PAC Prediction Sets for Meta-Learning

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Abstract

Uncertainty quantification is a key component of machine learning models targeted at safety-critical systems such as in healthcare or autonomous vehicles. We study this problem in the context of meta learning, where the goal is to quickly adapt a predictor to new tasks. In particular, we propose a novel algorithm to construct *PAC prediction sets*, which capture uncertainty via sets of labels, that can be adapted to new tasks with only a few training examples. These prediction sets satisfy an extension of the typical PAC guarantee to the meta learning setting; in particular, the PAC guarantee holds with high probability over future tasks. We demonstrate the efficacy of our approach on four datasets across three application domains: mini-ImageNet and CIFAR10-C in the visual domain, FewRel in the language domain, and the CDC Heart Dataset in the medical domain. In particular, our prediction sets satisfy the PAC guarantee while having smaller size compared to other baselines that also satisfy this guarantee.

1 Introduction

Uncertainty quantification is a key component for safety-critical systems such as healthcare and robotics, since it enables agents to account for risk when making decisions. Prediction sets are a promising approach, since they provide theoretical guarantees when the training and test data are i.i.d. [1, 2, 3, 4]; there have been extensions to handle covariate shift [5, 6, 7] and online learning [8].

We consider the meta learning setting, where the goal is to adapt an existing predictor to new tasks using just a few training examples [9, 10, 11, 12, 13]. Most approaches follow two steps: meta learning (*i.e.,* learn a predictor for fast adaptation) and adaptation (*i.e.,* adapt this predictor to the new task). While there has been work on prediction sets in this setting [14], a key shortcoming is that their guarantees do not address some important needs in meta learning; in particular, they do not hold with high probability over future tasks. For instance, in autonomous driving, the future tasks might be new regions, and correctness guarantees ought to hold for *each* region; in healthcare, future tasks might be new patient cohort, and correctness guarantees ought to hold for *each* cohort.

We propose an algorithm for constructing probably approximately correct (PAC) prediction sets for the meta learning setting. As an example, consider learning an image classifier for self-driving cars as our use case (Figure 1). Labeled images for image classifier learning are collected, with different regions representing different but related tasks (*e.g.,* New York, Pennsylvania, and California). The goal is to deploy this learned image classifier to a new target region (*e.g.,* Alaska) in a cost-efficient way, *e.g.,* minimizing label gathering cost on labeled images from Alaska for the classifier adaptation.

Due to the safety-critical nature of the task, it is desirable to quantify of uncertainty in a way that provides rigorous guarantees, where the guarantees are adapted to a new task (*e.g.,* Alaska images)—i.e., they hold with high probability specifically for future observations from this new task. In contrast, existing approaches only provide guarantees on average across future tasks [14].

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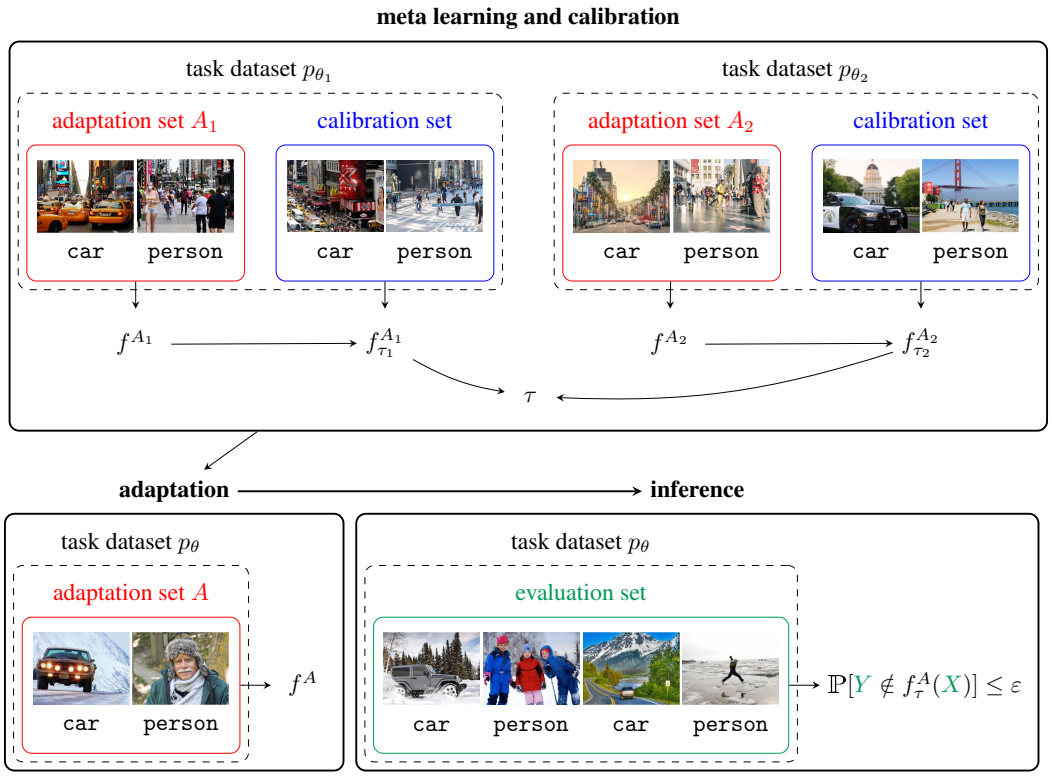


Figure 1: Learning for PAC prediction sets with fast adaptation. In meta learning and calibration, the PAC prediction set parameter τ is chosen from multiple task datasets given a meta-learned and adapted score function f^{A_i} and an adapted PAC prediction set $f^{A_i}_{\tau_i}$ (*e.g.,* an image classifier and a prediction set are learned over labeled images from various regions, including New York). In adaptation, the score function is adapted to the new task distribution f^A (*e.g.,* the image classifier is adapted using labeled images from Alaska). In inference, by using the same parameter τ is used without additional calibration, the constructed and adapted prediction set f^A_τ has a correctness guarantee for most of future examples (*e.g.,* the prediction set along with the adapted image classifier has a correctness guarantee over most images from Alaska). Importantly, the correctness guarantee (error below ε) is achieved with probability at least (1) $1-\delta$ over the calibration sets in the meta learning phase and (2) $1-\alpha$ over an adaptation set in the adaptation phase. This explains why we use a three-parameter PAC-style guarantee for meta learning.

Our proposed PAC prediction set starts with a meta-learned and potentially adaptable score function as our base predictor (using a standard meta learning or few shot classification approach). Then, we learn the parameter of a prediction set for meta "calibration" by using calibration task distributions (*e.g.,* labeled images from Texas and Massachusetts). Given a test task distribution (*e.g.,* labeled images from Alaska), we only have a few labeled examples for adapting the score function to this target task without further updating the prediction set parameter, which potentially saves additional labeled examples. We prove that the proposed algorithm satisfies the PAC guarantee tailored to the meta learning setup. Additionally, we demonstrate the validity of the proposed algorithm over four datasets across three application domains: mini-ImageNet [10] and CIFAR10-C [15] in the visual domain, FewRel [16] in the language domain, and CDC Heart Dataset [17] in the medical domain.

2 Related Work

Meta learning for few-shot learning. Meta-learning follows the paradigm of learning-to-learn [9], usually formulated as few-shot learning: learning or adapting a model to a new task or distribution by leveraging a few examples from the distribution. Existing approaches propose neural network predictors or adaptation algorithms [10, 11, 12, 13] for few-shot learning. However, there is no

guarantee that these approaches can quantify uncertainty properly, and thus they do not provide guarantees for probabilistic decision-making.

Conformal prediction. The classical goal in conformal prediction (and inductive conformal prediction) [18, 2, 19] is to find a prediction set that contains the label with a given probability, with respect to randomness in both calibration examples and a test example, where a score function (or non-conformity score) is given for the inductive conformal prediction. This property is known as marginal coverage. If the labeled examples are independent and identically distributed (or more precisely exchangeable), prediction sets constructed via inductive conformal prediction have marginal coverage [19, 2]. However, the identical distribution assumption can fail if the covariates of a test datapoint are differently distributed from the training covariates, *i.e.,* covariate shift occurs. Assuming that the likelihood ratio is known, the weighted split conformal prediction set [5] satisfies marginal coverage under covariate shift.

So far, we have considered only two distributions, a calibration distribution and test distribution. In meta learning, a few examples from multiple distributions are given, providing a different setup. Assuming exchangeability of these distributions, conformal prediction sets for meta learning have been constructed, covering over a random sample from a new randomly drawn distribution, exchangeable with the training distributions [14].

Tolerance region and PAC prediction sets. Marginal coverage is unconditional over calibration data, and does not hold conditionally over calibration data (i.e., with specified probability for a fixed calibration set). Tolerance regions [1, 20], the conditional validity of conformal prediction [21], and PAC prediction sets [3] address this issue. In particular, for independent and identically distributed calibration examples, they construct a prediction set that contains true label with high probability with respect to calibration examples. We refer to this property as *conditional coverage* or a PAC property. Thus, these prediction sets cover the labels for most future test examples. Conditional coverage can be extended to hold under covariate shift, assuming the distributions are sufficiently smooth [6] or well estimated [7]. In meta learning, the meta conformal prediction set approach also has a PAC property [14], while losing control over the randomness from the adaptation test examples. In contrast, we propose a fully-conditional prediction set; conditional with respect to both calibration data and the test adaptation examples. See Section 4.1 for a discussion of the difference.

3 Background

3.1 PAC Prediction Sets

We describe a probably approximately correct (PAC) prediction set [3], which is equivalent to tolerance regions [1] and training-conditional inductive conformal prediction [21]; the PAC prediction set forms the basis of our proposed algorithm. Let $\mathcal{X}$ be a set of examples or features and $\mathcal{Y}$ be a set of labels. We consider a given score function $f : \mathcal{X} \times \mathcal{Y} \to \mathbb{R}_{\geq 0}$, which is higher if $y \in \mathcal{Y}$ is the true label for $x \in \mathcal{X}$. We consider a parametrized prediction set; letting $\tau \in \mathbb{R}_{\geq 0}$, we define a prediction set $f_\tau : \mathcal{X} \to 2^{\mathcal{Y}}$ as follows:

$$f_\tau \coloneqq \{y \in \mathcal{Y} \mid f(x, y) \geq \tau\}.$$

Consider a family of distributions $(p_\theta)_{\theta \in \Theta}$ over $\mathcal{Z} \coloneqq \mathcal{X} \times \mathcal{Y}$, parametrized by $\theta \in \Theta$. For an unknown θ, we observe independent and identically distributed (i.i.d.) calibration datapoints $S \sim p_\theta^n$. We define a prediction set f_τ, or equivalently the corresponding parameter τ, to be ε-correct, as follows:

Definition 1. A parameter $\tau \in \mathbb{R}_{\geq 0}$ is *ε-correct* for p_θ if

$$\mathbb{P}_{(X,Y)\sim p_\theta}[Y \in f_\tau(X)] \geq 1 - \varepsilon. \tag{1}$$

Letting $T_\varepsilon(\theta)$ be the set of τ satisfying (1) for p_θ, we can write $\tau \in T_\varepsilon(\theta) \subseteq \mathbb{R}_{\geq 0}$ if τ is ε-correct for p_θ. If an estimator of τ is ε-correct on most random calibration sets $S \sim p_\theta^n$, we say it is PAC.

Definition 2. *An estimator $\hat{\tau}_{\varepsilon,\delta} : \mathcal{Z}^n \to \mathbb{R}_{\geq 0}$ is* (ε, δ)-probably approximately correct (PAC) *for p_θ if*

$$\mathbb{P}_{S\sim p_\theta^n}[\hat{\tau}_{\varepsilon,\delta}(S) \in T_\varepsilon(\theta)] \geq 1 - \delta.$$

A practical (ε, δ)-PAC algorithm that implements the estimator $\hat{\tau}_{\varepsilon,\delta}$ maximizes τ while satisfying a PAC constraint to minimize the expected prediction set size [3].

3.2 Meta Learning

Meta learning aims to learn a score function that can be conveniently adapted to a new distribution, also called a *task*. Consider a *task distribution* p_π over Θ, and M training task distributions $p_{\theta_1}, \ldots, p_{\theta_M}$, where $\theta_1, \ldots, \theta_M$ is an i.i.d. sample from p_π. Here, we mainly consider meta learning with adaptation (*e.g.,* few-shot learning) to learn the score function, while having learning without adaptation (*e.g.,* zero-shot learning) as a special case of our main setup.

For meta learning without adaptation, labeled examples are drawn from each training task distribution to learn the score function $f : \mathcal{X} \times \mathcal{Y} \to \mathbb{R}_{\geq 0}$, and the same score function is used for inference (i.e., at test time). For meta learning with adaptation, t adaptation examples are also drawn from each training task distribution to learn the score function $f : \mathcal{Z}^t \times \mathcal{X} \times \mathcal{Y} \to \mathbb{R}_{\geq 0}$, and the same number of adaptation examples are drawn from a new test task distribution for adaptation. Given an adaptation set $A \in \mathcal{Z}^t$, the adapted score function is denoted by $f^A : \mathcal{X} \times \mathcal{Y} \to \mathbb{R}_{\geq 0}$, where $f^A(x, y) \coloneqq f(A, x, y)$. We consider $\mathcal{Y}$ large enough to include all label classes, some of which possibly seen during testing but not during training. This formulation includes learning setups (*e.g.,* few-shot learning) where unseen label classes are observed during inference, by considering different distributions over labeled examples during training and inference.

4 Meta PAC Prediction Sets

We propose a PAC prediction set for meta learning. In particular, we consider a meta-learned score function, which is typically trained to be a good predictor after adaptation to the test distribution. Our prediction set has a correctness guarantee for future test distributions.

4.1 Setup and Problem

We describe the problem on PAC prediction set construction for meta learning with adaptation; see Appendix A for a simpler problem setup without adaptation, a special case of our main problem.

Setup. In the setting of Section 3.2, the training samples from some training distributions $p_{\theta'_i}$, $i = 1, \ldots, M$ are used to learn a score function via an arbitrary meta learning method. We denote the given meta-learned score function by f. Additionally, we have N calibration distributions $p_{\theta_1}, \ldots, p_{\theta_N}$, where $\theta_1, \ldots, \theta_N$ is an i.i.d. sample from p_π. From each calibration distribution p_{θ_i}, we draw n i.i.d. labeled examples for a calibration set, *i.e.,* $(S_1, \ldots, S_N) \sim p^n_{\theta_1} \cdots p^n_{\theta_N}$. Additionally, we draw t i.i.d. labeled examples for an adaptation set, *i.e.,* $(A_1, \ldots, A_N) \sim p^t_{\theta_1} \cdots p^t_{\theta_N}$; we use them to construct the meta PAC prediction set. Finally, we consider a test distribution p_θ, where $\theta \sim p_\pi$. From it, we draw i.i.d. labeled adaptation examples A and i.i.d. evaluation examples.

Problem. Our goal is to find a prediction set $f_\tau : \mathcal{Z}^t \times \mathcal{X} \to 2^{\mathcal{Y}}$ parametrized by $\tau \in \mathbb{R}_{\geq 0}$ which satisfies a meta-learning variant of the PAC definition. In particular, consider an estimator $\hat{\tau}_{\varepsilon,\alpha,\delta} : \mathcal{Z}^{n \times N} \times \mathcal{Z}^{t \times N} \to \mathbb{R}_{\geq 0}$ that estimates τ for a prediction set, given an *augmented calibration set* $(S_1, \ldots, S_N, A_1, \ldots, A_N)$. Let $T_\varepsilon(\theta, A)$ be a set of all ε-correct parameters τ with respect to f adapted using a test adaptation set A. We also consider $f^A_\tau(x, y) \coloneqq f_\tau(A, x, y)$.

We say that a prediction set f_τ parametrized by τ is ε-correct for p_θ for a fixed adaptation set A, if $\tau \in T_\varepsilon(\theta, A)$. Moreover, we want the prediction set f_τ where τ is estimated via $\hat{\tau}_{\varepsilon,\alpha,\delta}$ to be correct on most test sets A for adaptation and for most test tasks θ. Letting $S_{1:k} \coloneqq (S_1, \ldots, S_k)$ and $A_{1:k} \coloneqq (A_1, \ldots, A_k)$ for any $k \geq 1$, we want that, given $S_{1:N} \in \mathcal{Z}^{n \times N}$ and $A_{1:N} \in \mathcal{Z}^{t \times N}$,

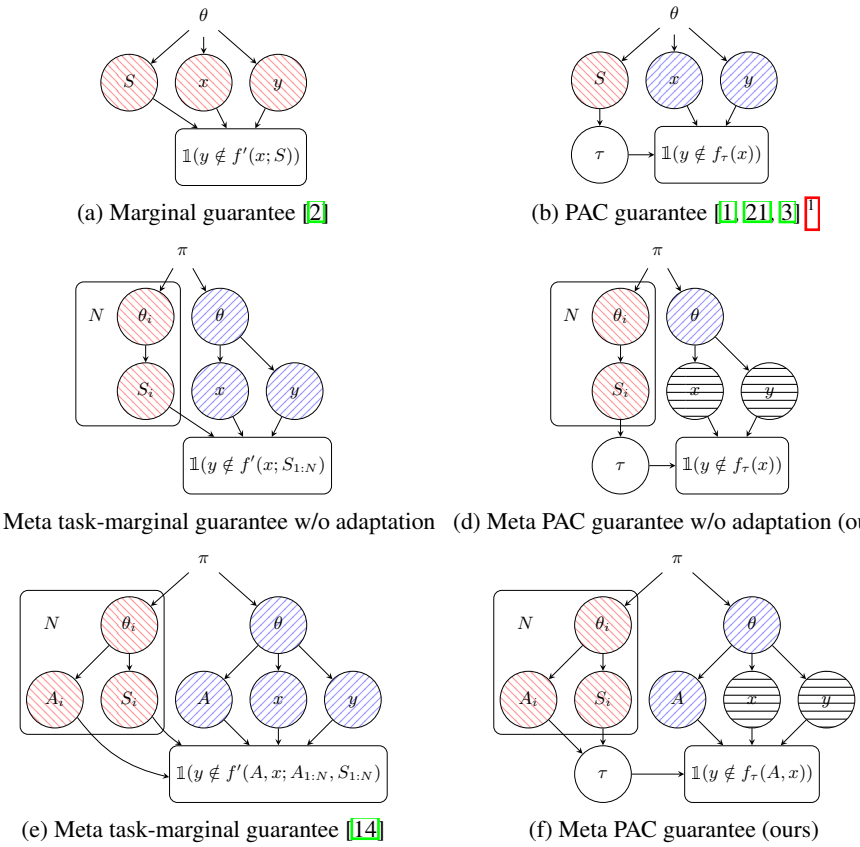
$$\mathbb{P}_{\theta,A}[\hat{\tau}_{\varepsilon,\alpha,\delta}(S_{1:N}, A_{1:N}) \in T_\varepsilon(\theta, A)] \geq 1 - \alpha,$$

where $\theta \sim p_\pi$ and $A \sim p^t_\theta$. Intuitively, we want a prediction set, adapted via A, to be correct on future labeled examples from p_θ. Finally, we want the above to hold for most augmented calibration sets $(S_{1:N}, A_{1:N})$ from most training tasks $\theta_1, \ldots, \theta_N \sim p_\pi$, leading to the following definition.

Definition 3. *An estimator* $\hat{\tau}_{\varepsilon,\alpha,\delta} : \mathcal{Z}^{n \times N} \times \mathcal{Z}^{t \times N} \to \mathbb{R}_{\geq 0}$ *is* $(\varepsilon, \alpha, \delta)$-meta probably approximately correct (mPAC) *for* p_π *if*

$$\mathbb{P}_{\theta_{1:N}, S_{1:N}, A_{1:N}}\left[\mathbb{P}_{\theta,A}\left[\hat{\tau}_{\varepsilon,\alpha,\delta}(S_{1:N}, A_{1:N}) \in T_\varepsilon(\theta, A)\right] \geq 1 - \alpha\right] \geq 1 - \delta,$$

where $\theta_i, \theta \sim p_\pi$, $S_i \sim p^n_{\theta_i}$ *for* $i = 1, \ldots, N$, $S \sim p^n_\theta$, $A_i \sim p^t_{\theta_i}$ *for* $i = 1, \ldots, N$, *and* $A \sim p^t_\theta$.



(a) Marginal guarantee [2]

(b) PAC guarantee [1, 21, 3] [1]

(c) Meta task-marginal guarantee w/o adaptation

(d) Meta PAC guarantee w/o adaptation (ours)

(e) Meta task-marginal guarantee [14]

(f) Meta PAC guarantee (ours)

Figure 2: Comparison among different guarantees on prediction sets. Each stripe pattern with a different color indicates that the corresponding random variables are conditioned on in the correctness guarantee; f' denotes a conformal prediction set. The proposed meta PAC prediction set (2f) has the most fine-grained control over the correctness guarantee conditioning over training tasks, the test task and adaptation set, and the test data.

Notably, Definition 3 is tightly related to the PAC definition of meta conformal prediction [14]. We illustrate the difference in Figure 2; the figure represents the different guarantees of prediction sets via graphical models. Each stripe pattern indicates the random variables that are conditioned on in the respective guarantee. Figure 2f represents the proposed guarantee, having Figure 2b and 2d as special cases. Figure 2e shows the guarantee of meta conformal prediction proposed in [14], also having Figure 2a and 2c as special cases.

Figure 2f shows that the proposed correctness guarantee is conditioned over *calibration tasks*, an *adaptation set* A *from a test task*, and *test data* (x, y). This implies that the correctness guarantee of an adapted prediction set (thus conditioned on the adaptation set) holds on most future test datasets from the same test task. In contrast, the guarantee in Figure 2e is conditioned on the entire test task. Thus, the correctness guarantee does not hold conditionally over adaptation sets; this means that the adapted prediction set (thus conditioned on an adaptation set) does not need to be correct over most future datasets in the same task.

We next propose an algorithm for an estimator $\hat{\tau}_{\varepsilon,\alpha,\delta}$ that satisfies Definition 3, while aiming to minimize the prediction set size.

4.2 Algorithm

We propose a meta PAC prediction set algorithm, which leverages the scalar parameterization of a prediction set. The algorithm consists of two steps: find a prediction set parameter over labeled

[1] It is also called a training-set conditional guarantee in [21].

Algorithm 1 Meta-PS: PAC prediction set for meta-learning. Internally, any PAC prediction set algorithms are used to implement an estimator $\hat{\tau}_{\varepsilon,\delta}$; we use PS-BINOM (Algorithm 2) in Appendix B.

1: **procedure** META-PS($S_{1:N}$, $A_{1:N}$, f, g, ε, α, δ)
2: **for** $i \in \{1, \ldots, N\}$ **do**
3: $\hat{\tau}_i \leftarrow$ PS-BINOM($S_i, f^{A_i}, \varepsilon, \alpha/2$) (▷) Use Algorithm 2 in Appendix B
4: $S' \leftarrow ((\hat{\tau}_1, 1), \ldots, (\hat{\tau}_N, 1))$
5: $\hat{\tau} \leftarrow$ PS-BINOM($S', g, \alpha/2, \delta$)
6: **return** $\hat{\tau}$

examples S_i and A_i from the i-th calibration task distribution, and find a prediction set over the parameter of prediction sets in the previous step. At inference, the constructed prediction set is adapted to a test task distribution via an adaptation set A. Importantly, in finding prediction sets (*i.e.,* implementating an (ε, δ)-PAC estimator $\hat{\tau}_{\varepsilon,\delta}$), we can use any PAC prediction set algorithms (*e.g.,* Algorithm 2 in Appendix B).

Meta calibration. For the first step, for each $i \in \{1, \ldots, N\}$, we estimate a prediction set parameter $\hat{\tau}_{\varepsilon,\alpha/2}(S_i)$, satisfying a $(\varepsilon,\ \alpha/2)$-PAC property using a calibration set S_i and a score function f adapted via an adaptation set A_i, leading to f^{A_i}, by using any meta learning and adaptation algorithm. We consider the N learned prediction set parameters—with a dummy label 1 to fit the convention of the PAC prediction set algorithm—to form a new labeled sample, *i.e.,* $S' := ((\hat{\tau}_{\varepsilon,\alpha/2}(S_1), 1), \ldots, (\hat{\tau}_{\varepsilon,\alpha/2}(S_N), 1))$.

In the second part, we construct an $(\alpha/2,\ \delta)$-PAC prediction set for the threshold τ using S' and a score function g defined as $g(\tau, y) := \tau \mathbb{1}(y = 1)$, where $\mathbb{1}(\cdot)$ is the indicator function. Thus, the constructed prediction set can be equivalently viewed as an interval $[\hat{\tau}_{\alpha/2,\delta}(S'), \infty)$ where the thresholds τ of most calibration distributions are included; see Section 4.3 for a formal statement along with intuition on our design choice, and see Algorithm 1 for an implementation.

Adaptation and inference. We then use labeled examples A from a test distribution to adapt the meta-learned score function f as in the meta calibration part. Then, we use the same parameter $\hat{\tau}_{\varepsilon,\alpha,\delta}(S_{1:N}, A_{1:N})$ of the meta prediction set along with the adapted score function as our final meta prediction set $f_{\hat{\tau}_{\varepsilon,\alpha,\delta}(S_{1:N}, A_{1:N})}$ for inference in the future.

Reusing the same meta prediction set parameter after adaptation is valid, as the meta prediction set parameter is also chosen after adaptation via a hold-out adaptation set from the same distribution as each respective calibration set. Moreover, by reusing the same parameter, we only need a few labeled examples from the test distribution for an adaptation set, without requiring additional labeled examples for calibration on the test distribution. Finally, we rely on a PAC prediction set algorithm that aims to minimize the expected prediction set size [21, 3]; Algorithm 1 relies on this property, thus making the meta prediction set size small.

4.3 Theory

The proposed Algorithm 1 outputs a threshold for a prediction set that satisfies the mPAC guarantee, as stated in the following result (see Appendix C for a proof):

Theorem 1. *The estimator $\hat{\tau}_{\varepsilon,\alpha,\delta}$ implemented in Algorithm 1 is $(\varepsilon, \alpha, \delta)$-mPAC for p_π.*

Intuitively, the algorithm implicitly constructs an interval $[\hat{\tau}_{\alpha/2,\delta}(S'), \infty)$ over scalar parameters of prediction sets. In particular, for the i-th distribution, the Algorithm in Line 3 finds a scalar parameter of a prediction set for the i-th distribution, which forms an empirical distribution over the scalar parameters. Due to the i.i.d. nature of θ_i, $i = 1, \ldots, N$, the parameter of a prediction set for a test distribution follows the same distribution over scalar parameters. Thus, choosing a conservative scalar parameter as in Line 5 of the Algorithm suffices to satisfy the mPAC guarantee.

5 Experiments

We demonstrate the efficacy of the proposed meta PAC prediction set based on four few-shot learning datasets across three application domains: mini-ImageNet [10] and CIFAR10-C [15] for the visual

domain, FewRel [16] for the language domain, and CDC Heart Dataset [17] for the medical domain. See Appendix E for additional experiments, including the results for CIFAR10-C.

5.1 Experimental Setup

Few-shot learning setup. We consider k-shot c-way learning except for the CDC Heart Dataset; In particular, there are c classes for each task dataset, and k adaptation examples for each class. Thus, we have $t := kc$ labeled examples to adapt a model to a new task. As the CDC Heart dataset is a label unbalanced dataset, we do not assume equal shots per class.

Score functions. We use a prototypical network [11] as a score function. It uses t adaptation examples to adapt the network to a given task dataset, and predicts labels on query examples.

Baselines. We compare four approaches, including our proposed approach.

- **PS**: We consider a naive application of PAC prediction sets [3]. We pool all nN labeled examples from calibration datasets into one calibration set to run the PAC prediction set algorithm.
- **PS-Test**: We construct PAC prediction sets by using 20 shots for each class directly drawn from the test distribution.
- **Meta-CP**: We use the PAC variant of meta conformal prediction [14], which trains a quantile predictor along with a score function, while our approach only needs a score function. We run the authors' code with the same evaluation parameters for comparison.
- **Meta-PS**: This is the proposed meta PAC prediction set from Algorithm 1.

Metric. We evaluate prediction sets mainly via their empirical prediction set error over a test sample, *i.e.,* having learned a parameter τ, we find $1/|E| \sum_{(x,y)\in E} \mathbb{1}(y \notin f_\tau^A(x))$, where A is an adaptation set, and E is an evaluation set drawn from each test task distribution. We desire this to be at most ε given fixed calibration and test datasets. This should hold with probability at least $1-\delta$ over the randomness due to the calibration and adaptation data; and with probability at least $1-\alpha$ over the randomness due to the test adaptation set. To evaluate this, we conduct 100 random trials, drawing independent calibration datasets, and for each fixed calibration dataset, we conduct 50 random trials drawing independent test datasets. The prediction set size evaluation is done similarly to the error; we compute the empirical prediction set size $1/|E| \sum_{(x,y)\in E} S(f_\tau^A(x))$, where S is a size measure, *e.g.,* set cardinality for classification.

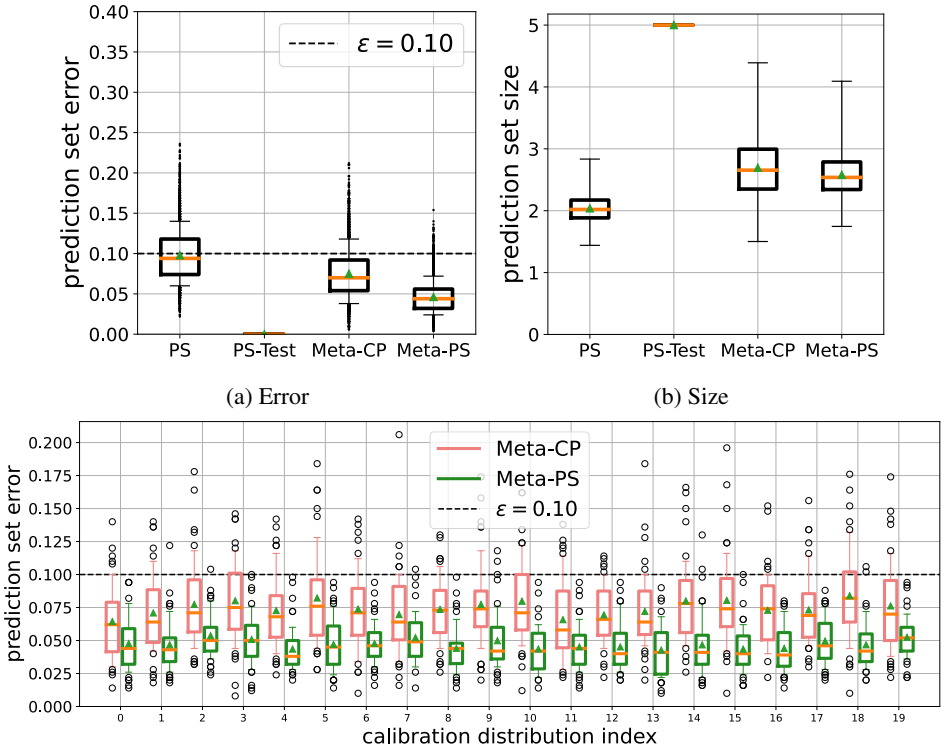
5.2 Mini-ImageNet

Mini-ImageNet [10] is a smaller version of the ImageNet dataset for few-shot learning.

Setup. Mini-ImageNet consists of 100 classes with 64 classes for training, 16 classes for calibration, and 20 classes for testing; each class has 600 images. Following a standard setup, we consider five randomly chosen classes as one task and 5-way classification. In training, we follows 5-shot 5-way learning, considering $M = 800$ training task distribution randomly drawn from the $\binom{64}{5}$ possible tasks. In calibration, we have $N = 500$ calibration task datasets randomly drawn from the $\binom{16}{5}$ possible tasks, and use 5 shots for adaptation and 500 shots for calibration (*i.e.,* $t = 25$ and $n = 2500$). In evaluation, we have 50 test task datasets randomly drawn from the $\binom{20}{5}$ possible tasks and use 5 shots from each of 5 classes for adaptation and 100 shots from each 5 classes for evaluation.

Results. Figure 3 shows the prediction set error and size of the various approaches in box plots. Whiskers in each box plot for the error cover the range between the 10-th and 90-th percentiles of the empirical error distribution, while whiskers in each box plot for the size represents the minimum and maximum of the empirical size distribution. The randomness of error and size is due to the randomness of the augmented calibration $(S_{1:N}, A_{1:N})$ and a test adaptation set A; but since $\delta = 10^{-5}$, the randomness is mostly due to the adaptation set.

The prediction set error of the proposed approach is below the desired level $\varepsilon = 0.1$ at least a fraction $1-\alpha = 0.9$ of the time. This supports that the proposed prediction set satisfies the meta PAC criterion. However, **PS** and **Meta-CP** do not empirically satisfy the meta PAC criterion, and **PS-Test** is too conservative. In particular, **Meta-CP** does not empirically control the randomness due to the test distribution. To make this point precise, Figure 3c shows a prediction set error distribution over different test distributions given a fixed calibration dataset. As can be seen, the proposed **Meta-PS**

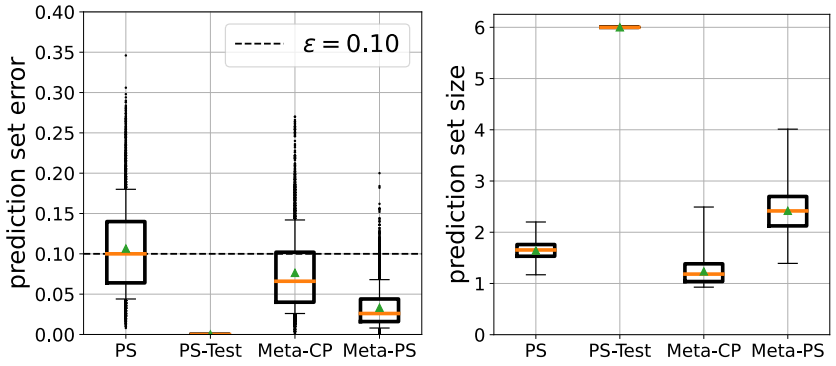


(a) Error

(b) Size

(c) Error given an augmented calibration set

Figure 3: Prediction set error (3a), size (3a), and error given a calibration set (3c) on mini-ImageNet. Parameters are $N = 500$, $n = 2500$, $t = 25$, $\varepsilon = 0.1$, $\alpha = 0.1$, $\delta = 10^{-5}$ for **Meta-PS** and $\varepsilon = 0.1$, $\delta = 10^{-5}$ for the other methods.



(a) Error

(b) Size

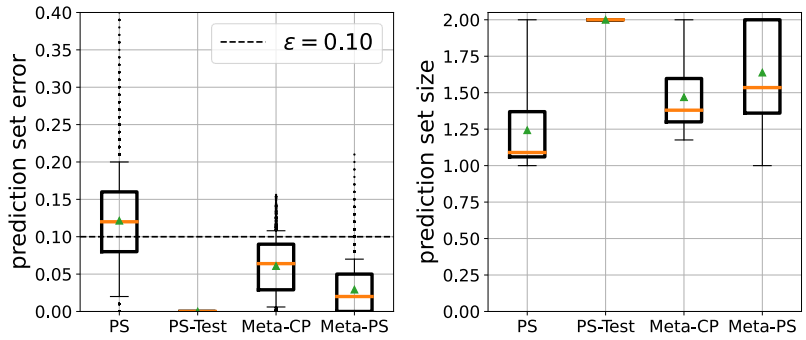
Figure 4: Prediction set error and size on FewRel. Parameters are $N = 500$, $n = 2500$, $t = 25$, $\varepsilon = 0.1$, $\alpha = 0.1$, $\delta = 10^{-5}$ for **Meta-PS** and $\varepsilon = 0.1$, $\delta = 10^{-5}$ for other methods.

approach empirically satisfies the ε error criterion at least a fraction $1 - \alpha = 0.9$ of the time (as shown in the whiskers), but **Meta-CP** does not empirically control it.

Figure 3b demonstrates that the proposed **Meta-PS** produces smaller prediction sets compared to the **PS-Test** approach that also satisfies the ε error constraint.

5.3 FewRel

FewRel [16] is an entity relation dataset, where each example is the tuple of the first and second entities in a sentence along with their relation as a label.



(a) Error (b) Size

Figure 5: Prediction set error and size on CDC Heart Dataset. Parameters are $N = 250$, $n = 3000$, $t = 10$, $\varepsilon = 0.1$, $\alpha = 0.1$, $\delta = 10^{-5}$ for **Meta-PS** and $\varepsilon = 0.1$, $\delta = 10^{-5}$ for other methods.

Setup. FewRel consists of 100 classes, where 64 classes are used for training and 16 classes are originally used validation; each class has 700 examples. The detailed setup for training, calibration, and test are the same as those of mini-ImageNet, except that the test task distributions are randomly drawn from the original validation split.

Results. Figure 4 presents the prediction set error and size of the approaches considered. The trend of the results is similar to the mini-ImageNet result. Our approach empirically satisfies the desired prediction set error specified by ε with empirical probabilities of at least $1 - \alpha$ over the test adaptation set and $1 - \delta$ over the (augmented) calibration data. In contrast, the other approaches either do not empirically satisfy the meta PAC criterion or are highly conservative. Figure 7a also confirms that the proposed approach empirically controls the error with probability at least $1 - \alpha$ over the randomness in the test dataset.

5.4 CDC Heart Dataset

The CDC Behavioral Risk Factor Surveillance System [17] consists of health-related telephone surveys started in 1984. The survey data is collected from US residents. We use the data collected from 2011 to 2020 and consider predicting the risk of heart attack given other features (*e.g.,* level of exercise or weight). We call this curated dataset the CDC Heart Dataset. See Appendix D.4 for the details of the experiment setup.

Setup. The 10 years of the CDC Heart Dataset consists of 530 task distributions from various US states. We consider data from 2011-2014 as the training task distributions, consisting of 212 different tasks and 1,805,073 labeled examples, and data from 2015-2019 as calibration task distributions, consisting of 265 different tasks and 2,045,981 labeled examples, We use the data from 2020 as a test task distribution, consisting of 53 different tasks and 367,511 labeled examples. We use $M = 200$, $N = 250$, $n = 3000$, and $t = 10$; see Appendix D.4 for the details.

Results. Figure 5 includes the prediction set error and size of each approach. The trend is as before. The proposed **Meta-PS** empirically satisfies the $\varepsilon = 0.1$ constraint (*i.e.,* the top of the whisker is below of the $\varepsilon = 0.1$ line), while **PS** and **Meta-CP** violate this constraint. Meanwhile, **PS-Test** conservatively satisfies it. As before, Figure 7b empirically justifies that the proposed approach controls the prediction set error due to the randomness over the test adaptation data.

6 Conclusion

We propose a PAC prediction set algorithm for meta learning, which satisfies a PAC property tailored to a meta learning setup. The efficacy of the proposed algorithm is demonstrated in four datasets across three application domains. In particular, we observe that the proposed algorithm finds a prediction set that satisfies a specified PAC guarantee, while producing a small set size. A limitation of the current approach is that it requires enough calibration datapoints to satisfy the PAC guarantee, see [3] for an analysis. A potential societal impact is that a user of the proposed algorithm might misuse the guarantee without a proper understanding of the assumptions.

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Checklist

1. For all authors...
   (a) Do the main claims made in the abstract and introduction accurately reflect the paper's contributions and scope? [Yes]
   (b) Did you describe the limitations of your work? [Yes] See Section 6.
   (c) Did you discuss any potential negative societal impacts of your work? [Yes] See Section 6.
   (d) Have you read the ethics review guidelines and ensured that your paper conforms to them? [Yes]
2. If you are including theoretical results...
   (a) Did you state the full set of assumptions of all theoretical results? [Yes] See Section 4.1.
   (b) Did you include complete proofs of all theoretical results? [Yes] See Section C.
3. If you ran experiments...
   (a) Did you include the code, data, and instructions needed to reproduce the main experimental results (either in the supplemental material or as a URL)? [No] Code will be released once accepted along with data and precise instructions to run it.
   (b) Did you specify all the training details (e.g., data splits, hyperparameters, how they were chosen)? [Yes] See Section 5 and D.
   (c) Did you report error bars (e.g., with respect to the random seed after running experiments multiple times)? [Yes] We use box plots to represent the randomness on error.
   (d) Did you include the total amount of compute and the type of resources used (e.g., type of GPUs, internal cluster, or cloud provider)? [Yes] See Section D.1.
4. If you are using existing assets (e.g., code, data, models) or curating/releasing new assets...
   (a) If your work uses existing assets, did you cite the creators? [Yes]
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   (d) Did you discuss whether and how consent was obtained from people whose data you're using/curating? [Yes] See Section D.2.
   (e) Did you discuss whether the data you are using/curating contains personally identifiable information or offensive content? [Yes] See Section D.2.
5. If you used crowdsourcing or conducted research with human subjects...
   (a) Did you include the full text of instructions given to participants and screenshots, if applicable? [N/A]
   (b) Did you describe any potential participant risks, with links to Institutional Review Board (IRB) approvals, if applicable? [N/A]
   (c) Did you include the estimated hourly wage paid to participants and the total amount spent on participant compensation? [N/A]