kNN-CLIP: Retrieval Enables Training-Free Segmentation on Continually Expanding Large Vocabularies

Anonymous authors
Paper under double-blind review

Abstract

Rapid advancements in continual segmentation have yet to bridge the gap of scaling to large continually expanding vocabularies under compute-constrained scenarios. We discover that traditional continual training leads to catastrophic forgetting under compute constraints, unable to outperform zero-shot segmentation methods. We introduce a novel strategy for semantic and panoptic segmentation with zero forgetting, capable of adapting to continually growing vocabularies without the need for retraining or large memory costs. Our training-free approach, kNN-CLIP, leverages a database of instance embeddings to enable open-vocabulary segmentation approaches to continually expand their vocabulary on any given domain with a single-pass through data, while only storing embeddings minimizing both compute and memory costs. This method achieves state-of-the-art mIoU performance across large-vocabulary semantic and panoptic segmentation datasets. We hope kNN-CLIP represents a step forward in enabling more efficient and adaptable continual segmentation, paving the way for advances in real-world large-vocabulary continual segmentation methods.

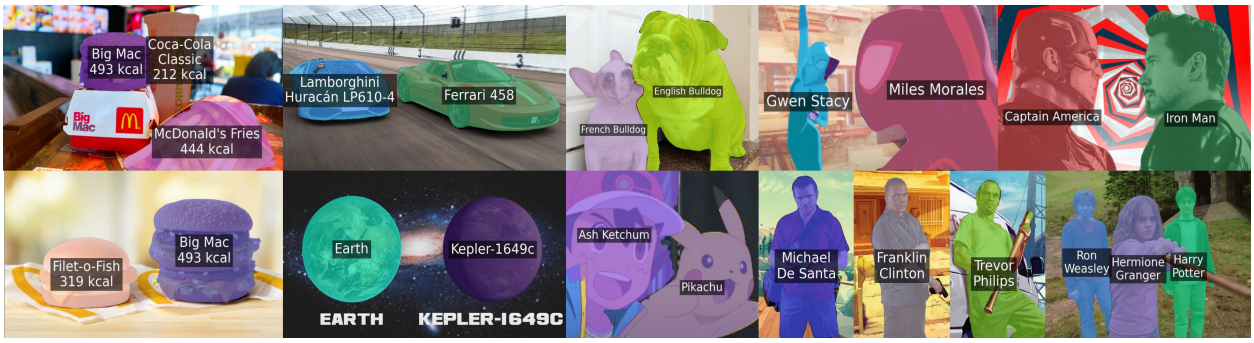

Figure 1: We propose kNN-CLIP to continually expand the vocabulary space of segmentation models. Our approach adapts to concept customization and identifying long-tailed concepts like famous personas. The above image is a qualitative demonstration of our work.

1 Introduction

The holy grail in image segmentation is to accurately segment any concept images based on a text query. This task was made more achievable through the rapid advances of vision-language models (VLMs) like CLIP, which when applied to semantic and panoptic segmentation, showing promise in handling a broad vocabulary of visual data. However, while they excel in common categories on segmentation benchmarks, they fall short in achieving broad-vocabulary segmentation (Shao et al., 2023; Udandarao et al., 2024).

Our analysis begins by identifying that the success of these models on standard datasets stems from their fine-tuning on specific datasets with detailed labels, such as COCO Stuff (Caesar et al., 2018), which often overlaps with the classes of many other benchmarks with fine-grained annotations. For example, COCO-Stuff

and ADE-20K have a class overlap of 73 out of 150 classes. Previous works (Sun et al., 2023) have shown that removing this overlapping vocabulary results in poor segmentation performance. We further discover that this finetuning significantly reduces the open-vocabulary segmentation abilities derived from the pre-trained CLIP model, attributable to catastrophic forgetting. This raises the question: *Can we enhance these models to a continually-growing vocabulary with data without catastrophic forgetting?*

First, we investigate continual training of these VLM segmentation algorithms to data with new categories. We consistently find that continual training of these models causes **concept forgetting** by encoding new information into a limited, poorly understood parameter space inadvertently overwriting past knowledge. However, recent state-of-the-art open-vocabulary segmentation approaches (Yu et al., 2023; Liu et al., 2023b) still rely on fine-tuning with datasets containing fine-grained annotations like masks and boxes. This limits the effective vocabulary of these open-vocabulary model, *i.e.*, we observe that training significantly narrows down the vocabulary size of these models, restricting their ability to generalize to a wider range of objects and concepts[1]. The primary question this work tackles is how to expand the knowledge of the model given in-domain data *without any training*.

Our novel method, kNN-CLIP, circumvents the need for retraining by using a retrieval database that matches images with text descriptions, updating a support set with new data in a single pass without storing any previous images for replay. In contrast to traditional continual learning techniques, we can guarantee that the model **never forgets** previously seen data, learns with a single pass, optimizes memory by only storing features, and crucially, expands its vocabulary with minimal computational resources due to no additional training.

Our straightforward and effortless approach significantly improves the performance of leading semantic and panoptic segmentation algorithms without the need for additional training. We apply our method to the state-of-the-art open-vocabulary semantic and panoptic segmentation framework FC-CLIP (Yu et al., 2023), and achieve notable increases in performance (mIoU) across various challenging datasets—A-847, PC-459, and A-150—by **+2.6**, **+1.7** and **+7.2** points, respectively. This improvement is achieved with small computational and memory overheads, and without any training cost. As shown in Figure 1, we also qualitatively demonstrate that our method can be used for multiple purposes including concept customization and person identification.

Overall, the key contributions of our study include:

- ***Identifying Degradation in Open-Vocabulary Segmenters***: We uncover the paradox where fine-tuning VLM models for segmentation using downstream annotations dramatically reduces their ability to recognize the broad VLM vocabulary, illustrating that catastrophic forgetting in open-vocabulary restricts the scope of open-vocabulary segmentation.
- ***Training-Free Continual Vocabulary Expansion***: We introduce a novel technique, kNN-CLIP, that continually expands the vocabulary of image segmentation models without additional training. This method utilizes a continually expanding support set, recasting the problem of concept prediction as an image retrieval task.
- ***Consistent Improvements Across Diverse Datasets***: We present extensive experimental evidence of our approach's effectiveness, demonstrating substantial improvements in semantic and panoptic segmentation across datasets with long-tailed distributions (A-847, PC-459, A-150).

2 Related Works

Retrieval-Augmented Models. In the NLP domain, Retrieval-Augmented Generation (RAG) has been shown as a promising technique for enhancing Large Language Models (LLM) by leveraging external structured data (Guu et al., 2020; Wu et al., 2022; Borgeaud et al., 2022; Liu et al., 2020; Peters et al., 2019; Yu et al., 2021; Izacard et al., 2022; Ram et al., 2023). The dynamic nature of RAG facilitates continuous

[1]Concept forgetting is a term borrowed from Mukhoti et al. (2023), who demonstrated a similar degradation of open-vocabulary performance after fine-tuning CLIP models but on classification tasks

knowledge updates, enabling models to integrate domain-specific information seamlessly. This is particularly beneficial for knowledge-intensive tasks (Lewis et al., 2020; Wang et al., 2022; Khandelwal et al., 2019; Shi et al., 2023; Petroni et al., 2023).Inspired by its success in NLP, researchers are now exploring the application of RAG in computer vision tasks (Chen et al., 2022a; Marino et al., 2021; Roth et al., 2022; Shen et al., 2022; Sheynin et al., 2022; Yasunaga et al., 2022; Blattmann et al., 2022; Chen et al., 2022b; Liu et al., 2023a; Udandarao et al., 2023; Iscen et al., 2023; Prabhu et al., 2023c; Balazevic et al., 2024). For instance, REACT (Liu et al., 2023a) presents a methodology aimed at retrieving relevant knowledge and learning customized visual modules accordingly for specific domains. Meanwhile, SuS-X (Udandarao et al., 2023) and C2C (Prabhu et al., 2023c) introduce frameworks that utilizes retrieved support sets for far more accurate CLIP classification to open-set domains. Although these two works show promises in applying retrieval-based methods to visual perception, they did not discuss how to apply such techniques successfully in visual segmentation. Hummingbird (Balazevic et al., 2024) suggests employing a straightforward non-parametric nearest neighbor retrieval as the decoder for dense scene understanding tasks. Moreover, beyond integrating new visual features, RECO (Iscen et al., 2023) demonstrates the efficacy of incorporating text representations by cross-modal fusion alongside original and retrieved embeddings. However, both Hummingbird (Balazevic et al., 2024) and RECO (Iscen et al., 2023) require training to better integrate retrieval augmentation into their pipelines; in contrast, our method demands no training efforts while providing faster adaptability and strong performance.

Open Vocabulary Learning in Image Understanding. Benefiting from advancement in vision-language model (Radford et al., 2021; Jia et al., 2021), visual models demonstrate the potential of open vocabulary image understanding to break the constraints of pre-defined closed-set concept. In particular for dense prediction tasks (Yu et al., 2023; Rao et al., 2022; Ding et al., 2022; Chen et al., 2023; Karazija et al., 2023; Liang et al., 2023; Li et al., 2022a; Xu et al., 2023a;b; 2022b;a; Sun et al., 2023; Wang et al., 2023b; Lüddecke & Ecker, 2022; Xie et al., 2023), one line of works such as SimBaseline (Xu et al., 2022b) and OVSeg (Liang et al., 2023) focus on leveraging cross-modality supervision from CLIP to align class-agnostic mask proposal with language concepts. ODISE (Xu et al., 2023a) and FC-CLIP (Yu et al., 2023), further explore such idea with improved visual encoder and mask proposal strategy to achieve promising performance on both semantic and panoptic segmentation. However, a critical limitation of these works is catastrophic forgetting during fine-tuning on concept-restricted dense prediction datasets, leading to severe degradation in model vocabulary size. To address this challenge, training-free method such as ReCO (Shin et al., 2022) and CaR (Sun et al., 2023) aim to achieve efficient adaptation of CLIP model through recurrently pruning the label space. While these method circumvent the problem of catastrophic forgetting, they are still unable to accommodate continually expanding large vocabulary. Thus, in this work, we leverage retrieval augmentation for continual open vocabulary image understanding.

Continual Learning for Semantic Segmentation. As opposed to open vocabulary semantic segmentation, continual learning does not intend to encompass an extremely large vocabulary space at the first place but preserve the ability to expand the vocabulary space continuously. Nevertheless, continual learning suffers from catastrophic forgetting and semantic drift. To alleviate these issues, iCaRL (Rebuffi et al., 2017) proposes to replay the most representative samples during the continual learning stage, and following works attempt to optimize the associated memory burden (Cha et al., 2021; Zhu et al., 2023; Wang et al., 2023a; Kalb et al., 2022; Kim et al., 2022). Moreover, feature-replay scheme is proposed by ALIFE (Oh et al., 2022) to reduce memory requirements. More works explore how to leverage memorized features to preserve known knowledge (Yoon et al., 2022; Yu et al., 2020; Wang et al., 2021; Michieli & Zanuttigh, 2021; Lin et al., 2022a). One notable shortcoming of using memorized features is that the representation capacity of features might be insufficient, hindering the performance of continual learning (Yuan & Zhao, 2023). Either using hyper-class knowledge (Shi et al., 2022) or dynamically updating stored features (Liu et al., 2022; Lin et al., 2022b; Li et al., 2022b) mitigates the problem but still not circumventing it inherently. Serving the same purpose of expanding vocabulary space dynamically, our method resembles the feature-replay methods, as we also construct a support set of features. Nonetheless, our method operates without the need for training and utilizes a support set, storing powerful features learned through self-supervised learning techniques (Caron et al., 2021), with low memory requirements.

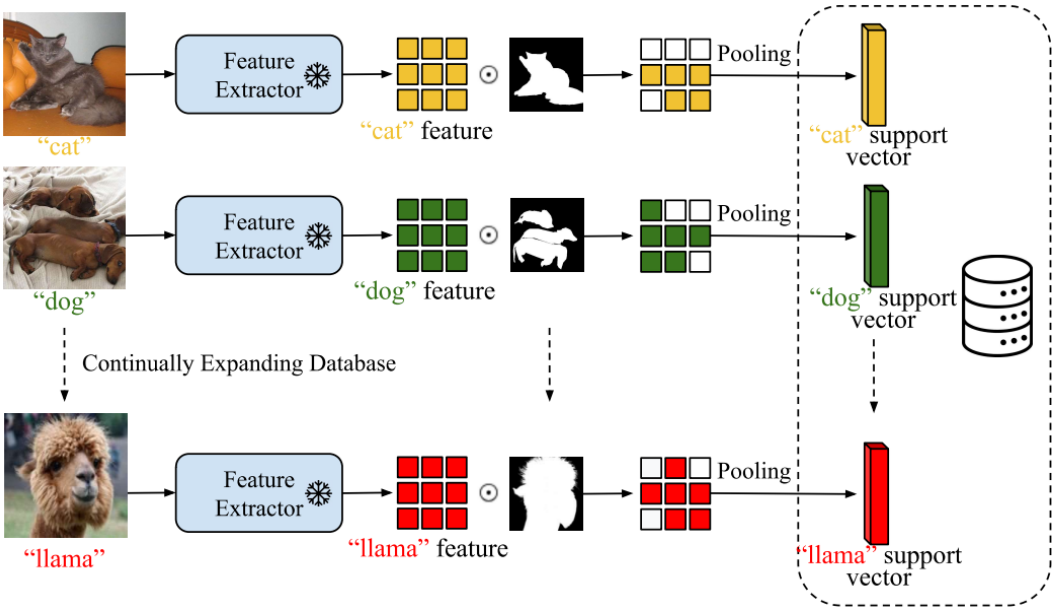

Figure 2: **Dynamic Database Construction.** A key benefit of our methodology is that it allows for the seamless integration of embeddings for new classes into our database, continuously expanding its vocabulary space.

3 Continually Expanding Retrieval-Augmented Dense Prediction

We introduce a novel, training-free framework for continual dense prediction with expanding vocabularies, applicable on diverse domains and across dense prediction tasks. Inspired by the Retrieval-Augmented Generation (RAG) method used in Large Language Models, our framework leverages a customizable embedding database to incorporate domain-specific knowledge directly at inference, with no additional training.

This approach is applicable to a range of dense prediction tasks including semantic and panoptic image segmentation. We first evaluate the confidence level of CLIP classification results for each query mask. For queries falling below a given confidence threshold, we extract DINO features and use mask pooling to generate query embeddings. These embeddings are then matched against a vectorized database using a kNN search algorithm based on cosine similarities. For the most similar embeddings found, we create a set of confidence-aware pseudo-logits by stacking similarities across class vectors, guided by the labels of these embeddings. The results from this retrieval process are then combined with the initial CLIP results through a given weighting parameter λ. We now provide details of our training-free method. We first describe the embedding construction process and detail the query mechanisms.

3.1 Designing Continually Expanding Embedding Databases

One appealing characteristic of our framework is the dynamic extendability of the database and the customization of the database construction based on personalized interest. Depending on the purpose specified by the user-defined applications (fine-grained setting such as smart retail, species classification, etc.), the database could be sourced from various domains through manual curation, online web-based collection, or synthetic data sources.

Database Construction. To obtain distinctive vectorized representations for the database images, we employ mask-pooling on features extracted by pre-trained encoders from the images as shown in Figure 2. Our input consists of an incoming image ($x_i \in \mathcal{R}^{3\times h\times w}$) with it's corresponding k class-agnostic masks, which could be semantic, instance dense masks, or bounding box masks ($M_i \in \mathcal{R}^{k\times h\times w}$) and class annotations (C_i) containing the class $\{c_{ji}\}_{j=1}^{k}$ corresponding to mask $\{m_{ji}\}_{j=1}^{k} = M_i$. We extract features of this image using a Vision Transformer (ViT, Dosovitskiy et al. (2021))-based encoder ($\mathcal{E}$), yielding $h_i = \mathcal{E}(x_i)$. Here, $h_i \in \mathcal{R}^{d\times h'\times w'}$ with d represents the embedding dimension of the feature, and h', w' represent the dimensions

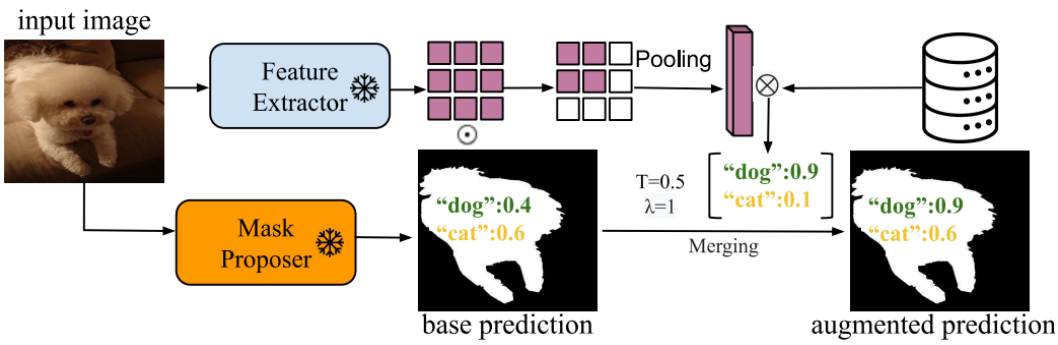

Figure 3: **Retrieval Augmentation from the Database.** By retrieving similar features from the database, we integrate the retrieved information with our previous prediction.

of the feature map. The embedding dimensions h', w' are determined by image size divided by the patch size of the vision transformer, thus usually shrunken by a magnitude of 10 each, and efficiently representing images with small feature maps guarantees the memory efficiency of our method. The ground-truth masks M_i are resized to $M'_i \in \mathcal{R}^{k \times h' \times w'}$ to align with the feature map dimensions. By applying mask average pooling along h' and w', the final embedding sets $\{e_{ji}\}_{j=1}^{k}$ on image x_i is obtained by:

$$E_i \in \mathcal{R}^{k \times d} = \{e_{ji} = \frac{\sum_{h'} \sum_{w'} (h_i \times m'_{ji})}{\sum_{h'} \sum_{w'} m'_{ij}}\}_{j=1}^{k} \tag{1}$$

Then, the vectorized embedding database is constructed by concatenating the embedding sets and class sets from all images, so that $D_{vec} = \{E_i, C_i\}_{i=1}^{n} = \{e_{i'}, c_{i'}\}_{i'=1}^{n'}$, if there are n' embeddings in total. New embeddings can also be continually added to the database repeating the above process. Note that *we do not store any images for replay, enabling low storage-costs and allowing deletion of previously seen data.*

3.2 Inference Using the Continually Expanding Embedding Databases

The embedding database established serves as the retrieval source during inference to enhance the capabilities for various downstream visual models, as shown in Figure 3. Given a test image along with a set of query mask proposals $M_q \in \mathcal{R}^{k \times h \times w}$ and corresponding feature embeddings acquired through the same method outlined in Section 3.1, we conduct a k-Nearest Neighbor (kNN) search for each query e_q within the embedding database D_{vec} as follows:

$$\text{kNN}_k(e_q) = \{(c_j, s_j(\cdot,\cdot)) \,|\, (e_j, c_j) \in D_{vec}\}_{j=1}^{k}, s_j(e_q, e_j) = \frac{e_q \cdot e_j}{\|e_q\| \|e_j\|} \tag{2}$$

We then utilize the retrieved sample class labels $\{c_j\}^k$ and cosine similarity scores $\{s_j\}^k$ to construct confidence-aware pseudo-logits $P_{ret} \in \mathcal{R}^C$ for retrieval-based prediction as follows:

$$P_{ret} = \frac{exp\Big(\sum_{i=1}^{k}(s_i \cdot \mathbb{I}(c_i = j)) + \epsilon\Big)}{\sum_{l=1}^{C} exp\Big(\sum_{i=1}^{k}(s_i \cdot \mathbb{I}(c_i = l)) + \epsilon\Big)}, \quad \forall j \in [1, C] \tag{3}$$

where we accumulate the class-wise similarity over the class vector and normalize it into a probability distribution through a softmax operation. We consider the higher similarity between instance embeddings with a more frequent retrieval reflects higher confidence in the kNN-based prediction. We then leverage the prediction logits to augment the raw prediction logits $P_{base} \in \mathcal{R}^C$ from a pre-trained visual model through a class-wise logit modification as follows:

$$P_{final} = \lambda P_{ret} \cdot (1 - \mathbb{I}(max(P_{base}) > T)) + P_{base} \cdot \mathbb{I}(max(P_{base}) > T) \tag{4}$$

where we set a confidence threshold T on raw prediction with the logit lower than it replaced by the corresponding value in retrieval-based prediction.

Our construction of pseudo-logits using a weighting based on cosine similarity only enhances the downstream performance on tasks or classes whose labels are stored in the embedding database. If the true label of a query is not in the database, or if the cosine similarity of a retrieved result is too low, our method will naturally prefer the original predictions. This preserves the broad zero-shot capabilities and the knowledge gained during pretraining, which are adept at making accurate predictions for concepts they were trained on (Udandarao et al., 2024). This flexible design enables us to dynamically expand to larger vocabularies and effectively addresses the recently highlighted issue of concept forgetting (Mukhoti et al., 2023).

4 Experiments

We present the results of our training-free approach, aimed at improving open-vocabulary dense prediction for large-scale datasets, including semantic and panoptic segmentation, testing continually expanding vocabularies in customized contexts.

4.1 Implementation Details

Database Construction. Our database is created by extracting features from each dataset's training sets using DINOv2 (Oquab et al., 2023) with a ViT-Giant architecture, featuring 4 register tokens. We select "keys" as our feature representation. We resize the images to 518×518 and acquire a image feature of dimensions $1536 \times 37 \times 37$, as the patch size of chosen ViT is 14. We then conduct mask average pooling to shrink the feature dimension to 1536. Then, we store the shrunken feature with dimension of 1536 and its corresponding label c into the database using FAISS. Note that we do not store past images alongside.

k-Nearest Neighbors Search. We employ FAISS for feature retrieval using cosine similarity metric. Our method uses a brute force approach for identifying the closest embeddings, but we also explore approximate search methods like Hierarchical Navigable Small Worlds (HNSW) to improve efficiency at inference time (Prabhu et al., 2023a). We shall compare HNSW approximation with exact-search and detail the tradeoffs in our ablations. The number of nearest neighbors retrieved is 16 across dense visual tasks, with further details in the ablation section.

Augmenting FC-CLIP. We integrate our methodology into the current state-of-the-art open-vocabulary segmentation method FC-CLIP, which generates query masks and assigns class probabilities for each mask, following Mask2Former (Cheng et al., 2022). We use a linear combination of the original predicted class probabilities, with the retrieved prediction class probabilities from the kNN-CLIP method. We subsequently follow FC-CLIP to fuse the in-vocabulary classification scores and the retrieval-augmented out-of-vocabulary classification scores via geometric ensemble. This allows us to enhance the out-of-distribution classification without losing pretraining knowledge.

4.2 Catastrophic Forgetting Restricts Open-Vocabulary Capabilities of Models

Motivation. We study how the open-vocabulary performance of dense predictors varies as these models are trained to recognize new classes. Specifically, we compare their segmentation performance before and after training and report performance deterioration.

Setup. We adopt a class-incremental continual learning setting adopted from CoMFormer(Cermelli et al., 2023). We benchmark this on semantic segmentation benchmark of COCO Panoptic as base dataset (having 330K images and 80 classes) and ADE20K (Zhou et al., 2019) as continual dataset (having 27K images and 150 classes). We first train the models like FC-CLIP on COCO Panoptic and then incrementally update this base model on ADE20K, with 5, 10 and 30 classes per timestep and a computational budget of one epoch (Prabhu et al., 2023b;a). We follow Mask2Former (Cheng et al., 2022) to use their loss function on an FC-CLIP (Yu et al., 2023) model, and evaluate mIoU across all classes in COCO Panoptic and ADE20K respectively after continual training.

Results. As shown in Table 1, when using naïve continual learning baseline, regardless of the number of incremental class, we observe consistent performance degradation of around 6 mIoU and 24 mIoU on the continual learning dataset ADE20K and the base dataset COCO-Panoptic respectively. The degradation on

Table 1: **Vocabulary Narrowing FC-CLIP.** We observe that further training FC-CLIP within a computational budget leads to significantly poorer performance on the downstream ADE20K dataset, while our retrieval augmentation method circumvents the problem in a compute efficient manner. We also observe significant vocabulary narrowing in COCO Panoptic dataset, which serves as the original training set of FC-CLIP.

Method	Base Dataset	Continual Dataset	Incremental Class	COCO Panoptic	ADE20K
FC-CLIP (Yu et al., 2023)	COCO Panoptic	-	-	63.7	34.1
FC-CLIP (Yu et al., 2023)	COCO Panoptic	ADE20K	5	43.0 (-20.7)	28.9 (-5.2)
	COCO Panoptic	ADE20K	10	38.9 (-24.8)	27.7 (-6.4)
	COCO Panoptic	ADE20K	30	39.6 (-24.1)	26.3 (-7.8)
kNN-FC-CLIP (Ours)	COCO Panoptic	ADE20K	1	**65.5 (+1.8)**	**41.3 (+7.2)**

Table 2: **Comparisons with Continual Learning.** Retrieval augmentation circumvents catastrophic forgetting occuring in continual learning.

Method	Base Dataset	Continual Dataset	Incremental Class	ADE20K (mIoU)
FC-CLIP (Yu et al., 2023)	COCO Panoptic	-	-	34.1
FC-CLIP (Yu et al., 2023)	COCO Panoptic	ADE20K (150 classes)	5	28.9 (-5.2)
	COCO Panoptic	ADE20K (150 classes)	10	27.7 (-6.4)
	COCO Panoptic	ADE20K (150 classes)	30	26.3 (-7.8)
Mask2Former (Cheng et al., 2022)	ADE20K (100 classes)	ADE20K (50 classes)	5	26.3
	ADE20K (100 classes)	ADE20K (50 classes)	10	31.0
	ADE20K (100 classes)	ADE20K (50 classes)	50	38.1
CoMFormer (Cermelli et al., 2023)	ADE20K (100 classes)	ADE20K (50 classes)	5	30.9
	ADE20K (100 classes)	ADE20K (50 classes)	10	32.3
	ADE20K (100 classes)	ADE20K (50 classes)	50	38.4
kNN-FC-CLIP (Ours)	COCO Panoptic	ADE20K	1	**41.3 (+7.2)**

ADE20K can be attributable to catastrophic forgetting when learning across timesteps. Moreover, this causes concept forgetting, i.e., degradation of the open-vocabulary performance by a large margin, as measured by performance on COCO-Panoptic. This indicates that there is an pressing need for techniques to allow segmentation models to continually expand their vocabulary across novel concepts without losing their open-vocabulary segmentation capabilities. We show that our proposed training-free method kNN-CLIP allows effective alleviation of concept forgetting leading to significant performance improvement of **+7.2** mIoU in ADE20K and **+1.8** mIoU in COCO Panoptic.

4.3 Comparison with Continual Segmentation Approaches

Setup. We compare our method against the popular supervised method, Mask2Former (Cheng et al., 2022) and current state-of-the-art continual learning method, CoMFormer (Cermelli et al., 2023). We use the same experimental protocol as previously described for our method. These supervised models were initially trained on the first 100 classes and subsequently updated incrementally with the next 50 classes. We then evaluated the performance of these models using the mean Intersection over Union (mIoU) metric across all 150 classes from the ADE20K dataset.

Results. As shown in Table 2, Mask2Former (Cheng et al., 2022) and CoMFormer (Cermelli et al., 2023), exhibit large performance degradation when we reduce the number of incremental classes within 50 classes. In contrast, kNN-CLIP demonstrates a substantial advantage in preserving previous knowledge and mitigating knowledge loss, and it is inherently unaffected by the number of incremental classes. This resilience is attributed to our dynamic and continuously expanding embedding database, which significantly enhances our method's effectiveness in continual learning scenarios.

Table 3: **Open-vocabulary panoptic segmentation performance.** Retrieval augmentation showcases improvements in panoptic segmentation.

Method	ADE20K			COCO Panoptic		
	PQ	AP	mIoU	PQ	AP	mIoU
ODISE	22.6	14.4	29.9	55.4	**46.0**	65.2
ODISE(caption)	23.4	13.9	28.7	45.6	38.4	52.4
FC-CLIP(baseline)	26.8	16.8	34.1	54.4	44.6	63.7
kNN-FC-CLIP(Ours)	**29.6**	**17.5**	**41.3**	**54.8**	44.8	**65.5**
Δ *w.r.t baseline*	+2.8	+0.7	+7.2	+0.4	+0.2	+1.8

Table 4: **Open-vocabulary semantic segmentation performance.** Retrieval augmentation demonstrates state-of-the-art performances on open-vocabulary semantic segmentation.

Method	Training Dataset	A-847	PC-459	A-150	PC-59	PC-21
SimBaseline (Hsia et al., 2022)	COCO Stuff	-	-	15.3	-	74.5
ZegFormer (Ding et al., 2022)	COCO Stuff	-	-	16.4	-	73.3
LSeg+ (Li et al., 2022a)	COCO Stuff	3.8	7.8	18.0	46.5	-
OVSeg (Liang et al., 2023)	COCO Stuff	9.0	12.4	29.6	55.7	-
SAN (Xu et al., 2023b)	COCO Stuff	13.7	17.1	33.3	60.2	-
OpenSeg (Ghiasi et al., 2022)	COCO Panoptic + COCO Caption	6.3	9.0	21.1	42.1	-
ODISE (caption) (Xu et al., 2023a)	COCO Panoptic + COCO Caption	11.0	13.8	28.7	55.3	82.7
MaskCLIP (Zhou et al., 2021)	COCO Panoptic	8.2	10.0	23.7	45.9	-
ODISE (Xu et al., 2023a)	COCO Panoptic	11.1	14.5	29.9	57.3	84.6
FC-CLIP(baseline) (Yu et al., 2023)	COCO Panoptic	14.8	18.2	34.1	58.4	81.8
kNN-FC-CLIP(ours)	COCO Panoptic	**17.4**	**19.9**	**41.3**	**62.8**	**85.3**
Δ *w.r.t baseline*		+2.6	+1.7	+7.2	+4.4	+3.5

4.4 Retrieval Enhances Panoptic Segmentation.

Setup. Our exploration extends to panoptic segmentation, further validating the discernability on instance-level open-vocabulary recognition. We evaluate our method on ADE20K and COCO Panoptic datasets. To assess the performance comprehensively, we employ three critical metrics: Panoptic Quality (PQ), Average Precision (AP), and mean Intersection over Union (mIoU).

Results. As detailed in Table 3, retrieving information from additional support sets dramatically increases performance on ADE20K, with PQ, AP, and mIoU rising by **+2.8**, **+0.7**, **+7.2** respectively without any training. Overall, the performance of open-vocabulary panoptic segmentation can be significantly boosted without any training.

Improving Base Dataset Performance. We highlight that we observed improvements of **+0.4** in PQ, **+0.2** in AP, and **+1.8** in mIoU for COCO Panoptic dataset itself. This highlights that using retrieval even from the baseline model's training dataset, in this case, COCO Panoptic, significantly enhances segmentation accuracy. Our method complements advances in open-vocabulary panoptic segmentation tasks, with these results demonstrating the consistent improvement achieved.

4.5 Retrieval Enhances Semantic Segmentation

Setup. Our study extends studying the impact of training-free continual vocabulary expansion of kNN-CLIP to semantic segmentation, testing it's efficacy across dense prediction tasks. We analyze the performance of kNN-CLIP over five diverse datasets: ADE20K and A847 (Zhou et al., 2019), containing 27K images, Pascal Context(PC)-59/459 (Mottaghi et al., 2014), and Pascal VOC-21 (Everingham et al., 2010) containing 10K images. These datasets include pixel-level annotation on various granularity covering wide-range of semantic concepts from 150, 847, 21, 59, and 459 classes, respectively. We use the same FC-CLIP backbone as in Section 4.1. For all benchmarks, we leverage mIoU metric to evaluate segmentation performance.

Table 5: **Comparisons with Hummingbird.** Our method adopts a similar nearest neighbors retrieval module as Hummingbird but shows significant improvements.

Dataset	Hummingbird	Hummingbird++	kNN-CLIP (Ours)
PASCAL VOC	76.9	77.3	85.3 (+8.0)
ADE20K	35.0	35.8	41.3 (+5.5)

Table 6: **Confidence Threshold and Confidence Weighting Ablations.** Comparisons of different choices of hyper-parameters on A-847.

No. Neighbors (k)	Confidence Weighting	Confidence Threshold	ADE-847 (mIoU)
-	-	-	14.79
16	1.0	0.65	17.28
16	1.2	0.65	17.27
16	1.4	0.65	17.33
16	1.0	0.7	17.43
16	**1.2**	**0.7**	**17.45**
16	1.4	0.7	17.42
16	1.0	0.75	17.35
16	1.2	0.75	17.42
16	1.4	0.75	17.41
16	1.0	0.85	17.25

Results. The effectiveness of our method is clearly demonstrated in Table 4, showcasing significant improvements across various benchmarks. When compared to the baseline FC-CLIP model, we boost mIoU by **+2.6**, **+1.7**, **+7.2**, **+4.4**, **+3.5**, across A-847, PC-459, A-150, PC-59, and PC-21, respectively. With retrieval augmentation, the performance on long-tailed datasets, such as A-847 and PC-459, is generally improved. Our method aims to complement advances in open-vocabulary semantic segmentation and these results underscore the robustness and adaptability of our approach in handling complex segmentation tasks.

4.6 Comparisons with Retrieval-based Approaches

Comparison. We also compare our results with Hummingbird (Balazevic et al., 2024), which proposes a novel pretraining framework that is suitable for fast downstream adaptions. We compare our semantic segmentation results with Hummingbird's best performing model on Pascal VOC and ADE20K. The results of both methods are derived by performing nearest neighbors retrieval from the same evaluated downstream datasets without any further training.

Results. As shown in Table 5, our method outperforms the best Hummingbird model with an increase of **+8.0** and **+5.5** mIoU in PASCAL VOC and ADE20K respectively. The result further showcases the strong performance and fast adaptability of our straightforward method over other retrieval-based approaches.

4.7 Ablations

Effect of Confidence Threshold and Confidence Weightings. We examine the impact of varying hyper-parameter settings on performance, focusing on two key parameters: the confidence threshold and the retrieved confidence weightings. The selection of the confidence threshold is primarily influenced by the accuracy of the kNN retrieval module across different datasets. Our experiments are carried out on the A-847 dataset. As shown in Table 6, the optimal performance, measured in terms of the highest mIoU, is achieved when the confidence threshold, denoted as T in Section 3.2, is set to 0.7, and the confidence weighting, represented by λ in the same section, is set at 1.2.

Effect of Numbers of Neighbors Retrieved. In dense visual tasks, such as semantic segmentation, our approach is to enhance the pseudo classification logits for each query mask by incorporating information from the 16 closest neighbors. Additionally, we conduct experiments to examine the impact of varying the

Table 7: **Number of Retrieved Nearest Neighbors Ablations.** Comparisons of different choices of number of retrieved nearest neighbors on A-847 with $T = 0.7$ and $\lambda = 1.2$.

Number of Neighbors	mIoU
-	14.79 (baseline result)
1	13.77
4	14.84
8	16.60
16	**17.45**
32	17.24
64	16.64

Table 8: **Ablations on Approximate Nearest Neighbors Search.** Comparisons of Inference FPS using Brute Force KNN and HNSW built with efConstruction = 100 and efSearch = 64 for COCO and ADE20K datasets. All results were obtained using a single A40 GPU with CUDA 11.8 and PyTorch 2.0.0. The average runtime was calculated across the entire validation set and includes post-processing time.

	ADE20K		COCO	
method	FPS	mIoU	FPS	mIoU
ODISE	0.41	29.9	0.39	65.2
FC-CLIP	2.86	34.1	2.84	63.7
RA-FC-CLIP (Brute Force)	1.31	41.3 (+7.2)	0.83	65.5 (+1.8)
RA-FC-CLIP(HNSW)	1.52 (×1.16)	34.2 (+0.1)	1.51 (×1.82)	64.5 (+0.8)

number of nearest neighbors retrieved. The results are shown in Table 7. These experiments are carried out using the previously determined optimal hyper-parameters, where T is set to 0.7 and λ is set to 1.2.

Approximate Nearest Neighbors Search. To optimize our inference time, we explore approximate nearest neighbors search algorithms to reduce runtime. We apply Hierarchical Navigable Small World to our feature retrieval module. As expected, we observe a trade-off between inference time and model performance. As in Table 8, it can be seen that adopting HNSW leads to a faster runtime but makes compromises with mIoU. With medium size of support set, such as ADE20K including approximately 220k features, brute force search is preferred; if the size of support set is large, as for COCO, which has 860k features, approximate nearest neighbors search offers better balance between inference time and accuracy.

Inference Time. We assess the inference time based on our implementation of FC-CLIP, taking into account only the time required to infer an image. The retrieval database is preconstructed, ensuring that our evaluation focuses solely on the inference cost. By integrating an additional feature extractor, DINOv2, into the existing architecture, we observe a compromise in inference speed as shown in Table 8. Furthermore, the kNN search module contributes to the slower inference time due to our utilization of brute force search. We observe that inference speed can be enhanced by implementing approximate neighbor search techniques as alternatives to brute force search, but approximate neighbor search leads to a slightly worse performance.

5 Conclusion

In our study, we examine the constraints related to the vocabulary used in earlier open-vocabulary methods that rely on CLIP, and we also highlight how performance diminishes when Vision-Language Models (VLMs) are fine-tuned using downstream annotations. Instead of adopting continual learning approaches, we introduce a novel method called kNN-CLIP, which does not require training and utilizes nearest neighbors retrieval to predict dense visual tasks. To accommodate ever-growing vocabularies, we employ a dynamic retrieval database, circumventing the need for retraining. Our approach demonstrates strong performance across several datasets and showcases significant improvements over other methods.

References

Ivana Balazevic, David Steiner, Nikhil Parthasarathy, Relja Arandjelović, and Olivier Henaff. Towards in-context scene understanding. *Advances in Neural Information Processing Systems*, 36, 2024.

Andreas Blattmann, Robin Rombach, Kaan Oktay, Jonas Müller, and Björn Ommer. Retrieval-augmented diffusion models. *Advances in Neural Information Processing Systems*, 35:15309–15324, 2022.

Sebastian Borgeaud, Arthur Mensch, Jordan Hoffmann, Trevor Cai, Eliza Rutherford, Katie Millican, George Bm Van Den Driessche, Jean-Baptiste Lespiau, Bogdan Damoc, Aidan Clark, et al. Improving language models by retrieving from trillions of tokens. In *International conference on machine learning*, pp. 2206–2240. PMLR, 2022.

Holger Caesar, Jasper Uijlings, and Vittorio Ferrari. Coco-stuff: Thing and stuff classes in context. In *Proceedings of the IEEE conference on computer vision and pattern recognition*, pp. 1209–1218, 2018.

Mathilde Caron, Hugo Touvron, Ishan Misra, Hervé Jégou, Julien Mairal, Piotr Bojanowski, and Armand Joulin. Emerging properties in self-supervised vision transformers. In *Proceedings of the IEEE/CVF international conference on computer vision*, pp. 9650–9660, 2021.

Fabio Cermelli, Matthieu Cord, and Arthur Douillard. Comformer: Continual learning in semantic and panoptic segmentation. In *Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition*, pp. 3010–3020, 2023.

Sungmin Cha, YoungJoon Yoo, Taesup Moon, et al. Ssul: Semantic segmentation with unknown label for exemplar-based class-incremental learning. *Advances in neural information processing systems*, 34: 10919–10930, 2021.

Jun Chen, Deyao Zhu, Guocheng Qian, Bernard Ghanem, Zhicheng Yan, Chenchen Zhu, Fanyi Xiao, Mohamed Elhoseiny, and Sean Chang Culatana. Exploring open-vocabulary semantic segmentation without human labels. *arXiv preprint arXiv:2306.00450*, 2023.

Wenhu Chen, Hexiang Hu, Xi Chen, Pat Verga, and William W Cohen. Murag: Multimodal retrieval-augmented generator for open question answering over images and text. *arXiv preprint arXiv:2210.02928*, 2022a.

Wenhu Chen, Hexiang Hu, Chitwan Saharia, and William W Cohen. Re-imagen: Retrieval-augmented text-to-image generator. *arXiv preprint arXiv:2209.14491*, 2022b.

Bowen Cheng, Anwesa Choudhuri, Ishan Misra, Alexander Kirillov, Rohit Girdhar, and Alexander G Schwing. Mask2former for video instance segmentation. In *CVPR*, 2022.

Jian Ding, Nan Xue, Gui-Song Xia, and Dengxin Dai. Decoupling zero-shot semantic segmentation. In *Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition*, pp. 11583–11592, 2022.

Alexey Dosovitskiy, Lucas Beyer, Alexander Kolesnikov, Dirk Weissenborn, Xiaohua Zhai, Thomas Unterthiner, Mostafa Dehghani, Matthias Minderer, Georg Heigold, Sylvain Gelly, et al. An image is worth 16x16 words: Transformers for image recognition at scale. In *ICLR*, 2021.

Mark Everingham, Luc Van Gool, Christopher KI Williams, John Winn, and Andrew Zisserman. The pascal visual object classes (voc) challenge. *International journal of computer vision*, 88:303–338, 2010.

Golnaz Ghiasi, Xiuye Gu, Yin Cui, and Tsung-Yi Lin. Scaling open-vocabulary image segmentation with image-level labels. In *European Conference on Computer Vision*, pp. 540–557. Springer, 2022.

Kelvin Guu, Kenton Lee, Zora Tung, Panupong Pasupat, and Mingwei Chang. Retrieval augmented language model pre-training. In *International conference on machine learning*, pp. 3929–3938. PMLR, 2020.

Hsuan-An Hsia, Che-Hsien Lin, Bo-Han Kung, Jhao-Ting Chen, Daniel Stanley Tan, Jun-Cheng Chen, and Kai-Lung Hua. Clipcam: A simple baseline for zero-shot text-guided object and action localization. In *ICASSP 2022-2022 IEEE International Conference on Acoustics, Speech and Signal Processing (ICASSP)*, pp. 4453–4457. IEEE, 2022.

Ahmet Iscen, Mathilde Caron, Alireza Fathi, and Cordelia Schmid. Retrieval-enhanced contrastive vision-text models. *arXiv preprint arXiv:2306.07196*, 2023.

Gautier Izacard, Patrick Lewis, Maria Lomeli, Lucas Hosseini, Fabio Petroni, Timo Schick, Jane Dwivedi-Yu, Armand Joulin, Sebastian Riedel, and Edouard Grave. Few-shot learning with retrieval augmented language models. *arXiv preprint arXiv:2208.03299*, 2022.

Chao Jia, Yinfei Yang, Ye Xia, Yi-Ting Chen, Zarana Parekh, Hieu Pham, Quoc Le, Yun-Hsuan Sung, Zhen Li, and Tom Duerig. Scaling up visual and vision-language representation learning with noisy text supervision. In *International conference on machine learning*, pp. 4904–4916. PMLR, 2021.

Tobias Kalb, Björn Mauthe, and Jürgen Beyerer. Improving replay-based continual semantic segmentation with smart data selection. In *2022 IEEE 25th International Conference on Intelligent Transportation Systems (ITSC)*, pp. 1114–1121. IEEE, 2022.

Laurynas Karazija, Iro Laina, Andrea Vedaldi, and Christian Rupprecht. Diffusion models for zero-shot open-vocabulary segmentation. *arXiv preprint arXiv:2306.09316*, 2023.

Urvashi Khandelwal, Omer Levy, Dan Jurafsky, Luke Zettlemoyer, and Mike Lewis. Generalization through memorization: Nearest neighbor language models. *arXiv preprint arXiv:1911.00172*, 2019.

Jin Kim, Jiyoung Lee, Jungin Park, Dongbo Min, and Kwanghoon Sohn. Pin the memory: Learning to generalize semantic segmentation. In *Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition*, pp. 4350–4360, 2022.

Patrick Lewis, Ethan Perez, Aleksandra Piktus, Fabio Petroni, Vladimir Karpukhin, Naman Goyal, Heinrich Küttler, Mike Lewis, Wen-tau Yih, Tim Rocktäschel, et al. Retrieval-augmented generation for knowledge-intensive nlp tasks. *Advances in Neural Information Processing Systems*, 33:9459–9474, 2020.

Boyi Li, Kilian Q Weinberger, Serge Belongie, Vladlen Koltun, and Rene Ranftl. Language-driven semantic segmentation. In *International Conference on Learning Representations*, 2022a.

Junxi Li, Wenhui Diao, Xiaonan Lu, Peijin Wang, Yidan Zhang, Zhujun Yang, Guangluan Xu, and Xian Sun. Sil-land: Segmentation incremental learning in aerial imagery via label number distribution consistency. *IEEE Transactions on Geoscience and Remote Sensing*, 60:1–20, 2022b.

Feng Liang, Bichen Wu, Xiaoliang Dai, Kunpeng Li, Yinan Zhao, Hang Zhang, Peizhao Zhang, Peter Vajda, and Diana Marculescu. Open-vocabulary semantic segmentation with mask-adapted clip. In *Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition*, pp. 7061–7070, 2023.

Hongbin Lin, Yifan Zhang, Zhen Qiu, Shuaicheng Niu, Chuang Gan, Yanxia Liu, and Mingkui Tan. Prototype-guided continual adaptation for class-incremental unsupervised domain adaptation. In *European Conference on Computer Vision*, pp. 351–368. Springer, 2022a.

Zihan Lin, Zilei Wang, and Yixin Zhang. Continual semantic segmentation via structure preserving and projected feature alignment. In *European Conference on Computer Vision*, pp. 345–361. Springer, 2022b.

Haotian Liu, Kilho Son, Jianwei Yang, Ce Liu, Jianfeng Gao, Yong Jae Lee, and Chunyuan Li. Learning customized visual models with retrieval-augmented knowledge. In *Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition*, pp. 15148–15158, 2023a.

Jie Liu, Yanqi Bao, Guo-Sen Xie, Huan Xiong, Jan-Jakob Sonke, and Efstratios Gavves. Dynamic prototype convolution network for few-shot semantic segmentation. In *Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition*, pp. 11553–11562, 2022.

Shilong Liu, Zhaoyang Zeng, Tianhe Ren, Feng Li, Hao Zhang, Jie Yang, Chunyuan Li, Jianwei Yang, Hang Su, Jun Zhu, et al. Grounding dino: Marrying dino with grounded pre-training for open-set object detection. *arXiv preprint arXiv:2303.05499*, 2023b.

Weijie Liu, Peng Zhou, Zhe Zhao, Zhiruo Wang, Qi Ju, Haotang Deng, and Ping Wang. K-bert: Enabling language representation with knowledge graph. In *Proceedings of the AAAI Conference on Artificial Intelligence*, volume 34, pp. 2901–2908, 2020.

Timo Lüddecke and Alexander Ecker. Image segmentation using text and image prompts. In *Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition*, pp. 7086–7096, 2022.

Kenneth Marino, Xinlei Chen, Devi Parikh, Abhinav Gupta, and Marcus Rohrbach. Krisp: Integrating implicit and symbolic knowledge for open-domain knowledge-based vqa. In *Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition*, pp. 14111–14121, 2021.

Umberto Michieli and Pietro Zanuttigh. Continual semantic segmentation via repulsion-attraction of sparse and disentangled latent representations. In *Proceedings of the IEEE/CVF conference on computer vision and pattern recognition*, pp. 1114–1124, 2021.

Roozbeh Mottaghi, Xianjie Chen, Xiaobai Liu, Nam-Gyu Cho, Seong-Whan Lee, Sanja Fidler, Raquel Urtasun, and Alan Yuille. The role of context for object detection and semantic segmentation in the wild. In *Proceedings of the IEEE conference on computer vision and pattern recognition*, pp. 891–898, 2014.

Jishnu Mukhoti, Yarin Gal, Philip HS Torr, and Puneet K Dokania. Fine-tuning can cripple your foundation model; preserving features may be the solution. *arXiv preprint arXiv:2308.13320*, 2023.

Youngmin Oh, Donghyeon Baek, and Bumsub Ham. Alife: Adaptive logit regularizer and feature replay for incremental semantic segmentation. *Advances in Neural Information Processing Systems*, 35:14516–14528, 2022.

Maxime Oquab, Timothée Darcet, Théo Moutakanni, Huy Vo, Marc Szafraniec, Vasil Khalidov, Pierre Fernandez, Daniel Haziza, Francisco Massa, Alaaeldin El-Nouby, et al. Dinov2: Learning robust visual features without supervision. *arXiv preprint arXiv:2304.07193*, 2023.

Matthew E Peters, Mark Neumann, Robert L Logan IV, Roy Schwartz, Vidur Joshi, Sameer Singh, and Noah A Smith. Knowledge enhanced contextual word representations. *arXiv preprint arXiv:1909.04164*, 2019.

Fabio Petroni, Samuel Broscheit, Aleksandra Piktus, Patrick Lewis, Gautier Izacard, Lucas Hosseini, Jane Dwivedi-Yu, Maria Lomeli, Timo Schick, Michele Bevilacqua, et al. Improving wikipedia verifiability with ai. *Nature Machine Intelligence*, 5(10):1142–1148, 2023.

Ameya Prabhu, Zhipeng Cai, Puneet Dokania, Philip Torr, Vladlen Koltun, and Ozan Sener. Online continual learning without the storage constraint. *arXiv preprint arXiv:2305.09253*, 2023a.

Ameya Prabhu, Hasan Abed Al Kader Hammoud, Puneet Dokania, Philip HS Torr, Ser-Nam Lim, Bernard Ghanem, and Adel Bibi. Computationally budgeted continual learning: What does matter? In *CVPR*, 2023b.

Ameya Prabhu, Hasan Abed Al Kader Hammoud, Ser-Nam Lim, Bernard Ghanem, Philip HS Torr, and Adel Bibi. From categories to classifier: Name-only continual learning by exploring the web. *arXiv preprint arXiv:2311.11293*, 2023c.

Alec Radford, Jong Wook Kim, Chris Hallacy, Aditya Ramesh, Gabriel Goh, Sandhini Agarwal, Girish Sastry, Amanda Askell, Pamela Mishkin, Jack Clark, et al. Learning transferable visual models from natural language supervision. In *International conference on machine learning*, pp. 8748–8763. PMLR, 2021.

Ori Ram, Yoav Levine, Itay Dalmedigos, Dor Muhlgay, Amnon Shashua, Kevin Leyton-Brown, and Yoav Shoham. In-context retrieval-augmented language models. *arXiv preprint arXiv:2302.00083*, 2023.

Yongming Rao, Wenliang Zhao, Guangyi Chen, Yansong Tang, Zheng Zhu, Guan Huang, Jie Zhou, and Jiwen Lu. Denseclip: Language-guided dense prediction with context-aware prompting. In *Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition*, pp. 18082–18091, 2022.

Sylvestre-Alvise Rebuffi, Alexander Kolesnikov, Georg Sperl, and Christoph H Lampert. icarl: Incremental classifier and representation learning. In *Proceedings of the IEEE conference on Computer Vision and Pattern Recognition*, pp. 2001–2010, 2017.

Karsten Roth, Latha Pemula, Joaquin Zepeda, Bernhard Schölkopf, Thomas Brox, and Peter Gehler. Towards total recall in industrial anomaly detection. In *Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR)*, pp. 14318–14328, June 2022.

Jie-Jing Shao, Jiang-Xin Shi, Xiao-Wen Yang, Lan-Zhe Guo, and Yu-Feng Li. Investigating the limitation of clip models: The worst-performing categories. *arXiv preprint arXiv:2310.03324*, 2023.

Sheng Shen, Chunyuan Li, Xiaowei Hu, Yujia Xie, Jianwei Yang, Pengchuan Zhang, Zhe Gan, Lijuan Wang, Lu Yuan, Ce Liu, et al. K-lite: Learning transferable visual models with external knowledge. *Advances in Neural Information Processing Systems*, 35:15558–15573, 2022.

Shelly Sheynin, Oron Ashual, Adam Polyak, Uriel Singer, Oran Gafni, Eliya Nachmani, and Yaniv Taigman. Knn-diffusion: Image generation via large-scale retrieval. *arXiv preprint arXiv:2204.02849*, 2022.

Guangchen Shi, Yirui Wu, Jun Liu, Shaohua Wan, Wenhai Wang, and Tong Lu. Incremental few-shot semantic segmentation via embedding adaptive-update and hyper-class representation. In *Proceedings of the 30th ACM international conference on multimedia*, pp. 5547–5556, 2022.

Weijia Shi, Sewon Min, Michihiro Yasunaga, Minjoon Seo, Rich James, Mike Lewis, Luke Zettlemoyer, and Wen-tau Yih. Replug: Retrieval-augmented black-box language models. *arXiv preprint arXiv:2301.12652*, 2023.

Gyungin Shin, Weidi Xie, and Samuel Albanie. Reco: Retrieve and co-segment for zero-shot transfer. *Advances in Neural Information Processing Systems*, 35:33754–33767, 2022.

Shuyang Sun, Runjia Li, Philip Torr, Xiuye Gu, and Siyang Li. Clip as rnn: Segment countless visual concepts without training endeavor. *arXiv preprint arXiv:2312.07661*, 2023.

Vishaal Udandarao, Ankush Gupta, and Samuel Albanie. Sus-x: Training-free name-only transfer of vision-language models. In *Proceedings of the IEEE/CVF International Conference on Computer Vision*, pp. 2725–2736, 2023.

Vishaal Udandarao, Ameya Prabhu, Philip Torr, Matthias Bethge, Adel Bibi, and Samuel Albanie. No "zero-shot" without exponential data: Pretraining concept frequency determines multimodal model performance. *arXiv preprint*, 2024.

Guankun Wang, Long Bai, Yanan Wu, Tong Chen, and Hongliang Ren. Rethinking exemplars for continual semantic segmentation in endoscopy scenes: Entropy-based mini-batch pseudo-replay. *Computers in Biology and Medicine*, 165:107412, 2023a.

Haoxiang Wang, Pavan Kumar Anasosalu Vasu, Fartash Faghri, Raviteja Vemulapalli, Mehrdad Farajtabar, Sachin Mehta, Mohammad Rastegari, Oncel Tuzel, and Hadi Pouransari. Sam-clip: Merging vision foundation models towards semantic and spatial understanding. *arXiv preprint arXiv:2310.15308*, 2023b.

Shuohang Wang, Yichong Xu, Yuwei Fang, Yang Liu, Siqi Sun, Ruochen Xu, Chenguang Zhu, and Michael Zeng. Training data is more valuable than you think: A simple and effective method by retrieving from training data. *arXiv preprint arXiv:2203.08773*, 2022.

Yulin Wang, Gao Huang, Shiji Song, Xuran Pan, Yitong Xia, and Cheng Wu. Regularizing deep networks with semantic data augmentation. *IEEE Transactions on Pattern Analysis and Machine Intelligence*, 44 (7):3733–3748, 2021.

Yuhuai Wu, Markus N Rabe, DeLesley Hutchins, and Christian Szegedy. Memorizing transformers. *arXiv preprint arXiv:2203.08913*, 2022.

Bin Xie, Jiale Cao, Jin Xie, Fahad Shahbaz Khan, and Yanwei Pang. Sed: A simple encoder-decoder for open-vocabulary semantic segmentation. *arXiv preprint arXiv:2311.15537*, 2023.

Jiarui Xu, Shalini De Mello, Sifei Liu, Wonmin Byeon, Thomas Breuel, Jan Kautz, and Xiaolong Wang. Groupvit: Semantic segmentation emerges from text supervision. In *CVPR*, 2022a.

Jiarui Xu, Sifei Liu, Arash Vahdat, Wonmin Byeon, Xiaolong Wang, and Shalini De Mello. Open-vocabulary panoptic segmentation with text-to-image diffusion models. In *Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition*, pp. 2955–2966, 2023a.

Mengde Xu, Zheng Zhang, Fangyun Wei, Yutong Lin, Yue Cao, Han Hu, and Xiang Bai. A simple baseline for open-vocabulary semantic segmentation with pre-trained vision-language model. In *European Conference on Computer Vision*, pp. 736–753. Springer, 2022b.

Mengde Xu, Zheng Zhang, Fangyun Wei, Han Hu, and Xiang Bai. Side adapter network for open-vocabulary semantic segmentation. In *Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition*, pp. 2945–2954, 2023b.

Michihiro Yasunaga, Armen Aghajanyan, Weijia Shi, Rich James, Jure Leskovec, Percy Liang, Mike Lewis, Luke Zettlemoyer, and Wen-tau Yih. Retrieval-augmented multimodal language modeling. *arXiv preprint arXiv:2211.12561*, 2022.

Jeongbeen Yoon, Dahyun Kang, and Minsu Cho. Semi-supervised domain adaptation via sample-to-sample self-distillation. In *Proceedings of the IEEE/CVF Winter Conference on Applications of Computer Vision*, pp. 1978–1987, 2022.

Lu Yu, Bartlomiej Twardowski, Xialei Liu, Luis Herranz, Kai Wang, Yongmei Cheng, Shangling Jui, and Joost van de Weijer. Semantic drift compensation for class-incremental learning. In *Proceedings of the IEEE/CVF conference on computer vision and pattern recognition*, pp. 6982–6991, 2020.

Qihang Yu, Ju He, Xueqing Deng, Xiaohui Shen, and Liang-Chieh Chen. Convolutions die hard: Open-vocabulary segmentation with single frozen convolutional clip. *arXiv preprint arXiv:2308.02487*, 2023.

Wenhao Yu, Chenguang Zhu, Yuwei Fang, Donghan Yu, Shuohang Wang, Yichong Xu, Michael Zeng, and Meng Jiang. Dict-bert: Enhancing language model pre-training with dictionary. *arXiv preprint arXiv:2110.06490*, 2021.

Bo Yuan and Danpei Zhao. A survey on continual semantic segmentation: Theory, challenge, method and application. *arXiv preprint arXiv:2310.14277*, 2023.

Bolei Zhou, Hang Zhao, Xavier Puig, Tete Xiao, Sanja Fidler, Adela Barriuso, and Antonio Torralba. Semantic understanding of scenes through the ade20k dataset. *International Journal of Computer Vision*, 127:302–321, 2019.

Chong Zhou, Chen Change Loy, and Bo Dai. Denseclip: Extract free dense labels from clip. *arXiv preprint arXiv:2112.01071*, 2021.

Lanyun Zhu, Tianrun Chen, Jianxiong Yin, Simon See, and Jun Liu. Continual semantic segmentation with automatic memory sample selection. In *Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition*, pp. 3082–3092, 2023.