SPECULATIVE DECODING: LOSSLESS SPEEDUP OF AUTOREGRESSIVE TRANSLATION

ABSTRACT

Different from some previous work accelerating autoregressive translation (AT) at the sacrifice of quality, we propose Speculative Decoding (SpecDec) – a novel decoding paradigm inspired by speculative execution in computer architecture, which combines respective advantages of AT and non-autoregressive translation (NAT) for lossless speedup of translation. At each decoding step, SpecDec first speculatively drafts (i.e. decodes) next k tokens with an NAT model and then verifies them with an AT model, where only the drafted tokens passing the verification are accepted as decoded tokens for guaranteeing its translation result is exactly the same as AT. The collaboration of NAT drafting and AT verification leads to a much higher decoding speed without quality loss due to parallel computing enabled by speculative decoding.

We conduct experiments in 4 standard WMT translation benchmarks and confirm the vanilla SpecDec yields exactly the same results as AT greedy decoding with an around $3\times$ speedup, and that its variant (SpecDec++) with an advanced verification strategy not only outperforms AT greedy decoding, but also further improves the decoding speed, resulting in an around $5\times$ speedup over AT. Moreover, SpecDec can be easily generalized for speeding up other seq2seq tasks like Abstractive Summarization, and benefit more from stronger computing devices, demonstrating its potential to become a *de facto* decoding standard in the future for efficient and lossless seq2seq generation.

1 INTRODUCTION

Since the Transformer (Vaswani et al., 2017) prevailed in Natural Language Processing (NLP), autoregressive decoding has become the *de facto* standard for neural machine translation (NMT) as well as other generation tasks, because it is easy to train and reliable to generate high-quality results. Despite its advantages, autoregressive translation (AT) has been widely blamed for its poor inference efficiency, motivating non-autoregressive translation (NAT). Unlike AT which sequentially decodes only one token at each iteration so that the next token prediction can condition on the previous decoding results, NAT decodes tokens in parallel without depending on the surface form of previous tokens, largely improving the inference efficiency.

Recent research in NAT mainly focuses on improving its translation quality to bridge the performance gap between NAT and AT (Gu et al., 2018; Qian et al., 2021; Geng et al., 2021; Savinov et al., 2021). Until now, however, NAT's performance is still less reliable than AT, as NAT is more difficult than AT given its unawareness of the conditional dependence of translated tokens.

Given AT's reliable generation results and NAT's high efficiency, we propose an approach named Speculative Decoding (SpecDec) to combine their advantages, inspired by speculative execution[1], to accelerate translation without quality loss compared with AT. SpecDec decomposes a decoding iteration into two substeps: *draft* and *verify*: At each iteration, SpecDec first speculatively *drafts* (i.e., decodes) a fixed number of tokens[2] in parallel through NAT; Then, the drafted tokens are *verified*

---

[1]Speculative execution is an optimization technique used in computer architecture where a system performs some task in advance to avoid delays that would have to be incurred by doing the task after it is known that it is required (`https://wikipedia.org/wiki/Speculative_execution`).

[2]We use "*a block of* drafted tokens" to denote them in the following parts of this paper.

Figure 1: Speculative Decoding where a decoding iteration involves two substeps: *draft* and *verify*. In the **Draft** substep, an NAT model speculatively drafts (i.e., decodes) a block (block size $k = 5$ for this example) of tokens in parallel conditioning on the source sentence and previously decoded tokens (i.e., the tokens in the rectangle boxes). In the **Verify** substep, drafted tokens are verified in parallel: bifurcation is detected as the first position where we find the drafted token does not match the top-1 result verified by an AT model. The drafted tokens after the bifurcation position are all discarded, for guaranteeing SpecDec's translation is exactly the same with greedy decoding of AT.

by an AT model in an autoregressive manner to determine how many of them match AT's (top-1) results and thus can be accepted as translation results, as Figure 1 shows. In contrast to conventional AT which decodes at a low speed, AT verification is highly efficient because it performs in parallel; more importantly, it helps guarantee SpecDec's translation is identical to AT, resulting in a desirable balance between translation speed and quality, as shown in Figure 2.

In addition to the vanilla SpecDec whose translation is required (strictly by the top-1 matching criterion in AT verification) to be identical to greedy decoding of AT, we propose SpecDec++ — an advanced variant of SpecDec by slightly relaxing the rigid requirement during AT verification. SpecDec++ not only yields translations beyond greedy decoding, but also prevents good drafted tokens from being discarded just because they are different from greedy decoding results, leading to a higher inference speedup.

The experiments in four standard WMT benchmarks show that SpecDec can yield exactly the same translations as greedy decoding of AT with a $3\times$ speedup and that its variant SpecDec++ can outperform greedy decoding with an even higher ($\sim 5\times$) speedup. Moreover, the SpecDec paradigm can be easily generalized to other seq2seq tasks like Abstractive Summarization and benefit more from stronger computing devices. Its lossless quality and promising speedup results demonstrate its great potential to evolve into a *de facto* decoding standard for efficient seq2eq generation in the future.

Figure 2: Translation quality and efficiency of models on WMT14 EN-DE. The speedup baseline ($1.0\times$) is the Transformer-base (Vaswani et al., 2017) with beam search. All models above except "AT" are trained with KD by a Transformer-big teacher.

2 BACKGROUND

2.1 AUTOREGRESSIVE TRANSLATION

Given a source sentence $\boldsymbol{x} = (x_1, x_2, \ldots, x_n)$ and the target sentence $\boldsymbol{y} = (y_1, y_2, \ldots, y_m)$, an autoregressive translation (AT) model is trained with the target distribution of conditional probabilities based on the chain rule:

$$\mathcal{L}_{\text{AT}} = \log P(\boldsymbol{y} \mid \boldsymbol{x}; \boldsymbol{\theta}_{\text{AT}}) = \sum_{i=1}^{m} \log P(y_i \mid \boldsymbol{y}_{<i}, \boldsymbol{x}; \boldsymbol{\theta}_{\text{AT}}) \tag{1}$$

where $\boldsymbol{y}_{<i}$ denotes previous target tokens before the ith position. As Eq (1) shows, an AT model is trained via the teacher-forcing strategy that uses target tokens as previously decoded tokens, which performs efficiently as the probability $P(y_i \mid \boldsymbol{y}_{<i}, \boldsymbol{x})$ at each iteration can be calculated in parallel.

During inference, an AT model sequentially predicts output tokens given preceding decoded tokens:

$$\hat{\boldsymbol{y}} = \arg\max_{\boldsymbol{y}^*} \sum_{j=1}^{m'} \log P\left(y_j^* \mid \boldsymbol{y}_{<j}^*, \boldsymbol{x}; \boldsymbol{\theta}_{\text{AT}}\right) \tag{2}$$

where $\hat{\boldsymbol{y}} = (\hat{y}_1, \hat{y}_2, \ldots, \hat{y}_{m'})$ is the predicted output sentence.

Although AT offers desirable translation quality, its sequential decoding scheme with limited parallelism largely reduces its decoding speed, being its main efficiency bottleneck.

2.2 NON-AUTOREGRESSIVE TRANSLATION

To accelerate inference, non-autoregressive translation (NAT) (Gu et al., 2018) removes sequential dependence between target tokens with a conditional independence assumption:

$$\mathcal{L}_{\text{NAT}} = \sum_{i=1}^{m} \log P\left(y_i \mid \boldsymbol{x}; \boldsymbol{\theta}_{\text{NAT}}\right) \tag{3}$$

In contrast to AT that will not start predicting y_j until $\boldsymbol{y}_{<j}$ are completely decoded, NAT decodes[3] the output sentence in parallel, which is much more efficient than AT:

$$\widetilde{\boldsymbol{y}} = \arg\max_{\boldsymbol{y}^*} \sum_{j=1}^{m'} \log P\left(y_j^* \mid \boldsymbol{x}; \boldsymbol{\theta}_{\text{NAT}}\right) \tag{4}$$

On the other hand, however, the conditional independence assumption makes it hard to train an NAT model well, leading to degradation in translation quality despite an improvement in decoding speed.

3 SPECULATIVE DECODING

Given the fact that AT translates better whereas NAT performs faster, we propose Speculative Decoding (SpecDec) to combine their respective advantages, inspired by speculative execution, to achieve lossless acceleration for seq2seq generation. Specifically, SpecDec decomposes every decoding iteration into two substeps – *draft* and *verify*:

Draft At each iteration, SpecDec first utilizes an NAT model to simultaneously decode a block of drafted tokens (denoted as [MASK] in its decoder input in Figure 1) speculatively, conditioning on preceding translated tokens. Formally, given the source sentence $\boldsymbol{x} = (x_1, x_2, \ldots, x_n)$ and the previously translated tokens $\boldsymbol{y}_{\leq j} = (y_1, y_2, \ldots, y_j)$, SpecDec decodes the next k (drafted) tokens as a block in parallel:

$$\widetilde{\boldsymbol{y}}_{j+1\cdots j+k} = \arg\max_{\widetilde{\boldsymbol{y}}_{j+1\cdots j+k}} \sum_{i=1}^{k} \log P\left(\widetilde{y}_{j+i} \mid \boldsymbol{y}_{\leq j}, \boldsymbol{x}; \boldsymbol{\theta}_{\text{NAT}}\right)$$

Verify Then, the drafted tokens $\widetilde{\boldsymbol{y}}_{j+1\cdots j+k}$ are verified with an AT model in the autoregressive manner, which performs in parallel. We find the bifurcation position c by comparing the drafted tokens with the autoregressive decoding results conditioning on the draft as Figure 1 shows:

$$c = \arg\max_{i} \frac{\mathbb{1}\left(\widetilde{y}_{j+i} \neq \hat{y}_{j+i}\right)}{i}, 1 \leq i \leq k$$

$$\hat{y}_{j+i} = \arg\max_{\hat{y}_{j+i}} \log P(\hat{y}_{j+i} \mid \boldsymbol{y}_{\leq j}, \widetilde{\boldsymbol{y}}_{j+1\cdots j+i-1}, \boldsymbol{x}; \boldsymbol{\theta}_{\text{AT}}) \tag{5}$$

where $\mathbb{1}(\cdot)$ is the indicator function and $\hat{y}_{j+i}$ is the top-1 result verified by the AT model conditioning on the previously translated tokens $\boldsymbol{y}_{<j}$ and the drafted tokens $\widetilde{\boldsymbol{y}}_{j+1\cdots j+i-1}$. We only accept the verified tokens before (including) the bifurcation position as translated tokens, which ensures that SpecDec yields the same results as greedy decoding of AT:

$$\boldsymbol{y}_{j+1\cdots j+c} = \hat{\boldsymbol{y}}_{j+1\cdots j+c} = (\widetilde{\boldsymbol{y}}_{j+1\cdots j+c-1}, \hat{y}_{j+c})$$

We iterate decoding with the above substeps until the termination condition is met, i.e. the [EOS] token is decoded or the sentence reaches the maximal length. As illustrated, SpecDec is highly efficient because both *draft* and *verify* perform in parallel.

---

[3]We use $\widetilde{\boldsymbol{y}}$ to denote NAT's translations, while we use $\hat{\boldsymbol{y}}$ to denote AT decoded/verified translation results.

Figure 3: Illustration of SpecDec++. Compared to the vanilla SpecDec strictly requiring the drafted tokens to match the top-1 result of the AT verifier, SpecDec++ slightly relaxes the criterion to trust NAT's draft more, by only requiring the drafted tokens to fall in the *top-β* candidates of the AT verifier with a tolerable log-likelihood gap (not shown in this Figure; see Eq (7)). As a result, SpecDec++ allows more drafted tokens to be accepted even if they are slightly different from the top-1 result of the AT verifier, leading to a higher inference speedup.

3.1 NAT DRAFTER

As demonstrated above, an NAT model is the key to speculative decoding, which can efficiently generate a block of drafted tokens in parallel. Our NAT drafter differs from other NAT models in two aspects: First, we only require the NAT drafter to decode a block (i.e., fixed length) of tokens in each decoding iteration, instead of the whole sequence; Second, as illustrated in Figure 1, since we decode from *Left* to *Right*, the NAT drafter is required to decode tokens conditioning on the previously decoded tokens. Formally, given the source sentence $\boldsymbol{x} = (x_1, \cdots, x_n)$ and the randomly sampled prefix $\boldsymbol{y}_{\leq p}$ ($0 \leq p < m$) of the target sentence $\boldsymbol{y} = (y_1, \cdots, y_m)$, the model is trained to predict the next k tokens, as shown in Figure 1:

$$\mathcal{L}_{\text{NAT}} = \sum_{i=p+1}^{p+k} \log P\left(y_i | \boldsymbol{y}_{\leq p}, \boldsymbol{x}; \boldsymbol{\theta}_{\text{NAT}}\right)$$

In addition, we leverage the glancing strategy following Qian et al. (2021), which exploits curriculum learning during training to get better performance. As in previous NAT work, we apply sequence-level knowledge distillation (Seq-KD) (Kim & Rush, 2016) by an autoregressive Transformer teacher model to train our NAT drafter.

3.2 AT VERIFIER

We use the conventional Transformer (see Section 2.1) as our AT verifier, which is the key to guaranteeing translation quality. As we hope as many drafted tokens by the NAT model as possible can be accepted by the AT verifier for a higher speedup, we also apply Seq-KD to the AT verifier by a shared teacher (with the NAT drafter), which not only allows the NAT drafter and AT verifier to perform similarly, but also improves the AT verifier's translation quality (Furlanello et al., 2018).

4 SPECDEC++

As shown in Figure 1 and discussed in Section 3, the vanilla SpecDec only accepts the drafted tokens that match the top-1 result of the AT verifier, which guarantees that SpecDec's translation is identical to greedy decoding of AT. However, the top-1 results are not necessarily better than the drafted tokens. As a result, the strict verification criterion (i.e., top-1 matching) will result in many good drafted tokens being discarded just because they are different from the top-1 result of the AT verifier, which limits the speedup of SpecDec.

To overcome this limitation, we propose a variant of SpecDec named SpecDec++, which is illustrated in Figure 3. Instead of the rigid top-1 matching requirement shown in Eq (5), SpecDec++ relaxes the criterion to trust NAT's draft more, by only requiring the drafted tokens to fall in *top-β* candidates with a tolerable (log-likelihood) score gap τ (away from the top-1 result):

$$\hat{y}_{j+i} = \begin{cases} \widetilde{y}_{j+i}, & \text{if } \textit{SpecDec++ requirement} \text{ is met} \\ \text{same as Eq (5),} & \text{otherwise} \end{cases}$$

As discussed above, *SpecDec++ requirement* is met if Eq (6) and (7) are both true:

$$\log P(\widetilde{y}_{j+i}|\cdot) \geq \log P(\hat{y}_{j+i}^{(\beta)}|\cdot) \tag{6}$$

$$\log P(\hat{y}_{j+i}^{(1)}|\cdot) - \log P(\widetilde{y}_{j+i}|\cdot) \leq \tau \tag{7}$$

where $\log P(\hat{y}_{j+i}^{(\beta)}|\cdot)$ is the top-β ranked result's log-likelihood score by the AT verifier.

The advanced verification criterion with the hyperparameter top-β and tolerance τ not only allows more drafted tokens to be accepted for a higher speedup but also enables SpecDec++ to yield translations beyond greedy decoding.

5 EXPERIMENTS

5.1 EXPERIMENTAL SETTINGS

Datasets and Evaluation We mainly evaluate our approach on the most recognized machine translation benchmark: WMT14 English-German translation which contains 4.5M translation pairs for training. Following prior work (Ott et al., 2018), we adopt *newstest-13* as our validation set for finding the best hyperparameters and model checkpoints, and test on *newstest-14*. We use 32K Byte Pair Encoding (BPE) (Sennrich et al., 2016) subwords[4] as the joint source-target dictionary. Following prior work in NAT, we report BLEU (Papineni et al., 2002) to facilitate translation quality comparison. For inference efficiency, we use both the average number of decoding iterations and speedup over beam search. Specifically, we test the inference speed with fairseq implementation[5] on 1 Nvidia P100 GPU.

In addition to WMT14 EN-DE, we also test SpecDec on WMT14 DE-EN and WMT16 EN-RO/RO-EN benchmarks, as previous NAT work.

Model Configuration We mainly conduct experiments on the most commonly used base-size Transformer (Vaswani et al., 2017) architecture. The Transformer-base[6] has a 6-layer encoder and a 6-layer decoder. Its embedding/FFN dimension/#heads are 512/2,048/8. We use the model architecture for both the drafter (NAT) and the verifier (AT). We apply sequence-level knowledge distillation as discussed in Section 3.1 and 3.2 for both the drafter and verifier using a shared teacher. Following recent iterative NAT work (Saharia et al., 2020; Savinov et al., 2021), we use the Transformer-big as the teacher for WMT14 EN-DE/DE-EN[7] and use Transformer-base for WMT16 EN-RO/RO-EN, which all train with the raw training set and generate the distilled training set with beam search ($b = 5$). We include model training details in Appendix A.

5.2 MAIN RESULTS

The translation quality and speedup results on WMT14 EN-DE are presented in Table 1. Unlike previous NAT approaches that are inferior to AT with Seq-KD (i.e., our AT verifier), SpecDec introduces an around $3\times$ speedup with exactly the same translation quality as (autoregressive) greedy decoding by our AT verifier, truly achieving lossless acceleration. SpecDec++ further improves the results by relaxing the strict top-1 matching criterion: slightly relaxing (i.e., SpecDec++ high-quality) allows us to achieve better translation than greedy decoding – even approaching the beam search result with a higher speedup ($3.0\times \rightarrow 3.6\times$), and a little more aggressively relaxing (i.e., SpecDec++ high-efficiency) further accelerates inference ($3.6\times \rightarrow 4.5\times$) owing to the acceptance of more tokens despite a marginal loss of translation quality.

---

[4]We use the same BPE tokenization and vocabulary as Ghazvininejad et al. (2019).

[5]`https://github.com/pytorch/fairseq`. Beam search ($b = 5$) is our speed baseline ($1.0\times$).

[6]We also include results of a Transformer with a deep encoder and a shallow decoder in Appendix B.5.

[7]As a reference, the teacher models of Saharia et al. (2020) achieve 29.5 and 32.2 BLEU in WMT14 EN-DE and DE-EN respectively, which are stronger than our teachers achieving 29.3 and 32.1 respectively.

	Models	Iter.	Speedup		WMT14		WMT16	
					EN-DE	DE-EN	EN-RO	RO-EN
AT baseline	Transformer-base (w/o Seq-KD)[†]	N	-	1.0×	27.74	31.09	34.28	33.99
Fully NAT	NAT w/ Fertility (Gu et al., 2018)	1	15.6×	-	17.69	21.47	27.29	29.06
	CTC (Libovický & Helcl, 2018)	1	-	-	17.68	19.80	19.93	24.71
	AXE (Ghazvininejad et al., 2020a)*	1	-	-	23.53	27.90	30.75	31.54
	GLAT (Qian et al., 2021)	1	15.3×	-	25.21	29.84	31.19	32.04
	OaXE (Du et al., 2021)*	1	-	-	26.10	30.20	32.40	33.30
	AligNART (Song et al., 2021)	1	13.4×	-	26.40	30.40	32.50	33.10
	DSLP (Huang et al., 2021)	1	14.8×	-	27.02	**31.61**	**34.17**	**34.60**
	F-VAE (Gu & Kong, 2021)	1	16.5×	-	27.49	31.10	33.79	33.87
	REDER (Zheng et al., 2021)	1	5.5×	-	**27.50**	31.25	33.60	34.03
	DA-Transformer (Huang et al., 2022a)*	1	13.9×	-	27.49	31.37	-	-
Iterative NAT	iNAT (Lee et al., 2018)	10	-	-	21.61	25.48	29.32	30.19
	CMLM (Ghazvininejad et al., 2019)*	10	1.7×	1.8×	27.03	30.53	33.08	33.31
	LevT (Gu et al., 2019)	2.1	4.0×	3.7×	27.27	-	-	33.26
	SMART (Ghazvininejad et al., 2020b)*	10	1.7×	1.8×	27.65	31.27	-	-
	DisCo (Kasai et al., 2020)*	4.8	3.5×	-	27.34	31.31	33.22	33.25
	Imputer (Saharia et al., 2020)*	8	3.9×	-	28.20	31.80	34.40	34.10
	Multi-Task NAT (Hao et al., 2021)*	10	1.7×	1.8×	27.98	31.27	33.80	33.60
	RewriteNAT (Geng et al., 2021)*	2.7	3.1×	2.8×	27.83	31.52	33.63	34.09
	SUNDAE (Savinov et al., 2021)*	16	1.4×	-	28.46	32.30	-	-
	CMLMC (Huang et al., 2022b)*	10	-	1.5×	28.37	31.41	34.57	34.13
Ours	Teacher	N	-	/	29.31[‡]	32.11[‡]	34.72	34.49
	NAT drafter ($k = 25$)	1.6	-	14.3×	26.48	30.23	32.08	32.21
	AT verifier ($b = 5$)	N	-	1.0×	28.89	32.53	34.96	34.86
	AT verifier ($b = 1$)	N	-	1.1×	28.73	32.18	34.83	34.65
	SpecDec ($k = 25$)	4.9	-	3.0×	28.73	32.18	34.83	34.65
	SpecDec++ ($k = 25$, *high-quality*)	4.0	-	3.6×	**28.89**	**32.56**	**35.32**	**34.98**
	SpecDec++ ($k = 25$, *high-efficiency*)	3.1	-	**4.5×**	28.73	32.19	34.92	34.80

Table 1: Results of SpecDec on four standard WMT benchmarks. For inference efficiency, we report the averaged decoding iteration (denoted as *Iter.*) and speedup on WMT14 EN-DE. The results that truly match or outperform autoregressive decoding (i.e., AT verifier with $b = 1$) are highlighted in red. [†] AT baselines' results are from Ghazvininejad et al. (2019). [‡] indicates results obtained by Transformer-big. * denotes models distilled by a Transformer-big model. While speedup numbers reported by the previous papers (left column) are not strictly comparable to ours due to different devices and environments, we reran some of them that are open source using the same device and environment as ours and report their speedups (right column), observing no significant difference.

By looking into the results, our NAT drafter's translation quality is better than the majority of early fully NAT work but inferior to most iterative NAT approaches. Compared with the NAT models including complicated mechanisms such as length prediction, length beam, reranking, and CTC that slow down the efficiency per iteration[8], our NAT drafter is simple and straightforward. As a result, its decoding efficiency per iteration is higher – even comparable to fully NAT despite taking 1.6 decoding iterations on average. The acceptable translation quality and high efficiency of our NAT drafter significantly help accelerate autoregressive decoding, playing an instrumental role in lossless acceleration of SpecDec.

Results for other language pairs are similar to WMT14 EN-DE. We include details in Table 8 in Appendix B.1.

5.3 ANALYSIS

5.3.1 HYPERPARAMETER

Block Size k   We conduct experiments with various block sizes on the development set and show the results in Table 2. As the block size k increases, the number of mean accepted tokens, which highly correlates with speedup and the number of decoding iterations, first increases and reaches a peak when $k = 25$. Further increasing k has an adverse effect, because it will become very hard for the model to learn to translate too many tokens simultaneously given the limited model capacity, leading to a drop in both efficiency and quality.

Top-β and Tolerance τ in SpecDec++   We study the effects of hyperparameters in SpecDec++: top-β and tolerance τ, and show the results on the development set in Table 3. Moderately increasing τ and β not only leads to an increase of mean accepted tokens since AT verification becomes

---

[8]For example, RewriteNAT (Geng et al., 2021) uses length beam size 5, slowing down its efficiency.

Models	k	Tok.	BLEU	Speed
AT ($b=5$)	-	1.00	26.72	$1.00\times$
SpecDec++	10	5.97	26.68	$3.04\times$
	15	6.74	**26.94**	$3.47\times$
	20	7.24	26.75	$3.55\times$
	25	**7.56**	26.92	$\mathbf{3.79\times}$
	30	7.44	26.75	$3.63\times$

Table 2: The mean accepted tokens (*Tok.*), the translation quality (*BLEU*), and the efficiency (*Speed*) when decoding with a various number of block size k on the development set (*newstest-13*). The results are obtained with SpecDec++ (*top-3*, $\tau = 1.0$).

Models	τ	Top-3 ($\beta=3$)	Top-5 ($\beta=5$)
SpecDec++	1	7.56/**27.02**	7.58/27.02
	2	8.64/26.92	8.77/26.92
	3	9.46/26.84	9.72/26.84
	4	10.04/26.78	10.50/26.74
	5	10.38/26.70	**10.99**/26.64

Table 3: Results on the development set (*newstest-13*) with different hyperparameters in SpecDec++ ($k = 25$). Each cell lists the mean accepted tokens and BLEU score. The BLEU score of greedy decoding of the AT verifier is 26.62.

	Models	Iteration	BLEU	Speed
Blockwise Stern et al. (2018)	Blockwise decoding ($k=1$)	N	29.11	$1.0\times^{\dagger}$
	Blockwise decoding ($k=2$)	/	28.95	$1.7\times^{\dagger}$
	Blockwise decoding ($k=10$)	/	27.40	$3.0\times^{\dagger}$
Ours	Teacher (Transformer-big, $b=5$)	N	29.31	$1.0\times$
	AT verifier ($b=5$)	N	29.25	$1.0\times$
	AT verifier ($b=1$)	N	29.18	$1.1\times$
	NAT drafter ($k=10$)	3.3	27.41	$7.2\times$
	SpecDec ($k=10$)	5.4	29.18	$2.7\times$
	SpecDec++ ($k=10$, *top-3*, $\tau=1.0$)	5.0	29.28	$2.9\times$
	SpecDec++ ($k=10$, *top-5*, $\tau=6.0$)	3.9	29.12	$3.8\times$
	NAT drafter ($k=30$)	1.4	27.35	$15.0\times$
	SpecDec ($k=30$)	4.8	29.18	$3.0\times$
	SpecDec++ ($k=30$, *top-3*, $\tau=1.0$)	4.2	**29.32**	$3.5\times$
	SpecDec++ ($k=30$, *top-5*, $\tau=6.0$)	2.6	29.15	$\mathbf{5.0\times}$

Table 4: Results of SpecDec of the big-size model configuration on WMT14 EN-DE and the comparison to the state-of-the-art Blockwise Decoding Stern et al. (2018). † denotes the speedup results reported in original papers obtained by comparison with greedy decoding.

less strict but also improves the translation quality over greedy decoding. However, the translation quality will decrease if the constraints are over relaxed: the BLEU score will degrade from the peak of 27.02 to 26.64 when decoding with *top-5* selection (i.e., $\beta = 5$) and $\tau = 5.0$. Based on the results in the development set, we conservatively select $\beta = 3, \tau = 1.0$ for the *high-quality* SpecDec++, and use $\beta = 5, \tau = 3.0$ as the *high-efficiency* SpecDec++ to pursue the higher speedup without substantial loss of translation quality for WMT14 EN-DE as in Table 1.

5.3.2 Model Size

In addition to models of the base-size configuration, we also study larger models to test the effectiveness of SpecDec. We here use Transformer-big (Vaswani et al., 2017) as our model architecture for both the NAT drafter and the AT verifier in SpecDec/SpecDec++[9], and compare it with the conventional Transformer-big baseline as well as Blockwise Decoding (Stern et al., 2018) – a state-of-the-art efficient Transformer-big variant by introducing additional $k - 1$ heads on top of the Transformer decoder to generate next k tokens as a block and verifies, which works in a similar way to ours. According to Table 4, our SpecDec/SpecDec++ substantially speeds up the AT baselines and outperforms Blockwise Decoding with both better results and a higher speedup. Compared with Blockwise Decoding whose performance drops significantly when k increases to 10 due to its underinvestment in speculation by only using lightweight heads to generate the next few tokens in parallel, SpecDec/SpecDec++ using an independent NAT drafter is much more powerful to generate more drafted tokens that can be accepted, turning out to result in a significantly higher speedup, despite introducing more parameters (see Appendix C for detailed discussion of memory cost issues).

---

[9]The hyperparameters (e.g., block size k, Top-β, tolerance τ) in SpecDec (big) are re-tuned on the development set, which may be different from those in the base-size models.

Models	Drafter	Tok.	Iter.	BLEU
AT-base (greedy)	-	1.00	N	28.73
SpecDec-base	lightweight heads	2.23	11.5	28.73
	NAT-base	5.53	5.0	28.73
	NAT-big	**5.90**	**4.7**	**28.73**
SpecDec++-base (*top-3*, $\tau = 1.0$)	lightweight heads	2.35	10.9	28.11
	NAT-base	6.69	4.1	28.81
	NAT-big	**7.32**	**3.8**	**29.12**
SpecDec++-base (*top-5*, $\tau = 3.0$)	lightweight heads	2.61	10.6	27.02
	NAT-base	8.71	3.2	28.58
	NAT-big	**9.73**	**2.8**	**28.98**

Table 5: Results of SpecDec-base ($k = 30$) with various sizes of drafters on WMT14 EN-DE.

	Models	Iteration	R-1	R-2	R-L	Speed
Teacher	BART (Lewis et al., 2020)	N	44.16	21.28	40.90	-
AT (w/o Seq-KD)	BART-base ($b = 5$)	N	42.84	20.08	39.51	1.0×
Ours	NAT drafter ($k = 25$)	3.3	37.10	14.87	33.47	15.0×
	AT verifier ($b = 5$)	N	42.55	19.83	39.31	1.0×
	AT verifier ($b = 1$)	N	43.00	20.28	39.96	1.1×
	SpecDec ($k = 25$)	14.0	**43.00**	**20.28**	**39.96**	3.0×
	SpecDec++ ($k = 25$, *top-3*, $\tau = 1.0$)	10.8	42.95	20.24	39.73	3.7×
	SpecDec++ ($k = 25$, *top-5*, $\tau = 3.0$)	7.9	42.02	19.42	38.66	**4.8×**

Table 6: Results of SpecDec-base model on CNN-DM for Abstractive Summarization.

Moreover, we observe that big-size models can use a larger block size ($k = 30$) than the base-size models ($k = 25$) since larger capacity equips the model with a more powerful ability to learn to decode more tokens well in parallel. To better demonstrate this point, we conduct a comparative study of using drafters of different sizes in SpecDec-base, given the same block size ($k = 30$). According to Table 5, the big-size NAT drafter largely outperforms the base-size counterpart and the drafter with lightweight heads (as used in Stern et al. (2018)) performs worst, demonstrating that a stronger drafter can generate drafted tokens more reliably (i.e., on average more drafted tokens accepted by the AT verifier), resulting in fewer decoding iterations, which indicates that SpecDec may be further improved if a more powerful (not necessarily larger) NAT drafter is equipped.

5.3.3 OTHER SEQ2SEQ TASKS

We test SpecDec's effectiveness in one of the most representative seq2seq tasks – Abstractive Summarization. We employ the distilled training data of CNN Daily Mail (Hermann et al., 2015) from BART (Lewis et al., 2020) to train the NAT drafter and the AT verifier whose model architectures are both BART-base, and test on the CNN Daily Mail test split following previous work.

According to Table 6, the vanilla SpecDec consistently achieves exactly the same result as the AT verifier ($b = 1$), which is, to the best of our knowledge, the first work that achieves such a 3× lossless speedup for Abstractive Summarization. SpecDec++ further accelerates inference but does not show any quality improvement as observed in NMT experiments because of the larger performance gap between the NAT drafter and the AT verifier in the abstractive summarization benchmark.

5.4 DISCUSSION

Extensive experiments in multiple tasks show that SpecDec can significantly speed up seq2seq generation without quality loss. The state-of-the-art lossless speedup is attributed to the substantially improved computational parallelism that allows better utilization of (hardware) computing resources. We believe SpecDec is promising and can even benefit more from evolving processor hardware that will become increasingly powerful and better at parallel computing (shown in Appendix E).

As a preliminary study, SpecDec is far from perfect and has much headroom for improvement. First, according to the experimental results above, we know SpecDec's translation quality mainly depends on the AT verifier and its efficiency relies on the NAT drafter (whose capability matters how many drafted tokens can be accepted). We believe more powerful NAT/AT models (than the simple and naive ones used in this paper) will benefit SpecDec to achieve better results.

Moreover, SpecDec's potential can be further exploited by optimizing its implementation in computing and memory access. For example, according to Table 16 showing time cost by modules in SpecDec++, our naive implementation costs a total of approximately 16% of overall time to (sequentially) encode the input for AT and NAT. Obviously, this part can be optimized by performing AT and NAT encoding in parallel because they are independent, or sharing (or partially sharing) AT's encoder with NAT, which we leave as future exploration. Also, the NAT decoder costs more than the AT decoder because it employs bi-directional attention and cannot save the computation for the already decoded tokens as AT, which we believe can be improved in the future with a better non-autoregressive decoding mechanism designed for SpecDec.

6 RELATED WORK

Non-autoregressive Decoding To accelerate autoregressive translation (AT), Gu et al. (2018) first proposed Non-Autoregressive Translation (NAT), which decodes the output sentence in one single iteration despite translation quality loss. Recent work mainly focused on improving the quality while maintaining competitive speedups, including applying various training objectives (Wang et al., 2019; Wei et al., 2019; Shu et al., 2020; Shao et al., 2020; Guo et al., 2020; Liu et al., 2021; Ding et al., 2021b; Zeng et al., 2022; Shao et al., 2022), modeling dependencies between target tokens (Kaiser et al., 2018; Sun et al., 2019; Ghazvininejad et al., 2019; Liu et al., 2020; Bao et al., 2021; Zhan et al., 2022; Zhu et al., 2022) and refining the translation outputs with multi-pass iterations (Chan et al., 2019; Stern et al., 2019; Sun & Yang, 2020; Ghazvininejad et al., 2020b; Ding et al., 2021a; Norouzi et al., 2022). However, due to the inherent conditional independence assumption, NAT models' translation quality is generally less reliable than AT.

Semi-autoregressive Decoding There are also some attempts trying to combine autoregressive (AR) and non-autoregressive (NAR) decoding: Wang et al. (2018) proposed to utilize NAR decoding locally while keeping the AR property globally; on the contrary, Ran et al. (2020) and Kong et al. (2020) introduced a local-AR model which retained the NAR property globally. Similar ideas have been also proposed for Grammatical Error Correction (GEC): Chen et al. (2020) proposed to use a sequence tagger to identify the grammatical errors' spans and then use AR decoding to correct them; Aggressive Decoding (Sun et al., 2021) is the first work that introduces speculative decoding into GEC. It assumes that the input is the sentence to be generated in the future (i.e., there are no grammatical errors in the input), and then verifies the whole sentence in parallel through greedy decoding of AT. However, Aggressive Decoding works only for tasks where the input and output are highly similar, which limits its application. The most similar work to ours is Blockwise Decoding (Stern et al., 2018) that proposed to additionally insert $k-1$ NAR heads on top of the Transformer decoder to generate k positions in parallel and use the original AR head to verify these outputs. However, its underinvestment in the NAR modeling seriously limits its performance, resulting in a much lower efficiency than our approach.

7 CONCLUSION AND FUTURE WORK

We propose a novel Speculative Decoding (SpecDec) paradigm as well as its variant (SpecDec++) by combining respective advantages of AT and NAT. Contrary to the stereotype that more models (parameters) tend to slow down inference, SpecDec's introduction of an additional NAT model substantially speeds up AT without quality loss, achieving a state-of-the-art lossless acceleration result owing to higher computational parallelism introduced by the idea of speculative execution to better utilize computing resources.

Besides machine translation, SpecDec can be easily generalized to other seq2seq tasks like Abstractive Summarization and benefit from stronger computing devices (to discuss in Appendix E). It demonstrates a novel yet promising perspective for efficient seq2seq generation, orthogonal to the efforts for advancing the state-of-the-art NAT and AT models that can further benefit SpecDec.

Despite the state-of-the-art results, SpecDec still has great potential with much headroom for improvement, as we discuss in Section 5.4. We hope that our preliminary study could draw more attention to improving this promising decoding paradigm with potential to evolve into a *de facto* standard for efficient and lossless seq2seq generation in the near future.

REFERENCES

Yu Bao, Shujian Huang, Tong Xiao, Dongqi Wang, Xinyu Dai, and Jiajun Chen. Non-autoregressive translation by learning target categorical codes. In Kristina Toutanova, Anna Rumshisky, Luke Zettlemoyer, Dilek Hakkani-Tür, Iz Beltagy, Steven Bethard, Ryan Cotterell, Tanmoy Chakraborty, and Yichao Zhou (eds.), Proceedings of the 2021 Conference of the North American Chapter of the Association for Computational Linguistics: Human Language Technologies, NAACL-HLT 2021, Online, June 6-11, 2021, pp. 5749–5759. Association for Computational Linguistics, 2021. doi: 10.18653/v1/2021.naacl-main.458. URL https://doi.org/10.18653/v1/2021.naacl-main.458.

William Chan, Nikita Kitaev, Kelvin Guu, Mitchell Stern, and Jakob Uszkoreit. KERMIT: generative insertion-based modeling for sequences. CoRR, abs/1906.01604, 2019. URL http://arxiv.org/abs/1906.01604.

Mengyun Chen, Tao Ge, Xingxing Zhang, Furu Wei, and Ming Zhou. Improving the efficiency of grammatical error correction with erroneous span detection and correction. arXiv preprint arXiv:2010.03260, 2020.

Liang Ding, Longyue Wang, Xuebo Liu, Derek F. Wong, Dacheng Tao, and Zhaopeng Tu. Rejuvenating low-frequency words: Making the most of parallel data in non-autoregressive translation. In Chengqing Zong, Fei Xia, Wenjie Li, and Roberto Navigli (eds.), Proceedings of the 59th Annual Meeting of the Association for Computational Linguistics and the 11th International Joint Conference on Natural Language Processing, ACL/IJCNLP 2021, (Volume 1: Long Papers), Virtual Event, August 1-6, 2021, pp. 3431–3441. Association for Computational Linguistics, 2021a. doi: 10.18653/v1/2021.acl-long.266. URL https://doi.org/10.18653/v1/2021.acl-long.266.

Liang Ding, Longyue Wang, Xuebo Liu, Derek F. Wong, Dacheng Tao, and Zhaopeng Tu. Understanding and improving lexical choice in non-autoregressive translation. In 9th International Conference on Learning Representations, ICLR 2021, Virtual Event, Austria, May 3-7, 2021. OpenReview.net, 2021b. URL https://openreview.net/forum?id=ZTFeSBIX9C.

Cunxiao Du, Zhaopeng Tu, and Jing Jiang. Order-agnostic cross entropy for non-autoregressive machine translation. In Marina Meila and Tong Zhang (eds.), Proceedings of the 38th International Conference on Machine Learning, ICML 2021, 18-24 July 2021, Virtual Event, volume 139 of Proceedings of Machine Learning Research, pp. 2849–2859. PMLR, 2021. URL http://proceedings.mlr.press/v139/du21c.html.

Tommaso Furlanello, Zachary Lipton, Michael Tschannen, Laurent Itti, and Anima Anandkumar. Born again neural networks. In International Conference on Machine Learning, pp. 1607–1616. PMLR, 2018.

Xinwei Geng, Xiaocheng Feng, and Bing Qin. Learning to rewrite for non-autoregressive neural machine translation. In Marie-Francine Moens, Xuanjing Huang, Lucia Specia, and Scott Wen-tau Yih (eds.), Proceedings of the 2021 Conference on Empirical Methods in Natural Language Processing, EMNLP 2021, Virtual Event / Punta Cana, Dominican Republic, 7-11 November, 2021, pp. 3297–3308. Association for Computational Linguistics, 2021. doi: 10.18653/v1/2021.emnlp-main.265. URL https://doi.org/10.18653/v1/2021.emnlp-main.265.

Marjan Ghazvininejad, Omer Levy, Yinhan Liu, and Luke Zettlemoyer. Mask-predict: Parallel decoding of conditional masked language models. In Kentaro Inui, Jing Jiang, Vincent Ng, and Xiaojun Wan (eds.), Proceedings of the 2019 Conference on Empirical Methods in Natural Language Processing and the 9th International Joint Conference on Natural Language Processing, EMNLP-IJCNLP 2019, Hong Kong, China, November 3-7, 2019, pp. 6111–6120. Association for Computational Linguistics, 2019. doi: 10.18653/v1/D19-1633. URL https://doi.org/10.18653/v1/D19-1633.

Marjan Ghazvininejad, Vladimir Karpukhin, Luke Zettlemoyer, and Omer Levy. Aligned cross entropy for non-autoregressive machine translation. In Proceedings of the 37th International Conference on Machine Learning, ICML 2020, 13-18 July 2020, Virtual Event, volume 119 of Proceedings of Machine Learning Research, pp. 3515–3523. PMLR, 2020a. URL http://proceedings.mlr.press/v119/ghazvininejad20a.html.

Marjan Ghazvininejad, Omer Levy, and Luke Zettlemoyer. Semi-autoregressive training improves mask-predict decoding. CoRR, abs/2001.08785, 2020b. URL `https://arxiv.org/abs/2001.08785`.

Jiatao Gu and Xiang Kong. Fully non-autoregressive neural machine translation: Tricks of the trade. In Chengqing Zong, Fei Xia, Wenjie Li, and Roberto Navigli (eds.), Findings of the Association for Computational Linguistics: ACL/IJCNLP 2021, Online Event, August 1-6, 2021, volume ACL/IJCNLP 2021 of Findings of ACL, pp. 120–133. Association for Computational Linguistics, 2021. doi: 10.18653/v1/2021.findings-acl.11. URL `https://doi.org/10.18653/v1/2021.findings-acl.11`.

Jiatao Gu, James Bradbury, Caiming Xiong, Victor O.K. Li, and Richard Socher. Non-autoregressive neural machine translation. In International Conference on Learning Representations, 2018. URL `https://openreview.net/forum?id=B1l8BtlCb`.

Jiatao Gu, Changhan Wang, and Junbo Zhao. Levenshtein transformer. In Hanna M. Wallach, Hugo Larochelle, Alina Beygelzimer, Florence d'Alché-Buc, Emily B. Fox, and Roman Garnett (eds.), Advances in Neural Information Processing Systems 32: Annual Conference on Neural Information Processing Systems 2019, NeurIPS 2019, December 8-14, 2019, Vancouver, BC, Canada, pp. 11179–11189, 2019. URL `https://proceedings.neurips.cc/paper/2019/hash/675f9820626f5bc0afb47b57890b466e-Abstract.html`.

Junliang Guo, Linli Xu, and Enhong Chen. Jointly masked sequence-to-sequence model for non-autoregressive neural machine translation. In Dan Jurafsky, Joyce Chai, Natalie Schluter, and Joel R. Tetreault (eds.), Proceedings of the 58th Annual Meeting of the Association for Computational Linguistics, ACL 2020, Online, July 5-10, 2020, pp. 376–385. Association for Computational Linguistics, 2020. doi: 10.18653/v1/2020.acl-main.36. URL `https://doi.org/10.18653/v1/2020.acl-main.36`.

Yongchang Hao, Shilin He, Wenxiang Jiao, Zhaopeng Tu, Michael R. Lyu, and Xing Wang. Multi-task learning with shared encoder for non-autoregressive machine translation. In Kristina Toutanova, Anna Rumshisky, Luke Zettlemoyer, Dilek Hakkani-Tür, Iz Beltagy, Steven Bethard, Ryan Cotterell, Tanmoy Chakraborty, and Yichao Zhou (eds.), Proceedings of the 2021 Conference of the North American Chapter of the Association for Computational Linguistics: Human Language Technologies, NAACL-HLT 2021, Online, June 6-11, 2021, pp. 3989–3996. Association for Computational Linguistics, 2021. doi: 10.18653/v1/2021.naacl-main.313. URL `https://doi.org/10.18653/v1/2021.naacl-main.313`.

Karl Moritz Hermann, Tomás Kociský, Edward Grefenstette, Lasse Espeholt, Will Kay, Mustafa Suleyman, and Phil Blunsom. Teaching machines to read and comprehend. In Corinna Cortes, Neil D. Lawrence, Daniel D. Lee, Masashi Sugiyama, and Roman Garnett (eds.), Advances in Neural Information Processing Systems 28: Annual Conference on Neural Information Processing Systems 2015, December 7-12, 2015, Montreal, Quebec, Canada, pp. 1693–1701, 2015. URL `https://proceedings.neurips.cc/paper/2015/hash/afdec7005cc9f14302cd0474fd0f3c96-Abstract.html`.

Chenyang Huang, Hao Zhou, Osmar R. Zaïane, Lili Mou, and Lei Li. Non-autoregressive translation with layer-wise prediction and deep supervision. CoRR, abs/2110.07515, 2021. URL `https://arxiv.org/abs/2110.07515`.

Fei Huang, Hao Zhou, Yang Liu, Hang Li, and Minlie Huang. Directed acyclic transformer for non-autoregressive machine translation. In Kamalika Chaudhuri, Stefanie Jegelka, Le Song, Csaba Szepesvári, Gang Niu, and Sivan Sabato (eds.), International Conference on Machine Learning, ICML 2022, 17-23 July 2022, Baltimore, Maryland, USA, volume 162 of Proceedings of Machine Learning Research, pp. 9410–9428. PMLR, 2022a. URL `https://proceedings.mlr.press/v162/huang22m.html`.

Xiao Shi Huang, Felipe Perez, and Maksims Volkovs. Improving non-autoregressive translation models without distillation. In International Conference on Learning Representations, 2022b. URL `https://openreview.net/forum?id=I2Hw58KHp8O`.

Lukasz Kaiser, Samy Bengio, Aurko Roy, Ashish Vaswani, Niki Parmar, Jakob Uszkoreit, and Noam Shazeer. Fast decoding in sequence models using discrete latent variables. In Jennifer G. Dy and Andreas Krause (eds.), Proceedings of the 35th International Conference on Machine Learning, ICML 2018, Stockholmsmässan, Stockholm, Sweden, July 10-15, 2018, volume 80 of Proceedings of Machine Learning Research, pp. 2395–2404. PMLR, 2018. URL http://proceedings.mlr.press/v80/kaiser18a.html.

Jungo Kasai, James Cross, Marjan Ghazvininejad, and Jiatao Gu. Non-autoregressive machine translation with disentangled context transformer. In Proceedings of the 37th International Conference on Machine Learning, ICML 2020, 13-18 July 2020, Virtual Event, volume 119 of Proceedings of Machine Learning Research, pp. 5144–5155. PMLR, 2020. URL http://proceedings.mlr.press/v119/kasai20a.html.

Jungo Kasai, Nikolaos Pappas, Hao Peng, James Cross, and Noah A. Smith. Deep encoder, shallow decoder: Reevaluating non-autoregressive machine translation. In 9th International Conference on Learning Representations, ICLR 2021, Virtual Event, Austria, May 3-7, 2021. OpenReview.net, 2021. URL https://openreview.net/forum?id=KpfasTaLUpq.

Yoon Kim and Alexander M Rush. Sequence-level knowledge distillation. arXiv preprint arXiv:1606.07947, 2016.

Xiang Kong, Zhisong Zhang, and Eduard H. Hovy. Incorporating a local translation mechanism into non-autoregressive translation. In Bonnie Webber, Trevor Cohn, Yulan He, and Yang Liu (eds.), Proceedings of the 2020 Conference on Empirical Methods in Natural Language Processing, EMNLP 2020, Online, November 16-20, 2020, pp. 1067–1073. Association for Computational Linguistics, 2020. doi: 10.18653/v1/2020.emnlp-main.79. URL https://doi.org/10.18653/v1/2020.emnlp-main.79.

Jason Lee, Elman Mansimov, and Kyunghyun Cho. Deterministic non-autoregressive neural sequence modeling by iterative refinement. In Ellen Riloff, David Chiang, Julia Hockenmaier, and Jun'ichi Tsujii (eds.), Proceedings of the 2018 Conference on Empirical Methods in Natural Language Processing, Brussels, Belgium, October 31 - November 4, 2018, pp. 1173–1182. Association for Computational Linguistics, 2018. doi: 10.18653/v1/d18-1149. URL https://doi.org/10.18653/v1/d18-1149.

Mike Lewis, Yinhan Liu, Naman Goyal, Marjan Ghazvininejad, Abdelrahman Mohamed, Omer Levy, Veselin Stoyanov, and Luke Zettlemoyer. BART: denoising sequence-to-sequence pre-training for natural language generation, translation, and comprehension. In Dan Jurafsky, Joyce Chai, Natalie Schluter, and Joel R. Tetreault (eds.), Proceedings of the 58th Annual Meeting of the Association for Computational Linguistics, ACL 2020, Online, July 5-10, 2020, pp. 7871–7880. Association for Computational Linguistics, 2020. doi: 10.18653/v1/2020.acl-main.703. URL https://doi.org/10.18653/v1/2020.acl-main.703.

Jindrich Libovický and Jindrich Helcl. End-to-end non-autoregressive neural machine translation with connectionist temporal classification. In Ellen Riloff, David Chiang, Julia Hockenmaier, and Jun'ichi Tsujii (eds.), Proceedings of the 2018 Conference on Empirical Methods in Natural Language Processing, Brussels, Belgium, October 31 - November 4, 2018, pp. 3016–3021. Association for Computational Linguistics, 2018. doi: 10.18653/v1/d18-1336. URL https://doi.org/10.18653/v1/d18-1336.

Jinglin Liu, Yi Ren, Xu Tan, Chen Zhang, Tao Qin, Zhou Zhao, and Tie-Yan Liu. Task-level curriculum learning for non-autoregressive neural machine translation. In Christian Bessiere (ed.), Proceedings of the Twenty-Ninth International Joint Conference on Artificial Intelligence, IJCAI 2020, pp. 3861–3867. ijcai.org, 2020. doi: 10.24963/ijcai.2020/534. URL https://doi.org/10.24963/ijcai.2020/534.

Ye Liu, Yao Wan, Jian-Guo Zhang, Wenting Zhao, and Philip S. Yu. Enriching non-autoregressive transformer with syntactic and semantic structures for neural machine translation. In Paola Merlo, Jörg Tiedemann, and Reut Tsarfaty (eds.), Proceedings of the 16th Conference of the European Chapter of the Association for Computational Linguistics: Main Volume, EACL 2021, Online, April 19 - 23, 2021, pp. 1235–1244. Association for Computational Linguistics, 2021.

doi: 10.18653/v1/2021.eacl-main.105. URL https://doi.org/10.18653/v1/2021.eacl-main.105.

Sajad Norouzi, Rasa Hosseinzadeh, Felipe Pérez, and Maksims Volkovs. Dims: Distilling multiple steps of iterative non-autoregressive transformers. CoRR, abs/2206.02999, 2022. doi: 10.48550/arXiv.2206.02999. URL https://doi.org/10.48550/arXiv.2206.02999.

Myle Ott, Sergey Edunov, David Grangier, and Michael Auli. Scaling neural machine translation. In Proceedings of the Third Conference on Machine Translation: Research Papers, pp. 1–9, Brussels, Belgium, October 2018. Association for Computational Linguistics. doi: 10.18653/v1/W18-6301. URL https://aclanthology.org/W18-6301.

Kishore Papineni, Salim Roukos, Todd Ward, and Wei-Jing Zhu. Bleu: a method for automatic evaluation of machine translation. In Proceedings of the 40th Annual Meeting of the Association for Computational Linguistics, July 6-12, 2002, Philadelphia, PA, USA, pp. 311–318. ACL, 2002. doi: 10.3115/1073083.1073135. URL https://aclanthology.org/P02-1040/.

Lihua Qian, Hao Zhou, Yu Bao, Mingxuan Wang, Lin Qiu, Weinan Zhang, Yong Yu, and Lei Li. Glancing transformer for non-autoregressive neural machine translation. In Chengqing Zong, Fei Xia, Wenjie Li, and Roberto Navigli (eds.), Proceedings of the 59th Annual Meeting of the Association for Computational Linguistics and the 11th International Joint Conference on Natural Language Processing, ACL/IJCNLP 2021, (Volume 1: Long Papers), Virtual Event, August 1-6, 2021, pp. 1993–2003. Association for Computational Linguistics, 2021. doi: 10.18653/v1/2021.acl-long.155. URL https://doi.org/10.18653/v1/2021.acl-long.155.

Samyam Rajbhandari, Conglong Li, Zhewei Yao, Minjia Zhang, Reza Yazdani Aminabadi, Ammar Ahmad Awan, Jeff Rasley, and Yuxiong He. Deepspeed-moe: Advancing mixture-of-experts inference and training to power next-generation ai scale. arXiv preprint arXiv:2201.05596, 2022.

Qiu Ran, Yankai Lin, Peng Li, and Jie Zhou. Learning to recover from multi-modality errors for non-autoregressive neural machine translation. In Dan Jurafsky, Joyce Chai, Natalie Schluter, and Joel R. Tetreault (eds.), Proceedings of the 58th Annual Meeting of the Association for Computational Linguistics, ACL 2020, Online, July 5-10, 2020, pp. 3059–3069. Association for Computational Linguistics, 2020. doi: 10.18653/v1/2020.acl-main.277. URL https://doi.org/10.18653/v1/2020.acl-main.277.

Chitwan Saharia, William Chan, Saurabh Saxena, and Mohammad Norouzi. Non-autoregressive machine translation with latent alignments. In Bonnie Webber, Trevor Cohn, Yulan He, and Yang Liu (eds.), Proceedings of the 2020 Conference on Empirical Methods in Natural Language Processing, EMNLP 2020, Online, November 16-20, 2020, pp. 1098–1108. Association for Computational Linguistics, 2020. doi: 10.18653/v1/2020.emnlp-main.83. URL https://doi.org/10.18653/v1/2020.emnlp-main.83.

Nikolay Savinov, Junyoung Chung, Mikolaj Binkowski, Erich Elsen, and Aäron van den Oord. Step-unrolled denoising autoencoders for text generation. CoRR, abs/2112.06749, 2021. URL https://arxiv.org/abs/2112.06749.

Rico Sennrich, Barry Haddow, and Alexandra Birch. Neural machine translation of rare words with subword units. In Proceedings of the 54th Annual Meeting of the Association for Computational Linguistics, ACL 2016, August 7-12, 2016, Berlin, Germany, Volume 1: Long Papers. The Association for Computer Linguistics, 2016. doi: 10.18653/v1/p16-1162. URL https://doi.org/10.18653/v1/p16-1162.

Chenze Shao, Jinchao Zhang, Yang Feng, Fandong Meng, and Jie Zhou. Minimizing the bag-of-ngrams difference for non-autoregressive neural machine translation. In The Thirty-Fourth AAAI Conference on Artificial Intelligence, AAAI 2020, The Thirty-Second Innovative Applications of Artificial Intelligence Conference, IAAI 2020, The Tenth AAAI Symposium on Educational Advances in Artificial Intelligence, EAAI 2020, New York, NY, USA, February 7-12, 2020, pp. 198–205. AAAI Press, 2020. URL https://aaai.org/ojs/index.php/AAAI/article/view/5351.

Chenze Shao, Xuanfu Wu, and Yang Feng. One reference is not enough: Diverse distillation with reference selection for non-autoregressive translation. In Marine Carpuat, Marie-Catherine de Marneffe, and Iván Vladimir Meza Ruíz (eds.), Proceedings of the 2022 Conference of the North American Chapter of the Association for Computational Linguistics: Human Language Technologies, NAACL 2022, Seattle, WA, United States, July 10-15, 2022, pp. 3779–3791. Association for Computational Linguistics, 2022. doi: 10.18653/v1/2022.naacl-main.277. URL https://doi.org/10.18653/v1/2022.naacl-main.277.

Raphael Shu, Jason Lee, Hideki Nakayama, and Kyunghyun Cho. Latent-variable non-autoregressive neural machine translation with deterministic inference using a delta posterior. In The Thirty-Fourth AAAI Conference on Artificial Intelligence, AAAI 2020, The Thirty-Second Innovative Applications of Artificial Intelligence Conference, IAAI 2020, The Tenth AAAI Symposium on Educational Advances in Artificial Intelligence, EAAI 2020, New York, NY, USA, February 7-12, 2020, pp. 8846–8853. AAAI Press, 2020. URL https://ojs.aaai.org/index.php/AAAI/article/view/6413.

Jongyoon Song, Sungwon Kim, and Sungroh Yoon. Alignart: Non-autoregressive neural machine translation by jointly learning to estimate alignment and translate. In Marie-Francine Moens, Xuanjing Huang, Lucia Specia, and Scott Wen-tau Yih (eds.), Proceedings of the 2021 Conference on Empirical Methods in Natural Language Processing, EMNLP 2021, Virtual Event / Punta Cana, Dominican Republic, 7-11 November, 2021, pp. 1–14. Association for Computational Linguistics, 2021. doi: 10.18653/v1/2021.emnlp-main.1. URL https://doi.org/10.18653/v1/2021.emnlp-main.1.

Mitchell Stern, Noam Shazeer, and Jakob Uszkoreit. Blockwise parallel decoding for deep autoregressive models. In Samy Bengio, Hanna M. Wallach, Hugo Larochelle, Kristen Grauman, Nicolò Cesa-Bianchi, and Roman Garnett (eds.), Advances in Neural Information Processing Systems 31: Annual Conference on Neural Information Processing Systems 2018, NeurIPS 2018, December 3-8, 2018, Montréal, Canada, pp. 10107–10116, 2018. URL https://proceedings.neurips.cc/paper/2018/hash/c4127b9194fe8562c64dc0f5bf2c93bc-Abstract.html.

Mitchell Stern, William Chan, Jamie Kiros, and Jakob Uszkoreit. Insertion transformer: Flexible sequence generation via insertion operations. In Kamalika Chaudhuri and Ruslan Salakhutdinov (eds.), Proceedings of the 36th International Conference on Machine Learning, ICML 2019, 9-15 June 2019, Long Beach, California, USA, volume 97 of Proceedings of Machine Learning Research, pp. 5976–5985. PMLR, 2019. URL http://proceedings.mlr.press/v97/stern19a.html.

Xin Sun, Tao Ge, Furu Wei, and Houfeng Wang. Instantaneous grammatical error correction with shallow aggressive decoding. In Chengqing Zong, Fei Xia, Wenjie Li, and Roberto Navigli (eds.), Proceedings of the 59th Annual Meeting of the Association for Computational Linguistics and the 11th International Joint Conference on Natural Language Processing, ACL/IJCNLP 2021, (Volume 1: Long Papers), Virtual Event, August 1-6, 2021, pp. 5937–5947. Association for Computational Linguistics, 2021. doi: 10.18653/v1/2021.acl-long.462. URL https://doi.org/10.18653/v1/2021.acl-long.462.

Zhiqing Sun and Yiming Yang. An EM approach to non-autoregressive conditional sequence generation. In Proceedings of the 37th International Conference on Machine Learning, ICML 2020, 13-18 July 2020, Virtual Event, volume 119 of Proceedings of Machine Learning Research, pp. 9249–9258. PMLR, 2020. URL http://proceedings.mlr.press/v119/sun20c.html.

Zhiqing Sun, Zhuohan Li, Haoqing Wang, Di He, Zi Lin, and Zhi-Hong Deng. Fast structured decoding for sequence models. In Hanna M. Wallach, Hugo Larochelle, Alina Beygelzimer, Florence d'Alché-Buc, Emily B. Fox, and Roman Garnett (eds.), Advances in Neural Information Processing Systems 32: Annual Conference on Neural Information Processing Systems 2019, NeurIPS 2019, December 8-14, 2019, Vancouver, BC, Canada, pp. 3011–3020, 2019. URL https://proceedings.neurips.cc/paper/2019/hash/74563ba21a90da13dacf2a73e3ddefa7-Abstract.html.

Ashish Vaswani, Noam Shazeer, Niki Parmar, Jakob Uszkoreit, Llion Jones, Aidan N. Gomez, Lukasz Kaiser, and Illia Polosukhin. Attention is all you need. In Isabelle Guyon, Ulrike von Luxburg, Samy Bengio, Hanna M. Wallach, Rob Fergus, S. V. N. Vishwanathan, and Roman Garnett (eds.), Advances in Neural Information Processing Systems 30: Annual Conference on Neural Information Processing Systems 2017, December 4-9, 2017, Long Beach, CA, USA, pp. 5998–6008, 2017. URL https://proceedings.neurips.cc/paper/2017/hash/3f5ee243547dee91fbd053c1c4a845aa-Abstract.html.

Chunqi Wang, Ji Zhang, and Haiqing Chen. Semi-autoregressive neural machine translation. In Ellen Riloff, David Chiang, Julia Hockenmaier, and Jun'ichi Tsujii (eds.), Proceedings of the 2018 Conference on Empirical Methods in Natural Language Processing, Brussels, Belgium, October 31 - November 4, 2018, pp. 479–488. Association for Computational Linguistics, 2018. doi: 10.18653/v1/d18-1044. URL https://doi.org/10.18653/v1/d18-1044.

Yiren Wang, Fei Tian, Di He, Tao Qin, ChengXiang Zhai, and Tie-Yan Liu. Non-autoregressive machine translation with auxiliary regularization. In The Thirty-Third AAAI Conference on Artificial Intelligence, AAAI 2019, The Thirty-First Innovative Applications of Artificial Intelligence Conference, IAAI 2019, The Ninth AAAI Symposium on Educational Advances in Artificial Intelligence, EAAI 2019, Honolulu, Hawaii, USA, January 27 - February 1, 2019, pp. 5377–5384. AAAI Press, 2019. doi: 10.1609/aaai.v33i01.33015377. URL https://doi.org/10.1609/aaai.v33i01.33015377.

Bingzhen Wei, Mingxuan Wang, Hao Zhou, Junyang Lin, and Xu Sun. Imitation learning for non-autoregressive neural machine translation. In Anna Korhonen, David R. Traum, and Lluís Màrquez (eds.), Proceedings of the 57th Conference of the Association for Computational Linguistics, ACL 2019, Florence, Italy, July 28- August 2, 2019, Volume 1: Long Papers, pp. 1304–1312. Association for Computational Linguistics, 2019. doi: 10.18653/v1/p19-1125. URL https://doi.org/10.18653/v1/p19-1125.

Chun Zeng, Jiangjie Chen, Tianyi Zhuang, Rui Xu, Hao Yang, Ying Qin, Shimin Tao, and Yanghua Xiao. Neighbors are not strangers: Improving non-autoregressive translation under low-frequency lexical constraints. In Marine Carpuat, Marie-Catherine de Marneffe, and Iván Vladimir Meza Ruíz (eds.), Proceedings of the 2022 Conference of the North American Chapter of the Association for Computational Linguistics: Human Language Technologies, NAACL 2022, Seattle, WA, United States, July 10-15, 2022, pp. 5777–5790. Association for Computational Linguistics, 2022. doi: 10.18653/v1/2022.naacl-main.424. URL https://doi.org/10.18653/v1/2022.naacl-main.424.

Jiaao Zhan, Qian Chen, Boxing Chen, Wen Wang, Yu Bai, and Yang Gao. Non-autoregressive translation with dependency-aware decoder. CoRR, abs/2203.16266, 2022. doi: 10.48550/arXiv.2203.16266. URL https://doi.org/10.48550/arXiv.2203.16266.

Zaixiang Zheng, Hao Zhou, Shujian Huang, Jiajun Chen, Jingjing Xu, and Lei Li. Duplex sequence-to-sequence learning for reversible machine translation. In Marc'Aurelio Ranzato, Alina Beygelzimer, Yann N. Dauphin, Percy Liang, and Jennifer Wortman Vaughan (eds.), Advances in Neural Information Processing Systems 34: Annual Conference on Neural Information Processing Systems 2021, NeurIPS 2021, December 6-14, 2021, virtual, pp. 21070–21084, 2021. URL https://proceedings.neurips.cc/paper/2021/hash/afecc60f82be41c1b52f6705ec69e0f1-Abstract.html.

Minghao Zhu, Junli Wang, and Chungang Yan. Non-autoregressive neural machine translation with consistency regularization optimized variational framework. In Marine Carpuat, Marie-Catherine de Marneffe, and Iván Vladimir Meza Ruíz (eds.), Proceedings of the 2022 Conference of the North American Chapter of the Association for Computational Linguistics: Human Language Technologies, NAACL 2022, Seattle, WA, United States, July 10-15, 2022, pp. 607–617. Association for Computational Linguistics, 2022. doi: 10.18653/v1/2022.naacl-main.45. URL https://doi.org/10.18653/v1/2022.naacl-main.45.

APPENDIX

A   HYPERPARAMETERS

Hyper-parameters of training SpecDec are listed in Table 7. Following Vaswani et al. (2017) and Ott et al. (2018), we also average model parameters from the last 10 checkpoints.

Hyperparameter	Value	Hyperparameter	Value
devices	8 Nvidia V100 GPU	devices	8 Nvidia V100 GPU
label smoothing	0.1	label smoothing	0.1
# max tokens	20000	# max tokens	4096
update frequency	4	update frequency	4
dropout rate	[0.1, 0.2, 0.3]	dropout rate	[0.1, 0.2, 0.3]
max source positions	1000	max source positions	1000
max target positions	1000	max target positions	1000
Adam lr	1×10^{-3}	Adam lr	5×10^{-4}
Adam β_1	0.9	Adam β_1	0.9
Adam β_2	0.99	Adam β_2	0.999
lr-scheduler	inverse square	Adam ϵ	1×10^{-6}
warm-up lr	1×10^{-7}	lr-scheduler	inverse square
weight decay	0.00001	warm-up lr	1×10^{-7}
clip norm	3.0	weight decay	0.01
# warmup updates	4000	clip norm	5.0
max updates	100K	# warmup updates	10000
max epoch	1000	max updates	300K

Table 7: Hyper-parameters and settings of the AT verifier (left) and the NAT drafter (right).

B   DETAILS OF EXPERIMENTAL RESULTS

B.1   SPEEDUP RESULTS FOR MACHINE TRANSLATION

While we only report the speedup results of EN-DE translation in the main body of this paper due to space limitation, we here report speedup details of EN-DE, DE-EN, EN-RO and RO-EN in Table 8. As demonstrated in Section 5.3.1, we tune the hyperparameters (k, β and τ) of SpecDec/SpecDec++ on the development set for each direction of benchmarks. According to Table 8, SpecDec/SpecDec++ performs consistently well on all the language pairs despite slight differences in speedup ratios.

	Models	EN-X				X-EN			
		β, τ	Iter.	BLEU	Speed	β, τ	Iter.	BLEU	Speed
AT	AT verifier ($b = 1$)	-	N	28.73	1.1×	-	N	32.18	1.1×
	NAT drafter	-	1.6	26.48	14.3×	-	1.5	30.23	14.0×
WMT14	SpecDec ($k = 25$)	-	4.9	28.73	3.0×	-	4.4	32.18	3.0×
EN-DE	SpecDec++ ($k = 25$, *high-quality*)	3,1.0	4.0	28.89	3.6×	3,1.0	3.4	32.56	3.9×
	SpecDec++ ($k = 25$, *high-efficiency*)	5,3.0	3.1	28.73	4.5×	5,3.0	2.5	32.19	4.8×
AT	AT verifier ($b = 1$)	-	N	34.83	1.1×	-	N	34.65	1.1×
	NAT drafter	-	1.6	32.08	13.3×	-	1.6	32.21	13.8×
WMT16	SpecDec ($k = 25$)	-	6.4	34.83	2.2×	-	5.9	34.65	2.4×
EN-RO	SpecDec++ ($k = 25$, *high-quality*)	5,4.0	4.5	35.32	3.1×	3,2.0	4.6	34.98	2.9×
	SpecDec++ ($k = 25$, *high-efficiency*)	5,6.0	4.0	34.92	3.3×	5,3.0	4.0	34.80	3.3×

Table 8: Details of the main results of SpecDec/SpecDec++ on WMT benchmarks. *X* denotes the corresponding language in each benchmark (*German* in WMT14 EN-DE and *Romanian* in WMT16 EN-RO). k is the block size. β indicates the Top-β selection in SpecDec++ and τ is the tolerance hyperparameter. All hyperparameters (k, β and τ) are tuned on the development set of each benchmark.

B.2 SPEEDUP DISTRIBUTION

To further understand the acceleration effects of SpecDec, we present the speedup distribution of a single sentence on the WMT14 EN-DE test set (which has 3,003 sentences in total) in Figure 4, showing that most sentences are translated with a $3\times \sim 6\times$ speedup compared to the beam search baseline, while some rare cases can even achieve over $10\times$ speedup.

Figure 4: Single sentence speedup distribution by SpecDec++ ($k = 25$, *high-efficiency*).

Models	BLEU	Rep.
AT (greedy)	28.73	0.18%
CMLM ($T = 4$)	25.75	1.13%
CMLM ($T = 10$)	27.09	0.24%
SpecDec	28.73	0.18%
SpecDec++	**28.89**	**0.17%**

Table 9: Token repetition ratio on WMT14 EN-DE. SpecDec-base is test with hyper-parameters $k = 25$, *top-3*, $\tau = 1.0$. CMLM is tested with our implementation with the length beam set to 3.

B.3 WORD REPETITIONS

With the conditional independence assumption, NAT models show a serious weakness in modeling highly multimodal distributions. The token repetition ratio is often utilized as a proxy to measure this *multi-modality* problem, which represents the degree of the text inconsistency. However, the role of our AT verifier guarantees that this problem does not exist in SpecDec. As shown in Table 9, the token repetition ratio of SpecDec/SpecDec++ is similar to that of our AT baseline, which is significantly lower than most relevant NAT models.

B.4 TEACHER MODEL(S)

We study the effects of the teacher[10] on SpecDec, by comparing the results of a single teacher with the teacher ensemble of 3 Transformer-big models in Table 10. Compared with a single teacher model, teacher ensemble improves all the NAT drafter, AT verifier, and end-to-end SpecDec/SpecDec++ results, indicating that our approach can benefit from a better teacher.

	Models	Single Teacher			Teacher Ensemble		
		Iter.	BLEU	Speed	Iter.	BLEU	Speed
Teacher	Transformer-big ($b = 5$)	N	29.31	-	N	30.64	-
Base	NAT drafter	1.6	26.48	**14.3×**	1.6	**27.16**	14.0×
	AT verifier ($b = 5$)	N	28.89	1.0×	N	29.19	1.0×
	AT verifier ($b = 1$)	N	28.73	1.1×	N	29.24	1.1×
	SpecDec ($k = 25$)	4.9	28.73	3.0×	4.5	29.24	3.3×
	SpecDec++ ($k = 25$, *top-3*, $\tau = 1.0$)	4.0	28.89	3.6×	4.0	29.31	3.4×
	SpecDec++ ($k = 25$, *top-5*, $\tau = 3.0$)	3.1	28.73	**4.5×**	3.1	**29.52**	4.3×
Big	NAT drafter	1.4	27.35	**15.0×**	1.4	**28.10**	14.8×
	AT verifier ($b = 5$)	N	29.25	1.0×	N	29.74	1.0×
	AT verifier ($b = 1$)	N	29.18	1.1×	N	29.69	1.1×
	SpecDec ($k = 30$)	4.8	29.18	3.0×	4.2	29.69	3.3×
	SpecDec++ ($k = 30$, *top-3*, $\tau = 1.0$)	4.2	29.32	3.5×	3.8	**29.88**	3.6×
	SpecDec++ ($k = 30$, *top-5*, $\tau = 6.0$)	2.6	29.15	5.0×	2.5	29.81	**5.1×**

Table 10: Performance comparison between a single teacher model and teacher ensemble (3 teacher models) on WMT14 EN-DE. We report the results of both base-size and big-size SpecDec. Transformer-base/big with beam search are the speed baselines of SpecDec-base/big respectively.

---

[10]We will release all our teachers to facilitate reproducing our results.

B.5 Results for Transformer-12-2

Kasai et al. (2021) points out that the Transformer with a deep encoder and a shallow decoder can achieve comparable translation quality with remarkable speedups. In Table 11, we present the results of SpecDec-base with the configuration of 12 encoder layers and 2 decoder layers. The results indicate that even in the deep-shallow configuration, SpecDec/SpecDec++ can further speed up translation without quality loss.

	Models	**E-D**	**Iteration**	**BLEU**	**Speed**
AT baseline	Transformer-base (w/o Seq-KD)*	6-6	N	27.74	1.0×
Ours	Teacher	6-6	N	29.31†	-
	NAT drafter ($k = 25$)	12-2	1.6	25.67	18.1×
	AT verifier ($b = 5$)	12-2	N	29.13	1.8×
	AT verifier ($b = 1$)	12-2	N	28.99	2.0×
	SpecDec ($k = 25$)	12-2	5.6	28.99	4.6×
	SpecDec++ ($k = 25$, *top-3*, $\tau = 1.0$)	12-2	4.7	**29.13**	5.0×
	SpecDec++ ($k = 25$, *top-5*, $\tau = 4.0$)	12-2	3.4	29.00	**6.3×**

Table 11: Results of SpecDec with the deep-shallow model configuration on WMT14 EN-DE. Both the AT verifier and the NAT drafter have 12 encoder layers and 2 decoder layers. *E*: encoder depth; *D*: decoder depth. * denotes the results of AT baselines ($b = 5$) implemented by Ghazvininejad et al. (2019). † indicates results obtained by Transformer-big.

C Memory Analysis

C.1 Additional Memory Cost by SpecDec

The peak memory footnote of SpecDec during inference mainly comes from three parts:

- Static AT verifier's weights
- Static NAT drafter's weights
- Intermediate variables/results

Compared with AT, the additional memory cost of SpecDec comes from the last two parts. While the static NAT drafter's weights account for the majority of the additional memory cost, the additional cost for storing intermediate variables is negligible because the NAT drafter and AT verifier decode alternatively during inference. Compared with AT, SpecDec's additional intermediate variables/results include:

- The NAT drafter's last encoder layer's representation that will not be freed until decoding finishes, which is equal to $B \cdot S \cdot d$ where B is the batch size, S is the sequence length and d is the dimension of the model. This part is actually negligible: for example, when $B = 32$, $S = 128$, $d = 512$, this part's memory cost is only 8MB (fp32) / 4MB (fp16).
- The largest intermediate variables/results during inference:
  - For a short sequence (e.g., sentence-level inputs/outputs in MT tasks), the largest intermediate variable is the output tensor after the NAT drafter's/AT verifier's vocabulary projection layer – $B \cdot |V| \cdot k$ where B is the batch size, $|V|$ is the vocabulary size and k is the block size. Compared with the memory cost for storing the NAT drafter's weights, this part is usually smaller. Also $B \cdot k$ tokens can be easily divided into small batches (e.g., –softmax-batch in fairseq) for vocabulary projection to avoid massive memory cost in case $B \cdot |V| \cdot k$ is large.
  - For a long sequence (e.g., paragraph/document-level inputs/outputs in summarization tasks), the largest intermediate variable becomes the tensor for storing self-attention computation whose size increases quadratically with S (S is the sequence length). This variable accounts for the largest memory cost for storing intermediate results in both AT and SpecDec. Therefore, in this case, this part does not introduce additional memory cost compared with AT.

Models	Model Weights	Batch Size				
		1	4	8	16	32
AT (greedy)	232.4	243.2	271.7	301.4	366.4	494.6
SpecDec++	469.8	483.4	511.8	551.1	626.0	774.4
ΔMemory	237.4	240.2	240.1	249.7	259.6	279.8

Table 12: Peak GPU memory utilization on WMT14 EN-DE translation dataset. The results are obtained with fp32 on a single Nvidia P100 GPU. The hyperparameters of SpecDec++ are $k = 25$, *top-5*, $\tau = 3.0$.

Models	Model Weights	Memory Cost
AT (greedy)	534.6	696.9
SpecDec++	1071.4	1246.2
ΔMemory	536.8	549.3

Table 13: Peak GPU memory utilization on CNN-DM with batch size 1 with fp32 on a single Nvidia P100 GPU.

Table 12 and Table 13 show the comparisons of peak GPU memory footprint[11] (MB) between SpecDec and AT (during inference) on the above two scenarios (i.e., MT and summarization). The results are consistent with our analysis above:

> **The majority of the additional memory cost (i.e., ΔMemory) is for storing the NAT drafter's weights and the additional memory cost is not very likely to significantly increase as the batch size or sequence length increases.**

Our experiments above pre-loaded both the NAT drafter and AT verifier. In fact, it is also possible to load the static weights of the AT verifier and NAT drafter in a lazy loading manner in the meantime of GPU computation to save memory as they run alternatively. However, it is usually unnecessary in practice, because for a seq2seq model deployed on modern GPUs for online service, **it is latency rather than memory that is the performance bottleneck**. See the next section for more discussion.

C.2 MEMORY IS RARELY THE BOTTLENECK

To understand the performance bottleneck of online deployed seq2seq models, we test the latency and memory cost of T5-large[12] (around 770M parameters) with fp16 on 1 Nvidia A40 GPU running greedy decoding in the machine translation and abstractive summarization task, and show results in Table 14 and 15.

Statistics	Batch Size	
	1	32
Latency (s)	1.0▲	1.4▲
Memory Util. (MB)	1482	2003
Memory Util. (%)	3.0	4.0

Table 14: Latency and peak GPU memory utilization of T5-Large on WMT14 EN-DE.

Statistics	Batch Size	
	1	32
Latency (s)	2.7▲	4.7▲
Memory Util. (MB)	2999	7230
Memory Util. (%)	6.2	15.0

Table 15: Latency and peak GPU memory utilization of T5-Large on CNN-DM.

For MT, T5-large's latency is over 1 second which is actually too long to be accepted because most MT engines in practice require the latency to be less than 100ms. However, its memory cost is only less than 2GB – far below A40 GPU's memory capacity (i.e., 48GB[13]).

---

[11]Tested with the command `torch.cuda.max_memory_allocated()`

[12]In practice, T5-large is rarely deployed for online service because it is too large and expensive to serve.

[13]It can also easily scale to 96GB with NVIDIA NVLink connection of multiple GPUs.

For abstractive summarization, even if the batch size increases to 32, its memory cost is still less than 50% utilization of 1 A40 GPU but its latency is already close up to 5 seconds that is too long for an online service in practice.

To sum up, we now understand latency is the bottleneck of seq2seq models for online deployment in most cases. Therefore, we do not think additional memory cost by SpecDec will undermine its practical value; instead, we think a significant lossless acceleration even at the cost of memory (i.e., time–memory trade-off) is much more meaningful than the acceleration at the cost of quality, which should be the right path that we need to pay more attention to given much memory headroom on modern GPUs.

D   PROFILING

We show the inference time cost by modules in SpecDec++ in Table 16. The current naive implementation costs a total of approximately 16% of overall time to (sequentially) encode the input for the AT and NAT model, which can be obviously optimized. Also, the NAT decoder costs more than the AT decoder because of the multi-round computation for previously decoded tokens.

Modules	Latency(ms)	Percent(%)
AT Encoder	5.65	7.70
NAT Encoder	5.73	7.80
NAT Decoder	31.44	42.81
AT Decoder	27.33	37.21
Others	3.31	4.48
Total	73.46	100

Table 16: Profiling of SpecDec++(*base-size*, $k = 25$, *top-5*, $\tau = 3.0$) on the WMT14 EN-DE test set.

E   SPECDEC ON VARIOUS COMPUTING DEVICES

We also test[14] the inference efficiency of SpecDec with the batch implementation[15] on various GPUs, as shown in Figure 5. It is obvious that more powerful devices (e.g., V100/A100) can benefit SpecDec/SpecDec++ more (i.e., higher speedup).

Figure 5: Inference latency of SpecDec-base ($k = 25$, *top-5*, $\tau = 3.0$) on P100 (fp32), V100 (fp16) and A100 (fp16). The results are obtained on WMT14 EN-DE. The speedup baseline ($1\times$) is AT ($b = 5$) when batch = 32.

---

[14]We test with the batch size up to 32 because as the batch size increases, the inference latency per batch will become higher. Therefore, it is impractical to use a large batch size during inference, as Rajbhandari et al. (2022) points out.

[15]For simplifying implementation, we do not use incremental states in SpecDec to save the computation for previously decoded tokens as conventional AT, which means that its result is probably much underestimated. But even so, SpecDec/SpecDec++ still shows very promising speedup.

Therefore, we believe SpecDec's speedup ratio in the future can be much higher than the number we report in this paper, because it can benefit more from evolving processor hardware that will become increasingly powerful and better at parallel computing (e.g., Nvidia H100[16] with fp8 support).

F   CASE STUDY

In Table 17, we represent several examples to illustrate how SpecDec/SpecDec++ generates translations. Take *Example 1* for illustration, in the first iteration, the outputs of the drafter are non-autoregressive with *multi-modality* problems like "Angaben Angaben". The verifier accepts tokens of "Nach den" and replaces the inappropriate translation "Angaben" with "vorliegenden". In the second iteration, the verification of the vanilla SpecDec finds the bifurcation at the first position thus all tokens after this position are discarded. After 4 iterations, the decoding is finished since the `[EOS]` token is found.

Compared with the vanilla SpecDec, in the second iteration, SpecDec++ finds that the top-β candidate "Angaben" meets the relaxing requirement so that it accepts this token, showing that the relaxing constraints do help to accept more tokens for our proposed SpecDec model.

---

[16]`https://www.nvidia.com/en-us/data-center/h100/`

Example 1- vanilla SpecDec	
SOURCE	According to the details provided , the tunnel had not yet been put into use .
D	Nach den Angaben Angaben war der Tunnel noch nicht in
V	Nach den vorliegenden ~~war war der Tunnel noch nicht in Betrieb~~
D	Nach den vorliegenden Angaben war der Tunnel noch nicht in Betrieb genommen
V	Nach den vorliegenden Einzelheiten ~~war der Tunnel noch nicht in Betrieb genommen worden .~~
D	Nach den vorliegenden Einzelheiten war der Tunnel noch nicht in Betrieb genommen [EOS]
V	Nach den vorliegenden Einzelheiten war der Tunnel noch nicht in Betrieb genommen worden
D	Nach den vorliegenden Einzelheiten war der Tunnel noch nicht in Betrieb genommen worden . [EOS]
V	Nach den vorliegenden Einzelheiten war der Tunnel noch nicht in Betrieb genommen worden . [EOS]
RESULTS	Nach den vorliegenden Einzelheiten war der Tunnel noch nicht in Betrieb genommen worden .
Example 2-vanilla SpecDec	
SOURCE	Yesterday , Gut@@ acht 's Mayor gave a clear answer to this question .
D	Gestern hat der Bürger@@ meister von Gut@@ acht eine klare
V	Gestern hat Gut@@ ~~Bürger@@ meister von Gut@@ acht eine klare Antwort~~
D	Gestern hat Gut@@ acht@@ ts Bürger@@ meister eine klare Antwort auf diese Frage
V	Gestern hat Gut@@ ach@@ s ~~Bürger@@ meister eine klare Antwort auf diese Frage gegeben~~
D	Gestern hat Gut@@ ach@@ ts Bürger@@ meister eine klare Antwort auf diese Frage gegeben
V	Gestern hat Gut@@ ach@@ ts Bürger@@ meister eine klare Antwort auf diese Frage gegeben .
D	Gestern hat Gut@@ ach@@ ts Bürger@@ meister eine klare Antwort auf diese Frage gegeben . [EOS]
V	Gestern hat Gut@@ ach@@ ts Bürger@@ meister eine klare Antwort auf diese Frage gegeben . [EOS]
RESULTS	Gestern hat Gut@@ ach@@ ts Bürger@@ meister eine klare Antwort auf diese Frage gegeben .
Example 1-SpecDec++	
SOURCE	According to the details provided , the tunnel had not yet been put into use .
D	Nach den Angaben Angaben war der Tunnel noch nicht in
V	Nach den vorliegenden ~~war war der Tunnel noch nicht in Betrieb~~
D	Nach den vorliegenden Angaben war der Tunnel noch nicht in Betrieb genommen [EOS]
V	Nach den vorliegenden Angaben war der Tunnel noch nicht in Betrieb genommen worden
D	Nach den vorliegenden Angaben war der Tunnel noch nicht in Betrieb genommen worden . [EOS]
V	Nach den vorliegenden Angaben war der Tunnel noch nicht in Betrieb genommen worden . [EOS]
RESULTS	Nach den vorliegenden Angaben war der Tunnel noch nicht in Betrieb genommen worden .
Example 2-SpecDec++	
SOURCE	Yesterday , Gut@@ acht 's Mayor gave a clear answer to this question .
D	Gestern hat der Bürger@@ meister von Gut@@ acht eine klare
V	Gestern hat der Bürger@@ meister von Gut@@ acht eine klare Antwort
D	Gestern hat der Bürger@@ meister von Gut@@ acht eine klare Antwort auf diese Frage gegeben . [EOS]
V	Gestern hat der Bürger@@ meister von Gut@@ acht eine klare Antwort auf diese Frage gegeben . [EOS]
RESULTS	Gestern hat der Bürger@@ meister von Gut@@ acht eine klare Antwort auf diese Frage gegeben .

Table 17: Examples from the WMT14 English-German translation task. At each iteration, *D* and *V* are the outputs of the drafter and the verifier, respectively. Tokens within red blocks are the bifurcation positions. The verification pieces after the bifurcation are annotated as strikethrough. The highlighted parts are translations of previous iterations. Tokens in blue blocks are *top-β* candidates which meet the SpecDec++ requirement. The hyperparameters are $k = 10$, *top-3*, $\tau = 1.0$. '@@' is the BPE token, e.g., Gut@@ acht → *Gutacht*. The output pieces after the [EOS] token is omitted in the table.