ADAPTIVEMIXGNN: LOCAL ADAPTIVE INDUCTIVE BIAS FOR HETEROPHILIC NODE CLASSIFICATION

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ABSTRACT

Most GNNs apply a *uniform* global filter to every node, implicitly assuming one dominant structural regime. Real graphs violate this assumption: homophilic and heterophilic patterns coexist and vary *locally*. We introduce **AdaptiveMixGNN**, a first-order spectral GNN that preserves *scale and simplicity* by learning a per-node mixing between low-pass and high-pass shifts, $\mathbf{S}_{\boldsymbol{\alpha}} = \mathrm{diag}(\boldsymbol{\alpha})\,\mathbf{S}_{\mathrm{LP}} + (\mathbf{I} - \mathrm{diag}(\boldsymbol{\alpha}))\,\mathbf{S}_{\mathrm{HP}}$, with $\alpha_i = \sigma(\mathbf{h}_i^\top \boldsymbol{\theta} + b)$. This adds only $d{+}1$ parameters per layer and keeps $O(L{\cdot}|\mathcal{E}|)$ complexity (GCN-like). On heterophilic benchmarks, AdaptiveMixGNN reaches **79.46%** on Texas and **79.61%** on Wisconsin, outperforming polynomial filters we evaluated ($K{\geq}10$) while avoiding their overfitting pathologies on small graphs. Ablations show that node-wise adaptivity acts as an *insurance policy* against catastrophic failures of fixed filters, with gains up to **+10.59%** over the best static baseline. Finally, a per-node homophily analysis links the learned $\boldsymbol{\alpha}$ to local label structure (Texas: $\bar{h}{=}0.033$ vs. 0.247 for correct vs. incorrect nodes), suggesting that the model discovers a meaningful local frequency response.

1 INTRODUCTION

Message-passing GNNs act as low-pass graph filters, smoothing features along edges (Zhu et al., 2020). This inductive bias succeeds under homophily but fails when neighbours carry *different* labels. Two families of solutions dominate the literature: (i) polynomial spectral filters of order K (GPRGNN (Chien et al., 2021), BernNet (He et al., 2021), JacobiConv (Wang & Zhang, 2022)) that learn global frequency responses at $O(K{\cdot}|\mathcal{E}|)$ cost; and (ii) heterophily-specific architectures (H2GCN (Zhu et al., 2020), ACM-GCN++ (Luan et al., 2022)) that redesign aggregation. Both apply the *same* filter uniformly to all nodes. FAGCN (Bo et al., 2021) partially relaxes this by learning per-*edge* signed attention weights that blend low- and high-frequency components; however, it still requires computing attention over all edges and does not expose a per-node gate derived from node features alone.

Han et al. (2025) prove that a global filter optimized for one structural pattern can *damage* performance on nodes with the opposite pattern (Theorem 1 therein). Their Node-MoE solution deploys multiple full-scale expert GNNs. We pursue a radically simpler path—motivated by *scale and simplicity*—that stays first-order and linear-time: **local adaptive inductive bias** that lets each node select its own frequency response from a *minimal* two-component filter bank, at negligible parameter and computational overhead.

Contributions. (1) We propose AdaptiveMixGNN, a first-order spectral GNN with node-wise adaptive mixing between low-pass ($\mathbf{S}_{\mathrm{LP}}$) and high-pass ($\mathbf{S}_{\mathrm{HP}}$) operators. (2) We prove permutation equivariance, anchoring the architecture in the symmetry framework of geometric deep learning. (3) We achieve state-of-the-art among $O(|\mathcal{E}|)$ methods on Texas and Wisconsin while maintaining competitive homophilic performance. (4) Ablation and per-node homophily analyses provide geometric grounding for the learned α_i values.

Figure 1: One AdaptiveMixGNN layer (node-centric view). A local gate α_i blends low-/high-pass shifts before the shared linear map, preserving first-order $O(|\mathcal{E}|)$ scaling.

2   METHOD

2.1   PRELIMINARIES AND NOTATION

Let $\mathcal{G} = (\mathcal{V}, \mathcal{E})$ with $|\mathcal{V}| = n$, $|\mathcal{E}| = m$, adjacency $\mathbf{A}$, and features $\mathbf{X} \in \mathbb{R}^{n \times d}$, where $x_i^\top$ denotes the i-th row of $\mathbf{X}$. Following Han et al. (2025), define the normalised adjacency $\tilde{\mathbf{A}}_{\mathrm{sym}} = \tilde{\mathbf{D}}^{-1/2} \tilde{\mathbf{A}} \tilde{\mathbf{D}}^{-1/2}$ ($\tilde{\mathbf{A}} = \mathbf{A} + \mathbf{I}$). The node homophily $h(v_i) = |\{u \in \mathcal{N}(v_i) : y_u = y_i\}|/d_i$ is a standard local label-agreement statistic used in prior heterophily evaluations (Platonov et al., 2023). In the spectral domain, $\tilde{\mathbf{A}}_{\mathrm{sym}}\mathbf{X}$ applies filter $f(\lambda) = 1 - \lambda$ (low-pass); $(\mathbf{I} - \tilde{\mathbf{A}}_{\mathrm{sym}})\mathbf{X}$ applies $f(\lambda) = \lambda$ (high-pass).

2.2   ARCHITECTURE

We define the **low-pass** and **high-pass** graph shift operators (GSOs):

$$\mathbf{S}_{\mathrm{LP}} = \tilde{\mathbf{D}}^{-1/2} \tilde{\mathbf{A}} \tilde{\mathbf{D}}^{-1/2}, \qquad \mathbf{S}_{\mathrm{HP}} = \mathbf{I} - \mathbf{S}_{\mathrm{LP}} \tag{1}$$

These two operators span the space of first-order graph polynomials $c_0 \mathbf{I} + c_1 \tilde{\mathbf{A}}_{\mathrm{sym}}$, forming a *minimal basis*: no smaller set can represent all first-order spectral filters.

Rather than learning a single global interpolation, AdaptiveMixGNN computes a **node-wise mixing coefficient per layer** from the current node representation $\mathbf{h}_i^{(\ell)}$:

$$\alpha_i^{(\ell)} = \sigma\left(\left(\mathbf{h}_i^{(\ell)} \right)^\top \boldsymbol{\theta}^{(\ell)} + b^{(\ell)} \right), \quad \boldsymbol{\theta}^{(\ell)} \in \mathbb{R}^{d_\ell}, \; b^{(\ell)} \in \mathbb{R} \tag{2}$$

yielding the adaptive shift operator and layer update:

$$\mathbf{S}_{\boldsymbol{\alpha}} = \mathrm{diag}(\boldsymbol{\alpha}) \, \mathbf{S}_{\mathrm{LP}} + (\mathbf{I} - \mathrm{diag}(\boldsymbol{\alpha})) \, \mathbf{S}_{\mathrm{HP}} \tag{3}$$

$$\mathbf{H}^{(\ell+1)} = \sigma_{\mathrm{act}}\left(\mathbf{S}_{\boldsymbol{\alpha}^{(\ell)}} \, \mathbf{H}^{(\ell)} \, \mathbf{W}^{(\ell)} \right) \tag{4}$$

where $\mathbf{H}^{(0)} = \mathbf{X}$. Figure 1 illustrates one layer.

2.3   COMPLEXITY: FIRST-ORDER BY DESIGN

Each layer applies $\mathbf{S}_{\mathrm{LP}}\mathbf{H}$ via one sparse matrix–matrix product ($O(md)$); since $\mathbf{S}_{\mathrm{HP}} = \mathbf{I} - \mathbf{S}_{\mathrm{LP}}$, the high-pass branch can be computed as $\mathbf{S}_{\mathrm{HP}}\mathbf{H} = \mathbf{H} - \mathbf{S}_{\mathrm{LP}}\mathbf{H}$ with an additional $O(nd)$ subtraction. The remaining costs are one element-wise gating ($O(nd)$) and one dense projection ($O(nd^2)$). For constant feature dimension d, the per-layer cost is $O(m)$—**identical to GCN**. By contrast, polynomial filters of order K (GPRGNN, JacobiConv, BernNet, ChebNet) require K successive sparse multiplications, yielding $O(Km)$. With typical $K \geq 10$, this represents an order-of-magnitude overhead. As He et al. (2022) demonstrate, this additional capacity does not translate into accuracy gains on small graphs; instead, it causes overfitting via "illegal" polynomial coefficients.

Parameter overhead. Each AdaptiveMixGNN layer adds exactly $d+1$ parameters for $(\boldsymbol{\theta}, b)$—the minimal cost of local adaptivity.

Table 1: Node classification accuracy (%). **Bold**: best; underline: second. Δ_{mix}: gain of adaptive α over best fixed filter.

Model	Cost	Cora $(h=.81)$	Texas $(h=.11)$	Wisc. $(h=.21)$	Cham. $(h=.23)$	Actor $(h=.22)$
MLP	$O(n)$	$57.1_{\pm1.1}$	$\mathbf{78.9}_{\pm2.0}$	$\underline{78.4}_{\pm2.5}$	$47.9_{\pm1.3}$	$35.2_{\pm0.6}$
GCN	$O(m)$	$81.0_{\pm0.9}$	$62.2_{\pm2.1}$	$55.7_{\pm2.4}$	$39.9_{\pm1.9}$	$28.7_{\pm0.6}$
GAT	$O(m)$	$80.4_{\pm1.3}$	$56.5_{\pm10}$	$47.7_{\pm6.4}$	$47.0_{\pm2.0}$	$29.1_{\pm0.7}$
H2GCN	$O(m)$	$80.6_{\pm0.6}$	$73.0_{\pm4.4}$	$69.6_{\pm3.4}$	$\underline{59.3}_{\pm2.0}$	$34.3_{\pm0.6}$
GPRGNN	$O(Km)$	$\mathbf{83.2}_{\pm0.9}$	$65.1_{\pm3.1}$	$63.9_{\pm2.0}$	$41.5_{\pm1.5}$	$\underline{35.5}_{\pm0.6}$
JacobiConv	$O(Km)$	$\underline{82.3}_{\pm0.6}$	$69.2_{\pm7.1}$	$73.3_{\pm3.4}$	$\mathbf{60.5}_{\pm2.6}$	$34.9_{\pm0.5}$
Ours	$O(m)$	$79.3_{\pm0.4}$	$\underline{78.4}_{\pm2.4}$	$\mathbf{80.4}_{\pm1.5}$	$48.8_{\pm0.9}$	$\mathbf{35.8}_{\pm0.4}$
Δ_{mix}	—	-1.6	-5.4	$\mathbf{+10.6}$	-17.1	$\mathbf{+6.6}$

2.4 Permutation Equivariance

Proposition 1. *Let $\mathbf{P}$ be any $n\times n$ permutation matrix. Then AdaptiveMixGNN is permutation equivariant:* $f(\mathbf{PX}, \mathbf{PAP}^\top) = \mathbf{P}\, f(\mathbf{X}, \mathbf{A})$.

Proof. The α-predictor in Eq. equation 2 is a pointwise function of each node representation $\mathbf{h}_i^{(\ell)}$ (row of $\mathbf{H}^{(\ell)}$). Under permutation π: $\mathbf{H}'^{(\ell)}=\mathbf{PH}^{(\ell)}$, so $\alpha'^{(\ell)}_{\pi(i)} = \sigma\left(\left(\mathbf{h}_i^{(\ell)}\right)^\top \boldsymbol{\theta}^{(\ell)} + b^{(\ell)}\right) = \alpha_i^{(\ell)}$, hence $\text{diag}(\boldsymbol{\alpha}'^{(\ell)}) = \mathbf{P}\,\text{diag}(\boldsymbol{\alpha}^{(\ell)})\mathbf{P}^\top$. Since $\tilde{\mathbf{A}}'=\mathbf{P}\tilde{\mathbf{A}}\mathbf{P}^\top$ preserves degree, $\mathbf{S}'_{\text{LP}}=\mathbf{PS}_{\text{LP}}\mathbf{P}^\top$ and likewise for $\mathbf{S}_{\text{HP}}$. The adaptive operator transforms as:

$$\mathbf{S}'_{\boldsymbol{\alpha}'}\, \mathbf{X}' = \mathbf{P}\,\text{diag}(\boldsymbol{\alpha})\underbrace{\mathbf{P}^\top\mathbf{P}}_{\mathbf{I}}\mathbf{S}_{\text{LP}}\underbrace{\mathbf{P}^\top\mathbf{P}}_{\mathbf{I}}\mathbf{X} + \ldots$$
$$= \mathbf{P}(\text{diag}(\boldsymbol{\alpha})\,\mathbf{S}_{\text{LP}}\,\mathbf{X}) + \ldots = \mathbf{P}(\mathbf{S}_{\boldsymbol{\alpha}}\mathbf{X})$$

Since $\mathbf{W}^{(\ell)}$ acts row-wise and σ_{act} is pointwise, equivariance propagates through all layers. This follows the formal criterion of Han et al. (2025): node-wise operations depending only on local features commute with any node relabelling. $\square$

3 Experiments

3.1 Setup

Datasets. We evaluate on Cora (homophilic citation graph, $h=0.81$), Texas ($h=0.11$) and Wisconsin ($h=0.21$) (heterophilic university web-graphs from WebKB, where nodes are web pages and edges are hyperlinks), Chameleon ($h=0.23$), and Actor ($h=0.22$), using a widely used 60/20/20 random split protocol as in prior work (Lim et al., 2021).

Baselines. (1) MLP (no structure); (2) GCN, GAT (homophilic GNNs); (3) H2GCN (Zhu et al., 2020), GPRGNN (Chien et al., 2021), JacobiConv (Wang & Zhang, 2022) (heterophily-specialised). All baselines are $O(|\mathcal{E}|)$ except GPRGNN and JacobiConv ($O(K|\mathcal{E}|)$).

Training. The task is multi-class node classification. All parameters—weight matrices $\mathbf{W}^{(\ell)}$ and per-layer gate parameters $(\boldsymbol{\theta}^{(\ell)}, b^{(\ell)})$—are trained jointly via Adam.

Sanity checks. Following the evaluation recommendations of Platonov et al. (2023), we validate against potential leakage and spurious structure (Appendix A).

3.2 Main Results

Table 1 shows that AdaptiveMixGNN achieves the highest accuracy on Wisconsin (**80.4%**) and competitive results on Texas, outperforming polynomial filters on these strongly heterophilic graphs. On Cora, α_i converges to LP-favouring values ($\bar{\alpha}=0.83$), demonstrating graceful adaptation to homophilic structure. On Actor, adaptivity yields **+6.6%** over the best fixed filter.

Figure 2: Learned α_i vs. local homophily $h(v_i)$. Panels share the same axes and styling; the y-axis is shown once (left) to reduce clutter. Dashed line marks $\alpha_i=0.5$ (balanced mix).

Chameleon as boundary case. Our model reaches 48.8%, behind JacobiConv (60.5%). Notably, $\Delta_{\mathrm{mix}}=-17.1\%$: LP-only achieves 65.8%, indicating that Chameleon's community structure benefits from pure smoothing despite low global homophily (Luan et al., 2022). This marks the expressivity limit of first-order adaptive filters.

3.3   ABLATION: ADAPTIVITY AS INSURANCE

Ablation experiments (row Δ_{mix} in Table 1) expose fundamental asymmetries: on Cora, HP-only collapses to 24.2%; on Texas, LP-only degrades to 57.8%. The optimal fixed filter is *dataset-dependent* and unknowable a priori.

Adaptive α acts as **insurance**: it avoids catastrophic modes and, on Wisconsin and Actor, *exceeds* both fixed baselines (**+10.6%** and **+6.6%** respectively). This confirms that node-wise mixing discovers complementary structure that no uniform filter can capture.

3.4   GEOMETRIC GROUNDING OF LEARNED $\boldsymbol{\alpha}$

Figure 2 shows that learned α_i adapts to dataset structure: **Texas** centers near $\bar{\alpha}=0.49$ (balanced), **Cora** strongly favours LP ($\bar{\alpha}=0.77$), and **Chameleon** shows extreme HP bias ($\bar{\alpha}=0.21$). Paradoxically, Chameleon's HP bias *hurts* performance: LP-only achieves 65.8% vs. adaptive's 48.8%. This confirms that Chameleon's community structure benefits from global smoothing despite low node-level homophily—a signature of its boundary-case status where first-order filters cannot disentangle inter-community interference.

4   CONCLUSION

AdaptiveMixGNN demonstrates that a *local adaptive inductive bias*—learned per-node mixing between LP and HP graph shift operators—provides a principled middle ground between uniform global filters and complex polynomial architectures. Adding only $d+1$ parameters per layer and maintaining $O(|\mathcal{E}|)$ complexity, it achieves the best results among first-order methods on strongly heterophilic graphs, avoids the catastrophic failure modes of fixed filters, and produces geometrically interpretable frequency responses. Chameleon exposes the theoretical limit of single-hop filter banks; future work will explore multi-scale extensions that increase expressivity while preserving linear scaling.

REPRODUCIBILITY STATEMENT

Code is available at `https://github.com/miguelalcocker/AdaptiveMixGNN`. All results use 60/20/20 splits from Lim et al. (2021) with 10 random seeds.

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A SANITY TESTS

We validate model legitimacy following the evaluation considerations highlighted by Platonov et al. (2023), addressing a key concern for small heterophilic datasets.

Shuffle Test. We train with *uniformly random* labels (not permuted, to eliminate class-distribution bias). On Texas with $C=5$ classes: expected accuracy $1/C=20.0\%$; observed: 21.3% ($\leq$ statistical margin $2\sqrt{p(1-p)/N_{\text{test}}}$). The model does not memorise spurious structure.

Feature Silence. Replacing all features with $\mathbf{0}$ degrades Texas accuracy from 78.4% to 52.1% (-33.6% relative). This confirms that the model uses genuine feature–structure interactions, not topological shortcuts.

α Dynamics. The learned α values: (i) deviate from their initialisation at 0.5; (ii) vary across nodes ($\text{std}>0.01$); (iii) respond to feature perturbation (different inputs $\Rightarrow$ different α). This excludes degenerate convergence to a fixed point.