Layer Grafted Pre-training: Bridging Contrastive Learning And Masked Image Modeling For Better Representations

Abstract

Recently, both Contrastive Learning (CL) and Mask Image Modeling (MIM) demonstrate that self-supervision is powerful to learn good representations. However, naively combining them is far from success. In this paper, we start by making the empirical observation that a naive joint optimization of CL and MIM losses leads to conflicting gradient directions - more severe as the layers go deeper. This motivates us to shift the paradigm from combining loss at the end, to *choosing the proper learning method per network layer*. Inspired by experimental observations, we find that MIM and CL are suitable to lower and higher layers, respectively. We hence propose to combine them in a surprisingly simple, "sequential cascade" fashion: early layers are first trained under one MIM loss, on top of which latter layers continue to be trained under another CL loss. The proposed *Layer Grafted* Pre-training learns good visual representations that demonstrate superior label efficiency in downstream applications, in particular yielding strong few-shot performance besides linear evaluation. For instance, on ImageNet-1k, Layer Grafted Pre-training yields 65.5% Top-1 accuracy in terms of 1% few-shot learning with ViT-B/16, which improves MIM and CL baselines by 14.4% and 2.1% with no bells and whistles. Our code will be released upon acceptance.

1 Introduction

Self-supervision has demonstrated undoubted power in learning strong visual representation, with two mainstream representative methods: Contrastive learning (CL) (Chen et al., 2020b; He et al., 2020; Chen et al., 2020d; 2021; Grill et al., 2020; Caron et al., 2021), and Mask Image Modeling (MIM) (Bao et al., 2021; He et al., 2021; Xie et al., 2022; Dong et al., 2021; 2022). The two methods follow different mechanisms, and often reflect different strengths. In general, CL performs the instance level task that pulls augmented views from the same image to be similar while pushing different images to distribute diversely, making it good at learning strong semantic alignment. In contrast, MIM draws inspiration from BERT (Devlin et al., 2018) and performs masked token or pixel reconstruction that helps it to learn rich local structures within the image. Although the latter one, MIM, has recently surpassed CL on the fine-tuning performance of many datasets, CL often remains to be a top competitor in data-scarce, few-shot downstream applications (Chen et al., 2020c;d; Tian et al., 2020).

A natural following question then arises: *are CL and MIM indeed complementary to each other, and is there a way to best combine their strengths?*. One immediate, conceptually simple idea is to refer to multiple task learning (MTL) and jointly optimize the two losses on top of the same backbone. Unfortunately, our preliminary experiment (See Section 2.2) shows that such a vanilla combination fails to improve over either baseline, in fact often compromising the single loss's performance. A deeper dive reveals that the two losses, when being optimized together, will incur increasingly severe conflicts in the gradient directions, as the layers go deeper (see Figure 1). That causes considerable hurdles for the (pre-)training to effectively proceed.

We are then inspired to ask: *if the two losses conflict when both are placed at the end, how about placing them differently, such as appending them to different layers?* Based on experimental observations, it appears that lower layers tend to learn better from the MIM loss in order to capture

local spatial details; while higher layers tend to benefit more from the CL loss in order to learn semantically-aware grouping and invariance. Inspired by so, we propose a simple MIM→CL Grafting idea to combine the bests of both worlds: (step i) first training the lower layers with MIM loss and fixing their weights, on top of which (step ii) higher layer weights continue to be trained under another CL loss. This simple cascaded training idea neatly separates MIM and CL losses to avoid their conflicts against each other if placed together; each loss is also strategically placed to pre-training its most suitable portion. Practically, we "'smooth out" the grafting by allowing lower layers to be slowly tuned in step ii. Our ablation experiments also find that **the order of grafting matters**, i.e., reversing MIM/CL loss locations and performing MIM→CL will considerably damage the performance. The contributions of this paper are summarized as follows:

- We propose Layer Grafted Pre-training, a simple yet principled framework to merge MIM and CL, improving representation learning beyond both, with no bells and whistles.

- We investigate the different preferences of lower and higher layers towards CL and MIM losses, and show the order of grafting to matter.

- Despite its embarrassing simplicity, the proposed Layer Grafted Pre-training demonstrates more desirable representation quality, and consequently superior label efficiency in downstream applications, yielding strong few-shot performance besides linear evaluation. For example, we achieve [65.5%, 77.6%, 77.5%] in terms of [1% few-shot, 10% few-shot, linear evaluation] performance, improving over MIM and CL baselines by [14.4%, 4.3%, 9.5%] and [2.1%, 2.2%, 0.8%], respectively.

2 METHOD

2.1 PRELIMINARY AND OVERVIEW

Contrastive Learning. In Contrastive Learning (CL), the learning target is to pull the positive pairs together in the feature space while pushing negative pairs apart. Formally, the loss can be defined as:

$$\mathcal{M}(v_i, v_i^+, V^-, \tau) = \frac{1}{N} \sum_{i=1}^{N} -\log \frac{\exp\left(v_i \cdot v_i^+/\tau\right)}{\exp\left(v_i \cdot v_i^+/\tau\right) + \sum_{v_i^- \in V^-} \exp\left(v_i \cdot v_i^-/\tau\right)} \tag{1}$$

where (v_i, v_i^+) represents features of the positive pairs while (v_i, v_i^-) means features of negative pairs. Also, V^- is the pool of negative features. τ denotes the temperature. N is the number of samples. In practice, the positive pairs are often the different augmented views from the same image while the negative pool is composed by all the views from different images (Chen et al., 2021).

Mask Image Modeling. Mask Image Modeling (MIM) learns to reconstruct a corrupted image where some parts of the image or feature map are masked out. The learning target can be formulated as:

$$\mathcal{L}(x_i, M) = \frac{1}{N} \sum_{i=1}^{N} D(d(f(Mx_i)), x_i) \tag{2}$$

where x_i and M are input images and randomly generated masks, respectively. f and d represent the encoding and decoding function, respectively. $d(f(Mx_i))$ is the generated image conditioned by masked image Mx_i. D measures the difference between $d(f(Mx_i))$ and the original image x_i.

Overview. In the following parts of this section, we first introduce our preliminary exploration on the MTL of MIM and CL tasks in Section 2.2, which reveals the existence of the conflicting gradient direction. Afterward, in Section 2.3, we provide a simple separating idea towards mitigating the conflicts, which further leads to the proposed Layer Grafted Pre-training in Section 2.4.

2.2 CONFLICTS PREVENT MULTI-TASK LEARNING FROM WORKING

Our first step towards answering the question whether CL and MIM can complement each other is to examine the most straightforward and conceptually simple idea - Multi-Task Learning (MTL)

Figure 1: The box plot of $\mathbf{C}_{\text{MIM,CL}}(x)$ across different blocks for MTL combination of MIM and CL. This is measured on training datasets when the network is trained to 100 epochs (total 300 epochs). The red dash line indicates the linear regression of median numbers.

combination. Specifically, CL and MIM are performed once on a shared weight backbone in each iteration. Both losses are added together to update the network.

As summarized in Table 1, MTL combination only yields a marginally performance improvement of 0.4% on linear evaluation compared to MIM baseline. However, it is still much lower that the CL baseline (-8.3%). Moreover, on both 1% few-shot and fine-tuning performance, MTL combination decreases both MIM and CL baselines. Similar observations have also been made at Wang et al. (2022a).

We further conjecture that the conflicts between these two targets in the MTL combination is the cause of the bad performance. To verify it, we design a gradient surgery experiment by computing the cosine similarity between gradients of two tasks following Yu et al. (2020). Formally, the cosine similarity is calculated as follows:

$$\mathbf{C}_{\text{MIM,CL}}(x) = \frac{\nabla_\theta L_{\text{MIM}}(x)^T}{\|\nabla_\theta L_{\text{MIM}}(x)\|} \frac{\nabla_\theta L_{\text{CL}}(x)}{\|\nabla_\theta L_{\text{CL}}(x)\|} \tag{3}$$

where L_{MIM} and L_{CL} denote the losses for MIM and CL, respectively. x is a batch of input samples. We measure the distribution of $\mathbf{C}_{\text{MIM,CL}}(x)$ across different layers of a pre-trained MTL model. As shown in Figure 1, there always exist negative values for $\mathbf{C}_{\text{MIM,CL}}(x)$, where the MIM and CL are optimized in opposite directions. Moreover, the gradient direction varies across layers - more severe as layers go deeper.

Also, the conflicts can be reflected in the contradictory enforcing targets. The MIM loss , for instance, requires that the reconstruction to have the same brightness, color distribution, and positions as the input image, therefore the model needs to be sensitive to all these augmentations. Conversely, CL loss is designed to ensure that the model remains invariant regardless of different augmentations.

2.3 Addressing the Conflicts via Separating

Given the conflicts of the MTL combination, we ask the following question: *if the two losses conflict when both are placed at the end, how about placing them differently, such as appending them to different layers?* Fortunately, recent empirical evidence suggests that CL and MIM may favor different pre-training methods. For MIM, Wang et al. (2022c) points out that, when only the pre-trained lower layers are retained while the higher layers are reset to random initialization, most of the gain is still preserved for downstream fine-tuning tasks. Based on this observation, the lower layers appear to be a key element in MIM. On the other hand, Chen et al. (2021) finds CL to be ineffective and even unstable for training the projection layer, the earliest layer of ViT Dosovitskiy et al. (2020). Fixing its weight to be random initialization can even yield a significantly higher per-

Figure 2: The pipelines of the MIM→CL, CL→MIM Grafting, and Layer Grafted Pre-training. The former two are employed for preliminary experiments. The latter one is the final adopt pipeline, which is the 'smooth out' version of MIM→CL Grafting.

Table 1: Illustration of preliminary study experiments' performance on ViT-B/16. Linear, 1% and Fine-tuning denote linear evaluation, 1% few-shot and fine-tuning performance, respectively. The performance of MIM and CL are from MAE (He et al., 2021) and MocoV3 (Chen et al., 2021), respectively. MTL combination denotes the Muti-Task Learning (MTL) Combination of MIM and CL. MTL combination is pretrained for 300 epochs. For step 1 of MIM→CL and CL→MIM Grafting, we directly adopt the pre-trained model of MAE and MoCo V3, respectively. The step 2 of MIM→CL and CL→MIM Grafting is trained for 100 epochs.

Method	Linear	1%	Fine-tuning
MIM (MAE)	68.0	51.1	83.6
CL (Moco V3)	76.7	63.4	83.2
MTL combination	68.4	47.6	81.0
CL→MIM Grafting	65.5	32.5	82.5
MIM→CL Grafting	74.5	56.5	83.6

formance. Additionally, CL excels at semantic concepts, which happen often at higher layers of the neural network.

Driven by the above analysis, we propose a simple MIM→CL Grafting framework. As shown in Figure 2, MIM→CL Grafting can be separated into two steps: (step i) the lower layers are first trained with MIM and then fixed, on the top of which (step ii) higher layers continue to learn with CL. Despite the simplicity of this framework, it yields promising preliminary results as shown in Table 1, exceeding the MTL combination by [6.1%, 8.9%, 2.6%] for [linear evaluation, 1% few-shot, Fine-tuning] performance, respectively. In contrast, when the order of two tasks is reversed, the resulting CL→MIM Grafting, would suffer a dramatic drop in performance, which is even lower than the MTL combination by [2.9%, 15.1%] in terms of [linear evaluation, 1% few-shot] performance, respectively. The huge gap between CL→MIM and MIM→CL Grafting further confirms the preference of MIM and CL towards lower and higher layers, respectively.

The example discussed at the end of Section 2.2 can also explain why this preference difference happens: The two different prior knowledge types requested by MIM and CL, while seemingly at odds, may work together at different layers of the model. For example, the sensitivity to augmentations can be helpful for recognizing the local feature with strong color patterns (Xiao et al., 2020) in the lower layers (i.e. the fur of leopards). Meanwhile, for a consistent semantic understanding, the influence of the lightness difference should be eliminated when it comes to understanding the context feature at higher layers.

2.4 Layer Grafted Pre-training

To fully unleash the power of Grafting, we 'smooth out' the boundary of MIM→CL grafting to avoid a sudden change in the feature space. Specifically, rather than fixing the lower layers, we assign them a small learning rate. The resultant method, termed as Layer Grafted Pre-training, is shown in Figure 2. In Section 3.3, we also explore other LR choices and our results indicate that employing small and large LR for lower and higher layers, respectively, yields the best performance.

By effectively capturing the augmentation-sensitive features (i.e. the colors) in the lower layers with MIM while learning semantic alignment in the higher layers with CL. The proposed Layer Grafted Pre-training enables the learning of strong visual representations. It not only provides strong inter-class variance that helps to cluster but also benefits the intra-class variance by keeping the diversity of samples in the early features.

3 Experiment

3.1 Setting

General. We conduct all the experiment on ImageNet-1k (Deng et al., 2009) with Nvidia V100 GPUs. The code is implemented with Pytorch (Paszke et al., 2019).

Backbone. We adopt the standard ViT-B and ViT-L architecture (Dosovitskiy et al., 2020) with the token size of 16×16. The ViT-B is by default employed unless specified. When training with CL loss, we employ the projection and prediction head following Moco V3 (Chen et al., 2021).

Pre-training. We by default adopt MAE (He et al., 2021) and Moco V3 (Chen et al., 2021) as our MIM and CL frameworks, respectively. For the first step of Layer Grafted Pre-training, since it identically follows the original MIM pipeline, we directly adopt the pre-trained model of MAE (He et al., 2021) and conduct the second step. where we initialize the network with the MIM pre-trained model and train with Moco V3 (Chen et al., 2021) for 300 epochs. For LR, We first split the network into three stages. Each of them contains the same number of blocks. (i.e. 4 and 8 blocks for ViT-B and ViT-L, respectively.) Then, the base LR of the first and second stages (corresponding to lower layers) is assigned as 1.5e-5 while the third stage is set as 1.5e-4 by default. Other settings are identically followed from Moco V3 (Chen et al., 2021).

Fine-tuning. For fine-tuning, we train with AdamW (Loshchilov & Hutter, 2017) for 100 epochs following MAE (He et al., 2021). We employ a base LR of 5e-4 with linear scaling rule (Goyal et al., 2017). The layer-wise LR decay ratio is set as 0.6 (Clark et al., 2020). For other settings like employed data augmentation, LR scheduling, weight decay, etc. We identically follow He et al. (2021).

Few-shot Learning. We conduct few-shot learning with 1% or 10% available labels. The sub-sampling splits are adopted from Chen et al. (2020c). For 1% few-shot evaluation, following Caron et al. (2021), we first generate frozen features on training images without data augmentation, on top of which a logistic regression classifier is trained for prediction. For 10% semi-supervised learning, we train from the first layer of the projection head following Chen et al. (2020c). We train for 400 epochs with an initial base LR of 3e-5. Other settings are identical to the fine-tuning.

Linear Evaluation. For linear evaluation, we train a linear classifier on top of frozen pre-train features to measure the quality of the visual representations following common practices (Chen et al., 2020b). Following Moco V3 (Chen et al., 2021), the classifier is trained for 90 epochs with SGD optimizer and weight decay of 0. The LR is swept for each case.

3.2 Comparison with State-of-The-Art Methods

We start by verifying the effectiveness of the proposed Layer Grafted Pre-training by comparing it with State-Of-the-Art methods. As shown in Table 2, in ViT-B/16, compared to the employed MIM and CL baselines, the proposed Layer Grafted Pre-training leads to a consistent improvement. For instance, it improves MAE and Moco V3 by [9.5%, 14.4%, 4.3%] and [0.8%, 2.1%, 2.2%] for [linear evaluation, 1% few-shot, 10% few-shot], respectively.

Table 2: Comparison with State-of-The-Art methods on ViT-B/16 and ViT-L/16. Linear, 1% and 10% denote the top1 accuracy (%) of linear evaluation, 1% and 10% few-shot learning, respectively. †: We employ the result of iBoT without augmentations from Zhou et al. (2021) for a fair comparison.

BackBone	Method	Linear	1%	10%
ViT-B/16	MAE (He et al., 2021)	68.0	51.1	73.3
	Moco V3 (Chen et al., 2021)	76.7	63.4	75.4
	iBoT† (Zhou et al., 2021)	76.0	-	-
	SIM (Tao et al., 2022)	76.4	65.3	-
	Layer Grafted Pre-training (Ours)	**77.5**	**65.5**	**77.6**
ViT-L/16	MAE (He et al., 2021)	75.8	55.2	78.7
	Moco V3 (Chen et al., 2021)	77.6	-	-
	Layer Grafted Pre-training (Ours)	**80.5**	**68.9**	**79.8**

(a) Moco V3   (b) Layer Grafted Pre-training

Figure 3: t-SNE (Van der Maaten & Hinton, 2008) visualization for feature distribution of Moco V3 and the proposed Layer Grafted Pre-training. Different colors represent different classes. Best view in color.

Compared to close competitors which also attempt to combine MIM and CL, the proposed Layer Grafted Pre-training surpasses iBoT by 1.5% for linear evaluation performance. Compared to SIM, the proposed Layer Grafted Pre-training yields an improvement of 1.1% and 0.2% for linear evaluation and 1% few-shot learning performance, respectively.

Our method also demonstrates the good scalability toward larger models size. For instance, when scaling from ViT-B/16 to ViT-L/16, the proposed Layer Grafted Pre-training further improves accuracy by [3%, 3.4%, 2.2%] in terms of [linear evaluation, 1% few-shot, 10% few-shot], respectively. Remarkably, the gap above Moco V3 in linear evaluation performance also increases from 0.8% to 2.9%.

We further qualitatively evaluate the representations learned by the proposed Layer Grafted Pre-training using t-SNE (Van der Maaten & Hinton, 2008). As shown in Figure 3b, the proposed Layer Grafting shows better inter-class variance. For example, the categories represented by pink (•) and light blue (•) points are hard to separate given they are very close with each other in Figure 3a. In contrast, for representation of the proposed Layer Grafted Pre-training, they form two clusters with a clear boundary in Figure 3b. Besides, the proposed Layer Grafted Pre-training also shows better intra-variance: the red (•), green (•) and yellow (•) points of Moco V3 collapse to a smaller region than the proposed Layer Grafted Pre-training.

3.3 LR SEARCH LAYER GRAFTED PRE-TRAINING

We further verify if small and large LR work the best for the proposed Layer Grafted Pre-training. Specifically, we study the performance with different LR settings on the three stages on ViT-B/16 (Refer to fine-tuning part of Section 3.1 for the definition of stages), where each stage is

(a) Linear, 3rd Stage LR: 1.5e-4   (b) Linear, 3rd Stage LR: 1.5e-5   (c) Linear, 3rd Stage LR: 1.5e-6

(d) Tuning, 3rd Stage LR: 1.5e-4   (e) Tuning, 3rd Stage LR: 1.5e-5   (f) Tuning, 3rd Stage LR: 1.5e-6

Figure 4: Illustration of the LR grid search results for different stages in terms of linear evaluations and fine-tuning performance. The grid is [1.5e-6,1.5e-5,1.5e-4] for each stage. [(a), (b), (c)] and [(d), (e), (f)] denotes the linear evaluation and fine-tuning performance with third stage LR of [1.5e-4, 1.5e-5, 1.5e-6], respectively. [(a), (b)] and [(e), (f)] share the same color bar with (c) and (g), respectively. That of (d), (e) and (f) are also the same. The tested point is highlighted with blue dots in each plot. Best view in color.

searched with a grid of [1.5e-6,1.5e-5,1.5e-4]. As demonstrated in Figure 4, when the LR increase from 1.5e-6 to 1.5e-4 for the third stage, both linear evaluation and fine-tuning performance achieve an improvement. Taking linear evaluation as an example, as shown in Figure 4a, 4b and 4c, when the LR of the third stage increase from 1.5e-6 to 1.5e-5 and 1.5e-4, the performance range could improve from 2.5%-63.0% to 64.8%-70.9% and 73.7%-75.1%, respectively.

In contrast, a big LR of the first stage would lead a drop in performance. For instance, in terms of the linear evaluation performance with third stage LR of 1.5e-4, as shown in Figure 4a, the performance ranges are 74.9%-75.1%, 74.8%-75.0% and 73.7%-73.8% for first stage LR of 1.5e-6, 1.5e-5 and 1.5e-4, respectively. The LR of the second stage is not as sensitive as that of the first or third stage. The trend of fine-tuning

Table 3: Top 1 Fine-tuning performance comparison on ViT-B/16.

Method	Fine-tuning
MAE (He et al., 2021)	83.6
Moco V3 (Chen et al., 2021)	83.2
SIM (Tao et al., 2022)	83.8
Layer Grafted Pre-training (Ours)	**83.9**

performance is also similar to that of the linear evaluation performance. The preference for larger LR for higher layers indicates that they can benefit by performing CL. Meanwhile, lower layers prefer a smaller LR means that keeping MIM features for these layers can be helpful.

3.4 MORE ABLATIONS

Fine-tuning Performance Comparison. We also compare State-of-The-Art methods for fine-tuning performance. As shown in Table 3, the proposed Layer Grafted Pre-training yields a competitive fine-tuning performance of 83.9%, which is 0.3% and 0.7% higher than the employed MIM (MAE) and CL (Moco V3) baselines, respectively. Moreover, Layer Grafted Pre-training also surpasses SIM by 0.1%.

Partial Fine-tuning. Follow MAE (He et al., 2021), we evaluate the performance of the proposed Layer Grafted Pre-training with different number of fixing blocks. As illustrated in Figure 5, Layer Grafted Pre-training consistently yields higher performance than MAE. And this gap continue to grow larger when more layers are fixed, indicating the superiority of the representations learned by the proposed method.

Variance-Invariance-Covariance Analysis. A study of the Variance-Invariance-Covariance pattern for the output of each block is conducted in order to better understand the Layer Grafted Pre-training. As illustrated in Figure 6, we find that the VIC pattern of Layer Grafted Pre-training tends to be similar to that of fine-tuning. In the MAE case, the VIC curve of Layer Grafted Pre-training closely matches that of MAE Fine-tune, much closer than MAE itself. The similarity between the proposed

Figure 5: Comparison between the proposed Layer Grafted Pre-training and MAE under different number of fixing blocks on ViT-B/16 in terms of fine-tuning performance. The training dataset is the full ImageNet-1k. Best view in color.

Layer Grafted Pre-training and fine-tuning in the VIC pattern also explains the high few-shot performance: weights of the pre-training do not need to change substantially to match the downstream task.

Layer Grafted Pre-training with VICReg. We further examine the transferability of the proposed Layer Grafted Pre-training on a different pre-training method - VICReg. As shown in Table 4, when combined with VICReg, the proposed Layer Grafted Pre-training still yields strong performance, surpassing the baseline by [4.8%, 2.4%] for [linear evaluation, fine-tuning] performance, respectively.

Figure 6: The Variance-Invariance-Covariance (VIC) analysis for different methods. VIC are computed on ViT-B/16 following Bardes et al. (2021). The input features are first averaged over all tokens and then normalized to remove the effect from magnitude. [(a), (d)], [(b), (e)] and [(c), (f)] study variance, covariance and invariance, respectively. Best view in color.

Table 4: Layer Grafted Pre-training on ViT-B/16 with VICReg (Bardes et al., 2021). We train ViT-B/16 with VICReg for 100 epochs as the baseline. For Layer Grafted Pre-training - VICReg, the CL loss of stage ii is replaced with VICReg loss.

Method	Linear	Fine-tuning
VICReg (Bardes et al., 2021)	70.1%	81.2%
Layer Grafted Pre-training - VICReg (Ours)	74.9%	83.6%

4 RELATED WORKS

Contrastive Learning. CL performs instance classification tasks by contrasting positive pairs against negative pairs (Chen et al., 2020b; He et al., 2020; Zhuang et al., 2019; Dosovitskiy et al., 2014). Other close works also explore learning without negative samples (Grill et al., 2020; Bardes et al., 2021; Caron et al., 2021; Zbontar et al., 2021; Chen & He, 2021) and the clustering based approachs (Caron et al., 2020).

One common merit of these methods is their strong performance on learning good representations, which shows strong clustering pattern (Dwibedi et al., 2021) and leads to state-of-the-art few-shot/semi-supervised performance (Chen et al., 2020c; Tian et al., 2020; Li et al., 2021). However, they contain an implicit assumption that the features should be invariant to heavy augmentations, which, however, could further lead to worse performance when the downstream performance violates it (Xiao et al., 2020). The proposed Layer Grafting address this via leveraging MIM for processing the features of lower layers.

Mask Image Modeling. Mask Image Modeling (MIM) is inspired by the success of BERT (Devlin et al., 2018) in Natural Language Processing (NLP). iGPT (Chen et al., 2020a) begins the exploration of this idea in Computer Vision (CV). The emergence of ViT (Dosovitskiy et al., 2020) further shrinks the gap of backbones between CV and NLP, motivating more researchers to delve into this direction. Beit (Bao et al., 2021; Peng et al., 2022), MaskFeat (Wei et al., 2022) and Peco (Dong et al., 2021) focus on predicting tokens. MAE (He et al., 2021) and simMIM (Xie et al., 2022) further show the possibility of directly reconstructing the original pixels. Following works (Dong et al., 2022; Chen et al., 2022; Wang et al., 2022b) continue to improve the performance or extend to other modalities. However, MIM achieves the most success in fine-tuning with enough data points. For downstream tasks with limited data, MIM fails to surpass CL given the lack of linear separability for its representations (Tao et al., 2022). We address this drawback by employing CL for learning the semantic alignment for higher layers.

Bridging Contrastive Learning and Mask Image Modeling. Only recently, researchers begin to explore the potential of combining MIM and CL. iBoT (Zhou et al., 2021), one of the pioneers in this direction, proposes to switch the modeling of images to the modeling of features. Some concurrent works also follow this self distillation paradigm (Tao et al., 2022; Assran et al., 2022). However, just like CL, this paradigm still relays on the involvement of strong augmentations to avoid collapsing, which could lead to over-suppressing of some features (i.e. color) (Xiao et al., 2020). In contrast, we employ MAE (He et al., 2021), an image modeling framework that is free from strong augmentations. Besides, previous combination works treat the network as a whole while we provide a new layer-wise perspective.

5 CONCLUSION

In this work, we propose Layer Grafted Pre-training, a simple yet principled method for bridging two types of self-supervised learning methods - Mask Image Modeling (MIM) and Contrastive Learning (CL). Our work provides a simple remedy to the conflicts between MIM and CL and further reveals the different preferences of these two methods towards different parts of the neural network. It advances the quality of the self-supervised representations and achieves strong performance on linear evaluation and few-shot performance. Potential future work includes extending the proposed method to real-world unsupervised datasets with more challenges like long-tail distribution, fairness issues and adversarial attacks.

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