 2 and 3. For each test set, after obtaining the distance of each test point, we bin the test data points based on their distances to the training set and show them in the histogram at the bottom half of each figure (red). The top half of each figure (blue) represents the attack success rates for the test images in the corresponding bins. The missing bars on the right are due to too few points in the corresponding bins. We only attack correctly classified images and only calculate success rate on those images. Note that we should not compare the distances shown between the left and right columns of Figures 1, 2 and 3 because they are obtained from two different models



(a) Using adversarially trained model as $h(x)$ (b) Using naturally trained model as $h(x)$

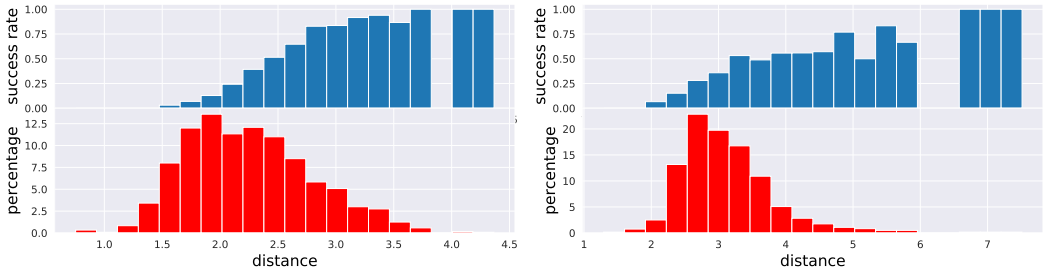
Figure 1: Attack success rate and distance distribution of MNIST in Madry et al. (2018). Upper: The C&W ℓ_∞ attack success rate, $\epsilon = 0.3$. Lower: The distribution of the average ℓ_2 (embedding space) distance between the images in test set and the top-5 nearest images in training set.



(a) Using adversarially trained model as $h(x)$ (b) Using naturally trained model as $h(x)$

Figure 2: Attack success rate and distance distribution of Fashion MNIST in Madry et al. (2018). Upper: The C&W ℓ_∞ attack success rate, $\epsilon = 0.1$. Lower: The distribution of the average ℓ_2 (embedding space) distance between the images in test set and the top-5 nearest images in training set.

As we can observe in all three figures, most successful attacks in test sets for adversarially trained networks concentrate on the right hand side of the distance distribution, and the success rates tend to grow when the distance is increasing. The trend is independent of the feature extractor being used (naturally or adversarially trained). The strong correlation between attack success rates and the



(a) Using adversarially trained model as $h(x)$

(b) Using naturally trained model as $h(x)$

Figure 3: Attack success rate and distance distribution of CIFAR in Madry et al. (2018). Upper: The C&W ℓ_∞ attack success rate, $\epsilon = 8/255$. Lower: The distribution of the average ℓ_2 (embedding space) distance between the images in test set and the top-5 nearest images in training set.

distance from a test point to the training dataset supports our hypothesize that adversarial training tends to fail on test points that are far enough from the training data distribution.

4.3 K-L Divergence between training and test sets vs attack success rate

To quantify the overall distance between the training and the test set, we calculate the K-L divergence between the KDE distributions of training set and test set for each class according to Eq. (3). Then, for each dataset we take the average K-L divergence across all classes, as shown in Table 1. We use both adversarially trained networks and naturally trained networks as our feature extractors $h(x)$. As a reference, we also calculate the average normalized ℓ_2 distance. We first calculate the feature representations of test points and training points. To compare between datasets, we normalize each element of the feature representation to mean 0 and variance 1. Then we calculate the ℓ_2 distance between each test point and the training set as in Section 4.2. We average this distance among all test points and divide it by $\sqrt{t}$ to normalize the dimension, where t is the dimension of the feature representation $h(\cdot)$. We also report the attack success rates and test accuracy for each adversarially trained model.

Clearly, Fashion-MNIST is the dataset with strongest defense as measured by the attack success rates on test set, and its K-L divergence is also the smallest. For CIFAR, the divergence between training and test sets is significantly larger, and adversarial training only has limited success. The hardness of training a robust model for MNIST is in between Fashion-MNIST and CIFAR. Another important observation is that the effectiveness of adversarial training does not depend on the accuracy; for Fashion-MNIST, classification is harder as the data is more complicated than MNIST, but training a robust Fashion-MNIST model is easier as the data distortion is more concentrated and adversarial training has less "blind-spots".

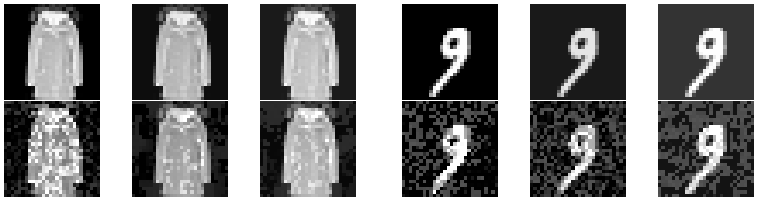
Table 1: Average K-L divergence and normalized ℓ_2 distance between training and test sets across all classes. We use both adversarially trained networks (adv.) and naturally trained networks (nat.)as our feature extractors when computing K-L divergence. Note that we only attack images that are *correctly classified* and calculate success rate on those images.

Dataset	**Avg K-L div. (adv. trained)**	**Avg K-L div. (nat. trained)**	**Avg. normalized ℓ_2 Distance**	**Attack Success Rates (Test Set)**	**Test Accuracy**
Fashion-MNIST	0.046	0.058	0.4233	6.4%	86.1%
MNIST	0.119	0.095	0.3993	9.7%	98.2%
CIFAR	0.571	0.143	0.6715	37.9%	87.0%

4.4 Blind-Spot Attack on MNIST and Fashion MNIST

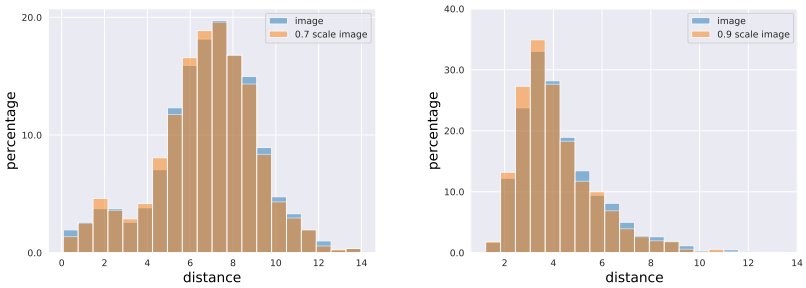
In this section we focus on applying the proposed blind-spot attack to MNIST and Fashion MNIST. For MNIST, $\epsilon = 0.3$ so we set the scaling factor to $\alpha = \{1.0, 0.9, 0.8, 0.7\}$. For Fashion-MNIST,

$\epsilon = 0.1$ so we set the scaling factor to $\alpha = \{1.0, 0.95, 0.9\}$. We set β to either 0 or a small constant. The case $\alpha = 1.0, \beta = 0.0$ represents the original test set images. We report the model's accuracy and attack success rates for each choice of α and β in Table 2 and Table 3. Because we scale the image by a factor of α, we also set a stricter criterion of success – the ℓ_∞ perturbation must be less than $\alpha\epsilon$ to be counted as a successful attack. For MNIST, $\epsilon = 0.3$ and for Fashion-MNIST, $\epsilon = 0.1$. We report both success criterion, ϵ and $\alpha\epsilon$ in Tables 2 and 3.



(a)	(b)	(c)	(d)	(e)	(f)
$\alpha = 1.0$	$\alpha = 0.9$	$\alpha = 0.9$	$\alpha = 1.0$	$\alpha = 0.8$	$\alpha = 0.8$
$\beta = 0.0$	$\beta = 0.0$	$\beta = 0.05$	$\beta = 0.0$	$\beta = 0.0$	$\beta = 0.1$
dist= 0.218	dist= 0.099	dist= 0.070	dist= 0.338	dist= 0.229	dist= 0.129

Figure 4: Blind-spot attacks on Fashion-MNIST and MNIST data with scaling and shifting in Madry et al. (2018). First row contains input images after scaling and shifting and the second row contains the found adversarial examples. "dist" represents the ℓ_∞ distortion of adversarial perturbations. The first rows of figures (a) and (d) represent the original test set images ($\alpha = 1.0, \beta = 0.0$); first rows of figures (b), (c), (e), and (f) illustrate the images after transformation. Adversarial examples for these transformed images can be found with small distortions.



(a) MNIST (b) Fashion-MNIST

Figure 5: The distribution of the ℓ_2 distance between the original and scaled images in test set and the top-5 nearest images ($k = 5$) in training set using the distance metric defined in Eq. (2).

We first observe that for all pairs of α and β the transformation does not affect the models' test accuracy at all. The adversarially trained model classifies these slightly scaled and shifted images very well, with test accuracy equivalent to the original test set. Visual comparisons in Figure 12 show that when α is close to 1 and β is close to 0, it is hard to distinguish the transformed images from the original images. On the other hand, according to Tables 2 and 3, the attack success rates for those transformed test images are significantly higher than the original test images, for both the

α, β	$\alpha = 1.0$	$\alpha = 0.9$				$\alpha = 0.8$				$\alpha = 0.7$			
	$\beta = 0$	$\beta = 0$		$\beta = 0.05$		$\beta = 0$		$\beta = 0.1$		$\beta = 0$		$\beta = 0.15$	
acc	98.2%	98.3%		98.5%		98.4%		98.5%		98.4%		98.1%	
th.	0.3	0.3	0.27	0.3	0.27	0.3	0.24	0.3	0.24	0.3	0.21	0.3	0.21
suc. rate	9.70%	75.20%	15.20%	93.65%	82.50%	94.85%	52.30%	99.55%	95.45%	98.60%	82.45%	99.95%	99.95%

Table 2: The attack success rate (suc. rate) and test accuracy (acc) of scaled and shifted MNIST. An attack is considered as successful if its ℓ_∞ distortion is less than given thresholds (th.) 0.3 or 0.3α.

α, β	$\alpha = 1.0$	$\alpha = 0.95$				$\alpha = 0.9$			
	$\beta = 0$	$\beta = 0$		$\beta = 0.025$		$\beta = 0$		$\beta = 0.05$	
acc	86.1%	86.1%		86.4%		86.1%		86.2%	
th.	0.1	0.1	0.095	0.1	0.095	0.1	0.09	0.1	0.09
suc. rate	6.40%	11.25%	9.05%	22.55%	18.55%	25.70%	19.15%	62.60%	55.95%

Table 3: Attack success rate (suc. rate) and test accuracy (acc) of scaled and shifted Fashion-MNIST. An attack is considered successful if its ℓ_∞ distortion is less than a given thresholds (th.) 0.1 or 0.1α.

original criterion ϵ and the stricter criterion $\alpha\epsilon$. In Figure 12, we can see that the ℓ_∞ adversarial perturbation required is much smaller than the original image after the transformation. Thus, the proposed scale and shift transformations indeed move test images into blind-spots.

One might think that we can generally detect blind-spot attacks by observing their distances to the training dataset, using a metric similar to Eq. (2). Thus, we plot histograms for the distances between tests points and training dataset, for both original test images and those slightly transformed ones in Figure 5. We set $\alpha = 0.7, \beta = 0$ for MNIST and $\alpha = 0.9, \beta = 0$ for Fashion-MNIST. Unfortunately, the differences in distance histograms for these blind-spots is so tiny that we cannot reliably detect the change, yet the robustness property drastically changes on these transformed images.

5 Conclusion

In this paper, we observed that the effectiveness of adversarial training is highly correlated with the characteristics of the dataset, and data points that are far enough from the distribution of training data are still vulnerable to adversarial attacks despite adversarial training. Following this observation, we defined a new class of attacks called "blind-spot attack" and proposed a simple scale-and-shift scheme for conducting blind-spot attacks on adversarially trained MNIST and Fashion MNIST datasets with high success rates. Our findings suggest that adversarial training can be challenging due to the prevalence of blind-spots in high dimensional datasets.

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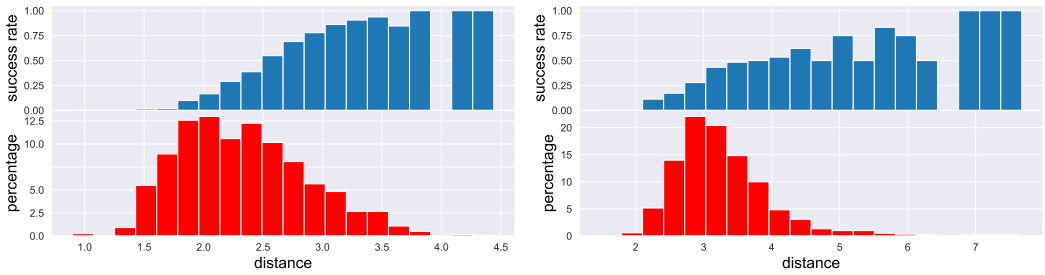
6 APPENDIX

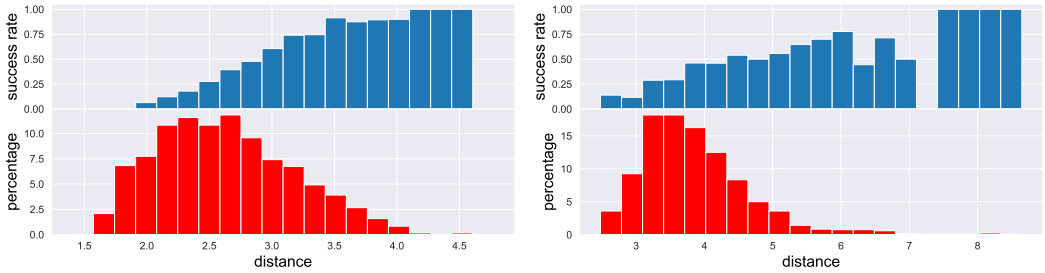
6.1 DISTANCE DISTRIBUTIONS UNDER DIFFERENT NEAREST NEIGHBOUR PARAMETERS k

As discussed in Section 3.1, we use k-nearest neighbour in embedding space to measure the distance between a test example and the training set. In Section 4.2 we use $k = 5$. In this section we show that the choice of k does not have much influence on our results. We use the adversarially trained model on the CIFAR dataset as an example. In Figures 6, 7 and 8 we choose $k = 10, 100, 1000$, respectively. The results are similar to those we have shown in Figure 3: a strong correlation between attack success rates and the distance from a test point to the training dataset.



(a) Using adversarially trained model as $h(x)$ (b) Using naturally trained model as $h(x)$

Figure 6: Attack success rates and distance distribution of the adversarially trained CIFAR model by Madry et al. (2018). Upper: The C&W ℓ_∞ attack success rate, $\epsilon = 8/255$. Lower: The distribution of the average ℓ_2 (embedding space) distance between the images in test set and the **top-10** ($k = 10$) nearest images in training set.



(a) Using adversarially trained model as $h(x)$ (b) Using naturally trained model as $h(x)$

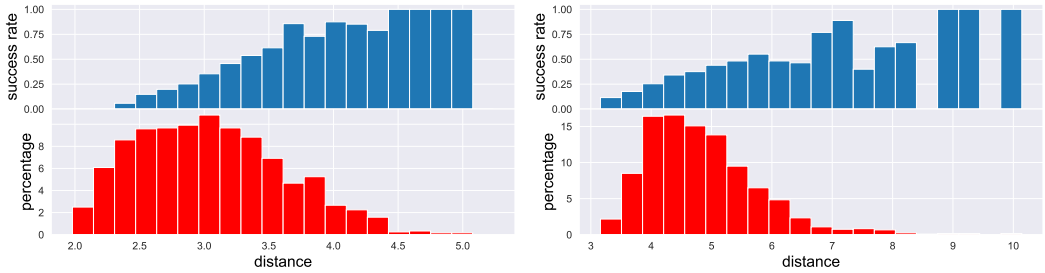
Figure 7: Attack success rates and distance distribution of the adversarially trained CIFAR model by Madry et al. (2018). Upper: The C&W ℓ_∞ attack success rate, $\epsilon = 8/255$. Lower: The distribution of the average ℓ_2 (embedding space) distance between the images in test set and the **top-100** ($k = 100$) nearest images in training set.

6.2 GERMAN TRAFFIC SIGN (GTS) DATASET

We also studied the German Traffic Sign (GTS) (Houben et al., 2013) dataset. For GTS, we train our own model with the same model structure and parameters as the adversarially trained CIFAR model (Madry et al., 2018). We set $\epsilon = 8/255$ for adversarial training with PGD, and also use the same ϵ as the threshold of success. The results are shown in Figure 9. The GTS model behaves similarly to the CIFAR model: attack success rates are much higher when the distances between the test example and the training dataset are larger.

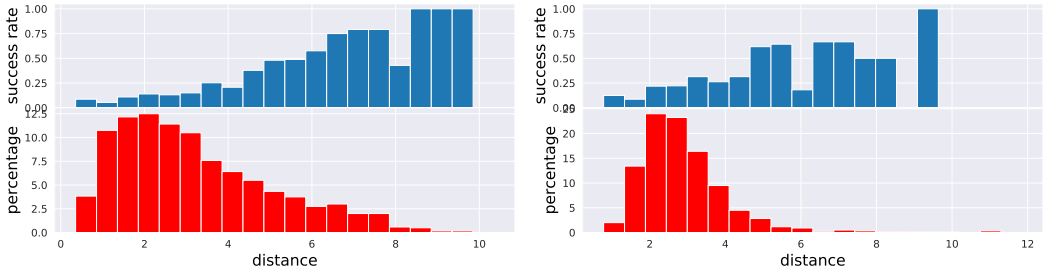
6.3 MORE VISUALIZATION RESULTS

We demonstrate more MNIST and Fashion-MNIST visualizations in Figure 10.



(a) Using adversarially trained model as $h(x)$ (b) Using naturally trained model as $h(x)$

Figure 8: Attack success rates and distance distribution of the adversarially trained CIFAR model by Madry et al. (2018). Upper: The C&W ℓ_∞ attack success rate, $\epsilon = 8/255$. Lower: The distribution of the average ℓ_2 (embedding space) distance between the images in test set and the **top-1000** ($k = 1000$) nearest images in training set.



(a) Using adversarially trained model as $h(x)$ (b) Using naturally trained model as $h(x)$

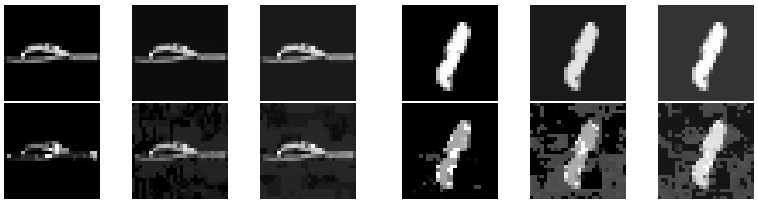
Figure 9: Attack success rate and distance distribution of GTS in Madry et al. (2018). Upper: The C&W ℓ_∞ attack success rate, $\epsilon = 8/255$. Lower: The distribution of the average ℓ_2 (embedding space) distance between the images in test set and the top-5 nearest images in training set.

6.4 Results on other robust training methods

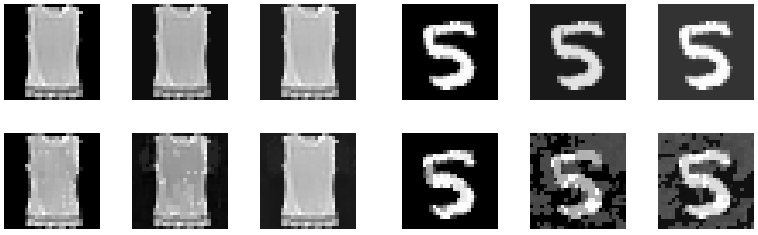
In this section we demonstrate our experimental results on two other state-of-the-art *certified* defense methods, including convex adversarial polytope by Wong et al. (2018) and Kolter & Wong (2018), and distributional robust optimization based adversarial training by Sinha et al. (2018). Different from the adversarial training by Madry et al. (2018), these two methods can provide a formal certification on the robustness of the model and provably improve robustness on the training dataset. However, they cannot guarantee robustness on test data. We did not include other certified defenses like Raghunathan et al. (2018) and Hein & Andriushchenko (2017) because they are not applicable to multi-layer networks. For all defenses, we use their official implementations and pretrained models (if available). Figure 11 shows the results on CIFAR using the defences in Wong et al. (2018). Tables 4 and 5 show the blind-spot attack results on MNIST and Fashion-MNIST for robust models in Kolter & Wong (2018) and Sinha et al. (2018), respectively. Figure 12 shows the blind-spot attack examples on Madry et al. (2018), Kolter & Wong (2018) and Sinha et al. (2018).

MNIST	α, β	$\alpha = 1.0$	$\alpha = 0.95$				$\alpha = 0.9$			
		$\beta = 0$	$\beta = 0$		$\beta = 0.025$		$\beta = 0$		$\beta = 0.05$	
	Accuracy	97.5%	97.5%		97.5%		97.5%		97.4%	
	Success criterion (ℓ_∞ norm)	0.1	0.1	0.095	0.1	0.095	0.1	0.09	0.1	0.09
	Success rates	2.15%	5.55%	4.35%	28.5%	17.55%	30.1%	15.4%	**86.35%**	80.7%
Fashion-MNIST	α, β	$\alpha = 1.0$	$\alpha = 0.95$				$\alpha = 0.9$			
		$\beta = 0$	$\beta = 0$		$\beta = 0.025$		$\beta = 0$		$\beta = 0.05$	
	Accuracy	79.1%	79.1%		79.4%		79.2%		79.2%	
	Success criterion (ℓ_∞ norm)	0.1	0.1	0.095	0.1	0.095	0.1	0.09	0.1	0.09
	Success rates	6.85%	15.45%	9.3%	39.75%	29.35%	34.25%	24.65%	**69.95%**	65.2%

Table 4: Blind-spot attack on MNIST and Fashion-MNIST for robust models by Kolter & Wong (2018)

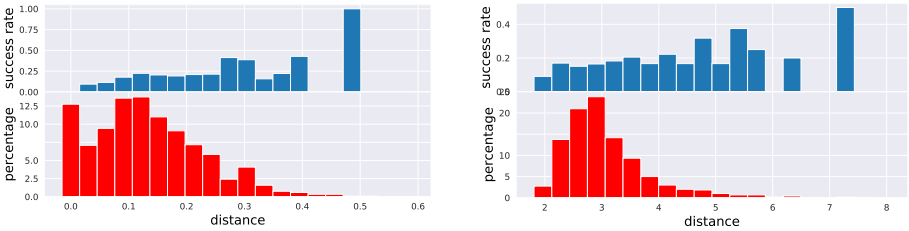


(a) $\alpha = 1.0$ $\beta = 0.0$ dist= 0.363
(b) $\alpha = 0.9$ $\beta = 0.0$ dist= 0.097
(c) $\alpha = 0.9$ $\beta = 0.05$ dist= 0.053
(d) $\alpha = 1.0$ $\beta = 0.0$ dist= 0.342
(e) $\alpha = 0.8$ $\beta = 0.0$ dist= 0.227
(f) $\alpha = 0.8$ $\beta = 0.1$ dist= 0.123



(g) $\alpha = 1.0$ $\beta = 0.0$ dist= 0.409
(h) $\alpha = 0.9$ $\beta = 0.0$ dist= 0.093
(i) $\alpha = 0.9$ $\beta = 0.041$ dist= 0.053
(j) $\alpha = 1.0$ $\beta = 0.0$ dist= 0.327
(k) $\alpha = 0.8$ $\beta = 0.0$ dist= 0.220
(l) $\alpha = 0.8$ $\beta = 0.1$ dist= 0.140

Figure 10: Blind-spot attacks on Fashion-MNIST and MNIST data with scaling and shifting in Madry et al. (2018). First row contains input images after scaling and shifting and the second row contains the found adversarial examples. "dist" represents the ℓ_∞ distortion of adversarial perturbations. The first rows of figures (a), (d), (g) and (j) represent the original test set images ($\alpha = 1.0, \beta = 0.0$); first rows of figures (b), (c), (e), (f), (h), (i), (k) and (l) illustrate the images after transformation. Adversarial examples for these transformed images can be found with small distortions.



(a) Using adversarially trained model as $h(x)$ (b) Using naturally trained model as $h(x)$

Figure 11: Attack success rates and distance distribution of CIFAR in Wong et al. (2018). Lower: the histogram of the average ℓ_2 (in embedding space) distance between the images in test set and the top-5 nearest images in training set. Upper: the C&W ℓ_∞ attack success rate with success criterion $\epsilon = 8/255$.

MNIST	α, β	$\alpha = 1.0$	$\alpha = 0.95$				$\alpha = 0.9$			
		$\beta = 0$	$\beta = 0$		$\beta = 0.025$		$\beta = 0$		$\beta = 0.05$	
	Accuracy	98.7%	98.5%		98.6%		98.7%		98.4%	
	Success criterion (ℓ_2 norm)	2	2	1.9	2	1.9	2	1.8	2	1.8
	Success rates	12.2%	27.05%	22.95%	36.15%	30.9%	45.25%	31.55%	**58.9%**	45.6%
Fashion-MNIST	α, β	$\alpha = 1.0$	$\alpha = 0.95$				$\alpha = 0.9$			
		$\beta = 0$	$\beta = 0$		$\beta = 0.025$		$\beta = 0$		$\beta = 0.05$	
	Accuracy	88.5%	88.3%		88.2%		88.1%		87.8%	
	Success criterion (ℓ_2 norm)	2	2	1.9	2	1.9	2	1.8	2	1.8
	Success rates	31.4%	46.3%	41.1%	58 %	53.3%	61.2%	51.8%	**69.1%**	62.85%

Table 5: Blind-spot attack on MNIST and Fashion-MNIST for robust models by Sinha et al. (2018)

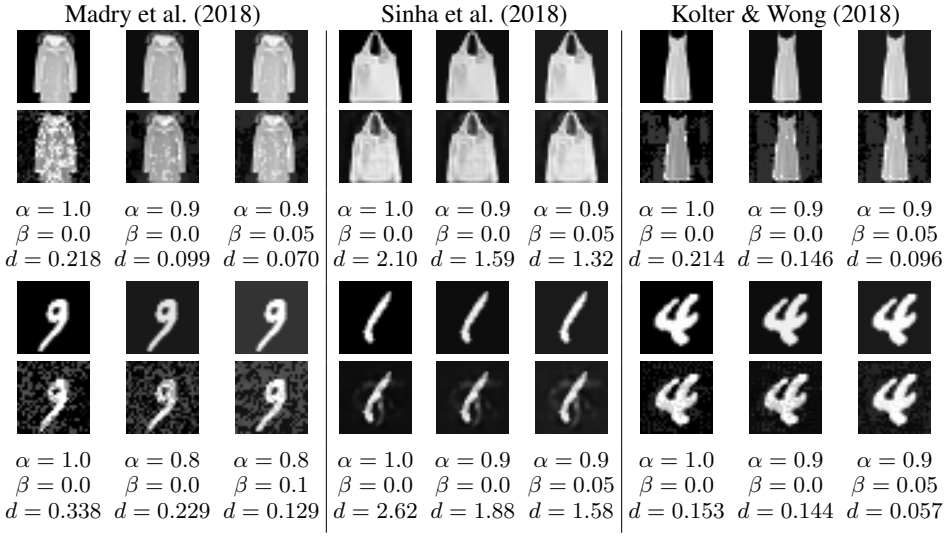


Figure 12: Blind-spot attacks on Fashion-MNIST and MNIST datasets with scaling and shifting. For each group, the first row contains input images transformed with different scaling and shifting parameter α, β ($\alpha = 1.0, \beta = 0.0$ is the original image) and the second row contains the found adversarial examples. d represents the distortion of adversarial perturbations. For models from Madry et al. (2018) and Kolter & Wong (2018) we use ℓ_∞ norm and for models from Sinha et al. (2018) we use ℓ_2 norm. Adversarial examples for these transformed images can be found with small distortions d.