FLEET: Unifying Evaluation for Few-Shot NLP

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Abstract

Few-shot NLP research is highly active, yet conducted in disjoint research threads with evaluation suites that lack challenging-yet-realistic testing setups and fail to employ careful experimental design. Consequently, the community does not know which techniques perform best or even if they outperform simple baselines. We formulate desiderata for an ideal few-shot NLP benchmark and present FLEET,[1] the first benchmark, public leaderboard, and framework that provides unified, comprehensive measurement for few-shot NLP techniques. FLEET incorporates and introduces new best practices for few-shot evaluation, including measurement of four transfer settings, textual labels for zero-shot evaluation, and a principled approach to benchmark design that optimizes statistical accuracy while keeping evaluation costs accessible to researchers without large compute resources. We also present UniFew, a simple yet strong baseline model with unified pretraining and finetuning prompt format. UniFew achieves results competitive with popular meta-learning procedures and recent prompt-based approaches, while eschewing their complex machinery.

1 Introduction

Few-shot learning, the challenge of learning from a small number of examples, is critical for developing efficient, robust NLP techniques [65, 72]. In recent years, separate threads of few-shot NLP research have pursued goals like generalization to new classes [e.g., 4, 24], adaptation to new domains and tasks [e.g., 2, 3, 20], and direct application of pretrained language models (LMs) [e.g., 9, 23, 50, 51]. Unfortunately, despite the shared goal of advancing few-shot NLP techniques, the community does not know which techniques work best or even if they perform better than simple baselines. Evaluation suites across these research threads are disjoint, lack challenging-yet-realistic testing setups (e.g., class imbalance, variable training set sizes, etc.), and do not employ careful experimental design to ensure accurate and precise evaluation estimates and minimal computational burden. Prior work in few-shot learning outside of NLP serves as a stark warning of the consequences of improper measurement: Dhillon et al. [18] showed that techniques from several years of prior work did not make clear progress due to large overlapping accuracy distributions and, moreover, do not outperform a simple, carefully-tuned baseline.

As such, a high-quality benchmark is urgently needed to enable rigorous comparison of techniques across disjoint, highly-active threads of few-shot NLP research. But what should such an evaluation suite look like? Some best practices for evaluation of few-shot methods have been introduced in the computer vision (CV) literature [18, 61] and should be applied to NLP. However, unifying few-shot NLP work introduces new challenges. For example, the benchmark needs to test all types of transfer studied in separate research threads to measure progress on new techniques that make gains in each of these important generalization settings (§2). Also, given the importance of zero-shot learning

[1] https://github.com/anonymous.

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Table 1: Comparison of FLEET with closest prior work. FLEET consists of episodes with variable number of shots in the range [1-5] and with class imbalance. "No extra test data" refers to not including validation data with the testing tasks, which can unfairly advantage models that use such data [45]. FLEET's number of test episodes is selected to balance statistical accuracy, which suffers in few-episode setups, and compute requirements, which is too costly in many-episode setups (§5).

	CrossFit[71]	LM-BFF[23]	GPT-3[9]	DS[4]	SMLMT[3]	FewGlue[51]	**FLEET (ours)**
Class Transfer	-	-	-	✓	-	-	✓
Domain Transfer	-	-	-	-	✓	-	✓
Task Transfer	✓	-	-	-	✓	-	✓
Pretraining Transfer	-	✓	✓	-	-	✓	✓
Shots per class	{16, 32}	16	variable	{1,5}	{4,8,16,32}	{total 32}[3]	[1–5]
Variable shots	-	-	✓	-	-	-	✓
Unbalanced	-	-	-	-	-	-	✓
Textual labels	✓	✓	✓	-	-	✓	✓
Zero-shot	-	✓	✓	-	-	-	✓
No extra test data	-	-	-	✓	✓	mixed[4]	✓
# test episodes	5	5	1	1000	10	1	90
Reporting	avg	avg, SD	avg	avg, SD	avg, SD	avg, SD	all[5]
# datasets	160	16	37	7	18	8	20

and learning from task descriptions [28, 67], the benchmark needs to include zero-shot episodes and textual labels to enable measuring progress for models that do not use conventional supervised training, including methods that leverage the latent knowledge in pretrained LMs [9, 23, 74]. Further, the benchmark must accommodate new, computationally-expensive approaches, without overly reducing the number of evaluation episodes at the expense of statistical accuracy [2, 23, 71].

In this paper, we tackle these issues by contributing the following:

- Desiderata (§3) for few-shot NLP benchmarks, which include best practices from CV and introduce new ones that enable unified, comprehensive, low-cost measurement across several disjoint few-shot NLP research threads.
- FLEET (§4)—**F**ew-shot **L**anguag**E** **E**valua**T**ion— a unified benchmark that meets these desiderata. Our benchmark includes the first evaluation protocol that efficiently tests across *four* few-shot transfer settings,[2] and includes a public leaderboard for few-shot NLP that covers 20 datasets across diverse NLP tasks (e.g., NLI, relation classification, entity typing). Table 1 summarizes key differences between FLEET and other few-shot NLP evaluation suites.
- Novel approach to few-shot sample size design (§5) that optimizes for the benchmark's statistical accuracy and precision while keeping computational costs accessible to a broad range of researchers. Our analysis reveals the pitfalls of few-episode designs used in prior works, and demonstrates a principled solution for determining the right balance of episodes to test examples.
- UniFew (§6), a simple but powerful baseline that formats tasks as multiple-choice questions. It achieves results competitive with recent few-shot methods without extensive prompt-engineering or complicated modeling or training techniques.
- An extensible, open-source framework for few-shot NLP model development and benchmark creation, used to train UniFew and produce FLEET. Unlike existing few-shot frameworks, it enables easily adding a wide range of NLP datasets and advanced sampling options.

2 Background and Related Work

We first provide background and notation for few-shot learning and evaluation, then discuss related work in NLP and outside NLP that motivated us to create FLEET.

[2] Prior work evaluated at most two settings.

[3] The total number of training shots in each episode, not number of shots per class per episode.

[4] Most users use unlabeled examples, though recently, Tam et al. [59] do not.

[5] Average (avg), confidence interval (CI), standard deviation (SD), individual episode metrics

Few-Shot Background and Notation Broadly, modern approaches to few-shot learning are evaluated in a three-phase procedure [62]. In the first phase, a general-purpose pretrained model is obtained. In the subsequent "meta-training" phase,[6] techniques aim to adapt the model to be well-suited for few-shot generalization. Finally, a "meta-testing" phase evaluates the adapted model in new few-shot prediction settings.

Let $\mathcal{D}$ be a dataset of (x, y) examples with full label set $\mathcal{Y}_{\mathcal{D}}$. From it, we construct three *sets* of episodes, corresponding to meta-training, meta-validation, and meta-testing and denoted by $\mathcal{E}_{\text{train}}$, $\mathcal{E}_{\text{val}}$, and $\mathcal{E}_{\text{test}}$, respectively. Each episode in each of these sets is a few-shot problem with its own test set and other attributes. Formally, each episode E is a tuple $(\mathcal{D}^E_{\text{train}}, \mathcal{D}^E_{\text{val}}, \mathcal{D}^E_{\text{test}}, \mathcal{Y}^E_{\mathcal{D}})$, where $\mathcal{Y}^E_{\mathcal{D}}$ is a sampled subset of labels in $\mathcal{Y}_{\mathcal{D}}$ and $\mathcal{D}^E_{\text{train|val|test}}$ are disjoint sets of examples from $\mathcal{D}$ with labels in $\mathcal{Y}^E_{\mathcal{D}}$.[7] For each episode, the model's objective is to correctly predict labels for examples $\mathcal{D}^E_{\text{test}}$. To accomplish this, models make use of labeled examples in $\mathcal{D}^E_{\text{train}}$, which is typically configured such that each label i in $\mathcal{Y}^E_{\mathcal{D}}$ has K^E_i provided examples; K^E_i is known as the *shot*, and the setting when a class has no examples in $\mathcal{D}^E_{\text{train}}$ (i.e., $K^E_i = 0$) is called *zero-shot*.

Few-Shot Evaluation in NLP Research in few-shot NLP has proceeded in several parallel threads, each focused on a different type of transfer ability [72]. Each thread has separate evaluation practices, and the vast majority of few-shot NLP research has limited to single type of transfer (see Table 1). Here, we describe these types of transfer and their evaluation practices.

Following CV literature [61, 62], one thread of few-shot NLP focuses on **class transfer**, the problem of generalizing from a supervised set of classes at meta-train time to a different set of classes from the same dataset at meta-test time. Evaluation typically requires splitting classes $\mathcal{Y}_{\mathcal{D}}$ into $\mathcal{Y}^{\mathcal{D}}_{\text{train}}$, $\mathcal{Y}^{\mathcal{D}}_{\text{val}}$ and $\mathcal{Y}^{\mathcal{D}}_{\text{test}}$ disjoint subsets. Class transfer has been studied on many text classification tasks [4], including relation classification [24, 27, 58], intent classification [34, 58], inter alia. In contrast, **domain transfer** keeps the same classes between meta-training and meta-testing but changes the textual domain (e.g., generalizing from MNLI to science-focused SciTail [3, 20]). Evaluation then requires identifying pairs of datasets with the same classes $\mathcal{Y}_{\mathcal{D}}$ where one's episodes are assigned to $\mathcal{E}_{\text{train}}$ and the other's to $\mathcal{E}_{\text{test}}$. Domain transfer has also been studied on many tasks [2, 3], including dialogue intent detection & slot tagging [30], sentiment classification [73], NLI [20], machine translation [26, 53].

Researchers have also begun to study **task transfer**, the problem of generalizing from a set of tasks at meta-train time to unseen tasks at meta-test time. Evaluation requires tasks (e.g., NLI) appearing in $\mathcal{E}_{\text{test}}$ to not appear in $\mathcal{E}_{\text{train}}$ or $\mathcal{E}_{\text{val}}$. Prior work has used GLUE tasks [64] for meta-training before meta-testing on tasks such as entity typing [2, 3], while other work instead used GLUE for meta-testing [20]. Very recent work has studied task transfer over a large set of datasets [71]. A limited amount of work evaluates both domain and task transfer [2, 3, 20]. An important emerging line of work not noted by Yin [72] is **pretraining transfer**, the problem of whether pretrained language models can perform well at meta-test time without any meta-training. Evaluation in this setting requires $\mathcal{E}_{\text{train}}, \mathcal{E}_{\text{val}} = \emptyset$. Prior work has shown that pretrained language models are capable of surprising performance on many few-shot tasks, even without fine-tuning [9]. More recent work, mainly focusing on text classification, has reported further gains with cloze-style formats [50, 51, 59], prompt engineering [23], or calibration [74]. FLEET is designed to exercise all four of these transfer types from previous work.

Few-Shot Evaluation Outside NLP The few-shot learning literature has largely focused on image classification, with the introduction of increasingly complex meta-learning algorithms [e.g., 22, 36, 49, 55, 62]. However, more recent work has shown that simple fine-tuning baselines are in fact competitive, and attribute this delayed discovery to problematic evaluation methodology [14, 18]. FLEET adopts recommended methodology [18, 61], and we introduce an analogous baseline to provide a strong measurement foundation for few-shot NLP.

[6] Meta-training may include a "meta-validation" component, for validating generalization.

[7] In the few-shot literature, $\mathcal{D}^E_{\text{train}}$ and $\mathcal{D}^E_{\text{test}}$ are also called the *support* and *query* sets, and $|\mathcal{Y}^E_{\mathcal{D}}|$ the *way*.

3 Desiderata for Few-Shot NLP Evaluation

We now enumerate key desiderata for a few-shot NLP benchmark capable of solving the urgent problems with few-shot NLP evaluation, including separate evaluations for each transfer type (§2) and failure to incorporate best measurement practices from other domains (§2).

Diversity of transfer types To make NLP models broadly useful, few-shot NLP techniques must be capable of class, domain, and task transfer. Moreover, techniques should make use of the relevant supervision provided during meta-training to increase performance compared to the pretraining transfer setting. The benchmark should measure all four transfer settings to ensure that the community develops techniques that improve on strong pretraining transfer baselines, and enable comparison across these currently separate threads of research.

Variable number of shots and classes To better simulate a variety of real-world scenarios, the benchmark should include a variety of training set sizes and number of classes [61]. Testing robustness to these factors is crucial; few-shot techniques are often sensitive to changes in these factors [11], yet all prior few-shot NLP evaluations we are aware of used a fixed number of training shots and classes, known in advance during meta-training.

Unbalanced training sets The benchmark should also include unbalanced training sets with different training shots per class, another realistic setting adopted by CV benchmarks [61]. Class imbalance has also been observed to degrade performance [10, 41], yet prior few-shot NLP evaluations do not include this setting either.

Textual labels While numerical label values are often used in classification tasks, descriptive textual labels are also present for many tasks. Making these textual labels available for use by few-shot techniques enables the development of techniques that can leverage the class name, like in-context learning [9] and template generation [23]. Textual labels are crucial in particular for zero-shot evaluation.

Zero-shot evaluation We believe zero-shot evaluation is integral to the goals of few-shot evaluation. Similar to the motivation for measuring pretraining transfer, zero-shot evaluation is an important use case and also provides a strong baseline for some tasks. In the absence of training examples, textual class labels or richer task descriptions [68] must be provided. Some recent NLP work [e.g., 9, 23] evaluated with zero training shots, but most [e.g., 2, 4, 71] did not.

No extra meta-testing data We believe the benchmark should *not* provide validation data ($\mathcal{D}^E_{\text{val}} = \emptyset, \forall E \in \mathcal{E}_{\text{test}}$) or unlabeled data for meta-testing tasks, since few-shot learning seeks to enable high performance in environments where collecting additional data is costly.[8] Variation in these dimensions in prior NLP work makes comparison of results extremely difficult because it is often under-reported and gives unfair advantage to approaches that leverage such data [45]. For example, per-episode hyperparameter tuning on extra data has been shown to greatly inflate evaluation scores [23]. Bao et al. [4], Tam et al. [59] follow our suggested approach, but other researchers have used many other settings, from validation sets of various sizes [9, 23] to no validation set but a large set of unlabeled examples [50, 51].

Principled sample size design Promising few-shot techniques can incur significant computational cost per episode, e.g., due to fine-tuning model parameters [3], searching for prompts [23], inter alia. To alleviate these costs, related works often evaluate with a limited number of episodes, which precludes statistically accurate or precise performance estimates. We believe the benchmark's test sample size should be optimized to enable proper performance evaluation for such techniques, while ensuring the computational burden is inclusive toward researchers without large compute resources.

Proper reporting of CIs, SDs, and individual results The benchmark should report confidence intervals (CIs) of performance estimates and follow recent guidelines [18] to report standard deviations (SDs) for understanding variability. Moreover, we newly advocate for controlling for the *same* sampled few-shot episodes across all methods and reporting individual episode results, so that researchers can run higher-powered paired statistical tests when comparing results [21], crucial when the benchmark has been optimized for low evaluation budgets.

[8] Unlabeled data collection can be costly too, e.g. due to manual filtering [15].

4 The FLEET Benchmark

FLEET is a unifying, rigorous benchmark for few-shot learning in NLP, which implements the desiderata outlined in the previous section. In this section, we describe detailed design decisions and our few-shot NLP framework (§4.4), which we are releasing to facilitate easily adding NLP datasets and advanced sampling options to future benchmarks.

4.1 Task and Dataset Selection

Following GLUE [64] and other prior work [2, 4, 23, 74], we focus on tasks formatted as classification. Despite recent advances, NLP state-of-the-art models remain significantly worse than human performance on many text classification tasks, particularly in the few-shot setting. Automatic scoring of classification tasks is also more reliable than text generation tasks.

We selected datasets across three recent few-shot NLP evaluation suites, which separately studied class transfer [4], domain and task transfer [2, 3], and pretraining transfer [23]. FLEET includes a broad mix of tasks (NLI, question classification, entity typing, relation classification, and sentiment analysis) and formats (document, sentence, sentence pair). More complete dataset and license details are available in subsequent subsections and Appendix A.

4.2 Meta-Evaluation Protocols

As discussed earlier, FLEET evaluates four different types of transfer: Class, Domain, Task and Pretraining Transfer. To support all types, we report results to the FLEET benchmark both *without* meta-training (pretraining-only) and *with* meta-training. This reporting scheme evaluates the performance of the basic pretrained model and the benefit (or lack thereof) of meta-training. A similar reporting scheme was proposed by Triantafillou et al. [61].

Pretraining-Only In this setting, the pretrained model is directly meta-tested on FLEET without any additional training. This is the *Pretraining Transfer* setting, and it is the most difficult, but given the recent success of pretrained models in NLP for few-shot learning [9, 23], we believe that comparison to models without any meta-training is important for NLP tasks.

Meta-Trained In this setting, the model is meta-trained then meta-tested on FLEET. We carefully selected and split datasets across meta-train/validation/test in order to enable testing of Class, Domain, and Task transfer with a single meta-training phase (to reduce computational burden). Datasets involved in each transfer setting (detailed split information in Table 4 in Appendix A):

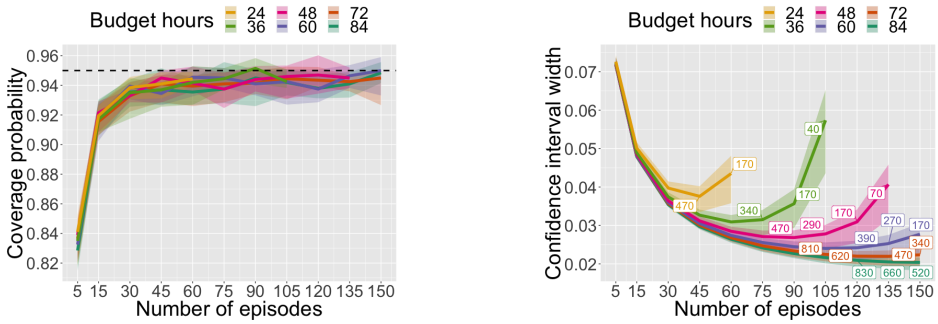
- *Class Transfer*: FewRel [27], HuffPost [40], Amazon [29], 20News [35], and Reuters [38] take part in meta-training and meta-testing but with different classes.
- *Domain Transfer*: MR [44], CR [31], SNLI [8], and SciTail [33] are only in the meta-testing phase, but the corresponding sentiment and NLI datasets exist in the meta-training phase (MNLI [69], QNLI [47], and SST-2 [56]).
- *Task Transfer*: Subj [43], TREC [63], and CoNLL [60] are also for meta-testing only, and they represent tasks that the model does not encounter during meta-training.

Instead of per-episode hyperparameter tuning, we provide meta-validation episodes $\mathcal{E}_{\text{val}}$ for learning (during meta-training) global hyperparameters that work across all episodes. Specifically, the meta-validation dataset splits (see Table 4) consist of CoLa [66] for task transfer, WNLI [37] for domain transfer, and the validation splits used by Bao et al. [4] for all class transfer datasets. Following [2], we also include meta-training datasets MRPC [19], RTE [5, 7, 16, 25], and QQP [64].

4.3 Episode Sampling

We describe how FLEET samples meta-testing episodes $\mathcal{E}_{\text{test}}$. For meta-training, we allow users to sample from $\mathcal{E}_{\text{train}}$, $\mathcal{E}_{\text{val}}$ in any way, or directly use the underlying dataset splits.

Number of classes For Class Transfer datasets, FLEET aims to evaluate model robustness to a variable number of classes. When constructing episode E from one of these datasets $\mathcal{D}$, FLEET samples an episode-specific number of classes from dataset D, the sampler picks a random number



(a) Coverage probability of 95% CIs.

(b) Mean width of 95% CIs.

Figure 1: Results of simulation study described in §5. Each curve corresponds to a compute budget constraint C (GPU-hours). Each point on a curve is an allocation of test data between the number of test episodes $|\mathcal{E}_{\text{test}}|$ or mean number of examples per episode $\overline{|\mathcal{D}_{\text{test}}|}$ such that evaluation can be completed within given budget. Per curve, lower values of $|\mathcal{E}_{\text{test}}|$ correspond linearly to larger values of $\overline{|\mathcal{D}_{\text{test}}|}$, which are shown as numerical text annotations in (b). Error bars represent the 10th and 90th percentile values from repeated simulations across $\mu_{acc} \in \{0.3, 0.35, \ldots, 0.95\}$.

from the range $\mathcal{Y}_{\mathcal{D}}^{E} \sim \text{Unif}(5, \min(|\mathcal{Y}_{\mathcal{D}}|, 10))$.[9] For Domain and Task Transfer, the number of classes is fixed to the maximum number of classes because Class Transfer is not being evaluated.

Number of shots Following prior work outside NLP [42, 61], FLEET samples the training shot independently for each episode E and class i, as $K_i^E \sim \text{Unif}(K_{\min}, K_{\max})$, where $K_{\min} = 1$. Given strong performance of NLP models with few or even zero examples [9, 68] and following prior work [4], we set the limit $K_{\max} = 5$. Separately, we allocate an equal number of episodes as zero-shot, where we instead set $\mathcal{D}_{\text{train}}^{E} = \emptyset$ (equivalently, $K_i^E = 0, \forall i$).

4.4 Extensible Framework for Benchmark Creation and Model Training & Evaluation

Alongside the FLEET benchmark, we release an extensible, highly-configurable Python framework, which we used to generate FLEET (and earlier benchmarks), and train and evaluate our models. Unlike existing meta-learning frameworks (e.g., Torchmeta [17], learn2learn [1]), our framework makes available a wide range of community-contributed NLP datasets and utilities via HuggingFace Datasets [70][10]. Our code also provides advanced sampling utilities (e.g., for class imbalance), ensures reproducibility by checksumming generated episodes, and reports all recommended statistics.

5 Sample Size: Balancing Statistical Measurement and Computational Cost

We demonstrate a principled approach to determining the optimal sample size configuration in our few-shot benchmark. A proper benchmark should produce performance estimates that are *accurate*, close to the true value, and *precise*, low variance. A large (test) sample size can achieve this, yet must be considered alongside computational cost so that a broad community of researchers with differing amounts of compute resources can participate. This decision is further complicated in the few-shot setting, where sample size refers to both the number of test episodes $|\mathcal{E}_{\text{test}}|$ and the number of test examples $|\mathcal{D}_{\text{test}}^{E}|$ per episode $E \in \mathcal{E}_{\text{test}}$. For practicality, we consider $\overline{|\mathcal{D}_{\text{test}}|}$, the mean $|\mathcal{D}_{\text{test}}^{E}|$ across all episodes, rather than every $|\mathcal{D}_{\text{test}}^{E}|$. It remains unknown how one should best distribute test examples between $|\mathcal{E}_{\text{test}}|$ and $\overline{|\mathcal{D}_{\text{test}}|}$: More episodes each with fewer examples, or fewer episodes each with many examples? Prior work has been inconsistent in this regard. For example, Gao et al. [23] used $|\mathcal{E}_{\text{test}}| = 5$ and large $\overline{|\mathcal{D}_{\text{test}}|}$, while Bao et al. [4] used $|\mathcal{E}_{\text{test}}| = 1000$ and much smaller $\overline{|\mathcal{D}_{\text{test}}|}$.

Inspired by simulation techniques for informing statistically-powered experimental design [12], we study how different configurations of $|\mathcal{E}_{\text{test}}|$ and $\overline{|\mathcal{D}_{\text{test}}|}$ across different compute budgets C impact the

[9] We limit to 10 classes to avoid undue burden on in-context approaches that fit examples in memory [9], and use a lower bound of 5 classes to match prior work [4].

[10] Apache License 2.0. Full license details for all software dependencies available in Appendix H.

accuracy and precision of our estimated CIs, specifically with respect to *coverage probability* [48] and *width*. First, we estimate per-episode and per-test-example costs of our few-shot baseline (§6) to obtain valid $(C, |\mathcal{E}_{\text{test}}|, \overline{|\mathcal{D}_{\text{test}}|})$ configurations s.t. the full benchmark completes within given C (GPU-hours).[11] Then, for each $(C, |\mathcal{E}_{\text{test}}|, \overline{|\mathcal{D}_{\text{test}}|})$, we perform 1000 simulation runs, in which each run samples predictions under a true model accuracy μ_{acc} and computes a single 95% CI, its width, and whether it correctly covers μ_{acc}. Averaging over simulation runs gives us estimates for the coverage probability and width of our benchmark's CI for a single $(C, |\mathcal{E}_{\text{test}}|, \overline{|\mathcal{D}_{\text{test}}|})$. We repeat this whole procedure for different $\mu_{acc} \in \{0.3, 0.35, \ldots, 0.95\}$ to cover a wide range of possible model performances observed across many datasets (see Table 3).

Figure 1 shows CI coverage probability and width for many $(C, |\mathcal{E}_{\text{test}}|, \overline{|\mathcal{D}_{\text{test}}|})$ configurations. First, we find in Figure 1a that sufficiently-many test episodes (i.e. $|\mathcal{E}_{\text{test}}| > 60$) is needed to guarantee coverage probability of our CIs is within one percentage point of the target 95%, a trend that holds regardless of compute budget. Small $|\mathcal{E}_{\text{test}}|$ also corresponds to large CI widths across all considered budgets in Figure 1b. This suggests that the choices of $|\mathcal{E}_{\text{test}}| = 1, 5, 10$ in prior work [3, 23, 51, 71] can mean inaccurate and wide CIs, while choices of $|\mathcal{E}_{\text{test}}| = 1000$ [4] can be prohibitively costly for methods with high training cost.

Next, Figure 1b reveals (i) diminishing returns in CI width (decrease in y-axis) as compute increases, and (ii) existence of an optimal balance between $|\mathcal{E}_{\text{test}}|$ and $\overline{|\mathcal{D}_{\text{test}}|}$ for each budget. Restricting our consideration to budgets with optima satisfying $|\mathcal{E}_{\text{test}}| > 60$, the minimum viable budget is 36 GPU-hours. Then, assessing the marginal benefit of each 12 GPU-hour budget increase in terms of marginal reduction in CI width between optima, we arrive at our FLEET configuration of $|\mathcal{E}_{\text{test}}| = 90$ and $\overline{|\mathcal{D}_{\text{test}}|} \approx 470$ under a budget of $C = 48$ GPU-hours.[12] Further details are in Appendix B.

6 UniFew: A Simple yet Powerful Baseline

Despite their encouraging results, existing works on few-shot learning are based on either customized and often complex meta-learning algorithms [2, 3, 4, 54], heavy engineering of textual descriptions or prompts [23, 50, 74], ordering of training examples [39, 51], extensive hyperparameter tuning on held-out sets [23, 39, 50], or custom learning algorithms [50, 59]. We present UniFew, a strong baseline across *all* transfer settings and datasets tested, that eschews the need for incorporating the above-mentioned complexities and challenges.

UniFew is a prompt-based model [51], a class of models that tailor the input/output format of their data to match the format used during pretraining. While this technique allows them to perform a task without the need for additional classification layers, prompt-based models are typically sensitive to the choice of the prompts, which can require extensive search, trial-and-error, and even additional models to get right [23, 74]. To avoid this issue while still leveraging the strong capabilities of pretrained models, UniFew (1) converts examples into multiple-choice question-answer (QA) format, and (2) uses UnifiedQA [32], a T5 [46] model further pretrained on a large collection of QA pairs.[13,14]

Compared to other prompt-based models, UniFew has two main strengths. First, the prompt design problem is much simpler because UnifiedQA questions had well-defined formats. For example, we need only two prompt templates to cover 19 of the 20 datasets in FLEET, while prior works have needed specialized prompts for each dataset. Second, UnifiedQA's multiple-choice format ensures the model outputs a valid class label, without the need for learned or manually-defined mappings required for other prompt-based methods [23, 50].[15]

[11] Costs estimated using a Quadro RTX-8000 GPU with 48Gb memory. For few-shot settings, model was trained with 300 steps. Per-episode and per-test-example costs were approx. 95–98 and 0.7–0.11 GPU-sec, respectively. Using a model with high per-episode cost for this analysis allows us to define a lower-bound sample size requirement; we can always test inexpensive or zero-shot models on more $|\mathcal{E}_{\text{test}}|$ or $\overline{|\mathcal{D}_{\text{test}}|}$ within budget.

[12] Consider budget increases $36 \rightarrow 48$, $48 \rightarrow 60$, $60 \rightarrow 72$ and $72 \rightarrow 80$. The first reduces CI width by 13%. Further increases reduce CI width by an additional 9%, 7%, and 5%, respectively. We choose $C = 48$ based on these diminishing returns.

[13] UnifiedQA and T5 both use Apache License 2.0. We use publicly-released large-size model weights.

[14] None of the supervised datasets in the pretraining of UnifiedQA or T5 are in FLEET.

[15] In rare cases, especially for zero-shot, UnifiedQA may generate an invalid answer (e.g., "Yes, Yes, No" instead of "Yes"). We use simple heuristics to normalize the answer in such cases.

Table 2: Comparing UniFew with prior methods on their respective test suites reporting mean accuracy (and standard deviation). For each test suite, for each result set on same number of shots, we indicate with ▷ when results are directly comparable: (i) either both use meta-training (H-SMLMT & DS with $\text{UniFew}_{\text{meta}}$) or neither do (LM-BFF with UniFew). We **bold** the better of the two.

(a) H-SMLMT (Bansal et al. [3])

Model	Shots	CNLL	SciT
▷ H-SMLMT	4	57.6 ±7.1	76.8 ±3.4
UniFew	4	76.6 ±2.6	65.1 ±9.9
▷ $\text{UniFew}_{\text{meta}}$	4	**79.7** ±2.8	**85.4** ±2.5
▷ H-SMLMT	8	70.2 ±3.0	79.1 ±1.1
UniFew	8	80.6 ±3.7	70.9 ±5.2
▷ $\text{UniFew}_{\text{meta}}$	8	**81.2** ±3.8	**86.8** ±1.4
▷ H-SMLMT	16	80.6 ±2.8	80.4 ±1.4
UniFew	16	85.8 ±1.9	76.7 ±4.6
▷ $\text{UniFew}_{\text{meta}}$	16	**87.9** ±1.9	**85.4** ±2.5

(b) LM-BFF (Gao et al. [23])

Model	Shots	CR	MR	SNLI	Subj	TREC
▷ $\text{LM-BFF}_{\text{man}}$[16]	0[17]	**79.5**	**80.8**	49.5	**51.4**	**32.0**
▷ UniFew	0	78.8	74.8	**54.4**	50.3	15.0
$\text{UniFew}_{\text{meta}}$	0	92.1	90.5	83.8	56.8	39.1
▷ LM-BFF	16/16[18]	91.0 ±0.9	**87.7** ±1.4	**77.5** ±3.5	**91.4** ±1.8	**89.4** ±1.7
▷ UniFew	16/16	**92.2** ±0.8	87.2 ±0.1	75.6 ±1.5	84.6 ±5.4	86.7 ±0.3
$\text{UniFew}_{\text{meta}}$	16/16	92.7 ±0.4	90.2 ±0.8	84.9 ±0.5	87.6 ±2.0	86.1 ±0.4

(c) Distributional Signature (Bao et al. [4])

Model	Shots	Amzn†	Frel†	HuffP†	20N†	Reut†
▷ DS	1	62.7 ±0.7	67.1 ±0.9	43.1 ±0.2	52.2 ±0.7	81.8 ±1.6
UniFew	1	82.1 ±8.5	75.7 ±13.2	65.9 ±13.4	58.4 ±11.6	92.0 ±8.3
▷ $\text{UniFew}_{\text{meta}}$	1	**84.3** ±8.9	**90.6** ±6.2	**78.6** ±6.9	**70.3** ±9.1	**96.9** ±2.5
▷ DS	5	81.2 ±0.3	83.5 ±0.3	63.5 ±0.1	68.3 ±0.2	96.0 ±0.3
UniFew	5	88.5 ±7.4	88.8 ±6.5	77.1 ±6.0	72.2 ±8.4	97.0 ±2.8
▷ $\text{UniFew}_{\text{meta}}$	5	**90.5** ±5.9	**93.1** ±4.4	**81.7** ±5.2	**76.2** ±7.1	**98.0** ±2.0

We experiment with UniFew both without and with meta-training on FLEET's meta-training data. We call the meta-trained variant $\text{UniFew}_{\text{meta}}$. Details about prompts and training are in Appendix C and D, respectively.

7 Experiments

Comparing UniFew with Prior Work To demonstrate the efficacy of UniFew, we evaluate it against state-of-the-art approaches for few-shot and meta-learning in NLP: LM-BFF [23], a language model prompt-based fine-tuning method, and Distributional Signatures (DS) [4] and H-SMLMT [3], two state-of-the-art meta-learning techniques. Refer to Appendix E for details on these methods.

We compare to these methods using the datasets in FLEET to establish the quality of our baseline on our benchmark. Since we constructed FLEET from disjoint subsets of datasets evaluated in each of these prior works (§4.1), we compare each method with its corresponding subset of datasets. Each of these prior works evaluates their methods using different experimental setups (classes, number of episodes, shots) than FLEET and was not designed to handle FLEET's challenging episode characteristics like class imbalance. To enable fair comparison, we test UniFew on the exact data splits released by the authors when available (H-SMLMT and LM-BFF). For DS, we sample (balanced) episodes using our framework after matching their test settings (number of shots and classes, class splits, etc.) and reproduce their reported results to within 1% absolute difference using their model code; we use these episodes for our experiments. The results in Table 2 show that $\text{UniFew}_{\text{meta}}$

[16] Gao et al. [23]'s automatic prompt search and in-context learning are not available in the zero-shot setting, so they instead use manually-designed prompts.

[17] Zero-shot results from Gao et al. [23] are on the entire test set, so there is no reported standard deviation.

[18] 16/16 denotes 16 shots for training plus 16 more for validation which we only use for early stopping while Gao et al. [23] use for grid-search hyperparameter tuning.

Table 3: Mean accuracies of UniFew and UniFew$_{\text{meta}}$ on FLEET in zero and few-shot settings.

	Zero-shot				Few-shot				
	Class	Domain	Task	Overall	Class	Domain	Task	Overall	Δ_{few} (Overall)
UniFew	44.6	59.2	35.0	47.1	71.1	64.9	48.3	63.3	+16.2
UniFew$_{\text{meta}}$	75.6	87.6	41.1	71.0	80.2	86.8	62.4	77.9	+6.9
Δ_{meta}	+30.7	+27.2	+7.7	+23.9	+8.5	+21.1	+9.1	+14.6	

outperforms both H-SMLMT and DS meta-learning approaches by relatively large margins, while achieving competitive results compared with LM-BFF. Note that UniFew's strong results are without meta-learning approaches, extensive prompt-engineering, or per-episode hyperparameter search.

Evaluating UniFew on FLEET Having established UniFew as a strong model comparable to recent, state-of-the art techniques, we present its baseline results on the final version of FLEET (with class imbalance, etc.). From Table 3, we observe three findings. First, pretraining is an effective technique for infusing an NLP model with the ability to perform few-shot generalization even without any meta-training, as UniFew is able to score $\Delta_{\text{few}} = +16.2$ higher when provided few examples. Second, by comparing UniFew$_{\text{meta}}$ and UniFew, we see that meta-training has a substantial impact on zero-shot performance ($\Delta_{\text{meta}} = +23.9$), but its benefit, while still significant, is less in the few-shot setting ($\Delta_{\text{meta}} = +14.6$). Third, while meta-training adds roughly the same benefit to zero and few-shot performance for both domain and task transfer settings, meta-training disproportionately benefits zero-shot class transfer ($\Delta_{\text{meta}} = +30.7$) over few-shot class transfer ($\Delta_{\text{meta}} = +8.5$). Such observations are made possible through unified evaluation and comparison across different transfer types. The full FLEET results broken down by individual datasets are in Appendix G.

8 Limitations and Future Work

Ultimately, we believe that a few-shot NLP benchmark should measure the abilities of language models on a variety of task formats. While FLEET is currently limited in its focus solely on classification, we aim to use our new framework (§4.4) to incorporate additional task formats like span selection or text generation.

In addition, our sample size analysis (§5) currently uses simulations that are not based on a representative sample of many techniques, instead focusing on our own available training estimates. We plan to gather compute estimates from community submissions to FLEET to refine our configurations.

Our public leaderboard currently provides limited support for detailed comparisons between submissions based on properties of techniques. For example, approaches may vary in terms of model characteristics (e.g., number of parameters), data and supervision used during pretraining, amount of compute, etc. We encourage users of FLEET to report all these factors to enable the community to analyze and make progress on important sub-spaces in the overall few-shot technique design space.

Finally, we believe the benefits of improving few-shot NLP techniques outweigh potential risks, but we acknowledge potential harms associated with language models [6, 13, 52, 57]. We provide more discussion in Appendix I.

9 Conclusion

We introduce FLEET, the first benchmark and public leaderboard that provides a systematic, unified measurement of few-shot NLP. It incorporates and introduces new best practices for few-shot evaluation, including four transfer settings, textual labels for zero-shot evaluation, and novel analysis for determining a sample size that optimizes statistical accuracy and precision while keeping computational burden low. Along with the benchmark, we present UniFew, a simple and strong baseline that achieves results competitive with recent few-shot methods despite using trivial prompt engineering. Finally, we release an extensible, open-source framework (used to train UniFew and generate FLEET) that enables addition of NLP datasets and advanced sampling options to future benchmarks.

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Checklist

1. For all authors...
   (a) Do the main claims made in the abstract and introduction accurately reflect the paper's contributions and scope? [Yes]
   (b) Did you describe the limitations of your work? [Yes] See Section 8.
   (c) Did you discuss any potential negative societal impacts of your work? [Yes] See Section 8 and Appendix I.
   (d) Have you read the ethics review guidelines and ensured that your paper conforms to them? [Yes]
2. If you are including theoretical results...
   (a) Did you state the full set of assumptions of all theoretical results? [N/A]
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   (a) Did you include the code, data, and instructions needed to reproduce the main experimental results (either in the supplemental material or as a URL)? [Yes]
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