When Does Group Invariant Learning Survive Spurious Correlations?

Abstract

By inferring latent groups in the training data, recent works introduce invariant learning to the case where environment annotations are unavailable. Typically, learning group invariance under a majority/minority split is empirically shown to be effective in improving out-of-distribution generalization on many datasets. However, theoretical guarantee for these methods on learning invariant mechanisms is lacking. In this paper, we reveal the insufficiency of existing group invariant learning methods in preventing classifiers from depending on spurious correlations in the training set. Specifically, we propose two criteria on judging such sufficiency. Theoretically and empirically, we show that existing methods can violate both criteria and thus fail in generalizing to spurious correlation shifts. Motivated by this, we design a new group invariant learning method, which constructs groups with statistical independence tests, and reweights samples by group label proportion to meet the criteria. Experiments on both synthetic and real data demonstrate that the new method significantly outperforms existing group invariant learning methods in generalizing to spurious correlation shifts.

1 Introduction

In many real-world applications, machine learning models inevitably encounter data that rarely represented in its training environment, i.e. being *out-of-distribution* (OOD). For example, data collected under new weather [33], locations [6], or light conditions [9] in vision tasks. However, machine learning models often fail in generalizing to OOD data, which blocks their deployment to critical applications [12; 35]. The dependence on spurious correlations that are prone to change across environments has been recognized as a major cause of such failure [4; 12; 34]. For example, it has been shown that models trained on MNLI [36] usually classify sentence pairs with high word overlap as the label 'entailment', regardless of their semantics [23]. On a new dataset where such relation no longer holds, the performance drops over 25% [23; 7].

A notable line of research on improving the robustness of models to distribution shifts is learning features with invariant conditioned label distribution across training environments [25; 4; 15], which has been termed *invariant learning* (IL). These methods are based on the assumption that causal mechanism keeps invariant across environments [25], while the spurious correlation varies. By penalizing the variance of model prediction across environments, models are then encouraged to capture causal mechanism instead of spurious correlations.

Recently, invariant learning has been introduced to the scenario where environment labels are unknown [30; 8], which we term the *group invariant learning* (group-IL). These methods utilize prior knowledge on spurious correlations to split the training data into groups. For example, Teney et al. [30] cluster training samples with their predefined spurious features. A more generic method, EIIL [8], split training data into the majority/minority sets on which the spurious feature conditioned

Submitted to 36th Conference on Neural Information Processing Systems (NeurIPS 2022). Do not distribute.

label distribution varies maximally. Similar to a priori environments, these groups are supposed to encode variations of spurious information, while hold the causal mechanism.

Though some performance improvements have been gained on several datasets, much uncertainty still exists on the effectiveness of group-IL methods. In particular, *when these methods can effectively address spurious correlations* remain a question. Though some theoretical analysis on the success and failure cases of IL with known environments has been proposed [2; 28; 20; 3], they are not sufficient for group-IL. First, inferred groups may not meet the assumptions on environments in existing theoretical analysis, thus their conclusions cannot generalize to group-IL. For example, in each environment, the spurious feature is assumed to have a Gaussian type distribution in [28]. However, the inferred group may not satisfy that condition, for example each group may only contain one unique value of spurious feature. Second, as environments are known and defined with causal structures, exiting analysis on the effect of environment on IL focus mostly on their number [28; 3] but less on their property or validity. However, the later are important for group-IL. Therefore, we need specific theoretical analysis under the setting of group-IL.

In this study, we discuss necessary conditions for group-IL to survive spurious correlations. For this purpose, we first formalize the setting of group-IL and clarify the necessary assumptions required for group-IL, which underlie our theoretical analysis. We then propose two criteria for group-IL, namely *falsity exposure criterion* and *label balance criterion*. They are respectively for judging whether spurious correlations are sufficiently exposed through their variation across groups and whether group invariance can reach spurious-free conditions. Based on that, we discuss the success and failure cases of existing methods. In some synthetic benchmarks (e.g. colored-MNIST in [4; 8]), the majority/minority groups meet the two criteria. However, in a case when the spurious feature is multivariate, the majority/minority split violates both criteria according to our theoretical analysis and observation on real datasets. As a result, existing group-IL methods are insufficient for solving spurious correlations.

To fix these problems, we propose a new group-IL method guided by the two criteria. Specifically, this method contains the following two steps to meet the two criteria. First, groups are defined by stratifying the prediction of a reference predictor which encodes spurious correlations. The strata is constructed with statistical tests, such that the spurious prediction is independent of the label on each group. Second, the label proportion of each inferred group is balanced by attaching weights to each instance within the group. Models are then trained with invariant learning objectives on the defined groups. We term this method Spurious-Correlation-Strata Invariant Learning with Label-balancing, abbreviated as SCILL. We further show that SCILL is provably sufficient in reaching spurious-free with ideal reference models.

To demonstrate the effectiveness of our proposed strategy, we conduct experiments on both synthetic and real data benchmarks on spurious correlations shifts in image Classification and natural language inference (NLI). Specifically, we adopt two different invariant learning objectives, IRM (IRMv1) [4] and REx (V-REx) [15], to show the consistency of SCILL. To show the availability of SCILL, we also experiment with PGI [1] and cMMD [16; 1], which are feature invariance targets used with EIIL [8] in [1]. The experimental results show that SCILL with all the four invariance objectives consistently outperforms the existing state-of-the-art method EIIL in generalizing to spurious correlation shifts. Ablation study further shows the effectiveness of each component in SCILL.

Our main contributions can be summarized as follows.

- We propose two criteria for group-IL, and theoretically show the insufficiency of existing methods.
- Guided by the two criteria, we propose a new practical group-IL method which is provably sufficient in solving spurious correlations.
- Extensive experiments on both synthetic and real-data benchmarks show that SCILL significantly outperforms existing methods on image classification and NLI tasks.

2 Related works

Combating spurious correlations. A typical kind of distribution-shift is caused by the shift of spurious correlations [35], which are correlations between meaningless features (e.g. hospital tokens on a lung scan) and labels (e.g. has pneumonia or not) in the training set. The existence of spurious

(a) [4]   (b) [28]   (c) [2; 21]   (d) [34; 20]

Figure 1: The causal graph depicting different assumptions on the data generating process in existing works (some are simplified). Shading indicates the variable is observed. Dotted arrow indicates possible causal relation. The spurious feature is anti-causal or correlates with Y through E in (a) and (b), confounded with the invariant feature in (c), and both anti-causal and confounded in (d).

correlations in popular benchmarks have been revealed by many works [13; 26; 23; 29]. For example, predictive models with only incomplete semantic inputs or syntactic statistics can achieve high accuracy in NLI benchmarks [13; 26]. Geirhos et al. [11] point out that deep neural networks are prone to take easy-to-fit spurious correlations, i.e. *shortcut* strategies, in solving problems. As a result, resolving model's dependence on spurious correlation is important for their robustness to distribution shifts.

Invariant learning.   Many works on domain generalization focus on capturing invariancies across training environments [12]. Recently a new kind of strategy which has made significant impacts is to learn features that permit an invariant predictor across environments [25; 4; 15; 34], termed as invariant learning in this paper. Such strategy is grounded upon the theory of causality [24], where Structural Equation Models [25] or causal graphs [34] are used to describe assumptions on the data generation process. The feature-conditioned label distribution invariance is then induced by the invariance of causal mechanisms in different environments.

Group invariant learning.   In recent works, invariant learning is extended to the scenario without a priori environment labels, but with knowledge on spurious correlations in the training data [30; 8]. Such knowledge is proven to be necessary in this setting [17]. They are utilized to split the training data into groups, which are supposed to encode variations of spurious information so that they can be avoided by learning the invariance. For example, Teney et al. [30] cluster samples according to their question types. Liu et al. [18] construct groups with varying spurious correlations, based on the spurious features uncovered with feature selection. A more generic method proposed in EIIL [8] assume the access to a reference predictor which encodes spurious correlations, and exploit the outputs of the reference predictor to split training data into two groups, namely the majority and the minority. This strategy is shown effective, sometimes even outperform an oracle method using true environment labels in proving the OOD generalization [8] and also systematic generalization [1].

3   Formalization of group invariant learning

In this section, we introduce the problem setting and formalization of the scheme of group-IL.

Notations.   Consider the problem of learning a classifier $f : \mathcal{X} \to \mathcal{Y}$, which maps a value $x \in \mathcal{X}$ of the input variable X to a value $y \in \mathcal{Y}$ of the target variable Y. For example, map an image of horse on grass to the label 'horse'. We denote x_{inv} as the essential features of input x which define its class label (e.g. the shape of the horse), while x_{sp} as features of x should not inform the label of x (e.g. the grass background). X_{inv}, X_{sp} denote the corresponding random variables. Now suppose a dataset $\mathcal{D}$ of the task is sampled from a probability distribution $\mathbb{P}(\mathcal{X} \times \mathcal{Y})$. The target is then to learn a *spurious-free* predictor modeling $\mathbb{P}(Y|X_{inv})$, which is supposed to have invariant performance on any different domain D'.

We begin with the introduction of invariant learning. Invariant learning methods suppose D consists of several environments, i.e. $\mathcal{D} = \mathcal{E} = \{e_1, e_2, \ldots, e_m\}$. $\mathbb{P}(Y|X_{inv})$ is invariant conditioned on each e_i, while $\mathbb{P}(Y|X_{sp})$ varies. Such idea is grounded on the invariance of causal mechanisms across environments [25; 4], with assumptions on the causal structure of the data. Figure 1 demonstrates

four kinds of different assumptions in existing works on invariant learning. In all the four kinds of causal graphs, $\mathbb{P}(Y|X_{inv})$ keeps invariant under different E, while $\mathbb{P}(Y|X_{sp})$, $\mathbb{P}(X_{sp})$, $\mathbb{P}(X_{inv})$, and $\mathbb{P}(X_{inv}|Y)$ can vary across different value of E.

Suppose the predictor f can be decomposed into $f = h \circ \Phi$, where Φ denotes a feature encoder, h is a classifier. The target of invariant learning is then to search for a Φ satisfies the following constraint:

$$\mathbb{P}(Y|\Phi(X), e) = \mathbb{P}(Y|\Phi(X), e'), \forall e, e' \in \mathcal{E}. \tag{PIC}$$

It is termed as *Environment Invariance Constraint* (EIC). Note that the EIC stated in [8] is a weaker form of this EIC. The constraint is incorporated into the training target via a penalty term. In a generic form, the learning target of invariant learning methods can be written as follows:

$$\min_f \sum_{e \in \mathcal{E}} \lambda_e \mathcal{R}^e(f) + \lambda \cdot penalty(\{S_e(f)\}_{e \in \mathcal{E}}) \tag{1}$$

where $\mathcal{R}^e(f)$ stands for the loss of f on e, weighted by a scalar λ_e. $S_e(f)$ stands for some statistics of f on e, and the *penalty* is on the variation of $S_e(f)$ to measure the deviation degree of EIC. In IRM [4], the penalty is the summation of $S_e(f) = \|\nabla_w R^e(w \circ f)\|$, where w is a constant scalar multiplier of 1.0 for each output dimension. In V-REx [15], $S_e(f) = R^e(f)$, and the penalty is the variance of $S_e(f)$ on different environments. In CLOvE [34], the penalty is defined as the summation of calibration errors of the model on each environment.

Group invariant learning methods release the dependency of invariant learning on predefined environments by splitting the training data into groups, such that $\mathcal{D} = \mathcal{G} = \{g_1, g_2, \ldots, g_m\}$. Intuitively, such groups are expected to hold the invariant mechanism $\mathbb{P}_{\mathcal{D}}(Y|X_{inv})$, while inform the variation of X_{sp}. Denote G as the function which maps a sample to its group identity. G is then (X_{sp}, Y)-measurable, i.e. it differs according to X_{sp}, as in [30; 18], or both X_{sp} and Y [8].

In the following section, we ground our analysis on group-IL with the causal structures in Figure 1 (a) and (b). This choice is due to the following two observations. First, for the causal structure in (d), $\mathbb{P}(Y|X_{inv})$ changes when it is conditioned on X_{sp}. As a result, group-IL can not be applied to (d). To keep $\mathbb{P}_{\mathcal{D}}(Y|X_{inv}, g)$ invariant on any g, G can be a function of both X_{sp} and Y when we assume the causal structures in Figure 1(a) and (b). For (c), G should only rely on X_{sp}. Second, as shown by Ahuja et al. [2], invariance itself can not deal with spurious feature for causal structure (c). Additional knowledge or penalty, e.g. information bottleneck, is needed together with group-IL. As a result, group-IL is only suitable for (a) and (b).

4   Two group criteria

With the above formulation, we are ready to theoretically analyze the ability of existing group-IL methods in learning spurious-free predictors. For this purpose, in this section we derive two necessary conditions for group-IL in surviving spurious correlations, i.e. falsity exposure, and label balance. Both conditions can be used as criteria to judge the sufficiency of group-IL methods. We then show that existing methods can violate the two criteria, thus become insufficient for learning a spurious-free predictor.

4.1   Falsity exposure criterion

As groups are supposed to expose variance of spurious features so that they can be avoided by invariant learning, a natural idea is to take into account the sufficiency of such exposure on inferred groups. Ideally, if groups are split according to X_{sp}, any variance of $\mathbb{P}(Y|X_{sp})$ is then fully exposed. However, such split is only practical when the value of X_{sp} is accessible and sparse. On the contrary, we consider the condition when groups provide insufficient exposure. Intuitively, if some spurious correlation keeps invariant across groups, its variation is then not exposed, thus group invariant predictor may still depend on such correlation. Formally, this can be written as the following criterion.

Criterion 4.1 (Falsity Exposure). For any function h that satisfies $\forall g, g' \in \mathcal{G}$, $\mathbb{P}(Y|h(X_{sp}), g) = \mathbb{P}(Y|h(X_{sp}), g')$, it must satisfies $\mathbb{P}(Y|h(X_{sp})) = \mathbb{P}(Y)$.

Intuitively, if the falsity exposure criterion is not satisfied, $h(X_{sp})$ will be an invariant feature across environments, with predictive ability on Y. The predictor depending on both X_{inv} and $h(X_{sp})$

can satisfy EIC, but fails to be free of spurious features. The following theorem formalizes the significance of the falsity exposure criterion.

Theorem 4.2. *Suppose the falsity exposure criterion is violated, i.e. $\exists h$ satisfies $\mathbb{P}(Y|h(X_{sp}), g) = \mathbb{P}(Y|h(X_{sp}), g') \neq \mathbb{P}(Y), \forall g, g' \in \mathcal{G}$. Then the optimal solution of group-IL is $f(X) = \mathbb{P}[Y|X_{inv}, h(X_{sp})]$, which fails to generalize when $\mathbb{P}(Y|X_{sp})$ shifts.*

4.2 Label balance criterion

Even if we have sufficient falsity exposure, would the constraint in group-IL, i.e. EIC, guarantee the model to be free of spurious correlations? We study this problem by analyzing the relation between EIC and the constraint for a predictor to be spurious-free. In our assumed causal structures, $X_{inv} \perp\!\!\!\perp X_{sp}|Y$. Thus, a spurious-free predictor, which only depends on X_{inv}, satisfies $f(X) \perp\!\!\!\perp X_{sp}|Y$. In fact, it can be proved that this is a sufficient condition for $f(X)$ to be invariant to the intervention [24] on X_{sp}. As a result, we term $f(X) \perp\!\!\!\perp X_{sp}|Y$ as the *spurious-free constraint*, i.e.

$$\mathbb{P}(f(X)|X_{sp} = b, Y) = \mathbb{P}(f(X)|X_{sp} = b', Y), \forall b, b' \in \mathcal{B}, \tag{SFC}$$

The following is a necessary condition for EIC to induce the above constraint, which we term as the *label balance* criterion. It states that the label proportion in different environments should be the same.

Criterion 4.3 (Label Balance). *For any $g, g' \in \mathcal{G}$ and $y, y' \in \mathcal{Y}$ with non-zero $\mathbb{P}(Y = y|g), \mathbb{P}(Y = y'|g), \mathbb{P}(Y = y|g')$ and $\mathbb{P}(Y = y'|g')$, the following equation holds,*

$$\frac{\mathbb{P}(Y = y|g)}{\mathbb{P}(Y = y'|g)} = \frac{\mathbb{P}(Y = y|g')}{\mathbb{P}(Y = y'|g')}. \tag{2}$$

Mathematically, the following theorem shows the significance of this criterion on the effectiveness group-IL.

Theorem 4.4. *With a set of groups $\mathcal{G}$ inferred by (X_{sp}, Y), if the label balance criterion is violated, functions satisfying EIC can not satisfy SFC.*

4.3 Analysis on existing group invariant learning methods

Now we analyze whether the groups in existing group-IL methods meet the two criteria. Directly, randomly grouped clusters of X_{sp} as in [30] do not guarantee to meet either criteria, and clusters of $\mathbb{P}(Y|X_{sp})$ [18] do not meet the label balance criterion. In the following discussions, we focus on the majority/minority groups inferred by the EI algorithm in EIIL [8]. We find that in some synthetic datasets where the spurious feature only has two distinct values, the majority/minority groups satisfy the two criteria. However, observation on real datasets and theoretical results on the case when the spurious feature is multivariate show that they can violate both criteria.

On some synthetic datasets constructed in existing works [1; 8], the majority/minority groups satisfy these two criteria. For example, on both colored-MNIST [4] and coloured-MNIST [1], Y has a uniform distribution, and the spurious correlation has the same ratio for any spurious features, e.g. $\mathbb{P}(Y = 0|\text{color} = green) = \mathbb{P}(Y = 1|\text{color} = red))$ on colored-MNIST. It can be proved that in this case the majority/minority groups satisfy both criteria (see the appendix).

However, it no longer holds in general cases. Empirically, we observe that on MNLI, the label distributions of the two groups inferred by EI are significantly different. Specifically, the ratio of the counts of label 0 and label 1 on the two groups are 2.87 and 0.17 respectively. The following proposition theoretically provides a case where the majority/minority split satisfies the label balance but breaks the falsity exposure, and invariant learning objectives fail to find the spurious-free classifier.

Proposition 4.5. *Suppose we have $(X, Y) \sim \mathbb{P}(X, Y)$. Y takes value in $\{0, 1\}$. X is formed with spurious feature variables $X_{sp} = (B_0, B_1)$, and invariant feature variable S, i.e. $X = r(B_0, B_1, S)$. B_0 and B_1 are both binary variables. B_0, B_1 and S are conditionally independent given Y. Denote $\mathbb{P}(Y = j|B_i = b_i^j) = p_i, \forall j = 0, 1$. Suppose $p_0 > p_1$. Then we have 1) the majority/minority split e_{mar}, e_{min} violates falsity exposure criterion. 2) the optimal classifier under invariant learning objectives depends on B_1.*

In this case, we suppose the spurious feature can be decomposed into two variables that are conditionally independent with each other given the label. Such case can realize when the dataset contains multiple kinds of spurious features. For example, in the image classification task, the background pattern and the color of an object can be independent but both correlate with the label spuriously.

5 SCILL: a new method

According to the above discussion in Section 4, existing group-IL methods may fail to meet the two criteria, leading to insufficient training loss for solving spurious correlations. Faced with this challenge, we propose a new group-IL method, to satisfy the two criteria. For the generality, we only assume the access to a reference model, as in EIIL, instead of spurious features. Our new method includes two steps. In the group inference step, we define groups as spurious correlation strata constructed with the reference model, for the falsity exposure criterion. While in the training objective step, we reweight each sample with group label proportion to meet the label balance criterion. To highlight the two parts, our method is named as Spurious-Correlation-strata Invariant Learning with Label-balance, abbreviated as SCILL. Theoretically, we prove that this method is provably sufficient with ideal reference models, i.e. its optimal solution is spurious-free.

5.1 Group inference with statistical split

We first introduce the group inference step in SCILL. As in EIIL, we assume a reference model f_r is available, which encodes spurious correlations in the training data. f_r can be a model trained with empirical risk minimization (ERM) [8] or a model designed to capture spurious correlations [19].

We propose to construct groups by stratify the outputs of f_r, with the target that $Y \perp\!\!\!\perp f_r | g$. The motivation of introducing spurious correlation strata comes from the deduction of falsity exposure criterion, i.e. when groups meet the requirements that $X_{sp} \perp\!\!\!\perp Y | g$, the falsity exposure criterion is satisfied. That is because with the above two conditions, we have for any function h, $h(X_{sp}) \perp\!\!\!\perp Y | g$, as a result $\mathbb{P}(Y|h(X_{sp}), g) = \mathbb{P}(Y|g)$. If $\mathbb{P}(Y|h(X_{sp}), g) = \mathbb{P}(Y|h(X_{sp}), g')$, $\forall g, g' \in \mathcal{G}$, we have $\mathbb{P}(Y|g) = \mathbb{P}(Y|g') = \mathbb{P}(Y)$. Thus $\mathbb{P}(Y|h(X_{sp}), g) = \mathbb{P}(Y)$. As a result the falsity exposure criterion is satisfied. As different output values of the reference model f_r inform the difference in $\mathbb{P}(Y|X_{sp})$, $Y \perp\!\!\!\perp f_r | g$ approximates $\mathbb{P}(Y|X_{sp}) \perp\!\!\!\perp Y | g$, which is equivalent to $X_{sp} \perp\!\!\!\perp Y | g$.

We propose to construct such environments through the *statistical-split* algorithm, inspired by the algorithm proposed in [14] for propensity score estimation. Specifically, we step-wise split current groups into subgroups according to hypothesis-test statistics. For example for the binary class case, a set B of samples is first divided into two subsets L_0, L_1 according to the labels of samples. Then the two-sample t-statistics t_B of $\log[f_r(x)_0 / f_r(x)_1]$ are computed on the two sets. If t_B exceeds a fixed threshold thr, the B is then split into two subsets according to the median of $f_r(x)_0$ on B. In this way, we enhance $f_r(X) \perp\!\!\!\perp Y$ in each group. Note that thr is a hyper-parameter of this algorithm. Empirical robustness analysis on thr is conducted in our experiments. More details about the algorithm are provided in the Appendix.

5.2 Training with reweighted loss

Now we introduce the second step. To guarantee the label balance criterion, we reweight each sample with group label proportion in the training loss. Correspondingly, the objective of invariant learning becomes the following form:

$$\mathcal{L}(f) := \sum_{g \in \mathcal{G}} \tilde{R}^g(f) + \lambda \cdot penalty(\{S_g(f)\}_{g \in \mathcal{G}}) \tag{3}$$

where $\tilde{R}^g(f) = \mathbb{G}[w^g(Y)\mathcal{L}^g(f(X), Y)]$, $\omega^g(y) := \mathbb{P}(Y = y)/\mathbb{P}(Y = y|g)$ for nonzero $\mathbb{P}(Y = y|g)$. The weight function is defined to balance the label distribution between groups, i.e. $\mathbb{P}(Y|g) = \mathbb{P}(Y|g')$, $\forall g, g'$, so as to achieve the label balance criterion.

With the above two parts, we can theoretically prove that our method is able to find the spurious-free predictor, as illustrated in the following theorem.

Theorem 5.1. *If $\mathcal{G}$ satisfies $f_r^*(X) \perp\!\!\!\perp Y$ on $\forall g \in \mathcal{G}$, where $f_r^*(x)$ minimizes the spurious-only prediction loss $\mathcal{L}_{ce}^r = \mathbb{E}_{x,y} p(x, y) \log f(X_{sp}(x))$, the optimal model minimizing the objective (4) satisfies SFC.*

Table 1: Classification accuracy on PC-MNIST under three model selection strategies ID, Oracle, TEV. Val columns contain the accuracy values computed on the in-distribution validation set, and Test columns contain those on the test set. As the label noise rate is set to 0.25 on PC-MNIST, the optimum predictor depending on invariant features achieves an accuracy around 75% on both sets.

Method	Penalty	ID		Oracle		TEV	
		Val	**Test**	**Val**	**Test**	**Val**	**Test**
ERM	-	90.22 ± 0.56	50.64 ± 0.56	89.95 ± 0.45	54.53 ± 0.60	-	-
EIIL	IRM	90.21 ± 0.48	50.63 ± 0.45	78.01 ± 0.45	63.63 ± 0.71	69.81 ± 0.27	50.99 ± 0.58
	REx	90.24 ± 0.45	51.21 ± 0.64	79.10 ± 0.43	64.04 ± 0.80	70.05 ± 0.23	51.01 ± 0.68
	cMMD	90.24 ± 0.43	51.36 ± 0.61	77.27 ± 0.28	65.09 ± 0.63	70.15 ± 0.25	52.70 ± 1.40
	PGI	90.19 ± 0.46	51.07 ± 0.54	80.03 ± 1.41	64.27 ± 0.26	70.37 ± 0.14	50.64 ± 0.38
SCILL	IRM	79.65 ± 0.76	62.49 ± 0.55	71.54 ± 0.35	67.46 ± 0.19	71.54 ± 0.35	67.46 ± 0.19
	REx	80.23 ± 0.83	62.13 ± 0.99	72.59 ± 1.44	$\mathbf{67.60} \pm 0.24$	70.77 ± 0.50	67.33 ± 0.30
	cMMD	83.13 ± 0.93	59.76 ± 0.92	73.12 ± 0.47	67.49 ± 0.52	72.38 ± 0.51	$\mathbf{67.81} \pm 0.34$
	PGI	80.67 ± 1.75	$\mathbf{62.52} \pm 0.32$	71.73 ± 1.43	67.26 ± 0.14	71.35 ± 0.24	67.36 ± 0.33
SCILL$_{uw}$	IRM	90.27 ± 0.39	50.95 ± 0.47	90.07 ± 0.34	53.51 ± 1.38	90.28 ± 0.39	50.85 ± 0.47
	REx	90.25 ± 0.30	51.50 ± 1.08	81.27 ± 0.13	61.63 ± 0.64	90.25 ± 0.30	51.50 ± 1.08
	cMMD	90.31 ± 0.38	51.70 ± 1.02	89.89 ± 0.28	54.50 ± 1.41	90.23 ± 0.32	52.96 ± 0.86
	PGI	90.22 ± 0.47	51.00 ± 0.52	70.05 ± 1.01	66.82 ± 1.01	90.18 ± 0.52	51.44 ± 0.58
opt	-	75	75	75	75	75	75

6 Experiments

In this section, we first conduct experiments to show that SCILL outperforms existing group-IL methods in generalizing to spurious correlation shifts. Then we empirically analyze whether the experimental improvements are consistent with the theoretical findings.

6.1 Experimental settings

Now we describe our experimental settings, including datasets, models and some training details. More details are provided in the Appendix.

Datasets We conduct experiments on both synthetic and real-world datasets. The synthetic dataset, Patched-Colored MNIST (PC-MNIST), is constructed as a realization of the conditions in the Proposition 4.5 to verify the proposed criteria. It is derived from MNIST, by assigning two conditionally independent spurious features given label, namely the color and patch bias to each image. The design of the patch bias is inspired by [5]. MNLI-HANS is a benchmark widely used in many previous works on combating spurious correlations, such as [7; 31]. In our experiments, we follow the practice to utilize MNLI [36] as the training data and HANS (Heuristic Analysis for NLI Systems) [23] as the test data.

Baselines and configurations In our experiments, we compare SCILL with two baselines, i.e. ERM and EIIL [8]. ERM represents the method with traditional empirical risk minimization (ERM) approach. EIIL is a state-of-the-art group-IL method, where environments are inferred by searching an assignment to make the reference model maximally violates the invariant learning principle. We experiment with three different invariance penalties: IRM [4], REx (V-REx) [15], cMMD [16; 1] and PGI [1]. Note that cMMD and PGI target to learn group invariant predictions conditioning on the label, different from EIC. See Appendix for more details of the four penalties.

The training configurations are presented as follows. For PC-MNIST, we adopt the classifier proposed in [4] for Colored MNIST, which is an MLP with two hidden layers of 390 neurons. The reference model is the model trained with ERM on the training set, following the setting in EIIL on Colored MNIST. While for MNLI, we use a BERT-based classifier with the standard setup for sentence pair classification [10]. The reference model is the same as the biased classifier propose in [31], which is

Table 2: Classification accuracy on HANS.

Method	Penalty	ID		Oracle		TEV	
		Val	**Test**	**Val**	**Test**	**Val**	**Test**
ERM	-	84.12 ± 0.15	64.88 ± 3.00	84.12 ± 0.15	64.88 ± 3.00	-	-
EIIL	IRM	84.01 ± 0.08	65.35 ± 0.93	83.82 ± 0.17	66.42 ± 0.98	84.01 ± 0.08	65.35 ± 0.93
	REx	84.10 ± 0.13	65.16 ± 0.19	83.91 ± 0.20	66.87 ± 2.92	84.00 ± 0.48	66.43 ± 1.00
	cMMD	83.56 ± 0.03	63.22 ± 1.76	83.22 ± 0.13	64.25 ± 1.63	83.38 ± 0.20	62.72 ± 2.03
	PGI	84.17 ± 0.08	65.57 ± 2.25	83.78 ± 0.03	66.02 ± 0.93	83.94 ± 0.64	65.57 ± 2.25
SCILL	IRM	82.75 ± 0.17	69.11 ± 1.76	82.56 ± 0.33	68.72 ± 1.24	82.67 ± 0.14	69.82 ± 1.29
	REx	82.68 ± 0.28	$\mathbf{69.73} \pm 1.63$	82.59 ± 0.22	$\mathbf{71.20} \pm 1.81$	82.56 ± 0.33	69.75 ± 1.53
	cMMD	82.74 ± 0.26	69.15 ± 1.39	82.39 ± 0.45	70.77 ± 1.40	82.61 ± 0.04	$\mathbf{70.92} \pm 0.79$
	PGI	82.79 ± 0.30	68.57 ± 0.54	81.69 ± 0.28	70.99 ± 0.48	82.79 ± 0.30	68.57 ± 0.54
EIIL$_{lb}$	IRM	83.39 ± 0.06	63.90 ± 1.16	83.39 ± 0.06	63.90 ± 1.16	83.16 ± 0.22	61.33 ± 0.33
SCILL$_{uw}$	IRM	84.15 ± 0.11	64.30 ± 0.67	83.77 ± 0.15	65.93 ± 0.12	83.84 ± 0.02	65.63 ± 1.46

Table 3: Robustness study on PC-MNIST. It shows the performance of SCILL-IRM with threshold $5, 10, 20$ on t-statistics in the statistical-split algorithm. Top values are in bold.

Method	ID		Oracle		TEV	
	Val	**Test**	**Val**	**Test**	**Val**	**Test**
ERM	90.22 ± 0.56	50.64 ± 0.56	89.95 ± 0.45	54.53 ± 0.60	-	-
SCILL-thr-20	83.15 ± 0.47	60.14 ± 1.12	73.37 ± 0.65	67.95 ± 0.66	72.59 ± 0.33	67.79 ± 0.57
SCILL-thr-15	82.84 ± 0.61	59.79 ± 1.00	73.07 ± 0.69	$\mathbf{68.17} \pm 0.56$	72.31 ± 0.32	$\mathbf{67.87} \pm 0.37$
SCILL-thr-10	79.65 ± 0.76	$\mathbf{62.49} \pm 0.55$	71.54 ± 0.35	67.46 ± 0.19	71.54 ± 0.35	67.46 ± 0.19
SCILL-thr-5	76.91 ± 0.60	55.50 ± 1.78	66.29 ± 13.1	58.81 ± 2.35	60.29 ± 9.97	61.89 ± 3.96

trained on top of some hand-crafted syntactic features. For each task, all implementations of SCILL and EIIL adopt the same model configurations and pretrained reference models.

Since models are tested with OOD data, it is important to specify the model selection strategy, as has been revealed by Gulrajani and Lopez-Paz [12] for the case of domain generalization. In our experiments, we report results with 3 different model selection strategies, including ID, Oracle, and TEV. ID refers to the strategy based on model performance on in-distribution validation set as used in [31]. Oracle refers to the selection based on data from the test data distribution, as used in [8; 12]. While TEV is a new strategy adapted from the training-domain validation method in [12] to the inferred environments, which alleviates the dependence with the test data as ID. The detailed algorithm can be found in the Appendix.

6.2 Experimental results

Now we demonstrate our experimental results, including performance comparison and detailed analysis.

6.2.1 Performance comparison

Table 1 and 2 shows the experimental results on PC-MNIST and MNLI-HANS, respectively. The main observation is that all implementations of SCILL consistently outperform the counterpart of EIIL across all model selection strategies, in terms of the performance on OOD data. Comparing different model selection strategies, Oracle performs the best for both EIIL and SCILL. However, SCILL with the TEV strategy has the ability to outperform EIIL with Oracle, demonstrating the superiority of our new objective. Additionally, SCILL also gains improvements against some debiasing methods utilizing the same reference model (see the appendix).

6.2.2 Empirical verification of two criteria

Our main theoretical results in Section 4 reveal two environment criteria as the necessary conditions for group-IL, i.e. falsity exposure criterion and label balance criterion. Now we empirically discuss the verification of these theoretical results.

First, we consider the falsity exposure criterion, which could be empirically verified from two perspectives. Considering the fact that the label proportion of each environment is quite balanced on PC-MNIST[1], the improvement of SCILL over EIIL on Table 1 and 2 directly verifies the necessity of falsity exposure criterion, as stated in Proposition 4.5. While for MNLI, the label is not balanced (see the appendix). So we add the similar instance reweight to EIIL, and obtain a label balanced version, denoted as EIIL-LB. However, EIIL-LB still can not achieve improved performance across different model selection strategies, as shown in Table 1 and 2. The necessity of the falsity exposure criterion is then verified.

To verify the necessity of label balance criterion, we directly remove the instance reweighting on SCILL, and obtain SCILL-UW. The experimental results in Table 1 and 2 show that SCILL-UW performs worse than SCILL, demonstrating the necessity of label balance criterion.

6.2.3 Robustness analysis

As shown in Section 5.1, the statistical-split algorithm contains a hyper-parameter thr. So We study the robustness of SCILL w.r.t. thr by experiments on PC-MNIST with thr set as $5, 10, 15, 20$ in SCILL-IRM. From the results shown in Table 3, the models are robust with different $thr = 10, 15, 20$, though the model with $thr = 5$ is worse than others. More results can be found in the Appendix.

7 Discussions

The main limitation of the paper is our assumptions on the causal structure. In fact, our conclusions can be generalized to more complex structures, e.g. those in [32] (see the appendix). The most central assumption is the conditional independence between X_{inv} and X_{sp} given Y, which is adopted in many existing works on solving spurious correlations [7; 32; 37]. It would be an important direction to find causal structures on which the assumption is not satisfied while group invariant learning can still be effective.

As this paper focuses on analyzing group invariant learning, comparing SCILL with other algorithms besides group-IL is beyond the scope of this paper. Notably, the form of the objective of SCILL appears to be similar to two recent methods in solving spurious correlations [22; 27], though the penalties are different. However, they are only applied for the case when spurious features can be explicitly defined [27], and are also discrete as assumed in [22].

Besides the setting of group invariant learning, the two criteria may also bring benefits to the study of domain generalization. Furthermore, our empirical results show SCILL can achieve good performance with other kinds of invariances besides that in invariant learning, e.g. the invariance of the distribution of model outputs conditioned on the label. Discussing the effect of the two group criteria on other kinds of group invariance is a potential research direction.

8 Conclusion

This paper is concerned with when group invariant learning (group-IL) can survive spurious correlations. We first formulate the setting of group-IL and necessary assumptions. Then we theoretically analyze the necessary conditions for group-IL in learning spurious-free predictors, and obtain two group criteria, i.e. falsity exposure and label balance. Considering the limitations of previous group-IL methods, we propose a new method SCILL to satisfy the two criteria. Furthermore, we theoretically prove that SCILL has the ability to learn an spurious-free predictor. Finally, we conduct extensive experiments on both synthetic and real data to evaluate the proposed new method. The experimental results show that SCILL significantly outperforms existing SOTA group-IL methods, owing to its ability to satisfy the two criteria. The empirical studies also verify the effectiveness of our theoretical findings.

---

[1] The ratio of label 0 and label 1 on environment 0 and environment 1 is 1:1.03 and 1:1.04, respectively.

References

[1] Faruk Ahmed, Yoshua Bengio, Harm van Seijen, and Aaron Courville. Systematic generalisation with group invariant predictions. In *International Conference on Learning Representations*, 2021.

[2] Kartik Ahuja, Ethan Caballero, Dinghuai Zhang, Yoshua Bengio, Ioannis Mitliagkas, and Irina Rish. Invariance principle meets information bottleneck for out-of-distribution generalization, 2021.

[3] Kartik Ahuja, Jun Wang, Amit Dhurandhar, Karthikeyan Shanmugam, and Kush R Varshney. Empirical or invariant risk minimization? a sample complexity perspective. In *International Conference on Learning Representations*, 2021.

[4] Martin Arjovsky, Léon Bottou, Ishaan Gulrajani, and David Lopez-Paz. Invariant risk minimization. *arXiv preprint arXiv:1907.02893*, 2019.

[5] N. N. Author. Blood: Bi-level learning framework for out-of-distribution generalization, 2021. URL https://openreview.net/forum?id=Cm08egNmrl3.

[6] Sara Beery, Grant Van Horn, and Pietro Perona. Recognition in terra incognita. In *Proceedings of the European conference on computer vision (ECCV)*, pages 456–473, 2018.

[7] Christopher Clark, Mark Yatskar, and Luke Zettlemoyer. Don't take the easy way out: Ensemble based methods for avoiding known dataset biases. In *Proceedings of the 2019 Conference on Empirical Methods in Natural Language Processing and the 9th International Joint Conference on Natural Language Processing (EMNLP-IJCNLP)*, pages 4060–4073, 2019.

[8] Elliot Creager, Jörn-Henrik Jacobsen, and Richard Zemel. Environment inference for invariant learning. In *International Conference on Machine Learning*, 2021.

[9] Dengxin Dai and Luc Van Gool. Dark model adaptation: Semantic image segmentation from daytime to nighttime. In *2018 21st International Conference on Intelligent Transportation Systems (ITSC)*, pages 3819–3824. IEEE, 2018.

[10] Jacob Devlin, Ming-Wei Chang, Kenton Lee, and Kristina Toutanova. Bert: Pre-training of deep bidirectional transformers for language understanding. In *Proceedings of the 2019 Conference of the North American Chapter of the Association for Computational Linguistics: Human Language Technologies, Volume 1 (Long and Short Papers)*, pages 4171–4186, 2019.

[11] Robert Geirhos, Jörn-Henrik Jacobsen, Claudio Michaelis, Richard Zemel, Wieland Brendel, Matthias Bethge, and Felix A Wichmann. Shortcut learning in deep neural networks. *Nature Machine Intelligence*, 2(11):665–673, 2020.

[12] Ishaan Gulrajani and David Lopez-Paz. In search of lost domain generalization. In *International Conference on Learning Representations*, 2021.

[13] Suchin Gururangan, Swabha Swayamdipta, Omer Levy, Roy Schwartz, Samuel Bowman, and Noah A Smith. Annotation artifacts in natural language inference data. In *Proceedings of the 2018 Conference of the North American Chapter of the Association for Computational Linguistics: Human Language Technologies, Volume 2 (Short Papers)*, pages 107–112, 2018.

[14] Guido W Imbens and Donald B Rubin. *Causal inference in statistics, social, and biomedical sciences*. Cambridge University Press, 2015.

[15] David Krueger, Ethan Caballero, Joern-Henrik Jacobsen, Amy Zhang, Jonathan Binas, Dinghuai Zhang, Remi Le Priol, and Aaron Courville. Out-of-distribution generalization via risk extrapolation (rex). In *International Conference on Machine Learning*, pages 5815–5826. PMLR, 2021.

[16] Ya Li, Xinmei Tian, Mingming Gong, Yajing Liu, Tongliang Liu, Kun Zhang, and Dacheng Tao. Deep domain generalization via conditional invariant adversarial networks. In *Proceedings of the European Conference on Computer Vision (ECCV)*, pages 624–639, 2018.

[17] Yong Lin, Shengyu Zhu, and Peng Cui. Zin: When and how to learn invariance by environment inference? *arXiv preprint arXiv:2203.05818*, 2022.

[18] Jiashuo Liu, Zheyuan Hu, Peng Cui, Bo Li, and Zheyan Shen. Heterogeneous risk minimization. In Marina Meila and Tong Zhang, editors, *Proceedings of the 38th International Conference on Machine Learning*, volume 139 of *Proceedings of Machine Learning Research*, pages 6804–6814. PMLR, 18–24 Jul 2021.

[19] Tianyu Liu, Zheng Xin, Baobao Chang, and Zhifang Sui. Hyponli: Exploring the artificial patterns of hypothesis-only bias in natural language inference. In *Proceedings of The 12th Language Resources and Evaluation Conference*, pages 6852–6860, 2020.

[20] Chaochao Lu, Yuhuai Wu, José Miguel Hernández-Lobato, and Bernhard Schölkopf. Invariant causal representation learning for out-of-distribution generalization. In *International Conference on Learning Representations*, 2022.

[21] Divyat Mahajan, Shruti Tople, and Amit Sharma. Domain generalization using causal matching. In *International Conference on Machine Learning*, pages 7313–7324. PMLR, 2021.

[22] Maggie Makar, Ben Packer, Dan Moldovan, Davis Blalock, Yoni Halpern, and Alexander D'Amour. Causally motivated shortcut removal using auxiliary labels. In *International Conference on Artificial Intelligence and Statistics*, pages 739–766. PMLR, 2022.

[23] Tom McCoy, Ellie Pavlick, and Tal Linzen. Right for the wrong reasons: Diagnosing syntactic heuristics in natural language inference. In *Proceedings of the 57th Annual Meeting of the Association for Computational Linguistics*, pages 3428–3448, 2019.

[24] Judea Pearl. *Causality*. Cambridge university press, 2009.

[25] Jonas Peters, Peter Bühlmann, and Nicolai Meinshausen. Causal inference by using invariant prediction: identification and confidence intervals. *Journal of the Royal Statistical Society: Series B (Statistical Methodology)*, 78(5):947–1012, 2016.

[26] Adam Poliak, Jason Naradowsky, Aparajita Haldar, Rachel Rudinger, and Benjamin Van Durme. Hypothesis only baselines in natural language inference. In *Proceedings of the Seventh Joint Conference on Lexical and Computational Semantics*, pages 180–191, 2018.

[27] Aahlad Puli, Lily H Zhang, Eric K Oermann, and Rajesh Ranganath. Predictive modeling in the presence of nuisance-induced spurious correlations. *arXiv preprint arXiv:2107.00520*, 2021.

[28] Elan Rosenfeld, Pradeep Kumar Ravikumar, and Andrej Risteski. The risks of invariant risk minimization. In *International Conference on Learning Representations*, 2020.

[29] Sahil Singla and Soheil Feizi. Salient imagenet: How to discover spurious features in deep learning? In *International Conference on Learning Representations*, 2022.

[30] Damien Teney, Ehsan Abbasnejad, and Anton van den Hengel. Unshuffling data for improved generalization in visual question answering. In *Proceedings of the IEEE/CVF International Conference on Computer Vision*, pages 1417–1427, 2021.

[31] Prasetya Ajie Utama, Nafise Sadat Moosavi, and Iryna Gurevych. Mind the trade-off: Debiasing nlu models without degrading the in-distribution performance. *arXiv preprint arXiv:2005.00315*, 2020.

[32] Victor Veitch, Alexander D'Amour, Steve Yadlowsky, and Jacob Eisenstein. Counterfactual invariance to spurious correlations in text classification. *Advances in Neural Information Processing Systems*, 34, 2021.

[33] Georg Volk, Stefan Müller, Alexander Von Bernuth, Dennis Hospach, and Oliver Bringmann. Towards robust cnn-based object detection through augmentation with synthetic rain variations. In *2019 IEEE Intelligent Transportation Systems Conference (ITSC)*, pages 285–292. IEEE, 2019.

[34] Yoav Wald, Amir Feder, Daniel Greenfeld, and Uri Shalit. On calibration and out-of-domain generalization. *Advances in Neural Information Processing Systems*, 34, 2021.

[35] Olivia Wiles, Sven Gowal, Florian Stimberg, Sylvestre Alvise-Rebuffi, Ira Ktena, Taylan Cemgil, et al. A fine-grained analysis on distribution shift. *arXiv preprint arXiv:2110.11328*, 2021.

[36] Adina Williams, Nikita Nangia, and Samuel Bowman. A broad-coverage challenge corpus for sentence understanding through inference. In *Proceedings of the 2018 Conference of the North American Chapter of the Association for Computational Linguistics: Human Language Technologies, Volume 1 (Long Papers)*, pages 1112–1122, 2018.

[37] Ruibin Xiong, Yimeng Chen, Liang Pang, Xueqi Cheng, Zhi-Ming Ma, and Yanyan Lan. Uncertainty calibration for ensemble-based debiasing methods. *Advances in Neural Information Processing Systems*, 34, 2021.