FEATURE INCAY FOR REPRESENTATION REGULARIZATION

Anonymous authors
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ABSTRACT

Softmax-based loss is widely used in deep learning for multi-class classification, where each class is represented by a weight vector and each sample is represented as a feature vector. Different from traditional learning algorithms where features are pre-defined and only weight vectors are tunable through training, feature vectors are also tunable as representation learning in deep learning. Thus we investigate how to improve the classification performance by better adjusting the features. One main observation is that elongating the feature norm of both correctly-classified and mis-classified feature vectors improves learning: (1) increasing the feature norm of correctly-classified examples induce smaller training loss; (2) increasing the feature norm of mis-classified examples can upweight the contribution from hard examples. Accordingly, we propose feature incay to regularize representation learning by encouraging larger feature norm. In contrast to weight decay which shrinks the weight norm, feature incay is proposed to stretch the feature norm. Extensive empirical results on MNIST, CIFAR10, CIFAR100 and LFW demonstrate the effectiveness of feature incay.

1 INTRODUCTION

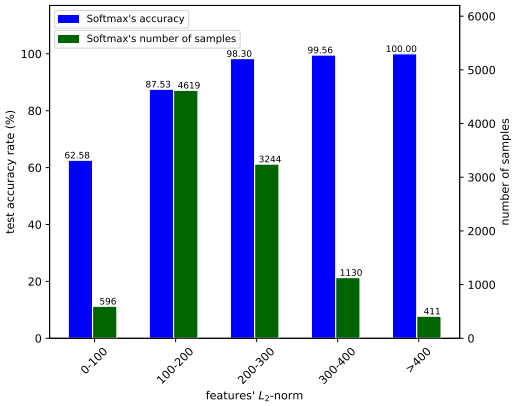


Figure 1: Test accuracy vs Features' L_2-norm and Number of samples vs Features' L_2-norm on CIFAR10, the test model is trained with Softmax loss. We divide the range of the feature's L_2-norm with stepsize 100. e.g., the test accuracy is 62.58% for samples with feature norm of range [0, 100]. When the feature norm exceeds 400, the test accuracy reaches 100%.

Deep Neural Networks (DNNs) with softmax-based loss have achieved state-of-the-art performance on numerous multi-class classification related tasks. In DNNs, both representations and classifiers are learned within a unified network concurrently, where the final representation for a sample is the feature vector $\mathbf{f}$ outputted from the penultimate layer, while the last layer outputs scores $z_i = \mathbf{w}_i \cdot \mathbf{f}$ for each category i, where $\mathbf{w}_i$ is the weight vector for category i. Before defining the loss, the scores for each category are normalized into probability via softmax function, i.e., $p_i = \frac{e^{z_i}}{\sum_j e^{z_j}}$. A well-trained DNN should output significant larger probability for the correct label than other labels, which requires the score for the correct label is significantly larger than other labels. Since $z_i = \mathbf{w}_i \cdot \mathbf{f} = \|\mathbf{w}_i\|\|\mathbf{f}\| \cos(\theta)$, where θ is the angle between $\mathbf{w}_i$ and $\mathbf{f}$, the goal of significant larger score for the correct label than other labels can be achieved by tuning $\|\mathbf{w}_i\|$, $\|\mathbf{f}\|$ and θ. While increasing the weight norm $\|\mathbf{w}_i\|$ is constrained by weight decay for regularization, thus $\|\mathbf{f}\|$ and θ become the two main factors for optimization. Although softmax loss can tune both of them, there still exist much room to improve either or both factors.

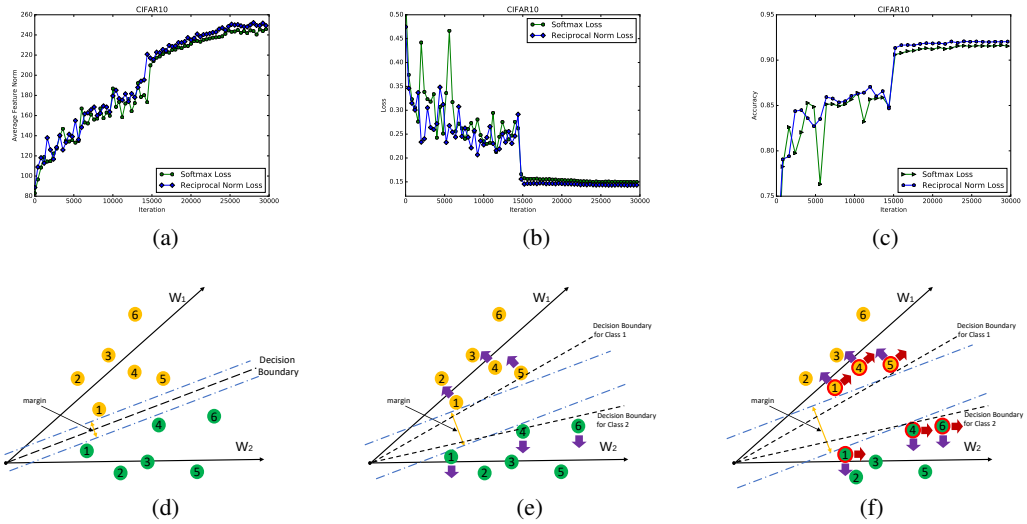


Figure 2: Comparison of Softmax loss with Softmax loss + Feature incay(i.e., Reciprocal Norm Loss, we will define it in Section 3) on test set of CIFAR10. (a) Average L_2-norm of feature vectors vs Iterations, (b) Softmax loss vs Iterations, (c) Top-1 accuracy vs iterations. Figure (d), (e) and (f) illustrate different approaches using binary classification as an example, where yellow points are samples of class1 and green points are samples of class2. The black dashed line represents the decision boundary between the two classes. The two blue dashed lines represent the hyperplanes that pass the points with minimal distances to the decision boundary. The numbers 1-6 represent the increasing L_2-norm of the points within each class. W_1 and W_2 represent the weight vectors. (d) Feature embedding of Softmax loss. (e) Feature embedding of Large-margin Softmax loss. The purple arrows represent the additional angle constraints compared with Softmax loss. (f) Large-margin Softmax loss + Feature incay. The red arrows correspond to the constraints from feature incay. The margin between class1 and class2 increases from left to right.

For example, Liu et al. (2016), Wang et al. (2017) and Liu et al. (2017a) propose different approaches to further optimize the factor of angular θ, and all of them have achieved obviously better performance. To further emphasize the factor of angular, Ranjan et al. (2017) and Liu et al. (2017c) propose to use normalized feature vectors for softmax loss where the factor of feature norm is totally ignored. In this work, we make the effort to optimize the feature norm. Firstly, we analyze the connections between the feature norm and the classification accuracy within softmax loss, they are highly correlated as illustrated in Figure 1. Features with larger norm tend to be correctly classified with higher probability. Here we propose to optimize the feature norm by augmenting the softmax loss with feature incay. In contrast to weight decay that shrinks weight vectors to be of small norm, feature incay tends to stretch out the feature vectors. From the computational perspective, larger feature norm results in larger score differences among categories, which can better separate the categories. From the perspective of pattern detection, larger feature norm encourages model to learn and detect more prominent patterns.

Figure 2(a), 2(b) and 2(c) show the results of comparison experiments by adding feature incay to softmax loss, where feature incay achieves larger feature norm, smaller loss value and higher accuracy on test set. The geometric interpretation of feature incay is illustrated in Figure 2(d), 2(e) and 2(f), we can achieve the largest inter-class separability by explicitly optimizing both the $\|\mathbf{f}\|$ and θ compared with the other methods. Besides, the proposed feature incay (implemented as Reciprocal Norm Loss) is designed to increase the feature norm adaptively according to the original feature norm, which can also help reduce the intra-class variances as illustrated in Figure 5.

In summary, we analyze the effect of feature norm and prove that: (1) increasing feature norm for correctly-classified examples induce smaller training loss; (2) increasing feature norm for misclassified examples can up-weight the contribution of hard examples; (3) the bound on feature norm to ensure the inter-class separability and intra-class compactness.

The proposed feature incay is verified on four widely used classification datasets(i.e., MNIST, CIFAR10, CIFAR100 and LFW) using various network architecture. By considering the feature incay, we achieve comparable performances on all of them.

2 RELATED WORK

Large-margin Softmax Loss. Liu et al. (2016) proposed to improve softmax loss by incorporating an adjustable margin m multiplying the angle between a feature vector and the corresponding weight vector. Compared with the softmax loss, it pays more attention to the angular decision margin between classes as illustrated in Figure 2(e). Large-margin softmax loss appends stronger constraint to the angular, while feature incay considers constraint to feature norm. As illustrated in Figure 2(f), feature incay is orthogonal to large-margin softmax loss.

Center Loss. Wen et al. (2016) presented the center loss to learn centers for deep features of each class and penalize the distances between the deep features and their corresponding class centers. The softmax loss tries to align feature vectors close to the weight vectors based on the inner product similarity, while center loss pushes feature vectors towards their class centers according Euclidean distances. Combining softmax loss with center loss actually uses two sets of classifiers, where representation is learned based on both the inner product to weight vector and the Euclidean distance to class center. The added center loss helps minimize the intra-class distances also by influencing the feature norm, namely, small feature norm will be increased and large feature norm will be decreased during the process of pushing feature vectors to class centers. Different from center loss, feature incay also increases the large feature norm instead of penalizing feature vectors with large norm as center loss.

Weight/Feature Normalization. Inspired by the fact that feature normalization before calculating the sample distances usually achieves better performance for retrieval tasks, Ranjan et al. (2017) proposed to use normalized feature vectors in softmax loss during training, thus the feature norm has no effect on softmax loss and angle is the main factor to be optimized. Congenerous cosine loss(Liu et al. (2017b)), NormFace(Wang et al. (2017)), and cosine normalization(Chunjie et al. (2017)) take a step further to normalize the weight vectors which replace inner product with cosine similarity within softmax loss, and only optimize the factor of angle. Although normalization mechanism achieves much lower intra-class angular variability by emphasizing more on the angle during training, they ignore that feature norm is another useful factor worth to optimize.

Feature Scale. COCO(Liu et al. (2017c)) and L_2-softmax(Ranjan et al. (2017)) are the most relevant to our work, and especially COCO is a concurrent work. Both of the them introduce a single scaling parameter to increase the magnitude of the features. However, they all enforce the L_2-norm of the features to be fixed for all samples. Specifically, they are optimizing the feature vectors on a hypersphere with fixed radius. Different from them, we are trying to investigate whether it is possible to optimize the original feature space instead of the "hypersphere" feature space.

3 OUR WORK

3.1 REVISITING SOFTMAX LOSS

Let $\mathbb{X} = \{(x_i, y_i)\}_{i=1}^N$ be the training set contains N samples, where x_i is the raw input to the DNN, $y_i \in \{1, 2, \cdots, K\}$ is the class label that supervises the output of the DNN. Denote $\mathbf{f}_i$ as the feature vector for x_i learned by the DNN, $\{\mathbf{w}_j\}_{j=1}^K$ represent weight vectors for the K categories. Then, softmax loss is defined as,

$$\mathcal{L}_{\text{softmax}} = -\frac{1}{N}\sum_{i=1}^{N}\log\left(\frac{e^{\mathbf{w}_{y_i}^T\mathbf{f}_i+\mathbf{b}_{y_i}}}{\sum_{j=1}^{K}e^{\mathbf{w}_j^T\mathbf{f}_i+\mathbf{b}_j}}\right), \tag{1}$$

where bias terms are ignored following the discussions in recent works Liu et al. (2016) and Wang et al. (2017). Denote the angle between $\mathbf{w}_j$ and $\mathbf{f}_i$ as $\theta_{\mathbf{w}_j,\mathbf{f}_i}$, the inner product between $\mathbf{w}_j$ and $\mathbf{f}_i$ can be rewritten as

$$\mathbf{w}_j^T\mathbf{f}_i = \|\mathbf{w}_j\|\|\mathbf{f}_i\|\cos(\theta_{\mathbf{w}_j,\mathbf{f}_i}) \tag{2}$$

By combining the above two equations, we get

$$\mathcal{L}_{\text{softmax}} = -\frac{1}{N}\sum_{i=1}^{N}\log\left(\frac{e^{\|\mathbf{w}_{y_i}\|\|\mathbf{f}_i\|\cos(\theta_{\mathbf{w}_{y_i},\mathbf{f}_i})}}{\sum_{j=1}^{K}e^{\|\mathbf{w}_j\|\|\mathbf{f}_i\|\cos(\theta_{\mathbf{w}_j,\mathbf{f}_i})}}\right) \tag{3}$$

3.2 FEATURE NORM MATTERS

Here we will illustrate how feature norm influences the softmax loss from two aspects: (1) increasing the feature norm of correctly-classified examples can induce smaller training loss; (2) increasing the feature norm of mis-classified examples can up-weight the contribution from the hard examples.

The first property is similar to the proposition proved by Wang et al. (2017), which states that softmax loss always encourages features of the correctly-classified examples to have larger magnitudes.

Property 1 [Feature Norm Matters for Correctly-classified Examples] *Suppose weight vectors and directions of the feature vectors are fixed, increasing feature norm of correctly-classified examples can further decrease the softmax loss.*

Proof. Let $\mathcal{L}_{\text{softmax}}(\mathbf{f}_i)$ represent the loss of the i-th sample, $i = 1, \cdots, N$. Specifically,

$$\begin{aligned}\mathcal{L}_{\text{softmax}}(\mathbf{f}_i) &= -\log\left(\frac{e^{\|\mathbf{w}_{y_i}\|\|\mathbf{f}_i\|\cos(\theta_{\mathbf{w}_{y_i},\mathbf{f}_i})}}{\sum_{j=1}^{K} e^{\|\mathbf{w}_j\|\|\mathbf{f}_i\|\cos(\theta_{\mathbf{w}_j,\mathbf{f}_i})}}\right) \\ &= -\log\left(\frac{1}{\sum_{j=1}^{K} e^{\|\mathbf{w}_j\|\|\mathbf{f}_i\|\cos(\theta_{\mathbf{w}_j,\mathbf{f}_i})-\|\mathbf{w}_{y_i}\|\|\mathbf{f}_i\|\cos(\theta_{\mathbf{w}_{y_i},\mathbf{f}_i})}}\right)\end{aligned} \tag{4}$$

Recall that when $\mathbf{f}_i$ is correctly classified, we have $\mathbf{w}_{y_i}^T\mathbf{f}_i > \mathbf{w}_j^T\mathbf{f}_i$ for any $j \neq y_i$, and $\|\mathbf{w}_j\|\|\mathbf{f}_i\|\cos(\theta_{\mathbf{w}_j,\mathbf{f}_i}) - \|\mathbf{w}_{y_i}\|\|\mathbf{f}_i\|\cos(\theta_{\mathbf{w}_{y_i},\mathbf{f}_i}) \leq 0$ always holds. Then, for any $t > 0$, we have

$$\mathcal{L}_{\text{softmax}}((1+t)\mathbf{f}_i) < \mathcal{L}_{\text{softmax}}(\mathbf{f}_i) \tag{5}$$

which means increasing the norm of correctly classified samples can decrease the softmax loss. To consider all samples including incorrectly classified ones, we set $t_i > 0$ if i is correctly classified and $t_i = 0$ otherwise, then we have

$$\sum_{i=1}^{N}\mathcal{L}_{\text{softmax}}((1+t_i)\mathbf{f}_i) \leq \sum_{i=1}^{N}\mathcal{L}_{\text{softmax}}(\mathbf{f}_i) \tag{6}$$

So feature norm is an important factor to achieve smaller softmax loss together with the angle. □

Though the decrease in softmax loss is marginal for some samples already with small softmax loss, the increased feature norm enlarges the margin among different categories which ensures better generalization.

Property 2 [Feature Norm Matters for Mis-classified Examples] *For a mis-classified feature vector* $\mathbf{f}_i$ *with small* L_2*-norm, the softmax loss tend to suppress it.*

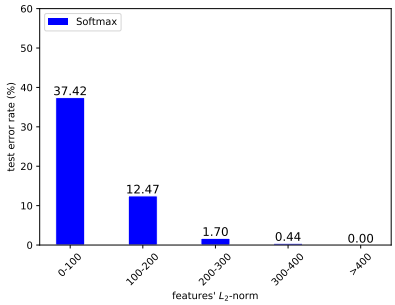


Figure 3: Histogram of error rates vs feature norm on CIFAR10 after the softmax loss converges. e.g., the first column represent the error rate is 37.42% when the feature norm is within range $[0, 100]$

Proof. According to definition of softmax loss in Eq.(3), the gradient with respect to weight vector $\mathbf{w}_j$ ($j = 1, \cdots, K$):

$$\frac{\partial\mathcal{L}_{\text{softmax}}}{\partial\mathbf{w}_j} = \frac{1}{N}\sum_{i=1}^{N}(P_j^i - h(i))\mathbf{f}_i \tag{7}$$

where the $h(i)$ is an indicator function, and $h(i) = 1$ when $\mathbf{y}_i = j$ otherwise $h(i) = 0$. When $\|\mathbf{f}_i\|$ is small, the gradient $\frac{\partial\mathcal{L}_{\text{softmax}}}{\partial\mathbf{w}_j}$ contributed by $\mathbf{f}_i$ also tend to be small. Thus the gradients contributed by the mis-classified features with small L_2-norm will be suppressed. □

According to **Property 2**, it is necessary to increase the feature norm of mis-classified examples, especially the ones with small feature norm. By optimizing the feature norm of mis-classified vectors, the errors can be fixed as illustrated in the fifth column of Table 5.

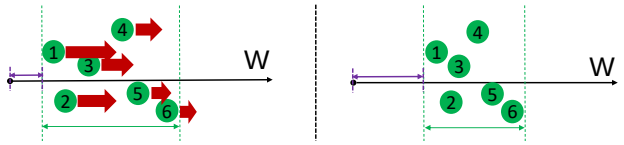


Figure 4: The original data distribution is on the left of the black dashed line and the data distribution updated according to the Reciprocal Norm Loss is on the right. The numbers 1-6 represent that the points are of increasing feature norm. The black point represents the original point. The lengths of the green bidirectional arrows represent the maximal distance in the direction of the weight vectors within all the points of one class. The purple bidirectional arrow means the minimal distance to origin, which is equal to the minimal feature norm. The red arrows represent the gradients update along the directions of the weight vectors computed with the Reciprocal Norm Loss, while the lengths represent the magnitude of the gradients.

The feature norm can be optimized by tuning the weight parameters from the previous layers, increasing the feature norm without influencing the magnitude of weights parameters from the previous layers is our target, which will be discussed in the supplementary details. The proposed Reciprocal Norm Loss will be discussed in next subsection to further explain how feature incay works.

3.3 Reciprocal Norm Loss

The superiorities of increasing feature norm have been investigated in the previous subsection. Here we explore several methods that increase the feature norm end-to-end by penalizing an additional term, such as $\|\mathbf{f}\|^2$, $\log(\|\mathbf{f}\|^2)$ and $-\frac{1}{\|\mathbf{f}\|^2}$. The comparison analysis is provided in supplementary. Specifically, we choose $-\frac{1}{\|\mathbf{f}\|^2}$ and propose the Reciprocal Norm Loss, where the definition of Reciprocal Norm Loss is,

$$\mathcal{L} = \underbrace{-\frac{1}{N}\sum_{i=1}^{N}\log\left(\frac{e^{\mathbf{w}_{y_i}^T\mathbf{f}_i}}{\sum_{j=1}^{K}e^{\mathbf{w}_j^T\mathbf{f}_i}}\right)}_{\text{softmax loss}} + \underbrace{\mu\sum_{k=1}^{K}\|\mathbf{w}_k\|^2}_{\text{weight decay}} + \underbrace{\lambda\frac{1}{N}\sum_{i=1}^{N}\frac{1}{\|\mathbf{f}_i\|^2+\epsilon}}_{\text{feature incay}} \tag{8}$$

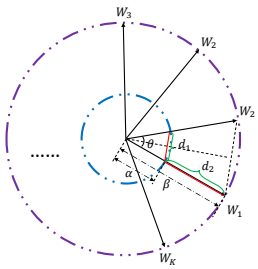


Figure 5: Illustration in 2-dimensional space.

where ϵ is a small positive value to prevent dividing by value close to zero, λ is a hyper-parameter used to control the influence of feature incay. The whole loss function consists of three parts: softmax loss, weight decay and feature incay, of which the later two items prefer small weight norm and large feature norm. Feature incay can be considered during the whole training procedure or after some training iterations with softmax loss. Large feature norm brings large inter-class separability under the constraint of small weight norm, otherwise large feature norm can be trivially achieved by increasing the weight norm. The simple reciprocal form of feature norm has an important property that moves feature vectors with small norm faster along weight vectors than feature vectors with large norm, which results intra-class compactness. Specifically, denote feature incay of $\mathbf{f}_i$ as $\mathcal{F}(\mathbf{f}_i) = \frac{1}{\|\mathbf{f}_i\|^2+\epsilon}$, the gradient is $\frac{\partial\mathcal{F}}{\partial\mathbf{f}_i} = -\frac{2\mathbf{f}_i}{(\|\mathbf{f}_i\|^2+\epsilon)^2}$, for any two feature vectors $\mathbf{f}_p$ and $\mathbf{f}_q$ satisfying $\|\mathbf{f}_q\| > \|\mathbf{f}_p\|$, we always have $\|\frac{\partial\mathcal{F}}{\partial\mathbf{f}_p}\| > \|\frac{\partial\mathcal{F}}{\partial\mathbf{f}_q}\|$.

3.4 Geometric Interpretation of Reciprocal Norm Loss

As stated in previous subsection, Reciprocal Norm Loss can increase feature norm adaptively to decrease the intra-class variance. Here we prove that there exists an upper bound for feature norm.

Property 3 [Feature Norm Bound] *Suppose that (a) the angle between any feature vector $\mathbf{f}_i$ and its corresponding weight vector $\mathbf{w}_{y_i}$ is zero, (b) the angles between any two neighbor weight vectors of different classes are θ, we have (1) the minimal inter-class distance is $2\alpha\sin(\frac{\theta}{2})$, where r is lower bound of feature norm, (2) when $K < 2D$, the upper bound of feature norm is in the range of*

Table 1: Face verification accuracy (%) on LFW.

Method	Data	Network	mAcc
FaceNet(Schroff et al. (2015))	200M	N/A	99.65
DeepID2(Sun et al. (2015))	300K	N/A	99.47
CenterFace(Wen et al. (2016))	700K	N/A	99.28
L-Softmax(Liu et al. (2016))	CASIA-WebFace	SphereNet-64	99.10
A-Softmax(Liu et al. (2017a))	CASIA-WebFace	SphereNet-20	99.26
A-Softmax(Liu et al. (2017a))	CASIA-WebFace	SphereNet-64	99.42
COCO(Liu et al. (2017c))	MS-1M	ResNet-101	**99.78**
L-Softmax	CASIA-WebFace	SphereNet-20	99.03
RN + L-Softmax	CASIA-WebFace	SphereNet-20	**99.18**
A-Softmax	CASIA-WebFace	SphereNet-64	99.42
RN + A-Softmax	CASIA-WebFace	SphereNet-64	**99.47**

$[(1+\sqrt{2})\alpha, 3\alpha]$ *to ensure the maximal intra-class distance is smaller than the minimal inter-class distance.*

Proof. Figure 5 shows the 2-dimensional case satisfying the (a) and (b), where black arrows named with W_i represent weight vectors for each class. As we have assumed that all feature vectors are lying on the directions of their corresponding W_i, blue circle and purple circle denote the lower bound and upper bound of feature norm respectively. Thus the maximal intra-class distance is $d_2 = \beta - \alpha$ and the minimal inter-class distance is $d_1 = 2\alpha\sin(\frac{\theta}{2})$. To ensure minimal inter-class distance is larger than intra-class distance, i.e., $d_1 = 2\alpha\sin(\frac{\theta}{2}) > d_2 = \beta - \alpha$, which requires $\beta < 2\alpha\sin(\frac{\theta}{2}) + \alpha$.

When $K < 2D$, according to the **Lemma**(refer to supplementary), we can ensure that $\theta \geq 90°$. Besides, the angle between any two vectors is smaller than $180°$. Then $\frac{\theta}{2} \in [45°, 90°]$ and $\sin(\frac{\theta}{2})$ is a monotonously increasing function within the range $[45°, 90°]$. Based on $\sin(\frac{\theta}{2}) \in [\frac{\sqrt{2}}{2}, 1]$, the upper bound of L_2-norm of feature vectors is in the range $[(1+\sqrt{2})\alpha, 3\alpha]$. □

According to the **Property 3**, We can estimate the upper bound of the feature norm based on the original features' L_2-norm. In our experiments, we choose the average L_2-norm as the lower bound to avoid the influence of outliers. For example, if the average L_2-norm on CIFAR10 is 200, we will choose $483 \approx (1+\sqrt{2}) \times 200$ as the threshold to control the feature incay. The feature incay for features with feature norm exceeding 483 will be set as 0.

In summary, feature norm matters and softmax loss can benifit from the proposed feature incay.

4 EXPERIMENTS

4.1 EXPERIMENTAL SETTINGS

We evaluate feature incay on four datasets, i.e., MNIST, CIFAR10, CIFAR100 and LFW. MNIST consists of 60,000 training images and 10,000 test images from 10 handwritten digits, both CIFAR10 and CIFAR100 contain 50,000 training images and 10,000 test images from 10 object categories and 100 object categories respectively. LFW(Huang et al. (2007)) dataset contains 13,233 face images from 5749 different identities, 6000 face pairs are used as test set following the standard protocol. Images are subtracted by mean image and randomly flipped horizontally for data augmentation. The specific network architectures are detailed in supplementary. We adopt Caffe framework(Jia et al. (2014)) for training and testing. The weight μ for weight decay is set as 0.0005 in all experiments. We choose different weight λ in different experiments, i.e., 1.0, 0.1 or 0.01. The momentum is 0.9, and the learning rate starts from 0.1 and is divided by a factor of 10 three times when the training error stops decreasing.

4.2 COMPARISON EXPERIMENTS

Feature incay is added to Sofmax, L-Softmax and A-Softmax to compare with state-of-the-art approaches, and the reproduced results by Softmax, L-Softmax and A-Softmax following Liu et al. (2016; 2017a) are the same as or slightly better than the referred numbers in the original works. Table 2 reports the error rates of compared approaches and our method on MNIST, CIFAR10 and

Table 2: Error Rates (%) on MNIST/CIFAR10/CIFAR100.

Method	MNIST	CIFAR10	CIFAR100
CNN(Jarrett et al. (2009))	0.53	N/A	N/A
DropConnect(Wan et al. (2013))	0.57	9.41	N/A
FitNet(Romero et al. (2014))	0.51	N/A	35.04
NiN(Lin et al. (2013))	0.47	10.47	35.68
Maxout(Goodfellow et al. (2013))	0.45	11.68	38.57
DSN(Lee et al. (2015))	0.39	9.69	34.57
R-CNN(Liang & Hu (2015))	0.31	8.69	31.75
GenPool(Lee et al. (2016))	0.31	7.62	32.37
Hinge Loss(Liu et al. (2016))	0.47	9.91	33.10
Softmax(Liu et al. (2016))	0.40	9.05	32.74
L-Softmax(Liu et al. (2016))	0.31	7.58	29.53
Softmax	0.35	8.59	32.36
RN + Softmax	0.31	7.84	31.76
L-Softmax	**0.25**	7.56	29.95
RN + L-Softmax	0.29	**7.22**	**29.18**

Table 3: Accuracy(%) Comparison of different λ.

Method	$\lambda = 0$	$\lambda = 1$	$\lambda = 0.1$	$\lambda = 0.01$
RN + Softmax	91.41	91.68	**92.16**	91.96
RN + L-Softmax	92.44	92.40	**92.78**	92.65

CIFAR100. It can be concluded that feature incay can consistently improve over Softmax and L-Softmax on CIFAR10/CIFAR100. For example, RN decreases the error rate of Softmax from 8.59% to 7.84% while L-Softmax achieves 7.56% on CIFAR10, which demonstrates both of them are better than Softmax. By combining RN and L-Sofmax, we achieve better result 7.22%, which means that they are complementary. However, RN + L-Softmax is slightly worse than L-Softmax on MNIST, our hypothesis is that the performance on MNIST is already saturate and difficult to improve further.

To further verify our method's effectiveness on more challenging datasets, we test RN + L-Softmax and RN + A-Softmax on LFW and achieve competitive performance with SphereNet-20 and SphereNet-64. The results are illustrated in Table 1. The reproduced results with L-Softmax and A-Softmax are comparable. With feature incay, RN + L-Softmax improves the L-Softmax from 99.03% to 99.18% and RN + A-Softmax improves the A-Softmax from 99.42% to 99.47%. Thus feature incay can even promote the A-Softmax(Liu et al. (2017a)) with normalized features by elongating the features before normalization.

4.3 Effects of λ.

Here we conduct experiments on CIFAR10 to investigate the influence of hyper-parameter λ. Results are illustrated in Table 3. Both RN + Softmax and RN + L-Softmax achieve consistent improvement for all different λ except on RN + L-Softmax when $\lambda = 1$, which is caused by that the loss item of L-Softmax can be smaller than the loss item of feature incay. To balance the L-Softmax and feature incay for training, λ should be set to a relatively small weight.

4.4 Simply Scale the Feature

To verify whether it is possible to improve the performance by simply rescaling the features before computing softmax loss, we conduct extensive experiments on CIFAR10 and present the related results in Table 4. Simply scaling the features fails to improve the performance, where too large value can cause the network fails to converge. For example, when we scale the features more than 10 times, the softmax loss will explode during training.

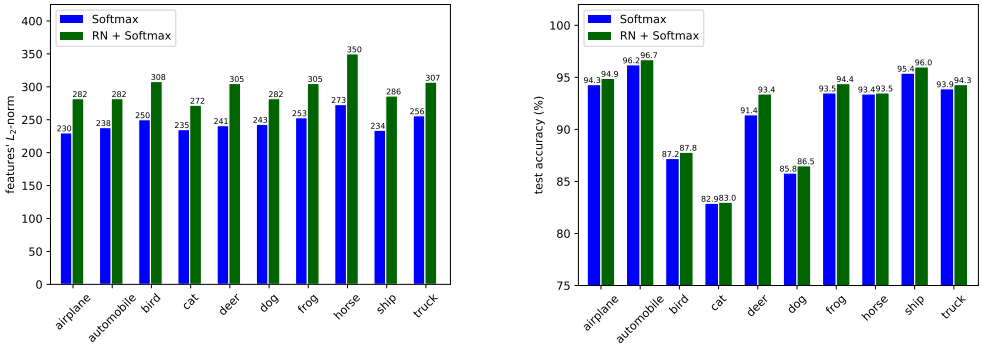
Table 4: Accuracy(%) Comparison by simply Scaling the Feature on CIFAR10, We scale the features for different times before the features are processed by softmax loss. NAN represents the softmax loss is exploded during training.

Scale	1	2	4	6	8	> 10
Softmax	**91.41**	90.90	90.18	90.91	90.97	NAN

Table 5: Average L_2-norm and the corresponding number of examples on test set of CIFAR10, e.g., 253.2 / 9141 represents 9141 examples are correctly classified and their average L_2-norm is 253.2. Error-fixed represents the examples mis-classified by Softmax but correctly-classified by RN + Softmax. Error-added represents the examples correctly-classified by Softmax but mis-classified by RN + Softmax.

Method	Accuracy	correctly-classified	Mis-classified	Error-fixed	Error-added
Softmax	91.41	253.2 / 9141	167.5 / 859	169.3 / 336	161.6 / 261
RN + Softmax	92.16	308.3 / 9216	187.2 / 784	195.9 / 336	187.3 / 261

4.5 Result Analysis



(a) Average L_2-norm on test set. (b) Accuracy on test set.

Figure 6: Histograms of Average L_2-norm and Accuracy on CIFAR10, (a) the feature norm is increased over all the classes. e.g., the feature norm increases from 230 to 282 for class airplane. (b) the test accuracy is boosted over all the classes. e.g., the test accuracy increases from 95.4 to 96.0 for class ship.

By analyzing the features' L_2-norm and classification accuracy on each class of CIFAR10, we want to investigate where the improvements come from, and we find 336 examples that are mis-classified by Softmax but correctly classified by RN + Softmax. However, 259 mis-classified examples are furhter introduced by RN + Softmax, which limits the final performance improvement.

We also plot the histograms of average L_2-norm and accuracy for Softmax and Softmax + RN. The details are illustrated in Figure 6. With feature incay, the feature norm is enlarged and the accuracy is on all ten classes.

5 Conclusions and Future Work

In this paper, we propose the feature incay implemented as Reciprocal Norm Loss to increase the feature norm. Based on the theoretical analysis of the feature norm, the Reciprocal Norm Loss induces smaller training loss and forces the model to focus on hard examples by managing the feature norm of both the correctly-classified and mis-classified feature vectors. Extensive experiments on MNIST, CIFAR10, CIFAR100 and LFW verify the effectiveness of our method.

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Table 6: Results of comparison experiments for three feature incay on CIFAR10, where LN represents the linear form, LogN represents the log form and RN represents the reciprocal form.

Method	Softmax	Softmax + LN	Softmax + LogN	Softmax + RN
Accuracy	91.41	91.86	91.83	**92.16**

6 SUPPLEMENTARY

6.1 LEMMA

Here is the **Lemma** proposed by Ranjan et al. (2017) and is used in the proof of **Property 3** and **Property 4**.

Lemma *When the number of classes K is smaller than twice the feature dimension D, we can distribute the classes on a hypersphere of dimension D such that any two class weight vectors are at least $90°$ apart.*

6.2 FEATURE NORM WITHIN SOFTMAX LOSS

Property 4 [Feature Norm in Softmax Loss]*For any feature vector $\mathbf{f}_i$, if $P^i_{y_i} \to 1$ and $P^i_j \to 0(\forall j \neq y_i)$, then $\frac{\partial \mathcal{L}_{softmax}}{\partial \mathbf{f}_i} \to 0$.*

Proof. According to definition of softmax loss in Eq.(3), the gradient of feature vector $\mathbf{f}_i$ is:

$$\frac{\partial \mathcal{L}_{\text{softmax}}}{\partial \mathbf{f}_i} = \frac{1}{N}(-\mathbf{w}_{y_i} + \sum_{j=1}^{K} P^i_j \mathbf{w}_j) \tag{9}$$

where the $P^i_j = \frac{e^{\mathbf{w}_j^T \mathbf{f}_i}}{\sum_{k=1}^{K} e^{\mathbf{w}_k^T \mathbf{f}_i}}$. When $P^i_{y_i} \to 1$ and $P^i_j \to 0(\forall j \neq y_i)$, $\frac{\partial \mathcal{L}_{\text{softmax}}}{\partial \mathbf{f}_i} \to 0$. That is after a training sample is confidently classified correctly, it will have no contribution to its own representation learning. For example, suppose $\|\mathbf{w}_j\| = 1$, $\theta_{\mathbf{w}_{y_i},\mathbf{f}_i} = 0$ and $\theta_{\mathbf{w}_j,\mathbf{f}_i} \geq 90°(\forall j \neq y_i)$ according the **Lemma**, then $\|\mathbf{w}_{y_i}\|\|\mathbf{f}_i\|\cos(\theta_{\mathbf{w}_{y_i},\mathbf{f}_i}) = \|\mathbf{f}_i\|$, $\|\mathbf{w}_j\|\|\mathbf{f}_i\|\cos(\theta_{\mathbf{w}_j,\mathbf{f}_i}) < 0, \forall j \neq y_i$. Putting together, we have $P^i_{y_i} \geq \frac{e^{\|\mathbf{f}_i\|}}{e^{\|\mathbf{f}_i\|}+K-1}$, for a modest number of categories say $K = 10$, $P^i_{y_i} > 0.999$ when $\|\mathbf{f}_i\| = 10$. □

6.3 FUNCTIONAL FORMAT OF FEATURE INCAY

The choice of the functional format of feature incay is important. Here we mainly analyze three different choices.

- **Linear.** $\mathcal{F}(\|\mathbf{f}\|^2) = \|\mathbf{f}\|^2$ $\quad \frac{\partial \mathcal{F}}{\partial \mathbf{f}} = 2\mathbf{f}$
- **Log.** $\mathcal{F}(\|\mathbf{f}\|^2) = log(\|\mathbf{f}\|^2)$ $\quad \frac{\partial \mathcal{F}}{\partial \mathbf{f}} = \frac{2\mathbf{f}}{\|\mathbf{f}\|^2}$
- **Reciprocal.** $\mathcal{F}(\|\mathbf{f}\|^2) = -\frac{1}{\|\mathbf{f}\|^2}$ $\quad \frac{\partial \mathcal{F}}{\partial \mathbf{f}} = \frac{2\mathbf{f}}{\|\mathbf{f}\|^2\|\mathbf{f}\|^2}$

Here we mainly analyze the differences of the above three functions by investigating the relationship between the gradients and the original feature norm. Assuming that we have two features $\mathbf{f}_1$ and $\mathbf{f}_2$ satisfying $\|\mathbf{f}_2\| > \|\mathbf{f}_1\|$. For the linear function case, we have $\| \frac{\partial \mathcal{F}}{\partial \mathbf{f}_2} \| > \| \frac{\partial \mathcal{F}}{\partial \mathbf{f}_1} \|$. Then, the intra-class variance will be increased as the distance between $\mathbf{f}_1$ and $\mathbf{f}_2$ increases with each gradient update. Besides, the gradients of the linear function have the same magnitude with the feature itself, such large gradients update can lead to explosion during the training. For the log function case, we have $\frac{\partial \mathcal{F}}{\partial \mathbf{f}} = \frac{2\mathbf{f}}{\|\mathbf{f}\|^2} = \frac{2\mathbf{u}}{\|\mathbf{f}\|}$, where $\mathbf{u}$ is the unit vector with feature norm equals 1. Thus $\| \frac{\partial \mathcal{F}}{\partial \mathbf{f}_1} \| > \| \frac{\partial \mathcal{F}}{\partial \mathbf{f}_2} \|$. The gradients within reciprocal function is also that $\| \frac{\partial \mathcal{F}}{\partial \mathbf{f}_1} \| > \| \frac{\partial \mathcal{F}}{\partial \mathbf{f}_2} \|$ always holds once $\|\mathbf{f}_2\| > \|\mathbf{f}_1\|$. Although both log function and reciprocal function increase the features with small feature norm faster than the features with larger feature norm, we find the performance of reciprocal function is better. In summary, reciprocal function can increase the overall feature norm and increase the intra-class similarity simultaneously, where the intra-class similarity along the direction of the weight vectors can be decreased with the log function. We choose the reciprocal function in all of our experiments.

Table 7: Accuracy(%) Comparison of different μ on CIFAR10. $\mu = 0.0005$ is the best choice among all of them, thus we choose this setting in all the other experiments.

Method	$\mu = 0.00001$	$\mu = 0.00005$	$\mu = 0.0005$	$\mu = 0.005$
Accuracy	89.21	89.35	**91.41**	91.16
Average Feature Norm	185.8	202.2	**246.2**	231.3

Table 6 reports the classification accuracies adopting the three different considered feature incay. The superiority of Softmax + RN over Softmax + LN and Softmax + LogN is well illustrated, where Softmax + RN can achieve better intra-class similarity according to the above analysis.

6.4 CNN Architectures Settings

For LFW, we adopt 20-layer/64-layer SphereNet following the same settings in Liu et al. (2017a). We modify the network settings for MNIST/CIFAR10/CIFAR100 based on the previous work(Liu et al. (2016)) and list them in Table 8.

Table 8: The CNN architectures used for MNIST/CIFAR10/CIFAR100. The count of the Conv1.x, Conv2.x and Conv3.x closely follows the settings in Liu et al. (2016). All the pooling layers are with window size 2×2 and stride of 2.

Layer	MNIST	CIFAR10	CIFAR100
Conv0.x	$[3 \times 3, 64] \times 1$	$[3 \times 3, 64] \times 1$	$[3 \times 3, 128] \times 1$
Conv1.x	$[3 \times 3, 64] \times 3$	$[3 \times 3, 64] \times 4$	$[3 \times 3, 128] \times 4$
Conv2.x	$[3 \times 3, 64] \times 3$	$[3 \times 3, 128] \times 4$	$[3 \times 3, 256] \times 4$
Conv3.x	$[3 \times 3, 64] \times 3$	$[3 \times 3, 256] \times 4$	$[3 \times 3, 512] \times 4$
Fully Connected	256	512	512

6.5 Effects of Weight Decay

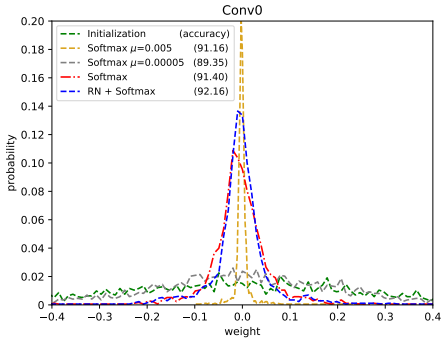
Here we also investigate the influence of the weigth decay on the classification accuracy and feature norm, where we conduct experiments considering only Softmax loss for fairness. The results are reported in Table 7, where we find that it fails to improve neither accuracy nor feature norm by simply increasing the weight decay or decreasing the weight decay. Thus simply changing the weight decay leads to either underfitting or overfitting.

6.6 Effects on Weights' Distribution

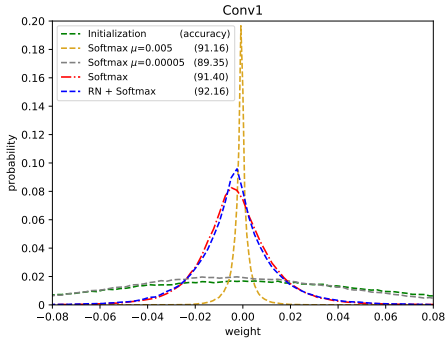
To avoid overfitting, we consider weight decay in all experiments. However, one main concern is the side effect of feature incay may increase the magnitude of the shallow layers. Here we plot the weights' distributions of initial state, difference choices of weight decay within Softmax and RN + Softmax. We find that the influence of feature incay is limited due to the constraint from weight decay. In summary, the feature incay enlarges the feature norm without harming the magnitude of weights from previous layers and will not lead to overfitting. Besides, we can also observe that different weight decay has big impact on the final weight distribution, such as larger weigth decay(e.g., $\mu = 0.005$) results in more weights are constrained to zero, which may lead to underfitting according to their final classification performances.

6.7 Experimental Analysis

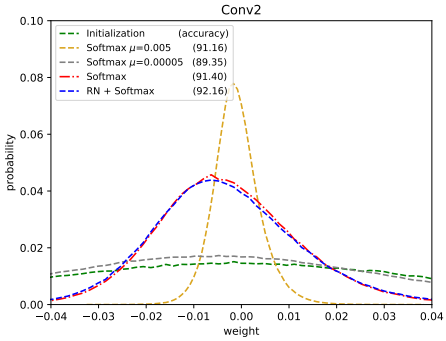
Figure 8(a), 8(b) and 8(c) show the accuracy, average feature norm and softmax loss during training by using $\lambda = 1, 0.1, 0.01$ respectively on CIFAR10. Feature incay achieves better or comparable accuracy compared with softmax loss under a wide range of λ, and results in larger feature norm on both training and test set. All methods achieve close to zero softmax loss on training set, while feature incay ensures lower softmax loss on test set. Figure 8(d) shows the accuracy vs iteration number on CIFAR100, which is similar to the results on CIFAR10.



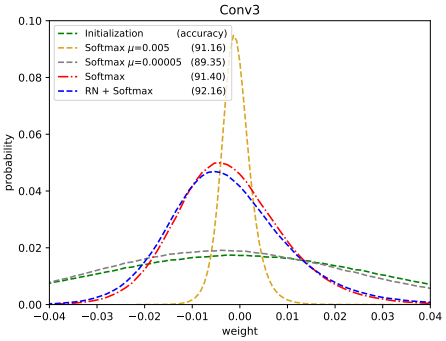
(a) Conv0.x



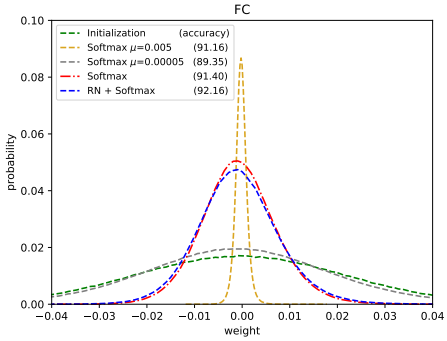
(b) Conv1.x



(c) Conv2.x



(d) Conv3.x



(e) FC

Figure 7: Histograms for Weights' distribution of different layers from model trained on CIFAR10. Here we consider five methods: (1) Weights' distribution after Initialization. (2) Weights' distribution after trained with Softmax loss where the weight decay chooses $\mu = 0.005$(classification accuracy is 91.16%). (3) Weights' distribution after trained with Softmax loss where the weight decay chooses $\mu = 0.00005$(classification accuracy is 89.35%). (4) Weights' distribution after trained with Softmax loss where the weight decay chooses $\mu = 0.0005$(classification accuracy is 91.40%). (5) Weights' distribution after trained with RN + Softmax(classification accuracy is 92.16%). The magnitude of the weight parameters is only slightly influenced by the feature incay. Besides, Softmax $\mu = 0.005$ represents larger weigth decay while Softmax $\mu = 0.00005$ represents smaller weight decay compared with the standard settings.(e.g., $\mu = 0.0005$). The weights parameters are very sparse within Softmax $\mu = 0.005$ while very dense within Softmax $\mu = 0.00005$, which induce either underfitting or overfitting.

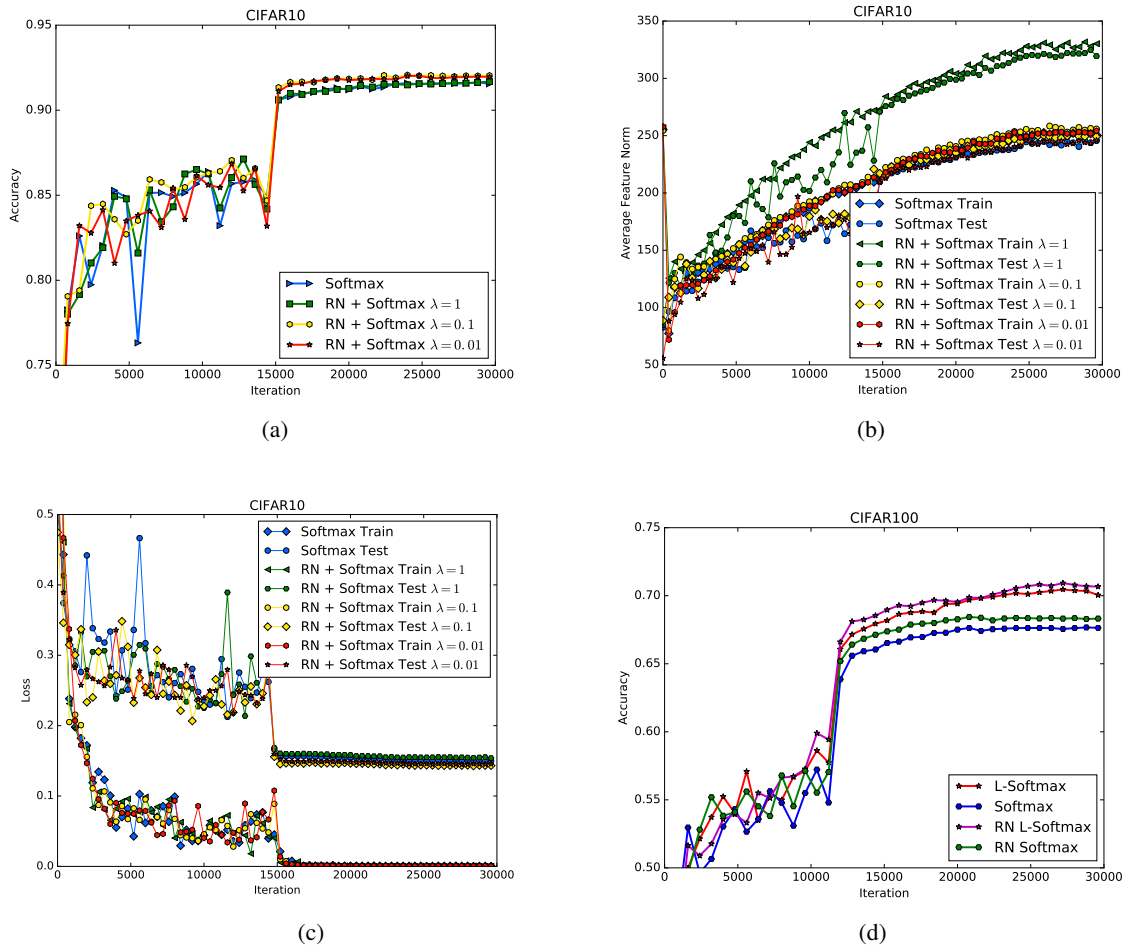


Figure 8: (a) Accuracy versus iterations with different choices of λ value on the test set of CIFAR10. The RN Softmax achieves 92.04% when $\lambda = 0.1$ (b) The training/testing sets' L_2 norm vs iterations with different choices of the λ value on CIFAR10. The RN Softmax with different λ all achieve larger L_2-norm. (c) The training/testing sets' loss vs iterations with different choices of the λ value on CIFAR10. The RN Softmax achieves notable smaller loss value 0.1432 than the Softmax with 0.1498. The training loss is very small for all the methods, but RN + Softmax has significantly smaller testing loss.(It is best viewed by zooming the figure.) (d) Accuracy vs iterations with Softmax/RN Softmax/L-Softmax/RN L-Softmax on CIFAR100. Both RN Softmax and RN + L-Softmax achieve better performance compared with baseline, where the best method is RN + L-Softmax.