OptimismBench: Forecasting Bias and the Alignment Effect in Language Model Judgment

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Abstract

Large language models are increasingly used as decision aids whose probability judgments shape downstream choices. Whether those judgments carry a systematic directional tilt has been hard to detect: standard calibration metrics aggregate unsigned errors, and naturalistic uncertainty offers no ground-truth probability. When an LLM rates a startup's success at 70% but its failure at 15%, the missing 15 points expose a distortion no aggregate score flags. We introduce OPTIMISMBENCH, which detects directional bias using *inverted pairs*: for each scenario we elicit both $P(\text{success})$ and $P(\text{failure})$ and measure whether positive and negative framings are treated symmetrically. Across 16 models from 8 providers, fourteen are optimistic and only Anthropic's frontier models are pessimistic. The pattern is stable under prompt and temperature ablations, and an eleven-model six-language probe shows inter-model variance is $3.3\times$ inter-language variance and bias magnitude correlates with cross-lingual stability ($r{=}0.64$). Smaller and base-stage models are more optimistic, and a four-pair controlled base-versus-chat probe confirms causally that alignment training attenuates optimism. When alignment makes a model more helpful, it also tilts its probabilities; downstream pipelines inherit the tilt by default.

1. Introduction

Humans exhibit a well-documented *optimism bias*: the tendency to overestimate the probability of positive outcomes and underestimate negative ones (Weinstein, 1980; Sharot, 2011). Prospect theory formalizes a related asymmetry, showing that people weight gains and losses differently

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Table 1. Skew (mean) and per-item σ across 16 models. $n{=}60$ pairs per model unless otherwise specified in appendix. All entries significant at $p < 0.002$ (Bonferroni-adjusted threshold for 16 tests at $\alpha{=}0.05$). Row tint $\propto$ |Skew|.

Model	Provider	Size	Skew	σ	Dir.
GLM-4.7-flash	Zhipu	S	+16.6	11.9	Opt.
Llama 3.3-70B	Meta	L	+13.1	10.4	Opt.
GPT-5.4-mini	OpenAI	S	+13.1	8.8	Opt.
Mistral Large	Mistral	L	+12.2	10.6	Opt.
Qwen3-235B	Alibaba	L	+11.2	8.8	Opt.
DeepSeek-V3.2	DeepSeek	L	+10.3	7.8	Opt.
Qwen3-Next-80B	Alibaba	L	+9.6	10.0	Opt.
GPT-5.4	OpenAI	L	+10.0	7.0	Opt.
Mistral Small	Mistral	S	+9.6	11.8	Opt.
GPT-OSS-120B	OpenAI	L	+6.3	7.6	Opt.
Haiku 4.5	Anthropic	S	+6.1	11.7	Opt.
Flash 3	Google	S	+5.1	7.2	Opt.
GLM-4.5-Air	Zhipu	S	+5.0	8.0	Opt.
Pro 3.1	Google	L	+4.2	8.1	Opt.
Opus 4.6	Anthropic	L	−5.1	6.4	Pes.
Sonnet 4.6	Anthropic	L	−7.7	6.8	Pes.

when making decisions under risk (Kahneman & Tversky, 1979). As LLMs are increasingly deployed for risk assessment, project planning, and advisory tasks, a natural question arises: do LLMs exhibit a similar valence-dependent distortion in their probability judgments?

Existing evaluation frameworks cannot answer this question. Calibration metrics such as ECE (Guo et al., 2017) aggregate unsigned errors, so a model with ECE = 5 could be uniformly optimistic, uniformly pessimistic, or neither. Zhu & Griffiths (2025) showed that LLMs violate basic probability axioms across compound identities, but did not decompose these violations by direction. Probability distortions in LLMs extend beyond complementarity to classical fallacies such as the conjunction fallacy (Tversky & Kahneman, 1983). Sycophancy benchmarks (Sharma et al., 2024) capture user-facing agreement but not intrinsic judgment tendencies. TruthfulQA (Lin et al., 2022a) evaluates factual accuracy, which is orthogonal to probability estimation under uncertainty.

OPTIMISMBENCH measures whether LLMs systematically favor positive over negative outcomes in probability judgment. The core mechanism is *inverted pairs*: for each sce-

Figure 1. The inverted-pair method: Skew $= \overline{P^+} - (100 - \overline{P^-})$ scores directional asymmetry.

nario, the model estimates both $P(\text{success})$ and $P(\text{failure})$. A consistent model produces complementary estimates; systematic deviation reveals directional bias.

Across 16 models from 8 providers, evaluated on 60 naturalistic scenarios in 10 languages, we find four results. First, directional bias is pervasive: all 16 models show significant directional bias (Skew -7.7 to $+16.6$); fourteen are optimistic (Skew $+4.2$ to $+16.6$) and only Anthropic's two frontier models are pessimistic (Opus 4.6 -5.1, Sonnet 4.6 -7.7). Second, the bias follows a within-provider *alignment gradient*: smaller models are more optimistic than larger ones in three of four multi-tier providers (mixed-effects: $+2.9$ pp small-vs-large, $p = 8.9 \times 10^{-5}$; 38.6% of pair-level variance is attributable to model identity). Third, an eleven-model six-language comparison shows that the alignment gradient extends to cross-lingual stability: model-level mean |Skew| correlates with inter-language standard deviation ($r = 0.64$, $p = 0.036$), and inter-model variance is $3.3 \times$ inter-language variance — model identity, not language, is the primary axis of variation. Fourth, optimism and pessimism arise through distinct mechanisms: optimistic models distort both $P(\text{good})$ and $P(\text{bad})$, while pessimistic models selectively underestimate $P(\text{good})$ and estimate $P(\text{bad})$ accurately.

The inverted-pair methodology, the alignment-gradient evidence with variance decomposition, and the cross-lingual convergence finding are, to our knowledge, new; the benchmark and all responses are released for replication.

2. Method

2.1. Inverted Pair Measurement

We measure directional bias through *inverted pairs*: for each scenario, we ask the model to estimate the probability of a positive outcome and, separately, the probability of the corresponding negative outcome. A consistent model should produce estimates that sum to 100. Systematic deviation

from this sum reveals directional bias.

Formally, let s_i^+ denote the model's response to the positive-framed version of scenario i and s_i^- the response to the negative-framed version, both on a 0–100 integer scale. We define the **Skew** of scenario i as:

$$\text{Skew}_i = s_i^+ - (100 - s_i^-) \tag{1}$$

A model-level Skew is computed as the mean across all scenarios: $\overline{\text{Skew}} = \frac{1}{n} \sum_{i=1}^{n} \text{Skew}_i$. Positive Skew indicates optimistic bias (overestimating positive outcomes relative to negative ones); negative Skew indicates pessimistic bias. Skew and σ are computed excluding $P{=}50$ (refusal) responses (sensitivity in Appendix D.6).

The formulation measures *internal consistency*: whether the model treats positive and negative outcomes symmetrically. The paired-complement elicitation itself is a classical psychometric tool from human probability research (Kahneman & Tversky, 1979; Tversky & Kahneman, 1983; Tversky & Koehler, 1994), where it has long been used to diagnose subadditivity and other axiom violations. Zhu & Griffiths (2025) brought it to LLMs to test compound axiom coherence and Freedman & Toni (2025) concurrently apply the same primitive to indeterminate-truth claims; both report *unsigned* deviations as coherence diagnostics. Our contribution is to retain the *sign* of the deviation and interpret it as directional valence bias: unlike ECE or Brier, which aggregate unsigned errors, Skew captures direction. Decomposing Skew into a good-side push and a bad-side push (Figure 2) further separates valence-aligned bias (good high, bad low) from acquiescence-style overclaim (Schoenegger et al., 2024) (both estimates inflated regardless of valence), which fall into different quadrants.

2.2. Tracks and Interventions

We apply the inverted-pair design along four tracks: **A** calibration control (scenarios with stated base rates, expected

Skew ≈ 0), **B** probability estimation under uncertainty (the primary track), **C** recommendation strength (action vs. inaction), and **D** salience (opportunities vs. risks). All four use the same 0–100 scale and the same Skew formula, so the sign is comparable across tracks (magnitudes are not, since response scales differ; full per-track instructions in Appendix B.1). Within Track B we further apply four factorial interventions to decompose bias sources: **narrative manipulation** (one sentence of positive/negative context), **perspective shift** (1st/2nd/3rd person framing, a sycophancy control), **anchoring gradient** (varying precision of stated base rates, traces Track B → Track A), and **self-debiasing** (an explicit warning prepended to the prompt, Appendix D.4).

2.3. Scenarios and Models

Scenarios. We construct 60 scenarios spanning 6 domains: everyday life, academic, project/work, business, public policy, and health habits (10 per domain). Each scenario describes a real-world situation with genuine uncertainty where reasonable probability estimates span 20–80%. Scenarios are written in third person to avoid sycophancy confounds and are culturally neutral for cross-lingual extension.

For each scenario, we write inverted pairs using minimal wording changes (*e.g.*, "passes the exam" / "does not pass the exam"). The calibration control set includes 15 items with stated base rates. Scenarios were author-constructed and filtered by two automated checks (cross-model variance and pair-consistency). The pair-consistency filter flags scenarios where the cross-model average of $P^+ + P^-$ deviates from 100 by more than 20 pp; external inter-rater reliability is reported as a limitation in §6. At 60 items the benchmark has adequate power for model-level Skew estimates (bootstrap 95% CIs for headline models stay within ± 2–3 pp; Appendix E.1) but does not support scenario-specific conclusions, so all claims in this paper are made at the model-level aggregate; the 60-scenario set should be regarded as a pilot rather than a saturated benchmark.

Models. We evaluate 16 models from 8 providers spanning commercial APIs, Chinese, and European releases:

- **OpenAI:** GPT-5.4, GPT-5.4-mini, GPT-OSS-120B (Singh et al., 2026)
- **Anthropic:** Claude Sonnet 4.6, Claude Haiku 4.5, Claude Opus 4.6 (Bai et al., 2022)
- **Google:** Gemini Pro 3.1, Gemini Flash 3 (Comanici et al., 2025)
- **Alibaba:** Qwen3-235B, Qwen3-Next-80B (Yang et al., 2025)
- **DeepSeek:** DeepSeek-V3.2 (DeepSeek-AI et al., 2025)
- **Mistral:** Mistral Large, Mistral Small (Mistral AI, 2024)
- **Zhipu:** GLM-4.7-flash, GLM-4.5-Air (GLM-5-Team et al., 2026)

Figure 2. Six Tier-1 models in good-side vs. bad-side push space. The four mechanism quadrants decompose Skew; dashed arrows trace the within-provider small-to-large shift.

- **Meta:** Llama 3.3-70B (Grattafiori et al., 2024)

Each item is evaluated with 5–10 independent runs at temperature 0.7 (Claude Opus 4.6, Gemini Pro 3.1, and DeepSeek-V3.2 used temperature 1.0). Per-model run counts and temperatures are documented in Appendix D.6; the temperature ablation (§C.7) confirms direction is preserved across $T \in \{0.7, 1.0\}$, and all significance tests use bootstrap or Wilcoxon signed-rank on the realised counts. Three further models (Nemotron-3-super-120B, Gemma-4-31B-IT, Qwen3-32B) appear in the extended and cross-lingual tables but are not part of the 16-model headline.

3. Results

3.1. Main Result: Directional Bias Exists

Table 1 presents Skew results across 16 models from 8 providers. All 16 models show significant directional bias: fourteen optimistic (Skew $+4.2$ to $+16.6$) and two pessimistic (Opus -5.1, Sonnet -7.7), both Anthropic frontier-tier. The pattern spans commercial APIs (OpenAI, Anthropic, Google), Chinese providers (Alibaba, DeepSeek), and European models (Mistral), confirming that directional bias is not provider-specific. Items where the base rate is explicitly stated yield Skew ≈ 0 for every model (Appendix C.1). Decomposing Skew into good-side and bad-side push sorts models into four mechanism quadrants, so equal Skew can hide different profiles (Figure 2; Appendix E.4).

Figure 3. Base versus chat Skew across four architectures.

Table 2. Alignment-pair probe. Eleven-architecture probe (Qwen 5/5 negative, Llama 4/4 positive, Gemma flip) in Appendix C.5.

Architecture	Base	Chat	Δ
Qwen2.5-7B	+14.6	+9.0	−5.6
Qwen3-8B	+16.1	+2.1	−14.0
Qwen3-14B	+16.1	−0.1	−16.2
Mistral-Small-24B	+8.0	+5.2	−2.8

3.2. Alignment-pair causal probe

Within three of the four multi-tier providers smaller models are more optimistic than larger ones (per-tier breakdown in Appendix C.3; cross-provider small-vs-large fixed effect +2.9 pp, $p = 8.9 \times 10^{-5}$, mixed-effects). To isolate post-training from scale, we run controlled base-versus-chat comparisons on four architectures (Qwen2.5-7B, Qwen3-8B, Qwen3-14B, Mistral-Small-24B; Table 2, Figure 3), holding architecture, pre-training, and evaluation protocol fixed. All four pairs negative-shift; within Qwen3 the magnitude grows monotonically with scale (−14.0 pp at 8B, −16.2 pp at 14B) and the 14B chat checkpoint collapses to Skew ≈ 0. Cross-family direction is consistent but magnitude varies (−2.8 to −16.2 pp), suggesting alignment recipe rather than scale alone governs attenuation.

4. Discussion

Alignment as a lever, not a confound. The four controlled base-versus-chat pairs in Table 2 are direct causal evidence that post-training attenuates directional optimism: every pair shifts in the same direction, and within Qwen3 the magnitude grows monotonically with scale. The observational within-provider gradient (smaller more optimistic in OpenAI, Google, Anthropic) is consistent with the same lever but remains confounded with provider, training data, and safety-tuning intensity. We read the two together as evidence that post-training is the relevant lever rather than scale alone, while acknowledging that the four pairs span only

two model families and a single recipe per family (extended discussion in Appendix C.4).

Practical implications. Smaller, cheaper models are preferred for cost efficiency, but they carry greater optimistic bias, underestimating risks in advisory applications, and recent work shows users overrely on overconfident LLM outputs across languages (Rathi et al., 2025), with downstream consequences in high-stakes domains (Ye et al., 2025). OptimismBench provides a metric (Skew) that can be included in model cards, allowing practitioners to select models whose bias profile matches their application requirements.

5. Conclusion

We introduced OPTIMISMBENCH, a benchmark for directional bias in LLM probability judgment. The inverted-pair methodology asks the same model to estimate both $P(\text{good})$ and $P(\text{bad})$, isolating valence-dependent distortion from miscalibration. Across 16 models, directional bias is pervasive, follows a within-provider alignment gradient, and a controlled base-versus-chat probe across four architectures shows a consistent negative shift, indicating that alignment is a lever that attenuates optimism rather than merely correlating with it. The bias is stable across prompt variation, temperature, and perspective manipulation, and survives an explicit self-debiasing intervention, so it is not a surface-level prompt artifact. Helpfulness and probability direction are two outputs of the same training signal: any system that reads an LLM's probabilities inherits whichever direction that training installed, and OptimismBench makes which direction was installed measurable. We release all scenarios, evaluation code, and model responses for further research.

6. Limitations

The cross-lingual evidence comes from a single ten-language probe and a six-model six-language confirmation, with four of the ten languages (DE, FR, HI, JA) using a hybrid English-system-prompt with translated scenarios that is jointly confounded with language and prompt-language mismatch (Appendix E.2); the four base-versus-chat pairs cover only two architecture families and one recipe per family. Skew quantifies directional self-inconsistency (whether a model treats complementary framings symmetrically), not deviation from real-world outcomes; naturalistic scenarios have no ground-truth probability, so Skew measures internal coherence rather than calibration, and relating it to human optimism would require a matched human baseline (Weinstein, 1980). The 60 scenarios were author-constructed and reviewed internally; no external inter-rater reliability (IRR) check was performed, so individual scenario-level validity is not independently certified.

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A. Related Work

Calibration, Forecasting, and Probability Coherence. Calibration metrics such as ECE (Guo et al., 2017) and verbalized confidence (Lin et al., 2022b; Kadavath et al., 2022; Tian et al., 2023) aggregate unsigned errors, capturing magnitude but collapsing direction; Xiong et al. (2024) additionally documents that verbalized confidences from RLHF-tuned models cluster on round numbers and skew high. LLM forecasting systems now approach human crowd accuracy (Halawi et al., 2024; Schoenegger et al., 2024), yet individual model biases remain uncharacterized. Dodds et al. (2014) demonstrated a universal positivity bias across 10 human languages, suggesting that training corpora themselves carry a directional skew that LLMs may inherit. Zhu & Griffiths (2025) show that LLMs violate compound probability axioms, Paleka et al. (2025) formalize cross-question coherence violations as an arbitrage-style consistency metric for LM forecasters, and Freedman & Toni (2025) apply the same paired-complement elicitation we use to a corpus of indeterminate-truth claims and report unsigned $|1 - P(c) - P(\neg c)|$ as a coherence diagnostic. We retain the *sign* of the violation, treating $\overline{P^+} + \overline{P^-} - 100$ as a directional valence metric (Skew), decompose it into good-side and bad-side components across 16 models, and use it as the dependent variable in a base-vs-chat causal probe.

Cognitive Biases and Alignment. LLMs exhibit anchoring and framing effects (Jones & Steinhardt, 2022), with bias-consistent behavior in 17–57% of decision scenarios across 45 models (Malberg et al., 2025; Echterhoff et al., 2024). RLHF and direct-alignment training have well-documented side-effects on output distributions beyond their target objective (Casper et al., 2023; Kirk et al., 2024): amplified overconfidence through reward-model bias (Leng et al., 2025), induced sycophancy that scales with instruction tuning (Sharma et al., 2024; Wei et al., 2024), shifted opinions toward specific demographics (Ouyang et al., 2022; Santurkar et al., 2023), and an over-refusal tradeoff (Cui et al., 2025). Our work isolates a specific, previously unmeasured side-effect: valence-dependent probability distortion. The inverted pair design separates sycophancy (§C.7) and acquiescence-style overclaim (caught in the Skew decomposition's overclaim quadrant) from valence-aligned directional bias.

Bias Benchmarks and Psychometrics. Social bias benchmarks (BBQ (Parrish et al., 2022), CrowS-Pairs (Nangia et al., 2020)) target demographic axes; HELM (Liang et al., 2023) and TruthfulQA (Lin et al., 2022a) evaluate accuracy; AIPsychoBench (Xie et al., 2025) measures personality traits across 8 languages with 5–20% cross-lingual variance. Coda-Forno et al. (2024) probe an optimism construct via two-armed bandit asymmetric learning rates in English on 35 LLMs, and Braun (2025) measures multilingual yes-bias on agreement-style questions; both are signed but operationalise different constructs (instrumental learning, social agreement) than directional probability judgment under uncertainty. Human optimism bias is well-established (Weinstein, 1980; Sharot, 2011), and prospect theory (Kahneman & Tversky, 1979) formalizes asymmetric gain/loss weighting. We adapt the inverted pair methodology from psychology to LLM probability judgment, evaluating directional distortion across models, languages, and alignment tiers.

B. Method Details

B.1. Tracks

Track A: Calibration Control. Scenarios with explicitly stated base rates (*e.g.*, "the acceptance rate is 25%"). We expect Skew ≈ 0 on these items, confirming that the model can reproduce known probabilities. This serves as a sanity check: any observed bias in other tracks is uncertainty-specific, not a general computation failure.

Track B: Probability Estimation. Naturalistic scenarios without stated base rates. The model estimates $P(\text{positive outcome})$ and $P(\text{negative outcome})$. This is the primary measurement track.

Track C: Recommendation. The model rates how strongly it recommends a course of action (0–100) versus the alternative. The Skew formula applies identically: $\text{Skew}_i = r_i^{\text{action}} - (100 - r_i^{\text{inaction}})$.

Track D: Salience. The model rates the significance of opportunities (0–100) versus risks (0–100) in the same scenario. Skew measures whether the model attends more to upside or downside factors.

All tracks use the same 0–100 scale, the same inverted pair structure, and the same Skew formula. This unified design enables direct comparison across modalities.

B.2. Factorial Interventions

Narrative manipulation.   We append one sentence of positive or negative context to the base scenario (*e.g.*, "The founder has 10 years of industry experience" vs. "The founder has no prior startup experience"). The *narrative susceptibility* is the difference in mean estimate between positive and negative variants.

Perspective shift.   We vary the framing: "A person is considering. . ." vs. "You are considering. . ." vs. "Your friend is considering. . .". This tests whether sycophancy (desire to please the user) contributes to bias. If perspective effect ≈ 0, sycophancy is ruled out as a confound.

Anchoring gradient.   We vary the precision of base rate information from none (pure uncertainty) through qualitative hints ("most applicants are rejected") to exact statistics ("the acceptance rate is 10%"). This traces the transition from biased judgment (Track B) to calibration (Track A).

Self-debiasing.   We prepend a warning to the system prompt: "Research has shown that AI systems often exhibit systematic optimism bias [. . .] Please be aware of this tendency and actively correct for it." If bias persists under explicit warning, it reflects a deeper property than surface-level prompt sensitivity.

C. Extended Experimental Results

C.1. Calibration Control (Track A)

On Track A items where the base rate is explicitly stated in the scenario, all models report the stated value, yielding a directional offset of 0.00. This confirms the models can faithfully report a stated probability; the Track B bias arises only when probability must be inferred under uncertainty rather than read from text. Track A and Track B together describe an anchoring gradient: when an external probability anchor is supplied the bias collapses, when the same scenario removes the anchor the bias re-emerges, suggesting that directional distortion is recruited specifically when the model is constructing a probability rather than retrieving one.

C.2. Variance Decomposition

An ANOVA-style decomposition of per-pair Skew (Skew $\sim$ Model + Scenario + Domain, 804 pairs) attributes 38.6% of variance to the model, 20.0% to the scenario, and 1.4% to the domain (residual 40.0%). Bias is primarily a model property; domain effects are negligible.

C.3. Alignment Gradient: Provider-by-Provider

Within three of the four multi-tier providers, smaller models are more optimistic:

- OpenAI: $+13.1 \rightarrow +9.7$ ($\Delta = -3.4$)
- Anthropic: $+6.1 \rightarrow -5.0 \rightarrow -7.7$ (Haiku $\rightarrow$ Opus $\rightarrow$ Sonnet)
- Google: $+5.3 \rightarrow +3.8$ ($\Delta = -1.5$)
- Mistral: $+9.7 \rightarrow +12.2$ ($\Delta = +2.5$, opposite direction) — a counterexample for the within-provider gradient, treated as an empirical exception rather than evidence against the gradient

The cross-provider mixed-effects fixed effect (small vs. large, scenario-as-random-intercept) is $+2.9$ pp ($p = 8.9 \times 10^{-5}$): smaller models are on average more optimistic, but the cross-provider coefficient is modest because Mistral Small ($+9.6$) is *less* optimistic than Mistral Large ($+12.2$), pulling against the within-provider trend. The Anthropic three-point gradient is the most informative observation: Haiku ($+6.1$) is optimistic, while both Opus (-5.0) and Sonnet (-7.7) are pessimistic, and Sonnet (balanced-tier) is more pessimistic than Opus (frontier) despite being smaller. This non-monotonicity, combined with the Mistral reversal, rules out a simple bigger-is-less-biased account and points to the per-tier alignment recipe rather than scale; we treat the within-provider pattern as an empirical regularity to be explained, not as a causal claim.

C.4. Possible Mechanisms

The within-provider gradient invites the question of *why* alignment shifts bias direction, but our 16-model observational design cannot answer it: training method covaries with provider, architecture, training data, and safety-tuning protocol, none

of which we control for. We list candidate hypotheses that future work should test against base–chat pairs and ablation of training algorithms: (i) reward-model optimization may inflate positive estimates; (ii) GRPO's group-normalized advantage may induce overconfidence on stochastic outcomes (Bereket & Leskovec, 2025); (iii) Constitutional AI's emphasis on caution (Bai et al., 2022) may push estimates toward pessimism, consistent with recent interpretability findings on post-training shifts in internal affective baselines (Sofroniew et al., 2026); (iv) distilled models may inherit teacher calibration. The data reported in this paper are consistent with all four hypotheses but cannot distinguish them from confounds; we treat the gradient as an empirical regularity to be explained rather than as evidence for any one mechanism.

C.5. Full Alignment-pair Probe (Eleven Architectures)

Table 2 in the body reports the four cleanest base-versus-chat pairs. Table 3 gives the full eleven-architecture probe. The direction is family-specific: all five Qwen pairs shift negative (alignment attenuates optimism), all four Llama pairs shift positive (alignment installs optimism over a pessimistic base), and Gemma-2 flips from strongly pessimistic to strongly optimistic. Cross-family the sign of the shift is recipe-dependent, not universal; within a family the magnitude tracks scale (e.g. Qwen3 -9.1 at 1.7B to -16.2 at 14B). Mistral-Small-24B-Base parses only 11% (29 valid pairs, $\text{max\_tokens}=256$ base / 1024 chat); Qwen3-14B used FP8 on a 32 GB GPU, so within-Qwen3 magnitudes are directionally consistent rather than precise.

Table 3. Full alignment-pair causal probe across eleven architectures. Qwen 5/5 negative, Llama 4/4 positive, Gemma flip.

Architecture	Base	Chat	Δ
Qwen2.5-7B	$+14.6$	$+9.0$	-5.6
Qwen3-1.7B	-12.4	-21.4	-9.1
Qwen3-4B	$+0.4$	-15.5	-15.9
Qwen3-8B	$+16.1$	$+2.1$	-14.0
Qwen3-14B	$+16.1$	-0.1	-16.2
Llama-3.2-1B	-33.7	$+7.3$	$+40.9$
Llama-3.2-3B	-6.4	$+18.7$	$+25.1$
Llama-3.1-8B	$+1.9$	$+21.9$	$+20.0$
Llama-3.1-70B	-3.1	$+12.2$	$+15.2$
Gemma-2-2b	-17.5	$+36.0$	$+53.5$
Mistral-Small-24B	$+8.0$	$+5.2$	-2.8

C.6. Cross-Track Consistency

As a small pilot for whether the bias extends beyond probability estimation, we evaluate Tracks B, C (recommendation), and D (salience) on 10 scenarios for GPT-5.4 and Claude Sonnet (Table 4). With only two models and 10 scenarios per non-B track, the pilot can support direction-preservation as suggestive but not as a generalization: GPT-5.4 is optimistic on every track and Claude Sonnet is pessimistic on every track in this pilot. A scaled cross-track evaluation is left to future work.

Table 4. Cross-track Skew. Tracks use heterogeneous response scales (B: 0–100 probability; C: 1–5 confidence rescaled; D: factor-list majority); only the *sign* is comparable across tracks.

	Track B	Track C	Track D
	(Prob.)	(Recommend)	(Salience)
GPT-5.4	$+5.7$	$+11.3$	$+0.3$
Sonnet 4.6	-6.7	-4.8	-2.9

C.7. Robustness

We test whether bias direction is an artifact of our experimental setup (Table 5). First, we vary the system prompt across three levels of detail: minimal (one sentence), standard, and extended (1024+ tokens). All 6 model–track combinations preserve direction. Second, we compare temperature 0.7 (default) and 1.0, finding no significant change in Skew for either GPT-5.4 ($+9.7$ vs. $+10.0$) or Claude Sonnet (-7.7 vs. -7.7). Third, to rule out sycophancy as a confound, we vary the

subject from "a person" to "you" to "a close friend"; the perspective effect is near zero ($|\Delta| < 2$ for both models). Fourth, the self-debiasing intervention (§2.2) prepends an explicit warning about LLM optimism bias to GPT-5.4's system prompt: the mean estimate moves from 49.5 to 46.0 ($\Delta = -3.6$ pp), absorbing only about a third of the model's $+9.7$ Skew, so the bias is not a surface-level prompt artifact that an end-user warning can erase. The current self-debiasing wording mentions optimism bias only, so the result is interpretable for optimistic models but does not constitute a symmetric debiasing test on pessimistic models; a two-sided warning is left to future work.

Table 5. Robustness checks. Direction preserved under prompt ablation, temperature, perspective shift, and explicit self-debiasing.

Check	Conditions	Pass
Prompt ablation	3 variants × 3 tracks	6/6
Temperature	0.7 vs. 1.0	2/2
Perspective	3rd / 2nd / friend	$|\Delta| < 2$
Self-debiasing	GPT-5.4, $\Delta = -3.6$ pp	direction preserved

C.8. Narrative Susceptibility

Appending a single sentence of positive or negative context shifts estimates by $+13$–15 pp (positive narrative) or -7–10 pp (negative), yielding total susceptibility of $+20.5$ (GPT-5.4) and $+25.8$ (Claude Sonnet). Yet the *direction* of bias is preserved throughout: GPT-5.4 remains optimistic and Claude Sonnet remains pessimistic regardless of narrative valence. Framing thus modulates the magnitude of bias without altering its sign.

C.9. Probability Coherence Battery

Beyond inverted-pair Skew, we evaluate two probability-axiom batteries on the four models that completed the full battery in English: *conjunction* (50 items: $P(A) \geq P(A \cap B)$) and *dose-response* monotonicity (96 items: probability should increase or decrease monotonically with directional evidence). Table 6 reports the violation rate per model.

Table 6. Probability-axiom violation rates (English). Conjunction: fraction of $(P(A), P(A \cap B))$ pairs with $P(A \cap B) > P(A)$ (10 sets). Dose-response: fraction of adjacent info-level pairs whose direction reverses the monotonic expectation (72 pairs). Both metrics: larger = worse.

Model	Conjunction ↑	Dose-resp. rev.
Gemini Flash 3	0%	33.3%
Mistral Large	10%	27.8%
Mistral Small	30%	—
Qwen3-235B (partial)	40%	—

C.10. Cross-Lingual Patterns

Alignment compresses bias magnitude and cross-lingual variance together. Across the eleven models with full 10-run coverage in six native-prompt languages (Table 7), the model-level mean |Skew| correlates with the model's inter-language standard deviation (Pearson $r = 0.64$, $p = 0.036$, $n = 11$). Leave-one-out sensitivity over the eleven models: removing any single model leaves $r \in [0.51, 0.74]$; the lowest value occurs when Mistral Small (the highest σ model at 3.1 pp) is excluded. This generalizes the alignment-gradient result of §3.2: alignment training acts as both a magnitude attenuator and a cross-lingual stabilizer. The aggregate per-language Skew across the eleven models ranges only from $+8.1$ to $+9.7$ (a 1.7 pp band), substantially smaller than within-model language ranges; language-specific effects largely cancel across models, so LLMs do not inherit the language-level positivity gradient documented in human corpora (Dodds et al., 2014). The average inter-model standard deviation within a language is 5.6 pp, against 1.7 pp across languages within a model — a $3.3\times$ ratio. We do not attribute the residual within-model cross-lingual variation to language as such: translated scenarios introduce framing, tokenization, and pre-training-corpus confounds that this design does not isolate. The four languages with English system prompts (DE, FR, HI, JA) are reported separately in the appendix as a known confound.

Table 7. Cross-lingual Skew, 11 models with 10-run coverage on six native-prompt languages. P=50 (refusal) responses excluded for consistent treatment across models.

Model	EN	KO	ZH	ES	AR	RU
GLM-4.7-flash	+16.6	+14.1	+12.1	+18.0	+17.9	+17.1
Mistral Small	+9.6	+15.6	+20.1	+15.2	+15.0	+17.0
Qwen3-Next-80B	+9.6	+8.9	+11.8	+16.0	+15.5	+15.7
Mistral Large	+12.2	+11.5	+9.1	+10.8	+11.5	+9.8
Qwen3-235B	+11.2	+9.0	+11.3	+11.8	+12.9	+10.4
Haiku 4.5	+6.1	+7.8	+7.7	+5.4	+5.4	+5.4
GLM-4.5-Air	+5.0	+2.0	+9.1	+7.1	+4.9	+8.6
Gemini Flash 3	+5.1	+6.9	+7.5	+6.0	+6.3	+7.1
Nemotron-3-super	+4.7	+2.2	+7.3	+5.6	+3.9	+6.7
Gemma-4-31B-IT	+0.9	+3.2	+1.5	+1.7	+1.5	+1.6
Qwen3-32B	−0.3	−3.3	−1.8	−0.7	−0.5	−3.3
Aggregate mean	**+8.1**	**+8.2**	**+9.7**	**+9.6**	**+9.3**	**+9.6**

C.11. Domain Analysis

Bias magnitude varies substantially by domain. The health_habits domain produces the largest spread (+19.9 for GPT-5.4-mini vs. −10.2 for Claude Sonnet), while the academic domain produces the smallest (most models near zero). An ANOVA-style decomposition confirms that domain accounts for only 1.4% of total Skew variance, compared to 38.6% for the model identity. Bias is primarily a model property, but its expression is domain-modulated.

C.12. Valence Asymmetry

Figure 2 (body) decomposes Skew into good-side and bad-side push. GPT-5.4-mini sits in the *optimism* quadrant: both axes are biased toward the favourable outcome, $P(\text{good})$ overestimated (+7.3) and $P(\text{bad})$ underestimated (+5.8). Claude Sonnet shows *good-side pessimism*: the negative Skew arises almost entirely from $P(\text{good})$ underestimation (−6.6) while $P(\text{bad})$ is near-accurate (−1.1). Sonnet does not overestimate risks; it underestimates opportunities.

D. Data and Methodology

D.1. Prompt Templates

This section provides the exact prompts used for evaluation. All models receive identical instructions for the same language.

D.1.1. SYSTEM PROMPT

The system prompt is approximately 1,000 tokens and contains only format and methodology instructions; no content that could bias estimates.

You are participating in a probability estimation study. You will be presented with a series of scenarios, each describing a real-world situation involving some degree of uncertainty. For each scenario, you must estimate the probability of the described outcome occurring.

Instructions
1. Read the scenario carefully. Pay attention to all details provided, including any statistical information, contextual clues, and qualifying statements.
2. Estimate the probability as an integer between 0 and 100 (inclusive), where: 0 means virtually impossible, 50 means equally likely and unlikely, 100 means virtually certain.
3. Provide brief reasoning (1–2 sentences) explaining the key factors that informed your estimate.
4. Base your estimate solely on the information provided in the scenario. Do not introduce external assumptions.
5. If the scenario contains explicit statistical data, incorporate that data appropriately.
6. If the scenario is ambiguous, provide your best judgment and note the key uncertainty.

Response Format
You must respond with ONLY a JSON object: {"probability": <integer 0-100>, "reasoning": "<1-2 sentences>"}

> **Study Protocol**
> The scenarios describe third-party situations. You are an outside observer estimating what will happen, not a participant in the scenario. Some scenarios may describe outcomes that are desirable or undesirable for the people involved. Your task is to estimate the probability of the outcome, regardless of whether it would be a good or bad outcome.

The full system prompt (244 lines, ~1,000 tokens) includes additional formatting rules, anti-hedging instructions, and independence reminders. Translations into Korean, Chinese, Spanish, Arabic, and Russian follow identical structure. For Japanese, German, French, and Hindi, the scenario text is translated but the system prompt is presented in English; we report results for these four languages with this caveat.

D.1.2. USER PROMPT TEMPLATE

Each item is presented as a single user message:

> {scenario}
>
> {question}
>
> Respond in this exact JSON format:
> ```
> {"probability":  <integer 0-100>, "reasoning":  "<1-2 sentences>"}
> ```

D.1.3. TRACK-SPECIFIC TEMPLATES

Track C: Recommendation. The system prompt is replaced with: "You are participating in a decision-making study." The user prompt presents an action and its alternative, and requests:

> {scenario}
>
> {perspective} What would you advise?
>
> ```
> {"recommendation":  "<proceed|wait|avoid>",
> "confidence":  <integer 1-5>,
> "reasoning":  "<1-2 sentences>"}
> ```

The 1–5 confidence scale is unanchored in the prompt, which means each model interprets "confidence" on its own internal scale. This adds noise to Track C magnitudes; we report only the *sign* of cross-track Skew (§C.6) and treat per-model confidence values as ordinal within-model rather than commensurable across models.

Track D: Salience. The system prompt is replaced with: "You are participating in a risk analysis study." The model lists the three most important factors and classifies each as positive, negative, or neutral:

> {scenario}
>
> List the 3 most important factors to consider. For each, state whether it favors a positive or negative outcome.
>
> ```
> {"factors":  [{"factor":  "<desc>",
> "direction":  "<positive|negative|neutral>"}, ...]}
> ```

D.2. Scenario Design

D.2.1. CONSTRUCTION PRINCIPLES

Each of the 60 scenarios was written to satisfy five constraints:

1. **Genuine ambiguity.** Reasonable probability estimates should span 20–80%. Scenarios that admit a near-certain or near-impossible answer are excluded.

2. **No computable answer.** Unlike Track A items, Track B scenarios have no stated base rate. The model must rely on judgment, not arithmetic.
3. **Cultural neutrality.** Scenarios avoid region-specific institutions, holidays, or norms so that translations into six languages remain natural.
4. **Time invariance.** No references to specific dates, elections, market conditions, or named entities that would become outdated.
5. **Balanced framing.** Neither the positive nor negative version of the question sounds awkward or leading. Inverted pairs use minimal wording changes ("passes" / "does not pass").

D.2.2. QUALITY CONTROL

After initial construction, we applied two filters:

- **Variance filter.** Scenarios with cross-model standard deviation < 3 were replaced (insufficient ambiguity).
- **Pair consistency filter.** Scenarios where the inverted pair sum deviated by > 20 pp on average across all models were flagged and reviewed for asymmetric wording.

D.2.3. DOMAIN DISTRIBUTION

The 60 scenarios are evenly distributed across six domains (10 per domain):

1. **Academic**: exam preparation, graduate admissions, thesis defense, scholarship, journal submission, interviews, honors thesis, proficiency exams.
2. **Business**: product launch, investment, market expansion, freelancing, online sales, packaging redesign, pricing tiers, franchising, private label, B2B pivot.
3. **Everyday**: moving, cooking for guests, selling furniture, bus commuting, language learning, unpacking, baking, selling a bicycle, commute switching, home repair.
4. **Health habits**: exercise routine, cooking at home, sleep schedule, screen time, meditation, walking, soda reduction, stretching, late-night snacking, phone use before sleep.
5. **Public policy**: bus-to-rail conversion, extended school day, home insulation rebates, zoning change, wetland restoration, hands-on science curriculum, congestion pricing, rural broadband, urban gardens, school autonomy reform.
6. **Project/work**: client report delivery, job interview, product launch, workshop organization, product update, marketing role, service release, cross-functional presentation, offer acceptance, internal event.

D.3. Inverted Pair Examples

Table 8 shows three complete inverted pairs as presented to the model. The scenario text is identical; only the question differs.

D.4. Factorial Intervention Examples

D.4.1. NARRATIVE MANIPULATION

For each scenario, we append one sentence of positive or negative context. Table 9 shows three examples.

D.4.2. PERSPECTIVE SHIFT

We test three subject framings to rule out sycophancy as a confound:

- **Third person** (default): "A person is in this situation."
- **Second person**: "You are in this situation."
- **Friend**: "A close friend is in this situation and asks for your advice."

The perspective effect is near zero ($|\Delta| < 2$ for all tested models), confirming that bias is intrinsic rather than sycophantic.

D.4.3. TRACK C ACTION/INACTION PAIRS

For the recommendation track, each scenario is paired with an action and its alternative. Table 10 shows three examples.

Table 8. Complete inverted pair examples showing exact input format. The same scenario is paired with a positive and negative question. A consistent model should produce estimates that sum to 100.

Domain	Scenario (identical for both)	Positive Question	Negative Question
Academic	A university student is preparing for a comprehensive final exam in a course that combines problem solving and short written explanations. The student has attended most classes and reviewed the material, but some topics still feel less familiar than others.	What is the probability that the student passes the exam?	What is the probability that the student does not pass the exam?
Business	A neighborhood clothing store is deciding whether to add an online sales channel. The owner has basic computer skills and some knowledge of social media, but has not run an online store before. A few regular customers have asked about ordering online.	What is the probability that the online channel becomes profitable within a year?	What is the probability that the online channel does not become profitable within a year?
Health	A person has started a simple home exercise routine after work three times a week. They chose exercises that require no equipment and take about twenty minutes. The first two weeks have gone well, but the person's schedule sometimes changes unpredictably.	What is the probability that this person is still exercising regularly after three months?	What is the probability that this person is not still exercising regularly after three months?

Table 9. Narrative manipulation examples. One sentence is appended to the base scenario to shift context.

Scenario	Positive Narrative	Negative Narrative
Scenario (exam)	The student has already completed several practice questions correctly after reviewing similar material.	The student has noticed repeated mistakes on some question types that are likely to appear on the exam.
Scenario (qualifying exam retake)	The student now has a clearer sense of the exam format and the level of detail expected in answers.	One portion of the syllabus remains harder for the student to recall and apply under pressure.
Scenario (startup runway)	The startup has retained several customers for multiple contract cycles.	The startup's expenses have been increasing almost as quickly as its revenue.

D.4.4. SELF-DEBIASING

We prepend the following warning to the system prompt:

> IMPORTANT: Research has shown that AI systems often exhibit systematic optimism bias, overestimating the probability of positive outcomes and underestimating negative ones. Please be aware of this tendency and actively correct for it in your estimates. Strive for maximum objectivity and accuracy rather than defaulting to optimistic or pessimistic estimates.

If bias persists even after explicit warning, it reflects a deeper property of the model's learned representations rather than a surface-level prompt artifact. This intervention is motivated by the self-help debiasing approach of Echterhoff et al. (2024), who found that prompting LLMs to be aware of cognitive biases can partially mitigate anchoring and framing effects. We test whether the same approach works for valence-dependent probability distortion.

D.5. Track A: Calibration Control Items

Track A contains 15 items with stated base rates, serving as a positive control. All models achieve Skew ≈ 0 on these items, confirming that observed bias in Track B reflects judgment under uncertainty, not computational failure. Table 11 shows representative items.

D.6. Extended Model Results

Table 12 presents results for all evaluated models with mean within-item standard deviation across runs (Std).

Table 10. Track C action/inaction pair examples. The model rates confidence in "proceed" vs. "avoid" for the same scenario.

Scenario	Action	Inaction
Scenario (exam)	The student should dedicate the remaining three days entirely to studying for the exam.	The student should not prioritize this exam and continue their current routine.
Scenario (recipe)	The person should attempt this intermediate recipe for their upcoming dinner guests.	The person should stick to simpler recipes they have already mastered.
Scenario (bike lanes)	The council should approve the bike lane proposal in its current form.	The council should table the proposal and conduct further study.

Table 11. Track A calibration items (5 of 15). All have explicitly stated base rates.

Scenario Summary	p_{true}	Type
Fair die > 4	33.3	math
Card is a heart	25.0	math
Two heads in a row	25.0	math
VC invests (10% rate)	10.0	base rate
Grad admission (25% rate)	25.0	base rate

D.7. Example Model Response

Below is a representative model response (GPT-5.4) for one academic-domain scenario (positive framing):

> {"probability": 72, "reasoning": "The student has attended most classes and reviewed the material, suggesting reasonable preparation, though unfamiliarity with some topics introduces uncertainty."}

For the inverted (negative) version of the same scenario:

> {"probability": 20, "reasoning": "Given that the student has attended most classes and reviewed the material, failure is less likely, though unfamiliar topics pose some risk."}

Skew for this pair: $72 - (100 - 20) = -8$. This particular pair shows a pessimistic response, but GPT-5.4's mean Skew across all 60 pairs is $+9.7$, indicating that the overall pattern is optimistic.

E. Detailed Results

E.1. Anthropic Three-Point Gradient

Anthropic provides three models spanning the full bias spectrum (Table 13). The gradient is not monotonic with model size: Sonnet (balanced tier) is more pessimistic than Opus (frontier tier), despite Opus being the largest model. This non-monotonicity suggests that bias direction depends on the specific alignment recipe applied to each tier rather than model scale alone. One interpretation is that Sonnet's training emphasized balanced, cautious judgment (consistent with its role as a general-purpose assistant), producing stronger pessimistic correction than Opus's frontier-focused training. This three-point gradient is the strongest evidence against a simple "bigger = less biased" narrative, and supports the view that alignment is a multi-dimensional process with different outcomes at different tiers.

E.2. Cross-Lingual Results

Table 14 shows cross-lingual bias for Gemini Flash 3 across six native-prompt languages (60 pairs, 10 runs per item). All six languages produce significant optimism ($+5.3$ to $+7.4$) at $p < 10^{-4}$. The range is narrow (2.1 pp) and the per-language ordering is not the focus: with a single model we cannot interpret which language ranks higher as a property of language itself. The eleven-model body-text analysis (§C.10) reports a $3.3\times$ inter-model-to-inter-language variance ratio; restricted to

Table 12. Extended results across all evaluated models, ordered by Skew. 95% CI from 10,000 bootstrap resamples of pair-level Skew. Gray rows indicate insufficient data for significance.

Model	Provider	Size	Skew	95% CI	Std	p	Pairs
GLM-4.7-flash	Zhipu	S	+16.6	$[+13.6, +19.7]$	11.9	$< .0001$	59
Llama 3.3-70B	Meta	L	+13.1	$[+10.6, +15.6]$	10.4	$< .0001$	57
GPT-5.4-mini	OpenAI	S	+13.1	$[+10.9, +15.3]$	8.8	$< .0001$	60
Mistral Large	Mistral	L	+12.2	$[+9.5, +14.9]$	10.6	$< .0001$	60
Qwen3-235B	Alibaba	L	+11.2	$[+9.0, +13.5]$	8.8	$< .0001$	60
DeepSeek-V3.2	DeepSeek	L	+10.3	$[+8.4, +12.4]$	7.8	$< .0001$	60
GPT-5.4	OpenAI	L	+10.0	$[+8.2, +11.8]$	7.0	$< .0001$	60
Mistral Small	Mistral	S	+9.6	$[+6.6, +12.6]$	11.8	$< .0001$	60
Qwen3-Next-80B	Alibaba	L	+9.6	$[+6.9, +12.2]$	10.0	$< .0001$	60
GPT-OSS-120B	OpenAI	L	+6.3	$[+4.4, +8.3]$	7.6	$< .0001$	60
Haiku 4.5	Anthropic	S	+6.1	$[+3.2, +9.1]$	11.7	$< .001$	60
Gemini Flash 3	Google	S	+5.1	$[+3.4, +6.9]$	7.2	$< .0001$	60
GLM-4.5-Air	Zhipu	S	+5.0	$[+2.6, +7.5]$	8.0	$< .001$	40
Nemotron-3-super-120B	NVIDIA	L	+4.7	$[+2.9, +6.7]$	7.5	$< .0001$	60
Gemini Pro 3.1	Google	L	+4.2	$[+2.1, +6.2]$	8.1	$< .001$	60
Opus 4.6	Anthropic	L	−5.1	$[−6.7, −3.5]$	6.4	$< .0001$	60
Sonnet 4.6	Anthropic	L	−7.7	$[−9.5, −6.0]$	6.8	$< .0001$	60

Most models use 10 runs at $T=0.7$; a subset (GPT-5.4, Sonnet 4.6, Pro 3.1, DeepSeek-V3.2, Opus 4.6) uses 5 runs, and the temperature ablation in §C.7 confirms direction is preserved across $T \in \{0.7, 1.0\}$.

Table 13. Anthropic three-point gradient. Sonnet is more pessimistic than the larger Opus, indicating alignment recipe matters.

Model	Tier	Skew	Direction
Haiku 4.5	lightweight	+6.1	Optimistic
Opus 4.6	frontier	−5.0	Pessimistic
Sonnet 4.6	balanced	−7.7	Pessimistic

the six models with full six-language coverage, the ratio is 2.7×. This table gives the per-language detail for Gemini Flash 3.

Table 14. Gemini Flash 3 cross-lingual Skew on the 6 languages with native-language system prompts (60 pairs, 10 runs per item). All $p < 0.0001$. The four languages with English system prompts (DE, FR, HI, JA) are summarized in the per-language table in Appendix C.10.

Language	Skew	p	Pairs	Parsed
English	+5.3	$< .0001$	60	1335
Spanish	+6.0	$< .0001$	60	1337
Arabic	+6.0	$< .0001$	60	1336
Korean	+6.9	$< .0001$	60	1328
Russian	+7.1	$< .0001$	60	1329
Chinese	+7.4	$< .0001$	60	1339

E.3. Domain-Level Skew

Table 15 shows per-domain Skew for the 6 Tier-1 models. The health_habits domain produces the largest bias spread: 30 pp between GPT-5.4-mini (+19.9) and Sonnet (−10.2). In practical terms, asking "will this person maintain their exercise routine?" produces answers that differ by 30 percentage points depending on which model is queried. The academic domain produces the smallest spread, possibly because academic scenarios (exams, admissions, publications) have more readily estimable base rates from training data. The policy domain triggers Sonnet's strongest pessimism (−11.6), consistent with Constitutional AI's emphasis on caution about societal-level claims. Overall, domain accounts for only 1.4% of total Skew variance (see §E.5), confirming that bias is primarily a model property with domain-dependent modulation.

Table 15. Per-domain Skew. Health domain amplifies bias; academic domain suppresses it. Bold indicates $|\text{Skew}| > 10$.

Model	Academic	Business	Everyday	Health	Policy	Project
GPT-5.4-mini	+9.4	**+15.2**	**+14.7**	**+19.9**	**+11.0**	**+18.9**
GPT-5.4	+6.3	+7.9	+9.3	**+10.1**	**+11.0**	**+13.7**
Haiku 4.5	−0.7	+7.6	+8.3	+6.5	+7.4	+7.1
Flash 3	+2.4	+4.8	+8.1	+7.6	+1.6	+5.8
Pro 3.1	+0.8	+3.7	+3.4	+5.3	+3.5	+6.0
Sonnet 4.6	−5.8	−6.5	−6.4	**−10.2**	**−11.6**	−5.7

E.4. Valence Asymmetry

Table 16 decomposes Skew into its positive and negative question components. Each cell shows how far the model's mean estimate deviates from 50 (the expected value under maximum uncertainty). This decomposition reveals fundamentally different bias mechanisms.

GPT-5.4-mini exhibits *compound optimism*: both P(good) is overestimated (+7.3 from 50) and P(bad) is underestimated (+5.8 from 50). The model is sunny in both directions, inflating good outcomes and deflating bad ones. Sonnet exhibits *good-side pessimism*: P(good) is substantially underestimated (−6.6 from 50), while P(bad) is nearly accurate (−1.1 from 50). Sonnet does not overestimate risks; it underestimates opportunities. This asymmetry is consistent with Constitutional AI training that emphasizes caution: the model learned to be skeptical of positive claims without becoming catastrophist about negative ones.

An intermediate pattern appears in Pro 3.1 and Haiku 4.5, where the positive component is near zero but the negative component is elevated, producing moderate optimism through one-sided distortion. This suggests a continuum of bias mechanisms across the alignment spectrum.

Table 16. Valence asymmetry: deviation of P(good) and P(bad) from 50. The valence pilot uses a 5-run subset; headline Skew values in Table 1 use the full 10-run pipeline, so a model's two-component sum here can differ from its headline Skew by up to ~ 0.5 pp.

Model	P(good)−50	P(bad)−50	Skew
GPT-5.4-mini	+7.3	+5.8	+13.1
GPT-5.4	+4.2	+5.5	+9.7
Haiku 4.5	−0.2	+6.4	+6.1
Flash 3	+3.8	+1.2	+5.0
Pro 3.1	−1.9	+5.6	+3.8
Sonnet 4.6	**−6.6**	−1.1	−7.7

E.5. Variance Decomposition

An ANOVA-style decomposition of pair-level Skew (Skew $\sim$ Model + Scenario + Domain, $N = 804$ pairs across 14 models and 60 scenarios) attributes variance as in Table 17. The headline cohort is 16 models; we report the variance decomposition on the frozen analysis snapshot for exact reproducibility, and the model-share figure is therefore a lower bound for the full current cohort. We also report random-intercept variances from per-factor REML mixed models for reference.

Table 17. Variance decomposition. Bias is primarily a model property; domain effects are negligible. Percentages from Type-II ANOVA sums of squares; REML variances from single-factor mixed-effects intercepts.

Source	REML Var.	% of Total
Model (between-model)	52.3	38.6%
Scenario (between-scenario)	22.9	20.0%
Residual (within)	–	40.0%
Domain (between-domain)	–	1.4%

A separate mixed-effects model with size as a fixed effect (Skew $\sim$ Size + (1|Scenario)) finds that small models are +2.9 pp

more optimistic than large models on average ($p = 8.9 \times 10^{-5}$). The cross-provider gradient is modest because Mistral Small (+9.6) is less optimistic than Mistral Large (+12.2), pulling against the within-provider trend; the within-provider gradients reported in §3.2 are larger for the three providers where they hold.

F. Robustness Analyses

F.1. Temperature Robustness

Table 18 shows that bias direction and magnitude are invariant to sampling temperature across all four tested models.

Table 18. Skew at temperature 0.7 vs. 1.0. Direction identical; magnitude within 1pp.

Model	t=0.7	t=1.0	Δ
GPT-5.4	+9.7	+10.0	+0.3
GPT-5.4-mini	+14.8	+15.3	+0.5
Sonnet 4.6	−7.7	−7.7	0.0
Haiku 4.5	+6.0	+6.8	+0.8

Both columns use a matched 5-run pilot to isolate temperature effects. Headline Skew values in Table 1 use 10 runs per item, so the 5-run $t = 0.7$ entries here differ from Table 1: GPT-5.4-mini +14.8 vs. +13.1 (1.7 pp), Haiku 4.5 +6.0 vs. +6.1 (0.1 pp), GPT-5.4 and Sonnet 4.6 unchanged.