Unsupervised Noise Adaptive Speech Enhancement by Discriminator-Constrained Optimal Transport

Abstract

This paper presents a novel discriminator-constrained optimal transport network (DOTN) that enables unsupervised domain adaptation for speech enhancement (SE), which is an essential regression task in speech processing. The DOTN aims to estimate clean references, given noisy speech signals in a testing domain, by exploiting the knowledge available from the training domain. The domain shift between training and testing data has been reported to be an obstacle to learning problems in diverse fields. Although rich literature exists on unsupervised domain adaptation for classification, the methods proposed, especially in regressions, remain scarce and often depend on additional information regarding the input data. The proposed DOTN approach tactically fuses the optimal transport theory from mathematical analysis with generative adversarial frameworks, to help evaluate continuous labels in the target domain. The experimental results on two SE tasks demonstrate that by extending the classical optimal transport formulation, our proposed DOTN outperforms previous adversarial domain adaptation frameworks in a purely unsupervised manner.

1 Introduction

The goal of speech enhancement (SE) is to convert low-quality speech signals to ones with improved quality and intelligibility. SE serves as an important regression task in the speech-processing filed and has been widely used for a pre-processor in speech-related applications, such as speech coding [1], automatic speech recognition (ASR) [2], speaker recognition [3], and assistive hearing devices [4, 5]. Recent advances in machine learning have made significant progress to the SE technology. Generally, learning-based SE approaches estimate a transformation to characterize the mapping function from noisy to clean speech signals in the training phase [6]. The estimated transformation converts noisy speech signals to generate clean-like signals in the testing phase. Various neural network models have been used to characterize noisy-to-clean transformations. Well-known examples of such models include fully connected neural network [7], deep denoising autoencoder [8], convolutional neural network [9], long-short-term memory [10], and Transformer [11]. To effectively handle diverse noisy conditions, we usually prepare a considerable amount of training data that cover various noise types to train SE models. However in real-application scenarios, the noise types in the testing data may not always be involved in the training set. Consequently, the noisy-to-clean transformation learned from the training data cannot be suitably applied to handle the testing noise, resulting in limited enhancement performance. This training-testing mismatch is generally called a domain mismatch issue for SE. An effective solution is required to perform domain adaptation to adjust the SE models with formulating a precise noisy-to-clean transformation that matches the testing conditions. Most existing domain adaptation methods rely on at least one of the following adaptation mechanisms: aligning domain-invariant features [12, 13, 14] and adversarial training, where a discriminator is introduced during training as a domain classifier [15, 16, 17].

Abundant promising results have been provided in the classification task; however, relatively limited results have been obtained regarding problems with a regression nature. In this study, we aim to solve the unsupervised domain adaptation problem for SE. In particular, we consider circumstances when SE is tested on a target domain with completely unlabeled data, and a source domain with a rich labeled dataset is available for reference.

We propose utilizing joint distribution optimal transport with integrating adversarial training for domain adaptation to attain better performance. Notably, although adversarial training is a key element in our proposed method, our discriminator is **not** a domain classifier, as in previous adversarial domain adaptation methods. In contrast, the discriminator in our method was employed to learn the probability distribution of the source labels. This novel approach was designed specifically for the SE domain adaptation and exhibited excellent performance on the standardized VoiceBank-DEMAND and TIMIT datasets.

Contributions We proposed a novel method designed specifically for unsupervised domain adaptation in a regression setting. This area of study still has very limited results; moreover, the existing methods often require additional classification of source domains or may not yet be supported by strong regression applications. Conversely, our approach does not require any additional input information other than the source samples, source labels, and target samples. Our approach was applied to two standardized SE tasks, namely VoiceBank-DEMAND and TIMIT, and achieved superior adaptation performance in terms of both perceptual evaluation of speech quality (PESQ) and short-time objective tntelligibility (STOI) scores. Furthermore, owing to the simple input requirements, we can easily investigate the effect of target sample complexity on our method by increasing the number of noise types allowed in the target domain, which has not been reported by in previous literature to the best of our knowledge.

2 Related work

Adversarial domain adaptation: The main objective of domain adversarial training (DAT) is to adapt a pre-trained deep model (from the source domain) by leveraging a considerable amount of unlabeled data from the target domain [15, 18]. A conventional DAT system consists of three parts, deep feature extractor, label predictor, and domain classifier. By using a gradient reversal layer, the extracted deep features are discriminative for the main learning task and invariant with shifts between the source and target domains. The DAT approach has been applied and confirmed to effectively compensate for the mismatch of source (training time) and target (testing time) conditions in numerous tasks, such as speech signal processing [19, 20], image processing [15, 21], and wearable sensor signal processing [22]. Subsequently, a multisource domain adversarial networks (MDAN) has been developed to extend the conventional DAT by using multiple domain classifiers to extract discriminative deep features for the main learning task while being invariant to multiple domain shifts [23, 3].

Optimal transport for domain adaptation: Hitherto, OT [24, 25] has been utlized to domain adaptation [26, 27] with related analytical results [28]. Furthermore, the concepts of OT have proved itself even more useful under a joint distribution framework [29, 30]. More recently, to improve the sensitivity of OT to outliers, Robust OT was proposed [31]. Moreover, a method for combining the notion of adversarial domain adaptation with OT and margin separation has been proposed [32]. However, almost all experiments performed in these studies were classification problems, unlike the SE task that is the focus of our study.

Domain adaptation in speech enhancement: Existing domain adaptation in SE approaches can be divided into two categories: supervised and unsupervised. For supervised domain adaptation, paired noisy and clean speech signals for the testing conditions are available to adjust the parameters in the SE models. In [33, 34], transfer-learning-based approaches have been proposed to adapt SE models to alleviate corpus mismatches. To combat the catastrophic forgetting issue, Lee et al., proposed a SERIL algorithm that combines curvature-based regularization and path optimization augmenting strategies when preforming domain adaptation on SE models [35]. Conversely, for unsupervised domain adaptation, only noisy speech signals are provided, and the corresponding clean counterparts are not accessible.

Generally, unsupervised domain adaptation has good applicability to real-world scenarios; nonetheless, its performance cannot be compared with supervised domain adaptation. In [36], unsupervised domain adaptation for SE was performed by minimizing the Kullback-Leibler divergence between posterior probabilities produced by teacher and student senone classifiers without paired noisy-clean adaptation data. In [19, 37], the DAT approach was used to adapt SE models to new noisy conditions. Despite yielding promising performance, the existing unsupervised domain adaptation approaches require additional information, such as word labels, language models, and noise-type labels. In this study, we propose a novel discriminator-constrained OT network (DOTN) to perform domain adaptation on SE in an unsupervised manner. In contrast to related works, DOTN does not require additional label information when adapting the original SE models to match new noisy conditions. Our experiments show that DOTN can effectively adapt the SE models to new testing conditions, and that it achieves better adaptation performance than DAT [19, 37], which requires additional noise type information.

3 Method

3.1 Problem setting and notation

Consider a source domain with paired data $(\mathbf{X}^s, \mathbf{Y}^s) = \{(\mathbf{x}_i^s, \mathbf{y}_i^s)\}_{i=1}^{N_s}$, where $\mathbf{x}_i^s \in \mathbb{R}^n$, $\mathbf{y}_i^s \in \mathbb{R}^m$ stand for the input and the corresponding label of sample i. The unsupervised domain adaptation assumes that another target domain exists containing only data unlabeled, $\mathbf{X}^t = \{\mathbf{x}_i^t \in \mathbb{R}^n\}_{i=1}^{N_s}$. The goal is to seek a ground truth estimator (or statistical hypothesis) $f : \mathbb{R}^n \to \mathbb{R}^m$ for the target labels $\mathbf{Y}^t = \{\mathbf{y}_i^t\}_{i=1}^{N_t}$ (exist but not known), based on the knowledge provided by the source domain.

The probability distribution of a dataset $\mathcal{D}$ is denoted by $\mathbb{P}_{\mathcal{D}}$, where $\mathcal{D}$ is either $\mathbf{X}^s$, $\mathbf{Y}^s$, $\mathbf{X}^t$ or $\mathbf{Y}^t$ in our discussion. Our problem is to find a function f such that f induces a probability distribution $\mathbb{P}_{f(\mathbf{X}^t)}$ in $\mathbf{Y}^t$ with $\mathbb{P}_{f(\mathbf{X}^t)} \to \mathbb{P}_{\mathbf{Y}^t}$ under certain measure. We propose using the concept of Optimal Transport (OT) to solve this problem.

3.2 Proposed model: Discriminator-Constrained Optimal Transport Network (DOTN)

Given a pair of distributions $\mathbb{P}_{\mathcal{D}_1}$ and $\mathbb{P}_{\mathcal{D}_2}$ and a displacement cost matrix $C \geq 0$, OT solves for the transportation plan $\gamma \in \prod(\mathbb{P}_{\mathcal{D}_1}, \mathbb{P}_{\mathcal{D}_2})$ that minimizes the total cost (in a discrete setting)

$$\min_{\gamma \in \prod(\mathbb{P}_{\mathcal{D}_1}, \mathbb{P}_{\mathcal{D}_2})} \langle C, \gamma \rangle_F,$$

where $\prod(\mathbb{P}_{\mathcal{D}_1}, \mathbb{P}_{\mathcal{D}_2})$ denotes the space of joint distributions with marginal $\mathbb{P}_{\mathcal{D}_1}$ and $\mathbb{P}_{\mathcal{D}_1}$. $\langle \cdot, \cdot \rangle_F$ is the Frobenius product, and the entry C_{ij} of C represents the displacement cost of the i-th and j-th samples. It can be proven that the minimum of this problem is a distance and called the Wasserstein distance when the corresponding cost is a norm [24, 25].

Our proposed method consists of two parts: OT alignment and Wasserstein Generative Adversarial Network (WGAN) training [38, 39]. Both steps are based on OT; however, they are considered with two different pairs of distributions and employ different algorithms.

Adaptation by Joint Distribution Optimal Transport Our adaptation mechanism relies on the alignment between the joint distributions of source and target domains (for the target domain, the label is estimated label). In particular, we approximated f by minimizing the OT loss between the joint distributions $\mathbb{P}_{\mathbf{X}^s} \times \mathbb{P}_{\mathbf{Y}^s}$ and $\mathbb{P}_{\mathbf{X}^t} \times \mathbb{P}_{f(\mathbf{X}^t)}$, with a chosen cost matrix

$$C_{ij} = \alpha \|\mathbf{x}_i^s - \mathbf{x}_j^t\|^2 + \beta \|\mathbf{y}_i^s - f(\mathbf{x}_j^t)\|^2,$$

where $\alpha, \beta > 0$.

By aligning the joint distributions of the source and target domains, noise adaptation is naturally achieved as OT seeks the source sample that is the most 'similar' for each target sample.

Although the joint distribution OT provides accurate estimates for each sample, the effect of each estimation error could accumulate in the training process and mislead f to a convenient local minimum. To avoid this situation, we employ Wasserstein Generative Adversarial Network (WGAN) training to complement and enhance our adaptation system.

Figure 1: DOTN network structure.

Discriminative training on outputs and source labels   Distinct from the adaptation where we consider the joint distributions of the inputs and labels, we focus on WGAN training for the source label distribution $\mathbb{P}_{\mathbf{Y}^s}$ and output distribution $\mathbb{P}_{f(\mathbf{X}^t)}$. In the terminology of generative adversarial training, we consider f a generator and introduce a convolutional neural network-based discriminator, h, as the 'critic'. In general, we use the discriminator to decide whether the outputs of f are 'similar' to the source labels. Formally, the WGAN algorithm solves

$$\min_f \max_{h \in \mathcal{L}} \left\{ \mathbb{E}_{y \sim \mathbb{P}_{\mathbf{Y}^s}}(h(y)) - \mathbb{E}_{x \sim \mathbb{P}_{\mathbf{X}^t}}(h(f(x))) \right\}$$

by Kantorovich-Rubinstein duality [24], where $\mathcal{L}$ is the set of 1-Lipschitz functions. In this case, under an optimal discriminator minimizing the value function with respect to the generator parameters minimizes the Wasserstein distance between the distributions $\mathbb{P}_{\mathbf{Y}^s}$ and $\mathbb{P}_{f(\mathbf{X}^t)}$.

This discriminative training complements our alignment and provides additional constraints from the explicit relation between the source labels and estimations of target labels. These constraints support the joint distribution alignment and provides further guidance in the gradient descent training process. The performance of the experiments is considerably improved when our discriminative training supports the joint distribution alignment.

3.3   Loss functions and the proposed algorithm

Our domain alignment can be achieved by solving the following optimization problem:

$$\min_{\gamma, f} \mathcal{L} = \min_{\gamma, f} \frac{1}{N^s} \sum_i \|\mathbf{y}_i^s - f(\mathbf{x}_i^s)\|^2 + \sum_{i,j} \gamma_{ij} \left(\alpha \|\mathbf{x}_i^s - \mathbf{x}_j^t\|^2 + \beta \|\mathbf{y}_i^s - f(\mathbf{x}_j^t)\|^2 \right), \quad (1)$$

where $\alpha, \beta > 0$ are the parameters chosen for balance. Notably, the first term emphasizes the knowledge in the source domain, such that during training the information is not forgotten. It has been revealed in several works that without this emphasis, the results are degraded as the source domain knowledge cannot be well-maintained [40, 41, 30]. This phenomenon was also observed in the SE experiments.

For discriminative training, discriminator h is trained by the discriminator loss function $\mathcal{L}_h = \frac{1}{m} \sum_{i=1}^m h(\mathbf{y}_i^s) - h(f(\mathbf{x}_i^t))$, and f follows the generator loss function $\mathcal{L}_f = -\frac{1}{m} \sum_{i=1}^m h(f(\mathbf{x}_i^t))$ where m is the batch size. As there are three sets of parameters γ, h and f in our framework, one set of parameters is updated each time, while the other sets of parameters are fixed.

4   Experiment

We evaluated our method in SE on two datasets: Voice Bank corpus [42] and TIMIT [43]. Although there is abundant literature on unsupervised domain adaptation, very limited methods have been successfully applied to SE or regression problems. Further, closely relevant methods often require additional input structures or domain label information, such as multiple source domains and noise-type labels. Unlike previous methods, our approach does **not** rely on either noise type labels or multiple source domain structure. Nevertheless, we compared our results with those of two most

Algorithm 1 DOTN, proposed algorithm

Require: $\mathbf{x}^s$, source domain inputs. $\mathbf{y}^s$, source domain labels. $\mathbf{x}^t$, target domain inputs. c, the clipping parameter. m, the batch size. n_f, the number of iterations of the OT alignment per generator's parameters. n_h, the number of iterations of OT alignment per critic's parameters.

Require: θ_f, initial parameters of estimator f. θ_h, initial parameters of discriminator h.

1: **for** each batch of source samples $(\mathbf{x}^s, \mathbf{y}^s)$ and target samples $(\mathbf{y}^t)$ **do**
2:      fix θ_f, solve for γ in (1) by OT.
3:      fix γ, $\theta_f \leftarrow \text{Adam}(\nabla_{\theta_f}\mathcal{L}, \theta_f)$.
4:      **if** $t \bmod n_f == 0$ **then**
5:          $\theta_f \leftarrow \text{Adam}(\nabla_{\theta_f}\mathcal{L}_f, \theta_f)$.
6:      **end if**
7:      **if** $t \bmod n_h == 0$ **then**
8:          $\theta_h \leftarrow \text{Adam}(\nabla_{\theta_h}\mathcal{L}_h, \theta_h)$.
9:          $\theta_h \leftarrow \text{clip}(\theta_h, -c, c)$.
10:     **end if**
11: **end for**

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relevant adversarial domain adaptation methods: DAT method in [19] and MDAN [44]. In fact, noise type labels of source and target samples are needed by DAT, and the structure of multiple source domains is needed by MDAN. Furthermore, the original MDAN was designed for classification problem and cannot be applied directly for SE application. Preserving the fundamental ideas, we modified the MDAN structure for regression problem, so that it can be applied to the experiments here for comparison. Our code is available at: https://github.com/Anonymous.

Due to the requirements of domain labels, DAT received inputs of the form $\{\mathbf{x}_i^s, \mathbf{y}_i^s, c_i\}_i$ and $\{\mathbf{x}_j^t, c_j\}_j$, where c_i is the noise type of its corresponding $\mathbf{x}_i^s$ or $\mathbf{x}_i^t$. MDAN was provided with five source domains, where each of them contains the source samples with one of the 5 pre-selected stationary noise type. On the other hand, the inputs for DOTN were directly the entire training set $\{\mathbf{x}_i^s, \mathbf{y}_i^s, \mathbf{x}_j^t\}_{i,j}$.

4.1 Voice Bank with DEMAND noise database

Dataset In the first set of experiments, the pre-selected subset of Voice Bank provided by [45] was used to test the proposed DOTN. For source domain data, 14 male speakers and 14 female speakers were randomly selected out of totally 84 speakers (42 male and 42 female), and each speaker pronounced around 400 sentences. As a result, the clean data in source domain contained 5,724 male utterances and 5,848 female utterances, amounting 11,572 utterances in total. We then mixed the 11,572 clean utterances with noise from DEMAND [46], in transportation category: "Bus", "Car", "Metro" at 7 Signal-to-noise ratio (SNR) levels (-9, -6, -3, 0, 3, 6, and 9 dB). Accordingly, for this set of source domain data, both noisy speech signals and the corresponding clean references are prepared.

The target domain data contained $17,304$ noisy utterances mixed from two random speakers (1 male, 1 female) (followed the design in [47]) with one of the three noise types from DEMAND, in STREET category: "Traffic", "Cafe", "Public square", and 7 SNR levels (-9, -6, -3, 0, 3, 6, and 9 dB). No clean labels were given under target domain. That is, for the target domain data, only noisy speech signals are provided and the corresponding clean references are not accessible.

All source samples (both noisy utterances and the corresponding clean references, prepared from the three transportation noise types) and the target samples (only noisy utterances without the corresponding clean references, prepared from the one street noise type) were included in our training set. We conducted the experiments under single-target noise-type circumstances and compared the results with DAT and MDAN. More specifically, we ran this setting for all three cases, where the target domain contained either cafe, public square, or traffic noise.

Results Table 1 and Table 2 list the PESQ and STOI scores, respectively, of DAT, MDAN and DOTN under three noise types at 7 SNR levels. "Avg" denotes the averaged scores over 7 SNR levels. From the PESQ scores reported in Table 1, we note that the proposed DOTN outperforms both DAT

Table 1: PESQ scores for VoiceBank-DEMAND

	DAT [19]	MDAN [44]	DOTN	DAT [19]	MDAN [44]	DOTN	DAT [19]	MDAN [44]	DOTN
SNR(dB)		**Traffic**			**Cafe**			**Public square**	
-9	1.307	1.670	**1.863**	1.058	**1.539**	1.497	1.436	1.929	**2.037**
-6	1.446	1.920	**2.182**	1.184	1.735	**1.853**	1.655	2.119	**2.258**
-3	1.718	2.153	**2.395**	1.362	1.949	**2.089**	1.939	2.318	**2.439**
0	2.081	2.366	**2.591**	1.599	2.153	**2.332**	2.268	2.512	**2.601**
3	2.381	2.535	**2.740**	1.865	2.345	**2.490**	2.575	2.670	**2.761**
6	2.712	2.708	**2.888**	2.189	2.534	**2.661**	2.867	2.824	**2.889**
9	3.016	2.854	**3.015**	2.493	2.695	**2.783**	3.120	2.966	**3.057**
Avg	2.094	2.315	**2.525**	1.679	2.136	**2.244**	2.266	2.477	**2.577**

Table 2: STOI scores for VoiceBank-DEMAND

	DAT [19]	MDAN [44]	DOTN	DAT [19]	MDAN [44]	DOTN	DAT [19]	MDAN [44]	DOTN
SNR(dB)		**Traffic**			**Cafe**			**Public square**	
-9	0.584	0.708	**0.721**	0.557	**0.643**	0.633	0.667	0.747	**0.765**
-6	0.659	0.761	**0.790**	0.616	0.702	**0.723**	0.725	0.792	**0.815**
-3	0.728	0.810	**0.833**	0.687	0.760	**0.779**	0.771	0.830	**0.850**
0	0.785	0.849	**0.871**	0.741	0.805	**0.831**	0.815	0.859	**0.877**
3	0.824	0.874	**0.894**	0.785	0.842	**0.861**	0.845	0.881	**0.900**
6	0.860	0.896	**0.914**	0.825	0.871	**0.887**	0.872	0.898	**0.915**
9	0.885	0.910	**0.927**	0.854	0.893	**0.905**	0.893	0.914	**0.931**
Avg	0.761	0.830	**0.850**	0.724	0.788	**0.803**	0.798	0.846	**0.865**

and MDAN consistently over different noise types and SNR levels, except for the Cafe noise type at -9 dB SNR. This might be owning to a potential limitation of DOTN, which will be detailed in the next section. Next, from Table 2, We note that STOI scores show very similar trends to that of PRSQ scores, as listed in Table 1.

4.2 TIMIT

Dataset   For the second part of experiments, TIMIT was used to prepare the source and target samples. The *clean speech* of the source domain $\{y_i^s\}_{i=1}^{N_s}$ for training consists of utterances, contributed by 10 male speakers and 5 female speakers. Each speaker had 8 sentences, including 5 SX (phonetically compact sentences) and 3 SI (phonetically diverse sentences), according to the official suggestion of TIMIT. The number of the speakers selected was to maintain the balance of the original data.

The above clean utterances were used to mix with 5 *stationary* noise types (Car, Engine, Pink, Wind, and Cabin) at 9 SNR levels (-12, -9, -6, -3, 0, 3, 6, 9, and 12 dB), amounting to 23040 noisy utterances, to be the *noisy speech* of the source domain $\{x_i^s\}_{i=1}^{N_s}$ with $N_s = 23040$.

For the target domain, a total of 24 speakers suggested by TIMIT core test set was all used to have 192 clean utterances for the target domain y_i^t, which were subsequently mingled with 4 *non-stationary* noise types: Helicopter, Cafeteria, Baby-cry, and Crowd-party with 7 SNR levels (-9, -6, -3, 0, 3, 6, and 9 dB) as target inputs $\{x_i^t\}_{i=1}^{N_t}$ with $N_t = 3612$. The choice of noise types for the source and target domain was to let the learning algorithms adapt from distinguished environments in the real-world.

Results   Table 3 lists the PESQ and STOI scores of the DAT, MDAN, and DOTN under four noise types at seven SNR levels. From the table, we first note that DOTN consistently outperforms DAT and MDAN in terms of both "Avg" PESQ and STOI scores among the four noise types. With a more careful investigation, the DOTN achieves higher PESQ and STOI scores over DAT and MDAN for all SNR conditions in the Helicopter noise. For the Crowd-party and Cafeteria noises, DOTN outperforms DAT and MDAN in most higher SNR conditions for both PESQ and STOI scores. However, for the Baby-cry noise, DOTN outperforms DAT and MDAN in STOI but underperforms MDAN in PESQ. Note that Cafeteria, Crowd-party, and Baby-cry noise types involved clear human speech components, which may cause confusions when DOTN tries to retrieve the target speech (clean reference). Thus, DOTN yields sub-optimal performance when dealing with these noise

Table 3: TIMIT results

	DAT [19]		MDAN [44]		DOTN		DAT [19]		MDAN [44]		DOTN	
Noise type	Helicopter						Crowd-party					
SNR(dB)	PESQ	STOI	PESQ	STOI	PESQ	STOI	PESQ	STOI	PESQ	STOI	PESQ	STOI
-9	1.031	0.392	1.252	0.517	**1.455**	**0.577**	**1.483**	**0.544**	1.150	0.440	1.056	0.451
-6	1.015	0.431	1.443	0.594	**1.669**	**0.649**	**1.484**	**0.560**	1.356	0.516	1.302	0.538
-3	1.094	0.497	1.664	0.670	**1.890**	**0.716**	1.528	0.592	**1.560**	0.600	1.559	**0.621**
0	1.268	0.566	1.902	0.742	**2.104**	**0.775**	1.596	0.636	1.776	0.684	**1.816**	**0.709**
3	1.518	0.637	2.134	0.801	**2.289**	**0.822**	1.736	0.690	1.986	0.762	**2.042**	**0.782**
6	1.779	0.701	2.363	0.849	**2.497**	**0.865**	1.953	0.750	2.179	0.823	**2.236**	**0.838**
9	2.094	0.759	2.563	0.884	**2.677**	**0.895**	2.200	0.801	2.355	0.865	**2.447**	**0.885**
Avg	1.400	0.569	1.903	0.722	**2.083**	**0.757**	1.711	0.653	1.766	0.670	**1.780**	**0.690**

	DAT [19]		MDAN [44]		DOTN		DAT [19]		MDAN [44]		DOTN	
Noise type	Cafeteria						Baby-cry					
SNR(dB)	PESQ	STOI	PESQ	STOI	PESQ	STOI	PESQ	STOI	PESQ	STOI	PESQ	STOI
-9	1.196	0.440	**1.248**	**0.471**	1.185	0.436	1.109	0.580	**1.116**	0.561	0.984	**0.597**
-6	1.206	0.471	1.395	**0.535**	1.419	0.528	1.313	0.630	**1.313**	0.636	1.180	**0.668**
-3	1.244	0.519	1.608	0.614	**1.631**	**0.620**	1.495	0.665	**1.500**	0.699	1.431	**0.732**
0	1.408	0.579	1.827	0.692	**1.859**	**0.699**	1.621	0.707	**1.734**	0.768	1.665	**0.789**
3	1.631	0.651	2.031	0.764	**2.075**	**0.769**	1.801	0.746	**1.909**	0.809	1.889	**0.835**
6	1.915	0.719	2.244	0.822	**2.271**	**0.826**	1.973	0.782	**2.112**	0.849	2.105	**0.871**
9	2.216	0.782	2.422	0.864	**2.458**	**0.873**	2.133	0.814	2.274	0.880	**2.277**	**0.890**
Avg	1.545	0.594	1.825	**0.680**	1.843	0.679	1.635	0.703	**1.708**	0.743	1.647	**0.769**

types, especially under very low SNR conditions, where background speech components might overwhelm the target speech. Nevertheless, the overall average PESQ and STOI scores of DOTN (P=1.838; Q=0.7238) are still higher than that of DAT (P=1.5728; Q=0.6298) and MDAN (P=1.8001; Q=0.7038), where P and Q denote the PESQ and STOI scores, respectively, over the 4 noise types and 9 SNR levels. Please also note that DAT and MDAB require additional domain label information [19] while DOTN performs domain adaptation in a purely unsupervised manner.

To show the advantages and flexibility of DOTN, we further explored and applied DOTN to the circumstances when multiple noise types are included in the target domain. Fig 2 and Fig 3, respectively, present the PESQ and STOI results over four SNR levels on multiple target noise types; here H, Ca, Cr, and B denote Helicopter, Cafeteria, Crowd-party, and Baby-cry noise types, respectively. In Fig 2, when the testing noise is "Helicopter", the PESQ scores of using two noise types (H+Ca, H+Cr, H+B) and three noise types (H+Cr+B, H+Cr+Ca, H+B+Ca) are comparable. Further, the PESQ scores of these six systems are also comparable to that of using one noise type (H). The results confirmed that the DOTN has minor effects on catastrophic forgetting, which is a common issue in domain adaptation approaches [48, 49]. In the case of 4 noise types (the system sequentially learned Helicopter, Baby-cry, Cafeteria, and Crowd-party noise types and was tested on the Helicopter noise), the achieved performance drops moderately. We observe very similar trends for the other three noise types (baby-cry, cafeteria, and crowd-party) in Fig 2.

From Fig 3, similar trends as those from Fig 2 are observed: (1) The seven results using 1, 2, and 3 noise types are comparable, thereby confirming that the DOTN has minor effects on catastrophic forgetting. (2) When there are 4 noise types for sequential learning, the achievable STOI scores start to decrease.

5 Conclusion

In this study, we proposed a novel DOTN method, which was designed specifically for unsupervised domain adaptation in regression setting. Our approach skillfully fuses OT and generative adversarial frameworks to achieve unsupervised learning in target domain based on the information provided from the source domain, requiring no additional structure or inputs, such as multi-source domain and noise type labels. Our experiments show that the proposed method is capable of superior adaptation performance in SE by outperforming other adversarial domain adaptation methods on both PESQ and STOI scores for the VoiceBank-DEMAND and TIMIT datasets. Further, we show that when moderately increasing the complexity of the target samples (by increasing the number of noise types

Figure 2: Comparison in PSEQ average for cases with multiple noise types in target domain, where H, Ca, Cr, and B denote Helicopter, Cafeteria, Crowd-party, and Baby-cry noise types.

Figure 3: Comparison in STOI average for cases with multiple noise types in target domain.

in the target domain), only a small degree of degradation was observed. This suggests that our method is robust to sample complexity in the target domain.

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