Unsupervised Stain Decomposition via Inversion Regulation for Multiplex Immunohistochemistry Images

Abstract

Multiplex Immunohistochemistry (mIHC) is a cost-effective and accessible method for in situ labeling of multiple protein biomarkers in a tissue sample. By assigning a different stain to each biomarker, it allows the visualization of different types of cells within the tumor vicinity for downstream analysis. However, to detect different types of stains in a given mIHC image is a challenging problem, especially when the number of stains is high. Previous deep-learning-based methods mostly assume full supervision; yet the annotation can be costly. In this paper, we propose a novel unsupervised stain decomposition method to detect different stains simultaneously. Our method does not require any supervision, except for color samples of different stains. A main technical challenge is that the problem is underdetermined and can have multiple solutions. To conquer this issue, we propose a novel inversion regulation technique, which eliminates most undesirable solutions. On a 7-plexed IHC image dataset, the proposed method achieves high quality stain decomposition results without human annotation.

Keywords: Color deconvolution, Deep learning, Multiplex, Immunohistochemistry, Unsupervised.

1. Introduction

Multiplex Immunohistochemistry (mIHC) is a tissue imaging technique that allows simultaneous detection of multiple biomarkers in the same tissue section. Multiplex imaging has become an important tool in diagnostic pathology and cancer immunotherapy. It enables the study of cell composition, cellular function and cell-cell interactions, not to mention, allowing a more in depth comprehension and profiling of the tumor microenvironment (Ilié et al., 2018; Johnson et al., 2018; Remark et al., 2016; Tan et al., 2020). While there are various multiplex imaging technologies, brightfield mIHC is a cost effective and accessible method that can be captured in a single step with traditional brightfield light microscopy. Moreover, it does not require any special software or visualization tools, making biomarker research and profiling more accessible (Tan et al., 2020). mIHC offers simultaneous staining of 5+ biomarkers (Tan et al., 2020; Fassler et al., 2020; Hofman et al., 2019; Dixon et al., 2015). Unlike more expensive multiplex imaging techniques, e.g., multiplex immunofluorescence, mIHC does not offer separate channels for different biomarkers. It rather provides a single image with all the biomarkers visualized together, see Figure 1 (left). The simultaneous staining in mIHC images can offer insights into the tumor microenvironment that are not obtainable with singly stained IHC images but it still requires much manual effort to analyze. Visual inspection is both challenging and time consuming for pathologists, especially with increasing number of stains.

Figure 1: An mIHC image and the corresponding unsupervised stain decomposition. Samples from the different biomarkers are shown. The CD20 sample is from a different image since it is not present in this view. The yellow staining looks like olive yellow because of the interaction with the blue nuclei staining.

To analyze the images at a large scale, this process needs to be automated. The images need to be decomposed into individual biomarker maps before any spatial analysis or quantification can take place (Compare the left- and right-hand sides in Figure 1). To that end, digital analysis methods are essential to automate the stain unmixing, i.e., extracting masks corresponding to different biomarkers (Van Herck et al., 2021) to use them for tumor microenvironment analysis (Fassler et al., 2020).

Color deconvolution is the unmixing of stains into separate stain concentration maps. Several unsupervised color deconvolution methods (Ruifrok and Johnston, 2001; Vahadane et al., 2016; Macenko et al., 2009) have been successfully deployed for the analysis of up to two biomarkers, such as hematoxylin and eosin (H&E). Extending to a larger number of stains involves solving an under-determined linear equation system, which can have many undesired solutions. To address this issue, in (Chen and Chefd'hotel, 2014; Chen and Srinivas, 2015), a lasso regression model is proposed to select a sparse set of stains at each pixel. The results, however, are not satisfying, mostly because these methods treat different pixels independently, and fail to consider the contextual information. In (Duggal et al., 2017) dual-stained images are implicitly deconvolved for downstream classification tasks, but the deconvolution channels are not guaranteed to accurately correspond to the different stains. Commercial tools such as HALO can unmix up to 4-colored chromogenic stains (Thommen et al., 2018). More recently, (Abousamra et al., 2020) proposed a weakly supervised deep learning approach for stain decomposition. Its performance depends on manual annotations of cell centers, which can be very time consuming.

In this work, we propose an unsupervised mIHC stain decomposition method that can scale to a larger number of stains. Our method only requires the reference stain colors. To

Figure 2: InverseAE architecture and training. The model's output is conditioned on the input mIHC image and the target reference stain. It is trained with a reconstruction loss and an inverse reconstruction loss.

properly leverage contextual information, we use a convolutional neural network autoencoder to generate the stain concentration maps. With an increased number of stains, the solution is not unique. Using the sparsity prior is not the best solution as it fails to consider the context. To this end, we propose a novel inverse-image-based regularization to help the network learn high quality stain concentration maps. We show how different cell types or biomarker segmentation maps can be directly inferred from the resulting concentration maps. On a 7-plex mIHC images dataset, we show the effectiveness of our proposed approach, achieving evaluation scores very close to the supervised method (Abousamra et al., 2020) ($\sim 94\%$ of the supervised f-score on average).

2. Related Work

Stain unmixing/decomposition is a classical problem that has been studied extensively on histological images, e.g., H&E. Ruifrok and Johnston (2001) were the first to use the optical density color representation to address the problem. The decomposition problem is transformed into solving a linear equation system. Different decomposition methods have been proposed (Macenko et al., 2009; Alsubaie et al., 2016, 2017; Vahadane et al., 2016; Hidalgo-Gavira et al., 2018; Pérez-Bueno et al., 2020).

Recent years have witnessed rapid advancement of staining technology; one may acquire simultaneous staining of more than 2 biomarkers in the same tissue section. See example in Figure 1. However, with mIHC allowing 5+ simultaneous stains (Tan et al., 2020), stain unmixing becomes more challenging and new methods are needed to handle a large number of stains. Chen and Chefd'hotel (2014) extended the work of (Ruifrok and Johnston, 2001) to support more than 2 biomarkers. With more than 2 biomarkers, the optical-density-based linear equation system is underdetermined. To address the issue, lasso regression

was proposed. Nevertheless, directly enforcing a sparsity prior is not sufficient, especially for higher number of stains, mainly because the sparsity prior fails to consider contextual information of each pixel. (Chen and Srinivas, 2015) further adds constraints on the lasso regression to model co-staining. Abousamra et al. (2020) proposes to use weak supervision in the form of dot annotations that are transformed into superpixels (Achanta et al., 2012) to overcome the underdetermined nature of the problem. They train a convolutional autoencoder to estimate the concentration maps and show the effectiveness of the method in decomposing 6 simultaneous stained mIHC images. Their method, however, still requires a large amount of annotations, which can be prohibitive in practice. For completeness, we also refer to methods that directly incorporate color deconvolution into downstream tasks (Duggal et al., 2017; Lahiani et al., 2018), e.g., tissue segmentation.

3. Background

MIHC images are obtained by histologic detection of multiple protein biomarkers. In this section we describe the linear relationship of stain concentrations under Beer Lambert law. This is the basis for most stain unmixing methods including ours.

Optical Density (OD). Optical density measures the absorption of light as it passes through a medium. The optical density at a pixel i is the negative log of its normalized RGB values, $[r_i, g_i, b_i]^T \in [0, 1]^3$:

$$\boldsymbol{y}_i = [-\log(r_i), -\log(g_i), -\log(b_i)]^T. \tag{1}$$

The stains and their concentrations are linearly related in the OD space. Assume a given set of m stain vectors, whose OD vectors are represented by the matrix $\boldsymbol{S} = [\boldsymbol{s}_1, \boldsymbol{s}_2, \cdots, \boldsymbol{s}_m] \in \mathbb{R}^{3 \times m}$, where $\boldsymbol{s}_j \in \mathbb{R}^3$ is the OD vector of the jth stain. By Beer Lambert Law (BL) (Lambert, 1760), for any pixel i, the optical density $\boldsymbol{y}_i$ and its stain concentration vector $\boldsymbol{c}_i$ satisfy a linear relationship, i.e., $\boldsymbol{y}_i = \boldsymbol{S} \cdot \boldsymbol{c}_i$, where $\boldsymbol{c}_i \in \mathbb{R}^m$ denotes the concentrations of the different stains at pixel i. Generalizing to an image with n pixels, we get:

$$\boldsymbol{Y} = [\boldsymbol{y}_1, \cdots, \boldsymbol{y}_n] = \boldsymbol{S} \cdot \boldsymbol{C} \tag{2}$$

in which $\boldsymbol{Y} \in \mathbb{R}^{3 \times n}$ is the optical density matrix of all the pixels in the image and $\boldsymbol{C} = [\boldsymbol{c}_1, \cdots, \boldsymbol{c}_n] \in \mathbb{R}^{m \times n}$ is the corresponding stains' concentrations matrix.

Solving the Linear Equation. The stain mixing was first modeled by (Ruifrok and Johnston, 2001) using Beer Lambert Law. Given the reference stains matrix $\boldsymbol{S}$, they proposed to recover the stain concentrations by solving the linear equation system, Equation (2). In practice, stain color vectors are obtained by sampling representative pixels of each stain and the background tissue. The background color vector prevents the background tissue from getting erroneously computed as a mixture of other stains. For higher than 2-plex staining i.e., when the stain matrix S consists of $m > 3$ stain vectors (2 stains and the background), the linear equation system is underdetermined and does not have a unique solution.

4. Method: InverseAE for Unsupervised Stain Decomposition

In this work we propose *InverseAE*, an unsupervised deep-learning stain decomposition method. We assume that at each pixel there is a dominant stain which should be assigned

Figure 3: Sample mIHC patches, our corresponding unsupervised stain decomposition, and the superpixel labels derived from the dot annotations.

to that pixel in the final stain segmentation maps. Hence, our proposed method is designed so that it results in meaningful stain concentration maps from which the dominant stain/biomarker at each pixel can be inferred directly. It only requires the set of multiplex stained images and the set of reference stains color vectors.

We use an autoencoder to generate the estimated stain concentration maps $\widehat{C}$ for an input image Y, based on the given stain vectors S. The autoencoder is trained with the reconstruction loss: $\mathcal{L}_{recon}(\widehat{C}) = MSE(Y, S \cdot \widehat{C})$ that is aimed to solve Equation (2). It compares the image Y with the reconstructed image from the estimated concentration maps $S \cdot \widehat{C}$ using a mean squared error. When the number of stain vectors $m > 3$, Equation (2) becomes an underdetermined system of equations with possibly infinite number of solutions. We observe that when we train the autoencoder with only the reconstruction loss, the model may (and oftentimes tends to) converge to suboptimal solutions because of the underdetermined nature of the optical density based linear equation system, Equation (2). To that end, we propose the inverse reconstruction regularizer to impose additional constraints.

4.1. Inversion Regulation

The inverse reconstruction regularizer implements a constrained training mechanism by promoting a solution –estimated concentration maps $\widehat{C}$– that satisfies both the image and its inverse. We use the term *inverse of an image* or *inverted image* to refer to the image formed from the pixels' complement color vectors, i.e. for an arbitrary pixel with normalized RGB color vector $[r, \; g, \; b]^T$, its *inverted color vector* is $[1-r, \; 1-g, \; 1-b]^T$, and its *inverted optical density* is $y_{inverse} = [-\log(1-r), -\log(1-g), -\log(1-b)]^T$. Similarly, $S_{inverse}$ is the inverted optical density for the stain matrix S. To regularize the solution of Equation (2), we add the inverted equations into the system.

$$\text{For each pixel:} \quad y_{inverse} = S_{inverse} \cdot c, \tag{3}$$

$$\text{For the image:} \quad Y_{inverse} = S_{inverse} \cdot C, \tag{4}$$

Therefore, the inverse reconstruction regularization loss is defined as:

$$\mathcal{L}_{inverse}(\widehat{\boldsymbol{C}}) = MSE(\boldsymbol{Y}_{inverse}, \boldsymbol{S}_{inverse} \cdot \widehat{\boldsymbol{C}}). \tag{5}$$

And the overall loss function becomes:

$$\mathcal{L}_{unsup}(\widehat{\boldsymbol{C}}) = \lambda_1 \mathcal{L}_{recon}(\widehat{\boldsymbol{C}}) + \lambda_2 \mathcal{L}_{inverse}(\widehat{\boldsymbol{C}}) \tag{6}$$

Where λ_1 and λ_2 are constant weight values. In other words, the model is trained to generate concentration maps $\widehat{\boldsymbol{C}}$ that when combined with the stain matrix $\boldsymbol{S}$, reconstructs the input image $\boldsymbol{Y}$, and meanwhile, when combined with the inverted stain matrix $\boldsymbol{S}_{inverse}$, reconstructs the inverted image $\boldsymbol{Y}_{inverse}$. We show in the experiments how this regularization pushes the prediction towards *good solutions*, that is, at any location, the stain corresponding to the observed dominant color gets the highest concentration. This allows us to infer high quality stain segmentation maps and achieve evaluation scores close to the supervised solution. We next describe the intuition behind the inversion regulation.

This choice of inverse as a regulator is not random. A suitable regulator requires 2 **properties**: **(I)** a solution exists that satisfies both the original image and the regulator, **(II)** the regulator adds constraints that limit the solution space by eliminating suboptimal solutions and promoting desired solutions. These properties prompt our choice of the inverse. First, there is a special relationship between a color and its complement (or inverse). When an object absorbs light of a particular color, we perceive the object as having the complementary color, and vice versa. Indeed, the relationship can be stated quantitatively. A color and its inverse share the same saturation in the HSL color space (see Appendix C for details). Saturation measures the departure of a hue from white (Agoston, 2005) and thus correlates with the amount of pigment present, i.e., its concentration. These observations suggest that a color and its inverse can share a same concentration vector, with regard to the original stains and the inverse stains, respectively. In other words, the same $\boldsymbol{c}$ can satisfy both $\boldsymbol{y} = \boldsymbol{S} \cdot \boldsymbol{c}$ and $\boldsymbol{y}_{inverse} = \boldsymbol{S}_{inverse} \cdot \boldsymbol{c}$. This is the desired *property I*.

Second, in the HSL color space, a color and its inverse have contrasting luminosity, i.e. when the luminosity of a color is L, the luminosity of its inverse is $1 - L$, see Appendix C. We can define the absorption power of a color as the average of the minimum and maximum of its red, green, and blue light absorption. Then, by definition, its luminosity is inversely correlated with it's absorption power. As a result, *since a color and its inverse have contrasting luminosity, they also have contrasting absorption powers*. This property allows inversion regulation to eliminate a large portion of the undesired solution space and promote good sparse solutions (*property II*). We discuss this in more detail in Appendix D.

We have shown how the inversion regulation brings special properties that are essential to converge to good solutions and hence, get high accuracy stain segmentation maps. Using the inverse reconstruction loss on a mIHC dataset with $m = 8$ stain vectors, we observe that it pushes the prediction towards the desired solution, that is, at any location, the stain corresponding to the observed dominant color gets the highest concentration. Figure 2 shows an overview of the model architecture and training.

5. Experiments

We performed experiments with 7-plex mIHC stained pancreatic cancer tissue. The 7 biomarkers include immune cell biomarkers: CD3 (yellow), CD4 (teal), CD8 (purple), CD16

Table 1: F-score of stain segmentations with respect to dot annotations on 96 patches from 42 cases. Shown in bold and underlined are the best and second best F-scores in each column, respectively.

Method	CD3	CD4	CD8	CD16	CD20	Tumor	Mean
PseudoInv	0.158	0.208	0.441	0.267	0.265	0.403	0.290
Nearest Neighbor	0.223	0.168	0.734	0.277	0.106	0.357	0.311
LassoReg	0.456	0.501	0.801	0.050	0.223	0.389	0.404
UNet (supervised)	0.496	0.496	**0.835**	0.699	0.144	0.405	0.513
ColorAE (supervised)	0.639	**0.585**	0.829	**0.728**	**0.353**	**0.573**	**0.618**
InverseAE	**0.644**	0.530	0.813	0.632	0.327	0.556	0.584

Table 2: Evaluation of concentration maps using SSIM score on single stain images.

Method	CD3	CD4	CD8	CD16	CD20	Tumor	Mean
ColorAE	0.893	**0.886**	**0.897**	0.657	0.876	**0.834**	0.841
InverseAE	**0.935**	0.881	0.879	**0.682**	**0.881**	0.800	**0.843**

(black), CD20 (red), a tumor biomarker (brown), in addition to hematoxylin as a nuclear counterstain (blue). The training dataset consisted of 240 patches of size 400×400 at $20x$ divided into training and validation. See Appendix A for more details on the training and obtaining the stain segmentation maps. Next, we describe how we use the estimated concentration maps to obtain the stain segmentation maps. After that, we present our experiments for evaluating the predicted segmentation maps and for evaluating the quality of the raw concentration maps. An ablation study of the effect of different components on the model is in Appendix B.

Stain Segmentation Maps Inference. The ultimate goal is to get a semantic segmentation map of the stains. Such a map would reflect the presence of different biomarkers or cell types to utilize in downstream analysis. The resulting concentration from our unsupervised solution can be used directly to do just that without further annotation or training. Each stain has a minimum concentration value below which the stain can be excluded from the competition for the dominating stain. During inference, each stain concentration map is thresholded and then an argmax function is applied to select the stain with the maximal concentration at each location. The resulting segmentation map has a single stain prediction at each pixel, reflecting the predicted dominant stain at each location. The threshold parameters are fixed for each stain and are empirically selected on a small held out set. See sample results in Figure 3.

Evaluation with Dot Annotations. We tested the model on 96 patches of size 1200×1920 from 42 cases. These test patches have manual dot annotations for each biomarker where each dot marks the approximate center of a cell. The dot annotations are expanded to superpixels (Achanta et al., 2012) for visualization in second row of Figure 3. We compute the F-score for the predicted semantic segmentation maps for each biomarker, based on whether or not the generated segments intersect with the dot annotations of the corresponding biomarker. Details of F-score computation are in Appendix A. Table 1 shows the

F-score results. We compare our method *InverseAE* to the supervised models: *ColorAE* and *UNet* (Ronneberger et al., 2015), and to the unsupervised methods: *LassoReg* (Chen and Chefd'hotel, 2014), *PseudoInv.* which is an extension of (Ruifrok and Johnston, 2001) to support a stain matrix with > 3 stains using matrix pseudo inverse, and *Nearest Neighbor*, which basically assigns the stain with the closest Euclidean distance to the pixel color value. See Appendix A for a description of the baselines. From Table 1, *InverseAE* outperforms all other unsupervised methods, coming at close second after *ColorAE*. Figure 3 shows sample results from *InverseAE*.

Evaluation with Ground Truth Concentration Maps. We assessed the quality of the concentration maps of the trained *InverseAE* and *ColorAE* models compared to 2-plex SOTA stain decomposition method (Vahadane et al., 2016) on a set of IHC 2-plex images using structure similarity index (SSIM). The 2-plex images were stained with one of the immune/tumor biomarkers plus hematoxylin. The results are in Table 2. Interestingly, the SSIM scores for *InverseAE* are often better than those for *ColorAE* showing that it better captures the continuous values of the concentration maps.

6. Conclusion

While brightfield mIHC is a cost effective and accessible multiplex imaging method, it does not offer separate channels for different biomarkers. Furthermore, existing unsupervised stain decomposition methods do not scale well with the increase in number of multiplexed stains. This makes brightfield mIHC impractical compared to more expensive multiplex imaging methods. In this work, we have tackled the problem of stain decomposition in mIHC images and shown the efficacy of our proposed approach on mIHC images with 7 simulataneous stains. Our unsupervised approach, '*InverseAE*' , allows pathologists to get accurate results while relieving them from the burden of annotation. We propose a novel training regularizer for stain decomposition, '*inversion regulation*', to create additional constraints during training that limit the solution space. Hence *InverseAE* learns to capture the correct cell types, and the resulting stain concentration maps are representative of the underlying staining. Consequently, *InverseAE* enables high quality stain segmentation maps which are essential for downstream analysis.

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Appendix A. Training and Implementation Details

Training Details. The constant weight values λ_1 and λ_2 in Equation 6 are both set to 1 in our experiments. The training dataset consists of 60 annotated patches from 6 whole slide images. The size of the patches is 1200×1920 at 40x. 40 Patches from 4 cases were used for training and the remaining 20 patches from the other 2 cases were used for validation. For training, the images are resized to 20x and cut up into 400×400 overlapping patches, resulting in a total of 240 labeled training patches.

Models Compared. We train our proposed method *InverseAE* on the 240 patches, without annotation. We compare to the unsupervised approaches:
(1) *LassoReg*: the lasso regression unsupervised method described in (Chen and Chefd'hotel, 2014) which is designed to work on images with 4+ multiplex staining. We used L1 norm weight $\lambda = 10^{-3}$.
(2) *PseudoInv*: an extension of (Ruifrok and Johnston, 2001) for color deconvolution that solves the equation $\boldsymbol{C} = \boldsymbol{S}^{-1} \times \boldsymbol{Y}$ for more than 3 stain vectors using pseudo inverse of $\boldsymbol{S}$.
(3) *Nearest Neighbor* baseline which basically assigns the stain with the closest Euclidean distance to the pixel color value.
Additionally, we use the dot annotations to train with weak supervision:
(4) *ColorAE*: the weakly supervised method in (Abousamra et al., 2020).
(5) *UNet*: a supervised deep learning model based on UNet model architecture (Ronneberger et al., 2015). Different from previous methods, UNet's output is not stain concentration maps but rather likelihood maps. For each pixel, the output is the probability that the pixel belongs to each stain class. Superpixel annotation maps (Achanta et al., 2012) derived from the dot labels are used as the ground truth labels.

F-score Computation. We computed the F-score for each biomarker/cell type, as follows: a true positive is a predicted stain segment that intersects with an annotation dot, a false positive is a segment that doesn't intersect with any annotation dot, a false negative is an annotation dot that does not intersect with any predicted segment.

Appendix B. Ablation Study.

Here we present ablation studies on the design choices for our unsupervised model *InverseAE*. In Table 3 we present the F-score results on the 96 annotated patches using variations from our proposed method. First, the results show the importance of the inverse reconstruction loss. Without it (rows 1-3), the predicted maps are not representative of the stains visually present in the mIHC image. This is clear from the very low F-scores. Second, replacing the inverse reconstruction loss with a L1 sparsity constraint (row 2) is not sufficient to get representative concentration maps. We notice sparsity in the prediction, nevertheless the prediction is not correlated with the observed stains. We find the dominating stains in the prediction are mostly CD3's yellow and CD8's purple, while the tumor (brown) and the CD16 (black) biomarkers are missing, as evidenced by their zero F-score in the table. Third, instead of the inverse regulation loss, we use the inverted images and stains as data augmentation (row 3). We observe that we get slightly improved performance compared to the L1 sparisity constraint (row 2), however it also suffers from missing biomarkers in the predicted concentration maps. Finally, without the conditional

Table 3: Ablation study on unsupervised model design InverseAE, evaluated with F-score of stain segmentations with respect to dot annotations on 96 patches from 42 cases.

Inverse Reg.	Conditional AE	$L1$ Sparsity	Inv. Aug.	CD3	CD4	CD8	CD16	CD20	Tumor	Mean
	✓			0.235	0.307	0.409	0.121	0.326	0.147	0.257
	✓	✓		0.215	0.228	0.337	0.000	0.300	0.000	0.180
	✓		✓	0.407	0.411	0.716	0.000	0.117	0.000	0.275
✓				0.482	0.501	0.753	0.324	0.274	0.220	0.426
✓	✓			**0.644**	**0.530**	**0.813**	**0.632**	**0.327**	**0.556**	**0.584**

autoencoder (row 4) i.e., predicting all the stains at once without target stains conditional input, the scores are lower and the model does not generalize well. The conditional input prevents the model from overfitting and allows the model to better capture the target stains in the image.

Appendix C. RGB to HSL Conversion.

We include here the formulas for obtaining saturation and lightness from RGB for their relevance. The complete conversion algorithm including hue can be found in (Agoston, 2005). To convert from a normalized RGB color (r, g, b) to HSL space, we first define the variables M and m that represent the maximum and minimum of (r, g, b), respectively :

$$M = max(r, g, b) \tag{7}$$

$$m = min(r, g, b) \tag{8}$$

The formula for luminosity L:

$$L = \frac{1}{2}(M + m) \tag{9}$$

The formula for saturation $\mathcal{S}$:

$$\mathcal{S} = \begin{cases} 0 & \text{if } L = 0 \text{ or } L = 1. \\ \frac{M-m}{1-|2L-1|} & \text{otherwise.} \end{cases} \tag{10}$$

For the inverted color $(r', g', b') = (1 - r, 1 - g, 1 - b)$, the formulas become:

$$M' = 1 - m \tag{11}$$

$$m' = 1 - M \tag{12}$$

$$L' = 1 - L \tag{13}$$

$$\mathcal{S}' = \begin{cases} 0 & \text{if } L' = 0 \text{ or } L' = 1. \\ \frac{M'-m'}{1-|2L'-1|} & \text{otherwise.} \end{cases} = \begin{cases} 0 & \text{if } L = 0 \text{ or } L = 1. \\ \frac{M-m}{1-|2L-1|} & \text{otherwise.} \end{cases} = \mathcal{S} \tag{14}$$

Appendix D. Inversion Regulation Eliminates Many Undesired Solutions

We assume that at each pixel there is a dominant stain which should be assigned to that pixel in the final stain segmentation maps. If we consider the luminosity component in the HSL color space, when the luminosity of a color is L, the luminosity of its inverse is $1-L$, see Appendix C. Now, if we define the absorption power of a color as the average of the minimum and maximum of its red, green, and blue light absorption, then by definition (Agoston, 2005), its luminosity is inversely correlated with it's absorption power. As a result, since a color and its inverse have opposite luminosity, they also have opposite absorption powers. We show here how this property allows us to eliminate a large part of the undesired solution space by employing the inverse regulation.

BL allows a color to be made up of multiple colors added together weighted by their concentrations. Consequently, in the OD space, a pixel's color can be composed by the addition of multiple stains -other than the true stain present at that pixel- as long as their red, green, and blue OD (absorption) values sum up to the color's red, green, and blue OD (absorption) values, respectively. This is an undesired solution. However, this solution will not hold in the inverse space as long as no stain is a function of another by a multiplicative factor. We can see this by a simple example: A stain vector representing white or the background tissue will have very low absorption, for instance $(250, 250, 250)_{RGB} \implies (0.01, 0.01, 0.01)_{OD}$. By BL, it can be added to any color without modifying the color's OD. Nevertheless, in the inverse space, this does not hold because the complement color has high absorption (OD): $(5, 5, 5)_{inv-RGB} \implies (1.7, 1.7, 1.7)_{inv-OD}$. As a result, it will modify the OD of any pixel it is added to its mixture and thus it cannot be added blindly. Another example, consider the 3 stain vectors:

$SA_{RGB} = (250, 100, 100) \implies SA_{OD} \simeq (0.0, 0.4, 0.4)$
$SB_{RGB} = (250, 250, 100) \implies SB_{OD} \simeq (0.0, 0.0, 0.4)$
$SC_{RGB} = (250, 100, 250) \implies SC_{OD} \simeq (0.0, 0.4, 0.0)$
By BL, SA can be expressed as a linear combination of SB and SC.

$$SA_{OD} = SB_{OD} + SC_{OD} \tag{15}$$

Now if we examine the same stains in the inverse space:
$SA_{inv-RGB} = (5, 155, 155) \implies SA_{inv-OD} \simeq (1.7, 0.2, 0.2)$
$SB_{inv-RGB} = (5, 5, 155) \implies SB_{inv-OD} \simeq (1.7, 1.7, 0.2)$
$SC_{inv-RGB} = (5, 155, 5) \implies SC_{inv-OD} \simeq (1.7, 0.2, 1.7)$
Equation 15 does not hold in the inverse space.

$$SA_{inv-OD} \neq SB_{inv-OD} + SC_{inv-OD} \tag{16}$$

This illustrates how the inverse regulation helps to avoid many such undesired solutions and promote good solutions.