MULTI-SEGMENTAL INFORMATIONAL CODING FOR SELF-SUPERVISED REPRESENTATION LEARNING

ABSTRACT

Self-supervised representation learning aims to map high-dimensional data into a compact embedding space, where samples with similar semantics are close to each other. Currently, most representation learning methods maximize the cosine similarity or minimize the distance between different views from the same sample in an ℓ^2 normalized embedding space, and reduce the feature redundancy via a linear correlation constraint. In this study, we propose MUlti-Segmental Informational Coding (MUSIC) as a new embedding scheme for self-supervised representation learning. MUSIC divides an embedding vector into multiple segments to represent different types of attributes, and each segment automatically learns a set of discrete and complementary attributes. MUSIC enables the estimation of the probability distribution over discrete attributes and thus the learning process can be directly guided by information measurements, reducing the feature redundancy beyond the linear correlation. Our theoretical analysis guarantees that MUSIC learns transform-invariant, non-trivial, diverse, and discriminative features. MUSIC does not require a special asymmetry design, a very high dimension of embedding features, or a deep projection head, making the training framework flexible and efficient. Extensive experiments demonstrate the superiority of MUSIC.

1 INTRODUCTION

Self-supervised representation learning (SSRL) is now recognized as a core task in machine learning with rapid progress over the past years Bengio et al. (2013); LeCun et al. (2015). Deep neural networks pre-trained on large-scale unlabeled datasets via SSRL have demonstrated impressive characteristics, such as strong robustness Hendrycks et al. (2019); Liu et al. (2021) and generalizability Mohseni et al. (2020), and improving various downstream tasks. For SSRL, various pretext tasks were designed such as auto-encoders Vincent et al. (2008); Pathak et al. (2016); Zhang et al. (2016; 2017); He et al. (2022), rotation Gidaris et al. (2018; 2020), patch ordering Noroozi & Favaro (2016); Doersch et al. (2015); Chen et al. (2021), clustering Caron et al. (2018; 2019); Asano et al. (2019); Yan et al. (2020); Huang et al. (2019); Zhuang et al. (2019); Gidaris et al. (2021), and instance discrimination Dosovitskiy et al. (2014); Wu et al. (2018); Tian et al. (2020b); Ye et al. (2019); Dwibedi et al. (2021). Among these pretext tasks, an effective approach is to drive semantically similar samples (*i.e.*, different transformations of the same instance) close to each other in the embedding space. Simply maximizing the similarity or minimizing the Euclidean distance between embedding features of semantically similar samples tends to produce trivial solutions; *e.g.*, all samples have the same embedding features. Recently, various excellent methods have been proposed to learn meaningful representations feature and avoid trivial solutions. Contrastive learning Hadsell et al. (2006); Oord et al. (2018) based methods, such as SimCLR Chen et al. (2020a;b) and MoCo He et al. (2020), have achieved great success by additionally minimizing the similarity between embeddings of the reference and negative samples, which requires either relatively large batches or a large memory bank Wu et al. (2018); Misra & Maaten (2020) for negative samples. To avoid using negative samples, BYOL Grill et al. (2020) and SimSiam Chen & He (2021) developed clever techniques, such as the asymmetry network architecture, stop gradients, and momentum weight updating. Subsequent theoretical analysis Wang & Isola (2020); Zhang et al. (2021); Richemond et al. (2020); Tian et al. (2021) have demonstrated why these techniques avoid trivial solutions and learn meaningful representations from different aspects. Clustering-based methods DeepCluster Caron et al. (2018), SELA Asano et al. (2019), SwAV Caron et al. (2020) alternatively compute the cluster assignment of one

Figure 1: Illustration of the MUSIC vector with piano keys. MUSIC divides an embedding vector into multiple segments (Seg-1, Seg-2, ..., Seg-S) that represent different types of attributes shown in different colors. Each attribute type is associated with a set of discrete and complementary attributes; *e.g.*, Seg-2 represents the texture attribute, and different units in Seg-2 specify different textural patterns, like dots, stripes, etc. (s, d) denotes the dth unit in the sth segment of the embedding vector q. Three representative samples are shown for some units. Each segment s is encoded with a vector $q(s, :)$ normalized by softmax.

view and optimize the network to predict the same assignment for other views of the same sample, where trivial solutions can be avoided via the even assignment of samples over different clusters. In another direction, W-MSE Ermolov et al. (2021) and Barlow Twins Zbontar et al. (2021) propose to drive self- or cross-correlation matrices towards the identity matrix, reducing the feature redundancy and learning meaningful features without requiring the asymmetry design. Most recently, VICReg Bardes et al. (2022) constructs a novel loss function with three terms, i.e., invariance, variance, and covariance constraints that explicitly suppress trivial solutions. A theoretical study Shwartz-Ziv et al. (2022) has given a deep analysis on why VICReg works well.

Fundamentally different from the current SSRL methods that normalize embedding features onto the unit hypersphere via ℓ^2 norm and use cosine similarity as the metric, we propose MUlti-Segmental Informational Coding (MUSIC) for representation learning in a novel way. The motivation is based on the observation that an object can be represented by a set of attributes Russakovsky & Fei-Fei (2010), such as object configuration, texture, shape, etc. As shown in Fig. 1, the embedding vector is divided into multiple segments to represent different types of attributes; *e.g.*, Seg-1, Seg-2, and Seg-S represent object configuration, texture, and shape, respectively. Each segment instantiates a set of specific attributes; *e.g.*, Seg-2 represents samples with different textural patterns (dots, stripes, etc.). In other words, each attribute type consists of a set of discrete and complementary attributes encoded by a one-hot vector, making it possible to estimate the probability distribution over specific attributes. Complex visual images are expected to be represented by a diversity of informational attributes, meaning that mutual information between different attributes should be minimal. To automatically learn such MUSIC embeddings from unlabeled datasets, we introduce an entropy-based loss function given the estimated probability distribution. The theoretical analysis based on information theory reveals why meaningful features can be promoted while trivial solutions are avoided. In particular, the entropy loss is minimizing any form of dependency between feature variables beyond the linear correlation.

The characteristics of MUSIC are as follows. (1) MUSIC presents a new embedding scheme and an information-theoretic optimization framework for SSRL. (2) Theoretical analysis ensures that the MUSIC embeddings are optimized to be transform-invariant, non-trivial, diverse, and discriminative. (3) Similar to Barlow Twins and VICReg, MUSIC does not require an asymmetry network architecture, negative samples in a large batch or a memory bank, gradient stopping, or momentum updating. (4) MUSIC does not need a very high dimension of embedding features or a deep projection head, significantly reducing the computational cost. (5) Extensive experimental results demonstrate the superiority of MUSIC on representative datasets in various evaluation settings.

2 METHODOLOGY

2.1 SELF-SUPERVISED LEARNING FRAMEWORK

Similar to W-MSE and Barlow Twins, in this study we adopt a twin architecture to learn the embedding features, where the same network is shared between two branches, as shown in Fig. 2.

Figure 2: SSRL framework through multi-segmental informational coding optimized with maximum entropy. Here there are four segments and each segment consists of four units for illustration.

During training, input images $\mathbb{X} = \{\boldsymbol{x}_i\}_{i=1}^N$ are mapped to two distorted sets $\mathbb{X}' = \{\boldsymbol{x}'_i\}_{i=1}^N$ and $\mathbb{X}'' = \{\boldsymbol{x}''_i\}_{i=1}^N$, where N is the batch size. A common transformation distribution, which covers random crops combined with color distortions, the same as that in Bardes et al. (2022), is used to generate training samples. Then, the two sets of distorted images $\mathbb{X}'$ and $\mathbb{X}''$ are respectively fed to two branches, each of which consists of an encoder $f(\cdot; \boldsymbol{\theta}_f)$ and a projector $g(\cdot; \boldsymbol{\theta}_g)$, where $\boldsymbol{\theta}_f$ and $\boldsymbol{\theta}_g$ respectively denote the parameters of the encoder and projector to be optimized. The outputs of the encoder are commonly used as the representation features. The projection head maps the representation features into the embedding space. Note that the presented method is not limited to this twin architecture, which can be extended to the two branches with different parameters, heterogeneous networks, or even different input modalities (e.g., text, audio, etc.) as studied in VICReg.

2.2 MULTI-SEGMENTAL INFORMATIONAL CODING

MUlti-Segmental Informational Coding (MUSIC) is a novel embedding scheme for SSRL. The embedding features of two transformed images are $\boldsymbol{z}'_i = g(f(\boldsymbol{x}'_i; \boldsymbol{\theta}_f); \boldsymbol{\theta}_g) \in \mathbb{R}^D$, and $\boldsymbol{z}''_i = g(f(\boldsymbol{x}''_i; \boldsymbol{\theta}_f); \boldsymbol{\theta}_g) \in \mathbb{R}^D$ respectively, where D is the feature dimension. Most of the existing SSRL methods normalize embedding features in the ℓ^2 norm and then maximize their cosine similarity between the two transformed versions. Motivated by the observation described in Fig. 1, we divide the embedding feature $\boldsymbol{z}_i$ into multiple segments to represent different types of attributes, denoted by $\boldsymbol{z}_i(s, d), s = 1, \cdots, S, d = 1, \cdots, D_s$, where S is the number of segments, D_s is the dimension of the sth segment. In this study, we evenly split the embedding vector, i.e., $\forall s, D_s = D_S$, and the dimension of the whole embedding space is $D = D_S \times S$. In principle, uneven partitions can be applied as well given prior knowledge. To make attributes discrete and complementary, one-hot encoding is applied to each segment. Specifically, each segment is normalized to a score vector using the softmax function:

$$\boldsymbol{q}'_i(s', d') = \frac{\exp(\boldsymbol{z}'_i(s', d'))}{\sum_{d=1}^{D_S} \exp(\boldsymbol{z}'_i(s', d))}, \tag{1}$$

where $\boldsymbol{q}'_i(s', d')$ denotes the score of the image $\boldsymbol{x}'_i$ belongs to the d'-th instantiated attribute in the s'-th segment. The score vector $\boldsymbol{q}''_i(s'', :)$ for the other branch is computed in the same way. Thus, the MUSIC scheme can be interpreted as a combination of multiple classifiers or cluster operators that implement different classification criteria learned in a data-driven fashion.

2.3 ENTROPY LOSS

Since each type of attribute has a finite number of discrete instantiations, it is possible to estimate the probability distribution of a set of samples over each and every segment. Specifically, we can compute the empirical joint distribution $\boldsymbol{P}(s', s'', d', d'')$ between every two instantiated attributes

within and across segments based on a set of samples as follows:

$$\boldsymbol{P}(s', s'', d', d'') = \frac{1}{N} \sum_{i=1}^{N} \boldsymbol{q}'_i(s', d') \boldsymbol{q}''_i(s'', d''), \tag{2}$$

where $\boldsymbol{P}(s', s'', d', d'')$ is computed as the statistical frequency of the sample having both the attribute-d' in the segment-s' and the attribute-d'' in the segment-s'' over N samples. With the empirical joint probability distribution, information-theoretic metrics can be directly computed. Here two versions of the loss function are defined. The first version L_{ent} is a pure joint entropy loss:

$$L_{ent} = \frac{1}{S^2} \sum_{s'=1}^{S} \sum_{s''=1}^{S} \sum_{d'=1}^{D_S} \sum_{d''=1}^{D_S} (1 - \mathbf{1}_{s'=s'',d'\neq d''}) \boldsymbol{P}(s', s'', d', d'') \log(\boldsymbol{P}(s', s'', d', d'')), \tag{3}$$

where $\mathbf{1}_{s'=s'',d'\neq d''}$ is an indicator function that equals to 1 if $s' = s''$ and $d' \neq d''$; otherwise, it is equal to 0. The empirical joint distribution can be denoted by a block matrix as shown in Fig. 2, where $(1 - \mathbf{1}_{s'=s'',d'\neq d''})$ means keeping the diagonal elements of the diagonal blocks and all elements of the off-diagonal blocks, as indicated by the orange area. Therefore, minimizing this loss function is maximizing the joint entropy over the selected elements. The following subsection will demonstrate the properties of the embedding features learned by optimizing this loss function.

To enhance the transformation invariance of features, we introduce an additional term to maximize the inner product between the embedding features from two transformations. Then, the second version of the loss function is defined as

$$L = L_{ent} - \lambda \frac{1}{NS} \sum_{i=1}^{N} \sum_{s=1}^{S} \sum_{d=1}^{D_S} \log(\boldsymbol{q}'_i(s, d) \boldsymbol{q}''_i(s, d)), \tag{4}$$

where λ is a balancing factor. By default, we set $\lambda = 1$, which is in principle neither too small nor too large for a good balance. Minimizing the transformation invariance loss enforces the embedding features between two transformations of the same image to be consistent and encourages the embedding feature within each segment to be one-hot. Clearly, this additional term promotes transformation invariance and confident assignments over different attributes. Different from the statistical entropy measurement, this transformation invariance term imposes a sample-specific constraint. The transformation invariance can be also achieved by minimizing the cross-entropy between the two embedding vectors, *i.e.*, $-\frac{1}{NS} \sum_{i=1}^{N} \sum_{s=1}^{S} \sum_{d=1}^{D_S} \boldsymbol{q}'_i(s, d) \log(\boldsymbol{q}''_i(s, d))$. However, by using the cross-entropy the performance would be degraded, as reported in Subsection 4.2.

Our proposed method can be easily implemented, with a PyTorch-style pseudo-code in Appendix A. Next, let us theoretically analyze why the entropy loss optimizes informational embedding features as illustrated in Fig. 1.

2.4 ANALYSIS

The entropy loss function consists of two parts, including the entropy over diagonal elements of diagonal blocks and the entropy over all elements of off-diagonal blocks as illustrated by the orange area in Fig. 2, and can be formally expressed as

$$
\begin{aligned}
L_{ent} =& \frac{1}{S} \sum_{s',s'',s'=s''} \sum_{d',d'',d'=d''} \boldsymbol{P}(s', s'', d', d'') \log(\boldsymbol{P}(s', s'', d', d'')) \\
&+ \frac{1}{S(S-1)} \sum_{s',s'',s'\neq s''} \sum_{d',d''} \boldsymbol{P}(s', s'', d', d'') \log(\boldsymbol{P}(s', s'', d', d'')).
\end{aligned} \tag{5}
$$

For the first part, it can be demonstrated that its optimal solution is that $\forall i, s, d, \boldsymbol{q}'_i(s, d) = \boldsymbol{q}''_i(s, d)$, $\boldsymbol{q}'_i(s, :)$ and $\boldsymbol{q}''_i(s, :)$ are one-hot vectors, the statistical probability of the sth attribute type taking the dth instantiation is $\boldsymbol{p}(s, d) = \frac{1}{N} \sum_{i=1}^{N} \boldsymbol{q}_i(s, d) = \frac{1}{D_S}$, and $\boldsymbol{P}(s, s, d, d) = \frac{1}{D_S}$. The proof can be found in Appendix B. For the second part, it is intuitive that the optimal solution to maximize the joint entropy over the off-diagonal block items is $\forall s', s'', d', d'', s' \neq s'', \boldsymbol{P}(s', s'', d', d'') = \frac{1}{(D_S)^2}$; *i.e.*, a batch of samples are evenly assigned over each off-diagonal block.

Transformation invariance: The solution that $\forall i, s, \boldsymbol{q}'_i(s,:) = \boldsymbol{q}''_i(s,:)$ are one-hot vectors means that the learned MUSIC embeddings are invariant to transformations, and a sample tends to be confidently represented by a single instantiated attribute within each and every segment.

Non-trivial solution: The solution that $\frac{1}{N} \sum_{i=1}^{N} \boldsymbol{q}_i(s,d) = \frac{1}{D_S}$ means that a batch of samples are evenly partitioned over different attributes in each segment as $\boldsymbol{q}'_i(s,:)$ and $\boldsymbol{q}''_i(s,:)$ are one-hot vectors. Thus, the trivial solution that all samples have the same embedding features can be avoided.

Minimum redundancy: As described in Fig. 1, different segments of the MUSIC embedding vector are expected to focus on diverse and complementary attributes. In other words, the redundancy or mutual information between any two segments should be minimized, which is a popular measure for feature selection Peng et al. (2005). Specifically, it can be demonstrated that the redundancy or mutual information between any two segments is minimized when the optimal solution is obtained. Specifically, the mutual information $I(s', s'')$ between any two segments s' and s'' is

$$
\begin{aligned}
I(s', s'') =& H(s') + H(s'') - H(s', s'') \\
=& - \sum_{d'=1}^{D_S} \boldsymbol{p}'(s', d') \log(\boldsymbol{p}'(s', d')) - \sum_{d''=1}^{D_S} \boldsymbol{p}''(s'', d'') \log(\boldsymbol{p}''(s'', d'')) \\
& + \sum_{d'=1}^{D_S} \sum_{d''=1}^{D_S} \boldsymbol{P}(s', s'', d', d'') log(\boldsymbol{P}(s', s'', d', d'')) \\
=& - log \frac{1}{D_S} - \log \frac{1}{D_S} + \log \frac{1}{(D_S)^2} = 0.
\end{aligned}
\tag{6}
$$

Thus, the mutual information is minimized and diverse attributes are learned. From another perspective, $\forall s', s'', d', d'', s' \neq s''$, we have $\boldsymbol{P}(s', s'', d', d'') = \frac{1}{(D_S)^2} = \boldsymbol{p}(s', d')\boldsymbol{p}(s'', d'')$, and thus the variables $\boldsymbol{q}(s', d')$ and $\boldsymbol{q}(s'', d'')$ are independent. The redundancy constraint was studied for W-MSE, Barlow Twins, and VICReg by minimizing the covariance or linear correlation. In contrast, our entropy-based loss function reduces the redundancy or mutual information in a non-linear way. Moreover, it can be derived that the optimal MUSIC embedding features have zero covariance between any two features in different segments and negative covariance between the features within the same segment; for details, please see Appendix B.

Discriminative encoding: Contrastive learning or instance discrimination has proven very effective for representation learning by maximizing the similarity between different transformations of the same instance while discriminating the reference from other instances. It is underlined that MUSIC is consistent to contrastive learning and discriminating instances in a novel way. Specifically, the optimal MUSIC embedding can totally encode $(D_S)^S$ different samples. In our default settings $D_S = 80, S = 102$ (See Section 3 for details), MUSIC can represent 80^{102} different samples. Maximizing the joint entropy is to evenly assign a batch of samples into all possible embeddings, which means that the embedding features of all instances are enforced to be different from each other like in contrastive learning, given the sufficiently large coding capacity. The difference lies in that contrastive learning differentiates instances by pushing the reference away from its negative instances, while MUSIC statistically assigns instances with different attribute codes.

In Appendix C, the individual MUSIC embeddings and the empirical joint probability matrix learned on the ImageNet dataset are visualized, showing that the empirical results are consistent with the above theoretical analysis. In summary, the MUSIC embedding features optimized with the entropy-based loss are transform-invariant, non-trivial, diverse, and discriminative.

3 IMPLEMENTATION DETAILS

For a fair comparison, we closely followed the implementation settings in VICReg to train MUSIC models. Specifically, the standard ResNet-50 backbone He et al. (2016) was used as the encoder that outputs a representation vector of 2,048 units in the same training settings, including the data augmentation (random cropping, horizontal flip, color jittering, grayscale, Gaussian blur, solarization, with the same parameters in VICReg), the optimizer of LARS You et al. (2017); Goyal et al. (2017) with a weight decay of 10^{-6} and the learning rate of $lr = batch\_size/256 \times base\_lr$, and the cosine decay schedule Loshchilov & Hutter (2016) from 0 with 10 warmup epochs towards the

final value of 0.002. The base learning rate $base\_lr$ was set to 0.6 in our study. By default, we used a two-layer MLP projector (8,192-8,160), the number of segments $S = 102$, the segment dimension $D_S = 80$, and $D = D_S \times S = 8,160$ (similar to the feature dimension of $8,192$ used by VICReg and Barlow Twins). The results were respectively analyzed for different feature dimensions, depths of projectors, batch sizes, segment dimensions, and numbers of training epochs. The effect of the single extra hyperparameter D_S of MUSIC was evaluated as well. The SSRL models were trained on the 1,000-classes ImageNet dataset without labels and evaluated in various downstream tasks. All implementation details for downstream tasks are in Appendix F. Code will be made available.

4 RESULTS

4.1 EVALUATION RESULTS IN DIFFERENT TASKS

Table 1: **Comparison of SSRL methods on ImageNet for linear and semi-supervised classification**. Top-1 and Top-5 accuracies (in %) are reported. The best three results are underlined.

Methods	Linear Classification		Semi-supervised Learning			
	Top-1	Top-5	Top-1		Top-5	
			1%	10%	1%	10%
Supervised	76.5	-	25.4	56.4	48.4	80.4
MoCo He et al. (2020)	60.6	-	-	57.2	83.8	
PIRL Misra & Maaten (2020)	63.6	-	-	-	-	-
CPC v2 Henaff (2020)	63.8	-	-	-	-	-
CMC Tian et al. (2020a)	66.2	-	-	-	-	-
SimCLR Chen et al. (2020a)	69.3	89.0	48.3	65.6	75.5	87.8
MoCo v2 Chen et al. (2020c)	71.1	90.1	-	-	-	-
SimSiam Chen & He (2021)	71.3	-	-	-	-	-
SwAV Caron et al. (2020)	71.8	-	-	-	-	-
InfoMin Aug Tian et al. (2020b)	73.0	91.1	-	-	-	-
BYOL Grill et al. (2020)	74.3	91.6	53.2	68.8	78.4	89.0
Barlow Twins Zbontar et al. (2021)	73.2	91.0	55.0	69.7	79.2	89.3
VICReg Bardes et al. (2022)	73.2	91.1	54.8	69.5	79.4	89.5
MUSIC (Ours)	73.6	91.4	54.0	69.1	78.9	89.1

Linear Classification on ImageNet. Linear probing is the commonly used evaluation protocol that trains a linear classifier on top of the frozen representations to evaluate the performance of SSRL methods. Being consistent with Barlow Twins and VICReg, a ResNet-50 backbone was trained with the batch size of 2,048 for 1,000 epochs on the training set of ImageNet, and the linear classification results including Top-1 and Top-5 accuracies of different methods on the evaluation set are reported in Table 1. The difference from Barlow Twins and VICReg is that MUSIC used a two-layer MLP projector (8,192-8,160) instead of three layers (8,192-8,192-8,192). The performance of MUSIC is on par with the state of the art method BYOL that uses asymmetric techniques, such as an additional predictor and a momentum encoder. Note that the results of some excellent methods Caron et al. (2020); Gidaris et al. (2021) based on multi-crop/multi-positive techniques are not included in Table 1. These techniques can usually boost performance further. The comparative results show that MUSIC achieves better results than Barlow Twins and VICReg, where all these three methods trained a twin architecture without using negative pairs or any asymmetric techniques.

Semi-Supervised Classification on ImageNet. We also evaluated MUSIC in the semi-supervised learning setting, where the pre-trained ResNet-50 with MUSIC was fine-tuned on subsets of ImageNet, including 1% and 10% of the full ImageNet dataset respectively, and all reported methods used the same subset images. Currently, MUSIC is not as good as Barlow Twins and VICReg in the semi-supervised learning settings, while it is better than BYOL and other compared methods, and significantly better than purely supervised learning without SSRL pretraining.

Transfer Learning. Transfer learning is another popular way for the evaluation of SSRL methods, including object detection, instance segmentation, and linear classification. Our results are reported

Table 2: **Transfer Learning**. For object detection and instance segmentation tasks, SSRL models pre-trained on ImageNet were used to initialize the backbone of the object detection and instance segmentation models on COCO. Mask R-CNN He et al. (2017) with the C4 backbone variant Wu et al. (2019) was fine-tuned using the 1 schedule. AP metrics defined by COCO are reported here. For the linear classification task, Top-1 accuracy (in %) for Places205 Zhou et al. (2014) and mAP for VOC07 Everingham et al. (2010) are based on the frozen representations pre-trained on ImageNet. The best results are in **bold**.

Methods	Object Detection			Instance Segmentation			Linear Classification	
	AP^{bb}	AP^{bb}_{50}	AP^{bb}_{75}	AP^{mk}	AP^{mk}_{50}	AP^{mk}_{75}	VOC2007	Places205
Sup.	38.2	58.2	41.2	33.3	54.7	35.2	87.5	53.2
MoCo-v2	**39.3**	58.9	42.5	**34.4**	55.8	36.5	86.4	51.8
SwAV	38.4	58.6	41.3	33.8	55.2	35.9	86.4	52.8
SimSiam	39.2	**59.3**	42.1	**34.4**	**56.0**	**36.7**	-	-
BT	39.2	59.0	42.5	34.3	**56.0**	36.5	86.2	54.1
MUSIC (Ours)	**39.3**	59.1	**42.6**	**34.4**	55.8	36.6	**86.5**	**54.8**

in Table 2. It is noted that various studies have different setups for the object detection and instance segmentation tasks. Here we closely followed Zbontar et al. (2021) selecting the same comparison methods in the same settings. MUSIC performs on par with the current methods and slightly better than Barlow Twins on the object detection and segmentation tasks. On the other hand, the linear classification results on VOC2007 and Places205 datasets show that MUSIC achieved better results than the selected methods. Also, similar to the other SSRL methods, MUSIC can effectively improve the downstream tasks in the transfer learning settings. All implementation details for the reproduction of transfer learning results are in Appendix F.2.

Table 3: **KNN classification**. Top-1 accuracy with 20 and 200 nearest neighbors are reported. The best results are highlighted in **bold**.

Method	20-NN	200-NN
NPID Wu et al. (2018)	-	46.5
LA Zhuang et al. (2019)	-	49.4
PCL Li et al. (2021)	54.5	-
BYOL Grill et al. (2020)	66.7	**64.9**
SwAV Caron et al. (2020)	65.7	62.7
BT Zbontar et al. (2021)	64.8	62.9
VICReg Bardes et al. (2022)	64.5	62.9
MUSIC (Ours)	**67.0**	**64.9**

Table 4: **Batch Size.** Top-1 accuracy (in %) results for linear classification on ImageNet were obtained based on ResNet50 with 100 pre-training epochs. The best results are highlighted in **bold**.

Batch Size	512	1024	2048	4096
SimSiam	68.1	68.0	67.9	64.0
VICReg	68.2	68.3	68.6	67.8
MUSIC	**68.3**	**69.3**	**69.4**	**68.7**

KNN Classification on ImageNet. Another common protocol for evaluating representation learning methods is by K-Nearest-Neighbors (KNN) classification on ImageNet. We followed the recent studies Wu et al. (2018); Zhuang et al. (2019); Caron et al. (2020); Bardes et al. (2022) that built KNN classifiers with the learned representations on the training set of ImageNet and evaluated the KNN classification results on the validation set of ImageNet. The results with 20 and 200 nearest neighbors are reported in Table 3, showing that MUSIC achieved the best performance among the comparison methods. Since the KNN classifier determines the class of a sample by directly searching its nearest samples in the feature space, the representation features learned by MUSIC is more semantically similar to each other among the nearest neighbors than those learned by other methods. Thus, MUSIC has the potential superiority when applied to the downstream tasks based on the nearest neighbors search.

All the above results demonstrate the effectiveness of MUSIC as a new embedding strategy in with the information-theoretic optimization framework. In the following subsections, the characteristics and superiority of MUSIC will be further discussed.

4.2 EMPIRICAL ANALYSIS

In this subsection, we comprehensively evaluate the proposed MUSIC method in various settings and compare it with other SSRL methods if the corresponding results in the same or comparable settings were already reported. All the models were evaluated with linear classification on ImageNet.

Effect of Batch Size. SSRL methods usually require a large batch size or a memory bank especially for contrastive learning. Here we evaluated MUSIC with different batch sizes and the results are reported in Table 4. It shows that MUSIC achieved consistently better results than the latest method VICReg over different batch sizes. As discussed in Subsection 2.4, an intrinsic property of MUSIC is to discriminatively encode different instances, making it work well without a large number of contrastive samples.

Table 5: **Training epochs**. Top-1 accuracy (in %) of linear classification on ImageNet using ResNet-50. The best results are highlighted in **bold** while the second best results are underlined.

Methods	SimCLR	MoCo v2	BYOL	SwAV	SimSiam	MUSIC
100 epochs	66.5	67.4	66.5	66.5	68.1	**69.4**
200 epochs	68.3	69.9	70.6	69.1	70.0	**71.8**
400 epochs	69.8	71.0	**73.2**	70.7	70.8	73.1
800 epochs	70.4	72.2	**74.3**	71.8	71.3	73.4

Effect of Epoch Number. The SSRL methods in different studies do not always use the same training epochs due to different computational costs and environments. MUSIC was evaluated with different numbers of training epochs as reported in Table 5. MUSIC is consistently better than most of the existing methods on all different training epochs. When the numbers of training epochs were small (100 and 200), MUSIC can converge to the best results.

Table 6: **Projector Depth**. The best results are highlighted in **bold**.

Table 7: **Feature Dimension**. The best Top-1 accuracies are highlighted in **bold**.

Depth	2	3	4
Top-1	**69.4**	68.5	67.9
Top-5	**89.3**	88.3	87.9
Time/100ep	8.5h	9.6h	10.8h
Memory/GPU	10.4G	11.5G	12.5G

D_{VICReg}	1024	2048	4096	8192	16384
D_{MUSIC}	960	2000	4080	8160	16320
VICReg	62.4	65.1	67.3	68.6	68.8
MUSIC	**64.1**	**66.6**	**69.2**	**69.4**	**69.1**
Time/100ep	7.6h	7.7h	8.0h	8.5h	10.9h
Memory/GPU	7.6G	8.0G	8.5G	10.4G	15.9G

Effect of Projector Depth. The existing studies Chen & He (2021); Zbontar et al. (2021); Bardes et al. (2022) show that using a three-layer MLP as the projector achieved the best results. However, MUSIC has a different behavior that a two-layer MLP achieved the best results as shown in Table 6. It may be due to the discriminability and diversity of MUSIC embeddings, allowing it to learn informational representations more effectively. At the same time, the computational cost can be reduced, especially for the fully-connected MLP with high-dimensional inputs and outputs. The running time per 100 epochs and the peak memory per GPU for different projector depth are reported in Table 6, where the computational environment is described in Appendix D. Moreover, the comparison results of different methods in Appendix E show that MUSIC cannot only reduce the running time and memory cost but also achieves better performance than Barlow Twins and VICReg.

Effect of Feature Dimension. In the previous Barlow Twins and VICReg studies, it was found that a very high-dimensional embedding vector is necessary for improving the representation learning performance. For MUSIC, the feature dimension plays an important role as well. The results of different feature dimensions for VICReg and MUSIC are reported in Table 7, where the the dimensions of MUSIC embeddings are similar to those of VICReg embeddings while keeping the dimension of each segment the same, $D_S = 80$. It can be seen that MUSIC achieved consistently better results than VICReg on different embedding feature dimensions. Importantly, when the embedding feature dimension was reasonably large (4,096 and 8,192), MUSIC achieves the best results that are even better than the best results of VICReg using the larger dimension of 16,384. This is because that minimizing linear correlation by the existing methods cannot ensure the minimized

Table 8: **Loss terms**. The best results are highlighted in **bold**.

Loss	DE+OE	OE+TI	DE+OE+TIC	DE+OE+TI
Top-1	65.4	64.1	68.3	**69.4**
Top-5	86.9	86.4	88.6	**89.3**

Table 9: **Segment Dimension**. The best results are highlighted in **bold**.

D_S	32	64	80	96	128
Top-1	67.8	69.1	**69.4**	69.2	68.4
Top-5	88.5	89.1	**89.3**	89.1	88.5

non-linear dependency while MUSIC can minimize any form of dependency between any two feature variables. Therefore, the redundancy between MUSIC feature variables tends to be lower than the existing methods so that feature dimension can be reduced for even better results. In principle, the large embedding feature dimension (i.e., 16,384) significantly increases the computational and memory cost for Barlow Twins, VICReg, and MUSIC that compute the covariance or joint probability matrix, which was also discussed in the Barlow Twins study Zbontar et al. (2021). This point is demonstrated in Table 7 by evaluating running time and memory cost, where the computational environment is described in Appendix D. Thus, MUSIC is both efficient and effective.

Effect of Loss Function. The effect of different loss terms was evaluated in Table 8, where DE, OE, TIC, and TI denote the diagonal entropy loss, off-diagonal entropy loss, transformation invariance loss implemented with cross-entropy, and transformation invariance loss implemented with inter-product, respectively. As described in Subsection 2.4, only optimizing the entropy loss (DE+OE) allows MUSIC to avoid trivial solutions and learn informational representations. This theoretical analysis is consistent with the empirical results in Table 8 that 65.4% Top-1 was achieved using the entropy loss only, comparable to some methods reported in Table 1. Adding the enhanced transformation invariance constraint in instance-level significantly improved the performance, as also discussed in the Subsection 2.3. Without adding the DE loss, the results were significantly degraded, as the DE loss not only enhances the transformation invariance but also helps learn non-trivial and complementary attributes in each and every segment. In our experiments, minimizing the cross-entropy degraded the performance compared with the inner-product implementation.

Effect of Segment Dimension. Finally, the effect of our unique hyperparameter, *i.e.*, segment dimension, was evaluated. Our empirical results with different segment dimensions in Table 9 indicate that $D_S = 80$ achieved the best results, where the dimension of the whole embedding vector was kept the same. It shows that the representation performance is not sensitive to this hyperparameter.

5 DISCUSSIONS AND CONCLUSION

From pairwise independence to mutual independence. Although MUSIC is minimizing the pairwise independence, the minimum mutual independence among multiple feature variables cannot be ensured Gallager (2013). In other words, redundancy may still exist among multiple feature variables. Similar to the study Niu & Wang (2022) that imposes high-order moment constraints on the embedding features, maximizing joint entropy among multiple variables could be implemented to reduce the redundancy further for even better self-learning performance.

From representation learning to hierarchical clustering. Each segment in MUSIC can be regarded as a clustering head, while different segments promote different and independent clustering criteria. In this study, we mainly focus on the general representation learning task, where each segment has the same number of clusters and every two segments are independent. This idea could be extended to hierarchical clustering; *e.g.*, different segments may have different numbers of hierarchical clusters and the independence constraint between segments can be adapted with task prior.

In conclusion, we have presented the multi-segment informational coding (MUSIC) scheme optimized with an entropy-based loss function for self-supervised representation learning. Theoretical analysis ensures that the optimized embedding features are transform-invariant, non-trivial, diverse, and discriminative. Our empirical results are consistent with the theoretical findings. Interestingly, MUSIC has shown unique characteristics that the MLP projector can be shallower, the batch size and the embedding feature dimension can be smaller, effectively reducing the computational cost while achieving comparable or better results than the existing methods. Various evaluation results clearly show the effectiveness and superiority of MUSIC. In the future, MUSIC would be adapted to more downstream tasks, such as clustering, multi-modality imaging, and other applications.

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APPENDIX A   PYTORCH PSEUDOCODE

An exemplary implementation for MUSIC in the PyTorch-style is described in Algorithm 1.

Algorithm 1: PyTorch-style pseudocode for MUSIC

```
# f:  network function
# lambda:  weight on the transformation invariance loss term
# N: batch size
# D: dimensionality of the embedding vector
# D_S: dimensionality of each segment
# S=D/D_S: number of segments
#
# select:  select the diagonal elements of diagonal blocks and
 all elements of off-diagonal blocks

for x in loader:  # load a batch with N samples
  # two randomly augmented versions of x
  x', x'' = augment(x)

  # compute embeddings
  z' = f(x')
  z'' = f(x'')

  # multi-segmental informational coding
  x' = torch.reshape(x', [N, -1, D_S]) # N×S×D_S
  x'' = torch.reshape(x'', [N, -1, D_S]) # N×S×D_S
  q' = torch.softmax(x', dim=2) # softmax normalization
  q'' = torch.softmax(x'', dim=2) # softmax normalization

  # compute transformation invariance loss
  loss_TI = -torch.log((q'*q'').sum(dim=2)).mean()

  # compute entropy loss
  q' = torch.reshape(q', [N, D]) # N × D
  q'' = torch.reshape(q'', [N, D]) # N × D
  P = torch.einsum('np,nq->pq', [q', q'']) / N # compute
   empirical joint probability distribution
  P_s = select(P)
  loss_ent = (P_s * torch.log(P_s)).sum() / (S × S)

  # final loss
  loss = loss_ent + lambda * loss_TI # lambda=1 by default

  # optimization step
  loss.backward()
  optimizer.step()
```

APPENDIX B   THEORETICAL ANALYSIS

The optimal solution to the first part in L_{ent}. As described in Subsection 2.4, the entropy loss function consists of two parts: (1) the entropy over diagonal elements of diagonal blocks and (2) the entropy over all elements of off-diagonal blocks, as illustrated in Fig. 2. Now, let us minimize the first part, which is formulated as

$$L_{ent} = \frac{1}{S} \sum_{s',s'',s'=s''} \sum_{d',d'',d'=d''} \boldsymbol{P}(s',s'',d',d'') \log(\boldsymbol{P}(s',s'',d',d'')) \tag{B-7}$$

Since every diagonal block has the same optimal solution, we only need to consider the sth diagonal block, and the objective function can be simplified as

$$L_{ent}(s, s) = \sum_{d=1}^{D_S} \boldsymbol{P}(s, s, d, d) \log(\boldsymbol{P}(s, s, d, d)) \tag{B-8}$$

where $0 \leq \boldsymbol{P}(s, s, d, d) \leq 1, 0 \leq \sum_{d=1}^{D_S} \boldsymbol{P}(s, s, d, d) \leq 1$. Then, it is easy to find the solution that minimizes this objective function; i.e., $\forall s, d, \boldsymbol{P}(s, s, d, d) = \frac{1}{D_S}$. Thus, $\forall s, d$, we have

$$\sum_{d} \boldsymbol{P}(s, s, d, d) = \sum_{d=1}^{D_S} \frac{1}{D_S} = 1 \tag{B-9}$$

As defined in Eqs. (1) and (2), we have $\forall s, d, 0 \leq \boldsymbol{q}'_i(s, d) \leq 1, 0 \leq \boldsymbol{q}''_i(s, d) \leq 1, \sum_{d=1}^{D_S} \boldsymbol{q}'_i(s, d) = 1, \sum_{d=1}^{D_S} \boldsymbol{q}''_i(s, d) = 1$, and $\boldsymbol{P}(s, s, d, d) = \frac{1}{N} \sum_{i=1}^{N} \boldsymbol{q}'_i(s, d) \boldsymbol{q}''_i(s, d)$.

Given the above conditions, let us next prove that for $\forall s, \exists d, \boldsymbol{q}'_i(s, d) = \boldsymbol{q}''_i(s, d) = 1$ by contradiction.

If its negation is true, *i.e.*, $\forall s, d$, either $0 \leq \boldsymbol{q}'_i(s, d) < 1$ or $0 \leq \boldsymbol{q}''_i(s, d) < 1$, then we have $\forall s, d$, either $\boldsymbol{q}'_i(s, d) < \sum_{d'=1}^{D_S} \boldsymbol{q}'_i(s, d') = 1$, or $\boldsymbol{q}''_i(s, d) < \sum_{d''=1}^{D_S} \boldsymbol{q}''_i(s, d'') = 1$. For $\boldsymbol{q}''_i(s, d) < \sum_{d''=1}^{D_S} \boldsymbol{q}''_i(s, d'') = 1$, we have

$$\begin{aligned}
\sum_{d=1}^{D_S} \boldsymbol{P}(s, s, d, d) &= \sum_{d=1}^{D_S} \frac{1}{N} \sum_{i=1}^{N} \boldsymbol{q}'_i(s, d) \boldsymbol{q}''_i(s, d) \\
&= \frac{1}{N} \sum_{i=1}^{N} \sum_{d=1}^{D_S} \boldsymbol{q}'_i(s, d) \boldsymbol{q}''_i(s, d) \\
&< \frac{1}{N} \sum_{i=1}^{N} \sum_{d=1}^{D_S} \left(\boldsymbol{q}'_i(s, d) \sum_{d''}^{D_S} \boldsymbol{q}''_i(s, d'') \right) \\
&= 1
\end{aligned} \tag{B-10}$$

That is, $\sum_d \boldsymbol{P}(s, s, d, d) < 1$, which leads to a contradiction with Eq. (B-9). Similarly, we have the same contradiction for $\boldsymbol{q}'_i(s', d) < \sum_{d'=1}^{D_S} \boldsymbol{q}'_i(s', d') = 1$. Therefore, the statement that $\forall s, \exists d, \boldsymbol{q}'_i(s, d) = \boldsymbol{q}''_i(s, d) = 1$ is true. It means that for $\forall s, \boldsymbol{q}'_i(s, :)$ and $\boldsymbol{q}''_i(s, :)$ are one-hot vectors and equal to each other.

Because $\forall s, d, \boldsymbol{P}(s, s, d, d) = \frac{1}{D_S}, \boldsymbol{q}'(s, d) = \boldsymbol{q}''(s, d)$, and $\boldsymbol{q}'(s, :)$ and $\boldsymbol{q}''(s, :)$ are one-hot vectors, then $\boldsymbol{P}(s, s, d, d) = \frac{1}{N} \sum_{i=1}^{N} \boldsymbol{q}'_i(s, d) \boldsymbol{q}''_i(s, d) = \frac{1}{N} \sum_{i=1}^{N} \boldsymbol{q}'_i(s, d) = \boldsymbol{p}(s, d) = \frac{1}{D_S}$.

Covariance of the optimal solution. The optimal solution to maximize the joint entropy over the off-diagonal blocks for the second part is $\forall s' \neq s'', \boldsymbol{P}(s', s'', d', d'') = \mathbb{E}[\boldsymbol{q}(s', d') \boldsymbol{q}(s'', d'')] = \frac{1}{(D_S)^2}$. According to the above proof, we have $\forall s, d, \boldsymbol{p}(s, d) = \mathbb{E}[\boldsymbol{q}(s, d)] = \frac{1}{D_S}$. We can theoretically demonstrate that the covariance is zero between any two units from different segments. Specifically, $\forall s', s'', d', d'', s' \neq s''$, we have

$$\begin{aligned}
\text{cov}[\boldsymbol{q}(s', d'), \boldsymbol{q}(s'', d'')] &= \mathbb{E}[\boldsymbol{q}(s', d') \boldsymbol{q}(s'', d'')] - \mathbb{E}[\boldsymbol{q}(s', d')] \mathbb{E}[\boldsymbol{q}(s'', d'')] \\
&= \frac{1}{(D_S)^2} - \frac{1}{D_S} \times \frac{1}{D_S} = 0.
\end{aligned} \tag{B-11}$$

Since $\forall s, d', d'', \sum_{d', d''} \boldsymbol{P}(s, s, d', d'') = 1$ and $\forall s, d', d'', d' = d'', \boldsymbol{P}(s, s, d', d'') = \frac{1}{D_S}$, then $\forall s, d', d'', d' \neq d'', \boldsymbol{P}(s, s, d', d'') = 0$. We can demonstrate that any two units within the same segment are negatively correlated. Formally, $\forall s, d', d'', d' \neq d''$, we have

$$\begin{aligned}
\text{cov}[\boldsymbol{q}(s, d'), \boldsymbol{q}(s, d'')] &= \mathbb{E}[\boldsymbol{q}(s, d') \boldsymbol{q}(s, d'')] - \mathbb{E}[\boldsymbol{q}(s, d')] \mathbb{E}[\boldsymbol{q}(s, d'')] \\
&= \boldsymbol{P}(s, s, d', d'') - \boldsymbol{p}(s, d') \boldsymbol{p}(s, d'') \\
&= 0 - \frac{1}{D_S} \times \frac{1}{D_S} = -\frac{1}{D_S{}^2}.
\end{aligned} \tag{B-12}$$

That is, every unit within each segment encodes discriminative and complementary features, while the units from different segments encode unrelated and diverse features.

| (a) | (b) | (c) |

Figure B.3: Visualization of MUSIC elements. (a) A partial joint probability matrix, where blue and yellow respectively represent small and large values, (b) two transformations of the same image, and (c) partial embedding vectors corresponding to the images in (b).

APPENDIX C   VISUALIZATION OF MUSIC EMBEDDING

In Fig. B.3, we visualize the MUSIC elements including an empirical joint probability matrix and individual embeddings, where the empirical joint probabilities were computed over the whole ImageNet dataset and only the left-upper partial matrix of 400×400 and the first 800 units of embedding features are selected for visualization. The theoretical analysis in Subsection 2.4 demonstrates that the embedding statistics are enforced to be uniform; *i.e.*, $\forall s, d, \boldsymbol{P}(s, s, d, d) = \frac{1}{D_S}$, meaning that the probabilities of the diagonal elements in all diagonal blocks are equal and those of off-diagonal elements are zeros. Also, the probabilities of all elements of the off-diagonal blocks are equal, *i.e.*, $\forall s', s'', d', d'', s' \neq s'', \boldsymbol{P}(s', s'', d', d'') = \frac{1}{(D_S)^2}$. The empirical joint probability matrix visualized in Fig. B.3-(a) is consistent with theoretical analysis although not a perfect match. Furthermore, Figs. B.3-(b) and (c) show that the embedding features in each segment tend to be one-hot and invariant to the transformations, which are also consistent with the theoretical analysis.

APPENDIX D   COMPUTATIONAL ENVIRONMENT

MUSIC models were distributively trained on four nodes, each of which has the system information:

- $2 \times$ 20 core 2.5 GHz Intel Xeon Gold 6248;
- $8 \times$ NVIDIA Tesla V100 GPU each with 32 GiB HBM;
- 768 GiB RAM per node;
- Dual 100 Gb EDR Infiniband

APPENDIX E   RUNNING TIME

In Table 10, the computational cost of MUSIC was evaluated and compared with other methods. All methods were run on 32 Tesla V100 GPUs. These methods offer different trade-offs among running time, memory and performance. SwAV with multi-crop and BYOL achieve better performance at the additional computational cost and memory usage. Barlow Twins and VICReg have balanced results with less memory than BYOL and SwAV (multi-crop), faster speed than SwAV (multi-crop), but a slightly worse performance. Compared with the most related Barlow Twins and VICReg methods, MUSIC cannot only reduce the running time and memory usage significantly, but also improve the performance. It is due to that MUSIC can use a shallower fully-connected MLP head for a better performance as discussed in Subsection 4.2. The computational cost of MUSIC will be significantly

Table 10: **Running time and peak memory**. Comparison of different methods in terms of the running time over 100 epochs, the peak memory on a single GPU, and the top-1 accuracy (%) on linear classification on top of the frozen representations. All models were distributively trained on 32 Tesla V100 GPUs.

Method	Time / 100epochs	Peak memory / GPU	Top-1 accuracy
SwAV	9h	9.5G	71.8
SwAV (w/multi-crop)	13h	12.9G	75.3
BYOL	10h	14.6G	74.3
Barlow Twins	12h	11.3G	73.2
VICReg	11h	11.3G	73.2
MUSIC	8.5h	10.4G	73.6

reduced further when using a ($\times 2$) lower dimension for embeddings, and the performance would be degraded very slightly, as discussed in Subsection 4.2.

APPENDIX F   IMPLEMENTATION DETAILS

F.1   EVALUATION ON IMAGENET

Linear classification: For all evaluation experiments on ImageNet linear classification, we followed the standard procedure that a linear classifier was trained on top of the frozen backbone of a ResNet-50 pre-trained with MUSIC. The SGD optimizer was used with a learning rate of 0.02, a cosine decay, a weight decay of 10^{-6}, a batch size of 256, and 100 training epochs. In the training stage, the images were augmented by the composition of random cropping and resizing of ratio 0.2 to 1.0 for size 224$\times$224, and random horizontal flips. In the testing stage, the images were simply cropped from the image center and resized to 224×224.

Semi-supervised learning: In the semi-supervised learning setting, a linear classifier was appended to the pre-trained backbone with MUSIC, and the network was fine-tuned using 1% and 10% of the labels. The SGD optimizer was used with no weight decay and a batch size of 256, and the model was trained for 20 epochs. In the 1% of labels case, we used a learning rate of 0.08 for the encoder and 0.1 for the linear head. In the 10% of labels case, we used 0.02 for the encoder and 0.1 for the linear head. Both these learning rates followed a cosine decay schedule. The data augmentation steps for training and testing followed the same settings of the linear evaluation.

F.2   TRANSFER LEARNING

Object detection and instance segmentation: Mask R-CNN He et al. (2017) with the C-4 backbone was trained on the COCO 2017 train split and tested on the validation set. We used a learning rate of 0.1 and kept the other parameters the same as in the 1 schedule in detectron2.

Linear classification: We followed the exact settings from PIRL Misra & Maaten (2020) in evaluating linear classifiers on the Places-205 and VOC07 datasets. For Places-205, a linear classifier was trained using the SGD optimizer for 14 epochs with a learning rate of 0.01 reduced by a factor of 10 at epochs 5 and 10, a weight decay of 5×10^{-4}, and a momentum of 0.9. For VOC2007 dataset, we trained SVM classifiers, where the C values were computed using cross-validation.