Towards Unbiased Calibration using Meta-Regularization

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Abstract

Model miscalibration has been frequently identified in modern deep neural networks. Recent work aims to improve model calibration directly through a differentiable calibration proxy. However, the calibration produced is often biased due to the binning mechanism. In this work, we propose to learn better-calibrated models via meta-regularization which has two components: (1) gamma network (γ-Net), a meta learner to output sample-wise gamma values (continuous variable) for Focal loss for regularizing the backbone network; (2) smooth expected calibration error (SECE), a Gaussian-kernel based unbiased and differentiable surrogate to ECE that enables the smooth optimization γ-Net. We evaluate the effectiveness of proposed approach in regularizing neural network towards improved and unbiased calibration on three computer vision datasets. We empirically demonstrate that: (a) learning sample-wise γ as continuous variables can effectively improve calibration; (b) SECE smoothly optimizes γ-Net towards unbiased and robustness to the binning schemes; and (c) the combination of γ-Net and SECE achieves the best calibration performance across various calibration metrics while retaining very competitive predictive performance as compared to multiple recently proposed methods.

1 Introduction

Deep Neural Networks (DNNs) have demonstrated promising predictive performance in various domains, including computer vision (Krizhevsky et al., 2012), speech recognition (Graves et al., 2013), and natural language processing (Vaswani et al., 2017). Consequently, trained deep neural network models are frequently deployed and utilized in real-world systems. However, recent work (Guo et al., 2017) has pointed out that these highly accurate, negative log likelihood-trained deep neural networks are often poorly calibrated (Niculescu-Mizil & Caruana, 2005b). Their predicted class probabilities do not accurately estimate the true probability of correctness, resulting in primarily overconfident and under-confident predictions. Deploying such miscalibrated models into real-world systems poses a significant risk, particularly when model outputs are directly utilized to serve customers' requests in applications such as medical diagnosis (Caruana et al., 2015) and autonomous driving (Bojarski et al., 2016). Better-calibrated model probabilities can serve as an essential signal toward building more reliable machine learning systems.

A recent trend aims to learn a calibrated model by directly optimizing the model to minimize errors on calibration metrics. One representative work is from Kumar et al. (2018), where they developed a differentiable equivalent of ECE, the Maximum Mean Calibration Error (MMCE). Mukhoti et al. (2020) found that focal loss (Lin et al., 2017), as a good alternative to standard cross-entropy, can effectively improve calibration. They also highlighted the crucial role of the gamma parameter in focal loss in making this approach effective, and proposed a sample-dependent schedule based on heuristics (Lambert-W function (Corless et al., 1996)) for the gamma in focal loss (FLSD), which showed superior calibration performance compared to baselines. Bohdal et al. (2021) proposed using a meta-learning-based approach termed as meta-calibration. In their formulation, the backbone network learns to optimize a standard cross-entropy loss, while a differentiable proxy for calibration error (i.e., DECE) is used to tune the parameters of the weight regularizer.

Motivated by advancements in this area, we introduce a learnable approach that involves learning sample-wise γ values via a meta-network, referred to as the gamma network (i.e., γ-Net), as illustrated in Figure 1. The key distinctions from Focal loss (Lin et al., 2017) and FLSD (Mukhoti et al., 2020), where a global

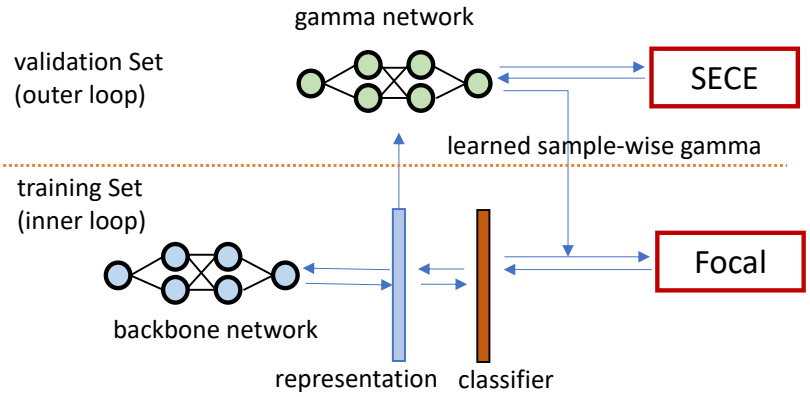


Figure 1: Our proposed approach for regularizing the base network towards better calibration with two new components: γ-Net and SECE . The inner loop optimizes the backbone network (e.g., ResNet) which uses focal loss as an objective function. The γ-Net in the outer loop takes the extracted second last layer representation of backbone network as input, learns to output sample-wise γ for focal loss at a continuous space. The γ-Net is optimized by using the proposed SECE, a Gaussian-kernel based unbiased and differentiable calibration error.

γ parameter (e.g., setting $\gamma = 3$ or $\gamma = 5$) is employed as a fixed parameter or scheduled across training epochs, are twofold: our approach (1) learns more finely-grained gamma values at the sample level; (2) the learned γ values are continuous variables. The output of the γ-Net, namely the learned γ values, is then utilized to regularize a backbone network towards improved calibration. The optimization of the γ-Net is achieved with a proposed differentiable surrogate for expected calibration error (Naeini et al., 2015): Smooth ECE (SECE), an unbiased Gaussian kernel based ECE estimator. SECE optimizes γ-Net towards unbiased calibration to the binning schemes by avoid binning step as in (Zhang et al., 2020).

Our contributions can be summarized as follows:

- We propose γ-Net , a meta-network designed to learn sample-wise γ values for Focal loss as continuous variables, rather than relying on a single pre-defined γ value. To the best of our knowledge, our proposed method learns the most fine-grained gamma values for Focal loss.
- We propose a kernel-based ECE estimator SECE , which is a variation of the kernel density estimate (KDE) approximation (Zhang et al., 2020). This estimator smoothly regularizes γ-Net towards improved and unbiased calibration.
- Through extensive experiments and analysis, we empirically demonstrate that γ-Net effectively calibrates models, while SECE provides stable and smooth calibration. The combination of both achieves competitive predictive performance and superior scores across multiple calibration metrics compared to the baselines.

2 Related Work

Calibration of ML models using Platt scaling (Platt et al., 1999) and Isotonic Regression (Zadrozny & Elkan, 2002) has shown significant improvements for SVMs and decision trees. With the advent of neural networks, Niculescu-Mizil & Caruana (2005a) showed that those methods can produce well-calibrated probabilities even without any dedicated modifications.

Recently, Guo et al. (2017) and Mukhoti et al. (2020) have shown that modern NNs are noticeably more accurate but poorly calibrated due to negative log likelihood (NLL) overfitting. Minderer et al. (2021) revisited this problem and found that architectures with large sizes have a larger effect on calibration, but nevertheless, more accurate models tend to produce less calibrated predictions.

One of the ways to tackle calibration is to rely on post-hoc corrections using non-parametric approaches such as histogram binning (Zadrozny & Elkan, 2001), isotonic regression (Zadrozny & Elkan, 2002) and parametric methods such as Bayesian binning into quantiles (BBQ) and Platt scaling (Platt et al., 1999). Beyond those four, temperature scaling (TS) is a single-parameter extension of Platt scaling (Platt et al., 1999) and the most recent addition to the offering of post-hoc methods. Recent work has showed that a single parameter TS leads to good calibration performance with minimal added computational complexity (Guo et al., 2017; Minderer et al., 2021). There have been multiple extensions to temperature scaling in recent years. Kull et al. (2019) proposed Dirichlet calibration which assumes probability distributions are parameterized Dirichlet distributions, and an attention-based mechanism was proposed to tackle noise in validation data (Mozafari et al., 2018), Laves et al. (2019) extended TS to dropout variational inference to calibrate model uncertainty by inserting temperature value in Monte Carlo integration.

Besides post-hoc methods, there are also methods that do not explicitly include the calibration objective but rather implicitly guide the training towards better calibration performance. There are basically two lines of work: (1) data augmentation-based methods and (2) regularization-based methods. For the former line, the representative methods include label smoothing (LS) (Müller et al., 2019) mitigates miscalibration by softening hard labels with an introduced smoothing modifier in the standard loss function (e.g., cross-entropy), while Mix-up training (Thulasidasan et al., 2019) extends *mixup* (Zhang et al., 2018) to generate synthetic samples during model training by combining two random elements from the dataset.

In the line of regularization-based methods. Focal loss (Lin et al., 2017) acts as a maximum entropy regularizer. One of its extensions, FLSD (Mukhoti et al., 2020) computes the gamma value for focal loss based on heuristics (Lambert-W function (Corless et al., 1996)), dual Focal (Tao et al., 2023) takes into account the logit corresponding to the ground truth label and the largest logit ranked after it. AdaFocal (Ghosh et al., 2022) utilizes the calibration properties of focal (and inverse-focal) loss and adaptively modifies gamma for different groups of samples based on previous gamma value the knowledge of model's under/over-confidence on the validation set. Most recently, Krishnan & Tickoo (2020) introduced a differentiable accuracy versus uncertainty calibration (AvUC) loss function that allows a model to learn to provide well-calibrated uncertainties. (Liu et al., 2022) analyzed some current calibration methods such as label smoothing (Müller et al., 2019), focal loss (Lin et al., 2017), and explicit confidence penalty (Pereyra et al., 2017) from a constrained-optimization perspective and pointed out those can be seen as approximations of a liner penalty. The authors proposed to add a margin into learning objective. (Cheng & Vasconcelos, 2022) proposed calibration by pairwise constraints (CPC), which aims to strengthen the calibration supervision by casting multi-class searino into pairwise binary calibration. Thus authors proposed binary discrimination constraints (BDC) loss and binary exclusion constraint (BEC) loss as addition to standard cross-entropy loss to increase the supervision rate for calibration of the training process.

Within regularization-based methods, some approaches develop differentiable calibration proxies as regularizer. For instance, Kumar et al. (2018) developed a differentiable equivalent of ECE, the Maximum Mean Calibration Error (MMCE), which can be optimized directly to train calibrated models. Similarly (Karandikar et al., 2021) proposed a softened version of ECE (SB-ECE) by employing a softmax-based bin-membership function with temperature, enabling the soft ECE to serve as either a primary or a auxiliary loss objective. Another interesting exploration is presented in Bohdal et al. (2021; 2023), where instead of utilizing a developed differentiable ECE(DECE) for optimizing the main network, the authors proposed a meta-learning approach (Luketina et al., 2015) to train a model that minimizes DECE, thereby finding the optimal parameters of the L2 regularizers.

Compared to the aforementioned regularization methods, to the best of our knowledge, our proposed method learns the most fine-grained gamma values for focal loss via a meta network. This network is optimized toward stable and unbiased calibration, mitigating the biases caused by the binning mechanism.

3 Preliminaries

3.1 Model Calibration

Calibration (Guo et al., 2017) measures and verifies how the predicted probability estimates the true likelihood of correctness. Assume a model $\mathcal{M}$ trained with dataset $\{\mathbf{x}, y\}, \mathbf{x} \in \mathcal{X}, y \in \mathcal{Y}$. $\mathbf{p} = \{p_1, p_2, ..., p_K\}$ is the predicted softmax probability of K classes. If $\mathcal{M}$ makes 100 independent predictions, each with confidence $p = \arg\max(\mathbf{p}) = 0.9$, a calibrated $\mathcal{M}$ is correct 90 times. Formally, $\text{accuracy}(\mathcal{M}(D)) = \text{confidence}(\mathcal{M}(D))$ if $\mathcal{M}$ is perfectly calibrated on dataset D.

Expected Calibration Error (ECE) (Naeini et al., 2015). ECE computes the difference between model accuracy and confidence. It quantifies the discrepancy between predicted probabilities and observed frequencies by partitioning data points into bins with similar confidence. It takes the form

$$\text{ECE} = \sum_{n=1}^{N} \frac{|b_n|}{N} |\textsc{acc}(b_n) - \textsc{conf}(b_n)|, \tag{1}$$

where N is the total number of samples and b_n represents a single bin, and

$$\textsc{acc}(b_m) = \frac{1}{|b_m|} \sum_{i \in B_m} \mathbf{1}(\hat{y}_i = y_i), \ \textsc{conf}(b_m) = \frac{1}{|b_m|} \sum_{i \in B_m} p_i. \tag{2}$$

Maximum Calibration Error (MCE) (Naeini et al., 2015) is particularly important in high-risk applications where reliable confidence measures are absolutely necessary. It measures the worst-case deviation between accuracy and confidence,

$$\text{MCE} = max_{n \in \{1,...,N\}} |\textsc{acc}(b_n) - \textsc{conf}(b_n)|. \tag{3}$$

For a perfectly calibrated model, the ideal ECE and MCE equal to 0.

Besides ECE and MCE, we also report *Classwise ECE* (Nixon et al., 2019), *Adaptive ECE* (Nixon et al., 2019) and *Reliability Diagrams* (DeGroot & Fienberg, 1983; Niculescu-Mizil & Caruana, 2005a), we describe these metrics in Appendix A.1.

3.2 Focal Loss

For a classification task, the focal loss (FL) (Lin et al., 2017) can be defined as $\mathcal{L}_\gamma^f = -(1 - p_{i,y_i})^\gamma \log p_{i,y_i}$ where γ is a hyper-parameter. It was originally proposed to handle imbalanced data distribution but Jishnu et al. (Mukhoti et al., 2020) found the models trained with focal loss are better calibrated w.r.t. cross-entropy trained counterparts. This is because focal loss can be interpreted as a trade-off between minimizing Kullback–Leibler (KL) divergence and maximizing the entropy of predictions, depending on γ (Mukhoti et al., 2020)[1]:

$$\mathcal{L}_f \geq \text{KL}(q \parallel p) + \mathbb{H}(q) - \gamma \mathbb{H}(p) \tag{4}$$

where p is the prediction distribution, q is the one-hot encoded target class, and $\mathbb{H}(q)$ is constant. Models trained with this loss learn to strike a balance between narrow p (high confidence of predictions) due to the KL term but and broad p (avoiding overconfidence) due to the entropy regularization term. Original authors provided a principled approach to select the γ for focal loss based on the Lambert-W function (Corless et al., 1996). Motivated by this, our work proposes to learn a more fine-grained sample-wise γ with a meta network.

3.3 Meta-Learning

Model calibration can be formulated as minimizing a multi-component loss objective where the base term is used to optimise predictive performance while a regularizer maintains model calibration (Bohdal et al., 2021; Lin et al., 2017). Tuning the hyper-parameters of the regularizer can be an a difficult process when

[1] More theoretical findings can be found in the paper.

conventional methods are used (Li et al., 2016; Snoek et al., 2012; Falkner et al., 2018). In this work, we adopt the meta learning approach (Luketina et al., 2015). At each training iteration, the model takes a mini-batch from the training dataset D_{train} and the validation dataset D_{val} to optimize

$$\arg\min_{\theta,\phi} \; \mathcal{L}(\theta, \phi, D_{train}, D_{val}) = \mathcal{L}_{FL_\gamma}(\theta, D_{train}) + \mathcal{L}_{SECE}(\phi, D_{val}) \tag{5}$$

First, the base loss function $\mathcal{L}_{FL_\gamma}$ is used to optimize the parameter of the backbone model θ on D_{train}, note that the γ parameter for this step is predicted by γ-Net . Following that, the validation mini batch D_{val} is used to optimize the parameters of the meta-network (γ-Net) ϕ using a validation loss $\mathcal{L}_{SECE}$. The validation loss is a function of the backbone model outputs and does not depend on γ-Net directly. The dependence between validation loss and parameters of the meta-network is mediated via the parameters of the backbone model as discussed by (Luketina et al., 2015).

4 Methods

This section introduces the two components of our approach: the γ-Net learns to parameterise the focal loss and the SECE provides differentiability to γ-Net towards calibration optimization.

4.1 γ-Net: Learning Sample-Wise Gamma for Focal Loss

Sample-dependent γ value for focal loss showed it effectiveness of calibrating deep neural networks (Mukhoti et al., 2020). In this work, instead of computing and scheduling γ value based on Lambert-W function (Corless et al., 1996). We propose a learnable approach which learns more fine-grained and local γ values, i.e., each sample has an individual γ, at a continuous space. Formally, γ-Net takes the representations from the second last layer of a backbone network (i.e., ResNet (He et al., 2016). Let $\mathbf{x} \in \mathbb{R}^{b \times d}$ (b: batch size, d: hidden dimension) be the extracted representation, $\mathbf{A} \in \mathbb{R}^{d \times k}$ be a k-head self-attention matrix that followed by a liner layer with parameters $\mathbf{W} \in \mathbb{R}^{d \times 1}$. The γ-Net transforms the representation to sample-wise γ:

$$\mathbf{a} = \mathbf{x} \cdot \mathbf{A} \quad \in \mathbb{R}^{b \times k}, \qquad \mathbf{p} = \textsc{Softmax}(\mathbf{a}) \quad \in \mathbb{R}^{b \times k} \tag{6}$$

$$\tilde{\mathbf{x}} = \mathbf{p} \cdot \mathbf{A}^\top \quad \in \mathbb{R}^{b \times d}, \qquad \gamma = |\tilde{\mathbf{x}} \cdot \mathbf{W}| \, / \tau \quad \in \mathbb{R}^{b \times 1} \tag{7}$$

Here we use $|\cdot|$ to ensure the γ is positive valued and tune the temperature $\tau = 0.01$ as a hyper-parameter. This is similar to the temperature setups as in meta-calibration (Bohdal et al., 2021; 2023). Those operations result in a set of sample-wise γ to be used in focal loss $\mathcal{L}_r^f$. Note that, $f_\gamma(\gamma_i|x_i), x_i \in D$ is learned as a continuous variable rather than discrete value as in original FL formulation (Lin et al., 2017) and scheduled FL (FLSD) (Mukhoti et al., 2020).

Practical Considerations To ensure $\gamma \geq 0$, we could apply operations based on min-max scaling or activation functions such as sigmoid, relu and softplus. However, our experimental evidences shows that the formulation presented in Equation 7 performs better across datasets.

4.2 SECE : Smooth Expected Calibration Error

Conventional calibration measurement via ECE, as discussed in Section 3.1, is computed over discrete bins by finding the accuracy and the confidence of examples in each interval. However, this approach is highly dependent on different settings of bin-edges and the number of bins, making it a biased estimator of the true value (Minderer et al., 2021).

The issue of bin-based ECE can be traced back to the discrete decision of binning samples (Minderer et al., 2021). The larger the number of bins, the less information is retained. Small bins lead to inaccurate measurements of accuracy. For instance, in single-example bins, confidence is well-defined, but accurately assessing the accuracy within that interval of model confidences is more difficult from a single point. Using the binary accuracy of a single example leads us to the brier score (Brier et al., 1950) which has been shown to not be a perfect measure of calibration.

To find a good representation of accuracy within the single-example bin (representing a small confidence interval), we leverage the accuracy of other points in the vicinity of the chosen single example, weighted by their distance in the confidence space. Formally, the soft estimation of a single-example bin accuracy is:

$$\text{SACC }(b_i) = \sum_{j}^{M} \pi(x_i) K(z_i, z_j) \tag{8}$$

$$K\left(x_i, x_j'\right) = \exp\left(-\frac{\left\|x_i - x_j'\right\|^2}{2h^2}\right) \tag{9}$$

where b_i is the bin housing example x_i and $K(\cdot,\cdot)$ is a chosen distance measure, for example a Gaussian kernel and h is bandwidth. Moreover, z_i and $\pi(x_i)$ respectively denote the confidence and accuracy of the ith example. As in meta-calibration (Bohdal et al., 2021), we use the all-pairs approach (Qin et al., 2010a) to ensure differentiability. Having good measures of soft accuracy and confidence for each single-example bin, we can write the updated ECE metric as soft-ECE in the form

$$\text{SECE } = \frac{1}{M} \sum_{i}^{M} |\text{SACC }(i) - \textsc{conf}(i)|, \tag{10}$$

where i represents a single example and M is the number of examples. The new formulation is (1) differentiable as long as the kernel we use is differentiable and (2) enables smooth control over how accuracy over a confidence bin is computed via tuning the kernel parameters. Regarding (2), choosing a dirac-delta function recovers the original brier score while choosing a broader kernel enables a smooth approximation of accuracy over all confidence values.

Connection to KDE-based ECE Estimator (Zhang et al., 2020) present a KDE-based ECE Estimator relying on kernel density estimation to approximate the desired metric. Canonically, ECE is computed as an integral over the confidence space as

$$\hat{\text{ECE}}^d = \int \|z - \hat{\pi}(z)\|_d^d \hat{p}(z) dz \tag{11}$$

where $z = \{z_1, z_2, ..., z_L\}$ denotes model confidence distribution over L classes, $\|\cdot\|_d^d$ denotes the dth power of the ℓ_d norm, and $\hat{p}(z)$ represents the marginal density function of model's confidence on a given dataset. The $\hat{p}(z)$ and $\hat{\pi}(z)$ are approximated using kernel density estimation. We argue that SECE is a special instance with $d = 1$ of $\hat{\text{ECE}}^d$ and estimate ECE with max probability $z_t, t = \arg\max\{z_1, z_2, ..., z_L\}$ for a single instance. And SECE is an upper bound of $\hat{\text{ECE}}^1$:

$$\hat{\text{ECE}} = \int |z - \hat{\pi}(z)| \, \hat{p}(z) dz \tag{12}$$

$$= \int |z_l - \hat{\pi}(z_l)| \, \hat{p}(z_l) dz_l \int |z_t - \hat{\pi}(z_t)| \, \hat{p}(z_t) dz_t \tag{13}$$

$$\leq \int |z_t - \hat{\pi}(z_t)| \, \hat{p}(z_t) dz_t = \text{SECE} \tag{14}$$

with $l = [1, L], l \neq t$ and density functions:

$$\hat{p}(z_t) = \frac{h^{-L}}{M} \sum_{i=1}^{M} K\left(z_t, z_i\right), \; \hat{\pi}_t(z_t) = \frac{\sum_{i=1}^{M} \pi(i) K\left(z_t, z_i\right)}{\sum_{i=1}^{M} K\left(z_t, z_i\right)} \tag{15}$$

where h is the kernel width and $\pi(i)$ represents the binary accuracy of point i. The $p(z_t)$ is a mixture of dirac deltas centered on confidence predicted for individual points in the dataset (used to approximate ECE). Replacing binary accuracy with accuracy computed using all-pairs approach (Qin et al., 2010a) results in SECE, which is differentiable and can be computed efficiently for smaller batches of data since the integral is replaced with a sum over all examples in a batch.

Discussion: There are also some other studies attempting to develop differentiable calibration errors, such as DECE (Bohdal et al., 2021) and SB-ECE (Karandikar et al., 2021). As pointed out in (Zhang et al., 2020), non-parametric density estimators are continuous, thus avoiding the binning step can potentially reduce binning biases. The aforementioned changes do not invalidate the analysis of $\hat{\text{ECE}}$ as an unbiased estimator of ECE (Theorem 4.1 in (Zhang et al., 2020)), as the all-pairs accuracy Qin et al. (2010b) is an unbiased estimator of accuracy and the details of the $p(z)$ distribution are not used in the derivation beyond setting the bounds. As a result, the analysis described in (Zhang et al., 2020) to demonstrate the unbiasedness of their KDE-based approximation to ECE can be reused to demonstrate the same property for SECE.

4.3 Optimising γ-Net with SECE

The newly introduced γ-Net and the SECE metric can be applied together to optimize selected ML models for both cross-entropy and calibration error using the meta learning scheme introduced in Section 3.3. As the probability calibration via maximising entropy is performed at a continuous space, we argue that SECE is an efficient learning objective to optimise γ-Net and provide calibration regularization to base network trained with focal loss.

Under the umbrella of meta-learning, two sets of parameters are learned simultaneously: θ, the parameters of base network f^c, as well as the ϕ, the parameters of γ-Net denoted as f^γ. The former, f^c, is used to classify each new example into appropriate classes and the latter, f^γ, is applied to find the optimal value of the focal loss parameter γ for each training example. Algorithm 1 in Appendix describes the learning procedures.

5 Experiments

We conducted a series of experiments to achieve the following objectives:

- Examine both the predictive and calibration performance of the proposed method. We used error (or accuracy) to measure the predictive performance and Negative Log-Likelihood (NLL), Expected Calibration Error (ECE), Maximum Calibration Error (MCE), Adaptive Calibration Error (ACE), and Classwise ECE for calibration performance.
- Observe the calibration behaviors of the proposed method during training.
- Empirically evaluate the learned γ values for Focal loss and the robustness of different methods to the binning mechanism.

Implementation Details. We implemented our methods by adapting and extending the code from (Bohdal et al., 2021) with Pytorch (Paszke et al., 2019). For all experiments we use their default settings (using ResNet18 as base model, batch size 128, data augmented with random crop and horizontal flip) unless stated otherwise. We run each experiments for 5 repetitions with different random seeds and average results. We conducted our experiments on CIFAR10 and CIFAR100 (in (Bohdal et al., 2021)) as well as Tiny-ImageNet (Ya Le, 2015); For meta-learning, we split the training set into 8:1:1 as training/val/meta-val with the original test sets are untouched. The experimental pipeline for all three datasets is identical. The models are trained with SGD (learning rate 0.1, momentum 0.9, weight decay 0.0005) for up to 350 epochs. The learning rate is decreased at 150 and 250 epochs by a factor of 10. The model selection is based on the best validation error.

The γ-Net is implemented with a multi-head attention layer with k heads and a fully-connected layer. The k is set to the number of categories. The hidden dim is set to 512, the temperature τ is fixed at 0.01. For SECE, we used the Gaussian kernel with bandwidth of 0.01 (selected with grid search) for both datasets. We initialize $\gamma = 1.0$. At inference stage, the meta network will not present except our ablation study on learned γ values in Section 5.2.

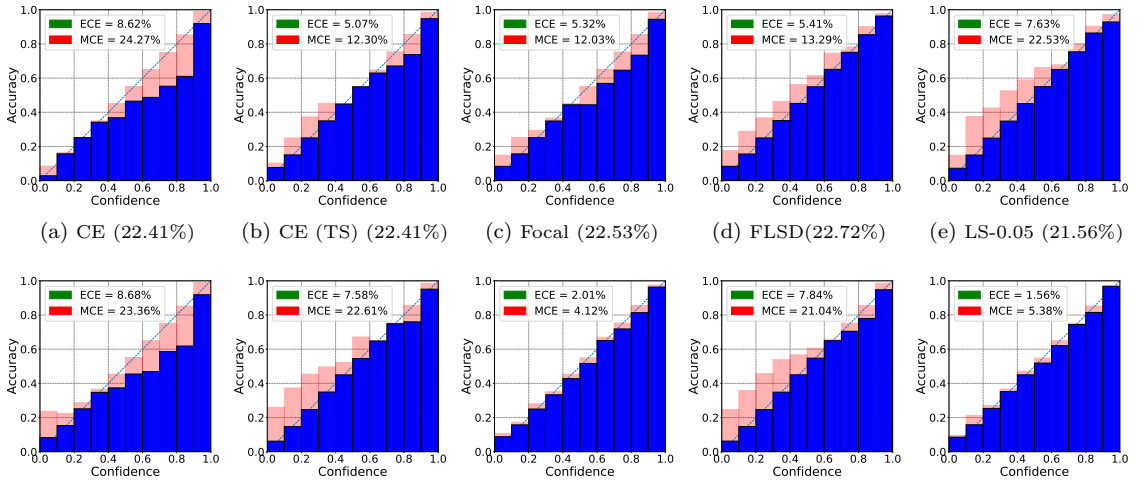
Baselines. We compare our method extensively with baselines including standard cross-entropy (CE), cross-entropy with post-hoc temperature scaling (TS) (Platt et al., 1999), Focal loss with standard gamma value (Focal), $\gamma = 1$ (Lin et al., 2017), Focal Loss with scheduled gamma (FLSD) (Mukhoti et al., 2020), MMCE (Maximum Mean Calibration Error) (Kumar et al., 2018) and Label Smoothing with smooth factor 0.05 (LS-0.05) or (LS-0.1) (Müller et al., 2019) and Mix-Up ($\alpha = 1.0$) (Thulasidasan et al., 2019). In meta-learning setting, we include CE-DECE (meta-calibration(Bohdal et al., 2021) for learning unit-wise weight regularization), which is also used as meta-learning baseline, CE-SECE, FL_γ-DECE, focal loss with learnable sample-wise γ and FL_γ-DECE.

Table 1: The predictive (test error) and calibration performance of different methods on CIFAR10 (Top), CIFAR100 (Middle) and Tiny-ImageNet (Bottom). The best scores are **bold**. The mean and standard deviation numbers are reported by averaging 5 runs with random seeds. As an alternative calibration method, our approach in general exhibits better calibration while retains competitive predictive performance as compared to conventional as well as meta-learning baselines.

Methods	Error	NLL	ECE	MCE	ACE	Classwise ECE
			CIFAR 10			
CE	4.812 ± 0.122	0.335 ± 0.01	4.056 ± 0.092	33.932 ± 5.433	4.022 ± 0.136	0.848 ± 0.023
CE (TS)	4.812 ± 0.122	0.211 ± 0.005	3.083 ± 0.140	26.695 ± 2.959	3.046 ± 0.157	0.656 ± 0.022
Focal	4.874 ± 0.100	0.207 ± 0.005	3.193 ± 0.104	28.034 ± 5.702	3.174 ± 0.098	0.690 ± 0.018
FLSD	4.916 ± 0.074	0.211 ± 0.005	6.904 ± 0.462	**19.246 ± 11.071**	6.805 ± 0.446	1.465 ± 0.088
LS (0.05)	4.744 ± 0.126	0.232 ± 0.003	2.900 ± 0.085	24.860 ± 8.599	3.985 ± 0.154	0.727 ± 0.009
LS(0.1)	4.918 ± 0.085	0.266 ± 0.004	7.566 ± 0.41	16.033 ± 3.783	7.611 ± 0.161	1.637 ± 0.056
Mixup(α=1.0)	**4.126 ± 0.068**	0.273 ± 0.033	12.863 ± 3.2	20.739 ± 4.205	12.833 ± 3.161	2.678 ± 0.615
MMCE	4.808 ± 0.082	0.333 ± 0.012	4.027 ± 0.082	41.647 ± 10.275	4.013 ± 0.091	0.845 ± 0.014
CE-DECE	5.194 ± 0.161	0.301 ± 0.038	4.106 ± 0.402	41.346 ± 13.325	4.088 ± 0.395	0.868 ± 0.074
CE-SECE	5.222 ± 0.168	0.289 ± 0.027	4.062 ± 0.241	50.81 ± 21.705	4.049 ± 0.251	0.852 ± 0.040
FL_γ-DECE	5.434 ± 0.095	**0.193 ± 0.009**	2.257 ± 0.787	56.633 ± 23.856	2.396 ± 0.669	**0.557 ± 0.165**
FL_γ-SECE	5.428 ± 0.144	**0.193 ± 0.010**	**2.138 ± 0.819**	22.725 ± 5.756	**2.357 ± 0.541**	**0.556 ± 0.165**
			CIFAR 100			
CE	22.570 ± 0.438	0.997 ± 0.014	8.380 ± 0.336	23.250 ± 2.436	8.347 ± 0.344	0.233 ± 0.006
CE (TS)	22.570 ± 0.438	0.959 ± 0.008	5.388 ± 0.393	13.454 ± 2.377	5.360 ± 0.315	0.208 ± 0.003
Focal	22.498 ± 0.214	0.900 ± 0.007	5.044 ± 0.203	12.454 ± 0.893	5.015 ± 0.207	0.203 ± 0.004
FLSD	22.656 ± 0.113	0.876 ± 0.005	5.956 ± 0.804	14.716 ± 1.387	5.958 ± 0.802	0.241 ± 0.008
LS (0.05)	21.810 ± 0.172	1.070 ± 0.011	8.108 ± 0.346	20.268 ± 1.536	8.106 ± 0.346	0.272 ± 0.006
LS(0.1)	22.244 ± 0.155	1.052 ± 0.011	4.754 ± 0.709	17.228 ± 0.923	4.777 ± 0.647	0.239 ± 0.004
Mixup(α=1.0)	**21.210 ± 0.227**	0.917 ± 0.017	9.716 ± 0.754	16.01 ± 1.335	9.722 ± 0.74	0.315 ± 0.011
MMCE	22.490 ± 0.143	1.021 ± 0.007	8.713 ± 0.245	23.565 ± 1.141	8.670 ± 0.305	0.238 ± 0.004
CE-DECE	23.406 ± 0.323	1.148 ± 0.006	7.309 ± 0.245	22.565 ± 1.446	7.253 ± 0.315	0.241 ± 0.002
CE-SECE	23.448 ± 0.302	1.153 ± 0.015	7.668 ± 0.330	24.261 ± 1.614	7.609 ± 0.295	0.244 ± 0.002
FL_γ-DECE	23.712 ± 0.204	0.888 ± 0.009	**1.879 ± 0.440**	8.271 ± 2.651	**1.838 ± 0.371**	0.195 ± 0.005
FL_γ-SECE	23.686 ± 0.377	**0.877 ± 0.004**	1.940 ± 0.365	**7.480 ± 1.867**	**1.939 ± 0.379**	**0.192 ± 0.006**
			Tiny-ImageNet			
CE	40.110 ± 0.110	1.838 ± 0.171	8.059 ± 1.296	15.73 ± 1.905	8.006 ± 1.282	0.154 ± 0.001
Focal	39.415 ± 0.625	1.896 ± 0.009	7.600 ± 0.309	13.771 ± 0.897	7.469 ± 0.301	0.152 ± 0.002
FLSD	39.705 ± 0.075	1.904 ± 0.025	14.501 ± 1.078	21.528 ± 2.116	14.501 ± 1.078	0.202 ± 0.006
LS (0.1)	**39.395** ± 0.305	2.185 ± 0.001	16.777 ± 0.476	29.088 ± 1.835	16.901 ± 0.460	0.199 ± 0.001
Mixup(α=1.0)	39.890 ± 0.271	1.932 ± 0.054	12.133 ± 2.069	31.440 ± 0.968	12.028 ± 2.079	0.193 ± 0.009
MMCE	40.310 ± 0.100	1.826 ± 0.177	8.206 ± 1.219	16.802 ± 2.339	8.165 ± 1.269	**0.149** ± 0.001
CE-DECE	41.350 ± 0.000	2.228 ± 0.033	10.694 ± 0.503	20.888 ± 0.430	10.553 ± 0.553	0.160 ± 0.000
CE-SECE	41.005 ± 0.145	2.213 ± 0.058	10.928 ± 1.125	21.362 ± 2.526	10.912 ± 1.069	0.157 ± 0.003
FL_γ-DECE	40.625 ± 0.095	**1.826** ± 0.007	5.944 ± 1.090	11.542 ± 1.990	6.077 ± 1.095	0.155 ± 0.007
FL_γ-SECE	40.850 ± 0.140	1.829 ± 0.005	**5.794** ± 0.756	**11.477** ± 1.563	**5.848** ± 0.751	0.156 ± 0.005

5.1 Predictive and Calibration Performance

Table 1 presents the performance comparison across approaches. Temperature Scaling (TS) can effectively reduce the errors on calibration metrics as compared to uncalibrated CE models (baseline). Label smoothing and Mixup achieve the best test errors on datasets but exhibit higher ECE and MCE scores. Focal and FLSD can improve calibration in general but we also observed high MCE score for FLSD. On the other hand, we also found that MMCE exhibits higher calibration errors as compared to baseline, this basically aligns with the findings from (Bohdal et al., 2021).



(a) CE (22.41%) (b) CE (TS) (22.41%) (c) Focal (22.53%) (d) FLSD(22.72%) (e) LS-0.05 (21.56%)

(f) MMCE (22.30%) (g) CE-DECE(23.05%) (h) FL$_\gamma$-DECE(24.04%) (i) CE-SECE(23.58%) (j) FL$_\gamma$-SECE(23.78%)

Figure 2: The reliability diagram plots for models on CIFAR100 test set. The $(\cdot)$ presents test error. The diagonal dash line presents perfect calibration. The red bar presents the gap between the observed accuracy and the desired accuracy of the perfectly calibrated model (diagonal) - it is positive if the observed accuracy is lower and negative otherwise. The model from the 5th run is used (same to Figure 4).

Figure 2 illustrates the reliability diagram plots of models on CIFAR100. The diagrams show that for CIFAR100, γ-Net based methods achieve better ECE compared to SECE and meta-loss for optimizing γ-Net ensures smooth and stable calibrations, and potentially reduces the calibration biases on bins. Similarly on CIFAR100, FL$_\gamma$-SECE shows improved ECE and MCE from CE-DECE.

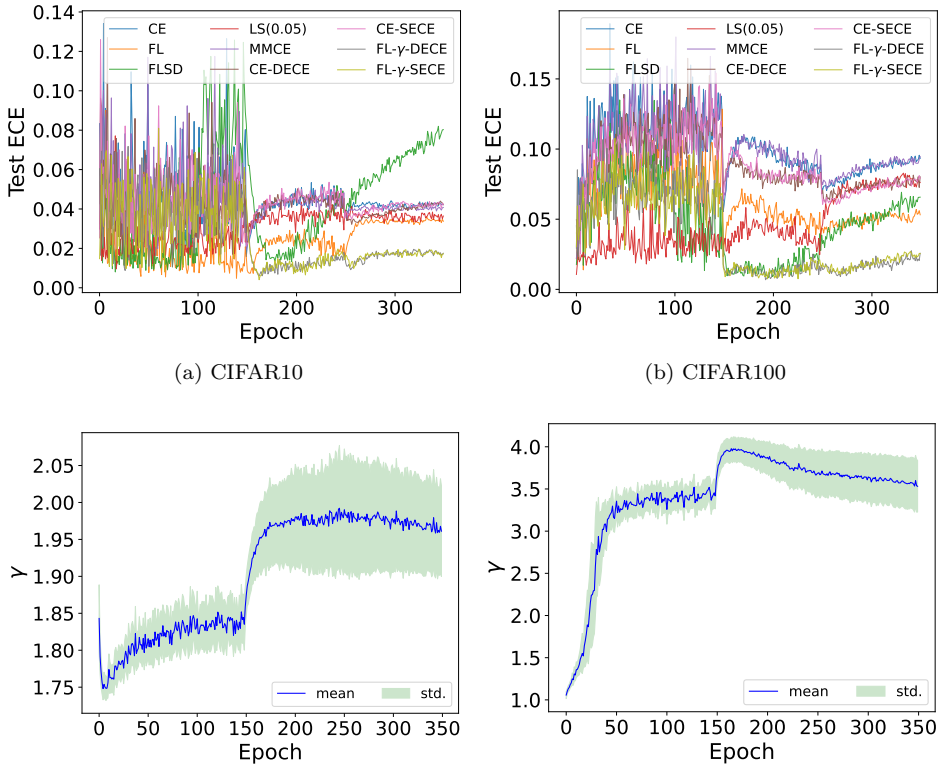
Among compared methods, our method FL$_\gamma$-SECE achieves considerably lower errors on calibration metrics. When comparing meta-learning based approaches: CE-DECE (meta-learning baseline), CE-SECE, FL$_\gamma$-DECE, FL$_\gamma$-SECE. We can see that our method (FL$_\gamma$-SECE) achieves comparable test error and better scores across calibration metrics. Particularly, it improves ECE by average 4.198% on three detests, in addition, by average 14.37% MCE and 3.917% ACE score respectively.

To observe the learning behavior of models, we plotted the changing the curves test ECE in Figure 3 (a-b) and test error (included in Appendix Section A.3.1). It is noteworthy that while the test error curves exhibit similar behaviors, the calibration behaviors vary significantly across methods. The primary advantage of γ-Net with SECE lies in its stable and smooth calibration behavior. After the 150th epoch, when the learning rate is decreased by a factor of 10, we observe an increase in ECE scores for all approaches, particularly for FLSD (green lines). This indicates that, during model training, the learning procedure aims to align the probability distribution as closely as possible with the ground-truth distribution (one-hot representation), causing models to become overconfident. It also demonstrates that our approach is more robust to this phenomenon.

5.2 Ablation Study

5.2.1 Learning γ as continous variables

Figure 3(c-d) presents the change of γ values on test dataset over epochs. At the earlier training stage, the samples γ_j for $x_j \in D_{test}$ have similar values (with low variance) because they are initialized with $\gamma_i = 1.0$ for $x_i \in D_{val}$. The γ parameter is observed to have higher standard deviation at the later training stage as γ-Net learns optimal value for each example in the dataset rather than relying on global values showcasing the flexibility of the network. It is also noted that γ is learned in a continuous space, different to the discrete values the pre-defined in Focal Loss (Lin et al., 2017) and FLSD (Mukhoti et al., 2020).



(a) CIFAR10 (b) CIFAR100

(c) CIFAR10 (d) CIFAR100

Figure 3: (a-b): ECE curves on the test dataset of CIFAR10 (a) and CIFAR100 (b).(c-d): The mean and standard deviation (std.) of γ on test dataset at each epoch. Low std. score indicates samples share similar gamma values, and high std. score indicates more samples have different γ values.

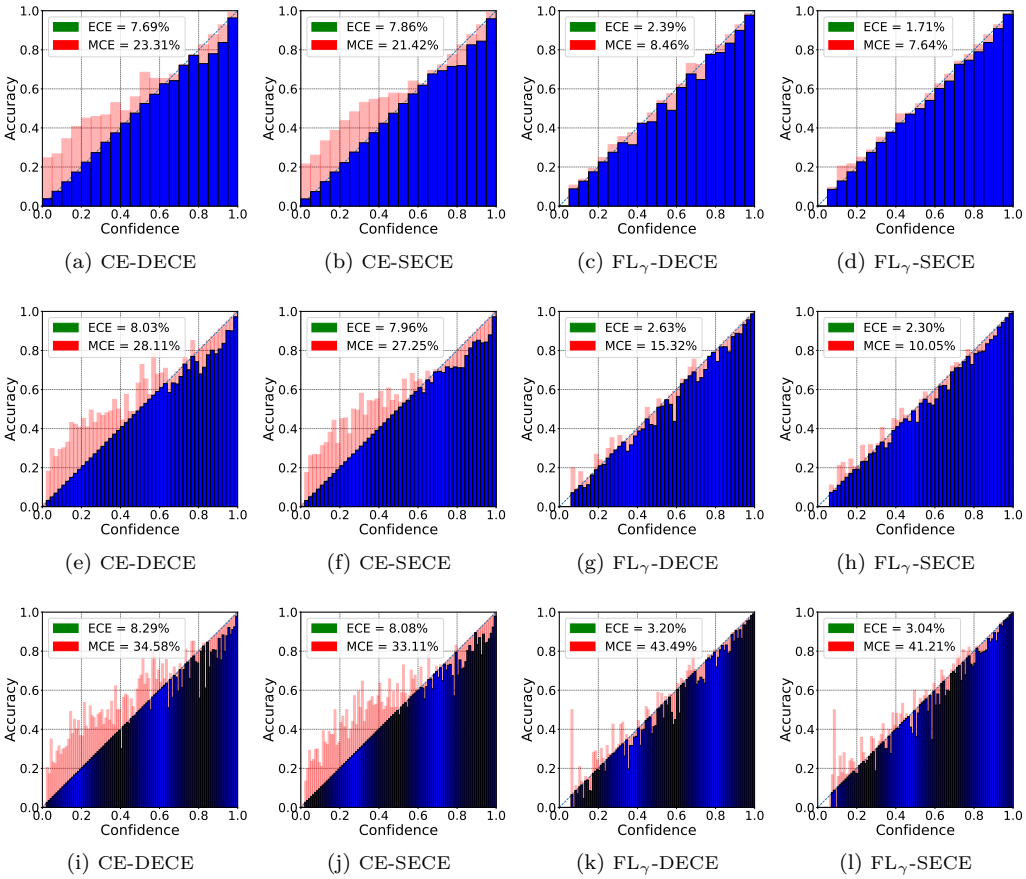
Methods	Error	NLL	ECE	MCE	ACE	Classwise ECE
FL_γ	5.632 ± 0.118	0.197 ± 0.009	2.177 ± 0.619	46.172 ± 28.24	**2.319 ± 0.407**	**0.553 ± 0.12**
FL_γ-SECE	**5.428 ± 0.144**	**0.193 ± 0.010**	**2.138 ± 0.819**	**22.725 ± 5.756**	2.357 ± 0.541	0.556 ± 0.165
FL_γ	28.148 ± 8.127	1.051 ± 0.278	3.044 ± 1.542	10.082 ± 3.441	3.016 ± 1.511	0.226 ± 0.063
FL_γ-SECE	**23.686 ± 0.377**	**0.877 ± 0.004**	**1.940 ± 0.365**	**7.480 ± 1.867**	**1.939 ± 0.379**	**0.192 ± 0.006**

Table 2: SECE calibration gain on CIFAR10 (top) and CIFAR100 (bottom).

5.2.2 Calibration bias and robustness

In Figure 5, we examine the robustness of those methods with different binning schemes by varying the number of bins, which is one of causes of introducing calibration bias (Minderer et al., 2021). It shows that γ-Net based approaches (FL_γ-DECE and FL_γ-SECE) maintain much lower ECE score when throughout all bin numbers from 10 to 1000 showing the trained based network is robustly calibrated. Furthermore FL_γ-SECE is also able to maintain lower MCE as compared to other methods.

Here we can clearly see the the role of SECE in stabilizing the calibration with γ-Net against the change of bin numbers. Table 2 shows the individual calibration gain from SECE as compared to using learnable γ only. Our method FL_γ-SECE. With SECE, we can see the improved both predictive and calibration performance. Importantly, from Figure 4 and 5, we observe that it reduces calibration bias that is introduced by different binning mechanisms. This is mostly reflected on reduced ECE/MCE scores, i.e., the model exhibits high MCE on a particular bin if calibration bias exists.



(a) CE-DECE (b) CE-SECE (c) FL$_\gamma$-DECE (d) FL$_\gamma$-SECE

(e) CE-DECE (f) CE-SECE (g) FL$_\gamma$-DECE (h) FL$_\gamma$-SECE

(i) CE-DECE (j) CE-SECE (k) FL$_\gamma$-DECE (l) FL$_\gamma$-SECE

Figure 4: The reliability diagram plots on CIFAR100 with large bin numbers (top to bottom: 20, 50, 100).

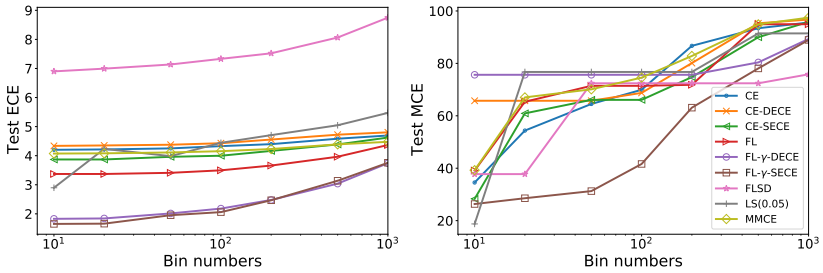


Figure 5: The changes in ECE (left) and MCE (right) scores on the CIFAR-10 test dataset with increasing bin numbers in the range of [10, 20, 50, 100, 200, 500, 1000] are illustrated. FL$_\gamma$-SECE demonstrates superior robustness to increasing bin numbers, as evidenced by lower MCE. A similar plot for CIFAR-100 is provided in the Figure 8 of Appendix.

6 Discussion

Novelties. Though we follow the general setup in (Bohdal et al., 2021), our work makes several novel contributions: (1) We introduce learnable sample-wise continuous variables for focal loss. To the best of our knowledge, this is the first work to introduce fine-grained γ for focal loss for the purpose of model calibration learned from a meta-network. (2) We propose SECE, which reduces model calibration bias against different binning mechanisms. This aspect is rarely discussed in the literature. Additionally, SECE is also more efficient than DECE in (Bohdal et al., 2021) as it uses simple summation rather than pre-

dicting the bin assignment with networks. (3) We further showcase the importance and feasibility of using gradient-based meta-learning (Finn et al., 2017) in alleviating model miscalibration. As shown in Table 3, meta-regularization is able to achieve very competitive predictive and calibration performance compared to conventional regularization methods.

Methods	ECE(%)	Test Error(%)
CIFAR10		
(Patra et al., 2023)	0.59	6.28
(Hebbalaguppe et al., 2022)	0.93	7.18
(Hebbalaguppe et al., 2022)	0.70	7.08
(Liu et al., 2022) (without marign)	3.72	5.24
(Liu et al., 2022)	1.16	4.75
(Karandikar et al., 2021) (Focal+SB-ECE)	1.19	4.90
(Karandikar et al., 2021) (Focal+SB-AvUC)	1.58	5.60
(Tao et al., 2023) (Dual Focal with ResNet50)	0.46	5.17
(Tao et al., 2023) (Dual Focal with ResNet110)	0.98	5.02
(Ghosh et al., 2022) (AdaFocal with ResNet50)	0.66	5.30
(Ghosh et al., 2022) (AdaFocal with ResNet50)	0.71	5.27
Meta-Regularization (Ours)	2.14	5.43
CIFAR100		
(Patra et al., 2023)	1.74	26.57
(Hebbalaguppe et al., 2022)	1.49	31.58
(Hebbalaguppe et al., 2022)	0.72	29.80
(Karandikar et al., 2021)(Focal+SB-ECE)	2.30	21.40
(Karandikar et al., 2021) (Focal+SB-AvUC)	1.57	21.90
(Tao et al., 2023) (Dual Focal with ResNet50)	1.08	22.67
(Tao et al., 2023) (Dual Focal with ResNet110)	2.90	22.59
(Ghosh et al., 2022) (AdaFocal with ResNet50)	1.36	22.60
(Ghosh et al., 2022) (AdaFocal with ResNet50)	1.40	22.79
Meta-Regularization (Ours)	1.94	23.69

Table 3: Comparing meta-regularization (our) to recent (non-meta) regularization methods on CIFAR10 and CIFAR100. The meta-regularization gives very competitive predictive and calibration performance to conventional regularization methods (the numbers are obatined from the corresponding papers).

Limitation. Our proposed method utilizes γ-Net for learning γ, which increases the number of parameters by approximately 0.46% during training. However, since γ-Net is not retained after training, there is no additional computational complexity during inference.

7 Conclusion

In this work, we have introduced a meta-learning based approach for acquiring well-calibrated models and demonstrated the advantages of two newly introduced components. By learning a sample-wise γ for Focal loss using γ-Net , we achieve both strong predictive performance and unbiased, robust calibration. The optimization of γ-Net with SECE proves crucial in ensuring stable calibration compared to baselines. Through extensive empirical results on three computer vision datasets, we have illustrated that our method enhances calibration capability without altering the original networks

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A Appendix

A.1 Evaluation Metrics

Besides ECE and MCE, we evaluate models on Classwise ECE and Adaptive ECE, we also inspect model's over- or under-confidence with reliability diagrams.

Reliability Diagrams (DeGroot & Fienberg, 1983; Niculescu-Mizil & Caruana, 2005a) visualise whether a model is over- or under-confident by grouping predictions into bins according to their prediction probability. The predictions are grouped into N interval bins (each of of size $1/N$) and the accuracy of samples y_i wrt. to the ground truth label $\hat{y}_i$ in each bin b_n is computed as: $\text{ACC}(b_n) = \frac{1}{|b_n|}\sum_i^I \mathbf{1}(\hat{y}_i = y_i)$, where i indexes all examples that fall into bin b_n. Let $\hat{p}_i$ be the probability for the predicted class y_i for i-th sample (i.e. the class with highest predicted probability for i-th sample), then average confidence is defined as: $\text{CONF}(b_n) = \frac{1}{|b_n|}\sum_i^I \hat{p}_i$. A model is perfectly calibrated if $\text{ACC}(b_n) = \text{CONF}(b_n), \forall n$ and in a diagram the bins would follow the identity function. Any deviation from this represents miscalibration.

Classwise ECE (Nixon et al., 2019). Classwise ECE extends the bin-based ECE to measure calibration across all the possible classes. In practice, predictions are binned separately for each class and the calibration error is computed at the level of individual class-bins and then averaged. The metric can be formulated as

$$\text{CECE} = \sum_{n=1}^{N}\sum_{c=1}^{K}\frac{|b_{n,c}|}{NK}|\text{ACC}_c(b_{n,c}) - \text{CONF}_c(b_{n,c})| \tag{16}$$

where N is the total number of samples, K is the number of classes and $b_{n,c}$ represents a single bin for class c. In this formulation, $\text{ACC}_c(b_{n,c})$ represents average binary accuracy for class c over bin $b_{n,c}$ and $\text{CONF}_c(b_{n,c})$ represents average confidence for class c over bin $b_{n,c}$

Adaptive ECE (Nixon et al., 2019). Adaptive ECE further extends the classwise variant of expected calibration error by introducing a new binning strategy which focuses the measurement on the confidence regions with multiple predictions and. Concretely Adaptive ECE (ACE) spaces the bin intervals such that each contains an equal number of predictions. The metric can be formulated as

$$\text{ACE} = \sum_{n=1}^{N}\sum_{c=1}^{K}\frac{1}{NK}|\text{ACC}_c(b_{n,c}) - \text{CONF}_c(b_{n,c})| \tag{17}$$

where the notation follows one from classwise ECE. The importance weighting for each bin is removed since each bin holds the same number of examples.

A.2 Algorithm

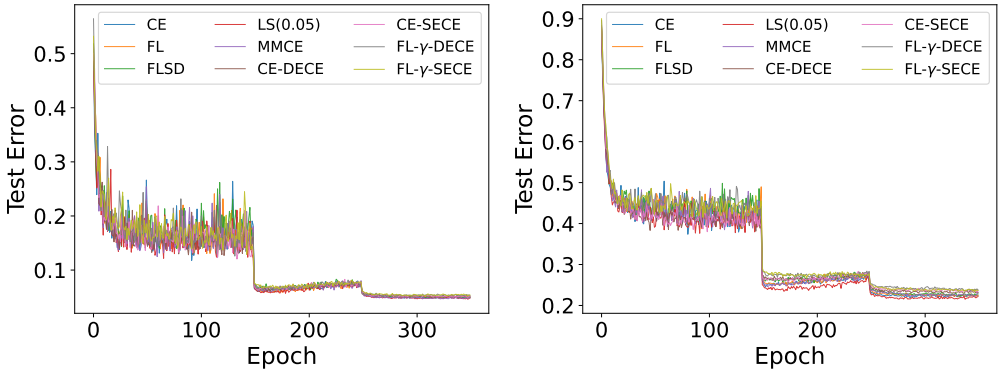
Algorithm 1 describes the learning procedures, it relies on the training and validation sets D_{train}, D_{val}, two networks f^c and f^γ with parameters θ and ϕ. The optimization proceeds in an iterative process until both sets are converged. Each iteration starts by sampling a mini-batch of training data $(\mathbf{x}_i^t, \mathbf{y}_i^t) \sim D_{train}$ as well as a mini-batch of validation data $(\mathbf{x}_i^v, \mathbf{y}_i^v) \sim D_{val}$. The training-mini batch is used to find the optimal value of γ as $\gamma = f^\gamma(\mathbf{x}_i^t)$ and following that, compute the focal loss on the output of the backbone network f^c. The gradient of the loss $\mathcal{L}_\gamma^f(f^c(\mathbf{x}_i^t), \mathbf{y}_i^t)$ is then used to update the parameters of the backbone network θ using the Adam algorithm (Kingma & Ba, 2014).

Once the backbone model f^c is updated, it is used to compute the value of the auxiliary loss SECE on the validation mini-batch SECE $(f^c(\mathbf{x}_i^v), \mathbf{y}_i^v)$. The auxiliary SECE loss is a differentiable proxy of the true expected calibration error and can be minimized w.r.t. ϕ to find the optimal parameters of γ-Net . It is important to note that SECE is computed based on the outputs of $f^c(\mathbf{x}_i^v)$ and the only dependence on γ is an indirect one based on the updates of θ as discussed in Section 2.3.

Algorithm 1: Meta optimization with γ-Net and SECE

Input: f^c and f^γ with initialized θ and ϕ
Output: Optimized θ and ϕ
Data: Training and validation sets: D_{train}, D_{val}

while θ *not converged* **do**
  $(\mathbf{x}_i^t, \mathbf{y}_i^t) \sim D_{train}$; $(\mathbf{x}_i^v, \mathbf{y}_i^v) \sim D_{val}$; # Sample a mini-batch from both datasets
  $\gamma_i = f^\gamma(\mathbf{x}_i^t)$; # learning sample-wise γ_i;
  $\mathcal{L}_\gamma^f = \mathcal{L}_\gamma^f(f^c(\mathbf{x}_i^t), \mathbf{y}_i^t)$: # Compute training loss based on γ
  $\theta := \theta - \eta \nabla_\theta \mathcal{L}_\gamma^f$: # Update parameters of f^c using training loss gradient
  $SECE = SECE\ (f^c(\mathbf{x}_i^v), \mathbf{y}_i^v)$: # Compute SECE auxiliary loss using validation batch
  $\phi := \phi - \eta_\phi \nabla_\phi SECE$: # Update parameters of f^γ using SECE gradient



(a) CIFAR10 (Error) (b) CIFAR100 (Error)

Figure 6: Test error on both test datasets.

A.3 Additional Experiments

A.3.1 Test Error Curves

Figure 6 presents the test error on CIFAR10 and CIFAR100 for compared methods. In general, they exhibit similar behaviour.

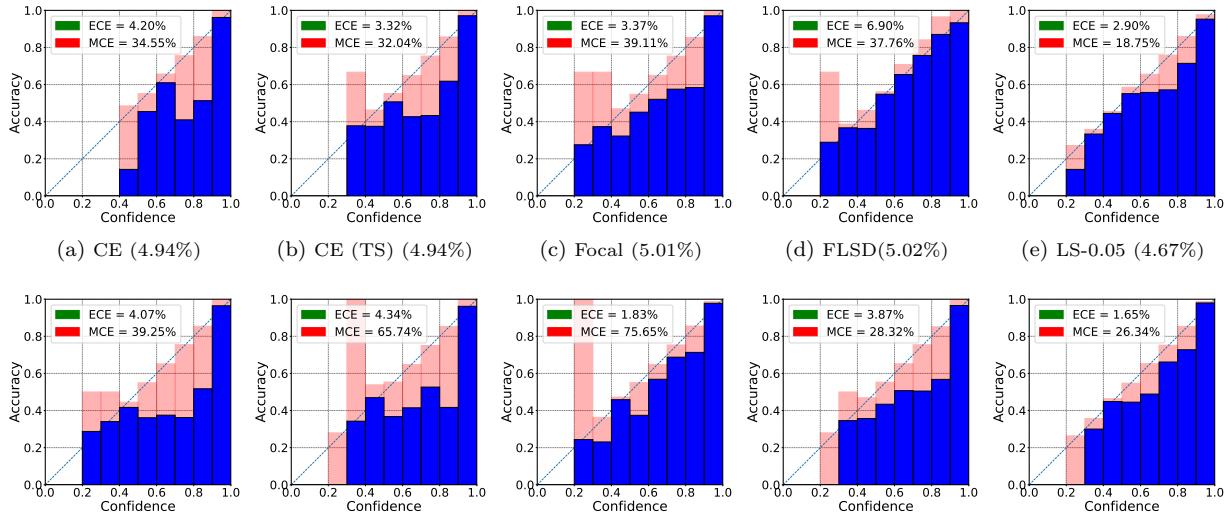
A.3.2 Reliability Diagram Plots

Figure 8 examines the robustness of those methods with different binning schemes by varying the number of bins. It shows that γ-Net based approaches (FL$_\gamma$-DECE and FL$_\gamma$-SECE) maintain much lower ECE score when throughout all bin numbers from 10 to 1000 showing the trained based network is robustly calibrated.

In Figure 9 we provide the comparison across meta-learning based approach via reliability plots with large bin numbers and corresponding ECE and MCE. FL$_\gamma$-SECE is able to maintain lowest ECE and MCE, it shows the robustness to the increased bin numbers.

A.3.3 Experiments with DenseNet

We conducted experiments on DenseNet with meta-learning baselines. Table 4 presents the effectiveness of gamma-net based methods, which exhibit better calibration across multiple metrics with comparable predictive performance.



(a) CE (4.94%) (b) CE (TS) (4.94%) (c) Focal (5.01%) (d) FLSD(5.02%) (e) LS-0.05 (4.67%)

(f) MMCE (4.83%) (g) CE-DECE(5.19%) (h) FL$_\gamma$-DECE(5.36%) (i) CE-SECE (5.06%) (j) FL$_\gamma$-SECE(5.38%)

Figure 7: The reliability diagram plots for models on CIFAR10 test set. The $(\cdot)$ presents test error. The diagonal dash line presents perfect calibration. The red bar presents the gap between the observed accuracy and the desired accuracy of the perfectly calibrated model (diagonal) - it is positive if the observed accuracy is lower and negative otherwise. The model from the 5th run is used.

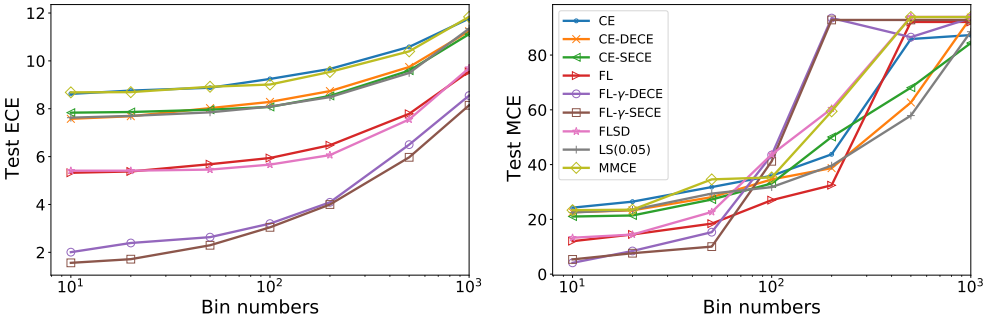


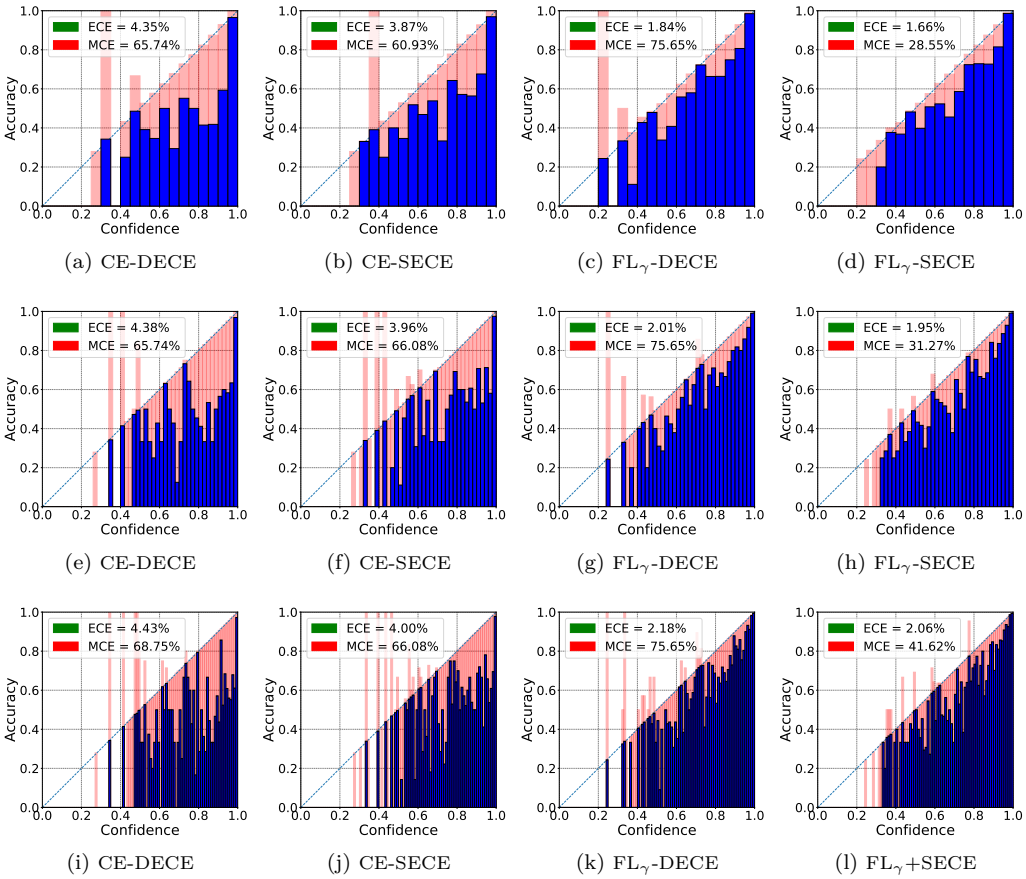
Figure 8: The ECE and MCE scores on CIFAR 100 test dataset with different bin numbers in $[10, 20, 50, 100, 200, 500, 1000]$. Our proposed approach shows better robustness on bin sizes.

Methods	Error	NLL	ECE	MCE	ACE	CLASSWISE_ECE
CE	5.354 ± 0.097	0.22 ± 0.015	3.038 ± 0.159	33.419 ± 19.597	3.035 ± 0.157	0.677 ± 0.031
CE-DECE	5.85 ± 0.421	0.236 ± 0.017	3.245 ± 0.471	25.062 ± 2.184	3.24 ± 0.471	0.723 ± 0.072
CE-SECE	5.895 ± 0.271	0.246 ± 0.032	3.555 ± 0.428	24.518 ± 3.613	3.555 ± 0.425	0.756 ± 0.083
FL$_\gamma$-DECE	6.084 ± 0.188	0.199 ± 0.012	2.151 ± 1.499	24.644 ± 11.227	2.139 ± 1.457	0.605 ± 0.201
FL$_\gamma$-SECE	6.263 ± 0.266	0.208 ± 0.021	2.549 ± 2.233	20.22 ± 5.235	2.559 ± 2.217	0.672 ± 0.355

Table 4: DenseNet (100 layers) on CIFAR10 with meta-learning based methods, 5 repetitions. gamma-net based methods exhibit better calibration across multiple metrics (NLL, ECE, ACE, CLASSWISE_ECE) while maintain competitive test error.

A.4 The Predictive-Calibration Trade-off

Figure 10 reports the empirical trade-off between predictive (measured by test error) and calibration (measured by ECE) performance. We can see that many methods exist at the Pareto front. For instance, mixup ($\alpha = 0.1$), LS(0.1) and FL$_\gamma$-SECE achieves the low test error but high ECE on CIFAR datasets. This indicates there is predictive-calibration trade-off for most of methods. Similar Pareto front are observed in

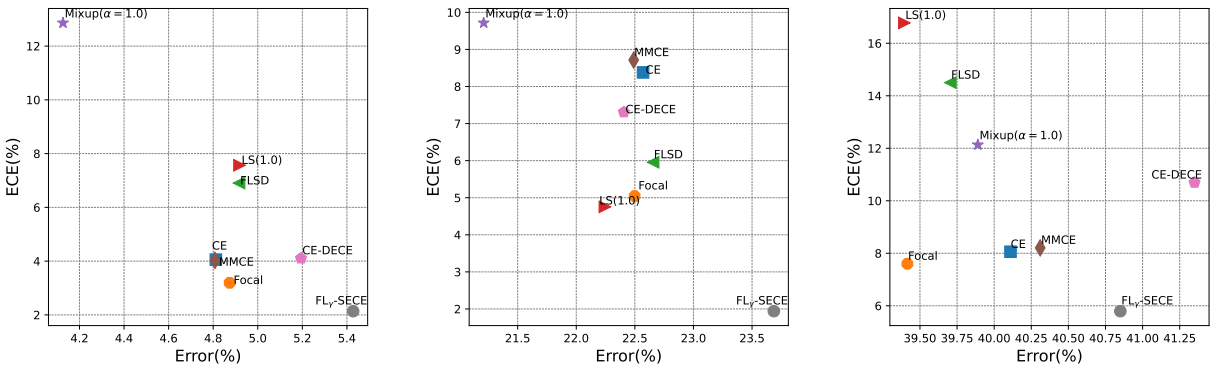


(a) CE-DECE (b) CE-SECE (c) FL$_\gamma$-DECE (d) FL$_\gamma$-SECE

(e) CE-DECE (f) CE-SECE (g) FL$_\gamma$-DECE (h) FL$_\gamma$-SECE

(i) CE-DECE (j) CE-SECE (k) FL$_\gamma$-DECE (l) FL$_\gamma$+SECE

Figure 9: The reliability diagram plots for models on CIFAR10 with large bin numbers (top to bottom: 20, 50, 100). The diagonal dash line presents perfect calibration, the red bar presents the gap to perfect calibration on each bin. The model from the 5th run is used.



(a) CIFAR10 (b) CIFAR100 (c) Tiny-ImageNet

Figure 10: The trade-off between predictive and calibration performance of different methods on the test set of CIFAR10, CIFAR100 and Tiny-ImageNet. The Pareto front are observed for most of methods.

pertained large language models (LLMs) (Stengel-Eskin & Van Durme, 2023). However, as depicted in Table

5, when evaluating the ECE improvement for our proposed FL_γ-SECE method, the reduction in predictive capability is modest.

Methods	CIFAR100		CIFAR100		Tiny-ImageNet	
	(Δ_{error})	Δ_{ECE}	(Δ_{error})	Δ_{ECE}	(Δ_{error})	Δ_{ECE}
Focal	0.062	-0.863	-0.072	-3.336	-0.695	-0.459
FLSD	0.104	2.848	0.086	-2.424	-0.405	6.442
LS(1.0)	0.106	3.510	-0.326	-3.626	-0.715	8.718
Mixup($\alpha = 1.0$)	-0.686	8.807	-1.360	1.336	-0.220	4.074
MMCE	-0.004	-0.029	-0.080	0.333	0.200	0.147
CE-DECE	0.382	0.050	-0.164	-1.071	1.240	2.635
FL_γ-SECE	0.616	-1.918	1.116	-6.44	0.740	-2.265

Table 5: The test error difference (Δ_{error}) and ECE difference (Δ_{ECE}) for different methods as compared to the baseline (CE)