PER-TENSOR FIXED-POINT QUANTIZATION OF THE BACK-PROPAGATION ALGORITHM

Anonymous authors
Paper under double-blind review

ABSTRACT

The high computational and parameter complexity of neural networks makes their training very slow and difficult to deploy on energy and storage-constrained computing systems. Many network complexity reduction techniques have been proposed including fixed-point implementation. However, a systematic approach for designing full fixed-point training and inference of deep neural networks remains elusive. We describe a precision assignment methodology for neural network training in which all network parameters, i.e., activations and weights in the feedforward path, gradients and weight accumulators in the feedback path, are assigned close to minimal precision. The precision assignment is derived analytically and enables tracking the convergence behavior of the full precision training, known to converge a priori. Thus, our work leads to a systematic methodology of determining suitable precision for fixed-point training. The near optimality (minimality) of the resulting precision assignment is validated empirically for four networks on the CIFAR-10, CIFAR-100, and SVHN datasets. The complexity reduction arising from our approach is compared with other fixed-point neural network designs.

1 INTRODUCTION

Though deep neural networks (DNNs) have established themselves as powerful predictive models achieving human-level accuracy on many machine learning tasks (He et al., 2016), their excellent performance has been achieved at the expense of a very high *computational* and *parameter* complexity. For instance, AlexNet (Krizhevsky et al., 2012) requires over 800×10^6 multiply-accumulates (MACs) per image and has 60 million parameters, while Deepface (Taigman et al., 2014) requires over 500×10^6 MACs/image and involves more than 120 million parameters. DNNs' enormous computational and parameter complexity leads to high energy consumption (Chen et al., 2017), makes their training via the *stochastic gradient descent* (SGD) algorithm very slow often requiring hours and days (Goyal et al., 2017), and inhibits their deployment on energy and resource-constrained platforms such as mobile devices and autonomous agents.

A fundamental problem contributing to the high computational and parameter complexity of DNNs is their realization using 32-b floating-point (FL) arithmetic in GPUs and CPUs. Reduced-precision representations such as *quantized FL* (QFL) and *fixed-point* (FX) have been employed in various combinations to both training and inference. Many employ FX during inference but train in FL, e.g., fully binarized neural networks (Hubara et al., 2016) use 1-b FX in the forward inference path but the network is trained in 32-b FL. Similarly, Gupta et al. (2015) employs 16-b FX for all tensors except for the internal accumulators which use 32-b FL, and 3-level QFL gradients were employed (Wen et al., 2017; Alistarh et al., 2017) to accelerate training in a distributed setting. Note that while QFL reduces storage and communication costs, it does not reduce the computational complexity as the arithmetic remains in 32-b FL.

Thus, none of the previous works address the fundamental problem of realizing *true fixed-point DNN training*, i.e., an SGD algorithm in which all parameters/variables and all computations are implemented in FX with *minimum precision* required to *guarantee the network's inference/prediction accuracy* and *training convergence*. The reasons for this gap are numerous including: 1) quantization errors propagate to the network output thereby directly affecting its accuracy (Lin et al., 2016); 2) precision requirements of different variables in a network are interdependent and involve hard-to-quantify trade-offs (Sakr et al., 2017); 3) proper quantization requires the knowledge of the dynamic range which may not be available (Pascanu et al., 2013); and 4) quantization errors may accumulate during training and can lead to stability issues (Gupta et al., 2015).

Our work makes a major advance in closing this gap by proposing a systematic methodology to obtain *close-to-minimum* per-layer precision requirements of an FX network that guarantees statistical

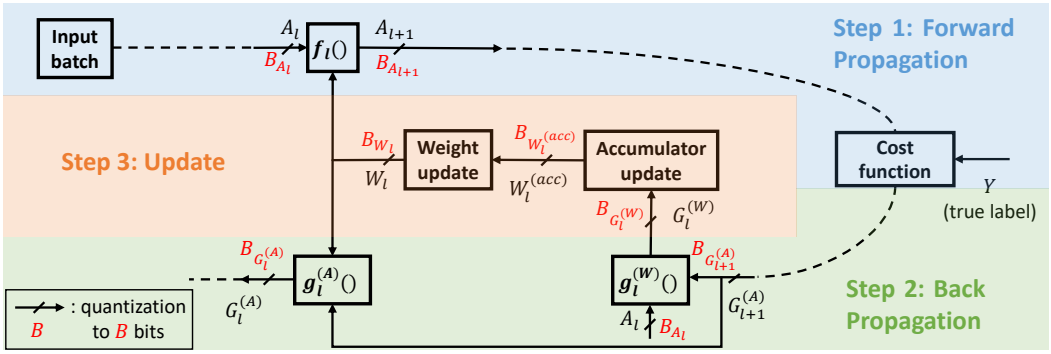

Figure 1: Problem setup: FX training at layer l of a DNN showing the quantized tensors and the associated precision configuration $C_l = (B_{W_l}, B_{A_l}, B_{G_l^{(W)}}, B_{G_{l+1}^{(A)}}, B_{W_l^{(acc)}})$.

similarity with full precision training. In particular, we jointly address the challenges of quantization noise, inter-layer and intra-layer precision trade-offs, dynamic range, and stability. As in (Sakr et al., 2017), we do assume that a fully-trained baseline FL network exists and one can observe its learning behavior. This one assumption is not too restrictive as state-of-the-art neural networks such as AlexNet (Krizhevsky et al., 2012), VGG-Net (Simonyan and Zisserman, 2014), and ResNet (He et al., 2016) to name a few, are already trained in FL. In practice, this assumption can be accounted for via a warm-up FL training on a small held-out portion of the dataset (Dwork et al., 2015).

Applying our methodology to three benchmarks reveals several lessons. First and foremost, our work shows that it is possible to FX quantize all variables including back-propagated gradients even though their dynamic range is unknown (Köster et al., 2017). Second, we find that the per-layer weight precision requirements decrease from the input to the output while those of the activation gradients and weight accumulators increase. Furthermore, the precision requirements for residual networks are found to be uniform across layers. Finally, hyper-precision reduction techniques such as weight and activation binarization (Hubara et al., 2016) or gradient ternarization (Wen et al., 2017) are not as efficient as our methodology since these do not address the fundamental problem of realizing true fixed-point DNN training.

We demonstrate FX training on three deep learning benchmarks (CIFAR-10, CIFAR-100, SVHN) achieving *high fidelity* to our FL baseline in that we observe no loss of accuracy higher then **0.56%** in all of our experiments. Our precision assignment is further shown to be *within 1-b per-tensor* of the minimum. We show that our precision assignment methodology reduces representational, computational, and communication costs of training by up to **6**×, **8**×, and **4**×, respectively, compared to the FL baseline and related works.

2 Problem Setup, Notation, and Metrics

We consider a L-layer DNN deployed on a M-class classification task using the setup in Figure 1. We denote the *precision configuration* as the $L \times 5$ matrix $C = (B_{W_l}, B_{A_l}, B_{G_l^{(W)}}, B_{G_{l+1}^{(A)}}, B_{W_l^{(acc)}})_{l=1}^{L}$ whose l^{th} row consists of the precision (in bits) of weight W_l (B_{W_l}), activation A_l (B_{A_l}), weight gradient $G_l^{(W)}$ ($B_{G_l^{(W)}}$), activation gradient $G_{l+1}^{(A)}$ ($B_{G_{l+1}^{(A)}}$), and internal weight accumulator $W_l^{(acc)}$ ($B_{W_l^{(acc)}}$) tensors at layer l. This DNN quantization setup is summarized in Appendix A.

2.1 Fixed-point Constraints & Definitions

We present definitions/constraints related to fixed-point arithmetic based on the design of fixed-point adaptive filters and signal processing systems (Parhi, 2007):

- A *signed* fixed-point scalar a with precision B_A and binary representation $R_A = (a_0, a_1, \ldots, a_{B_A-1}) \in \{0,1\}^{B_A}$ is equal to: $a = r_A \left(-a_0 + \sum_{i=1}^{B_A-1} 2^{-i} a_i\right)$, where r_A is the predetermined dynamic range (PDR) of a. The PDR is constrained to be a **constant power of 2** to minimize hardware overhead.
- An *unsigned* fixed-point scalar a with precision B_A and binary representation $R_A = (a_0, a_1, \ldots, a_{B_A-1}) \in \{0,1\}^{B_A}$ is equal to: $a = r_A \sum_{i=0}^{B_A-1} 2^{-i} a_i$.
- A fixed-point scalar a is called *normalized* if $r_A = 1$.

- The precision B_A is determined as: $B_A = \log_2 \frac{r_A}{\Delta_A} + 1$, where Δ_A is the *quantization step size* which is the value of the *least significant bit (LSB)*.
- An *additive model* for quantization is assumed: $a = \tilde{a} + q_a$, where a is the fixed-point number obtained by quantizing the floating-point scalar $\tilde{a}$, q_a is a random variable uniformly distributed on the interval $\left[-\frac{\Delta_A}{2}, \frac{\Delta_A}{2}\right]$, and the quantization noise variance is $Var(q_a) = \frac{\Delta_A^2}{12}$. The notion of quantization noise is most useful when there is limited knowledge of the distribution of $\tilde{a}$.
- The *relative quantization bias* η_A is the offset: $\eta_A = \frac{|\Delta_A - \mu_A|}{\mu_A}$, where the first unbiased quantization level $\mu_A = \mathbb{E}\left[\tilde{a} \middle| \tilde{a} \in I_1\right]$ and $I_1 = \left[\frac{\Delta_A}{2}, \frac{3\Delta_A}{2}\right]$. The notion of quantization bias is useful when there is some knowledge of the distribution of $\tilde{a}$.
- The *reflected quantization noise variance* from a tensor T to a scalar $\alpha = f(T)$, for an arbitrary function $f()$, is : $V_{T\to\alpha} = E_{T\to\alpha} \frac{\Delta_T^2}{12}$, where Δ_T is the quantization step of T and $E_{T\to\alpha}$ is the *quantization noise gain* from T to α.
- The *clipping rate* β_T of a tensor T is the probability: $\beta_T = \Pr\left(\{|t| \geq r_T : t \in T\}\right)$, where r_T is the PDR of T.

2.2 Complexity Metrics

We use a set of metrics inspired by those introduced by Sakr et al. (2017) which have also been used by Wu et al. (2018a). These metrics are algorithmic in nature which makes them easily reproducible.

- *Representational Cost* for weights ($\mathcal{C}_W$) and activations ($\mathcal{C}_A$):
  $\mathcal{C}_W = \sum_{l=1}^{L} |W_l| \left(B_{W_l} + B_{G_l^{(W)}} + B_{W_l^{(acc)}}\right)$ & $\mathcal{C}_A = \sum_{l=1}^{L} |A_l| \left(B_{A_l} + B_{G_{l+1}^{(A)}}\right)$,
  which equals the total number of bits needed to represent the weights, weight gradients, and internal weight accumulators (C_W), and those for activations and activation gradients (C_A). [1]
- *Computational Cost* of training: $\mathcal{C}_M = \sum_{l=1}^{L} |A_{l+1}| D_l \left(B_{W_l} B_{A_l} + B_{W_l} B_{G_{l+1}^{(A)}} + B_{A_l} B_{G_{l+1}^{(A)}}\right)$, where D_l is the dimensionality of the dot product needed to compute one output activation at layer l. This cost is a measure of the number of 1-b full adders (FAs) utilized for all multiplications in one back-prop iteration. [2]
- *Communication Cost*: $\mathcal{C}_C = \sum_{l=1}^{L} |W_l| B_{G_l^{(W)}}$, which represents cost of communicating weight gradients in a distributed setting (Wen et al., 2017; Alistarh et al., 2017).

3 Precision Assignment Methodology and Analysis

We aim to obtain a minimal or close-to-minimal precision configuration C_o of a FX network such that the mismatch probability $p_m = \Pr\{\hat{Y}_{fl} \neq \hat{Y}_{fx}\}$ between its predicted label ($\hat{Y}_{fx}$) and that of an associated FL network ($\hat{Y}_{fl}$) is bounded, and the convergence behavior of the two networks is similar.

Hence, we require that: (1) all quantization noise sources in the forward path contribute identically to the mismatch budget p_m (Sakr et al., 2017), (2) the gradients be properly clipped in order to limit the dynamic range (Pascanu et al., 2013), (3) accumulation of quantization noise bias in the weight updates be limited (Gupta et al., 2015), (4) the quantization noise in activation gradients be limited as these are back-propagated to calculate the weight gradients, and (5) the precision of weight accumulators should be set so as to avoid premature stoppage convergence (Goel and Shanbhag, 1998). The above insights can be formally described via the following five quantization criteria.

Criterion 1. *Equalizing Feedforward Quantization Noise (EFQN) Criterion.* The reflected quantization noise variances onto the mismatch probability p_m from all feedforward weights ($\{V_{W_l\to p_m}\}_{l=1}^{L}$) and activations ($\{V_{A_l\to p_m}\}_{l=1}^{L}$) should be equal:

$$V_{W_1\to p_m} = \ldots = V_{W_L\to p_m} = V_{A_1\to p_m} = \ldots = V_{A_L\to p_m}$$

Criterion 2. *Gradient Clipping (GC) Criterion.* The clipping rates of weight ($\{\beta_{G_l^{(W)}}\}_{l=1}^{L}$) and activation ($\{\beta_{G_{l+1}^{(A)}}\}_{l=1}^{L}$) gradients should be less than a maximum value β_0:

$$\beta_{G_l^{(W)}} < \beta_0 \quad \& \quad \beta_{G_{l+1}^{(A)}} < \beta_0 \quad \text{for } l = 1 \ldots L.$$

[1] We use the notation $|T|$ to denote the number of elements in tensor T. Unquantized tensors are assumed to have a 32-b FL representation, which is the single-precision in a GPU.

[2] When considering 32-b FL multiplications, we ignore the cost of exponent addition thereby favoring the FL (conventional) implementation. Boundary effects (in convolutions) are neglected.

Criterion 3. *Relative Quantization Bias (RQB) Criterion.* The relative quantization bias of weight gradients ($\{\eta_{G_l^{(W)}}\}_{l=1}^{L}$) should be less than a maximum value η_0:

$$\eta_{G_l^{(W)}} < \eta_0 \quad \text{for } l = 1 \dots L.$$

Criterion 4. *Back-propagated Quantization Noise (BQN) Criterion.* The reflected quantization noise variance $V_{G_{l+1}^{(A)} \to \Sigma_l}$, i.e., the total sum of element-wise variances of $G_l^{(W)}$ reflected from quantizing $G_{l+1}^{(A)}$, should be less than $V_{G_l^{(W)} \to \Sigma_l}$:

$$V_{G_{l+1}^{(A)} \to \Sigma_l} \leq V_{G_l^{(W)} \to \Sigma_l} \quad \text{for } l = 1 \dots L.$$

where Σ_l is the total sum of element-wise variances of $G_l^{(W)}$.

Criterion 5. *Accumulator Stopping (AS) Criterion.* The quantization noise of the internal accumulator should be zero, equivalently:

$$V_{W_l^{(acc)} \to \Sigma_l^{(acc)}} = 0 \quad \text{for } l = 1 \dots L$$

where $V_{W_l^{(acc)} \to \Sigma_l^{(acc)}}$ is the reflected quantization noise variance from $W_l^{(acc)}$ to $\Sigma_l^{(acc)}$, its total sum of element-wise variances.

The following claim ensures the satisfiability of the above criteria. This leads to closed form expressions for the precision requirements we are seeking and completes our methodology. The validity of the claim is proved in Appendix B.

Claim 1. *Satisfiability of Quantization Criteria.* The five quantization criteria (EFQN, GC, RQB, BQN, AS) are satisfied if:

- The precisions B_{W_l} and B_{A_l} are set as follows:

$$B_{W_l} = rnd\left(\log_2\left(\sqrt{\frac{E_{W_l \to p_m}}{E^{(\min)}}}\right)\right) + B^{(\min)} \;\;\&\;\; B_{A_l} = rnd\left(\log_2\left(\sqrt{\frac{E_{A_l \to p_m}}{E^{(\min)}}}\right)\right) + B^{(\min)} \tag{1}$$

  for $l = 1 \dots L$, where $rnd()$ denotes the rounding operation, $E_{W_l \to p_m}$ and $E_{A_l \to p_m}$ are the weight and activation quantization noise gains at layer l, respectively, $B^{(\min)}$ is a reference minimum precision, and $E^{(\min)} = \min\left(\{E_{W_l \to p_m}\}_{l=1}^{L}, \{E_{A_l \to p_m}\}_{l=1}^{L}\right)$.
- The weight and activation gradients PDRs are lower bounded as follows:

$$r_{G_l^{(W)}} \geq 2\sigma_{G_l^{(W)}}^{(\max)} \quad \& \quad r_{G_{l+1}^{(A)}} \geq 4\sigma_{G_{l+1}^{(A)}}^{(\max)} \quad \text{for } l = 1 \dots L \tag{2}$$

  where $\sigma_{G_l^{(W)}}^{(\max)}$ and $\sigma_{G_{l+1}^{(A)}}^{(\max)}$ are the largest recorded estimates of the weight and activation gradients standard deviations $\sigma_{G_l^{(W)}}$ and $\sigma_{G_{l+1}^{(A)}}$, respectively.
- The weight and activation gradients quantization step sizes are upper bounded as follows:

$$\Delta_{G_l^{(W)}} < \frac{\sigma_{G_l^{(W)}}^{(\min)}}{4} \quad \& \quad \Delta_{G_{l+1}^{(A)}} < \frac{\Delta_{G_l^{(W)}}}{\sqrt{\lambda_{G_{l+1}^{(A)} \to G_l^{(W)}}^{(\max)}}} \left(\frac{\left|G_l^{(W)}\right|}{\left|G_{l+1}^{(A)}\right|}\right)^{1/4} \quad \text{for } l = 1 \dots L \tag{3}$$

  where $\sigma_{G_l^{(W)}}^{(\min)}$ is the smallest recorded estimate of $\sigma_{G_l^{(W)}}$ and $\lambda_{G_{l+1}^{(A)} \to G_l^{(W)}}^{(\max)}$ is the largest singular value of the square-Jacobian (Jacobian matrix with squared entries) of $G_l^{(W)}$ with respect to $G_{l+1}^{(A)}$.
- The accumulator PDR and step size satisfy:

$$r_{W_l^{(acc)}} \geq 2^{-B_{W_l}} \quad \& \quad \Delta_{W_l^{(acc)}} < \gamma^{(\min)} \Delta_{G_l^{(W)}} \quad \text{for } l = 1 \dots L \tag{4}$$

  where $\gamma^{(\min)}$ is the smallest value of the learning rate used during training.

Practical considerations: Note that one of the $2L$ feedforward precisions will equal $B^{(\min)}$. The formulas to compute the quantization noise gains are given in Appendix B and require only one forward-backward pass on an estimation set. We would like the EFQN criterion to hold upon convergence; hence, (1) is computed using the converged model from the FL baseline. For backward signals, setting the values of PDR and LSB is sufficient to determine the precision as explained in Section 2.1. As per Claim 1, estimates of the second order statistics, e.g., $\sigma_{G_l^{(W)}}$ and $\sigma_{G_{l+1}^{(A)}}$, of the gradient tensors, are required. These are obtained via tensor spatial averaging, so that one estimate per tensor is required, and updated in a moving window fashion, as is done for normalization parameters in BatchNorm (Ioffe and Szegedy, 2015). Furthermore, it might seem that computing the Jacobian in (3) is a difficult task; however, the values of its elements are already computed by the back-prop algorithm, requiring no additional computations (see Appendix B). Thus, the Jacobians (at different layers) are also estimated during training. Due to the typical very large size of modern neural networks, we average the Jacobians spatially, i.e., the activations are aggregated across channels and mini-batches while weights are aggregated across filters. This is again inspired by the work on Batch Normalization (Ioffe and Szegedy, 2015) and makes the probed Jacobians much smaller.

4 Numerical Results

We conduct numerical simulations in order to illustrate the validity of the predicted precision configuration C_o and investigate its minimality and benefits. We employ three deep learning benchmarking datasets: CIFAR-10, CIFAR-100 (Krizhevsky and Hinton, 2009), and SVHN (Netzer et al., 2011). All experiments were done using a Pascal P100 NVIDIA GPU. We train the following networks:

- CIFAR-10 ConvNet: a 9-layer convolutional neural network trained on the CIFAR-10 dataset described as $2 \times (64C3) - MP2 - 2 \times (128C3) - MP2 - 2 \times (256C3) - 2 \times (512FC) - 10$ where $C3$ denotes 3×3 convolutions, $MP2$ denotes 2×2 max pooling operation, and FC denotes fully connected layers.
- SVHN ConvNet: the same network as the CIFAR-10 ConvNet, but trained on the SVHN dataset.
- CIFAR-10 ResNet: a wide deep residual network (Zagoruyko and Komodakis, 2016) with ResNet-20 architecture but having 8 times as many channels per layer compared to (He et al., 2016).
- CIFAR-100 ResNet: same network as CIFAR-10 ResNet save for the last layer to match the number of classes (100) in CIFAR-100.

A step by step description of the application of our method to the above four networks is provided in Appendix C. We hope the inclusion of these steps would: (1) clarify any ambiguity the reader may have from the previous section and (2) facilitate the reproduction of our results.

4.1 Precision Configuration C_o & Convergence

The precision configuration C_o, with target $p_m \leq 1\%$, $\beta_0 \leq 5\%$, and $\eta_0 \leq 1\%$, via our proposed method is depicted in Figure 2 for each of the four networks considered. We observe that C_o is dependent on the network *type*. Indeed, the precisions of the two ConvNets follow similar trends as do those the two ResNets. Furthermore, the following observations are made for the ConvNets:

- weight precision B_{W_l} *decreases as depth increases*. This is consistent with the observation that weight perturbations in the earlier layers are the most destructive (Raghu et al., 2017).
- the precisions of activation gradients ($B_{G_l^{(A)}}$) and internal weight accumulators ($B_{W_l^{(acc)}}$) *increases as depth increases* which we interpret as follows: (1) the back-propagation of gradients is the *dual* of the forward-propagation of activations, and (2) accumulators store the *most information* as their precision is the highest.
- the precisions of the weight gradients ($B_{G_l^{(W)}}$) and activations (B_{A_l}) are *relatively constant across layers*.

Interestingly, for ResNets, the precision is mostly uniform across the layers. Furthermore, the gap between $B_{W_l^{(acc)}}$ and the other precisions is not as pronounced as in the case of ConvNets. This suggests that information is spread equally among all signals which we speculate is due to the shortcut connections preventing the *shattering* of information (Balduzzi et al., 2017).

FX training curves in Figure 3 indicate that C_o leads to *convergence* and consistently track FL curves with *close fidelity*. This validates our analysis and justifies the choice of C_o.

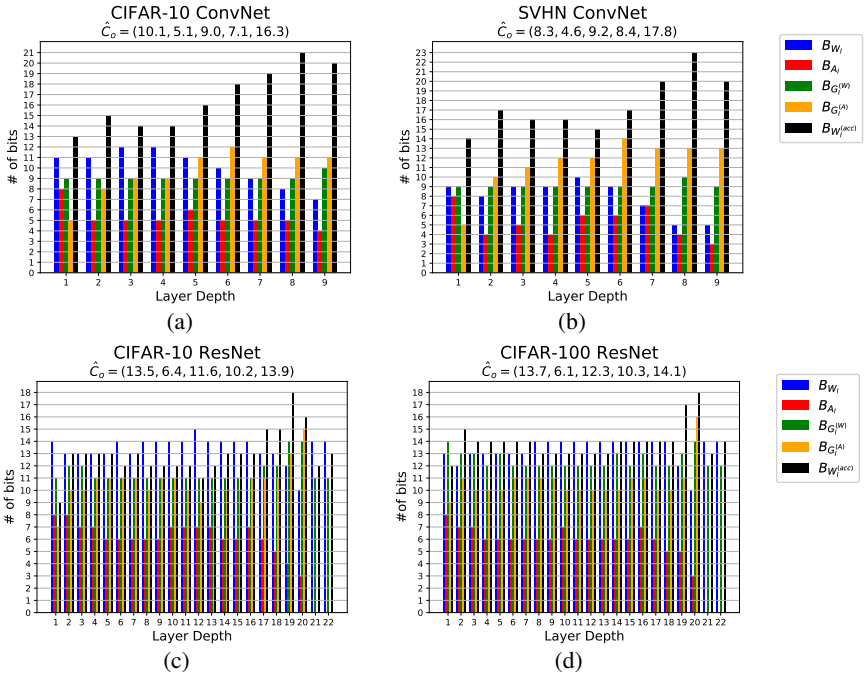

Figure 2: The predicted precision configurations C_o for the CIFAR-10 ConvNet (a), SVHN ConvNet (b), CIFAR-10 ResNet (c), and CIFAR-100 ResNet (d). For each network, the 5-tuple $\hat{C}_o$ represents the average number of bits per tensor type. For the ResNets, layer depths 21 and 22 correspond to the strided convolutions in the shortcut connections of residual blocks 4 and 7, respectively. Activation gradients go from layer 2 to $L+1$ and are "shifted to the left" in order to be aligned with the other tensors.

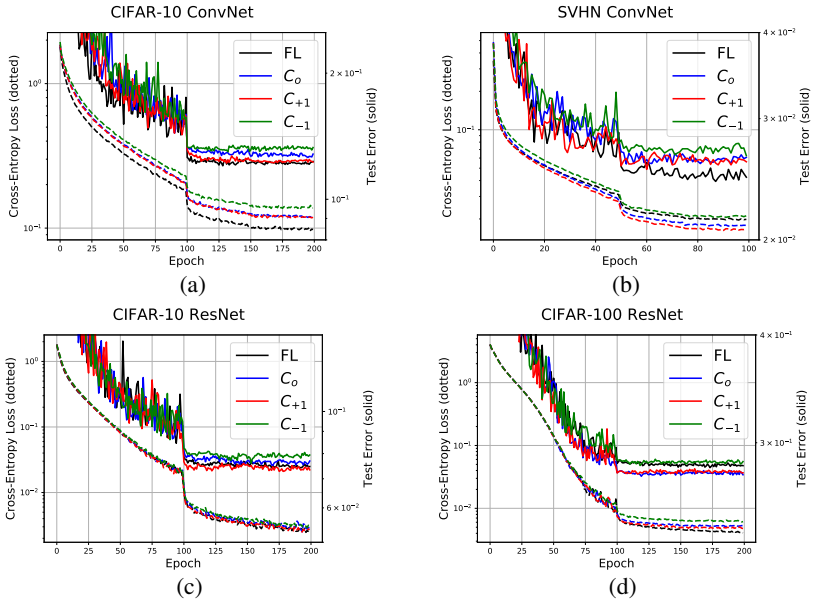

Figure 3: Convergence curves for the CIFAR-10 ConvNet (a), SVHN ConvNet (b), CIFAR-10 ResNet (c), and CIFAR-100 ResNet (d) including FL training as well as FX training with precision configurations C_o, C_1, and C_{-1}.

4.2 Near Minimality of C_o

To determine that C_o is a close-to-minimal precision assignment, we compare it with: (a) $C_{+1} = C_o + \mathbf{1}_{L\times 5}$, and (b) $C_{-1} = C_o - \mathbf{1}_{L\times 5}$, where $\mathbf{1}_{L\times 5}$ is an $L \times 5$ matrix with each entry equal to 1[3], i.e., we perturb C_o by 1-b in either direction. Figure 3 also contains the convergence curves for the two new configurations. As shown, C_{-1} always results in a noticeable gap compared to C_o for both

[3]PDRs are unchanged across configurations, except for $r_{W_l^{(acc)}}$ as per (4).

Table 1: Complexity ($\mathcal{C}_W$, $\mathcal{C}_A$, $\mathcal{C}_M$, and $\mathcal{C}_C$) and accuracy (test error) for the floating-point (FL), fixed-point (FX) with precision configuration C_o, binarized network (BN), stochastic quantization (SQ), and TernGrad (TG) training schemes.

	$\mathcal{C}_W$ (10^6b)	$\mathcal{C}_A$ (10^6b)	$\mathcal{C}_M$ (10^9FA)	$\mathcal{C}_C$ (10^6b)	Test Error	$\mathcal{C}_W$ (10^6b)	$\mathcal{C}_A$ (10^6b)	$\mathcal{C}_M$ (10^9FA)	$\mathcal{C}_C$ (10^6b)	Test Error
	CIFAR-10 ConvNet					**SVHN ConvNet**				
FL	148	9.3	94.4	49	12.02%	148	9.3	94.4	49	**2.43**%
FX (C_o)	**56.5**	**1.7**	11.9	14	12.58%	**54.3**	**1.9**	10.5	14	2.58%
BN	100	4.7	**2.8**	49	18.50%	100	4.7	**2.8**	49	3.60%
SQ	78.8	**1.7**	11.9	14	**11.32**%	76.3	**1.9**	10.5	14	2.73%
TG	102	9.3	94.4	**3.1**	12.49%	102	9.3	94.4	**3.1**	3.65%
	CIFAR-10 ResNet					**CIFAR-100 ResNet**				
FL	1784	96	4319	596	7.42%	1789	97	4319	597	28.06%
FX (C_o)	**726**	**25**	785	216	7.51%	**750**	**25**	776	216	**27.43**%
BN	1208	50	**128**	596	**7.24**%	1211	50	**128**	597	29.35%
SQ	1062	**25**	785	216	7.42%	1081	**25**	776	216	28.03%
TG	1227	96	4319	**37.3**	7.94%	1230	97	4319	**37.3**	30.62%

the loss function (except for the CIFAR-10 ResNet) and the test error. Furthermore, C_{+1} offers no observable improvements over C_o (except for the test error of CIFAR-10 ConvNet). These results support our contention that C_o is *close-to-minimal* in that increasing the precision above C_o leads to diminishing returns while reducing precision below C_o leads to a noticeable degradation in accuracy.

4.3 Complexity vs. Accuracy

We would like to quantify the reduction in training cost and expense in terms of accuracy resulting from our proposed method and compare them with those of other methods. Importantly, for a fair comparison, the *same* network architecture and training procedure are used. We report $\mathcal{C}_W$, $\mathcal{C}_A$, $\mathcal{C}_M$, $\mathcal{C}_C$, and test error, for each of the four networks considered for the following training methods:

- baseline FL training and FX training using C_o,
- binarized network (BN) training, where feedforward weights and activations are binary (constrained to ± 1) while gradients and accumulators are in floating-point and activation gradients are back-propagated via the straight through estimator (Bengio et al., 2013) as was done in (Hubara et al., 2016),
- fixed-point training with stochastic quantization (SQ). As was done in (Gupta et al., 2015), we quantize feedforward weights and activations as well as all gradients, but accumulators are kept in floating-point. The precision configuration (excluding accumulators) is inherited from C_o (hence we determine exactly how much stochastic quantization helps),
- training with ternarized gradients (TG) as was done in TernGrad (Wen et al., 2017). All computations are done in floating-point but weight gradients are ternarized according to the instantaneous tensor spatial standard deviations $\{-2.5\sigma, 0, 2.5\sigma\}$ as was suggested by Wen et al. (2017). To compute costs, we assume all weight gradients use two bits although they are not really fixed-point and do require computation of 32-b floating-point scalars for every tensor.

The comparison is presented in Table 1. The first observation is a massive complexity reduction compared to FL. For instance, for the CIFAR-10 ConvNet, the complexity reduction is $2.6\times$ $(148/56.5)$, $5.5\times$ $(9.3/1.7)$, $7.9\times$ $(94.4/11.9)$, and $3.5\times$ $(49/14)$ for $\mathcal{C}_W$, $\mathcal{C}_A$, $\mathcal{C}_M$, and $\mathcal{C}_C$, respectively. Similar trends are observed for the other four networks. Such complexity reduction comes at the expense of no more than **0.56%** increase in test error. For the CIFAR-100 network, the accuracy when training in fixed-point is even better than that of the baseline.

The representational and communication costs of BN is significantly greater than that of FX because the gradients and accumulators are kept in full precision, which masks the benefits of binarizing feedforward tensors. However, benefits are noticeable when considering the computational cost which is lowest as binarization eliminates multiplications. Furthermore, binarization causes a severe accuracy drop for the ConvNets but surprisingly not for the ResNets. We speculate that this is due to the high dimensional geometry of ResNets (Anderson and Berg, 2017).

As for SQ, since C_o was inherited, all costs are identical to FX, save for $\mathcal{C}_W$ which is larger due to full precision accumulators. Furthermore, SQ has a positive effect only on the CIFAR-10 ConvNet where it clearly acted as a regularizer.

TG does not provide complexity reductions in terms of representational and computational costs which is expected as it only compresses weight gradients. Additionally, the resulting accuracy is slightly worse than that of all other considered schemes, including FX. Naturally, it has the lowest communication cost as weight gradients are quantized to just 2-b.

5 DISCUSSION

5.1 RELATED WORKS

Many works have addressed the general problem of reduced precision/complexity deep learning.

Reducing the complexity of inference (forward path): several research efforts have addressed the problem of realizing a DNN's inference path in FX. For instance, the works in (Lin et al., 2016; Sakr et al., 2017) address the problem of precision assignment. While Lin et al. (2016) proposed a non-uniform precision assignment using the signal-to-quantization-noise ratio (SQNR) metric, Sakr et al. (2017) analytically quantified the trade-off between activation and weight precisions while providing minimal precision requirements of the inference path computations that bounds the probability p_m of a mismatch between predicted labels of the FX and its FL counterpart. An orthogonal approach which can be applied on top of quantization is pruning (Han et al., 2015). While significant inference efficiency can be achieved, this approach incurs a substantial training overhead. A subset of the FX training problem was addressed in binary weighted neural networks (Courbariaux et al., 2015; Rastegari et al., 2016) and fully binarized neural networks (Hubara et al., 2016), where direct training of neural networks with *pre-determined precisions* in the inference path was explored with the feedback path computations being done in 32-b FL.

Reducing the complexity of training (backward path): finite-precision training was explored in (Gupta et al., 2015) which employed stochastic quantization in order to counter quantization bias accumulation in the weight updates. This was done by quantizing all tensors to 16-b FX, except for the internal accumulators which were stored in a 32-b floating-point format. An important distinction our work makes is the circumvention of the overhead of implementing stochastic quantization (Hubara et al., 2016). Similarly, DoReFa-Net (Zhou et al., 2016) stores internal weight representations in 32-b FL, but quantizes the remaining tensors more aggressively. Thus arises the need to re-scale and re-compute in floating-point format, which our work avoids. Finally, Köster et al. (2017) suggests a new number format – Flexpoint – and were able to train neural networks using slightly 16-b per tensor element, with 5 shared exponent bits and a per-tensor dynamic range tracking algorithm. Such tracking causes a hardware overhead bypassed by our work since the arithmetic is purely FX. Augmenting Flexpoint with stochastic quantization effectively results in WAGE (Wu et al., 2018b), and enables integer quantization of each tensor.

As seen above, none of the prior works address the problem of predicting precision requirements of all training signals. Furthermore, the choice of precision is made in an ad-hoc manner. In contrast, we propose a *systematic methodology* to determine *close-to-minimal* precision requirements for FX-only training of deep neural networks.

5.2 CONCLUSION

In this paper, we have presented a study of precision requirements in a typical back-propagation based training procedure of neural networks. Using a set of quantization criteria, we have presented a precision assignment methodology for which FX training is made statistically similar to the FL baseline, known to converge a priori. We realized FX training of four networks on the CIFAR-10, CIFAR-100, and SVHN datasets and quantified the associated complexity reduction gains in terms costs of training. We also showed that our precision assignment is nearly minimal.

The presented work relies on the statistics of all tensors being quantized *during training*. This necessitates an initial baseline run in floating-point which can be costly. An open problem is to predict a suitable precision configuration by only observing the data statistics and the network architecture. We speculate that a similar study to that of the effects of initialization (Glorot and Bengio, 2010) on convergence could be one way to address this challenge. An even greater extension would be to completely suppress data and network dependence so that universal, yet nearly minimal precision configurations can be determined. Such extension would be of immense value to system designers.

REFERENCES

Alistarh, D., Grubic, D., Li, J., Tomioka, R., and Vojnovic, M. (2017). Qsgd: Communication-efficient sgd via gradient quantization and encoding. In *Advances in Neural Information Processing Systems*, pages 1707–1718.

Anderson, A. G. and Berg, C. P. (2017). The high-dimensional geometry of binary neural networks. *arXiv preprint arXiv:1705.07199*.

Balduzzi, D., Frean, M., Leary, L., Lewis, J. P., Ma, K. W.-D., and McWilliams, B. (2017). The shattered gradients problem: If resnets are the answer, then what is the question? In *Proceedings of the 34th International Conference on Machine Learning*, pages 342–350.

Bengio, Y., Léonard, N., and Courville, A. (2013). Estimating or propagating gradients through stochastic neurons for conditional computation. *arXiv preprint arXiv:1308.3432*.

Chen, Y.-H., Krishna, T., Emer, J. S., and Sze, V. (2017). Eyeriss: An energy-efficient reconfigurable accelerator for deep convolutional neural networks. *IEEE Journal of Solid-State Circuits*, 52(1):127–138.

Courbariaux, M., Bengio, Y., and David, J.-P. (2015). Binaryconnect: Training deep neural networks with binary weights during propagations. In *Advances in Neural Information Processing Systems*, pages 3123–3131.

Dwork, C., Feldman, V., Hardt, M., Pitassi, T., Reingold, O., and Roth, A. (2015). The reusable holdout: Preserving validity in adaptive data analysis. *Science*, 349(6248):636–638.

Glorot, X. and Bengio, Y. (2010). Understanding the difficulty of training deep feedforward neural networks. In *Proceedings of the Thirteenth International Conference on Artificial Intelligence and Statistics*, pages 249–256.

Goel, M. and Shanbhag, N. (1998). Finite-precision analysis of the pipelined strength-reduced adaptive filter. *Signal Processing, IEEE Transactions on*, 46(6):1763–1769.

Goodfellow, I. J. et al. (2013). Maxout networks. *ICML (3)*, 28:1319–1327.

Goyal, P., Dollár, P., Girshick, R., Noordhuis, P., Wesolowski, L., Kyrola, A., Tulloch, A., Jia, Y., and He, K. (2017). Accurate, large minibatch sgd: training imagenet in 1 hour. *arXiv preprint arXiv:1706.02677*.

Gupta, S., Agrawal, A., Gopalakrishnan, K., and Narayanan, P. (2015). Deep learning with limited numerical precision. In *Proceedings of The 32nd International Conference on Machine Learning*, pages 1737–1746.

Han, S., Mao, H., and Dally, W. J. (2015). Deep compression: Compressing deep neural networks with pruning, trained quantization and huffman coding. *arXiv preprint arXiv:1510.00149*.

He, K., Zhang, X., Ren, S., and Sun, J. (2016). Deep residual learning for image recognition. In *Proceedings of the IEEE Conference on Computer Vision and Pattern Recognition*, pages 770–778.

Hubara, I., Courbariaux, M., Soudry, D., El-Yaniv, R., and Bengio, Y. (2016). Binarized neural networks. In *Advances in Neural Information Processing Systems*, pages 4107–4115.

Ioffe, S. and Szegedy, C. (2015). Batch normalization: Accelerating deep network training by reducing internal covariate shift. In *International Conference on Machine Learning*, pages 448–456.

Köster, U., Webb, T., Wang, X., Nassar, M., Bansal, A. K., Constable, W., Elibol, O., Hall, S., Hornof, L., Khosrowshahi, A., et al. (2017). Flexpoint: An adaptive numerical format for efficient training of deep neural networks. In *Advances in Neural Information Processing Systems*, pages 1740–1750.

Krizhevsky, A. and Hinton, G. (2009). Learning multiple layers of features from tiny images.

Krizhevsky, A., Sutskever, I., and Hinton, G. E. (2012). ImageNet classification with deep convolutional neural networks. In *Advances in Neural Information Processing Systems*, pages 1097–1105.

Lin, D., Talathi, S., and Annapureddy, S. (2016). Fixed point quantization of deep convolutional networks. In *Proceedings of The 33rd International Conference on Machine Learning*, pages 2849–2858.

Netzer, Y., Wang, T., Coates, A., Bissacco, A., Wu, B., and Ng, A. Y. (2011). Reading digits in natural images with unsupervised feature learning. In *NIPS workshop on deep learning and unsupervised feature learning*, volume 2011, page 5.

Parhi, K. (2007). *VLSI Digital Signal Processing Systems: Design and Implementation*. John Wiley & Sons.

Pascanu, R., Mikolov, T., and Bengio, Y. (2013). On the difficulty of training recurrent neural networks. In *International Conference on Machine Learning*, pages 1310–1318.

Raghu, M. et al. (2017). On the expressive power of deep neural networks. In *Proceedings of the 34th International Conference on Machine Learning*, pages 2847–2854.

Rastegari, M., Ordonez, V., Redmon, J., and Farhadi, A. (2016). XNOR-Net: Imagenet classification using binary convolutional neural networks. In *European Conference on Computer Vision*, pages 525–542. Springer.

Sakr, C., Kim, Y., and Shanbhag, N. (2017). Analytical guarantees on numerical precision of deep neural networks. In *Proceedings of the 34th International Conference on Machine Learning*, pages 3007–3016.

Simonyan, K. and Zisserman, A. (2014). Very deep convolutional networks for large-scale image recognition. *arXiv preprint arXiv:1409.1556*.

Srivastava, N. et al. (2014). Dropout: a simple way to prevent neural networks from overfitting. *Journal of Machine Learning Research*, 15(1):1929–1958.

Taigman, Y., Yang, M., Ranzato, M., and Wolf, L. (2014). Deepface: Closing the gap to human-level performance in face verification. In *Proceedings of the IEEE Conference on Computer Vision and Pattern Recognition*, pages 1701–1708.

Wen, W., Xu, C., Yan, F., Wu, C., Wang, Y., Chen, Y., and Li, H. (2017). Terngrad: Ternary gradients to reduce communication in distributed deep learning. In *Advances in Neural Information Processing Systems*, pages 1508–1518.

Wu, J., Wang, Y., Wu, Z., Wang, Z., Veeraraghavan, A., and Lin, Y. (2018a). Deep k-means: Re-training and parameter sharing with harder cluster assignments for compressing deep convolutions. In *International Conference on Machine Learning*, pages 5359–5368.

Wu, S., Li, G., Chen, F., and Shi, L. (2018b). Training and inference with integers in deep neural networks. *arXiv preprint arXiv:1802.04680*.

Zagoruyko, S. and Komodakis, N. (2016). Wide residual networks. *arXiv preprint arXiv:1605.07146*.

Zhou, S., Wu, Y., Ni, Z., Zhou, X., Wen, H., and Zou, Y. (2016). DoReFa-Net: Training low bitwidth convolutional neural networks with low bitwidth gradients. *arXiv preprint arXiv:1606.06160*.

Supplementary Material

A SUMMARY OF QUANTIZATION SETUP

The quantization setup depicted in Figure 1 is summarized as follows:

- Feedforward computation at layer l:

$$A_{l+1} = f_l(A_l, W_l)$$

  where $f_l()$ is the function implemented at layer l, A_l (A_{l+1}) is the activation tensor at layer l ($l+1$) quantized to a normalized unsigned fixed-point format with precision B_{A_l} ($B_{A_{l+1}}$), and W_l is the weight tensor at layer l quantized to a normalized signed fixed-point format with precision B_{W_l}. We further assume the use of a ReLU-like activation function with a clipping level of 2 and a max-norm constraint on the weights which are clipped between $[-1, 1]$ at every iteration.
- Back-propagation of activation gradients at layer l:

$$G_l^{(A)} = g_l^{(A)}(W_l, G_{l+1}^{(A)})$$

  where $g_l()^{(A)}$ is the function that back-propagates the activation gradients at layer l, $G_l^{(A)}$ ($G_{l+1}^{(A)}$) is the activation gradient tensor at layer l ($l+1$) quantized to a signed fixed-point format with precision $B_{G_l^{(A)}}$ ($B_{G_{l+1}^{(A)}}$).
- Back-propagation of weight gradient tensor $G_l^{(W)}$ at layer l:

$$G_l^{(W)} = g_l^{(W)}(A_l, G_{l+1}^{(A)})$$

  where $g_l^{(W)}()$ is the function that back-propagates the weight gradients at layer l, and $G_l^{(W)}$ is quantized to a signed fixed-point format with precision $B_{G_l^{(W)}}$.
- Internal weight accumulator update at layer l:

$$W_l^{(acc)} = U(W_l^{(acc)}, G_l^{(W)}, \gamma)$$

  where $U()$ is the update function, γ is the learning rate, and $W_l^{(acc)}$ is the internal weight accumulator tensor at layer l quantized to signed fixed-point with precision $B_{W_l^{(acc)}}$. Note that, for the next iteration, W_l is directly obtained from $W_l^{(acc)}$ via quantization to B_{W_l} bits.

B PROOF OF CLAIM 1

The validity of Claim 1 is derived from the following five lemmas. Note that each lemma addresses the satisfiability of one of the five quantization criteria presented in the main text and corresponds to part of Claim 1.

Lemma 1. *The EFQN criterion holds if the precisions B_{W_l} and B_{A_l} are set as follows:*

$$B_{W_l} = rnd\left(\log_2\left(\sqrt{\frac{E_{W_l \to p_m}}{E^{(\min)}}}\right)\right) + B^{(\min)} \;\;\&\;\; B_{A_l} = rnd\left(\log_2\left(\sqrt{\frac{E_{A_l \to p_m}}{E^{(\min)}}}\right)\right) + B^{(\min)}$$

for $l = 1 \ldots L$, where $rnd()$ denotes the rounding operation, $B^{(\min)}$ is a reference minimum precision, and $E^{(\min)}$ is given by:

$$E^{(\min)} = \min\left(\{E_{W_l \to p_m}\}_{l=1}^{L}, \{E_{A_l \to p_m}\}_{l=1}^{L}\right). \tag{5}$$

Proof. By definition of the reflected quantization noise variance, the EFQN, by definition, is satisfied if:

$$\frac{\Delta_{W_1}^2}{12} E_{W_1 \to p_m} = \ldots = \frac{\Delta_{W_L}^2}{12} E_{W_L \to p_m} = \frac{\Delta_{A_1}^2}{12} E_{A_1 \to p_m} = \ldots = \frac{\Delta_{A_L}^2}{12} E_{A_L \to p_m},$$

where the quantization noise gains are given by:

$$E_{W_l \to p_m} = \mathbb{E}\left[\sum_{\substack{i=1 \\ i \neq \hat{Y}_{fl}}}^{M} \frac{\sum_{w \in W_l} \left| \frac{\partial (Z_i - Z_{\hat{Y}_{fl}})}{\partial w} \right|^2}{2|Z_i - Z_{\hat{Y}_{fl}}|^2}\right] \quad \& \quad E_{A_l \to p_m} = \mathbb{E}\left[\sum_{\substack{i=1 \\ i \neq \hat{Y}_{fl}}}^{M} \frac{\sum_{a \in A_l} \left| \frac{\partial (Z_i - Z_{\hat{Y}_{fl}})}{\partial a} \right|^2}{2|Z_i - Z_{\hat{Y}_{fl}}|^2}\right] \tag{6}$$

for $l = 1 \dots L$, where $\{Z_i\}_{i=1}^{M}$ are the soft outputs and $Z_{\hat{Y}_{fl}}$ is the soft output corresponding to $\hat{Y}_{fl}$. The expressions for these quantization gains are obtained by linearly expanding (across layers) those used in (Sakr et al., 2017). Note that a second order upper bound is used as a surrogate expression for p_m.

From the definition of quantization step size, the above is equivalent to:

$$2^{-2B_{W_1}} E_{W_1 \to p_m} = \dots = 2^{-2B_{W_L}} E_{W_L \to p_m} = 2^{-2B_{A_1}} E_{A_1 \to p_m} = \dots = 2^{-2B_{A_L}} E_{A_L \to p_m}.$$

Let $E^{(\min)}$ be as defined in (5):

$$E^{(\min)} = \min\left(\{E_{W_l \to p_m}\}_{l=1}^{L}, \{E_{A_l \to p_m}\}_{l=1}^{L}\right).$$

We can divide each term by $E^{(\min)}$:

$$2^{-2B_{W_1}} \frac{E_{W_1 \to p_m}}{E^{(\min)}} = \dots = 2^{-2B_{W_L}} \frac{E_{W_L \to p_m}}{E^{(\min)}} = 2^{-2B_{A_1}} \frac{E_{A_1 \to p_m}}{E^{(\min)}} = \dots = 2^{-2B_{A_L}} \frac{E_{A_L \to p_m}}{E^{(\min)}}$$

where each term is positive, so that we can take square roots and logarithms such that:

$$B_{W_1} - \log_2\left(\sqrt{\frac{E_{W_1 \to p_m}}{E^{(\min)}}}\right) = \dots = B_{W_L} - \log_2\left(\sqrt{\frac{E_{W_L \to p_m}}{E^{(\min)}}}\right)$$
$$= B_{A_1} - \log_2\left(\sqrt{\frac{E_{A_1 \to p_m}}{E^{(\min)}}}\right) = \dots = B_{A_L} - \log_2\left(\sqrt{\frac{E_{A_L \to p_m}}{E^{(\min)}}}\right)$$

Thus we equate all of the above to a reference precision $B^{(\min)}$ yielding:

$$B_{W_l} = \log_2\left(\sqrt{\frac{E_{W_l \to p_m}}{E^{(\min)}}}\right) + B^{(\min)} \;\; \& \;\; B_{A_l} = \log_2\left(\sqrt{\frac{E_{A_l \to p_m}}{E^{(\min)}}}\right) + B^{(\min)}$$

for $l = 1 \dots L$. Note that because $E^{(\min)}$ is the least quantization noise gain, it is equal to one of the above quantization noise gains so that the corresponding precision actually equates $B^{(\min)}$. As precisions must be integer valued, each of $B^{(\min)}$, $\{B_{W_l}\}_{l=1}^{L}$, and $\{B_{A_l}\}_{l=1}^{L}$ have to be integers, and thus a rounding operation is to be applied on all logarithm terms. Doing so results in (1) from Lemma 1 which completes this proof. □

Lemma 2. *The GC criterion holds for $\beta_0 = 5\%$ provided the weight and activation gradients pre-defined dynamic ranges (PDRs) are lower bounded as follows:*

$$r_{G_l^{(W)}} \geq 2\sigma^{(\max)}_{G_l^{(W)}} \quad \& \quad r_{G_{l+1}^{(A)}} \geq 4\sigma^{(\max)}_{G_{l+1}^{(A)}} \quad \textit{for } l = 1 \dots L$$

where $\sigma^{(\max)}_{G_l^{(W)}}$ and $\sigma^{(\max)}_{G_{l+1}^{(A)}}$ are the largest ever recorded estimates of the weight and activation gradients standard deviations $\sigma_{G_l^{(W)}}$ and $\sigma_{G_{l+1}^{(A)}}$, respectively.

Proof. Let us consider the case of weight gradients. The GC criterion, by definition requires:

$$\beta_{G_l^{(W)}} = \Pr\left(\left\{|g| \geq r_{G_l^{(W)}} : g \in G_l^{(W)}\right\}\right) < 0.05$$

Typically, weight gradients are obtained by computing the derivatives of a loss function with respect to a mini-batch. By linearity of derivatives, weight gradients are themselves averages of instantaneous

derivatives and are hence expected to follow a Gaussian distribution by application of the Central Limit Theorem. Furthermore, the gradient mean was estimated during baseline training and was found to oscillate around zero.

Thus

$$\beta_{G_l^{(W)}} = 2Q\left(\frac{r_{G_l^{(W)}}}{\sigma_{G_l^{(W)}}}\right)$$

where we used the fact that a Gaussian distribution is symmetric and $Q()$ is the elementary Q-function, which is a decreasing function. Thus, in the worst case, we have:

$$\beta_{G_l^{(W)}} \leq 2Q\left(\frac{r_{G_l^{(W)}}}{\sigma^{(\max)}_{G_l^{(W)}}}\right).$$

Hence, for a PDR as suggested by the lower bound in (2):

$$r_{G_l^{(W)}} \geq 2\sigma^{(\max)}_{G_l^{(W)}}$$

in Lemma 2, we obtain the upper bound:

$$\beta_{G_l^{(W)}} \leq 2Q(2) = 0.044 < 0.05$$

which means the GC criterion holds and completes the proof.

For activation gradients, the same reasoning applies, but the choice of a larger PDR in (2):

$$r_{G_{l+1}^{(A)}} \geq 4\sigma^{(\max)}_{G_{l+1}^{(A)}}$$

than for weight gradients is due to the fact that the true dynamic range of the activation gradients is larger than the value indicated by the second moment. This stems from the use of activation functions such as ReLU which make the activation gradients sparse. We also recommend increasing the PDR even more when using regularizers that sparsify gradients such as Dropout (Srivastava et al., 2014) or Maxout (Goodfellow et al., 2013). □

Lemma 3. *The RQB criterion holds for $\eta_0 = 1\%$ provided the weight gradient quantization step size is upper bounded as follows:*

$$\Delta_{G_l^{(W)}} < \frac{\sigma^{(\min)}_{G_l^{(W)}}}{4} \quad \textit{for } l = 1 \ldots L$$

where $\sigma^{(\min)}_{G_l^{(W)}}$ is the smallest ever recorded estimate of $\sigma_{G_l^{(W)}}$.

Proof. For the Gaussian distributed (see proof of Lemma 2) weight gradient at layer l, the true mean conditioned on the first non-zero quantization region is given by:

$$\begin{aligned}\mu_{G_l^{(W)}} &= \frac{\displaystyle\int_{\frac{\Delta_{G_l^{(W)}}}{2}}^{\frac{3\Delta_{G_l^{(W)}}}{2}} x \exp\left(-\frac{x^2}{2\sigma^2_{G_l^{(W)}}}\right) dx}{\left(Q\left(\frac{\Delta_{G_l^{(W)}}}{2\sigma_{G_l^{(W)}}}\right) - Q\left(\frac{3\Delta_{G_l^{(W)}}}{2\sigma_{G_l^{(W)}}}\right)\right)\sqrt{2\pi\sigma^2_{G_l^{(W)}}}} \\ &= \frac{\sigma_{G_l^{(W)}}\left(\exp\left(-\frac{\Delta^2_{G_l^{(W)}}}{8\sigma^2_{G_l^{(W)}}}\right) - \exp\left(-\frac{9\Delta^2_{G_l^{(W)}}}{8\sigma^2_{G_l^{(W)}}}\right)\right)}{\left(Q\left(\frac{\Delta_{G_l^{(W)}}}{2\sigma_{G_l^{(W)}}}\right) - Q\left(\frac{3\Delta_{G_l^{(W)}}}{2\sigma_{G_l^{(W)}}}\right)\right)\sqrt{2\pi}},\end{aligned}$$

where $\sigma_{G_l^{(W)}}$ is the standard deviation of $G_l^{(W)}$. By substituting $\Delta_{G_l^{(W)}} = \frac{\sigma_{G_l^{(W)}}}{4}$ into the above expression of $\mu_{G_l^{(W)}}$ and plugging in the definition of relative quantization bias, we obtain:

$$\eta_{G_l^{(W)}} = \frac{\left|\Delta_{G_l^{(W)}} - \mu_{G_l^{(W)}}\right|}{\mu_{G_l^{(W)}}} = 0.4\% < 1\%.$$

Hence, this choice of the quantization step satisfies the RQB. In order to ensure the RQB holds throughout training, $\sigma^{(\min)}_{G_l^{(W)}}$ is used in Lemma 3. This completes the proof. □

Lemma 4. *The BQN criterion holds provided the activation gradient quantization step size is upper bounded as follows:*

$$\Delta_{G_{l+1}^{(A)}} < \frac{\Delta_{G_l^{(W)}}}{\sqrt{\lambda^{(\max)}_{G_{l+1}^{(A)} \to G_l^{(W)}}}} \left(\frac{\left|G_l^{(W)}\right|}{\left|G_{l+1}^{(A)}\right|} \right)^{1/4} \qquad \textit{for } l = 1 \dots L$$

where $\lambda^{(\max)}_{G_{l+1}^{(A)} \to G_l^{(W)}}$, the largest singular value of the square-Jacobian (Jacobian matrix with squared entries) of $G_l^{(W)}$ with respect to $G_{l+1}^{(A)}$.

Proof. Let us unroll $G_l^{(W)}$ and $G_{l+1}^{(A)}$ to vectors of size $\left|G_l^{(W)}\right|$ and $\left|G_{l+1}^{(A)}\right|$, respectively. The element-wise quantization noise variance of each weight gradient is $\frac{\Delta^2_{G_l^{(W)}}}{12}$. Therefore we have:

$$V_{G^{(W)} \to \Sigma_l} = \left|G_l^{(W)}\right| \frac{\Delta^2_{G_l^{(W)}}}{12}.$$

The reflected quantization noise variance from an activation gradient $g_a \in G_{l+1}^{(A)}$ onto a weight gradient $g_w \in G_l^{(W)}$ is

$$\left|\frac{\partial g_w}{\partial g_a}\right|^2 \frac{\Delta^2_{G_{l+1}^{(A)}}}{12},$$

where cross products of quantization noise are neglected (Sakr et al., 2017). Hence, the reflected quantization noise variance element-wise from $G_{l+1}^{(A)}$ onto $G_l^{(W)}$ is given by:

$$\frac{\Delta^2_{G_{l+1}^{(A)}}}{12} J_{G_{l+1}^{(A)} \to G_l^{(W)}} \mathbf{1}_{\left|G_{l+1}^{(A)}\right|},$$

where $J_{G_{l+1}^{(A)} \to G_l^{(W)}}$ is the square-Jacobian of $G_l^{(W)}$ with respect to $G_{l+1}^{(A)}$ and $\mathbf{1}$ denotes the all one vector with size denoted by its subscript. Hence, we have:

$$\begin{aligned}
V_{G_{l+1}^{(A)} \to \Sigma_l} &= \frac{\Delta^2_{G_{l+1}^{(A)}}}{12} \left(J_{G_{l+1}^{(A)} \to G_l^{(W)}} \mathbf{1}_{\left|G_{l+1}^{(A)}\right|} \right)^T \mathbf{1}_{\left|G_l^{(W)}\right|} \\
&\leq \frac{\Delta^2_{G_l^{(A)}}}{12} \left\| J_{G_{l+1}^{(A)} \to G_l^{(W)}} \mathbf{1}_{\left|G_{l+1}^{(A)}\right|} \right\| \left\| \mathbf{1}_{\left|G_l^{(W)}\right|} \right\| \\
&\leq \sqrt{\left|G_l^{(W)}\right|} \frac{\Delta^2_{G_{l+1}^{(A)}}}{12} \left\| J_{G_{l+1}^{(A)} \to G_l^{(W)}} \right\| \left\| \mathbf{1}_{\left|G_{l+1}^{(A)}\right|} \right\| \\
&\leq \lambda^{(\max)}_{G_{l+1}^{(A)} \to G_l^{(W)}} \sqrt{\left|G_{l+1}^{(A)}\right| \left|G_l^{(W)}\right|} \frac{\Delta^2_{G_{l+1}^{(A)}}}{12},
\end{aligned}$$

where we used the Cauchy-Schwarz inequality and the spectral norm of a matrix. Next we set this upper bound on $V_{G_{l+1}^{(A)} \to \Sigma_l}$ to be less than the value of $V_{G_l^{(W)} \to \Sigma_l}$ determined above. This condition, by definition, is enough to satisfy the BQN criterion. Rearranging terms yields Lemma 4 which completes the proof.

In the main text, it was menitoned that each entry in the Jacobian matrix above is already computed by the back-propagation algorithm. We now explain how. Let us denote the instantaneous loss function being minimized by ξ. Note that each entry of $J_{G_{l+1}^{(A)} \to G_l^{(W)}}$ is of the form $\left|\frac{\partial g_w}{\partial g_a^{(0)}}\right|^2$ where $g_w = \frac{\partial \xi}{\partial w}$

with $w \in W_l$ and $g_a^{(0)} = \frac{\partial \xi}{\partial a^{(0)}}$ with $a^{(0)} \in A_{l+1}$. The back-propagation algorithm computes g_w using the chain rule as follows:

$$g_w = \frac{\partial \xi}{\partial w} = \sum_{a^{(i)} \in A_{l+1}} \frac{\partial \xi}{\partial a^{(i)}} \frac{\partial a^{(i)}}{\partial w}.$$

In particular, note that $g_a^{(0)}$ appears only once in the summation above and is multiplied by $\frac{\partial a^{(0)}}{\partial w}$. Thus $\frac{\partial g_w}{\partial g_a^{(0)}} = \frac{\partial a^{(0)}}{\partial w}$. This establishes that each entry of the Jacobian matrix is already computed via the back-propagation algorithm. □

Lemma 5. *The AS criterion holds provided the accumulator PDR and quantization step size satisfy:*

$$r_{W_l^{(acc)}} \geq 2^{-B_{W_l}} \quad \& \quad \Delta_{W_l^{(acc)}} < \gamma^{(\min)} \Delta_{G_l^{(W)}} \quad \textit{for } l = 1 \ldots L$$

where $\gamma^{(\min)}$ is the smallest value of the learning rate used during training.

Proof. The lower bound on the PDR of the weight accumulator, given by

$$r_{W_l^{(acc)}} \geq 2^{-B_{W_l}}$$

for $l = 1 \ldots L$, ensures that updates are able to cross over the feedforward weight quantization threshold so that it can be updated. Additionally, the lower bound on the quantization step size, given by

$$\Delta_{W_l^{(acc)}} < \gamma^{(\min)} \Delta_{G_l^{(W)}}$$

for $l = 1 \ldots L$, simply ensures that the internal weight accumulator overlaps with the least significant part of the representation of the weight gradient multiplied by the learning rate. Thus, the quantization noise of the internal accumulator is zero, or equivalently,

$$V_{W_l^{(acc)} \to \Sigma_l^{(acc)}} = 0 \quad \text{for } l = 1 \ldots L$$

which, by definition, is enough for the AS criterion to hold. Note that this criterion applies to the Vanilla-SGD learning rule (which was used in our experiments). Future work includes extending this criterion to other learning rules such as momentum and ADAM. □

C Illustration of Methodology Usage

We illustrate a step by step description of the application of our precision assignment methodology to the four networks we report results on.

C.1 CIFAR-10 ConvNet

Feedforward Precisions: The first step in our methodology consists of setting the feedforward precisions B_{W_l} and B_{A_l}. As per Claim 1, this requires using (1). To do so, it is first needed to compute the quantization noise gains using (6). Using the converged weights from the baseline run we obtain:

Layer Index l	1	2	3	4	5
$E_{W_l \to p_m}$	1.52E+06	1.24E+06	4.21E+06	3.57E+06	2.35E+06
$E_{A_l \to p_m}$	5.51E+04	3.27E+02	5.15E+02	6.60E+02	7.78E+02
Layer Index l	6	7	8	9	
$E_{W_l \to p_m}$	5.61E+05	5.97E+04	3.23E+04	8.66E+03	
$E_{A_l \to p_m}$	7.49E+02	6.32E+02	2.37E+02	9.47E+01	

And therefore, $E_{(\min)} = 94.7$ and the feedforward precisions should be set according to (1) as follows:

Layer Index l	1	2	3	4	5
B_{W_l}	7+$B^{(\min)}$	7+$B^{(\min)}$	8+$B^{(\min)}$	8+$B^{(\min)}$	7+$B^{(\min)}$
B_{A_l}	5+$B^{(\min)}$	1+$B^{(\min)}$	1+$B^{(\min)}$	1+$B^{(\min)}$	2+$B^{(\min)}$
Layer Index l	6	7	8	9	
B_{W_l}	6+$B^{(\min)}$	5+$B^{(\min)}$	4+$B^{(\min)}$	3+$B^{(\min)}$	
B_{A_l}	1+$B^{(\min)}$	1+$B^{(\min)}$	1+$B^{(\min)}$	0+$B^{(\min)}$	

The value of $B^{(\min)}$ is swept and p_m i evaluated on the validation set. It is found that the smallest value of $B^{(\min)}$ resulting in $p_m < 1\%$ is equal to 4 bits. Hence the feedforward precisions are set as follows and as illustrated in Figure 2:

Layer Index l	1	2	3	4	5	6	7	8	9
B_{W_l}	11	11	12	12	11	10	9	8	7
B_{A_l}	9	5	5	5	6	5	5	5	4

Gradient Precisions: The second step of the methodology is to determine the precisions of weight $B_{G_l^{(W)}}$ and activation $B_{G_{l+1}^{(A)}}$ gradients. As per Claim 1, an important statistic is the spatial variance of the gradient tensors. We estimate these variances via moving window averages, where at each iteration, the running variance estimate $\hat{\sigma}^2$ is updated using the instantaneous variance $\tilde{\sigma}^2$ as follows:

$$\hat{\sigma}^2 \leftarrow (1-\theta)\hat{\sigma}^2 + \theta\tilde{\sigma}^2$$

where θ is the running average factor, chosen to be 0.1. The running variance estimate of each gradient tensor is dumped every epoch. Using the maximum recorded estimate and (2) we compute the PDRs of the gradient tensors (as a reminder, the PDR is forced to be a power of 2):

Layer Index l	1	2	3	4	5
$r_{G_l^{(W)}}$	5.00E-01	1.25E-01	1.25E-01	1.25E-01	6.25E-02
$r_{G_{l+1}^{(A)}}$	4.88E-04	9.77E-04	9.77E-04	1.95E-03	7.81E-03
Layer Index l	6	7	8	9	
$r_{G_l^{(W)}}$	3.13E-02	3.13E-02	1.56E-02	1.25E-01	
$r_{G_{l+1}^{(A)}}$	1.56E-02	7.81E-03	7.81E-03	3.13E-02	

Furthermore, using the minimum recorded estimates of the weight gradient spatial variances and (3) we compute the values of the quantization step sizes of the weight tensors:

Layer Index l	1	2	3	4	5
$\Delta_{G_l^{(W)}}$	3.91E-03	1.95E-03	9.77E-04	9.77E-04	4.88E-04
Layer Index l	6	7	8	9	
$\Delta_{G_l^{(W)}}$	2.44E-04	2.44E-04	1.22E-04	4.88E-04	

Hence the weight gradients precisions $B_{G_l^{(W)}}$ are set as follows and as illustrated in Figure 2:

Layer Index l	1	2	3	4	5	6	7	8	9
$B_{G_l^{(W)}}$	9	9	9	9	9	9	9	9	10

In order to compute the activation gradients precisions, (3) dictates that we need the values of largest singular values of the of the square-Jacobians of $G_l^{(W)}$ with respect to $G_{l+1}^{(A)}$ for $l = 1 \ldots L$. The square Jacobians matrices are estimated in a moving window fashion as for the variances above. However, instead of updating a matrix every iteration, the updates are done every first batch of every epoch. The following are the maximum recorded singluar values:

Layer Index l	1	2	3	4	5
$\lambda^{(\max)}_{G_{l+1}^{(A)} \rightarrow G_l^{(W)}}$	1.44E+02	2.37E+02	4.28E+02	2.03E+02	4.20E+01
Layer Index l	6	7	8	9	
$\lambda^{(\max)}_{G_{l+1}^{(A)} \rightarrow G_l^{(W)}}$	9.08E+00	1.37E+01	1.26E+01	3.51E+00	

Using the above values and (3) we obtain the values of the quantization step sizes for the activation gradients:

Layer Index l	1	2	3	4	5
$\Delta_{G_{l+1}^{(A)}}$	6.10E-05	3.05E-05	7.63E-06	1.53E-05	1.53E-05
Layer Index l	6	7	8	9	
$\Delta_{G_{l+1}^{(A)}}$	1.53E-05	1.53E-05	7.63E-06	6.10E-05	

Hence the activation gradients precisions $B_{G_{l+1}^{(A)}}$ are set as follows and as illustrated in Figure 2:

Layer Index l	1	2	3	4	5	6	7	8	9
$B_{G_{l+1}^{(A)}}$	5	8	9	9	11	12	11	11	11

Internal Weight Accumulators Precisions: By application of (4), we use the above results to obtain the internal weight accumulator precisions. The only additional information needed is the value of the smallest learning rate value used in the training, which in our case is 0.0001. We obtain the following precisions which are illustrated in Figure 2

Layer Index l	1	2	3	4	5	6	7	8	9
$B_{W_l^{(Acc)}}$	13	15	14	14	16	18	19	21	20

C.2 SVHN ConvNet

Feedforward Precisions: The quantization noise gains are used to obtain values for the precisions as a function of $B^{(\min)}$ as summarized below:

Layer Index l	1	2	3	4	5
$E_{W_l \to p_m}$	3.07E+03	4.50E+02	1.54E+03	1.79E+03	6.01E+03
B_{W_l}	6+$B^{(\min)}$	5+$B^{(\min)}$	6+$B^{(\min)}$	6+$B^{(\min)}$	7+$B^{(\min)}$
$E_{A_l \to p_m}$	7.58E+02	2.86E+00	7.09E+00	2.55E+00	8.33E+00
B_{A_l}	5+$B^{(\min)}$	1+$B^{(\min)}$	2+$B^{(\min)}$	1+$B^{(\min)}$	2+$B^{(\min)}$
Layer Index l	6	7	8	9	
$E_{W_l \to p_m}$	1.25E+03	7.91E+01	1.20E+01	9.13E+00	
B_{W_l}	6+$B^{(\min)}$	4+$B^{(\min)}$	2+$B^{(\min)}$	2+$B^{(\min)}$	
$E_{A_l \to p_m}$	8.18E+00	1.78E+01	1.14E+00	3.90E-01	
B_{A_l}	2+$B^{(\min)}$	3+$B^{(\min)}$	1+$B^{(\min)}$	0+$B^{(\min)}$	

The value of $B^{(\min)}$ is again swept, and it is found that the $p_m < 1\%$ for $B^{(\min)} = 3$. The feedforward precisions are therefore set as follows and as illustrated in Figure 2:

Layer Index l	1	2	3	4	5	6	7	8	9
B_{W_l}	9	8	9	9	10	9	7	5	5
B_{A_l}	8	4	5	4	6	6	7	4	3

Gradient Precisions: The spatial variance of the gradient tensors is used to determine the PDRs and the quantization step sizes of weight gradients. The singular values of the square-Jacobians are needed to determine the quantization step sizes of activation gradients. They were computed as follows:

Layer Index l	1	2	3	4	5
$r_{G_l^{(W)}}$	6.25E-02	1.56E-02	1.56E-02	1.56E-02	1.56E-02
$\Delta_{G_l^{(W)}}$	2.44E-04	6.10E-05	6.10E-05	6.10E-05	6.10E-05
$r_{G_{l+1}^{(A)}}$	4.88E-04	4.88E-04	9.77E-04	1.95E-03	3.91E-03
$\lambda^{(\max)}_{G_{l+1}^{(A)} \to G_l^{(W)}}$	5.13E+00	1.48E+02	3.25E+02	1.37E+02	8.84E+01
$\Delta_{G_{l+1}^{(A)}}$	3.05E-05	9.54E-07	9.54E-07	9.54E-07	1.91E-06
Layer Index l	6	7	8	9	
$r_{G_l^{(W)}}$	7.81E-03	3.91E-03	3.91E-03	1.56E-02	
$\Delta_{G_l^{(W)}}$	3.05E-05	1.53E-05	7.63E-06	6.10E-05	
$r_{G_{l+1}^{(A)}}$	1.56E-02	3.91E-03	3.91E-03	3.13E-02	
$\lambda^{(\max)}_{G_{l+1}^{(A)} \to G_l^{(W)}}$	2.20E+01	9.58E+00	1.78E+00	1.71E+00	
$\Delta_{G_{l+1}^{(A)}}$	1.91E-06	9.54E-07	9.54E-07	7.63E-06	

Hence the gradients precisions are set as follows and as illustrated in Figure 2:

Layer Index l	1	2	3	4	5	6	7	8	9
$B_{G_l^{(W)}}$	9	9	9	9	9	9	9	10	9
$B_{G_{l+1}^{(A)}}$	5	10	11	12	12	14	13	13	13

Internal Weight Accumulators Precisions: The smallest learning rate value for this network is 0.001 which results in the following precisions for the internal weight accumulators as illustrated in Figure 2:

Layer Index l	1	2	3	4	5	6	7	8	9
$B_{W_l^{(Acc)}}$	14	17	16	16	15	17	20	23	20

C.3 CIFAR-10 RESNET

Feedforward Precisions: The quantization noise gains are used to obtain values for the precisions as a function of $B^{(\min)}$ as summarized below:

Layer Index l	1	2	3	4	5	6
$E_{W_l \to p_m}$	2.41E+03	9.80E+02	1.22E+03	1.62E+03	1.52E+03	3.05E+03
B_{W_l}	11+$B^{(\min)}$	10+$B^{(\min)}$	10+$B^{(\min)}$	10+$B^{(\min)}$	10+$B^{(\min)}$	11+$B^{(\min)}$
$E_{A_l \to p_m}$	7.32E-01	5.15E-01	1.29E-01	1.12E-01	7.31E-02	8.98E-02
B_{A_l}	5+$B^{(\min)}$	5+$B^{(\min)}$	4+$B^{(\min)}$	4+$B^{(\min)}$	3+$B^{(\min)}$	3+$B^{(\min)}$
Layer Index l	7	8	9	10	11	12
$E_{W_l \to p_m}$	1.47E+03	2.15E+03	2.74E+03	4.96E+03	4.23E+03	4.20E+03
B_{W_l}	10+$B^{(\min)}$	11+$B^{(\min)}$	11+$B^{(\min)}$	11+$B^{(\min)}$	11+$B^{(\min)}$	12+$B^{(\min)}$
$E_{A_l \to p_m}$	7.70E-02	8.39E-02	6.38E-02	1.92E-01	1.54E-01	1.33E-01
B_{A_l}	3+$B^{(\min)}$	3+$B^{(\min)}$	3+$B^{(\min)}$	4+$B^{(\min)}$	4+$B^{(\min)}$	4+$B^{(\min)}$
Layer Index l	13	14	15	16	17	18
$E_{W_l \to p_m}$	7.25E+03	2.99E+03	2.86E+03	3.00E+03	5.02E+03	4.34E+03
B_{W_l}	11+$B^{(\min)}$	11+$B^{(\min)}$	11+$B^{(\min)}$	11+$B^{(\min)}$	10+$B^{(\min)}$	10+$B^{(\min)}$
$E_{A_l \to p_m}$	1.13E-01	8.51E-02	6.57E-02	1.29E-01	6.51E-02	2.16E-02
B_{A_l}	4+$B^{(\min)}$	3+$B^{(\min)}$	3+$B^{(\min)}$	4+$B^{(\min)}$	3+$B^{(\min)}$	2+$B^{(\min)}$
Layer Index l	19	20	21	22		
$E_{W_l \to p_m}$	1.41E+03	1.30E+03	1.08E+02	8.31E+00		
B_{W_l}	9+$B^{(\min)}$	7+$B^{(\min)}$	11+$B^{(\min)}$	11+$B^{(\min)}$		
$E_{A_l \to p_m}$	4.80E-03	7.82E-04				
B_{A_l}	1+$B^{(\min)}$	0+$B^{(\min)}$				

Note that for weights, layer depths 21 and 22 correspond to the strided convolutions in the shortcut connections of residual blocks 4 and 7, respectively. The value of $B^{(\min)}$ is again swept, and it is found that the $p_m < 1\%$ for $B^{(\min)} = 3$. The feedforward precisions are therefore set as follows and as illustrated in Figure 2:

Layer Index l	1	2	3	4	5	6	7	8	9	10	11
B_{W_l}	14	13	13	13	13	14	13	14	14	14	14
B_{A_l}	8	8	7	7	6	6	6	6	6	7	7
Layer Index l	12	13	14	15	16	17	18	19	20	21	22
B_{W_l}	15	14	14	14	14	13	13	12	10	14	14
B_{A_l}	7	7	6	6	7	6	5	4	3		

Gradient Precisions: The spatial variance of the gradient tensors is used to determine the PDRs and the quantization step sizes of weight gradients. The singular values of the square-Jacobians are needed to determine the quantization step sizes of activation gradients. They were computed as follows:

Layer Index l	1	2	3	4	5	6
$r_{G_l^{(W)}}$	2.50E-01	6.25E-02	6.25E-02	3.13E-02	3.13E-02	3.13E-02
$\Delta_{G_l^{(W)}}$	2.44E-04	3.05E-05	3.05E-05	3.05E-05	3.05E-05	3.05E-05
$r_{G_{l+1}^{(A)}}$	4.88E-04	2.44E-04	2.44E-04	2.44E-04	2.44E-04	2.44E-04
$\lambda^{(\max)}_{G_{l+1}^{(A)} \rightarrow G_l^{(W)}}$	8.07E+02	2.84E+03	2.84E+03	5.43E+03	5.43E+03	4.94E+03
$\Delta_{G_{l+1}^{(A)}}$	7.63E-06	4.77E-07	4.77E-07	2.38E-07	2.38E-07	2.38E-07
Layer Index l	7	8	9	10	11	12
$r_{G_l^{(W)}}$	3.13E-02	3.13E-02	3.13E-02	3.13E-02	3.13E-02	3.13E-02
$\Delta_{G_l^{(W)}}$	3.05E-05	3.05E-05	3.05E-05	3.05E-05	3.05E-05	3.05E-05
$r_{G_{l+1}^{(A)}}$	2.44E-04	2.44E-04	4.88E-04	4.88E-04	2.44E-04	2.44E-04
$\lambda^{(\max)}_{G_{l+1}^{(A)} \rightarrow G_l^{(W)}}$	4.94E+03	1.22E+03	1.22E+03	1.08E+03	1.08E+03	8.07E+02
$\Delta_{G_{l+1}^{(A)}}$	2.38E-07	4.77E-07	4.77E-07	4.77E-07	4.77E-07	9.54E-07
Layer Index l	13	14	15	16	17	18
$r_{G_l^{(W)}}$	3.13E-02	3.13E-02	1.56E-02	1.56E-02	1.56E-02	1.56E-02
$\Delta_{G_l^{(W)}}$	3.05E-05	3.05E-05	1.53E-05	1.53E-05	1.53E-05	1.53E-05
$r_{G_{l+1}^{(A)}}$	2.44E-04	4.88E-04	4.88E-04	4.88E-04	2.44E-04	2.44E-04
$\lambda^{(\max)}_{G_{l+1}^{(A)} \rightarrow G_l^{(W)}}$	8.07E+02	1.93E+02	1.93E+02	2.98E+02	2.98E+02	3.01E+02
$\Delta_{G_{l+1}^{(A)}}$	9.54E-07	9.54E-07	9.54E-07	4.77E-07	2.38E-07	2.38E-07
Layer Index l	19	20	21	22		
$r_{G_l^{(W)}}$	1.56E-02	1.56E-02	1.56E-02	2.50E-01		
$\Delta_{G_l^{(W)}}$	7.63E-06	7.63E-06	1.91E-06	3.05E-05		
$r_{G_{l+1}^{(A)}}$	2.44E-04	6.25E-02				
$\lambda^{(\max)}_{G_{l+1}^{(A)} \rightarrow G_l^{(W)}}$	3.01E+02	2.32E+01				
$\Delta_{G_{l+1}^{(A)}}$	5.96E-08	3.81E-06				

Hence the gradients precisions are set as follows and as illustrated in Figure 2:

Layer Index l	1	2	3	4	5	6	7	8	9	10	11
$B_{G_l^{(W)}}$	11	12	12	11	11	11	11	11	11	11	11
$B_{G_{l+1}^{(A)}}$	7	10	10	11	11	11	11	10	11	11	10
Layer Index l	12	13	14	15	16	17	18	19	20	21	22
$B_{G_l^{(W)}}$	11	11	11	11	11	11	11	12	12	14	14
$B_{G_{l+1}^{(A)}}$	9	9	10	10	11	11	11	13	15		

Internal Weight Accumulators Precisions: The smallest learning rate value for this network is 0.001 which results in the following precisions for the internal weight accumulators as illustrated in Figure 2:

Layer Index l	1	2	3	4	5	6	7	8	9	10	11
$B_{W_l^{(Acc)}}$	9	13	13	13	13	12	13	12	12	12	12
Layer Index l	12	13	14	15	16	17	18	19	20	21	22
$B_{W_l^{(Acc)}}$	11	12	13	13	13	15	15	18	16	12	13

C.4 CIFAR-100 RESNET

Feedforward Precisions: The quantization noise gains are used to obtain values for the precisions as a function of $B^{(\min)}$ as summarized below:

Layer Index l	1	2	3	4	5	6
$E_{W_l \to p_m}$	2.32E+03	8.23E+02	1.18E+03	1.28E+03	1.70E+03	2.78E+03
B_{W_l}	10+$B^{(\min)}$	9+$B^{(\min)}$	10+$B^{(\min)}$	10+$B^{(\min)}$	10+$B^{(\min)}$	10+$B^{(\min)}$
$E_{A_l \to p_m}$	1.42E+00	7.84E-01	2.52E-01	1.46E-01	7.68E-02	7.40E-02
B_{A_l}	5+$B^{(\min)}$	4+$B^{(\min)}$	4+$B^{(\min)}$	3+$B^{(\min)}$	3+$B^{(\min)}$	3+$B^{(\min)}$
Layer Index l	7	8	9	10	11	12
$E_{W_l \to p_m}$	3.03E+03	5.80E+03	7.29E+03	9.20E+03	9.81E+03	1.41E+04
B_{W_l}	10+$B^{(\min)}$	11+$B^{(\min)}$	11+$B^{(\min)}$	11+$B^{(\min)}$	11+$B^{(\min)}$	11+$B^{(\min)}$
$E_{A_l \to p_m}$	7.52E-02	8.70E-02	1.38E-01	2.49E-01	2.11E-01	1.51E-01
B_{A_l}	3+$B^{(\min)}$	3+$B^{(\min)}$	3+$B^{(\min)}$	4+$B^{(\min)}$	3+$B^{(\min)}$	3+$B^{(\min)}$
Layer Index l	13	14	15	16	17	18
$E_{W_l \to p_m}$	7.67E+03	1.40E+04	1.13E+04	1.09E+04	5.35E+03	3.97E+03
B_{W_l}	11+$B^{(\min)}$	11+$B^{(\min)}$	11+$B^{(\min)}$	11+$B^{(\min)}$	11+$B^{(\min)}$	11+$B^{(\min)}$
$E_{A_l \to p_m}$	1.54E-01	1.09E-01	1.93E-01	2.36E-01	1.27E-01	3.01E-02
B_{A_l}	3+$B^{(\min)}$	3+$B^{(\min)}$	3+$B^{(\min)}$	4+$B^{(\min)}$	3+$B^{(\min)}$	2+$B^{(\min)}$
Layer Index l	19	20	21	22		
$E_{W_l \to p_m}$	8.35E+02	2.30E+01	6.78E+03	6.03E+03		
B_{W_l}	9+$B^{(\min)}$	7+$B^{(\min)}$	11+$B^{(\min)}$	11+$B^{(\min)}$		
$E_{A_l \to p_m}$	2.01E-02	1.80E-03				
B_{A_l}	2+$B^{(\min)}$	0+$B^{(\min)}$				

The value of $B^{(\min)}$ is again swept, and it is found that the $p_m < 1\%$ for $B^{(\min)} = 3$. The feedforward precisions are therefore set as follows and as illustrated in Figure 2:

Layer Index l	1	2	3	4	5	6	7	8	9	10	11
B_{W_l}	13	12	13	13	13	13	13	14	14	14	14
B_{A_l}	8	7	7	6	6	6	6	6	6	7	6
Layer Index l	12	13	14	15	16	17	18	19	20	21	22
B_{W_l}	14	14	14	14	14	14	14	12	10	14	14
B_{A_l}	6	6	6	6	7	6	5	5	3		

Gradient Precisions: The spatial variance of the gradient tensors is used to determine the PDRs and the quantization step sizes of weight gradients. The singular values of the square-Jacobians are needed to determine the quantization step sizes of activation gradients. They were computed as follows:

Layer Index l	1	2	3	4	5	6
$r_{G_l^{(W)}}$	5.00E-01	6.25E-02	6.25E-02	3.13E-02	6.25E-02	3.13E-02
$\Delta_{G_l^{(W)}}$	6.10E-05	1.53E-05	1.53E-05	1.53E-05	1.53E-05	1.53E-05
$r_{G_{l+1}^{(A)}}$	2.44E-04	1.22E-04	6.10E-05	6.10E-05	6.10E-05	6.10E-05
$\lambda^{(\max)}_{G_{l+1}^{(A)} \rightarrow G_l^{(W)}}$	6.46E+02	1.86E+03	1.86E+03	3.54E+03	3.54E+03	5.11E+03
$\Delta_{G_{l+1}^{(A)}}$	9.54E-07	1.19E-07	1.19E-07	1.19E-07	1.19E-07	5.96E-08
Layer Index l	7	8	9	10	11	12
$r_{G_l^{(W)}}$	3.13E-02	3.13E-02	3.13E-02	3.13E-02	3.13E-02	3.13E-02
$\Delta_{G_l^{(W)}}$	1.53E-05	1.53E-05	1.53E-05	1.53E-05	1.53E-05	1.53E-05
$r_{G_{l+1}^{(A)}}$	6.10E-05	1.22E-04	1.22E-04	1.22E-04	1.22E-04	1.22E-04
$\lambda^{(\max)}_{G_{l+1}^{(A)} \rightarrow G_l^{(W)}}$	5.11E+03	1.05E+03	1.05E+03	8.23E+02	8.23E+02	6.37E+02
$\Delta_{G_{l+1}^{(A)}}$	5.96E-08	1.19E-07	1.19E-07	2.38E-07	2.38E-07	2.38E-07
Layer Index l	13	14	15	16	17	18
$r_{G_l^{(W)}}$	3.13E-02	3.13E-02	1.56E-02	3.13E-02	1.56E-02	1.56E-02
$\Delta_{G_l^{(W)}}$	1.53E-05	7.63E-06	7.63E-06	7.63E-06	7.63E-06	7.63E-06
$r_{G_{l+1}^{(A)}}$	1.22E-04	1.22E-04	2.44E-04	1.22E-04	6.10E-05	6.10E-05
$\lambda^{(\max)}_{G_{l+1}^{(A)} \rightarrow G_l^{(W)}}$	6.37E+02	2.31E+02	2.31E+02	2.79E+02	2.79E+02	2.80E+02
$\Delta_{G_{l+1}^{(A)}}$	2.38E-07	2.38E-07	2.38E-07	1.19E-07	1.19E-07	1.19E-07
Layer Index l	19	20	21	22		
$r_{G_l^{(W)}}$	1.56E-02	6.25E-02	3.13E-02	1.56E-02		
$\Delta_{G_l^{(W)}}$	3.81E-06	7.63E-06	1.53E-05	7.63E-06		
$r_{G_{l+1}^{(A)}}$	6.10E-05	7.81E-03				
$\lambda^{(\max)}_{G_{l+1}^{(A)} \rightarrow G_l^{(W)}}$	2.80E+02	7.81E+01				
$\Delta_{G_{l+1}^{(A)}}$	5.96E-08	2.38E-07				

Hence the gradients precisions are set as follows and as illustrated in Figure 2:

Layer Index l	1	2	3	4	5	6	7	8	9	10	11
$B_{G_l^{(W)}}$	14	13	13	12	13	12	12	12	12	12	12
$B_{G_{l+1}^{(A)}}$	9	11	10	10	10	11	11	11	11	10	10
Layer Index l	12	13	14	15	16	17	18	19	20	21	22
$B_{G_l^{(W)}}$	12	12	13	12	13	12	12	13	14	12	12
$B_{G_{l+1}^{(A)}}$	10	10	10	11	11	10	10	11	16		

Internal Weight Accumulators Precisions: The smallest learning rate value for this network is 0.001 which results in the following precisions for the internal weight accumulators as illustrated in Figure 2:

Layer Index l	1	2	3	4	5	6	7	8	9	10	11
$B_{W_l^{(Acc)}}$	12	15	14	14	14	14	14	13	13	13	13
Layer Index l	12	13	14	15	16	17	18	19	20	21	22
$B_{W_l^{(Acc)}}$	13	13	14	14	14	14	14	17	18	13	14