Dueling Bandits with Adversarial Sleeping

Abstract

We introduce the problem of sleeping dueling bandits with stochastic preferences and adversarial availabilities (DB-SPAA). In almost all dueling bandit applications, the decision space often changes over time; eg, retail store management, online shopping, restaurant recommendation, search engine optimization, etc. Surprisingly, this 'sleeping aspect' of dueling bandits has never been studied in the literature. Like dueling bandits, the goal is to compete with the best arm by sequentially querying the preference feedback of item pairs. The non-triviality however results due to the non-stationary item spaces that allow any arbitrary subsets items to go unavailable every round. The goal is to find an optimal 'no-regret' policy that can identify the best available item at each round, as opposed to the standard 'fixed best-arm regret objective' of dueling bandits. We first derive an instance-specific lower bound for DB-SPAA $\Omega(\sum_{i=1}^{K-1} \sum_{j=i+1}^{K} \frac{\log T}{\Delta(i,j)})$, where K is the number of items and $\Delta(i,j)$ is the gap between items i and j. This indicates that the sleeping problem with preference feedback is inherently more difficult than that for classical multi-armed bandits (MAB). We then propose two algorithms, with near optimal regret guarantees. Our results are corroborated empirically.

1 Introduction

The problem of *Dueling-Bandits* has gained much attention in the machine learning community [34, 38, 36], which is an online learning framework that generalizes the standard multiarmed bandit (MAB) [6] setting for identifying a set of 'good' arms from a fixed decision-space (set of arms/items) by querying preference feedback of actively chosen item-pairs. More formally, in dueling bandits, the learning proceeds in rounds: At each round, the learner selects a pair of arms and observes stochastic preference feedback of the winner of the comparison (duel) between the selected arms; the objective of the learner is to minimize the regret with respect to a (or set of) 'best' arm(s) in hindsight. Towards this several algorithms have been proposed [2, 37, 21, 14]. Due to the inherent exploration-vs-exploitation tradeoff of the learning framework and several advantages of preference feedback [9, 35], many real-world applications can be modeled as dueling bandits, including movie recommendations, retail management, search engine optimization, job scheduling, etc.

However, in reality, the decision spaces might often change over time due to the non-availability of some items, which are considered to be 'sleeping'. This 'sleeping-aspect' of online decision making problems has been widely studied in the standard multiarmed bandit (MAB) literature [17, 24, 15, 19, 18, 11]. There the

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Parameters. Item set: $[K]$ (known), Preference: $\mathbf{P}$ (unknown), Available item sets: $\mathcal{S}_T$ (observed sequentially)
For $t = 1, 2, \ldots, T$, the learner:
- Observes $S_t \subseteq [K]$ the set of available items
- Chooses $(x_t, y_t) \in S_t^2$
- Observes $o_t := \mathbf{1}(x_t \succ y_t) \sim \mathrm{Ber}(\mathbf{P}(x_t, y_t))$
- Incurs $r_t := \frac{1}{2}(\mathbf{P}(i_t^*, x_t) + \mathbf{P}(i_t^*, y_t) - 1)$;
    where i_t^* is such that $\min_{j \in S_t} \mathbf{P}(i_t^*, j) \geq \frac{1}{2}$

Figure 1: Setting of DB-SPAA$(\mathbf{P}, \mathcal{S}_T)$

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goal is to learn a 'no-regret' policy that maps to the 'best awake item' of any available (non-sleeping) subset of items, and the learner's performance is measured with respect to the optimal policy in hindsight. This setting is famously known as *Sleeping Bandits* in MAB [17, 24, 15, 11]. More discussions are given in Related Works.

Surprisingly, however, the *'sleeping problem'* is completely unaddressed in the preference bandits literature, even for the special case of pairwise preference feedback, which is famously studied as *Dueling Bandits* [37, 34], even though the setup of changing decision spaces are quite relevant in almost every practical applications: Be that in retail stores where some items might go out of production over time, for search engine optimization some websites could be down on certain days, in recommender systems some restaurants might be closed or movies could be outdated, in clinical trials certain drugs could be out of stock, and many more. This work is the first to consider the problem of *Sleeping Dueling Bandits*, where we formulated the stochastic K-armed dueling bandit problem with adversarial item availabilities. Here at each round $t \in \{1, 2, \ldots, T\}$ the item preferences are considered to be generated from a fixed underlying (and of course unknown) preference matrix $\mathbf{P} \in [0,1]^{K \times K}$, however, the set of available actions $S_t \subseteq \{1, 2, \ldots, K\}$ is assumed to be adversarially chosen by the environment. We call the problem as *Sleeping-Dueling Bandit with Stochastic Preferences and Adversarial Availabilities* or in brief DB-SPAA($\mathbf{P}, \mathcal{S}_T$), where $\mathcal{S}_T = \{S_1, S_2, \ldots S_T\}$ denotes the sequence of available subsets over T rounds. We also assume the preference $\mathbf{P}$ follows a 'total-ordering assumption to ensure the existence of a best-item per available subset S_t. We describe the setting in Fig. 1 with a formal description in Sec. 2. Our specific contributions are as follows:

1. We first analyze the fundamental performance limit for the DB-SPAA($\mathbf{P}, \mathcal{S}_T$) problem in Sec. 3: Thm. 1 gives an instance-specific regret lower bound of

$$\Omega\big(\textstyle\sum_{i=1}^{K-1} \sum_{j=i+1}^{K} \frac{\log T}{\Delta(i,j)}\big),$$

with $\Delta(i,j)$ being the 'preference gap' of item i-vs-j (see Eqn. (2)). Our lower bound, which can be of order $\Omega(K^2 \log T / \Delta)$, $\Delta := \min_{i,j} \Delta(i,j)$ being the worst case gap, indicates that the *problem of sleeping dueling bandits is inherently more difficult that standard sleeping bandits (MAB)*, unlike the 'non-sleeping' case where both dueling bandits (with 'total-ordering' assumption on $\mathbf{P}$) and MAB are known to have the same fundamental performance limit of $\Omega(K \log T / \Delta)$ (Rem. 1).

2. We introduce an optimal algorithm S1DB-UCB (Alg. 1) which matches our lower bound (Thm. 3). It is inspired from the pairwise upper confidence bound (UCB) based algorithm [37]. However due to the 'adversarial-sleeping' nature of the problem, we need to separately maintain pairwise confidence bounds per item (based on the availability sequence $\{S_t\}$), and also introduce the idea of itemwise 'dominance-sets' which makes the resulting algorithm and its subsequent analysis significantly different than standard UCB based dueling bandit algorithms (see Rem. 2, Sec. 4).

3. In Sec. 5, we design another simple to implement and even more computationally efficient algorithm for DB-SPAA($\mathbf{P}, \mathcal{S}_T$), S1DB-ED (Alg. 2). Unlike the previous algorithm (S1DB-UCB), S1DB-ED uses empirical divergence (ED) based measures to filter out the 'good' set of arms, inspired from the idea of RMED algorithm of [21] for standard dueling bandits; however, due to sleeping nature of the items, it requires a different maintenance of 'good' arms and the regret analysis of the algorithm requires derivation of new results (as described in Sec. 5). The algorithm is shown to perform near optimally with an expected *non-asymptotic* regret upper-bound of $O\big(\min\big\{KT^{2/3}, \sum_{j=2}^{K} \frac{K \log T}{\Delta(j-1,j)}\big\}\big)$ (Thm. 8). Note that for any problem instance with constant suboptimality gaps $\Delta(i,j) = \Delta$ for all $i < j$, regret bound of S1DB-ED is tight and matches the lower-bound ensuring the near optimality of S1DB-ED in the worst case. Furthermore, a novelty of our finite time regret analysis lies in showing a cleaner tradeoff between regret vs. availability sequence $\mathcal{S}_T$ which automatically adapts to the inherent 'hardness' of the sequence of available subsets $\mathcal{S}_T$, compared to existing sleeping bandits work for adversarial availabilities in the MAB setting [19] which only gives a worst-case regret bound over all possible availability sequences (Rem. 3).

4. Finally we corroborate our theoretical results with extensive empirical evaluations. (Sec. 6).

Related Works. The problem of regret minimization for stochastic multiarmed bandits (MAB) is extremely well studied in the online learning literature [6, 1, 22, 5, 16], where the learner gets to see a noisy draw of absolute reward feedback of an arm upon playing a single arm per round.

A well motivated generalization of MAB framework is *Sleeping Bandits* [17, 24, 18, 15], much studied in the online learning community, where at any round the set of available actions could vary

stochastically based on some unknown distributions over the decision space of K items [24, 11] or adversarially [15, 19, 18]. Besides the reward model, the set of available actions could also vary stochastically or adversarially [17, 24]. The problem is NP-hard when both rewards and availabilities are adversarial [19, 18, 15]. In case of stochastic reward and adversarial availabilities [19] proposed an UCB based no-regret algorithm, which was also shown to be provably optimal. The case of adversarial reward and stochastic availabilities has also been studied where the achievable regret lower bound is known be $\Omega(\sqrt{KT})$ by the inefficient EXP4 algorithm [19, 15].

On the other hand over the last decade, the relative feedback variants of stochastic MAB problem has seen a widespread resurgence in the form of the Dueling Bandit problem, where, instead of getting noisy feedback of the reward of the chosen arm, the learner only gets to see a noisy feedback on the pairwise preference of two arms selected by the learner. The objective of the learner is to minimize the regret with respect to 'best arm in the stochastic model. Several algorithms have been proposed to address this dueling bandits problem, for different notions of 'best arms' or preference models [10, 31, 38, 37, 36, 21, 33, 13], or even extending the pairwise preference to subsetwise preferences [29, 8, 26, 27, 25]. However, surprisingly, unlike the 'sleeping bandits generalization' of MAB, no parallel has been drawn for dueling bandits, which remains our main focus.

2 Problem Formulation

Notations. Decision space (or item/arm set) $[K] := \{1, 2, \ldots, K\}$. The available set of items at round t is denoted by $S_t \subseteq [K]$. For any matrix $\mathbf{M} \in \mathbb{R}^{K \times K}$, we define $m_{ij} := M(i,j)$, $\forall i, j \in [K]$. We write $S_{\setminus i} = S \setminus \{i\}$, for any $S \subseteq [K]$ and $i \in S$. $\mathbf{1}(\cdot)$ denotes the indicator random variable which takes value 1 if the predicate is true and 0 otherwise and $\lesssim$ a rough inequality which holds up to universal constants. For any two items $x, y \in [K]$, we use the symbol $x \succ y$ to denote x is preferred over **y**. $\mathbf{\Sigma}_K$ denotes the set of all permutations of the items in set $[K]$. The KL-divergence of two Bernoullis with biases p and q respectively is written $\mathrm{kl}(p, q) := p \log(p/q) + (1 - p) \log((1-p)/(1-q))$. We assume $\frac{0}{0} := 0.5$ (in Alg. 1 and 2).

Setup. We consider the problem of stochastic K-armed dueling bandits with adversarial availabilities: At every iteration $t = 1, \ldots, T$, a set of available items (actions) $S_t \subseteq [K]$ is revealed, and the learner is asked to choose two items $x_t, y_t \in S_t$. Then, the learner receives a preference feedback $o_t = \mathbf{1}(x_t \succ y_t) \sim \mathrm{Ber}(\mathbf{P}(x_t, y_t))$, where $\mathbf{P} \in [0, 1]^{K \times K}$ is an underlying pairwise preference matrix, unknown to the learner. The setting is described in Figure 1. We assume that $\mathbf{P}$ respects a *'total ordering'*, say $\boldsymbol{\sigma}^* \in \mathbf{\Sigma}_K$: More formally, assuming $\boldsymbol{\sigma}^* = (1, 2, \ldots, K)$ without loss of generality, this implies $\forall i \in [K-1]$ and $j \in \{i+1, \ldots, K\}$, $\mathbf{P}(\sigma_i^*, \sigma_j^*) > 0.5$. One possible pairwise probability model which respects *'total ordering'* is Plackett-Luce [7], where it is assumed that the K items are associated to positive score parameters $\theta_1, \ldots, \theta_K$, and $\mathbf{P}(i, j) = \theta_i/(\theta_i + \theta_j)$ for all $i, j \in [K]$. In fact any well random utility (RUM) based preference model would have the above property, like [7, 28]. Note also that our assumption corresponds to assuming the existence of a Condorcet winner for every subset $S_t \subseteq [K]$.

Objective. The objective of the learner is to minimize his regret over T rounds with respect to the best policy in the policy class $\Pi = \{\pi : 2^K \mapsto [K] \mid \forall t \in [T],\ \pi(S_t) \in S_t\}$, i.e. any $\pi \in \Pi$ is such that for any $t \in [T]$, $\pi(S_t) \in S_t$. More formally we define the regret as follows:

$$R_T = \max_{\pi \in \Pi} \sum_{t=1}^{T} \frac{\mathbf{P}(\pi(S_t), x_t) + \mathbf{P}(\pi(S_t), y_t) - 1}{2}. \tag{1}$$

It is easy to note that under our preference modelling assumptions, the best policy, say π^*, turns out to be $\pi^*(S) = \arg\min\{i \in [K] \mid \sigma_i^* \in S\}$, for any $S \subseteq [K]$. We henceforth denote by $i_t^* = \pi^*(S_t)$. We define the above problem to be *Sleeping-Dueling Bandit with Stochastic Preferences and Adversarial Availabilities* over the stochastic preference matrix $\mathbf{P} \in [0, 1]^{K \times K}$ and the sequence of available subsets $\mathcal{S}_T = \{S_1, \ldots, S_T\}$, or in short DB-SPAA$(\mathbf{P}, \mathcal{S}_T)$. For ease of notation we respectively define the gaps and the non-zeros gaps as $\Delta(i, j) := \mathbf{P}(i, j) - 1/2$, and

$$\Delta(i, j)_+ := \begin{cases} \Delta(i, j) & \text{if } \Delta(i, j) \neq 0 \\ +\infty & \text{if } \Delta(i, j) = 0 \end{cases} \tag{2}$$

The regret thus can be rewritten as $R_T := \sum_{t=1}^{T} r_t$, where $r_t := (\Delta(i_t^*, x_t) + \Delta(i_t^*, y_t))/2$ denotes the instantaneous regret. We also denote by $n_{ij}(t) := \sum_{\tau=1}^{t} \mathbf{1}(\{x_t, y_t\} = \{i, j\})$ the number of times the pair (i, j) is played until time t and by $w_{ij}(t)$ the number of times i beats j in t rounds.

3 Lower Bound

We first derive a worst case regret lower bound over all possible sequences of $\mathcal{S}_T$. The proof idea essentially lies in constructing *hard enough* availability sequences $\mathcal{S}_T$, where no learner can escape learning the preferences of every distinct pair of items (i, j). This leads to a potential lower bound of $\Omega\big(K^2 \log(T)/\Delta\big)$. For this section we denote $\mathbf{P}$ by $\mathbf{P}_K$ to make the dependency on K more precise.

Theorem 1 (Lower Bound for DB-SPAA($\mathbf{P}_K, \mathcal{S}_T$)). *For any No-regret learning algorithm $\mathcal{A}$, there exists a problem instance DB-SPAA($\mathbf{P}_K, \mathcal{S}_T$) with $T \geq K^4$, such that its expected regret is lower-bounded as:*

$$\mathbf{E}[R_T(\mathcal{A})] \geq \Omega\bigg(\sum_{i=1}^{K-1} \sum_{j=i+1}^{K} \frac{\log T}{\Delta(i,j)_+} \bigg).$$

The *No-regret learning algorithm* refers to the class of 'consistent algorithms' which do not pull any suboptimal pair more than $O(T^\alpha)$, $\alpha \in [0, 1]$ (see Def. 9, Appendix 8)).

Proof (sketch) The main argument lies behind the fact that in the worst case the adversary can force the algorithm to learn the preference of every distinct pair (i, j) as for the 'worst-case' sequences $\mathcal{S}_T$, a knowledge of the already 'learnt' pairwise preferences would not disclose any information on the remaining pairs; e.g. assuming $\sigma^* = (1, 2, \ldots, K)$, revealing the available subsets in the following sequence $(1, 2), (1, 3), \ldots, (1, K), (2, 3), (2, 4), \ldots (K-1, K)$ would force the learner to explore (learn the preferences) all $\binom{K}{2}$ distinct pairs. The remaining proof establishes this formally, towards which we first show a $\Omega(\ln(T)/\Delta(1, 2))$ regret lower bound for a DB-SPAA instance with just two items (i.e. $K = 2$) as shown in Lem. 2. The lower bound for any general K can now be derived applying the above bound on independent $\binom{K}{2}$ subintervals, with the availability sequence $(1, 2), (1, 3), \ldots (1, K), (2, 3), (2, 4), \ldots (K-1, K)$. The full proof is given in Appendix 8. □

Lemma 2 (Lower Bound of DB-SPAA($\mathbf{P}_K, \mathcal{S}_T$) for 2 items). *For any No-regret learning algorithm $\mathcal{A}$, there exists a problem instance DB-SPAA($\mathbf{P}_2, \mathcal{S}_T$) such that the expected regret incurred by $\mathcal{A}$ on that can be lower bounded as: $\mathbf{E}[R_T(\mathcal{A})] \geq \Delta^{-1} \log(T)$, Δ being the 'preference-gap' between the two items (i.e. $\Delta = \mathbf{P}_{12} - 1/2$, assuming $P_{12} > 1/2$ or equivalently $\Delta > 0$).*

Remark 1 (Implication of the lower bound). The above result indicates that in the preference based learning setup, the fundamental problem complexity lies in distinguishing every pair of items $1 \leq i < j \leq K$. If the learner fails to learn the preference of any pair (i, j), the adversary can make the learner suffer $O(T)$ regret by setting $S_t = \{i, j\}$ henceforth at all round. It is worth noting that in the 'no sleeping' case both dueling bandits and MAB are known to have the same fundamental performance limit of $\Omega(K \log(T)/\Delta)$ (assuming $\mathbf{P}$ respects a *condorcet winner* [6, 21]). Thus Thm. 1 shows that the 'sleeping-aspect' of dueling bandits makes the problem K-times harder than 'sleeping-MAB' for which the regret lower bound is known to be only $\Omega\big(\sum_{i=1}^{K} \log(T)/\Delta(i, i+1)\big)$ [19].

4 SlDB-UCB: An Optimal Algorithm

In this section, we design an efficient algorithm for the DB-SPAA(K, T) problem with instance-dependent regret guarantee.

Main ideas. Our algorithm, described in Alg. 1, depends on an hyper-parameter $\alpha > 0.5$ and a confidence parameter $\delta > 0$. It maintains, for each item $k \in [K]$, its own record of empirical pairwise estimates of the duels, $(i, j) \in [K] \times [K]$ and their respective upper confidence bounds defined as:

$$\widehat{p}_{ij}(t) := \frac{w_{ij}(t)}{n_{ij}(t)} \qquad \text{and} \qquad u_{ij}(t) := \widehat{p}_{ij}(t) + c_{ij}(t), \text{ with } \quad c_{ij}(t) := \sqrt{\frac{\alpha \log a_{ij}(t)}{n_{ij}(t)}},$$

where $w_{ij}(t)$ denotes the total number of times item i beats j up to round t, $n_{ij}(t) := w_{ij}(t) + w_{ji}(t)$, and for all $i, j \in [K]$ and $t \in [T]$

$$a_{ij}(t) := \max\{C(K, \delta), n_{ij}(t)\} \qquad \text{and} \qquad C(K, \delta) := \Big(\frac{(4\alpha-1)K^2}{(2\alpha-1)\delta} \Big)^{\frac{1}{2\alpha-1}}.$$

The first key observation is that our careful choice of the confidence bounds $c_{ij}(t)$ ensures that with high probability $p_{ij}(t) \in [\widehat{p}_{ij}(t) - c_{ij}(t), \widehat{p}_{ij} + c_{ij}(t)]$ for any duel $i, j \in [K]$ and any $t \in [T]$ (Lem. 4). Now at any round $t \geq 1$, the algorithm first computes a set of potential winners of S_t as $\mathcal{C}_t = \{k \in S_t \mid |\mathcal{C}_k(t)| = \max_{j \in S_t} |\mathcal{C}_j(t)|\} \cap \{S_t \setminus \{\cup_{j \in S_t} \mathcal{D}_j(t)\}\}$, where $\mathcal{C}_k(t) := \{j \in$

Algorithm 1 `S1DB-UCB`

1: **input:** Arm set: $[K]$, parameters $\alpha > 0.5$, Confidence parameter $\delta \in [0,1)$
2: **init:** $w_{ij}(1) \leftarrow 0$, $\mathcal{D}_i(1) \leftarrow \emptyset$, $\forall i,j \in [K]$.
3: **define:** $n_{ij}(t) := w_{ij}(t) + w_{ji}(t)$, $\forall t \in [T]$
4: **for** $t = 1, 2, \ldots, T$ **do**
5:     Receive $S_t \subseteq [K]$
6:     $\widehat{p}_{ij}(t) = \dfrac{w_{ij}(t)}{n_{ij}(t)}$, $c_{ij}(t) \leftarrow \sqrt{\dfrac{\alpha \log a_{ij}(t)}{n_{ij}(t)}}$, $\forall i,j \in S_t$, (assume $\frac{x}{0} := 0.5$, $\forall x \in \mathbb{R}$)
7:     $u_{ij}(t) \leftarrow \widehat{p}_{ij}(t) + c_{ij}(t)$, $u_{ii}(t) \leftarrow 1/2$, $\forall i,j \in S_t$ $\triangleright$ UCB of empirical preferences
8:     **for** $k \in S_t$ **do**
9:         $\mathcal{C}_k(t) := \{j \in S_t \mid u_{kj}(t) > 1/2\}$ $\triangleright$ Potential losers to k
10:         **if** $\exists j \in \mathcal{D}_k(t) \cap S_t$ such that $j \notin \mathcal{C}_k(t)$, then $\mathcal{D}_k(t+1) \leftarrow \mathcal{D}_k(t) \setminus \{j\}$
11:     **end for**
12:     $\mathcal{C}_t = \{i \in S_t \mid |\mathcal{C}_i(t)| = \max_{j \in S_t} |\mathcal{C}_j(t)|\} \cap \{S_t \setminus \{\cup_{i \in S_t} \mathcal{D}_i(t)\}\}$ $\triangleright$ Potential best items
13:     **if** $\exists$ an unique $k \in \mathcal{C}_t$ s.t. $\mathcal{C}_k(t) = S_t \setminus \{k\}$: then $\mathcal{D}_k(t+1) \leftarrow \mathcal{D}_k(t) \cup \mathcal{C}_k(t)$, and $\mathcal{D}_i(t+1) \leftarrow \mathcal{D}_i(t) \setminus \{k\}$, $\forall i \in S_t \setminus \{k\}$ $\triangleright$ k uniquely dominates the rest
14:     Select a random x_t from $\mathcal{C}_t$. Choose $y_t \leftarrow \arg\max_{i \in \mathcal{C}_t} u_{ix_t}(t)$
15:     Play (x_t, y_t). Receive preference o_t
16:     Update: $\mathcal{D}_k(t+1) \leftarrow \mathcal{D}_k(t)$, $\forall i,j \in [K]$, $w_{x_t y_t}(t+1) \leftarrow w_{x_t y_t}(t) + o_t$, $w_{y_t x_t}(t+1) \leftarrow w_{y_t x_t}(t) + (1 - o_t)$, $a_{ij}(t+1) \leftarrow \max\{n_{ij}(t), C(K, \delta)\}$, $\forall i,j \in [K]$
17: **end for**

$S_t \mid u_{kj}(t) > \frac{1}{2}\}$ denotes the set of items that item k dominates (optimistically), and $\mathcal{D}_j(t)$ is the *'dominance set'* of item j at round t–another crucial concept as detailed below.

Since the *'sleeping dueling aspect'* of our problem formulation demands the knowledge of relative strengths of every distinct item-pair, the main idea of this algorithm lies in maintaining itemwise *'dominance sets'* $\mathcal{D}_k(t)$ for every item $k \in [K]$. Precisely, the *dominance set* $\mathcal{D}_k$, is supposed to capture the set of items suboptimal to $k \in [K]$, i.e. ideally if k is optimal at time t, we want $\mathcal{D}_k(t) \cap S_t = S_t \setminus [k]$ assuming the *total ordering* $\boldsymbol{\sigma}^* = (1, 2, \ldots, K)$ (Sec. 2). Towards this, we initialize $\mathcal{D}_k(1) = \emptyset$, and if at any round t, item k 'uniquely' satisfies $u_{kj}(t) > 1/2$ for all $j \in S_t \setminus \{k\}$, then we push all of them to $\mathcal{D}_k(t+1)$, precisely $\mathcal{D}_k(t+1) \leftarrow \mathcal{D}_k(t) \cup S_t \setminus \{k\}$. But if at any subsequent round t, $u_{kj} < 1/2$ for any $j \in \mathcal{D}_k(t)$ then j comes out from $\mathcal{D}_k(t+1)$. At each round, we play a random item from the set potential winners $\mathcal{C}_t$ as the left arm x_t, and the right arm is chosen to be its best challenger: $y_t \leftarrow \arg\max_{i \in \mathcal{C}_t} u_{ix_t}(t)$. One of the main novelty of our analysis lies in showing that $\mathcal{D}_k$ captures the desired set (i.e. $\mathcal{D}_k(t) \cap S_t = S_t \setminus [k]$) quickly enough (Lem. 6), following which it always plays i_t^* as the left arm x_t. But this in turn implies that any optimal arm j can not be played as y_t for more than $O(\log T/\Delta_{i_t^* j}^2)$ times against i_t^* (Lem. 7), leading to the optimal regret rate (details in Sec. 4).

Finally the right-arm y_t is then chosen to be the most competitive opponent of x_t as $y_t \leftarrow \arg\max_{i \in \mathcal{C}_t} u_{ji}(t)$ from the potential winners. Our arm selection strategy ensures that eventually for all t, algorithm plays the optimal pair (i_t^*, i_t^*) frequently enough as desired.

Theorem 3 (Regret analysis: `S1DB-UCB`). *Given any $\delta > 0$ and $\alpha \geq 1$, with probability at least $1 - \delta$, the regret incurred by* `S1DB-UCB` *(Alg. 1) is upper-bounded as*

$$R_T \leq O\left(\sum_{k=1}^{K-1} \sum_{i=k+1}^{K} \frac{\alpha \log T}{\Delta(k, i)_+}\right).$$

The complete proof with a precise dependencies on the model parameters is deferred to Appendix 9.

Remark 2 (Optimality of `S1DB-UCB`). *For a given $\delta \in [0,1)$, the regret bound of Alg. 1 is instance-wise optimal as follows from the lower bound (Thm. 1). This actually improves the state of the art $O(K/\Delta^2)$ regret bound of the UCB based dueling algorithms (e.g. RUCB [37], which is known to be $O(K \log T/\Delta^2)$), while our* `S1DB-UCB` *regret bound can shown to be only $O(K \log T/\Delta)$ for the standard condorcet-dueling bandit objective (without sleeping). Thus Alg. 1 also performs optimally for the standard dueling setting matching the known lower bound of $\Omega(K \log T/\Delta)$ [21].*

Proof sketch of Thm. 3. The key steps lie in proving the following four lemmas. The first lemma follows along the line of Lem. 1 of RUCB algorithm [37]and shows that all the pairwise estimates are contained within their respective confidence intervals with high probability.

Lemma 4. *Let $\alpha > 0.5$ and $\delta > 0$. Then, for any $i, j \in [K]$, with probability at least $1 - \delta/K^2$,*

$$\widehat{p}_{ij}(t) - c_{ij}(t) \le p_{ij} \le u_{ij}(t) := \widehat{p}_{ij}(t) + c_{ij}(t), \qquad \forall t \in [T].$$

The lemma below shows that once the algorithm can not play any suboptimal pair 'too many times'.

Lemma 5 (informal)**.** *Let $\alpha > 0.5$. Under the notations and the high-probability event of Lem. 4,*

$$\sum_{t=1}^{\tau} \mathbf{1}(i_t^* = k)\mathbf{1}\big(\{x_t, y_t\} = \{i, j\}\big) \le O\Big(\frac{\alpha \log(a_{ij}(\tau))}{\min\{\Delta(k,i)_+, \Delta(k,j)_+\}^2}\Big) \qquad \forall i, j \in [K].$$

The next two lemmas are the most crucial observations on the fast and correct estimations of the dominance sets $\mathcal{D}_k(t)$. Lem. 6 shows that the dominance set $\mathcal{D}_k(t)$ of any item $k \in [K]$ indeed captures all the suboptimal $S_{t \setminus k}$ 'soon enough' whenever $i_{t*} = k$ and continues to holds good for the rest of the game.

Lemma 6 (informal)**.** *Assuming that the event of Lem. 4 holds. Then, for any $k \in [K]$,*

$$\sum_{t=1}^{T} \mathbf{1}(i_t^* = k)\mathbf{1}\big(\mathcal{D}_k(t) \cap S_t \ne S_{t \setminus k}\big) \le O(1).$$

Our last lemma shows whenever $i_t^* = k$, and $\mathcal{D}_k(t)$ is correctly estimated, then item-k is always going to be pulled as the right arm x_t, and any suboptimal item $(i > k)$ can not be pulled too many times as the right arm y_t in such rounds (owning to Lem. 5).

Lemma 7. *Assuming that the event of Lem. 4 holds. Then, for any $k \in [K]$*

$$\sum_{t=1}^{T} \mathbf{1}(i_t^* = k)\mathbf{1}\big(\mathcal{D}_k(t) \cap S_t = S_{t \setminus k}\big) \sum_{i=k+1}^{K} \mathbf{1}(x_t = i) = 0,$$

and for any suboptimal item $i > k$,

$$\sum_{t=1}^{T} \mathbf{1}(i_t^* = k)\mathbf{1}\big(\mathcal{D}_k(t) \cap S_t = S_{t \setminus k}\big)\mathbf{1}(y_t = i) \le \frac{4\alpha \log T}{\Delta(k,i)_+^2}.$$

With probability of at least $1 - \delta$, the event of Lem. 4 holds and thus so do the ones of Lem. 5, 6, and 7. The regret of Alg. 1 then follows from applying the above lemmas with the following careful decomposition of the regret:

$$R_T \le \sum_{k=1}^{K-1} \sum_{t=1}^{T} \mathbf{1}(i_t^* = k)\big[\mathbf{1}(\mathcal{D}_k(t) \cap S_t \ne S_{t \setminus k}) + \mathbf{1}(\mathcal{D}_k(t) \cap S_t = S_{t \setminus k})\big]r_t$$

$$\le O(1) + \sum_{k=1}^{K-1} \sum_{t=1}^{T} \mathbf{1}(i_t^* = k) \sum_{i=k+1}^{K} \mathbf{1}(\mathcal{D}_k(t) \cap S_t = S_{t \setminus k})\mathbf{1}(i \in \{x_t, y_t\})r_t,$$

and the proof is concluded by using Lemma 7. $\qquad\qquad\qquad\qquad\qquad\qquad\qquad\square$

5   Algorithm: `S1DB-ED`

In this section, we propose a more computatinally efficient algorithm, `S1DB-ED` (Alg. 2), which achieves an almost optimal regret guarantee, and empirically performs competitively w.r.t. `S1DB-UCB` (as shown in our experiments, Sec. 6). Furthermore, a novelty of our finite time regret analysis of `S1DB-ED` lies in showing a cleaner tradeoff between regret vs availability sequence $\mathcal{S}_T$ which automatically adapts to the inherent 'hardness' of the sequence of available subsets $\mathcal{S}_T$, unlike the previous attempts made in standard sleeping bandits for adversarial availabilitie [19] (Rem. 3).

Main ideas. We again use the notations $w_{ij}(t), n_{ij}(t)$ as used for `S1DB-UCB` (Alg. 1), with the same initializations. Same as `S1DB-UCB`, this algorithm also maintains the empirical pairwise preferences $\widehat{p}_{ij}(t)$ for each item pair $i, j \in [K]$. However, unlike the earlier case here we need to ensure an

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Algorithm 2 `S1DB-ED`

1: **input:** Arm set: $[K]$, exploration parameter $t_0 > 0$, parameter $\alpha > 0$
2: **for** $t = 1, 2, \ldots, T$ **do**
3:     $\widehat{p}_{ij}(t) := \frac{w_{ij}(t)}{n_{ij}(t)}$, $\widehat{p}(i,i) \leftarrow 1/2$, $\forall i, j \in [K]$ (assume $\frac{x}{0} := 0.5$, $\forall x \in \mathbb{R}$)
4:     Receive $S_t \subseteq [K]$
5:     **if** $|S_t| \geq 2$ and $\exists i, j \in S_t$ s.t. $n_{ij}(t) < t_0$, $i \neq j$ **then**
6:         Set $x_t \leftarrow i$, $y_t \leftarrow j$ ▷ Exploration rounds
7:     **else**
8:         $\widehat{\mathcal{B}}_i(t) := \{ j \in [K] \setminus \{i\} \mid \widehat{p}_{ij}(t) \leq 1/2 \} \cap S_t$, $\forall i \in [K]$ ▷ Empirical winners over i
9:         $\mathcal{I}_i(t) := \sum_{j \in \widehat{\mathcal{B}}_i(t)} n_{ij}(t) \,\mathrm{kl}(\widehat{p}_{ij}(t), 1/2)$, $\forall i \in [K]$ and $\widehat{i}_t^* \leftarrow \arg\min_{i \in S_t} \mathcal{I}_i(t)$
10:        $\mathcal{C}_t := \{ i \in S_t \mid \mathcal{I}_i(t) - \mathcal{I}_{\widehat{i}_t^*}(t) \leq \alpha \log t \}$ ▷ Potential good arms
11:        Select any x_t from $\mathcal{C}_t$ uniformly at random
12:        **if** $\left(\widehat{i}_t^* \in \widehat{\mathcal{B}}_{x_t}(t) \text{ or } \widehat{\mathcal{B}}_{x_t}(t) = \emptyset \right)$: set $y_t \leftarrow \widehat{i}_t^*$, **else:** $y_t \leftarrow \arg\max_{i \in S_t \setminus \{x_t\}} \widehat{p}_{ix_t}(t)$
13:    **end if**
14:    Play (x_t, y_t) Receive preference feedback o_t
15: **end for**

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initial t_0 rounds of exploration ($t_0 = 1$ in the theorem) for every distinct pairs (i, j), and instead of maintaining pairwise UCBs, in this case the set of 'good-items' is defined in terms of *empirical divergences* for all $i \in S_t$

$$\mathcal{I}_i(t) := \sum_{j \in \widehat{\mathcal{B}}_i(t)} n_{ij}(t) \,\mathrm{kl}\left(\widehat{p}_{ij}(t), 1/2\right), \quad \widehat{\mathcal{B}}_i(t) := \left\{ j \in [K] \setminus \{i\} \mid \widehat{p}_{ij}(t) \leq 1/2 \right\} \cap S_t$$

denotes the empirical winners of item i in set S_t. Now intuitively since $\exp(-\mathcal{I}_i(t))$ can be interpreted as the likelihood of i being the *best-item* of S_t, we denote by $\widehat{i}_t^* \leftarrow \arg\min_{i \in S_t} \mathcal{I}_i(t)$ the *empirical-best* item of round t and define the set of 'near-best' items $\mathcal{C}_t := \left\{ i \in S_t \mid \mathcal{I}_i(t) - \mathcal{I}_{\widehat{i}_t^*}(t) \leq \alpha \log t \right\}$, whose likelihood is close enough to that of $\widehat{i}_t^*$. Finally the algorithm selects an arm pair (x_t, y_t) such that x_t is a potential candidate of good arm (which ensures the required exploration) and y_t being the strongest challenger of x_t w.r.t the empirical preferences. The algorithm is given in Alg. 2.

Theorem 8 (Regret analysis `S1DB-ED`). *Let $t_0 = 1$ and $\alpha = 4K$. Then as $T \to \infty$, the expected regret incurred by* `S1DB-ED` *(Alg. 2) can be upper bounded as: For all $\varepsilon_2, \ldots, \varepsilon_K \geq 0$*

$$\mathbf{E}\left[R_T\right] \lesssim K^2 + \sum_{1 \leq i < j \leq K} \left(\frac{K \mathbf{1}_{\{\Delta(i,j) > \varepsilon_j\}}}{\Delta(i,j)^2} + n_{ij}(T) \min\{\varepsilon_j, \Delta(i,j)\} \right) + \sum_{j=2}^{K} \frac{K \log T}{\max\left\{\varepsilon_j, \Delta(j-1,j)_+\right\}}$$

$$\leq O\left(\min\left\{ \sum_{j=2}^{K} \frac{K \log T}{\Delta(j-1,j)_+}, \; KT^{2/3} \right\} \right).$$

The proof is deferred to Appendix 10. Although it borrows some high-level ideas from [19] for sleeping bandits and from [21] for RMED in standard dueling bandits, our analysis needed new ingredients in order to obtain $O(K^2 (\log T)/\Delta)$. This is especially the case for the proofs of the technical Lemmas 10 and 11 which significantly differ from "corresponding" technical lemmas of [21]. Specifically, both regret bounds of RMED and ours need to control the length of an initial exploration t_0 after which pairwise preferences are well estimated by $\widehat{p}_{ij}(t)$. This is done respectively by our Lemma 10 and Lemma 5 of [21]. Yet, RMED's original analysis is based on a union bound over all possible subsets $S \subset \{1, \ldots, K\}$ of items (see Equation (19) in [21]), whose number is exponential in K. Despite our efforts, we could not follow the proof of Lemma 5 of [21], which to the best of our understanding, should yield to an exploration t_0 exponentially large in K contrary to $O(1)$ claimed in [21]. Instead, in our proof of Lem. 10, we carefully apply concentration inequalities to run union bounds over the items directly instead of sets of items.

The upper-bound of Thm. 8 is close to optimal. It suffers at most a suboptimal factor K and exactly matches the lower-bound for some problems. The distribution-free upper-bound of order $O(T^{2/3})$ matches obtainable standard dueling bandit problems [21, 37], since the later algorithms also suffer constant terms of order Δ^{-2}. Yet, it is unclear whether it is optimal or if $O(\sqrt{T})$ can be obtained.

Remark 3 (Sequence $\mathcal{S}_T$ adaptivity of Alg. 2)**.** It is worth pointing out that the regret bound of Thm. 8 is finite time and automatically adapts to the sequence of available sets $\mathcal{S}_T$. In the worst-case, the complexity lies in identifying for all items j the gap with the earlier item $j - 1$. Yet, our regret-bound, which holds for any $\varepsilon_j \geq 0$, will automatically perform a trade-off for each j between the gap $\Delta(j-1, j)_+^{-1}$ and $\varepsilon_j \sum_{i=1}^{j-1} n_{ij}(T)$ the number of times j is played together with a better item $i < j$. In particular, $\sum_{i=1}^{j-1} n_{ij}(T)$ can be small if j is rarely available in S_t while not optimal. Notably, this adaptivity to $\mathcal{S}_T$ item per item improves the regret guarantee of Thm. (10), [19], which also addresses the problem of sleeping bandits with 'adversarial availabilities' but for the stochastic multi-armed bandit setup and only provides worst-case guarantees over all $\mathcal{S}_T$ and a trade-off ε independent of j.

Remark 4 (Space and runtime complexity)**.** Although `SlDB-UCB` (Alg. 1) yields the optimal regret guarantee, it requires an additional $O(K^2)$ space complexity to maintain the itemwise dominance sets $\mathcal{D}_i(t)$ per item $i \in [K]$ at each round, along with the estimated pairwise preferences. Moreover it also requires an additional $O(|S_t|^2)$ computational complexity per round t to update/maintain the dominance sets which could be as bad as $O(K^2)$. `SlDB-ED` (Alg. 2) only requires $O(|S_t|)$ computational complexity per round to compute $\widehat{\mathcal{B}}_i(t)$ and $\mathcal{I}_i(t)$ for all $i \in S_t$.

Remark 5 (`SlDB-ED` in standard dueling bandits)**.** Even in the dueling bandit setting (without the sleeping component), `SlDB-ED` and Thm. 8 have advantages compared to the RMED algorithm and analysis of [21]. Our regret bound is valid for all number of items K, while the one of Thm. 3 of [21] is only asymptotic when $K \to \infty$. This is due to the fact that the algorithm of [21] depends on a hyper-parameter $f(K)$ which needs to larger than AK, where A is a constant in K and T but which depends on the unknown sub-optimality gaps $\Delta(i, j)$. Thus, [21] chooses $f(K) \approx K^{1+\varepsilon}$ so that eventually the bound is satisfied when $K \to \infty$. Instead, our algorithm only depends on easily tunable hyper-parameters t_0 and α, whose optimal values are independent of unknown parameters.

6 Experiments

In this section, we compare the empirical performances of our two proposed algorithms (Alg. 1 and 2). Note that there are no other existing algorithms for our problem (see Sec. 1).

Constructing Preference Matrices (P). We use the following three different utility based Plackett-Luce$(\boldsymbol{\theta})$ preference models (see Sec. 2) that ensures a *total-ordering*. We now construct three types of problem instances 1. *Easy* 2. *Medium* 3. *Hard*, for any given K, such that items with their respective $\boldsymbol{\theta}$ parameters are assigned as follows: 1. *Easy:* $\boldsymbol{\theta}(1 : \lfloor K/2 \rfloor) = 1$, $\boldsymbol{\theta}(\lfloor K/2 \rfloor + 1 : K) = 0.5$. 2. *Medium:* $\boldsymbol{\theta}(1 : \lfloor K/3 \rfloor) = 1$, $\boldsymbol{\theta}(\lfloor K/3 \rfloor + 1 : \lfloor 2K/3 \rfloor) = 0.7$, $\boldsymbol{\theta}(\lfloor 2K/3 \rfloor + 1 : K) = 0.4$. 3. *Hard:* $\boldsymbol{\theta}(i) = 1 - (i-1)/K$, $\forall i \in [K]$. Note for each $\boldsymbol{\sigma}^* = (1 > 2 > \ldots K)$.

In every experiment, we set the learning parameters $\alpha = 0.51$ for `SlDB-UCB` (Alg. 1) and as per Thm. 8 for `SlDB-ED` (Alg. 2). All results are averaged over 50 runs.

Regret over Varying Preference Matrices. We first plot the cumulative regret of our two algorithms (Alg. 1 and 2) over time on the above three Plackett-Luce datasets for K = 10. We generate availability sequence $\mathcal{S}_T$ randomly by sampling every item $i \in [K]$ independently with probability 0.5. Fig 2 shows that, as their names suggest too, *instance-Easy* is easiest to learn as the best-vs-worst item preferences are well separated and the diversity of the item preferences across different groups are least. Consequently the algorithms yield slightly more regret on *instance-Medium* due to higher preference diversity, and the hardest instance being *Hard* where the learner really needs to differentiate the ranking of every item for any arbitrary set sequences $\mathcal{S}_T$. Empirically `SlDB-UCB` is seen to slightly outperform `SlDB-ED`, though orderwise they perform competitively.

Regret over Varying Set Availabilities. In these set of experiments, the idea is to understand how the regret improves over completely random subset availabilities as now the learner may not have to distinguish all item preferences as some of the item combinations occurs rarely. We choose $K = 10$ and to enforce item dependencies we generate each set S_t by drawing a random sample from Gaussian$(\boldsymbol{\mu}, \Sigma)$ such that $\boldsymbol{\mu}_i = 0$, $\forall i \in [10]$, and Σ is a fixed 10×10 positive definite matrix which controls the set dependencies: Precisely we use two different block diagonal matrices for *Low-Correlation* and *High-Correlation* with the following correlations: 1. *Low-Correlation:* Σ is a separated block diagonal matrix on item partitions $\{1, 2, 3\}$, $\{4, 5, 6\}$, $\{7, 8, 9, 10\}$. 2. *High-Correlation:* Σ is constructed by merging three all-1 matrices on partitions $\{1 \ldots 5\}$, $\{2, \ldots 8\}$, and $\{6, \ldots 10\}$, however as the resulting matrix is positive semi-definite, so we further take its SVD and reconstruct the matrix back eliminating the negative eigenvalues. At every round we sample a random

vector from Gaussian($\boldsymbol{\mu}, \Sigma$), and S_t is considered to be the set of items whose value exceeds 0.5. Both experiments are run on *instance-Hard*. Fig. 3 shows, as expected, on *Low-Correlation* both algorithms converge to $\boldsymbol{\sigma}^*$ relatively faster and at lower regret compared to *High-Correlation* (as the later induces higher variability of the available subsets).

Figure 2: Regret (R_t) vs time (t) over three preference instances ($\mathbf{P}$)

Figure 3: Regret (R_t) vs time (t) over availability sequences $\mathcal{S}_T$

Figure 4: Final regret (R_T) at $T = 10^4$ with varying sizes (K)

Final Regret vs Setsize(K). We also compared the (averaged) final regret of the two algorithms over varying item sizes K. We additionally constructed two larger Plackett-Luce ($\boldsymbol{\theta}$) *Easy* and *Hard* instances for $K = 20$ and 40, using similar $\boldsymbol{\theta}$ assignments explained before. We set $T = 10\,000$ and use itemwise independent set generation idea, as described for Fig. 2. As expected, Fig. 4 shows the regret of both algorithms scales up with increasing K with effect on `SlDB-ED` being slightly worse than `SlDB-UCB`, though the later generally exhibits a higher variance.

Worst Case Regret vs Time. We run an experiment to analyse the regret of our two algorithms on the worst case problem instances. Towards this we use preference matrices $\mathbf{P}_\Delta$ of the form: $\mathbf{P}_\Delta(i, j) = 0.5 + \Delta$, $\forall 1 \le i < j \le K$, i.e. all items are spaced with equidistant gap $\Delta \in (0, 0.5]$. As before, we choose $T = 20,000$ and $K = 10$, and run the algorithms on above problem instances varying Δ in the range $[10/T, \dots, 0.5]$ with uniform grid-size of 0.005 (i.e. total 100 values of Δ, each corresponds to a separate problem instance $\mathbf{P}_\Delta$ with different 'gap-complexity'). We plot the worst case regret of both algorithms over time plotting $\max_\Delta R_t(P_\Delta)$ vs t. Details in Appendix 11.

Runtime comparison of `SlDB-UCB` and `SlDB-ED`. Lastly, we also compared the (averaged) runtime of our two algorithms on the *Easy* and *Medium* instances over varying $K = 10, 50, 100$ for $T = 5000$ rounds. As shown in Fig. 6, the runtime of `SlDB-ED` is always better than `SlDB-UCB`, and the effect becomes more drastic with increasing K. This corroborates with our theory since `SlDB-UCB` does have a multiplicative K-times worse runtime complexity compared to `SlDB-ED` (see Rem. 4).

Figure 5: "Worst Case Regret" ($\max_\Delta R_t(P_\Delta)$) vs time ($t$) over three availability sequences $\mathcal{S}_T$

Figure 6: Runtime of `SlDB-UCB` and `SlDB-ED` for $T = 5000$

7 Conclusion and Perspective

We give the first provably optimal algorithms for dueling bandits with adversarial availability sets. There are many open questions to address including generalizing the framework to other learning scenarios or assuming adversarial preferences. Moving forward, one can address many open questions along this direction, e.g. analyzing more general ranking objective based on borda [32] or copeland scores [36], or extending the framework to a general contextual scenario with subsetwise feedback. Another direction worth understanding is to analyze the connection of this problem with other bandit setups, e.g., learning with feedback graphs [3, 4] or other side information [23, 20]. It would also be interesting to consider the dueling bandit problem for adversarial preference and stochastic availabilities [24, 17], and also analyzing these class of problems for general subsetwise preferences [25, 30, 8]. Detailed discussion is given in Appendix 12.

Neurips21 Checklist

- Not applicable.

(e) Did you discuss whether the data you are using/curating contains personally identifiable information or offensive content?

- Not applicable.

(a) Did you include the full text of instructions given to participants and screenshots, if applicable?

- Not applicable.

(b) Did you describe any potential participant risks, with links to Institutional Review Board (IRB) approvals, if applicable?

- Not applicable.

(c) Did you include the estimated hourly wage paid to participants and the total amount spent on participant compensation?

- Not applicable.

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