Learning to Compare Longitudinal Images

Abstract

Longitudinal studies, where a series of images from the same set of individuals are acquired at different time points, represent a popular technique for studying and characterizing temporal dynamics in biomedical applications, including in the healthcare setting. The classical approach for longitudinal comparison involves normalizing for nuisance variations, such as image orientation or contrast differences, via pre-processing. A statistical analysis is, in turn, conducted to detect changes of interest, either at the individual or population level. This classical approach can suffer from pre-processing issues and limitations of the statistical analysis. For example, normalizing for nuisance variation might be hard in settings where there is a lot of idiosyncratic changes. Population-level statistical analyses often yield a single summary of longitudinal changes that might not capture the full diversity across individuals. Individual-level statistical analyses, on the other hand, do not typically leverage the population-level data. In this paper, we present a simple machine learning-based approach that can alleviate these issues. In our approach, we train a deep learning model (called PaIRNet, for Pairwise Image Ranking Network) to compare pairs of longitudinal images, with or without supervision. In the self-supervised setup, for instance, the model is trained to temporally order the images, which requires learning to recognize time-irreversible changes Our results from four datasets demonstrate that PaIRNet can be very effective in localizing and quantifying meaningful longitudinal changes, while discounting nuisance variation.

Keywords: Self-supervised Learning, Longitudinal Analysis, Pairwise Comparison

1. Introduction

Whether it is in the context of development, aging, or progressive diseases, characterizing and quantifying change over time is a fundamental goal in bio-medicine. The longitudinal paradigm, where individuals are observed over multiple time-points, is the primary approach for studying temporal dynamics. In medical imaging, longitudinal studies are widely adopted for capturing anatomical and physiological changes.

There are two scenarios where longitudinal imaging is mainly utilized. The first scenario is to localize and quantify change at an individual level, for example, in a brain cancer patient where the objective is to monitor tumor growth and spread, as in (Konukoglu et al., 2007). In the second scenario, researchers are interested in characterizing population-level longitudinal changes that are shared across individuals, with the objective of gaining insights into biological processes. Common examples of the population study include Alzheimer's disease and aging, as described in (Fox et al., 1996; Fjell et al., 2009).

In a longitudinal imaging study, whether it is at the individual or group-level, the core challenge is disentangling nuisance variation (e.g., due to differences in imaging parameters or artifacts) from meaningful (e.g. clinically significant) temporal changes (e.g., atrophy or

tumor growth). Virtually all existing algorithmic approaches rely on pre-processing the data to help with this core challenge. In pre-processing, the objective is to minimize nuisance variation. A common step in pre-processing, for instance, is image registration, where the longitudinal images are spatially normalized to some standard reference coordinate frame. The image registration step can account for orientation differences and/or other geometric changes that can be confounding - such as distortion. Even after pre-processing, there is likely residual nuisance variation that will need to be discounted and this is where statistical or machine learning-based techniques are often used. As we discuss below, these analyses can be constrained by modeling choices. For example, population-level statistical methods are not designed for characterizing longitudinal changes at the individual-level.

In this paper, we present a simple learning-based approach as a novel way for analyzing longitudinal imaging data. Crucially, our approach does not require pre-processing, is model-free, and leverages population-level data to capture time-irreversible changes that are shared across individuals, while offering the ability to visualize individual-level changes. Our core assumption is that nuisance variation, such as changes in orientation or image contrast, are independent of time, when examined across the population. We train a deep learning model, called Pairwise Image Ranking Network (PaIRNet), to compare pairs of longitudinal images. We consider two possible tasks. In the first task, which we refer to as *supervised*, PaIRNet is trained to predict a target variable that captures meaningful temporal change - such as tumor volume difference. In the second task, which we call *self-supervised*, the model is trained to predict the temporal ordering of the input longitudinal image pair. In the self-supervised setting, the only additional information we need is the timing of the images, which is often readily available. In our experiments, we demonstrate that the proposed strategy can localize and quantify individual-level longitudinal changes, even in the self-supervised setting.

2. Related Works

2.1. Individual-level Longitudinal Change Detection

A core objective of a longitudinal study, particularly in the healthcare setting, is to localize and quantify clinically significant, non-spurious changes over time at the patient level. Classical approaches, such as (Smith et al., 2001) rely on pre-processing steps such as image registration, as in (Reuter et al., 2012), intensity normalization, and/or segmentation, as in (Smith, 2002). After these pre-processing steps, a simple strategy might be just to overlay the images to reveal pixel-level changes or study differences in morpholigcal measurements, such as size of an anatomical structure. However, these differences can still contain confounding changes, due to image artifacts or failures in pre-processing steps. One can rely on statistical analyses to separate out spurious and clinically-significant changes, as demonstrated in (Nguyen et al., 2018). An important weakness in these individual-level analyses is that they often do not leverage population data to better characterize and detect longitudinal change. Model-based methods mitigate this weakness by adopting mechanisms that capture population and individual-level dynamics (Sophocleous et al., 2022), yet these are limited by the model's capacity to capture the signal.

Figure 1: How would you characterize clinically meaningful longitudinal change that is common across these cases? Note the nuisance variation due to changes in orientation and contrast. There is also significant variability across individual brains that can be confounding.

2.2. Statistical Analysis of Population-level Longitudinal Change

Another objective in population health is to characterize temporal changes due to processes like development, aging, or disease progression, that is shared across individuals. These population-level longitudinal studies, by construction, pool data across a group of individuals to reveal a shared map of temporal change. These studies also demand pre-processing steps to suppress nuisance variation across the images. The classic approach, in turn, relies on statistical techniques like linear mixed effects models (Bernal-Rusiel et al., 2013) to reveal non-spurious temporal associations, as demonstrated in (Huang et al., 2022; Wang and Guo, 2019; Peters et al., 2019; Durrleman et al., 2013).

Although widely adopted, population-level statistical analyses for studying longitudinal change have at least two challenges. Pre-processing and extracting measurements often require human input (annotations, quality control, etc), which can be costly and hard to achieve at scale. It can also be difficult to decide what time-varying variable to examine associations with. For example, chronological age is a common variable for studying aging-associated changes. Yet, the aging process can vary significantly across individuals, compromising the interpretation of the results.

2.3. Machine Learning Methods for Longitudinal Images

In recent years, machine learning based methods have been used for longitudinal medical imaging studies. One approach leverages the supervised paradigm and trains a model to predict clinical trajectories from pairs of images, as described in (Bhagwat et al., 2018). To derive the target label to train on, these techniques require meta-data, such as disease severity scores, which can be unreliable or unavailable.

An alternative learning technique is the so-called self-supervised paradigm, which does not require ground-truth labels. This approach has recently been applied to longitudinal imaging studies (Zhao et al., 2021; Ouyang et al., 2022; Couronné et al., 2021), where the temporal ordering is used to regularize the learning of representations extracted from the

image data, which is trained to capture inter-subject variability and within-subject temporal changes. These techniques rely on a reconstruction loss for regularization, which can make them sensitive to nuisance variation in the images, such as orientation or contrast changes over time. Thus these methods require pre-processing of the image data and cannot handle misaligned images. In contrast, the learning paradigm we propose in this paper is trained on a single task (supervised or self-supervised) and does not depend on any pre-processing. The task, which we implement a neural network to solve, involves comparing pairs of images from the same individual. In the self-supervised implementation, the model learns to rank the input image pair based on temporal ordering.

2.4. Pairwise Image Ranking

Pairwise image ranking is an important problem in computer vision with many applications, such as assessing aesthetic preference (Lee and Kim, 2019), skill (Doughty et al., 2018), perceptual image-error (Prashnani et al., 2018), and street safety (Dubey et al., 2016). Most of these prior works use a shared feature extraction back-bone (also called a Siamese architecture), In this work, we apply a similar model, for the first time, to longitudinal medical images and demonstrate how this approach can yield individual-level detection and quantification of temporal change.

3. Detecting Changes in Longitudinal Images

3.1. Problem Definition

Ranking (or ordering) is a system where items are ordered and classified as either higher or lower or equal to the second item for any two items. Motivated by longitudinal self-supervised learning problems, the attribute is temporal order in this paper(Agrawal et al., 2022; Zhao et al., 2021; Couronné et al., 2021).

Longitudinal study design involves repeated measures of the same variables at different time points. Each variable $(s = 1, ..., n)$, e.g., subject, has multiple images I_{si}, $i = 1, ..., m$, acquired at different time t_{si}. Given a set of image pairs (I_{si}, I_{sj}), $i, j = 1, ..., m$, and temporal ordering of the pairs, our goal is to train the model to detect longitudinal changes while learning to find the correct order of time. We formulate this temporal ordering problem as a ranking problem based on the seminar work of RankNet (Burges et al., 2005) and its variant, DirectRanker (Köppel et al., 2019).

$$R(I_{si}, I_{sj}) = \begin{cases} 1 & \text{if } t_{si} < t_{sj} \\ 0 & \text{if } t_{si} = t_{sj} \\ -1 & \text{if } t_{si} > t_{sj} \end{cases} \tag{1}$$

3.2. Pairwise Image Ranking Network

Pairwise Image Ranking Network (PaIRNet, R) consists of a feature extracting network (f), feature fusion (subtraction), and ranking network (g) as depicted in Figure 2. Given an image pair with corresponding labels that can be any quantitative values or preference, PaIRNet is trained to predict the order. A ranking function R satisfies the three properties:

Figure 2: Pairwise Image Ranking Network (PaIRNet) Structure. PaIRNet consists of a feature network, subtraction, and ranking network. Given an image pair, PaIRNet predicts the rank order following Equation (1).

(a) Reflexivity: if $t_{si} = t_{sj}$, then $R(I_{si}, I_{sj}) = 0$

(b) Antisymmetry: $R(I_{si}, I_{sj}) = -R(I_{sj}, I_{si})$

(c) Transitivity: if $R(I_{si}, I_{sj}) \geq 0$ and $R(I_{sj}, I_{sk}) \geq 0$, then $R(I_{si}, I_{sk}) \geq 0$

where I_{si} is an input image with the temporal rank t_{si} of subject s.

We can show that PaIRNet satisfies the above properties. (a) is guaranteed by construction (Equation (1)). As shown in (Köppel et al., 2019; Rigutini et al., 2008), the feature differences of two images from the same feature network guarantee the antisymmetry when biases are removed and antisymmetric activation functions are used. (b) is easily satisfied when g is a linear neural network without biases and with antisymmetric activation functions, like tanh and softshrink. If (b) is satisfied, (a) is also fulfilled as $r(I_1, I_1) = -r(I_1, I_1)$, then $r(I_1, I_1) = 0$. For (c), as g is an odd linear function where the sign of input is preserved, if $r(I1, I2) = g(f(I1) - f(I2)) > 0$ and $r(I2, I3) = g(f(I2) - f(I3)) \geq 0$, then $r(I1, I2) + r(I2, I3) = g(f(I1) - f(I2) + f(I2) - f(I3)) = r(I1, I3) > 0$.

3.3. Localization of longitudinal change

Class activation maps (CAMs) and improved methods like Grad-CAMs calculated from classification CNNs have been used for weakly-supervised object localization. We modified CAMs, which visualize CNN predictions using the global average pooling (GAP) and weights from the GAP output to output classes (Zhou et al., 2016), to localize the difference between a pair of images. The CAM from the original paper is a weighted sum of the feature maps of the last convolutional layer using the weights predicting the class. As PaIRNet learns to compare two image inputs by negating a pair of features, we additionally used the absolute value of feature difference and the absolute weights of the last layer together and calculated the weighted sum of activation maps as follows:

$$\sum f_{activation} \times |w_g(f(I_{si}) - f(I_{sj}))| \tag{2}$$

where w_g is a weight of the ranking layer and $f_{activation}$ is activation maps before GAP.

4. Experiments

4.1. Experimental setup

4.1.1. DATASET

Two synthetic datasets and two real-world datasets are used to validate the PaIRNet method. Two series of samples for each dataset are illustrated in Figure 1. All four datasets have sets of images that temporal change is monotonic and irreversible. We used 0.6/0.2/0.2 ratio for the train/validation/test split except for the Starmen. The split is done at the subject level.

Starmen. We used publicly available Starmen datasets that have been used for evaluating longitudinal frameworks (Bône et al., 2018; Couronné et al., 2021). Raising the left arm is the only temporal change within a subject in the original dataset. We randomly rotated (-6.8,6.8) degrees and translated (-10,10) pixels for subject variability. Out of 1000 sets of 10 longitudinal images, 400 sets of images are used for training, 100 sets for validation, and the rest for testing. The ground-truth value related to the progression of the left arm is ranged in -0.12 ± 4.25.

Tumor. Synthetic tumor growth dataset is generated based on T1 images of OASIS-2 dataset collected to study dementia (Marcus et al., 2010). To avoid possible capture of common degeneration from demented cohorts, we only selected first-visit images from 72 healthy cohorts. The images are preprocessed (brain extraction and intensity normalization) using the in-house software. We generated 3 to 5-time points of growing tumor placed within the brain tissue on the middle slice. The color, the initial size of the tumor, and the speed of the tumor growth rate are randomly generated. In total, 292 synthetic images with an average tumor size of 14.74 ± 6.86 are generated. All images are randomly rotated and translated for [-10, 10) degrees/pixels.

Embryo. Embryo development dataset is images of morphokinetics In Vitro Fertilization (IVF) collected using time-lapse imaging incubators (TLI)(Gomez et al., 2022). The images of developing embryos are fully annotated with 16 development phases. Embryos with more than one phase are used. We only selected one image in the middle if there are multiple images per phase. In total, 7784 images from 698 embryos are used. The embryos have on average 12.23 ± 2.41 phases.

Aging. OASIS-3 is a longitudinal dataset collected for normal aging and Alzheimer's disease (LaMontagne et al., 2019). We excluded Alzheimer's patients to focus on the aging effect. In total, 754 T1 images from 272 healthy cohorts ranging in age from $42 - 86$ (64.34 ± 8.53 on average) years at the initial scan are used. The subjects have 2.77 ± 0.96 repeated scans on average. All images are linearly aligned before extracting the middle slice.

4.1.2. BASELINE METHODS

We compared the proposed method with the state-of-the-art longitudinal self-supervised learning methods. LSSL with cosine loss (LSSL-CL) (Zhao et al., 2021) and longitudinal variational autoencoder (LVAE) (Couronné et al., 2021) methods showed successful results

on learning latent representation related to changes in time for synthetic data and brain aging task. They both use image reconstruction loss of an autoencoder style architecture and combine with additional loss to learn temporal change. LSSL-CL method optimizes the colinearity between temporal trajectories obtained from latent vectors representing feature differences of input pairs and a global direction using cosine similarity. LVAE method optimizes two encoders, one for subject-wise variability with DeepSet method to attain permutation invariance (Zaheer et al., 2017) and one for longitudinal changes with soft-ranking loss (Blondel et al., 2020). We will use the same notation of their paper for latent features (z for LSSL-CL and Z^Ψ for LVAE).

When the ground-truth temporal attribute for the longitudinal change is given, a weakly-supervised object localization (WSOL) method can be another solution that can avoid learning subject-wise nuisance factors. For a single instance, the CAM-based method that visualizes the activation map for the class label has been a popular method (Zhou et al., 2016). Two supervised methods are used for the comparison: WSOL trained with supervised regression (SR) without considering the longitudinal components and PaIRNet with supervision.

4.1.3. Implementation details

For the feature network of the PaIRNet, we used the ResNet-18 (He et al., 2016). PaIRNet is trained with cross-entropy loss, Adam optimizer (Kingma and Ba, 2014), and the early stopping criterion that is 5 epochs without a decrease of validation loss. We used a grid search for a learning rate. The details are in the Appx. A.

We used the same architecture and visualization method for the WSOL methods. For LSSL-CL (Zhao et al., 2021) and LVAE (Couronné et al., 2021), we followed the original paper and parameter settings.

4.2. Longitudinal Change Detection

The activation maps of PaIRNet and baseline methods are illustrated in Figure 3 for each dataset. The images are a subset of the longitudinal series and are represented in the temporal order (t0, t1, t2). Among the SOTA LSSL methods, we could only visualize LVAE as the individual image-level visualization for longitudinal change is not available for the LSSL-CL. We followed the original LVAE visualization method but we used the image-wise feature Z^Ψ instead of averaged feature. The color red and blue of the LVAE activation map represent positive and negative gradients. For the supervised methods, we used the same weighted CAM method as PaIRNet.

Figure 3 shows the successful performance of the PaIRNet method compared to the baseline methods. Although the WSOL using regression tasks can localize the changes well in general, the method struggles to generalize. For example, the method fails to localize when the tumor sizes are smaller than the average (Figure 3B t0 and t1 in Subject1, t0 in Subject 2), when the embryo images have a noisy background (Figure 3C t0 and t1 in Subject1 and t2 in Subject 2), when the embryo images are translated (Figure 3C t2 in Subject 1 and t2 in Subject2) and when learning the task is difficult (Figure 3D).

The LVAE method is designed to separate subject-wise variability from longitudinal changes by learning the distribution of the subset of longitudinal images while learning the

Figure 3: Activation map results. PaIRNet finds the similar activation patterns to supervised regression (SR) without using the ground-truth. Compared to the gradient maps of longitudinal variational autoencoder (LVAE), PaIRNet shows robust results in finding changes when the images are rotated or translated.

SoftRank of the images. Although successful in simple datasets, the method fails to separate and localize the longitudinal changes when the image has nuisance factors. For example, the factors in our experiments include image transformation in Starmen (Figure 3A t2) and Embryo (Figure 3C t2), image rotation in Tumor (Figure 3B t2) and brain with background, which includes CSF and skull, (Figure 3D). On the other hand, the PaIRNet methods could

learn to ignore the noisy factors by focusing on finding the difference between longitudinal pairs.

4.3. Correlation with ground-truth target label

Figure 4: Correlation between ground-truth label and predicted values.

We evaluate the performance of detecting the change rate quantitatively. We calculated Pearson correlation coefficient(Benesty et al., 2009) to measure the linear correlation between the ground-truth temporal change and the estimated value. Only the non-negative pairs are used to avoid duplicates, e.g., $t_{si} <= t_{sj}$. As our model outputs the scalar value representing the difference of a given input pair, we used the network output before activation. For the SOTA LSSL baselines, we calculated the cosine similarity of a given pair, $cosine(z_i, z_j)$, for LSSL-CL and the difference, $Z_i^{\Psi} - Z_j^{\Psi}$, for LVAE.

In all four datasets, the proposed method shows a significantly higher correlation with the ground truth than LSSL-CL and LVAE. As the learning representation for longitudinal changes underperformed due to the nuisance factors, measuring the longitudinal difference between images would be affected. Self-supervised PaIRNet, contrariwise, learned to localize

and quantify the longitudinal change well. The self-supervised PaIRNet results are even comparable to the PaIRNet trained with supervision.

5. Conclusion

We have shown that pairwise image ranking network (PaIRNet) is an effective self-supervised method to capture important temporal changes by ranking the ordinal labels of longitudinal data. The proposed method find better representation to localize changes and the change rates while ignoring irrelevant subject-wise variations compared to other self-supervised longitudinal learning methods. However, some challenges exist. First, longitudinal changes are often not monotonic. Second, assuming a single temporal factor is unrealistic in the real-world scenarios e.g., numerous factors are involved in brain aging (Mattson and Arumugam, 2018). Third, class activation map (CAM)-based methods are known to have low-resolution visualization due to multiple convolution and pooling layers. Applying full resolution CAM (F-CAM) method (Belharbi et al., 2022) that adds an additional parametric decoder can improve the visualization. Tackling these challenges and improving the proposed method will be our future direction. We believe the simplicity of PaIRNet will make it practical for various longitudinal imaging analysis tasks.

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Appendix A. Parameters?

For learning rate, we used grid search.

Starmen Augmentation diff-resnet18-1layer: 0.001 diff-delta-supervised: 0.01 Supervised: 0.01

Synth Tumor Diff-resnet18-1layer: 0.0001 diff-delta-supervised: 0.01 Supervised: 0.01
Embryo Diff-resnet18-1layer: 0.001 diff-delta-supervised: 0.001 Supervised: 0.001
Brain aging: Diff-resnet18-1layer: 0.001 diff-delta-supervised: 0.01 Supervised: 0.01

Appendix B. PaIRNet classification performance

To show that PaIRNet is an effective method for finding the temporal differences without ground-truth label, we compared the PaIRNet's ranking performance with supervised regression (SR). At inference of SR, the difference of estimated values are used to decide the ranking of a given pair. We did not use the same ranking pairs at testing time, which becomes a binary classification task. The AUC result in Table 1 shows the PaIRNet we can learn the order properly with high accuracy (AUC> 0.95). Although mean square error

(MSE) of regression task (SR-MSE in Table 1 is reasonably low considering standard deviation of ground-truth labels, the ranking using the SR results in Tumor, Embryo and Aging datasets underperform compared to PaIRNet results. This demonstrates that pairwise comparison may be more suitable task for learning difference between images than than SR. The results from Aging dataset highlights this. From the high SR MSE, we can determine predicting age from images is more difficult tasks than others. However, PaIRNet AUC was 0.985, which is comparable to other datasets.

Table 1: AUC result of binary classification from testing sets. Pairwise Imaging Ranking Network (PaIRNet) outperforms supervised regression (SR) results. Although mean square error (MSE) loss of SR is low, the AUC was not as high as PaIRNet.

	Starmen	Tumor	Embryo	Aging
PaIRNet	**1.0**	**0.964**	**0.994**	**0.985**
SR	**1.0**	0.929	0.965	0.893
SR-MSE	0.017	1.239	1.355	40.215