Reducing the Effect of Incomplete Annotations in Object Detection for Histopathology

Denys Kaliuzhnyi, Dmytro Fishman, Mikhail Papkov
Institute of Computer Science, University of Tartu
Tartu, Estonia
{denys.kaliuzhnyi,dmytro.fishman,mikhail.papkov}@ut.ee

Abstract

Training neural networks for object detection usually requires decent amounts of data to produce great results. Apart from the image variety, the number of annotated objects is a crucial factor for success. In histopathology, the average annotation density is very high, resulting in resource-consuming data preparation for neural network training. We explore the effect of incomplete annotations in object detection. We show that modern object detectors, such as YOLO-v5, can effectively learn from histopathology datasets that lack up to 90% of annotations. Additionally, we suggest an easy model tuning setup to reduce the impact of incomplete annotations and enhance learning capability overall. Code for reproducibility can be found at `https://github.com/DenysKaliuzhnyi/yolov5`.

1 Introduction

Deep neural networks performing object detection tasks demand large quantities of images. Usually each image is thoroughly annotated — every object has a label assigned by a human expert. The network is trained under the assumption that no object is missing. In histopathology, object density differs drastically from the popular natural image datasets, such as COCO (Lin et al., 2014), easily reaching several hundred per image. Thus, annotation efforts increase proportionally and can be costly and time-consuming.

This leads to a natural question: is it possible to label only a portion of the objects in each image without performance degradation from the model trained on 100% of data? A handful of research attempted to address this question. Zhang et al. (2020) proposed a background recalibration loss designed to downplay confidently misdetected objects . Wang et al. (2021) introduced a co-mining procedure with Siamese network generating pseudo-labels. Both methods were developed for RetinaNet (Lin et al., 2017) and reported more than 10% increase in AP_{50} compared to the baseline when trained on 50% of annotations. However, they introduce additional hyperparameters to tune and require a substantial modification of the pipeline when transferring to another architecture.

In this work, we explore the influence of missing annotations on object detection performance in the histopathology domain. We hypothesise that modern neural networks, such as YOLO-v5 (Jocher et al., 2021), can be trained efficiently with a significant portion of missing annotations without sophisticated add-ons. Additionally, we find a set of hyperparameters that increases the overall model performance and reveal an instance which greatly aids in missing annotation settings.

2 Methods

We used a small version of YOLO-v5 in all the experiments (we describe it in detail in Appendix A). To adopt the model for histopathology domain, we manually tuned hyperparameters. First, we took into account vertical flip invariance and enabled the respective augmentation (`flipud`). Second, we tuned optimization parameters, such as learning rate, scheduler, and batch size. The exact values of the default and changed hyperparameters are listed in Table 2. To improve the score under missing annotation data, we emphasise the importance of the objectness positive class weight (`obj_pw`). We decreased it tenfold, which downweighted the prediction of positive samples. This forced the model to learn less from false positive predictions (most of which we assume to be unannotated objects).

| (a)   100% | (b)   50% | (c)   25% | (d)   10% |

Figure 1: Example test predictions of YOLO-v5 models trained on datasets with randomly sampled annotations. Subset sampling ratio is displayed below the image (100% is no sampling). Red boxes correspond to ground truth, green ones – to predictions. Yellow arrows highlight false predictions.

3   EXPERIMENTS

We trained all the models on MoNuSeg 2018 dataset (Kumar et al., 2017; 2019) — stained tissue images of various tumour-affected organs from multiple hospitals. The training set contains 30 huge-resolution whole slide images (WSI) with around 22 000 annotated cells. The test set consists of 14 images with 7 000 annotations. We follow Nguyen et al. (2021) for data preprocessing and extraction of 512×512 px training patches.

We uniformly sampled 50%, 25%, and 10% of annotations with five different random seeds for each image in the training set to simulate incompleteness. The number of images in the dataset remained the same. For each of the generated subsets as well as the complete set (further mentioned as 100% subset), we trained the baseline and tuned model. Then, the training results were averaged out for each percentage value across experiment seeds to yield more stable results (except for the 100% set).

We selected the model checkpoint with the best validation loss and adjusted the confidence threshold to maximise F_1 score. Test evaluation results are summarised in Table 1. The scores on the training subsets show to be similar, even in the baseline model. The tuned model produced better results for all annotation subsets, including the full one. Additionally, the tuned model reduced the gap between the 100% set and 10% subset from 3.3% to 1,9% AP_{50} score. Example detection results are demonstrated in Figure 1.

We observe the robustness of YOLO-v5 to missing annotations under the assumption that the annotated remainder is still adequate to learn object features (e.g., 2 200 annotations in 10% set is still a decent volume). The robustness can be explained by the YOLO-v5's excessive box prediction (prior to suppression) in conjunction with adjustable confidence threshold estimated on a validation set.

Table 1: AP_{50} detection score of models trained on data with missing annotation averaged over five runs with different random sampling seeds ($N\%$ in header denotes a sampling ratio per image).

	100%	50%	25%	10%
baseline	0.903	0.892 ± 0.003	0.883 ± 0.015	0.870 ± 0.015
tuned	0.909	0.907 ± 0.002	0.901 ± 0.007	0.890 ± 0.012
	(+0.6%)	(+1.5%)	(+1.8%)	(+2%)

4   CONCLUSIONS

We demonstrated that YOLO-v5 can be tuned for handling histopathology data with missing annotations. With high object density, it is possible to annotate just 10% of them while losing only 2% of performance compared to the full annotation, and 50% can already yield near-equal results. This finding bears practical value for pathologists, allowing them to spend less time labelling data.

URM STATEMENT

The authors acknowledge that at least one key author of this work meets the URM criteria of ICLR 2023 Tiny Papers Track.

ACKNOWLEDGMENTS

This work was funded by Revvity, Inc. and the Estonian Ministry of Foreign Affairs Development Cooperation and Humanitarian Aid funds. The computational resources were provided by the High Performance Computing Center of the University of Tartu.

REFERENCES

Alexey Bochkovskiy, Chien-Yao Wang, and Hong-Yuan Mark Liao. Yolov4: Optimal speed and accuracy of object detection. *arXiv preprint arXiv:2004.10934*, 2020.

Kaiming He, Xiangyu Zhang, Shaoqing Ren, and Jian Sun. Spatial pyramid pooling in deep convolutional networks for visual recognition. *IEEE transactions on pattern analysis and machine intelligence*, 37(9):1904–1916, 2015.

Glenn Jocher, Alex Stoken, Ayush Chaurasia, Jirka Borovec, NanoCode012, TaoXie, Yonghye Kwon, Kalen Michael, Liu Changyu, Jiacong Fang, Abhiram V, Laughing, tkianai, yxNONG, Piotr Skalski, Adam Hogan, Jebastin Nadar, imyhxy, Lorenzo Mammana, AlexWang1900, Cristi Fati, Diego Montes, Jan Hajek, Laurentiu Diaconu, Mai Thanh Minh, Marc, albinxavi, fatih, oleg, and wanghaoyang0106. ultralytics/yolov5: v6.0 - YOLOv5n 'Nano' models, Roboflow integration, TensorFlow export, OpenCV DNN support, October 2021. URL https://doi.org/10.5281/zenodo.5563715.

Neeraj Kumar, Ruchika Verma, Sanuj Sharma, Surabhi Bhargava, Abhishek Vahadane, and Amit Sethi. A dataset and a technique for generalized nuclear segmentation for computational pathology. *IEEE transactions on medical imaging*, 36(7):1550–1560, 2017.

Neeraj Kumar, Ruchika Verma, Deepak Anand, Yanning Zhou, Omer Fahri Onder, Efstratios Tsougenis, Hao Chen, Pheng-Ann Heng, Jiahui Li, Zhiqiang Hu, et al. A multi-organ nucleus segmentation challenge. *IEEE transactions on medical imaging*, 39(5):1380–1391, 2019.

Tsung-Yi Lin, Michael Maire, Serge Belongie, James Hays, Pietro Perona, Deva Ramanan, Piotr Dollár, and C Lawrence Zitnick. Microsoft coco: Common objects in context. In *Computer Vision–ECCV 2014: 13th European Conference, Zurich, Switzerland, September 6-12, 2014, Proceedings, Part V 13*, pp. 740–755. Springer, 2014.

Tsung-Yi Lin, Priya Goyal, Ross Girshick, Kaiming He, and Piotr Dollár. Focal loss for dense object detection. In *Proceedings of the IEEE international conference on computer vision*, pp. 2980–2988, 2017.

Ethan H Nguyen, Haichun Yang, Ruining Deng, Yuzhe Lu, Zheyu Zhu, Joseph T Roland, Le Lu, Bennett A Landman, Agnes B Fogo, and Yuankai Huo. Circle representation for medical object detection. *IEEE transactions on medical imaging*, 41(3):746–754, 2021.

Joseph Redmon and Ali Farhadi. Yolov3: An incremental improvement. *arXiv preprint arXiv:1804.02767*, 2018.

Mingxing Tan and Quoc Le. Efficientnet: Rethinking model scaling for convolutional neural networks. In *International conference on machine learning*, pp. 6105–6114. PMLR, 2019.

Chien-Yao Wang, Hong-Yuan Mark Liao, Yueh-Hua Wu, Ping-Yang Chen, Jun-Wei Hsieh, and I-Hau Yeh. Cspnet: A new backbone that can enhance learning capability of cnn. In *Proceedings of the IEEE/CVF conference on computer vision and pattern recognition workshops*, pp. 390–391, 2020.

Tiancai Wang, Tong Yang, Jiale Cao, and Xiangyu Zhang. Co-mining: Self-supervised learning for sparsely annotated object detection. In *Proceedings of the AAAI Conference on Artificial Intelligence*, volume 35, pp. 2800–2808, 2021.

Han Zhang, Fangyi Chen, Zhiqiang Shen, Qiqi Hao, Chenchen Zhu, and Marios Savvides. Solving missing-annotation object detection with background recalibration loss. In *ICASSP 2020-2020 IEEE International Conference on Acoustics, Speech and Signal Processing (ICASSP)*, pp. 1888–1892. IEEE, 2020.

A TRAINING DETAILS

YOLO-v5 is a single-stage anchor-based object detector known to be very fast and accurate. Its backbone consists of CSP-DarkNet (Bochkovskiy et al., 2020), the neck is comprised of SPP He et al. (2015) layers and CSPNet (Wang et al., 2020), and the head is taken from YOLO-v3 (Redmon & Farhadi, 2018) model. YOLO-v5 provides a family of models that vary in size (network width and depth) with scaling analogous to the approach used in EfficientNet (Tan & Le, 2019). We took YOLO-v5s, a "small" family member that accounts for nearly 7.2M parameters and is generally considered to be very lightweight.

Table 2: Selected hyperparameters. Changed parameters highlighted in **bold**.

Hyperparameter	Tuned value	Default value
lr0	**0.005**	**0.01**
lrf	**0.05**	**0.1**
momentum	**0.977**	**0.937**
weight_decay	0.0005	0.0005
warmup_epochs	3.0	3.0
warmup_momentum	0.8	0.8
warmup_bias_lr	0.1	0.1
box	0.05	0.05
cls	0.3	0.3
cls_pw	1.0	1.0
obj	**1**	**0.7**
obj_pw	**0.1**	**1**
iou_t	0.20	0.20
anchor_t	4.0	4.0
fl_gamma	0.0	0.0
hsv_h	0.015	0.015
hsv_s	0.7	0.7
hsv_v	0.4	0.4
degrees	0.0	0.0
translate	0.1	0.1
scale	0.9	0.9
shear	0.0	0.0
perspective	0.0	0.0
flipud	**0.5**	**0.0**
fliplr	0.5	0.5
mosaic	1.0	1.0
mixup	0.1	0.1
copy_paste	0.0	0.0
weights	YOLO-v5s.pt	YOLO-v5s.pt
epochs	300	300
batch-size	**32**	**16**
imgsz	**512**	**640**
rect	disabled	disabled
noautoanchor	disabled	disabled
image-weights	**enabled**	**disabled**
multi-scale	disabled	disabled
optimizer	SGD	SGD
cos-lr	**enabled**	**disabled**
patience	100	100