# Algorithm Configuration for Structured Pfaffian Settings

**Anonymous authors**
**Paper under double-blind review**

## Abstract

Data-driven algorithm design automatically adapts algorithms to specific application domains, achieving better performance. In the context of parameterized algorithms, this approach involves tuning the algorithm's hyperparameters using problem instances drawn from the problem distribution of the target application domain. This can be achieved by maximizing empirical utilities that measure the algorithms' performance as a function of their hyperparameters, using problem instances.

While empirical evidence supports the effectiveness of data-driven algorithm design, providing theoretical guarantees for several parameterized families remains challenging. This is due to the intricate behaviors of their corresponding utility functions, which typically admit piecewise discontinuous structures. In this work, we present refined frameworks for providing learning guarantees for parameterized data-driven algorithm design problems in both distributional and online learning settings.

For the distributional learning setting, we introduce the *Pfaffian GJ framework*, an extension of the classical *GJ framework*, that is capable of providing learning guarantees for function classes for which the computation involves Pfaffian functions. Unlike the GJ framework, which is limited to function classes with computation characterized by rational functions, our proposed framework can deal with function classes involving Pfaffian functions, which are much more general and widely applicable. We then show that for many parameterized algorithms of interest, their utility function possesses a *refined piecewise structure*, which automatically translates to learning guarantees using our proposed framework.

For the online learning setting, we provide a new tool for verifying the *dispersion* property of a sequence of loss functions, a sufficient condition that allows no-regret learning for sequences of piecewise structured loss functions where the piecewise structure involves Pfaffian transition boundaries. We use our framework to provide novel learning guarantees for many challenging data-driven design problems of interest, including data-driven linkage-based clustering, graph-based semi-supervised learning, and regularized logistic regression.

## 1 Introduction

Data-driven algorithm design (Ailon et al., 2011; Gupta & Roughgarden, 2016; Balcan, 2020) is a modern approach that develops and analyzes algorithms based on the assumption that problem instances come from an underlying application domain. Unlike traditional worst-case or average-case analyses, this approach leverages observed problem instances to design algorithms that achieve high performance for specific problem domains. In many application domains (Balcan et al., 2017; 2018a; 2022a), algorithms are parameterized, meaning they are equipped with tunable hyperparameters which significantly influence their performance. We develop general techniques applicable to a large variety of parameterized algorithm families for the selection of domain-specific good algorithms by learning the hyperparameters from the problem instances coming from the domain.

Typically, the performance of an algorithm is evaluated by a specific utility function. In more concrete terms, for an algorithm parameterized by $\boldsymbol{a} \in \mathcal{A}$, consider the utility function class $\mathcal{U} = \{u_{\boldsymbol{a}} : \mathcal{X} \to [0, H] \mid \boldsymbol{a} \in \mathcal{A}\}$, where $u_{\boldsymbol{a}}(\boldsymbol{x})$ gauges the performance of the algorithm with hyperparameters $\boldsymbol{a}$ when inputting

a problem instance $\boldsymbol{x}$. In the data-driven algorithm design setting, we assume an unknown underlying distribution $\mathcal{D}$ over $\mathcal{X}$, representing the application domain on which the algorithm operates. Consequently, designing parameterized algorithms tailored to a specific domain corresponds to the optimal selection of hyperparameters $\boldsymbol{a}$ for the given domain.

Applications of data-driven algorithm design span various domains, including low-rank approximation (Indyk et al., 2019; 2021; Li et al., 2023), sparse linear systems solvers Luz et al. (2020), dimensionality reduction Ailon et al. (2021), among others. Its empirical success (Indyk et al., 2019; Ailon et al., 2011; Indyk et al., 2021) underscores the necessity for a theoretical understanding of this approach. Intensive efforts have been made towards theoretical understanding for data-driven algorithm design, including learning guarantees for numerical linear algebra methods (Bartlett et al., 2022), tuning regularization hyperparameters for regression problems (Balcan et al., 2022a; 2023b), unsupervised and semi-supervised learning (Balcan et al., 2018c; 2020a; Balcan & Sharma, 2021), application to integer and mixed-integer programming (Balcan et al., 2018a; 2021b), to name but a few.

Prior theoretical work on data-driven algorithm design focuses on two main settings: distributional (also known as statistical/batch) learning (Balcan et al., 2021a; Bartlett et al., 2022) and online learning (Balcan et al., 2018b). In the distributional learning setting, there is a learner trying to optimize hyperparameters for the algorithm within a specific domain, given access to problem instances from that domain. In this case, the question is about the sample complexity: How many problem instances are required to learn good hyperparameters that guarantee the algorithm's performance in that domain? In the online learning setting, there is a sequence of problem instances chosen by an adversary arriving over time. The goal now is to design a no-regret learning algorithm: adjusting the algorithm's hyperparameters on the fly so that the difference between the average utility and the utility corresponding to the best hyperparameters in hindsight diminishes over time.

The main challenge in establishing learning guarantees for the utility function classes lies in the complex structure of the utility function. In other words, even a minimal perturbation in $\boldsymbol{a}$ can lead to a drastic change in the performance of the algorithm, making the analysis of such classes of utility functions particularly challenging. In response to this challenge, prior work takes an alternative approach by analyzing the dual utility function class $\mathcal{U}^* = \{u^*_{\boldsymbol{x}} : \mathcal{A} \to [0, H] \mid \boldsymbol{x} \in \mathcal{X}\}$, of which each function often admits piecewise structured behavior (Balcan et al., 2021a; 2017; Bartlett et al., 2022).

Building upon this observation, in the distributional learning setting, Balcan et al. (2021a) propose a general approach that analyzes the learnability of the utility function class via the piece and boundary functions class induced by the piecewise structure. Targeting a more restricted scenario, Bartlett et al. (2022) introduced a refinement for the *GJ framework* (Goldberg & Jerrum, 1993), which establishes tighter guarantees for utility function classes of which the piecewise structure involves only rational functions. In the online learning setting, Balcan et al. (2018b) introduce the *dispersion* condition, which serves as a sufficient condition allowing no-regret learning for piecewise Lipschitz functions. Essentially, the dispersion property implies that if the discontinuities of utility function sequences do not densely concentrate in any small region of the hyperparameter space, then no-regret learning is possible.

Despite their broad applicability, these generalized frameworks exhibit inherent limitations. In the distributional learning setting, the framework introduced by Balcan et al. (2021a) reduces the problem of computing the learning-theoretic complexity of a piecewise structured utility function to the complexities of the corresponding piece and boundary functions, but these might themselves be challenging to compute for certain function classes. The refined GJ framework instantiated by Bartlett et al. (2022) is limited to the cases where the computation of utility functions only involves rational functions of the hyperparameters. For the online learning setting, the dispersion property is generally challenging to verify (Balcan et al., 2018b; 2020b; Balcan & Sharma, 2021), and requires further assumptions on the discontinuity of utility functions sequence. Moreover, when the form of discontinuities goes beyond affine and rational functions, prior techniques for verifying dispersion no longer apply.

Motivated by the limitations of prior research, part of this work aims to present refined theoretical frameworks for data-driven algorithm design when the utility function admits a specific structure. In the distributional learning setting, we introduce a powerful *Pfaffian GJ framework* that can establish learning guarantees for

function classes whose discontinuity involves *Pfaffian functions*. Roughly speaking, Pfaffian is a very general class of functions that captures a wide range of functions of interest, including rational, exponentiation, and combinations of those, among others. Furthermore, we demonstrate that many data-driven algorithm design problems exhibit a specific *refined Pfaffian piecewise structure*, which, when combined with the Pfaffian GJ framework, can establish learning guarantees for such problems. In the online learning setting, we introduce a novel tool to verify the dispersion property, where the discontinuity of utility function sequences involves Pfaffian functions, which go beyond affinity and rational functions.

Another aim of this work is to provide learning guarantees for several under-investigated data-driven algorithm design problems, where the piecewise structure of the utility functions involves Pfaffian functions. The problems we consider have been investigated in simpler settings, including data-driven agglomerative hierarchical clustering (Balcan et al., 2017; 2020a), data-driven semi-supervised learning (Balcan & Sharma, 2021), and data-driven regularized logistic regression (Balcan et al., 2023b). However, previous investigations have limitations: they either have missing results for natural extensions of the settings under study (Balcan et al., 2017; Balcan & Sharma, 2021), require strong assumptions (Balcan et al., 2020a), or solely consider distributional learning settings (Balcan et al., 2023b). Moreover, we emphasize that *the techniques used in prior work are insufficient and cannot be applied in our settings*, which involve Pfaffian analysis.

By carefully analyzing the utility functions associated with these problems, we uncover their underlying Pfaffian structures and carefully control the corresponding Pfaffian complexities, which allows us to leverage our proposed frameworks to establish learning guarantees. It is important to note that analyzing those specific problems poses a significant challenge: a loose estimation of the Pfaffian function complexity when combined with our proposed frameworks would still lead to loose or vacuous learning guarantees.

**Contributions.** In this work, we provide a refined framework for theoretical analysis of data-driven algorithm design problems. We then investigate many under-investigated data-driven algorithm design problems, analyzing their underlying problem structure, and then leveraging our newly proposed frameworks to provide learning guarantee for those problems. Concretely, our contributions are :

- We present the Pfaffian GJ framework (Definition 5, Theorem 4.2), a general approach for analyzing the pseudo-dimension of various function classes of interest. This framework draws inspiration from the refined version of the GJ framework introduced by Bartlett et al. (2022). However, in contrast to the conventional GJ framework which is only capable of handling computation related to rational functions, the Pfaffian GJ framework can handle computations that involve Pfaffian functions—a much broader function class—significantly increasing its applicability. We note that our proposed Pfaffian GJ framework is of independent interest and can be applied to other problems beyond data-driven algorithm design.

- For distributional learning (statistical/batch) data-driven algorithm design, we introduce a refined piecewise structures (Definition 8) for the dual utility function class, which applies whenever the piece and boundary functions are Pfaffian. In contrast to the prior piecewise structure proposed by (Balcan et al., 2021a; Bartlett et al., 2022), our framework can be used to obtain concrete learning guarantees when the piece and boundary functions belong to the class of Pfaffian functions, which includes widely used utility functions, including the exponential and logarithmic functions. We then show how the refined piecewise structure can be combined with the newly proposed Pfaffian GJ framework to provide learning guarantees (Theorem 5.2) for problems that satisfy this property.

- For online learning data-driven algorithm design, we introduce a general approach (Theorem 7.2, Theorem 7.3) for verifying the *dispersion* property (Balcan et al., 2018b)—a sufficient condition for online learning in data-driven algorithm design. Prior work (Balcan et al., 2020b; Balcan & Sharma, 2021) provides techniques for verifying dispersion only when the piece boundaries are algebraic functions. We significantly expand the class of functions for which online learning guarantees may be obtained by establishing a novel tool which applies for Pfaffian boundary functions.

- We derive novel learning guarantees for a variety of understudied data-driven algorithm design problems, including data-driven agglomerative clustering (Theorem 6.1), data-driven graph-based semi-supervised learning (Theorem 6.4), as well as recover the guarantee for data-driven regularized logistic regression in

previous work by Balcan et al. (2023b). By carefully analyzing the underlying structures of the utility functions for these problems, we can convert them into the form of our proposed frameworks, which automatically yield learning guarantees.

## 2 Related work

**Data-driven algorithm design.** Data-driven algorithm design (Ailon et al., 2011; Gupta & Roughgarden, 2016; Balcan, 2020) is a modern approach for automatically configuring algorithms and making them adaptive to specific application domains. In contrast to conventional algorithm design and analysis, which predominantly focuses on worst-case or average-case scenarios, data-driven algorithm design assumes the existence of an (unknown) underlying problem distribution that dictates the problem instance that algorithms encounter. The main objective is to identify optimal configurations for such algorithms, leveraging available problem instances at hand drawn from the same application domain. Empirical works have consistently validated the effectiveness of data-driven algorithm approaches in various domains, including matrix low-rank approximation (Indyk et al., 2019; 2021), matrix sketching (Li et al., 2023), mixed-integer linear programming (Cheng et al., 2024), among others. These findings underscore the application of the data-driven algorithm design approach in real-world applications.

**Distributional learning guarantee for data-driven algorithm design.** Motivated by the empirical successes of data-driven algorithm design, there is an emerged line of work that focuses on theoretically analyzing its underlying mechanism, mostly focusing on providing statistical generalization guarantees. This includes learning guarantee for data-driven algorithm designs of low-rank approximation and sketching (Bartlett et al., 2022), learning metrics for clustering (Balcan et al., 2020a; Balcan & Sharma, 2021; Balcan et al., 2018c), integer and mixed-integer linear programming (Balcan et al., 2021b; 2022b; 2018a), hyperparameter tuning for regularized regression (Balcan et al., 2022a; 2023b), decision tree learning (Balcan & Sharma, 2024), robust nearest-neighbors (Balcan et al., 2023a) among others.

Remarkably, Balcan et al. (2021a) introduced a general framework for establishing learning guarantees for problems that admit a specific piecewise structure. Despite its broad applicability, the framework exhibits limitations: (1) it requires an intermediate task of analyzing the dual piece and boundary function classes, which are not trivial tasks, and (2) naively applying the framework will likely lead to sub-optimal bounds (see Balcan et al., 2020a, Lemma 7, or Bartlett et al., 2022, Appendix E.3 for example). Building upon this insight, Bartlett et al. (2022) instantiated a refinement of the classical GJ framework (Goldberg & Jerrum, 1993), offering an improved learning guarantee for data-driven algorithm design where the piecewise structure involves only rational functions. However, it is essential to note that their framework has limitations since it cannot be applied beyond rational structures.

**Online learning guarantee for data-driven algorithm design.** Another line of work focuses on providing no-regret learning guarantees for data-driven algorithm design problems in online learning settings. This includes online learning guarantees for heuristic knapsack, SDP-rounding for integer quadratic programming Balcan et al. (2017), and data-driven linkage-based clustering Balcan et al. (2020b), among others.

Online learning for data-driven algorithm design is generally a challenging task due to the discontinuity and piecewise structure of the utility functions encountered. Most works provide learning guarantees in this setting by verifying the dispersion of the utility function sequence, a sufficient condition proposed by Balcan et al. (2018b) stating that the discontinuity of the sequence is not highly concentrated in any small region. However, verifying the dispersion property is generally challenging. Balcan et al. (2020b) provided a tool for verifying the dispersion property, targeting cases where the discontinuity is described by the roots of random polynomials for one-dimensional hyperparameters or algebraic curves in the two-dimensional case. Balcan & Sharma (2021) then generalize this, providing a tool for discontinuities described by algebraic varieties in higher-dimensional cases.

**Algorithms with predictions.** Another modern approach for design algorithms is *algorithms with predictions* (Mitzenmacher & Vassilvitskii, 2022), in which prediction is integrated at certain stages of algorithms to enhance their performance. Typically, this approach assumes the existence of a machine learning model

capable of receiving problem instances as input and generating predictions specific to each instance. The performance analysis of these algorithms is closely tied to the quality of predictions generated by the machine learning models. A higher quality of predictions generally correlates with improved algorithmic performance. Hence, the algorithm, now integrated with predictive models, is analyzed based on its inherent algorithmic performance and the quality of predictions. Algorithms with predictions have proved their efficacy in various classical problems, including support estimation (Eden et al., 2021), page migration (Indyk et al., 2022), online matching, flows, and load balancing (Lavastida et al., 2020), among others (Khodak et al., 2022; Lykouris & Vassilvitskii, 2021; Wei & Zhang, 2020).

While having many similarities and overlapping traits, there is a fundamental distinction between the two approaches. Data-driven algorithm design primarily seeks to optimize algorithmic hyperparameters directly for specific application domains. On the other hand, algorithms with predictions aim to incorporate prediction in some stages, with the hope that it will improve the performance of the algorithms if the quality of the prediction is good. Besides, algorithms with predictions also have to decide what qualities or quantities in the algorithms to predict, and how to predict using the input problem instance, which heavily affects the performance and properties of algorithms. It is worth noting that these two directions can complement each other and be integrated into the same system, as explored in numerous prior studies.

## 3 Preliminaries

In this section, we adhere closely to the problem setting and notation introduced by Balcan et al. (2021a).

**Parameterized algorithms, utility function class, and dual utility function class.** In this work, our main focus is on parameterized algorithms, in which each algorithm has a set of hyperparameters $\boldsymbol{a} \in \mathcal{A} \subseteq \mathbb{R}^d$ that have great influence on the performance of the algorithm. Let $\mathcal{X}$ represent the set of input problem instances on which the algorithm operates. The performance of the algorithm for any hyperparameter is measured by the *utility function* $u : \mathcal{X} \times \mathcal{A} \to [0, H]$, where $u(\boldsymbol{x}, \boldsymbol{a})$ represents the performance of the algorithm when operating on input problem instance $\boldsymbol{x}$ and be parameterized by $\boldsymbol{a}$. The *utility function class* $\mathcal{U}$ of the algorithm is then defined as $\mathcal{U} = \{u_{\boldsymbol{a}} : \mathcal{X} \to [0, H] \mid a \in \mathcal{A}\}$. The utility function class $\mathcal{U}$ plays a central role in our analysis since the problem of tuning hyperparameter $\boldsymbol{a}$ for the algorithm can be formulated as the problem of analyzing the learnability of $\mathcal{U}$ in both distributional and online learning described below.

However, in data-driven algorithm design, the structure of the utility function class $\mathcal{U}$ can be very intricate in the sense that: (1) a very small variation of the hyperparameter $\boldsymbol{a}$ can lead to sharp, unpredictable changes in the utility function $u_{\boldsymbol{a}}$, and (2) the utility function $u_{\boldsymbol{a}}$ corresponding to a fixed $\boldsymbol{a}$ admits a very complicated structure as a function of $\boldsymbol{x}$. Hence, analyzing $\mathcal{U}$ is often conducted via analyzing the dual utility function class $\mathcal{U}^*$, which often admits a certain degree of structure. The *dual utility function class* $\mathcal{U}^*$ of $\mathcal{U}$ can be defined as $\mathcal{U}^* = \{u^*_{\boldsymbol{x}} : \mathcal{A} \to [0, H] \mid \boldsymbol{x} \in \mathcal{X}\}$, of which each dual utility function $u^*_{\boldsymbol{x}}$ corresponding to a fixed problem instance $\boldsymbol{x}$ is defined as $u^*_{\boldsymbol{x}}(\boldsymbol{a}) := u_{\boldsymbol{a}}(\boldsymbol{x})$, which consists of utility functions obtained by varying the hyperparameter $\boldsymbol{a}$ for fixed problem instances from $\mathcal{X}$. In this work, we will show that if $\mathcal{U}^*$ admits Pfaffian piecewise structure, we can recover the distributional and online learning guarantees for the utility function class $\mathcal{U}$ in several cases of interest.

**Distributional (statistical/batch) learning.** In contrast to traditional worst-case or average-case algorithm analysis, we assume the existence of an underlying problem distribution $\mathcal{D}$ over $\mathcal{X}$, which encapsulates information about the relevant application domain. Under such an assumption, our goal is to answer the sample complexity question, i.e. how many problem instances are sufficient to learn near-optimal hyperparameters of the algorithm for any application-specific problem distribution. To this end, it suffices to bound the *pseudo-dimension* (Pollard, 2012) of the corresponding utility function class $\mathcal{U}$.

**Definition 1** (Pseudo-dimension, Pollard 2012)**.** *Consider a real-valued function class $\mathcal{U}$, of which each function takes input in $\mathcal{X}$. Given a set of inputs $S = (\boldsymbol{x}_1, \ldots, \boldsymbol{x}_N)$, we say that $S$ is shattered by $\mathcal{U}$ if there exists a set of real-valued threshold $r_1, \ldots, r_N \in \mathbb{R}$ such that $|\{(sign(u(\boldsymbol{x}_1) - r_1), \ldots, sign(u(\boldsymbol{x}_N) - r_N)) \mid u \in \mathcal{U}\}| =$*

$2^N$. *The pseudo-dimension of* $\mathcal{U}$*, denoted as* $\mathrm{Pdim}(\mathcal{U})$*, is the maximum size* $N$ *of a input set that* $\mathcal{U}$ *can shatter.*

If the function class $\mathcal{U}$ is binary-valued, this corresponds to the well-known VC-dimension (Vapnik & Chervonenkis, 1974). Standard results in learning theory suggest that a bound on the pseudo-dimension implies a bound on the sample complexity (See Appendix A.1 for further background), which is formalized as follows.

**Theorem 3.1** (Vapnik & Chervonenkis, 1974)**.** *Consider a real-valued function class* $\mathcal{U}$*, of which each function takes value in* $\mathcal{X}$*. Assume that* $\mathrm{Pdim}(\mathcal{U})$ *is finite and* $\mathcal{U}$ *is bounded by* $H$*. Then given* $\epsilon > 0$ *and* $\delta \in (0,1)$*, for any* $m \geq m(\delta, \epsilon)$*, where* $m(\delta,\epsilon) = \mathcal{O}\left(\frac{H^2}{\epsilon^2}(\mathrm{Pdim}(\mathcal{F}) + \log(1/\delta)\right)$*, with probability at least* $1-\delta$ *over the draw of* $S = (\boldsymbol{x}_1, \ldots, \boldsymbol{x}_m) \sim \mathcal{D}^m$*, we have*

$$\mathbb{E}_{\boldsymbol{x}\sim\mathcal{D}}(\hat{u}_S(\boldsymbol{x})) \geq \sup_{u\in\mathcal{U}} \mathbb{E}_{\boldsymbol{x}\sim\mathcal{D}} u(\boldsymbol{x}) - \epsilon.$$

*Here* $\hat{u}_S \in \arg\max_{u\in\mathcal{U}} \frac{1}{m}\sum_{i=1}^m u(\boldsymbol{x}_i)$*.*

**Online learning.** In the online learning setting, there is a sequence of utility functions $u(\boldsymbol{x}_1, \cdot), \ldots, u(\boldsymbol{x}_T, \cdot)$ corresponding to a sequence of problem instances $(\boldsymbol{x}_1, \ldots, \boldsymbol{x}_T)$, coming over $T$ rounds. The task is to design a sequence of hyperparameters $(\boldsymbol{a}_1, \ldots, \boldsymbol{a}_T)$ for the algorithm so that the regret (w.r.t. the best hyperparameter in hindsight) is small

$$\mathrm{Regret}_T = \max_{\boldsymbol{a}\in\mathcal{A}} \sum_{t=1}^T u(\boldsymbol{x}_t, \boldsymbol{a}) - \sum_{t=1}^T u(\boldsymbol{x}_t, \boldsymbol{a}_t).$$

Our goal is to design a sequence of hyperparameters $\boldsymbol{a}_1, \ldots, \boldsymbol{a}_T$ that achieve sub-linear regret.

## 4 Pfaffian GJ framework for data-driven algorithm design

In a classical work, Goldberg & Jerrum (1993) introduced a comprehensive framework for bounding the VC-dimension (or pseudo-dimension) of parameterized function classes exhibiting a specific property. They proposed that if any function within a given class can be computed via a specific type of computation, named a GJ algorithm, consisting of fundamental operators such as addition, subtraction, multiplication, division, and conditional statements, then the pseudo-dimension of such a function class can be effectively upper bounded. The bound depends on the running time of the algorithm, offering a convenient approach to reduce the task of bounding the complexity of a function class into the more manageable task of counting the number of operators.

However, a bound based on runtime can often be overly conservative. Recently, Bartlett et al. (2022) instantiated a refinement for the GJ framework. Noting that any intermediate values the GJ algorithm computes are rational functions of parameters, Bartlett et al. proposed more refined complexity measures of the GJ framework, namely the *predicate complexity* and the *degree* of the GJ algorithm. Informally, the predicate complexity and the degree are the number of distinct rational functions in conditional statements and the highest order of those rational functions, respectively. Remarkably, based on the refined complexity measures, Bartlett et al. showed a refined bound, demonstrating its efficacy in various cases, including applications on data-driven algorithm design for numerical linear algebra.

It is worth noting that the GJ algorithm has limitations as it can only accommodate scenarios where intermediate values are rational functions. In other words, it does not capture more prevalent classes of functions, such as the exponential function. Building upon the insights gained from the refined GJ framework, we introduce an extended framework called *the Pfaffian GJ Framework*. Our framework can be used to bound the pseudo-dimension of function classes that can be computed not only by fundamental operators and conditional statements but also by a broad class of functions called Pfaffian functions, which includes exponential and logarithmic functions. Technically, our result is a refinement of the analytical approach introduced by (Khovanski, 1991; Karpinski & Macintyre, 1997; Milnor & Weaver, 1997) which is directly applicable to data-driven algorithm design. An important part of our contribution is a careful instantiation of our main result for several important algorithmic problems, as a naive application could result in significantly looser bounds on the sample complexity.

### 4.1 Pfaffian functions

We present the foundational concepts of Pfaffian chains, Pfaffian functions, and their associated complexity measures. Introduced by Khovanski (1991), Pfaffian function analysis is a tool for analyzing the properties of solution sets of Pfaffian equations. We note that these techniques have been previously used to derive an upper bound on the VC-dimension of sigmoidal neural networks (Karpinski & Macintyre, 1997).

We first introduce the notion of a *Pfaffian chain*. Intuitively, a Pfaffian chain consists of an ordered sequence of functions, in which the derivative of each function can be represented as a polynomial of the variables and previous functions in the sequence.

**Definition 2** (Pfaffian Chain, Khovanski 1991)**.** *A finite sequence of continuously differentiable functions $\eta_1, \ldots, \eta_q : \mathbb{R}^d \to \mathbb{R}$ and variables $\boldsymbol{a} = (a_1, \ldots, a_d) \in \mathbb{R}^d$ form a Pfaffian chain $\mathcal{C}(\boldsymbol{a}, \eta_1, \ldots, \eta_q)$ if there are real polynomials $P_{i,j}(\boldsymbol{a}, \eta_1, \ldots, \eta_j)$ in $a_1, \ldots, a_d, \eta_1, \ldots, \eta_j$, for for all $i \in [d]$ and $j \in [q]$, such that*

$$\frac{\partial \eta_j}{\partial a_i} = P_{i,j}(\boldsymbol{a}, \eta_1, \ldots, \eta_j).$$

Here, we emphasize again that $P_{i,j}(\boldsymbol{a}, \eta_1, \ldots, \eta_j)$ is a polynomial in $\boldsymbol{a}$ and the functions $\eta_1(\boldsymbol{a}), \ldots, \eta_j(\boldsymbol{a})$ of $\boldsymbol{a}$. We now define two complexity notations for Pfaffian chains, termed the *length* and *Pfaffian degree*, that dictate the complexity of a Pfaffian chain. The length of a Pfaffian chain is the number of functions that appear on that chain, while the Pfaffian degree of a chain is the maximum degree of polynomials that can be used to express the partial derivative of functions on that chain. Formal definitions of Pfaffian chain length and Pfaffian degree are mentioned in Definition 3.

**Definition 3** (Complexity of Pfaffian chain)**.** *Given a Pfaffian chain $\mathcal{C}(\boldsymbol{a}, \eta_1, \ldots, \eta_q)$, as defined in Definition 2, we say that the length of $\mathcal{C}$ is $q$, and Pfaffian degree of $\mathcal{C}$ is $\max_{i,j} \deg(P_{i,j})$.*

Given a Pfaffian chain, one can define the Pfaffian function, which is simply a polynomial of variables and functions on that chain.

**Definition 4** (Pfaffian functions, Khovanski 1991)**.** *Given a Pfaffian chain $\mathcal{C}(\boldsymbol{a}, \eta_1, \ldots, \eta_q)$, as defined in Definition 2, a Pfaffian function over the chain $\mathcal{C}$ is a function of the form $g(\boldsymbol{a}) = Q(\boldsymbol{a}, \eta_1, \ldots, \eta_q)$, where $Q$ is a polynomial in variables $\boldsymbol{a}$ and functions $\eta_1, \ldots, \eta_q$ in the chain $\mathcal{C}$.*

The concepts of the Pfaffian chain, functions, and complexities may be a bit abstract to unfamiliar readers. To help readers better grasp the concepts of Pfaffian chains and Pfaffian functions, here are some simple examples.

**Example 1.** Consider the chain $\mathcal{C}(a, e^a)$ consisting of the variable $a$ and the function $e^a$, where $a \in \mathbb{R}$. Then $\mathcal{C}$ is a Pfaffian chain since $\frac{d}{da} e^a = e^a$, which is a polynomial of degree 1 in $e^a$. Hence, the chain $\mathcal{C}$ has length $q = 1$ and Pfaffian degree $M = 1$. Now, consider the function $f(a) = (e^a)^2 + a^3$. We observe that $f(a)$ is a polynomial in $a$ and $e^a$. Therefore, $f(a)$ is a Pfaffian function over the chain $\mathcal{C}$.

**Example 2.** The following example is useful when analyzing the learnability of clustering algorithms. Let $\boldsymbol{\beta} = (\beta_1, \ldots, \beta_k) \in \mathbb{R}^k$ and $\alpha \in \mathbb{R}$ be variables, and let $d(\boldsymbol{\beta}) = \sum_{i=1}^k d_i \beta_i > 0$, where $d_i$ are some fixed real coefficients for $i = 1, \ldots, k$. Consider the functions $f(\alpha, \boldsymbol{\beta}) := \frac{1}{d(\boldsymbol{\beta})}$, $g(\alpha, \boldsymbol{\beta}) := \ln d(\boldsymbol{\beta})$, and $h(\alpha, \boldsymbol{\beta}) := d(\boldsymbol{\beta})^\alpha$. Then $f$, $g$, and $h$ are Pfaffian functions from the chain $\mathcal{C}(\alpha, \boldsymbol{\beta}, f, g, h)$ of length 3 and Pfaffian degree 2, since

$$\begin{aligned}
\frac{\partial f}{\partial \alpha} &= 0, & \frac{\partial f}{\partial \beta_i} &= -d_i \cdot f^2, \\
\frac{\partial g}{\partial \alpha} &= 0, & \frac{\partial g}{\partial \beta_i} &= d_i \cdot f, \\
\frac{\partial h}{\partial \alpha} &= g \cdot h, & \frac{\partial h}{\partial \beta_i} &= d_i \cdot f \cdot h.
\end{aligned}$$

### 4.2 Pfaffian GJ Algorithm

We now present a formal definition of the *Pfaffian GJ algorithm*, which shares similarities with the GJ algorithm but extends its capabilities to compute Pfaffian functions as intermediate values, in addition to basic operators and conditional statements. This improvement makes the Pfaffian GJ algorithm significantly more versatile compared to the classical GJ framework.

**Definition 5** (Pfaffian GJ algorithm)**.** *A Pfaffian GJ algorithm* $\Gamma$ *operates on real-valued inputs* $\boldsymbol{a} \in \mathcal{A} \subseteq \mathbb{R}^d$*, and can perform three types of operations:*

- *Arithmetic operators of the form* $v'' = v \odot v'$*, where* $\odot \in \{+, -, \times, \div\}$*.*
- *Pfaffian operators of the form* $v'' = \eta(v)$*, where* $\eta : \mathbb{R} \to \mathbb{R}$ *is a Pfaffian function.*
- *Conditional statements of the form "if* $v \geq 0 \ldots$ *else* $\ldots$*".*

*Here* $v$ *and* $v'$ *are either inputs or (intermediate) values previously computed by the algorithm.*

The main difference between the classical GJ algorithm (Goldberg & Jerrum, 1993; Bartlett et al., 2022) and our Pfaffian GJ algorithm is that we allow unary Pfaffian operators in the algorithmic computation. By leveraging the fundamental properties of Pfaffian chains and functions, we can easily show that all intermediate functions computed by a specific Pfaffian GJ algorithm come from the same Pfaffian chain (see Appendix B.1 for details). Therefore, for a Pfaffian GJ algorithm $\Gamma$, we can define a Pfaffian chain $\mathcal{C}$ corresponding to $\Gamma$, as formalized below.

**Definition 6** (Pfaffian chain associated with Pfaffian GJ algorithm)**.** *Given a Pfaffian GJ algorithm* $\Gamma$ *operating on real-valued inputs* $\boldsymbol{a} \in \mathcal{A} \subseteq \mathbb{R}^d$*, we say that a Pfaffian chain* $\mathcal{C}$ *is associated with* $\Gamma$ *if all the intermediate values computed by* $\Gamma$ *is a Pfaffian function from the chain* $\mathcal{C}$*.*

This remarkable property enables us to control the complexity of the Pfaffian GJ algorithm $\Gamma$ by controlling the complexity of the corresponding Pfaffian chain $\mathcal{C}$. We formalize this claim in the following lemma.

**Lemma 4.1.** *For any Pfaffian GJ algorithm* $\Gamma$ *involving a finite number of operations, there is a Pfaffian chain* $\mathcal{C}$ *of finite length associated with* $\Gamma$*.*

*Proof Sketch.* The Pfaffian chain $\mathcal{C}$ can be constructed recursively as follows. Initially, we create a Pfaffian chain of variables $\boldsymbol{a}$ with length 0. Using the basic properties of Pfaffian functions discussed in Appendix B.1, each time $\Gamma$ computes a new value $v$, one of the following cases arises: (1) $v$ is a Pfaffian function on the current chain $\mathcal{C}$, or (2) we can extend the chain $\mathcal{C}$ by adding new functions, increasing its length (but still finite), such that $v$ becomes a Pfaffian function on the modified chain $\mathcal{C}$. □

**Remark 1.** *We note that each Pfaffian GJ algorithm* $\Gamma$ *can be associated with various Pfaffian chains, with different complexities. For example, if* $\mathcal{C}(\boldsymbol{a}, \eta_1, \ldots, \eta_q)$ *is a Pfaffian chain corresponding to* $\Gamma$*, then* $\mathcal{C}'(\boldsymbol{a}, \eta_1, \ldots, \eta_q, e^{a_1})$ *is also a Pfaffian chain corresponding to* $\Gamma$*, but with a greater length compared to* $\mathcal{C}$*. Therefore, in any specific application, designing the corresponding Pfaffian chain* $\mathcal{C}$ *for* $\Gamma$ *with a small complexity is a crucial task that requires careful analysis.*

We now present our main technical tool, which can be used to bound the pseudo-dimension of a function class by expressing the function computation as a Pfaffian GJ algorithm and giving a bound on the complexity of the associated Pfaffian chain. Technical background for the proof is located in Appendix B.2.

**Theorem 4.2.** *Consider a real-valued function class* $\mathcal{U} = \{u_{\boldsymbol{a}} : \mathcal{X} \to \mathbb{R} \mid \boldsymbol{a} \in \mathcal{A}\}$ *with domain* $\mathcal{X}$*, of which each function* $u_{\boldsymbol{a}} \in \mathcal{U}$ *is parameterized by* $\boldsymbol{a} \in \mathcal{A} \subseteq \mathbb{R}^d$*. Suppose that for every* $\boldsymbol{x} \in \mathcal{X}$ *and* $r \in \mathbb{R}$*, there is a Pfaffian GJ algorithm* $\Gamma_{\boldsymbol{x},r}$*, with associated Pfaffian chain* $\mathcal{C}_{\boldsymbol{x},r}$ *of length at most* $q$ *and Pfaffian degree at most* $M$*, that given* $u_{\boldsymbol{a}} \in \mathcal{U}$*, check whether* $u_{\boldsymbol{a}}(\boldsymbol{x}) > r$*. Moreover, assume that values computed at intermediate steps of* $\Gamma_{\boldsymbol{x},r}$ *are from the Pfaffian chain* $\mathcal{C}_{\boldsymbol{x},r}$*, each of degree at most* $\Delta$*; and the functions computed in the conditional statements are of at most* $K$ *Pfaffian functions. Then* $\mathrm{Pdim}(\mathcal{U}) \leq d^2q^2 + 2dq\log(\Delta + M) + 4dq\log d + 2d\log\Delta K + 16d$*.*

*Proof.* To bound $\text{Pdim}(\mathcal{U})$, the overall idea is that given $N$ input problem instances $\boldsymbol{x}_1, \ldots, \boldsymbol{x}_N$ and $N$ thresholds $r_1, \ldots, r_N$, we bound $\Pi_{\mathcal{U}}(N)$, the number of distinct sign patterns

$$\begin{aligned} & (\text{sign}(u_{\boldsymbol{a}}(\boldsymbol{x}_1) - r_1 > 0), \ldots, \text{sign}(u_{\boldsymbol{a}}(\boldsymbol{x}_N) - r_N > 0)) \\ = \; & (\text{sign}(u^*_{\boldsymbol{x}_N}(\boldsymbol{a}) - r_1 > 0), \ldots, \text{sign}(u^*_{\boldsymbol{x}_N}(\boldsymbol{a}) - r_N > 0)) \end{aligned}$$

obtained by varying $\boldsymbol{a} \in \mathcal{A}$. Then we solve the inequality $2^N \leq \Pi_{\mathcal{L}}(N)$ to obtain an upper bound for $\text{Pdim}(\mathcal{U})$.

From assumption, for each $\boldsymbol{x_i}$ and a threshold value $r_i$, the value of $\text{sign}(u_{\boldsymbol{a}}(\boldsymbol{x}_i) - r_i) = \text{sign}(u^*_{\boldsymbol{x}_i}(\boldsymbol{a}) - r_i)$ can be computed by a Pfaffian GJ algorithm $\Gamma_{\boldsymbol{x}_i, r_i}$ that takes input as $\boldsymbol{a}$ and return if $u_{\boldsymbol{a}}(\boldsymbol{x}_i) > r_i$.

Again, from the assumption, the Pfaffian GJ algorithm $\Gamma_{\boldsymbol{x}_i, r_i}$ has at most $K$ conditional statements, each determines if $\tau_{\boldsymbol{x},i}(\boldsymbol{a}) \geq 0$, where $\tau_{\boldsymbol{x},i}(\boldsymbol{a})$ is a Pfaffian function from the Pfaffian chain $\mathcal{C}_{\boldsymbol{x}_i}$ of length at most $q$ and Pfaffian degree at most $\Delta$ corresponding to $\Gamma_{\boldsymbol{x},i}$.

Therefore, each binary value $\text{sign}(u^*_{\boldsymbol{x}_i}(\boldsymbol{a}) - r_i)$ is determine by at most $K$ other values in the form $\text{sign}(\tau_{\boldsymbol{x}_i,j}(\boldsymbol{a}))$ for $j = 1, \ldots, K$, meaning that the number of patterns

$$(\text{sign}(u^*_{\boldsymbol{x}_1}(\boldsymbol{a}) - r_1 > 0), \ldots, \text{sign}(u^*_{\boldsymbol{x}_N}(\boldsymbol{a}) - r_N > 0))$$

is upper-bounded by the number of sign patterns

$$(\text{sign}(\tau_{\boldsymbol{x}_1,1}(\boldsymbol{a})), \ldots, \text{sign}(\tau_{\boldsymbol{x}_1,K}(\boldsymbol{a})), \ldots, \text{sign}(\tau_{\boldsymbol{x}_N,1}(\boldsymbol{a})), \ldots, \text{sign}(\tau_{\boldsymbol{x}_N,K}(\boldsymbol{a})))$$

obtained by varying $\boldsymbol{a}$. Moreover, we can construct a Pfaffian chain $\mathcal{C}'$ of length at most $qN$ and Pfaffian degree at most $\Delta$ by merging all the Pfaffian chain $\mathcal{C}_{\boldsymbol{x}_i}$, such that any function $\tau_{\boldsymbol{x},i}(\boldsymbol{a})$ above is a Pfaffian function from the Pfaffian chain $\mathcal{C}'$, and of degree at most $\Delta$.

Finally, the number of sign patterns $(\text{sign}(\tau_{\boldsymbol{x}_1,1}(\boldsymbol{a})), \ldots, \text{sign}(\tau_{\boldsymbol{x}_N,K}(\boldsymbol{a})))$ can be upper-bounded by the number of connected components of $\mathbb{R}^d - \cup_{i=1}^N \cup_{j=1}^K \{\boldsymbol{a} : \tau_{\boldsymbol{x}_i,j}(\boldsymbol{a}) = 0\}$, where $\tau_{\boldsymbol{x}_i,j}(\boldsymbol{a}) = 0$ is a Pfaffian hypersurface. Using results by Khovanski (1991) and Karpinski & Macintyre (1997) (see Appendix B.2 for background), we can establish Lemma B.6, which leads to the claimed bound $\text{Pdim}(\mathcal{U}) \leq d^2q^2 + 2dq\log(\Delta + M) + 4dq\log d + 2d\log\Delta K + 16d$.

□

**Remark 2.** *For the case $q = 0$, meaning that the functions computed in the conditional statements are merely rational functions in $\boldsymbol{a}$, Theorem 4.2 gives an upper bound of $\mathcal{O}(d\log(\Delta K))$, which matches the rate of GJ algorithm instantiated by Bartlett et al. (2022).*

## 5 Pfaffian piecewise structure for data-driven distributional learning

In this section, we analyze function classes for which the duals have a Pfaffian piecewise structure, a special case of the piecewise decomposable structure introduced by Balcan et al. (2021a). Compared to their piecewise decomposable structure, our proposed Pfaffian piecewise structure incorporates additional information about the Pfaffian structures of piece and boundary functions of the dual function classes, as well as the maximum number of forms that the piece functions can take. We argue that the additional information can be derived as a by-product in many data-driven algorithm design problems, but would be ignored if naively using the framework by Balcan et al. (2021a). We then show that if the dual utility function class $\mathcal{U}^*$ of a parameterized algorithm admits the Pfaffian piecewise structure, then we can directly establish learning guarantees for the utility function class $\mathcal{U}$. We note that the advantage of our framework compared to the framework by Balcan et al. (2021a) is two-fold: (1) our approach offers a concrete and alternative way of analyzing the pseudo-dimension for the utility function class $\mathcal{U}$, avoiding the non-trivial combinatorial tasks of analyzing the pseudo/VC-dimension of the dual piece and boundary function classes if using the framework by Balcan et al. (2021a), and (2) directly and naively applying the framework by Balcan et al. (2021a) can potentially lead to loose or vacuous bounds. Additionally, we propose a further refined argument for the case where all dual utility functions share the same boundary structures, which leads to further improved learning guarantees.

### 5.1 Prior generalization framework for piecewise structured utility functions in data-driven algorithm design and its limitations

In this section, we discuss a prior general framework for providing learning guarantees for data-driven algorithm design problems by Balcan et al. (2021a). Many parameterized algorithms, such as combinatorial algorithms and integer/mixed-integer programming (Balcan et al., 2018a; 2017), exhibit volatile utility functions with respect to their parameters. In other words, even minor changes in parameters can lead to significant alterations in the behavior of the utility function. Analyzing such volatile utility function classes poses a significant technical challenge.

Fortunately, many data-driven algorithm design problems still possess a certain degree of structure. Prior studies (Balcan et al., 2017; 2018a; 2022a; 2023b) have demonstrated that the dual utility functions associated with data-driven algorithm design problems often exhibit a piecewise structure. In other words, the parameter space of the dual utility function can be partitioned into regions, each separated by distinct *boundary functions*. Within each region, the dual utility function corresponds to a *piece function* that exhibits well-behaved properties, such as being linear, rational, or Pfaffian in nature. Building upon this insight, prior work by Balcan et al. (2021a) proposed a formal definition of a piecewise-structured dual utility function class and established a generalization guarantee applicable to any data-driven algorithm design problem conforming to such structures.

Formally, let us recall the definition of the utility function class $\mathcal{U} = \{u_{\boldsymbol{a}} : \mathcal{X} \to [0, H] \mid \boldsymbol{a} \in \mathcal{A}\}$ for an parameterized algorithm, where $\mathcal{A} \subseteq \mathbb{R}^d$. This class represents functions that evaluate the performance of the algorithm, with $u_{\boldsymbol{a}} : \mathcal{X} \to [0, H]$ denoting the utility function corresponding to parameter $\boldsymbol{a}$. For a given input problem instance $\boldsymbol{x} \in \mathcal{X}$, $u_{\boldsymbol{a}}(\boldsymbol{x})$ yields the performance evaluation of the algorithm on $\boldsymbol{x}$. Notably, for each input $\boldsymbol{x} \in \mathcal{X}$, we can define the *dual utility function corresponding to* $\boldsymbol{x}$ as $u^*_{\boldsymbol{x}} : \mathcal{A} \to [0, H]$, where $u^*_{\boldsymbol{x}}(\boldsymbol{a}) := u_{\boldsymbol{a}}(\boldsymbol{x})$ measures the performance for a specific problem instance $\boldsymbol{x}$ as a function of the parameter $\boldsymbol{a}$. Consequently, we can also define the dual utility function class $\mathcal{U}^* = \{u^*_{\boldsymbol{x}} : \mathcal{A} \to \mathbb{R} \mid \boldsymbol{x} \in \mathcal{X}\}$. It was shown in prior work (Balcan et al., 2021a; 2022a;c; 2023b) that in many data-driven algorithm design problems, every function in the dual function class $\mathcal{U}^*$ adheres to a specific piecewise structure, which can be precisely defined as follows:

**Definition 7** (piecewise decomposable, Balcan et al. 2021a)**.** *A function class $\mathcal{H} \subseteq \mathbb{R}^{\mathcal{A}}$ that maps a domain $\mathcal{A}$ to $\mathbb{R}$ is $(\mathcal{F}, \mathcal{G}, k)$-piecewise decomposable for a class $\mathcal{G} \subseteq \{0, 1\}^{\mathcal{A}}$ and a class $\mathcal{F} \subseteq \mathbb{R}^{\mathcal{A}}$ of piece functions if the following holds: for every $h \in \mathcal{H}$, there are $k$ boundary functions $\mathbb{I}(g^{(1)}(\boldsymbol{a}) \geq 0), \ldots, \mathbb{I}(g^{(k)}(\boldsymbol{a}) \geq 0) \in \mathcal{G}$ and a piece function $f_{\mathbf{b}} \in \mathcal{F}$ for each bit vector $\boldsymbol{b} \in \{0, 1\}^k$ such that for all $\boldsymbol{a} \in \mathcal{A}$, $h(\boldsymbol{a}) = f_{\mathbf{b}_y}(\boldsymbol{a})$ where $\mathbf{b}_{\boldsymbol{a}} = (g^{(1)}(\boldsymbol{a}), \ldots, g^{(k)}(\boldsymbol{a})) \in \{0, 1\}^k$.*

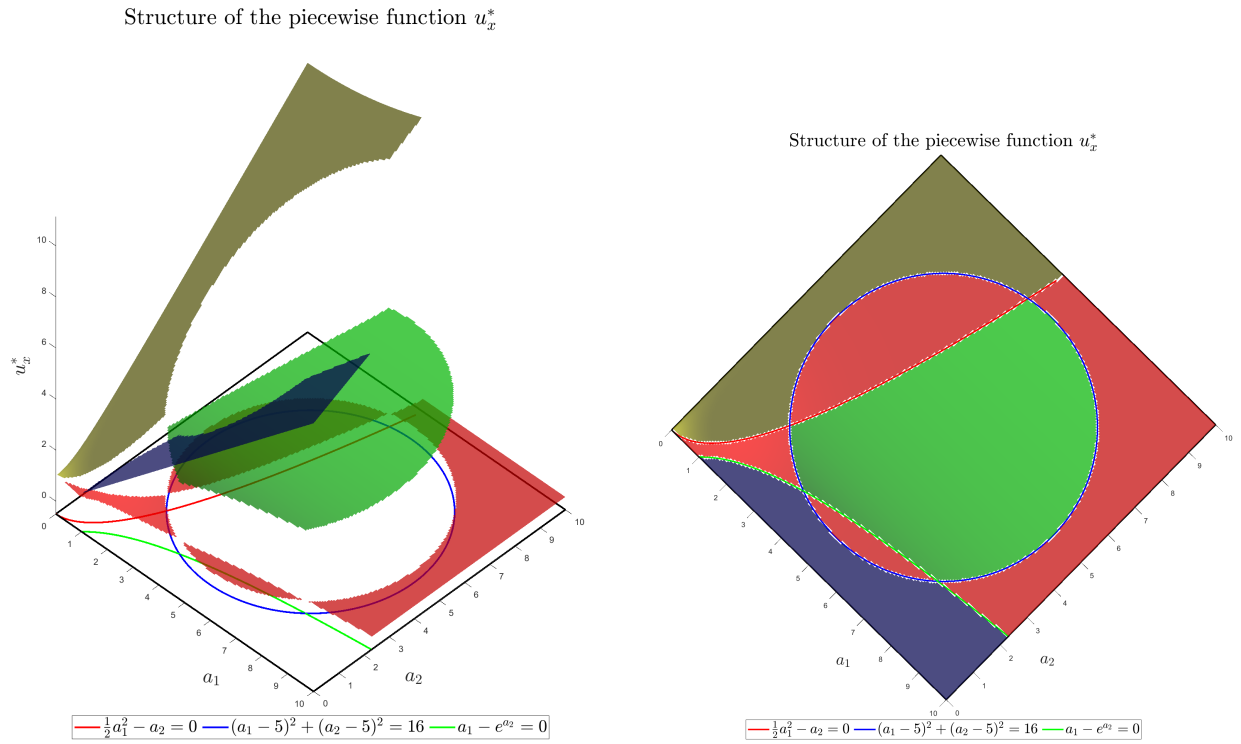
**Remark 3.** *At the risk of notation abuse, we sometimes use the term boundary functions to refer to $g^{(i)}(\boldsymbol{a})$ rather than $\mathbb{I}(g^{(i)}(\boldsymbol{a}) \geq 0)$. We will ensure the context is clear when employing this shorthand.*

An intuitive illustration of the piecewise structure can be found in Figure 1. Roughly speaking, if a function class satisfies the piecewise structure as defined in Definition 7, then for each function in such a class, the input domain is partitioned into multiple regions by $k$ boundary functions. Within each region, which corresponds to a $k$-element binary vector indicating its position relative to the $k$ boundary functions, the utility function is a well-behaved piece function. Based on this observation, Balcan et al. (2021a) showed that for any algorithm, if the dual utility function class satisfies the piecewise structure as defined in Definition 7, then the pseudo-dimension of the utility function class is bounded.

**Theorem 5.1** (Balcan et al. (2021a))**.** *Consider the utility function class $\mathcal{U} = \{u_{\boldsymbol{a}} : \mathcal{X} \to [0, H] \mid \boldsymbol{a} \in \mathcal{A}\}$. Suppose that the dual function class $\mathcal{U}^*$ is $(\mathcal{F}, \mathcal{G}, k)$-piecewise decomposable with boundary functions $\mathcal{G} \subseteq \{0, 1\}^{\mathcal{A}}$ and piece functions $\mathcal{F} \subseteq \mathbb{R}^{\mathcal{A}}$. Then the pseudo-dimension of $\mathcal{U}$ is bounded as follows*

$$\mathrm{Pdim}(\mathcal{U}) = \mathcal{O}((\mathrm{Pdim}(\mathcal{F}^*) + \mathrm{VCdim}(\mathcal{G}^*)) \log(\mathrm{Pdim}(\mathcal{F}^*) + \mathrm{VCdim}(\mathcal{G}^*)) + \mathrm{VCdim}(\mathcal{G}^*) \log k),$$

*where $\mathcal{F}^*$ and $\mathcal{G}^*$ is the dual class of $\mathcal{F}$ and $\mathcal{G}$, respectively.*




(a) A demonstration of piecewise structure of $u_{\boldsymbol{x}}^*$ in sheer view.

(b) The corresponding piecewise structure of $u_{\boldsymbol{x}}^*$ in top view.

Figure 1: An example of the original piecewise structure (Definition 7) and our proposed Pfaffian piecewise structure (Definition 8). Here, (a) demonstrates the sheer view of the piecewise structure of a specific dual utility function $u_{\boldsymbol{x}}^*$, while (b) shows the corresponding top view for better illustration of regions and their boundaries. As can be seen, there are three boundary functions $g_{\boldsymbol{x},1}(\boldsymbol{a}) = \frac{1}{2}a_1^2 - a_2$, $g_{\boldsymbol{x},2}(\boldsymbol{a}) = (a_1-5)^2 + (a_2-5)^2 - 16$, and $g_{\boldsymbol{x},3}(\boldsymbol{a}) = a_1 - e^{a_2}$, partitioning the domain $\mathcal{A}$ into 7 regions. In each region, the function $u_{\boldsymbol{x}}^*(\boldsymbol{a})$ takes the form of a Pfaffian function. What is not captured by the original piecewise structure Definition 7 is that, in this example, there is only 4 forms that $u_{\boldsymbol{x}}^*(\boldsymbol{a})$ can take, which is either $a_1 + \frac{a_2}{2}$ (blue region), $e^{-0.2(a_1^2+a_2^2)}$ (red regions), $\log(a_2) + 2$ (green region), and $\sqrt{a_1^2 + a_2^2 + \exp(0.1\sqrt{a_1})}$, (yellow region). It can be verified that all the piece and boundary functions are Pfaffian function from the Pfaffian chain $\mathcal{C}_{\boldsymbol{x}}(\boldsymbol{a}, e^{a_2}, e^{-0.2(a_1^2+a_2^2)}, \frac{1}{\sqrt{a_1}}, e^{0.1\sqrt{a_1}}, \frac{1}{\sqrt{a_1^2+a_2^2+\exp(0.1\sqrt{a_1})}})$.

Intuitively, Theorem 5.1 allows us to bound the pseudo-dimension of the utility function class $\mathcal{U}$, which is not well-behaved, by alternatively analyzing the dual boundary and piece function classes $\mathcal{F}^*$ and $\mathcal{G}^*$. However, Bartlett et al. (2022) demonstrate that for certain problems in which the piecewise structure involves only rational functions, naively applying Theorem 5.1 can yield looser bounds compared to the approach based on the GJ framework (Goldberg & Jerrum, 1993). Besides, applying Theorem 5.1 requires the non-trivial task of analyzing the dual classes $\mathcal{F}^*$ and $\mathcal{G}^*$ of piece and boundary functions. This might cause trouble, such as leading to loose bounds (see Balcan et al., 2020a, Lemma 7) or vacuous bounds (see Bartlett et al., 2022, Appendix E.3 for example). This situation arises when the piece and boundary functions involve Pfaffian functions, motivating the need to design a refined and concrete approach.

### 5.2 A refined piecewise structure for data-driven algorithm design

In this section, we propose a more refined and concrete approach to derive learning guarantees for data-driven algorithm design problems where the utility functions exhibit a Pfaffian piecewise structure. The key difference between our proposed frameworks and the framework by Balcan et al. (2021a) is that we consider

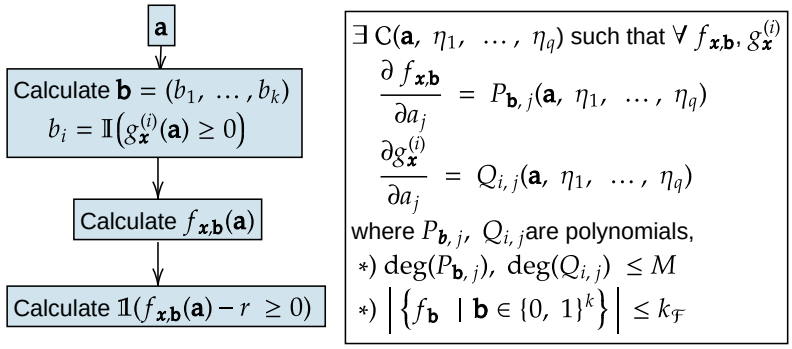



Figure 2: A demonstration of how the computation of a dual utility function satisfying Pfaffian piecewise structure can be described by Pfaffian GJ algorithm. Given an input $\boldsymbol{x} \in \mathcal{X}$ and a threshold $r \in \mathbb{R}$, the function $u_{\boldsymbol{x}}^*$ is piecewise structured with boundary functions $g_{\boldsymbol{x}}^{(i)}$ (for $i = 1, \ldots k$), and piece functions $f_{h,\mathbf{b}}$ ($\mathbf{b} \in \{0,1\}^k$). Note that, the piece functions $f_{h,\mathbf{b}}$ can take at most $k_{\mathcal{F}}$ forms and all the piece and boundary functions are Pfaffian functions from the chain $\mathcal{C}$.

the following additional factors: (1) Both piece and boundary functions are Pfaffian functions from the same Pfaffian chain, and (2) the maximum number of the distinct forms that the piece function can admit. Later, we will argue that by leveraging those extra structures, we can get a better pseudo-dimension upper bound by a logarithmic factor, compared to using the framework by Balcan et al. (2021a). The Pfaffian piecewise structure is formalized as below.

**Definition 8** (Pfaffian piecewise structure)**.** *A function class $\mathcal{H} \subseteq \mathbb{R}^{\mathcal{A}}$ that maps domain $\mathcal{A} \subseteq \mathbb{R}^d$ to $\mathbb{R}$ is said to be $(k_{\mathcal{F}}, k_{\mathcal{G}}, q, M, \Delta, d)$ piecewise structured if the following holds: for every $h \in \mathcal{H}$, there are at most $k_{\mathcal{G}}$ boundary functions of the forms $\mathbb{I}(g_h^{(1)}(\boldsymbol{a}) \geq 0), \ldots, \mathbb{I}(g_h^{(k)}(\boldsymbol{a}) \geq 0)$, where $k \leq k_{\mathcal{G}}$, and a piece function $f_{h,\mathbf{b}}$ for each binary vector $\mathbf{b} \in \{0,1\}^k$ such that for all $\boldsymbol{a} \in \mathcal{A}$, $h(\boldsymbol{a}) = f_{h,\mathbf{b}_{\boldsymbol{a}}}(\boldsymbol{a})$ where $\mathbf{b}_{\boldsymbol{a}} = (\mathbb{I}(g_h^{(1)}(\boldsymbol{a}) \geq 0), \ldots, \mathbb{I}(g_h^{(k)}(\boldsymbol{a}) \geq 0)) \in \{0,1\}^k$. Moreover, the piece functions $f_{h,\mathbf{b}}$ can take on of at most $k_{\mathcal{F}}$ forms, i.e. $\left|\left\{f_{h,\boldsymbol{b}} \mid \boldsymbol{b} \in \{0,1\}^k\right\}\right| \leq k_{\mathcal{F}}$, and all the piece and boundary functions $f_{h,\boldsymbol{b}}, g_h^{(i)}$ are Pfaffian functions of degree at most $\Delta$ over a Pfaffian chain $\mathcal{C}_h$ of length at most $q$ and Pfaffian degree at most $M$.*

An intuitive illustration of Pfaffian piecewise structure and its comparison with the piecewise structure by Balcan et al. (2021a) can be found in Figure 1. For a data-driven algorithm design problem with corresponding utility function class $\mathcal{U} = \{u_{\boldsymbol{a}} : \mathcal{X} \to [0, H] \mid \boldsymbol{a} \in \mathcal{A}\}$ where $\mathcal{A} \subseteq \mathbb{R}^d$, we can see that if its dual utility function class $\mathcal{U}^* = \{u_{\boldsymbol{x}}^* : \mathcal{A} \to \mathbb{R} \mid \boldsymbol{x} \in \mathcal{X}\}$ admits the Pfaffian piecewise structure as in Definition 8, then it can be computed using the Pfaffian GJ algorithm (see Figure 2 for a visualization). Therefore, we can use the established results for the Pfaffian GJ algorithm (Theorem 5) to derive learning guarantees for such problems. We formalize this claim in the following theorem.

**Theorem 5.2.** *Consider the utility function class $\mathcal{U} = \{u_{\boldsymbol{a}} : \mathcal{X} \to [0, H] \mid \boldsymbol{a} \in \mathcal{A}\}$ where $\mathcal{A} \subseteq \mathbb{R}^d$. Suppose that the dual function class $\mathcal{U}^* = \{u_{\boldsymbol{x}}^* : \mathcal{A} \to [0, H] \mid \boldsymbol{x} \in \mathcal{X}\}$ is $(k_{\mathcal{F}}, k_{\mathcal{G}}, q, M, \Delta, d)$-Pfaffian piecewise structured, then the pseudo-dimension of $\mathcal{U}$ is bounded as follows*

$$\mathrm{Pdim}(\mathcal{U}) \leq d^2q^2 + 2dq\log(\Delta + M) + 4dq\log d + 2d\log\Delta(k_{\mathcal{F}} + k_{\mathcal{G}}) + 16d.$$

*Proof.* An intuitive explanation of this theorem can be found at Figure 2. Since $\mathcal{U}^*$ admits $(k_{\mathcal{F}}, k_{\mathcal{G}}, q, M, \Delta, d)$-Pfaffian piecewise structure, then for any problem instance $\boldsymbol{x} \in \mathcal{X}$ corresponding to the dual utility function $u_{\boldsymbol{x}}^*$, there are at most $\mathbb{I}(g_{\boldsymbol{x}}^{(1)} \geq 0), \ldots, \mathbb{I}(g_{\boldsymbol{x}}^{(k)} \geq 0)$ where $k \leq k_{\mathcal{G}}$, and a piece function $f_{\boldsymbol{x},\boldsymbol{b}}$ for each binary vector $\boldsymbol{b} \in \{0,1\}^k$ such that for all $\boldsymbol{a} \in \mathcal{A}$, $u_{\boldsymbol{x}}^*(\boldsymbol{a}) = f_{\boldsymbol{x},\boldsymbol{b}_{\boldsymbol{a}}}(\boldsymbol{a})$, where

$\boldsymbol{b_a} = (\mathbb{I}(g_{\boldsymbol{x}}^{(1)}(\boldsymbol{a}) \geq 0), \ldots, \mathbb{I}(g_{\boldsymbol{x}}^{(k)}(\boldsymbol{a}) \geq 0))$. Therefore, for any problem instance $\boldsymbol{x}$ and real threshold $r \in \mathbb{R}$, the boolean value of $u_{\boldsymbol{x}}^*(\boldsymbol{a}) - r \geq 0$ for any $\boldsymbol{a} \in \mathcal{A}$ can be calculated an algorithm $\Gamma_{\boldsymbol{x},r}$ described as follow: first calculating the boolean vector $\boldsymbol{b_a}$, and then calculate the boolean value $f_{\boldsymbol{x},\boldsymbol{b_a}}(\boldsymbol{a}) - r \geq 0$.

From assumption, note that $g_{\boldsymbol{x}}^{(i)}$ and $f_{\boldsymbol{x},\boldsymbol{b}}$ are Pfaffian functions of degree at most $\Delta$ from Pfaffian chain $\mathcal{C}_{\boldsymbol{x}}$ of length at most $q$ and Pfaffian degree at most $M$. This means that $\Gamma_{\boldsymbol{x},r}$ is a Pfaffian GJ algorithm. Therefore, combining with Theorem 4.2, we have the above claim. □

**Remark 4.** *The details of the differences between our refined Pfaffian piecewise structure and the piecewise structure by Balcan et al. (2021a) can be found in Appendix C.1. In short, compared to the framework by Balcan et al. (2021a), our framework offers: (1) an improved upper bound on the pseudo-dimension by a logarithmic factor (Theorem C.1) compared to naively applying (Balcan et al., 2021a), and (2) a more concrete method for problems admitting a Pfaffian piecewise structure, without invoking dual piece and boundary function classes, which are non-trivial to analyze. This might lead to loose bounds (see (Balcan et al., 2020a), Lemma 7, or (Bartlett et al., 2022), Appendix E.3 for example).*

### 5.3 Special case: discontinuity-homogeneous function class

We now consider the case where all the dual utility functions $v^* \in \mathcal{V}^*$ share the same discontinuity structure, which can be used to establish an improved bound for the utility function class $\mathcal{V}$. We then argue that this analysis is particularly useful in some cases (Section 5.3.1).

Concretely, consider a utility function class $\mathcal{V} = \{v_{\boldsymbol{a}} : \mathcal{X} \to [0, H] \mid \boldsymbol{a} \in \mathcal{A}\}$ where $\mathcal{A} \subseteq \mathbb{R}^d$, with the corresponding dual function class $\mathcal{V} = \{v_{\boldsymbol{x}}^* : \mathcal{A} \to [0, H] \mid \boldsymbol{x} \in \mathcal{X}\}$. Different from Section 5.2, here all the dual utility function $v_{\boldsymbol{x}}^*$ shares the same discontinuity structure: that is, there is a partition $\mathcal{P} = \{\mathcal{A}_1, \ldots, \mathcal{A}_n\}$ of the parameter space $\mathcal{A}$ such that for any problem instance $\boldsymbol{x} \in \mathcal{X}$, the dual function $v_{\boldsymbol{x}}^*$ is a Pfaffian function. In this case, we have the following refined bound for the utility function class $\mathcal{V}$.

**Lemma 5.3.** *Consider a function class $\mathcal{V} = \{v_{\boldsymbol{a}} : \mathcal{X} \to [0, H] \mid \boldsymbol{a} \in \mathcal{A}\}$ where $\mathcal{A} \subseteq \mathbb{R}^d$. Assume there is a partition $\mathcal{P} = \{\mathcal{A}_1, \ldots, \mathcal{A}_n\}$ of the parameter space $\mathcal{A}$ such that for any problem instance $\boldsymbol{x} \in \mathcal{X}$, the dual function $v_{\boldsymbol{x}}^*$ is a Pfaffian function of degree at most $\Delta$ in region $\mathcal{A}_i$ from a Pfaffian chain $\mathcal{C}_{\boldsymbol{x},\mathcal{A}_i}$ of length at most $q$ and Pfaffian degree $M$. Then the pseudo-dimension of $\mathcal{V}$ is upper bounded as follows*

$$\mathrm{Pdim}(\mathcal{V}) = \mathcal{O}(q^2 d^2 + qd \log(\Delta + M) + qd \log d + \log n).$$

**Remark 5.** *The detailed proof is provided in Appendix C.2. Essentially, Lemma 5.3 simplifies the analysis by restricting the complexity of the Pfaffian chain to individual regions $\mathcal{A}_i$, rather than across the entire partition $\mathcal{P}$. The insight here is that, compared to the Pfaffian piecewise structure (Theorem 5.1), Lemma 5.3 makes use of the fact that all the dual functions $v_{\boldsymbol{x}}^*$ share the same discontinuity structure dictated by a fixed partition $\mathcal{P}$ of $\mathcal{A}$. This shared structure significantly reduces the length of the Pfaffian chain, which is typically the dominant term in the upper bound.*

#### 5.3.1 Use case: analyzing via surrogate function class

In many applications, we might want to analyze the utility function class $\mathcal{U}$ indirectly by studying a surrogate utility function class $\mathcal{V}$, of which the dual function class $\mathcal{V}^*$ is "sufficiently close" to $\mathcal{U}^*$. This indirect approach offers several advantages. First, even the dual utility function $\mathcal{U}^*$ may lack a clear structure or prove difficult to analyze, making it impractical to establish learning guarantees for $\mathcal{U}$ by examining $\mathcal{U}^*$ (Balcan et al., 2023b). Second, when $\mathcal{U}^*$ is excessively complex, deriving learning guarantees for $\mathcal{U}$ through its analysis may lead to sub-optimal bounds. In such cases, analyzing a simpler surrogate function class $\mathcal{V}$ can yield tighter bounds (Balcan et al., 2020c).

Formally, consider the utility function class $\mathcal{U} = \{u_{\boldsymbol{a}} : \mathcal{X} \to [0, H] \mid \boldsymbol{a} \in \mathcal{A}\}$ with the corresponding dual utility function class $\mathcal{U}^* = \{u_{\boldsymbol{x}}^* : \mathcal{A} \to [0, H] \mid \boldsymbol{x} \in \mathcal{X}\}$. Assume that for any dual utility function $u_{\boldsymbol{x}}^* \in \mathcal{U}^*$, there is a function $v_{\boldsymbol{x}}^* : \mathcal{A} \to [0, H]$ such that $\|v_{\boldsymbol{x}}^* - u_{\boldsymbol{x}}^*\|_\infty \leq \delta$. We then construct the surrogate dual function class $\mathcal{V}^* = \{v_{\boldsymbol{x}}^* : \mathcal{A} \to [0, H] \mid \boldsymbol{x} \in \mathcal{X}\}$, and the surrogate utility function class $\mathcal{V} = \{v_{\boldsymbol{a}} : \mathcal{X} \to [0, H] \mid \boldsymbol{a} \in \mathcal{A}\}$.

In this section, we consider a scenario where we approximate the parameterized utility function over a predefined partition $\mathcal{A}_1, \ldots, \mathcal{A}_n$ of the parameter space $\mathcal{A}$. Formally, a partition $\mathcal{P}$ of a set $\mathcal{A}$ is a collection $\{\mathcal{A}_1, \ldots, \mathcal{A}_n\}$ of non-empty subsets $\mathcal{A}_i$ of $\mathcal{A}$ that are pairwise disjoint and whose union is the entire set $\mathcal{A}$. For any problem instance $\boldsymbol{x}$, the function $v^*_{\boldsymbol{x}}(\boldsymbol{a})$ restricted to $\mathcal{A}_i$ (for any $i = 1, \ldots, n$) is a Pfaffian function from some Pfaffian chain $\mathcal{C}_{\boldsymbol{x}}$. This is a special case, as for every problem instance $\boldsymbol{x}$, the dual function $v^*_{\boldsymbol{x}}$ exhibits the same discontinuity structure, which can be leveraged to obtain a tighter bound. Our goal is for this property to recover the learning guarantee for the utility function class $\mathcal{U}$. To do that, we proceed with the following steps: (1) derive learning guarantee for $\mathcal{V}$ using the property of $\mathcal{V}^*$, (2) using the relation between $\mathcal{U}^*$ and $\mathcal{V}^*$, derive learning guarantee for $\mathcal{U}$ via $\mathcal{V}$. Step (1) is resolved by Lemma 5.3 above, and to proceed step (2), we first recall the following useful results.

**Lemma 5.4** (Balcan et al., 2020c)**.** *Let $\mathcal{F} = \{f_{\boldsymbol{r}} \mid \boldsymbol{r} \in \mathcal{R}\}$ and $\mathcal{G} = \{g_{\boldsymbol{r}} \mid \boldsymbol{r} \in \mathcal{R}\}$ consist of function mapping from $\mathcal{X}$ to $[0, 1]$. For any $S \subseteq \mathcal{X}$, we have*

$$\hat{\mathscr{R}}_S(\mathcal{F}) \leq \hat{\mathscr{G}}_S(\mathcal{G}) + \frac{1}{|S|} \sum_{\boldsymbol{x} \in S} \|f^*_{\boldsymbol{x}} - g^*_{\boldsymbol{x}}\|_\infty.$$

*Here $\hat{\mathscr{R}}_S(\mathcal{F})$ is the empirical Rademacher complexity of $\mathcal{F}$ corresponding to $S$.*

$$\hat{\mathscr{R}}_S(\mathcal{F}) = \mathbb{E}_{\boldsymbol{x}i_1, \ldots, \boldsymbol{x}i_i \text{ i.i.d from unif. } \{-1,1\}} \left( \sup_{f \in \mathcal{F}} \sum_{i=1}^{m} \boldsymbol{x}i_i f(\boldsymbol{x}_i) \right)$$

We also recall a standard result in learning theory, which draws a connection between empirical Rademacher complexity and the pseudo-dimension.

**Lemma 5.5** (Wainwright, 2019)**.** *Let $\mathcal{F}$ is a bounded function class. Then $\mathscr{R}_m(\mathcal{F}) = \mathcal{O}\left(\sqrt{\frac{\text{Pdim}(\mathcal{F})}{m}}\right)$. Here $\mathscr{R}_m(\mathcal{F}) = \sup_{S \in \mathcal{X}^m} \hat{\mathscr{R}}_S(\mathcal{F})$.*

We are now ready to present the main result in this section, which allows us to establish learning guarantee for the utility function class $\mathcal{U}$ via the surrogate function class $\mathcal{V}$ satisfying a very specific piecewise Pfaffian structure.

**Lemma 5.6.** *Consider the utility function class $\mathcal{U} = \{u_{\boldsymbol{a}} : \mathcal{X} \to [0, H] \mid \boldsymbol{a} \in \mathcal{A}\}$ where $\mathcal{A} \subseteq \mathbb{R}^d$. Assume that there exists a function class $\mathcal{V} = \{v_{\boldsymbol{a}} : \mathcal{X} \to \mathbb{R} \mid \boldsymbol{a} \in \mathcal{A}\}$ such that:*

1. *For any $\boldsymbol{x}$, we have $\|u^*_{\boldsymbol{x}} - v^*_{\boldsymbol{x}}\|_\infty \leq \xi$, and*
2. *There is a partition $\mathcal{P} = \{\mathcal{A}_1, \ldots, \mathcal{A}_n\}$ of $\mathcal{A}$ such that for any problem instance $\boldsymbol{x} \in \mathcal{X}$, the dual function $v^*_{\boldsymbol{x}}$ is a Pfaffian function of degree at most $\Delta$ when restricted to region $\mathcal{A}_i$, from a Pfaffian chain $\mathcal{C}_{\boldsymbol{x}, \mathcal{A}_i}$ of length at most $q$ and Pfaffian degree $M$.*

*Then, for any $\delta \in (0, 1)$, w.p. at least $1 - \delta$ over the draw of $m$ problem instances $S = \{\boldsymbol{x}_1, \ldots, \boldsymbol{x}_m\} \sim \mathcal{D}^m$, where $\mathcal{D}$ is any problem distribution over $\mathcal{X}$, we have*

$$\left| \sup_{\boldsymbol{a} \in \mathcal{A}} \mathbb{E}_{\boldsymbol{x} \sim \mathcal{D}} u_{\boldsymbol{a}}(\boldsymbol{x}) - \mathbb{E}_{\boldsymbol{x} \sim \mathcal{D}}[u_{\hat{\boldsymbol{a}}_S}(\boldsymbol{x})] \right| \leq \mathcal{O}\left( \sqrt{\frac{q^2 d^2 + qd \log(\Delta + M) + qd \log d + \log n}{m}} + \xi + \sqrt{\frac{\log(1/\delta)}{m}} \right).$$

*Here $\hat{\boldsymbol{a}}_S \in \arg\min_{\boldsymbol{a} \in \mathcal{A}} \frac{1}{m} \sum_{i=1}^{m} u_{\boldsymbol{a}}(\boldsymbol{x})$*

*Proof.* From Lemma 5.3, we have $\text{Pdim}(\mathcal{V}) = \mathcal{O}(q^2 d^2 + qd \log(\Delta + M) + qd \log d + \log n)$, which implies

$$\mathscr{R}_m(\mathcal{V}) = \mathcal{O}\left( \sqrt{\frac{q^2 d^2 + qd \log(\Delta + M) + qd \log d + \log n}{m}} \right).$$

From Lemma 5.4, we have

$$\mathscr{R}_m(\mathcal{U}) \leq \mathcal{O}\left(\sqrt{\frac{q^2d^2 + qd\log(\Delta + M) + qd\log d + \log n}{m}} + \xi\right).$$

From here, standard learning theory result implies the final claim. □

## 6 Applications of the Pfaffian piecewise structure framework

In this section, we demonstrate how to leverage our proposed framework to establish new distributional learning guarantees for under-explored data-driven algorithm design problems. For convenience, the notation used in this section might be redefined for each applications.

### 6.1 Data-driven agglomerative hierarchical clustering

Agglomerative hierarchical clustering (Murtagh & Contreras, 2012), or AHC, is a versatile, two-stage clustering approach widely employed across various domains. In the first stage, data is organized into a hierarchical clustering tree, determining the order in which data points are merged into clusters. Subsequently, in the second stage, the cluster tree is pruned according to a specific objective function, of which some common choices are $k$-mean, $k$-median, or $k$-center (Lloyd, 1982; Xu & Wunsch, 2005), among others, to obtain the final clusters.

The first stage of AHC involves carefully designing linkage functions, which measure the similarity between clusters and determine the pair of clusters to be merged at each step. These linkage functions require a pairwise distance function $\delta$ between data points and calculate the distance between clusters based on the distances of their constituent points in a specific manner. Common linkage functions include single-linkage, complete-linkage, and average-linkage, with numerous variants interpolating between these simple functions employed in practical applications (Awasthi et al., 2017; Saeed et al., 2003; White et al., 2010). It is important to note that *if two linkage functions generate the same hierarchical cluster tree, they will yield the same final clusters, irrespective of the objective function used in the subsequent pruning stage.* This observation will be useful in later analyses.

Although linkage functions are a crucial component of AHC, they are generally chosen heuristically without any theoretical guarantees. Recently, Balcan et al. (2017) proposed a data-driven, provable approach for designing linkage functions. Similar to other data-driven settings, their analysis operates under the assumption that there exists an unknown, application-specific distribution for clustering instances. They then provide learning guarantees for some simple families of linkage functions, parameterized by a single parameter, that interpolates among single, complete, and average linkage. However, they assume that the pairwise distance function $\delta$ is fixed, whereas in practice, multiple distance functions, each with distinct properties and benefits, are combined to achieve better performance (Balcan et al., 2005). Subsequent work by Balcan (2020) proposes combining multiple pairwise distance functions by jointly learning their weights and the parameters of the linkage function. However, their analysis holds only under a strict assumption on the linkage function and distance functions. In particular, it requires that the merge function $m$ is *2-point-based*, meaning that the distance $m_\delta(A, B)$, defined using the pairwise distance function $\delta$, between two clusters $A, B$ only depends on the distance $\delta(a, b)$ between two specific points $a \in A$ and $b \in B$. Moreover, that pair of points must depend only on the ordering of pairwise distances: for any two distances $\delta, \delta'$, and two pair of points $(a, b), (a', b') \in A \times B$, we have $\delta(a, b) \leq \delta(a', b')$ if and only if $\delta'(a, b) \leq \delta'(a', b')$, then $m_\delta(A, B) = \delta(a, b)$ implies that $m_{\delta'}(A, B) = \delta'(a, b)$. That restriction effectively rules out many merge functions of interests and compatibility of distance functions learned.

**Contributions.** In this section, we instantiate theoretical guarantees for novel data-driven AHC settings, where we near-optimally learn the parameter of the merge function family and the combination of multiple point-wise distance functions. Compared to prior work, the setting we consider is more general, since (1) requires no restriction on the considered point-wise distances, (2) extends to cluster families that are not 2-point-based, (3) and applies to any objective functions used for tree-pruning.

### 6.1.1 Problem setting

**Distance function, linkage function, and linkage family.** Given a set of $n$ points $S \in \mathcal{X}^n$, where $\mathcal{X}$ denotes the data domain, and a distance function $\delta : \mathcal{X} \times \mathcal{X} \to \mathbb{R}_{\geq 0}$, the overall goal of clustering is to partition $S$ into clusters such that the intra-cluster distance is minimized, and the inter-cluster distance is maximized. In the AHC approach, we first design a linkage function $m_\delta$ based on $\delta$, where $m_\delta(A, B)$ specifies the distance between two clusters $A$ and $B$. The cluster tree construction algorithm starts with $n$ singleton clusters, each containing a single data point, and successively merges the pair of clusters $A, B$ that minimizes the cluster-wise distance $m_\delta(A, B)$. This sequence of merges yields a hierarchical cluster tree, with the root corresponding to the entire set $S$, leaf nodes corresponding to individual points in $S$, and each internal node representing a subset of points in $S$ obtained by merging the point sets corresponding to its two child nodes. Subsequently, the cluster tree is pruned to obtain the final clusters via a dynamic programming procedure that optimizes a chosen objective function. Common objective functions include $k$-means, $k$-medians, and $k$-centers, among others. Importantly, given a fixed objective function, if two linkage functions generate the same cluster tree for a given dataset, they will yield the same final clusters.

As discussed previously, the point-wise distance function $\delta$ can be a convex combination of several distance functions chosen from a given set of distance functions $\boldsymbol{\delta} = \{\delta_1, \ldots, \delta_L\}$, i.e., $\delta = \delta_{\boldsymbol{\beta}} = \sum_{i=1}^{L} \beta_i \delta_i$ for some $\boldsymbol{\beta} = (\beta_1, \ldots, \beta_L) \in \Delta(L)$. Here $\Delta(L) = \{\boldsymbol{\beta} \in \mathbb{R}^L \mid \beta_i \geq 0, \sum_{i=1}^{L} \beta_i = 1\}$ denotes the $(L-1)$-dimensional probability simplex. The combined distance function $\delta_{\boldsymbol{\beta}}$ is then used in the linkage function. In this work, we consider the following parameterized families of linkage functions:

$$\mathcal{M}_1 = \left\{ m^{1,\alpha}_{\delta_{\boldsymbol{\beta}}} : (A, B) \mapsto \left( \min_{a \in A, b \in B} (\delta_{\boldsymbol{\beta}}(a, b))^\alpha + \max_{a \in A, b \in B} (\delta_{\boldsymbol{\beta}}(a, b))^\alpha \right)^{1/\alpha}, \alpha \in \mathbb{R} \cup \{-\infty, \infty\} \setminus \{0\} \right\},$$

$$\mathcal{M}_2 = \left\{ m^{2,\alpha}_{\delta_{\boldsymbol{\beta}}} : (A, B) \mapsto \left( \frac{1}{|A||B|} \sum_{a \in A, b \in B} (\delta_{\boldsymbol{\beta}}(a, b))^\alpha \right)^{1/\alpha}, \alpha \in \mathbb{R} \cup \{-\infty, \infty\} \setminus \{0\} \right\},$$

$$\mathcal{M}_3 = \left\{ m^{3,\alpha}_{\boldsymbol{\delta}} : (A, B) \mapsto \left( \frac{1}{|A||B|} \sum_{a \in A, b \in B} \Pi_{i \in [L]} (\delta_i(a, b))^{\alpha_i} \right)^{1/\sum_i \alpha_i}, \alpha_i \in \mathbb{R} \cup \{-\infty, \infty\} \setminus \{0\} \right\}.$$

The linkage function family $\mathcal{M}_1$ interpolates between single and complete linkage. The linkage function family $\mathcal{M}_2$ is called the versatile linkages (Fernández & Gómez, 2020), which interpolates among single, complete, and average linkage. The family $\mathcal{M}_3$ is another generalization of single, complete, and average linkages that incorporates multiple pairwise distance functions. Note that in $\mathcal{M}_3$, we do not combine all the given distance functions $\boldsymbol{\delta} = \{\delta_1, \ldots, \delta_L\}$ into one but treat them separately. Precisely, if we set $\alpha_i = 1$, and $\alpha_j = 0$ for all $j \neq i$, we have average linkage with respect to the distance function $\delta_i$; if we set $\alpha_i = \infty$, and $\alpha_j = 0$ for all $j \neq i$, we have complete linkage with respect to the distance function $\delta_i$; and if we set $\alpha_i = -\infty$, and $\alpha_j = 0$ for $j \neq i$, we have the well-known single linkage with respect to $\delta_i$.

**Data-driven AHC.** In the data-driven setting, we are given multiple problem instances $P_1, \ldots, P_N$, where each problem instance $P_i = (S_i, \boldsymbol{\delta})$ consists of a set of points $S_i$ that need to be clustered, a fixed set of distance functions $\boldsymbol{\delta}$ that is shared across problem instances. Assuming that there exists an underlying problem distribution that represents a specific application domain, we aim to determine how many problem instances are sufficient to learn the parameters $\alpha$ of the linkage function families and the weights $\boldsymbol{\beta}$ of the distance functions (for the families $\mathcal{M}_1$ and $\mathcal{M}_2$). These questions are equivalent to analyzing the pseudo-dimension of the following classes of utility functions.

For $i \in 1, 2$, let $A_i^{\alpha,\beta}$ denote the algorithm that takes a problem instance $P = (S, \boldsymbol{\delta})$ as input and returns a cluster tree $A_i^{\alpha,\beta}(S, \boldsymbol{\delta}) \in \mathcal{T}$, where $\mathcal{T}$ is the set of all possible cluster trees, by using the interpolated merge function $m^{1,\alpha}_{\delta_\beta}$. Then given an objective function, for example, the $k$-means objective, the pruning function $\mu_k : \mathcal{T} \to \mathcal{S}_k$ takes as input a clustering tree, and returns a $k$-partition $\{\mathcal{P}_1, \ldots, \mathcal{P}_k\}$ of $S$ that minimizes such objective function. Then, given a target cluster $\mathcal{Y} = \{C_1, \ldots, C_k\}$, the performance of the algorithm

$A_i^{\alpha,\beta}$ is given by the Hamming distance between the produced clusters $\mu_k(A_i^{\alpha,\beta}(S,\boldsymbol{\delta})) = \{\mathcal{P}_1,\ldots,\mathcal{P}_k\}$ and the target clusters $\mathcal{Y} = \{C_1,\ldots,C_k\}$

$$\ell(\mu_k(A_i^{\alpha,\beta}(S,\boldsymbol{\delta})),\mathcal{Y}) = \min_{\sigma\in\mathbb{S}_k}\frac{1}{|S|}\sum_{i=1}^{k}|C_i\setminus P_{\sigma_i}|.$$

Here, the minimum is taken over the set of all permutations of $\{1,\ldots,k\}$. We can clearly see that $\ell$ takes value in $\{0,\frac{1}{n},\ldots,\frac{n-1}{n},1\}$. However, note that given an objective function, the cluster tree is equivalent to the produced clusters. Thus, the performance of the algorithm is completely determined by the cluster tree it produces, and for simplicity, we can express the performance of $A_i^{\alpha,\beta}$ as $u_i^{\alpha,\beta} : (S,\boldsymbol{\delta}) \mapsto v(A_i^{\alpha,\beta}(S,\boldsymbol{\delta}))$, where $v$ is a function that maps a cluster tree to a value in $[0,1]$.

Similarly, we denote $A_3^{\alpha}$ as the cluster tree building algorithm that takes $P = (S,\boldsymbol{\delta})$ as the input and returns a cluster tree $A_3^{\alpha}(S,\boldsymbol{\delta})$ by using the linkage function $m_{\boldsymbol{\delta}}^{3,\alpha}$. Again, we have that $u_3^{\alpha} : (S,\boldsymbol{\delta}) \mapsto v(A_3^{\alpha}(S,\boldsymbol{\delta}))$ represents the performance of the algorithm. We consider the following function classes that measure the performance of the above algorithm families:

$$\begin{aligned}
\mathcal{H}_1 &= \{u_1^{\alpha,\beta} : (S,\boldsymbol{\delta}) \mapsto u(A_1^{\alpha,\beta}(S,\boldsymbol{\delta})) \mid \alpha\in\mathbb{R}\cup\{-\infty,+\infty\},\beta\in\Delta([L])\},\\
\mathcal{H}_2 &= \{u_2^{\alpha,\beta} : (S,\boldsymbol{\delta}) \mapsto u(A_2^{\alpha,\beta}(S,\boldsymbol{\delta})) \mid \alpha\in\mathbb{R}\cup\{-\infty,+\infty\},\beta\in\Delta([L])\},\\
\mathcal{H}_3 &= \{u_3^{\alpha} : (S,\boldsymbol{\delta}) \mapsto u(A_3^{\alpha}(S,\boldsymbol{\delta})) \mid \alpha_i\in\mathbb{R}\cup\{-\infty,\infty\}\setminus\{0\}\}.
\end{aligned}$$

In the next section, we analyze the pseudo-dimension of the function classes described above, which provides insights into the number of problem instances required to learn near-optimal AHC parameters for a specific application domain.

#### 6.1.2 Generalization guarantees for data-driven hierarchical clustering

In this section, we will leverage our proposed Pfaffian piecewise structure (Theorem 5.2) to establish the upper bounds for the pseudo-dimension of $\mathcal{H}_1$, $\mathcal{H}_2$, and $\mathcal{H}_3$ described above. First, we will instantiate a pseudo-dimension upper-bound for $\mathcal{H}_1$, which is formalized as the following Theorem 6.1.

**Theorem 6.1.** *Let $\mathcal{H}_1$ be a class of functions*

$$\mathcal{H}_1 = \{u_1^{\alpha,\beta} : (S,\boldsymbol{\delta}) \mapsto u(A_1^{\alpha,\beta}(S,\boldsymbol{\delta})) \mid \alpha\in\mathbb{R}\cup\{-\infty,+\infty\},\beta\in\Delta([L])\}$$

*mapping clustering instances $(S,\boldsymbol{\delta}))$ to $[0,1]$ by using merge functions from class $\mathcal{M}_1$ and an arbitrary objective function. Then* $\mathrm{Pdim}(\mathcal{H}_1) = \mathcal{O}(n^4L^2)$.

*Proof.* **Overview.** The high-level idea is to show that the dual utility function $u_{1,P}^* : (\alpha,\boldsymbol{\beta}) \mapsto u(A_1^{\alpha,\beta}(S,\boldsymbol{\delta}))$ for any fixed problem instance $P = (S,\boldsymbol{\delta})$ exhibits a piecewise structure: its parameter space is partitioned by multiple boundary functions, and within each region, the cluster tree remains unchanged, implying that the utility function is constant. We then characterize the number and complexity of the boundary functions, which we show belong to a Pfaffian system. Subsequently, we can utilize our framework to obtain a bound on the pseudo-dimension of $\mathcal{H}_1$.

**Proof details.** Fix a problem instance $P = (S,\boldsymbol{\delta})$, and consider the dual utility function $u_{1,P}^* : (\alpha,\boldsymbol{\beta}) \mapsto u(A_1^{\alpha,\beta}(S,\boldsymbol{\delta}))$. Suppose $A,B\subseteq S$ and $A',B'\subseteq S$ are two candidate clusters at some merge step of the algorithm. Then $A,B$ is preferred for merging over $A',B'$ iff

$$\left(\min_{a\in A,b\in B}(\delta_{\boldsymbol{\beta}}(a,b))^{\alpha} + \max_{a\in A,b\in B}(\delta_{\boldsymbol{\beta}}(a,b))^{\alpha}\right)^{1/\alpha} \le \left(\min_{a\in A',b\in B'}(\delta_{\boldsymbol{\beta}}(a,b))^{\alpha} + \max_{a\in A',b\in B'}(\delta_{\boldsymbol{\beta}}(a,b))^{\alpha}\right)^{1/\alpha},$$

or equivalently,

$$(\delta_{\boldsymbol{\beta}}(a_1,b_1))^{\alpha} + (\delta_{\boldsymbol{\beta}}(a_2,b_2))^{\alpha} \le (\delta_{\boldsymbol{\beta}}(a_1',b_1'))^{\alpha} + (\delta_{\boldsymbol{\beta}}(a_2',b_2'))^{\alpha},$$

where $(a_1, b_1) \in \arg\min_{a\in A, b\in B}(\delta_{\boldsymbol{\beta}}(a,b))^\alpha$, $(a_2, b_2) \in \arg\max_{a\in A, b\in B}(\delta_{\boldsymbol{\beta}}(a,b))^\alpha$, $(a'_1, b'_1) \in \arg\min_{a\in A', b\in B'}(\delta_{\boldsymbol{\beta}}(a,b))^\alpha$, and $(a'_2, b'_2) \in \arg\max_{a\in A', b\in B'}(\delta_{\boldsymbol{\beta}}(a,b))^\alpha$. Each possible choice of the points $a_1, b_1, a_2, b_2, a'_1, b'_1, a'_2, b'_2$ corresponds to a boundary function in the form

$$\mathbb{I}((\delta_{\boldsymbol{\beta}}(a_1,b_1))^\alpha + (\delta_{\boldsymbol{\beta}}(a_2,b_2))^\alpha - (\delta_{\boldsymbol{\beta}}(a'_1,b'_1))^\alpha + (\delta_{\boldsymbol{\beta}}(a'_2,b'_2))^\alpha \geq 0).$$

Among all possible choices of the points $a_1, b_1, a_2, b_2, a'_1, b'_1, a'_2, b'_2$, we get at most $n^8$ distinct boundary conditions across which the merge decision at any step of the algorithm may change

We next show that the boundary functions constitute a Pfaffian system in $\alpha, \beta_1, \ldots, \beta_L$ and bound its complexity. For each pair of points $a, b \in S$, define $f_{a,b}(\alpha, \boldsymbol{\beta}) := \frac{1}{\delta_{\boldsymbol{\beta}}(a,b)}$, $g_{a,b}(\alpha, \boldsymbol{\beta}) := \ln \delta_{\boldsymbol{\beta}}(a,b)$ and $h_{a,b}(\alpha, \boldsymbol{\beta}) := \delta_{\boldsymbol{\beta}}(a,b)^\alpha$. Recall $\delta_{\boldsymbol{\beta}}(a,b) = \sum_{i=1}^L \beta_i \delta_i(a,b)$. Consider the chain $\mathcal{C}(\alpha, \boldsymbol{\beta}, f_{a,b}, g_{a,b}, h_{a,b})$ of length $q = 3n^2$, for $a, b \in S$. We will show that these functions form a Pfaffian chain of Pfaffian degree $M = 2$. Indeed, we have for each $a, b \in S$,

$$\begin{aligned}
\frac{\partial f_{a,b}}{\partial \alpha} &= 0, & \frac{\partial f_{a,b}}{\partial \beta_i} &= -\delta_i(a,b) f_{a,b}^2, \\
\frac{\partial g_{a,b}}{\partial \alpha} &= 0, & \frac{\partial g_{a,b}}{\partial \beta_i} &= \delta_i(a,b) f_{a,b}, \\
\frac{\partial h_{a,b}}{\partial \alpha} &= g_{a,b} h_{a,b}, & \frac{\partial g_{a,b}}{\partial \beta_i} &= \delta_i(a,b) f_{a,b} h_{a,b},
\end{aligned}$$

which establishes the claim. The boundary conditions can clearly be all written in terms of the functions $\{h_{a,b}\}_{a,b\in S}$, meaning that the degree $\Delta = 1$. Note that the piece functions are constant and can only take value in $\{0, \frac{1}{n}, \ldots, 1\}$, meaning that $k_{\mathcal{F}} = n+1$. Then we conclude that $\mathcal{H}_1^*$ admits $(n+1, n^8, 3n^2, 2, 1, L+1)$-Pfaffian piecewise structure. Applying Theorem 5.2 now gives that $\mathrm{Pdim}(\mathcal{H}_1) = \mathcal{O}(n^4L^2 + n^2 L \log L + L \log(n^8 + n + 1)) = \mathcal{O}(n^4 L^2)$. □

Similarly, we also have the upper-bound for the pseudo-dimension of $\mathcal{H}_2$, and $\mathcal{H}_3$.

**Theorem 6.2.** *Let $\mathcal{H}_2$ be a class of functions*

$$\mathcal{H}_2 = \{u_2^{\alpha,\boldsymbol{\beta}} \colon (S, \boldsymbol{\delta}) \mapsto u(A_2^{\alpha,\boldsymbol{\beta}}(S, \boldsymbol{\delta})) \mid \alpha \in \mathbb{R} \cup \{-\infty, +\infty\}, \boldsymbol{\beta} \in \Delta([L])\}$$

*mapping clustering instances $(S, \boldsymbol{\delta})$ to $[0,1]$ by using merge functions from class $\mathcal{M}_2$ and an arbitrary merge function. Then $\mathrm{Pdim}(\mathcal{H}_2) = \mathcal{O}(n^4 L^2)$.*

**Theorem 6.3.** *Let $\mathcal{H}_3$ be a class of functions*

$$\mathcal{H}_3 = \{u_3^{\alpha} : (S, \boldsymbol{\delta}) \mapsto u(A_3^{\alpha}(S, \boldsymbol{\delta})) \mid \alpha_i \in \mathbb{R} \cup \{-\infty, \infty\} \setminus \{0\}\}$$

*mapping clustering instances $(S, \boldsymbol{\delta})$ to $[0,1]$ by using merge functions from class $\mathcal{M}_3$. Then $\mathrm{Pdim}(\mathcal{H}_3) = \mathcal{O}(n^4 L^2)$.*

The detailed proofs of Theorem 6.2, 6.3 for the function classes $\mathcal{H}_2$, and $\mathcal{H}_3$ can be found in Appendix D.1. Although these function classes share the same pseudo-dimension asymptotic upper-bound, their structures differ, necessitating separate analyses and leading to distinct Pfaffian piecewise structures. To show that the dual function classes of $\mathcal{H}_1$, $\mathcal{H}_2$, and $\mathcal{H}_3$ admit Pfaffian piecewise structure, we analyze the transition condition on the hyperparameters when the preference for merging two candidate clusters $A, B$ switches to merging a different pair of clusters $A', B'$ instead, at any merge step of the hierarchical clustering algorithm. The transition condition corresponds to an equality involving Pfaffian functions of the parameters $\alpha$ and $\boldsymbol{\beta}$. All of such equations corresponding to each tuple $(A, B, A', B') \subset S^4$ will divide the parameter space into regions, in each of which the AHC algorithm produces the same clustering tree, leading to the same performance. After this step, we construct the Pfaffian chains for each function in function classes $\mathcal{H}_1$, $\mathcal{H}_2$, and $\mathcal{H}_3$, where the difference naturally lies in the form of functions in those function classes. We then carefully analyze the complexities of the Pfaffian chain of those Pfaffian functions to obtain the above bounds.

### 6.2 Data-driven graph-based semi-supervised learning

Semi-supervised learning (Chapelle et al., 2010) is a learning paradigm where labeled data is scarce due to expensive labeling processes. This paradigm leverages unlabeled data in addition to a small set of labeled samples for effective learning. A common semi-supervised learning approach is the graph-based method (Zhu & Goldberg, 2009; Chapelle et al., 2010), which captures relationships between labeled and unlabeled data using a graph. In this approach, nodes represent data points, and edges are constructed based on the similarity between data point pairs, measured by a given distance function. Optimizing a labeling function on this graph helps propagate labels from the labeled data to the unlabeled data.

A large body of research focuses on how to learn such labeling functions given the graph, including using *st*-mincuts (Blum & Chawla, 2001), optimizing harmonic objective with soft mincuts (Zhu et al., 2003), label propagation (Zhu & Ghahramani, 2002), among others. However, under the assumption that the graph well describes the relationship amongst data, it is known that all algorithms for learning the labeling function above are equivalent (Zhu & Goldberg, 2009). This also highlights the importance of the graph in graph-based semi-supervised learning.

Despite its significance, the graph is usually considered given or constructed using heuristic methods without theoretical guarantees (Zhu, 2005; Zemel & Carreira-Perpiñán, 2004). Recently, Balcan & Sharma (2021) proposed a novel data-driven approach for constructing the graph, by learning the parameters of the graph kernel underlying the graph construction, from the problem instances at hand. Each problem instance $P$ consists of sets of labeled $\mathcal{L}$ and unlabeled data $\mathcal{U}$ and a distance metric $d$. Assuming that all problem instances are drawn from an underlying, potentially unknown distribution, they provide guarantees for learning near-optimal graph kernel parameters for such a distribution. Nonetheless, they consider only a single distance function, whereas in practical applications, combining multiple distance functions, each with its unique characteristics, can improve the graph quality and typically result in better outcomes compared to utilizing a single metric (Balcan et al., 2005).

**Contributions.** In this section, we consider a generalized and more practical setting for data-driven graph-based semi-supervised learning, where we learn the parameters of the commonly-used Gaussian RBF kernel $w_{\sigma,\boldsymbol{\beta}}(u,v) = \exp(-\delta(u,v)/\sigma^2)$ and the weights $\boldsymbol{\beta} \in \Delta(L) = \{\boldsymbol{\beta} \in \mathbb{R}^L \mid \beta_i \geq 0, \sum_{i=1}^L \beta_i = 1\}$ of $\delta = \sum_{i=1}^L \beta_i \delta_i$ which is a convex combination of multiple distance functions for constructing the graph.

#### 6.2.1 Problem setting

**Graph-based semi-supervised learning with Gaussian RBF Kernel.** In the graph-based semi-supervised learning with Gaussian RBF kernel, we are given a few labeled samples $\mathcal{L} \subset \mathcal{X} \times \mathcal{Y}$, a large number of unlabeled points $\mathcal{U} \subset \mathcal{X}$, and a set of distance functions $\boldsymbol{\delta} = \{\delta_1, \ldots, \delta_L\}$, where $\delta_i : \mathcal{X} \times \mathcal{X} \to \mathbb{R}\geq 0$ for $i = 1, \ldots, L$. Here, $\mathcal{X}$ denotes the data space, and $\mathcal{Y} = \{0, 1\}$ denotes the binary classification label space. To extrapolate labels from $\mathcal{L}$ to $\mathcal{U}$, a graph $G^{\sigma,\boldsymbol{\beta}}$ is constructed with the node set $\mathcal{L} \cup \mathcal{U}$ and edges weighted by the Gaussian RBF graph kernel $w_{\sigma,\boldsymbol{\beta}}(u,v) = \exp(-d(u,v)/\sigma^2)$, where $\sigma$ is the bandwidth parameter, and $\delta = \sum_{i=1}^L \beta_i \delta_i$ is a convex combination of the given distance functions. After constructing the graph $G^{\sigma,\boldsymbol{\beta}}$, a popular graph labeling algorithm called the harmonic method (Zhu et al., 2003) is employed. It assigns soft labels by minimizing the following quadratic objective:

$$\frac{1}{2} \sum_{u,v} w(u,v)(f(u) - f(v))^2 = f^T(D - W)f,$$

where $f \in [0,1]^n$, $n = |\mathcal{U}| + |\mathcal{L}|$, $W$ denotes the graph adjacency matrix $W_{uv} = w_{\alpha,\boldsymbol{\beta}}(u,v)$, and $D$ is the diagonal matrix with entries $D_{ii} = \sum_j W_{ij}$. The final predictions are obtained by rounding $f_u$ for $u \in U$, i.e. predicting $\mathbb{I}\{f_u \geq \frac{1}{2}\}$, denoted by $G^{\sigma,\boldsymbol{\beta}}(\mathcal{L}, \mathcal{U}, \boldsymbol{\delta})$. Let $v^{\sigma,\boldsymbol{\beta}} : (\mathcal{L}, \mathcal{U}, \boldsymbol{\delta}) \mapsto [0,1]$ denote the average 0-1 binary classification loss of the predictions of the above algorithm when the graph is built with parameters $\sigma, \boldsymbol{\beta}$.

**Data-driven graph-based semi-supervised learning.** In the data-driven setting, we are given multiple problem instances $P_1, \ldots, P_i$, each $P_i$ is represented as a tuple $(\mathcal{L}_i, \mathcal{U}_i, \boldsymbol{\delta})$ of a set of labeled samples $\mathcal{L}_i$, a set of a unlabeled samples $\mathcal{U}_i$, and a set of distance functions $\boldsymbol{\delta}$ that is shared across problem instances.

Assuming that there is an underlying problem distribution, that represents a specific application domain, we want to know how many problems instance is sufficient to learn the best parameters $\alpha, \boldsymbol{\beta}$ that is near-optimal for such problem distribution. To do that, we want to analyze the pseudo-dimension of the following function class:

$$\mathcal{G} = \{v^{\sigma,\boldsymbol{\beta}} : (\mathcal{L},\mathcal{U},\boldsymbol{\delta}) \mapsto v(G^{\sigma,\boldsymbol{\beta}}(\mathcal{L},\mathcal{U},\boldsymbol{\delta})) \mid \sigma \in \mathbb{R} \setminus \{0\}, \boldsymbol{\beta} \in \Delta(L)\}.$$

#### 6.2.2 Generalization guarantee for data-driven semi-supervised learning with Gaussian RBF kernel and multiple distance functions

We now instantiate the main result in this section, which establishes an upper bound for the pseudo-dimension of the function class $\mathcal{G}$ described above.

**Theorem 6.4.** *Let $\mathcal{G}$ be a class of functions mapping semi-supervised learning instances $(\mathcal{L},\mathcal{U},\boldsymbol{\delta})$ to $[0,1]$. Then $\mathrm{Pdim}(\mathcal{G}) = \mathcal{O}(n^4L^2)$, where $n = |\mathcal{L}| + |\mathcal{U}|$ is the total number of samples in each problem instance, and $L = |\boldsymbol{\delta}|$ is the number of distance functions.*

*Proof.* **Technical overview.** Fix a problem instance $P = (\mathcal{L},\mathcal{U},\boldsymbol{\delta})$, we will show that the dual loss function $v_P^*(\sigma,\boldsymbol{\beta}) := v^{\sigma,\boldsymbol{\beta}}(\mathcal{L},\mathcal{U},\boldsymbol{\delta})$ is piecewise constant and characterize the number and complexity of the boundary functions which we will show belong to a Pfaffian system. This implies a bound on the pseudo-dimension of $\mathcal{G}$ following our Pfaffian piecewise structure Theorem 5.2.

**Proof details.** First, the quadratic objective minimization has a closed-form solution (Zhu et al., 2003), given by

$$f_{\mathcal{U}} = (D_{\mathcal{U}\mathcal{U}} - W_{\mathcal{U}\mathcal{U}})^{-1} W_{\mathcal{U}\mathcal{L}} f_{\mathcal{L}},$$

where $W$ denotes the graph adjacent matrix, $D$ is the diagonal matrix with entries $D_{ii} = \sum_j W_{ij}$, and subscripts $\mathcal{U},\mathcal{L}$ refer to the unlabeled and labeled points, respectively. Here $f_{\mathcal{L}} \in \{0,1\}^{|\mathcal{L}|}$ is the ground truth label of samples in the labeled set $\mathcal{L}$.

The key challenge now is to analyze the formula $(D_{\mathcal{U}\mathcal{U}} - W_{\mathcal{U}\mathcal{U}})^{-1}$ of which the element will be shown to be Pfaffian functions of $\sigma,\boldsymbol{\beta}$. Recall that $w_{u,v} = \exp(-\delta_{\boldsymbol{\beta}}(u,v)/\sigma^2)$ for $u,v \in \mathcal{L}\cup\mathcal{U}$, and $D_{ii} = \sum_{j=1}^n w_{ij}$. First, we recall the identity $A^{-1} = \frac{\mathrm{adj}(A)}{\det(A)}$, for any invertible matrix $A$, where $\mathrm{adj}(A)$ and $\det A$ are the adjoint and determinant of matrix $A$, respectively. Therefore, we can see that any element of $(D_{\mathcal{U}\mathcal{U}} - W_{\mathcal{U}\mathcal{U}})^{-1}$ is a rational function of $w_{u,v}$ of degree at most $|\mathcal{U}|$.

Now, consider the Pfaffian chain $\mathcal{C}(\sigma,\boldsymbol{\beta},\frac{1}{\sigma},w_{11},\ldots,w_{nn})$ with $L+1$ variables $\sigma,\boldsymbol{\beta}$, and of length $q = n^2+1$. To see the Pfaffian degree of $\mathcal{C}$, note that for any pair of nodes $u,v \in \mathcal{U}\cup\mathcal{L}$, we have

$$\frac{\partial w_{u,v}}{\partial \beta_i} = -\frac{\delta_i(u,v)}{\sigma^2}\exp\left(-\frac{\delta_{\boldsymbol{\beta}}(u,v)}{\sigma^2}\right) = -\delta_i(u,v)g^2 w_{u,v},$$

$$\frac{\partial w_{u,v}}{\partial \alpha} = \frac{2\delta_{\boldsymbol{\beta}}(u,v)}{\sigma^3}\exp\left(-\frac{\delta_{\boldsymbol{\beta}}(u,v)}{\sigma^2}\right) = 2\delta_{\boldsymbol{\beta}}(u,v)g^3 w_{u,v}.$$

Thus, the Pfaffian chain $\mathcal{C}$ has Pfaffian degree $M = 5$.

Now, consider the dual loss function $v_{\mathcal{L},\mathcal{U},\boldsymbol{\delta}}(\sigma,\boldsymbol{\beta})$. Note that

$$v_{\mathcal{L},\mathcal{U},\boldsymbol{\delta}}(\sigma,\boldsymbol{\beta}) = \frac{1}{|\mathcal{U}|}\sum_{u\in\mathcal{U}} \mathbb{I}(\mathbb{I}(f_u \geq 1/2) = g_u),$$

where $g_u$ is the ground-truth label of unlabeled node $u$, using for evaluation purpose. We can see that, for each $u \in \mathcal{U}$, $\mathbb{I}(f_u \geq 1/2) = \mathbb{I}\left(\frac{f_u^{(1)}}{f_u^{(2)}} \geq 1/2\right) = \mathbb{I}\left(f_u^{(1)} \geq 1/2 f_u^{(2)}\right)$ is a boundary function. Both functions $f_u^{(1)}, f_u^{(2)}$ are Pfaffian functions from chain $\mathcal{C}$ and of degree $|\mathcal{U}|$. In each region determined by the sign vector $b_{\mathcal{U}}$, where $b_u = \mathbb{I}(f_u \geq 1/2)$ for $u \in \mathcal{U}$, the dual loss function $v_{\mathcal{L},\mathcal{U},\boldsymbol{\delta}}(\sigma,\boldsymbol{\beta})$ is a constant functions. We can see that there are at most $|\mathcal{U}|+1$ such constant functions that $v_{\mathcal{L},\mathcal{U},\boldsymbol{\delta}}(\sigma,\boldsymbol{\beta})$ can take. Therefore, by Definition

8, the dual function class $\mathcal{G}^*$ is $(|\mathcal{U}|+1, |\mathcal{U}|+1, n^2+1, 5, |\mathcal{U}|)$-Pfaffain piecewise structured. We can apply Theorem 5.2 to get

$$\mathrm{Pdim}(\mathcal{G}) = \mathcal{O}(n^4L^2 + n^2L\log(|\mathcal{U}|) + n^2L\log L + L\log|\mathcal{U}|).$$

Noting $|\mathcal{U}| \leq n$ and simplifying yields the claimed bound. □

At a high level, the solution to the harmonic objective of Zhu et al. (2003) has a closed-form expression $f_{\mathcal{U}} = (D_{\mathcal{U}\mathcal{U}} - W_{\mathcal{U}\mathcal{U}})^{-1}W_{\mathcal{U}\mathcal{L}}f_{\mathcal{L}}$. Here each element of $(D_{\mathcal{U}\mathcal{U}} - W_{\mathcal{U}\mathcal{U}})^{-1}$ can be shown to be a Pfaffian function of the graph hyperparameter $\sigma$ over a Pfaffian chain of length $n^2+1$. We then apply Theorem 5.2 to obtain the stated pseudo-dimension bound.

### 6.3 Data-driven regularized logistic regression

Logistic regression (James et al., 2013) is a fundamental statistical technique and widely used classification model with numerous applications across diverse domains, including healthcare screening (Armitage et al., 2008), market forecasting (Linoff & Berry, 2011), and engineering safety control (Palei & Das, 2009), among others. To mitigate overfitting and enhance robustness, regularizations, such as sparsity ($\ell_1$) and shrinkage ($\ell_2$) constraints, are commonly employed in logistic regression (Mohri et al., 2018; Murphy, 2012). In regularized logistic regression and regularized linear models in general, the regularization parameters, which control the magnitude of regularization, play a crucial role (Mohri et al., 2018; Murphy, 2012; James et al., 2013) and must be carefully chosen. Setting regularization parameters too high may lead to underfitting, while setting them too low may nullify the effectiveness of regularization. In practice, a common strategy for selecting regularization parameters is cross-validation, which is known to lack theoretical guarantees, in general, (Zhang, 2009; Chichignoud et al., 2016).

Recently, Balcan et al. (2023b) proposed a data-driven approach for selecting regularization parameters in regularized logistic regression. Their methodology considers each regression problem, comprising training and validation sets, as a problem instance drawn from an underlying problem distribution. The objective is to leverage the available problem instances to determine regularization parameters that minimize the validation loss for any future problem instance sampled from the same distribution.

**Contribution.** In this section, we will demonstrate the applicability of Lemma 5.3 by recovering a result by Balcan et al. (2023b).

#### 6.3.1 Problem setting

**Regularized logistic regression.** We closely follow the data-driven regularized logistic regression setting by Balcan et al. (2023b). A problem instance $P = (\boldsymbol{X}, \boldsymbol{y}, \boldsymbol{X}_{\mathrm{val}}, \boldsymbol{y}_{\mathrm{val}}) \in \mathcal{R}_{m,p,m'} = \mathbb{R}^{m\times p} \times \{\pm 1\}^m \times \mathbb{R}^{m'\times p} \times \{\pm 1\}^{m'}$ consists of a training set $(\boldsymbol{X}, \boldsymbol{y})$ and a validation set $(\boldsymbol{X}_{\mathrm{val}}, \boldsymbol{y}_{\mathrm{val}})$. Given a regularization parameter $\lambda \in [\lambda_{\min}, \lambda_{\max}]$, the regularized logistic regression solves for the coefficients $\hat{\boldsymbol{\beta}}_{(X,y)}$ that is the best fit for the training set $(\boldsymbol{X}, \boldsymbol{y})$

$$\hat{\boldsymbol{\beta}}_{(\boldsymbol{X},\boldsymbol{y})}(\lambda) = \arg\min_{\boldsymbol{\beta}\in\mathbb{R}^p} l(\boldsymbol{\beta}, (\boldsymbol{X}, \boldsymbol{y})) + \lambda R(\boldsymbol{\beta}),$$

where $l(\boldsymbol{\beta}, (\boldsymbol{X}, \boldsymbol{y})) = \frac{1}{m}\sum_{i=1}^m \log(1 + \exp(-y_i\boldsymbol{x}_i^\top\boldsymbol{\beta}))$ denotes the logistic loss, and $R(\boldsymbol{\beta})$ is either sparsity ($\|\boldsymbol{\beta}\|_1$) or shrinkage ($\|\boldsymbol{\beta}\|_2^2$) regularizer.

**Data-driven regularized logistic regression.** In the data-driven setting, we are given multiple problem instances $P_1, \ldots, P_N$. Assuming that there is an underlying problem distribution, that represents a specific application domain, we want to know how many problems instance is sufficient to learn the regularization hyperparameter $\lambda$ that is near-optimal for such problem distribution. To do that, we want to analyze the learnability of the function class $\mathcal{H} = \{h_\lambda : \mathcal{R}_{m,p,m'} \to [0, H] \mid \lambda \in [\lambda_{\min}, \lambda_{\max}]\}$. Here, for an input problem

instance $P = (\boldsymbol{X}, \boldsymbol{y}, \boldsymbol{X}_{\text{val}}, \boldsymbol{y}_{\text{val}})$, we define

$$h_\lambda(P) = l(\hat{\boldsymbol{\beta}}_{\boldsymbol{X},\boldsymbol{y}}(\lambda), (\boldsymbol{X}_{\text{val}}, \boldsymbol{y}_{\text{val}})) = \frac{1}{m'} \sum_{i=1}^{m'} \log(1 + \exp(-y_i \boldsymbol{x}_i^\top \hat{\boldsymbol{\beta}}_{(\boldsymbol{X},\boldsymbol{y})}(\lambda)) = \frac{1}{m'} \log \left( \prod_{i=1}^{m'} (1 + \exp(-y_i \boldsymbol{x}_i^\top \hat{\boldsymbol{\beta}}_{(\boldsymbol{X},\boldsymbol{y})}(\lambda)) \right)$$

which is the validation loss for the problem instance $P$ corresponding to the regularization hyperparameter $\lambda$.

### 6.3.2 Generalization guarantee for data-driven regularized logistic regression

As discussed previously, the challenge for analyzing the learnability of $\mathcal{H}$ is the unknown structure of $h_\lambda(P)$ as a function of problem instance $P$. Even if we consider the dual function class $\mathcal{H}^* = \{h_P^* : [\lambda_{\min}, \lambda_{\max}] \to [0, H] \mid P \in \mathcal{R}_{m,p,m'}\}$, it is also hard to analyze the structure of $\mathcal{H}^*$ as we do not have the explicit form of $h_P^*(\lambda)$. Hence, the approach here is to construct a surrogate function class $\mathcal{V}_\epsilon^*$ that is sufficiently "close" to $\mathcal{H}^*$ and is more well-behaved, and then we will use the idea proposed in Section 5.3.1 to recover the learning guarantee for $\mathcal{H}$.

Using this approach, we recover the following result by Balcan et al. (2023b), which establishes learning guarantee for hyperparameter tuning for regularized logistic regression.

**Theorem 6.5.** *Consider the problem of tuning regularization parameter for regularized logistic regression with $\ell_1$ (or $\ell_2$) regularizer under data-driven setting. Consider the function class $\mathcal{H} = \{h_\lambda : \mathcal{R}_{m,p,m'} \to \mathbb{R} \mid \lambda \in [\lambda_{\min}, \lambda_{\max}]\}$, where $h_\lambda(P)$ is the validation loss for the problem instance $P$ and with regularization hyperparameter $\lambda$. Then for any $\delta \in (0, 1)$, with probability at least $1-\delta$ over the draw of $m$ problem instances $S = \{P_1, \ldots, P_m\} \sim \mathcal{D}^m$, where $\mathcal{D}$ is some problem distribution over $\mathcal{R}_{m,p,m'}$, we have*

$$\mathbb{E}_{P\sim\mathcal{D}} h_{\hat{\lambda}_S}(P) \leq \sup_{\lambda \in [\lambda_{\min}, \lambda_{\max}]} \mathbb{E}_{p\sim\mathcal{D}} h_\lambda(P) + \mathcal{O}\left( \sqrt{\frac{m^2 + \log(1/\epsilon)}{m}} + \epsilon^2 + \sqrt{\frac{\log(1/\delta)}{m}} \right).$$

*Proof.* **Technical overview.** The idea is to construct a surrogate function class $\mathcal{V}_\epsilon^* = \{v_{P,\epsilon}^* : [\lambda_{\min}], \lambda_{\max}] \to [0, H]\}$ that is sufficiently close to $\mathcal{H}^*$ given any $\epsilon$: for any problem instance $P \in \mathcal{R}_{m,p,m'}$, we have $\|v_{P,\epsilon}^* - h_P^*\|_\infty < \epsilon$. This can be done using Theorem D.1. Moreover, we can partition the space $[\lambda_{\min}, \lambda_{\max}]$ into $\frac{1}{\epsilon}(\lambda_{\max} - \lambda_{\min})$, over each of which the function $v_{\boldsymbol{P},\epsilon}^*$ is a Pfaffian function. We then use our proposed result (Theorem 5.3) to bound the statistical complexity of $\mathcal{V}_\epsilon$, which then can convert to the statistical complexity of $\mathcal{H}$.

**Proof details.** We now go to the details of the proof, which consists of the following step.

**Constructing the surrogate function class $\mathcal{V}_\epsilon^*$ and $\mathcal{V}_\epsilon$.** To construct such a surrogate function class $\mathcal{V}_\epsilon^*$ for $\mathcal{H}^*$, for any problem instance $P = (\boldsymbol{X}, \boldsymbol{y}, \boldsymbol{X}_{\text{val}}, \boldsymbol{y}_{\text{val}})$, Balcan et al. (2023b) first approximate the regularized logistic regression estimator $\hat{\boldsymbol{\beta}}_{(\boldsymbol{X},\boldsymbol{y})}(\lambda)$ by $\boldsymbol{\beta}_{(\boldsymbol{X},\boldsymbol{y})}^{(\epsilon)}(\lambda)$, using Algorithm 1 if $R(\boldsymbol{\beta}) = \|\boldsymbol{\beta}\|_1$ (or Algorithm 2 if $R(\boldsymbol{\beta}) = \|\boldsymbol{\beta}\|_2$). Intuitively, for a sufficiently small $\epsilon$, the search space $[\lambda_{\min}, \lambda_{\max}]$ can be divided into $\frac{1}{\epsilon}(\lambda_{\max} - \lambda_{\min})$ pieces. Within each piece, $\boldsymbol{\beta}^{(\epsilon)}(\boldsymbol{x}, \boldsymbol{y})(\lambda)$ is a linear function of $\lambda$, and there exists a uniform error bound of $O(\epsilon^2)$ for the approximation error $\|\boldsymbol{\beta}_{(\boldsymbol{X},\boldsymbol{y})}^{(\epsilon)}(\lambda) - \hat{\beta}_{(\boldsymbol{X},\boldsymbol{y})}(\lambda)\|_2$ (formalized in Theorem D.1). The surrogate dual validation loss function class $\mathcal{V}_\epsilon^*$ can now be defined as $\mathcal{V}_\epsilon^* = \{v_{P,\epsilon}^* : [\lambda_{\min}, \lambda_{\max}] \to \mathbb{R} \mid P \in \mathcal{R}_{m,p,m'}\}$. Here

$$v_{P,\epsilon}^*(\lambda) = l(\boldsymbol{\beta}_{(\boldsymbol{X},\boldsymbol{y})}^{\epsilon}(\lambda), (\boldsymbol{X}_{\text{val}}, \boldsymbol{y}_{\text{val}})) = \frac{1}{m'} \sum_{i=1}^{m'} \log(1 + \exp(-y_i x_i^\top \boldsymbol{\beta}_{(\boldsymbol{X},\boldsymbol{y})}^{\epsilon}(\lambda))) = \frac{1}{m'} \log \left( \prod_{i=1}^{m'} (1 + \exp(-y_i x_i^\top \boldsymbol{\beta}_{(\boldsymbol{X},\boldsymbol{y})}^{\epsilon}(\lambda))) \right),$$

and $\boldsymbol{\beta}^{\epsilon}_{(\boldsymbol{X},\boldsymbol{y})}(\lambda)$ is defined as in Theorem D.1. An important property of $\boldsymbol{\beta}^{\epsilon}_{(\boldsymbol{X},\boldsymbol{y})}(\lambda)$ is its piecewise linear structure: we can partition $[\lambda_{\min}, \lambda_{\max}]$ into $\frac{1}{\epsilon}(\lambda_{\max} - \lambda_{\min})$ intervals, and in each interval $[\lambda_{\min} + t\epsilon, \lambda_{\min} + (t+1)\epsilon]$, $\boldsymbol{\beta}^{\epsilon}_{(\boldsymbol{X},\boldsymbol{y})}(\lambda) = \lambda \boldsymbol{a}_{P,\epsilon,t} + \boldsymbol{b}_{P,\epsilon,t}$, where $\boldsymbol{a}_{P,\epsilon,t}, \boldsymbol{b}_{P,\epsilon,t}$ is defined as in Theorem D.1. This leads to the piecewise structure of $\mathcal{V}^*_{\epsilon}$, and we have successfully construct a surrogate function class for $\mathcal{H}^*$ that is: (1) admits piecewise structure, and (2) sufficiently close to $\mathcal{H}^*$.

We can then the define $\mathcal{V}_{\epsilon} = \{v_{\lambda,\epsilon} : \mathcal{R}_{m,p,m'} \to \mathbb{R} \mid \lambda \in [\lambda_{\min}, \lambda_{\max}]\}$, where $v_{\lambda,\epsilon} := v^*_{P,\epsilon}(\lambda)$.

**Analyzing the pseudo-dimension of $\mathcal{V}_{\epsilon}$.** We can now proceed to analyze $\mathcal{V}_{\epsilon}$. First, notice that $z \mapsto \frac{1}{m'} \log z$ is a monotonic function. Hence, we can simplify the analysis by analyzing the pseudo-dimension of $\mathcal{G}_{\epsilon} = \{g_{\lambda,\epsilon}(P) : \mathcal{R}_{m,p,m'} \to \mathbb{R} \mid \lambda_{\min}\lambda_{\max}]\}$, where

$$g_{\lambda,\epsilon}(P) = \prod_{i=1}^{m'} (1 + \exp(-y_i x_i^{\top} \boldsymbol{\beta}^{\epsilon}_{(\boldsymbol{X},\boldsymbol{y})}(\lambda))).$$

Fixing a problem instance $P$ and a threshold $\tau \in \mathbb{R}$, by the property of $\boldsymbol{\beta}^{\epsilon}_{(\boldsymbol{X},\boldsymbol{y})}(\lambda)$, we know that the domain $[\lambda_{\min}, \lambda_{\max}]$ can be partitioned in to $\frac{1}{\epsilon}[\lambda_{\max} - \lambda_{\min}]$ intervals. In each interval $[\lambda_{\min} + t\epsilon, \lambda_{\min} + (t+1)\epsilon]$, $g_{\lambda,\epsilon}(P)$ takes the form

$$g_{\lambda,\epsilon}(P) = \prod_{i=1}^{m'} (1 + \exp(-y_i x_i^{\top} (\lambda a_t + b_t))).$$

This implies that, in each interval $[\lambda_{\min} + t\epsilon, \lambda_{\min} + (t+1)\epsilon]$, $g_{\lambda,\epsilon}(P)$ is a Pfaffian function of degree at most $m$ from a Pfaffian chain $\mathcal{C}$ of length at most $m$ and of Pfaffian degree at most $m$. From Lemma 5.3, we conclude that $\mathrm{Pdim}(\mathcal{G}_{\epsilon}) = \mathrm{Pdim}(\mathcal{V}_{\epsilon}) = \mathcal{O}(m^2 + \log(1/\epsilon))$.

**Recover the guarantee for $\mathcal{H}$.** Note that we just have the learning guarantee for the surrogate function class $\mathcal{V}_{\epsilon}$. To recover the learning guarantee for $\mathcal{H}$, we need to leverage the approximation error guarantee between $\mathcal{H}$ and $\mathcal{H}^{(\epsilon)}$. Using Theorem 5.4, we then conclude that

$$\mathscr{R}_m(\mathcal{H}) = \mathcal{O}\left(\sqrt{\frac{m^2 + \log(1/\epsilon)}{m}} + \epsilon^2\right).$$

Finally, classical learning theory results imply the claim. □

**Remark 6.** *Compared to Balcan et al. (2023b), our framework provides a significant generalization. The techniques used for analyzing the surrogate logistic loss in Balcan et al. (2023b) involves bounding the complexity of Pfaffian piece functions, while the piece boundaries of the surrogate function are nice linear functions. In contrast, in this work we develop general techniques that can handle Pfaffian boundary functions as well, and we recover results from Balcan et al. (2023b) as a special case.*

## 7 Online learning

In this section, we introduce new general techniques for establishing no-regret learning guarantees for data-driven algorithms in the online learning setting when discontinuity of the piecewise Lipschitz dual loss or utility functions admit Pfaffian structure. Prior work (Balcan et al., 2020b) provided a tool for online learning when non-Lipschitzness (or discontinuity) occurs along roots of polynomials in one and two dimensions, and Balcan & Sharma (2021) extended the result to algebraic varieties in higher dimensions. Here, we generalize the results to cases where non-Lipschitzness occurs along Pfaffian hypersurfaces.

### 7.1 Overview of the dispersion property

We first start by giving a high-level overview of the dispersion property, which serves as a sufficient condition for online learning where the sequence of loss (or utility) functions is not continuous but is piecewise Lipschitz. While it is not always possible to obtain sub-linear regret for online learning with piecewise Lipschitz loss

functions, Balcan et al. (2018b) introduce the dispersion condition under which online learning is possible. Roughly speaking, dispersion measures the number of discontinuities of the loss function that can occur in a ball of a given radius. A sufficient bound on the dispersion can lead to a no-regret learning guarantee. Concretely, we will use the $f$-point-dispersion (Balcan et al., 2020b) which is a slightly more generalized notion.

**Definition 9** ($f$-point-dispersed, Balcan et al. 2020b)**.** *The sequence of loss functions $\ell_1, \ell_2, \ldots$ is $f$-point-dispersed for the Lipschitz constant $L$ and dispersion function $f : \mathbb{N} \times [0, \infty) \to \mathbb{R}$ if for all $T$ and for all $\epsilon > 0$, we have*

$$\mathbb{E}[\max_{\rho,\rho'} |\{t = 1, \ldots, T : |\ell_t(\rho) - \ell_t(\rho')| > L\|\rho - \rho'\|_2\}|] \leq f(T, \epsilon),$$

*where the max is taken over all $\rho, \rho' \in \mathcal{C} : \|\rho - \rho'\|_2 \leq \epsilon$.*

A continuous version of the classical multiplicative weights algorithm achieves the following no-regret guarantee provided the loss functions are dispersed.

**Theorem 7.1** (Balcan et al., 2020b)**.** *Let $\mathcal{C} \subset \mathbb{R}^d$ be contained in a ball of radius $R$ and $\ell_1, \ell_2, \cdots : \mathcal{C} \to [0, 1]$ be piecewise $L$-Lipschitz functions that are $f$-point-dispersed with an $r_0$-interior minimizer. Then, there exists an algorithm that satisfies the regret bound*

$$\mathbb{E}[\sum_{t=1}^{T} \ell_t(\rho_t) - \ell_t(\rho^*)] \leq \mathcal{O}(\sqrt{dTM \log(R/r)} + f(T, r) + TLr),$$

*for any $r \in (0, r_0]$.*

**Contributions.** Though the dispersion property provides a sufficient condition for no-regret learning piecewise Lipschitz loss functions, it is verifying the dispersion property that poses a challenge for Pfaffian structured functions. In this section, we provide a general tool for verifying dispersion property for the sequence of loss functions of which the discontinuities involve in Pfaffian hypersurfaces (Section 7.2). We then demonstrate the applicability of our tool by providing no-regret learning guarantees for under-explored data-driven algorithm design problems in the online learning setting (Section 7.3).

### 7.2 A general tool for verifying dispersion property involving Pfaffian discontinuity

We first introduce a useful notion of shattering which we use to establish a constant upper bound on the VC-dimension of a class of Pfaffian functions with bounded chain length and Pfaffian degree when labeled by axis-aligned segments (i.e., line segments parallel to some coordinate axis). This bound is crucial in extending the framework for establishing dispersion developed in prior work (Balcan et al., 2020b; Balcan & Sharma, 2021). We use tools from the theory of Pfaffian functions (included in Appendix E).

**Definition 10** (Hitting and shattering)**.** *Consider a Pfaffian chain $\mathcal{C}(\boldsymbol{x}, f_1, \ldots, f_q)$. Let $\mathcal{P} = \{P_1, \ldots, P_K\}$ denote a set of hypersurface, each defined by a Pfaffian function $P(\boldsymbol{x}, f_1(\boldsymbol{x}), \ldots, f_q(\boldsymbol{x})) = 0$ from the Pfaffian chain $\mathcal{C}$. We say that a subset $\mathcal{P}' \subseteq \mathcal{P}$ is hit by a line segment $v$ if, for any $P \in \mathcal{P}$, $v$ intersects with $P$ iff $P \in \mathcal{P}'$. A line $\Upsilon$ hits a subset $\mathcal{P}' \subseteq \mathcal{P}$, there is a line segment $v \in \Upsilon$ such that $v$ hit $\mathcal{P}'$. A collection $\mathcal{V}$ of line segments shatters $\mathcal{P}$ if for each subset $\mathcal{P}' \subseteq \mathbb{R}$, there exists a line segment $\mathcal{V}$ such that $v$ hits $\mathcal{P}'$.*

We have the following key structural result which intuitively establishes a bound on the complexity of intersection of Pfaffian hypersurfaces.

**Theorem 7.2.** *There is a constant $K_{M,q,d,p}$ depending only on $M$, $q$, $d$, and $p$ such that axis-aligned line segments in $\mathbb{R}^p$ cannot shatter any collection of $K_{M,q,d,p}$ Pfaffian hypersurfaces consisting of functions from a Pfaffian $\mathcal{C}$ chain of length $q$, degree at most $d$ and Pfaffian degree at most $M$.*

*Proof.* Let $\mathcal{C}(\boldsymbol{x}, f_1, \ldots, f_q)$, where $\boldsymbol{x} \in \mathbb{R}^p$, is a Pfaffian chain of length $q$ and of Pfaffian degree at most $M$. Let $\mathcal{P} = \{P_1, \ldots, P_K\}$ denote a collection of $K$ Pfaffian hypersurfaces $P_i(\boldsymbol{x}, f_1(\boldsymbol{x}), \ldots, f_q(\boldsymbol{x})) = 0$ for $i = 1, \ldots, K$, where each $P_i$ is a Pfaffain function of degree at most $d$ from the Pfaffian chain $\mathcal{C}$. We seek

to upper bound the number of subsets of $\mathcal{P}$ which may be hit by axis-aligned line segments. We will first consider shattering by line segments in a fixed axial direction $x = \boldsymbol{x}_j$ for $j \in [p]$.

Let $\Upsilon_j$ be a line along the axial direction $x_j$. The subsets of $\mathcal{P}$ which may be hit by segments along $\Upsilon_j$ are determined by the pattern of intersections of $\Upsilon_j$ with the hypersurfaces in $\mathcal{P}$. We can now use Theorem E.1 to bound the number of intersections between $\Upsilon_j$ and any hypersurface $P_i = 0$ for $P_i \in \mathcal{P}$ as

$$R := 2^{q(q-1)/2} d(M \min\{q, p\} + d)^q,$$

using the fact that the straight line $\Upsilon_j$ is given by $p-1$ equations $x_k = 0$ for $k \neq j$ which form a Pfaffian system with $P_i$ of chain length $q$, Pfaffian degree $M$, and degrees $\deg(P_i) = d$, $\deg(x_k) = 1$ for $k \neq j$. Therefore $\Upsilon_j$ intersects hypersurfaces in $\mathcal{P}$ at most $KR$ points, resulting in at most $KR + 1$ segments of $\Upsilon_j$. Thus, $\Upsilon_j$ may hit at most $\binom{KR+1}{2} = \mathcal{O}(K^2 2^{q(q-1)} d^2 (M \min\{q, p\} + d)^{2q})$ subsets of $\mathcal{P}$. We remark that these upper bounds correspond to an assumption that the Pfaffian hypersurfaces are in a general position, i.e. a small perturbation to the hypersurfaces does not change the number of intersections. Note that there can only be fewer subsets otherwise, so the upper bound still holds.

We will now bound the number of distinct subsets that may be hit as the axis-aligned $\Upsilon_j$ is varied (while it is still along the direction $x_j$). Define the equivalence relation $L_{x_1} \sim L_{x_2}$ if the same sequence of hypersurfaces in $\mathcal{P}$ intersect $L_{x_1}$ and $L_{x_2}$ (in the same order, including with multiplicities). To obtain these equivalence classes, we will project the hypersurfaces in $\mathcal{P}$ onto a hyperplane orthogonal to the $x_j$-direction. By the generalization of the Tarski-Seidenberg theorem to Pfaffian manifolds, we get a collection of semi-Pfaffian sets (van den Dries, 1986), and these sets form a cell complex with at most $\mathcal{O}(K^{(p!)^2 (2p(2p+q))^p} (M+d)^{q^{\mathcal{O}(p^3)}})$ cells (Gabrielov & Vorobjov, 2001). This is also a bound on the number of equivalence classes for the relation $\sim$.

Putting together, for each axis-parallel direction $x_j$, the number of distinct subsets of $\mathcal{P}$ hit by any line segment along the direction $x_j$ is at most $\mathcal{O}(K^2 2^{q(q-1)} d^2 (M \min\{q, p\} + d)^{2q} K^{(p!)^2 (2p(2p+q))^p} (M+d)^{q^{\mathcal{O}(p^3)}})$. Thus, for all axis-parallel directions, we get that the total number of subsets of $\mathcal{P}$ that may be hit is at most

$$C_K = O\left(p 2^{q(q-1)} d^2 (M \min\{q, p\} + d)^{2q} K^{(p!)^2 (2p(2p+q))^p + 2} (M+d)^{q^{\mathcal{O}(p^3)}}\right).$$

For fixed $M, q, d, p$, this grows sub-exponentially in $K$, and therefore there is an absolute constant $K_{M,q,d,p}$ such that $C_K < 2^K$ provided $K \geq K_{M,q,d,p}$. This implies that a collection of $K_{M,q,d,p}$ Pfaffian hypersurfaces cannot be shattered by axis-aligned line segments and establishes the desired claim. □

We can now use the above theorem to establish the following general tool for verifying dispersion of piecewise-Lipschitz functions where the piece boundaries are given by Pfaffian hypersurfaces.

**Theorem 7.3.** *Let $l_1, \ldots, l_T : \mathbb{R}^p \to \mathbb{R}$ be independent piecewise $L$-Lipschitz functions, each having discontinuities specified by a collection of at most $K$ Pfaffian hypersurfaces of bounded degree $d$, Pfaffian degree $M$ and length of common Pfaffian chain $q$. Let $L$ denote the set of axis-aligned paths between pairs of points in $\mathbb{R}^p$, and for each $s \in L$ define $D(T, s) = |\{1 \leq t \leq T \mid l_t \text{ has a discontinuity along } s\}|$. Then we have that $\mathbb{E}[\sup_{s \in L} D(T, s)] \leq \sup_{s \in L} \mathbb{E}[D(T, s)] + \tilde{O}(\sqrt{T \log T})$, where the soft-O notation suppresses constants in $d, p, M, q$.*

*Proof.* **Technical overview**. We relate the number of ways line segments can label vectors of $K$ Pfaffian hypersurfaces of degree $d$, Pfaffian degree $M$ and common chain length $q$, to the VC-dimension of line segments (when labeling Pfaffian hypersurfaces), which from Theorem 7.2 is constant. To verify dispersion, we need a uniform-convergence bound on the number of Lipschitzness violations between the worst pair of points $\rho, \rho'$ at distance $\leq \epsilon$, but the definition allows us to bound the worst rate of discontinuities along any path between $\rho, \rho'$ of our choice. We can bound the VC-dimension of axis aligned segments against Pfaffian hypersurfaces of bounded complexity, which will allow us to establish dispersion by considering piecewise axis-aligned paths between points $\rho$ and $\rho'$.

**Proof details**. The proof is similar to analogous results in (Balcan et al., 2020b; Balcan & Sharma, 2021). The main difference is that instead of relating the number of ways intervals can label vectors of discontinuity points to the VC-dimension of intervals, we instead relate the number of ways line segments can label vectors of $K$ Pfaffian hypersurfaces of bounded complexity to the VC-dimension of line segments (when labeling Pfaffian hypersurfaces), which from Theorem 7.2 is constant. To verify dispersion, we need a uniform-convergence bound on the number of Lipschitz failures between the worst pair of points $\alpha, \alpha'$ at distance $\leq \epsilon$, but the definition allows us to bound the worst rate of discontinuities along any path between $\alpha, \alpha'$ of our choice. We can bound the VC dimension of axis aligned segments against bounded complexity Pfaffian hypersurfaces, which will allow us to establish dispersion by considering piecewise axis-aligned paths between points $\alpha$ and $\alpha'$.

Let $\mathcal{P}$ denote the set of all Pfaffian hypersurfaces of degree $d$, from a Pfaffian chain of length at most $q$ and Pfaffian degree at most $M$. For simplicity, we assume that every function has its discontinuities specified by a collection of exactly $K$ Pfaffian hypersurfaces ($K$ could be an upper bound, and we could simply duplicate hypersurfaces as needed which does not affect our argument below). For each function $l_t$, let $\pi^{(t)} \in \mathcal{P}^K$ denote the ordered tuple of Pfaffian hypersurfaces in $\mathcal{P}$ whose entries are the discontinuity locations of $l_t$. That is, $l_t$ has discontinuities along $(\pi_1^{(t)}, \ldots, \pi_K^{(t)})$, but is otherwise $L$-Lispchitz.

For any axis aligned path $s$, define the function $f_s : \mathcal{P}^K \to \{0, 1\}$ by

$$f_s(\pi) = \begin{cases} 1 & \text{if for some } i \in [K],\ \pi_i \text{ intersects } s, \\ 0 & \text{otherwise,} \end{cases}$$

where $\pi = (\pi_1, \ldots, \pi_K) \in \mathcal{P}^K$. The sum $\sum_{t=1}^T f_s(\pi^{(t)})$ counts the number of vectors $(\pi_1^{(t)}, \ldots, \pi_K^{(t)})$ that intersect $s$ or, equivalently, the number of functions $l_1, \ldots, l_T$ that are not $L$-Lipschitz on $s$. We will apply VC-dimension uniform convergence arguments to the class $\mathcal{F} = \{f_s : \mathcal{P}^K \to \{0, 1\} \mid s \text{ is an axis-aligned path}\}$. In particular, we will show that for an independent set of vectors $(\pi_1^{(t)}, \ldots, \pi_K^{(t)})$, with high probability we have that $\frac{1}{T}\sum_{t=1}^T f_s(\pi^{(t)})$ is close to $\mathbb{E}[\frac{1}{T}\sum_{t=1}^T f_s(\pi^{(t)})]$ for all paths $s$.

Now, Theorem 7.2 implies that VC dimension of $\mathcal{F}$ is at most $K_{M,q,d,p}$. A standard VC-dimension uniform convergence argument for the class $\mathcal{F}$ imply that with probability at least $1 - \delta$, for all $f_s \in \mathcal{F}$

$$\left| \frac{1}{T}\sum_{t=1}^T f_s(\pi^{(t)}) - \mathbb{E}\left[\frac{1}{T}\sum_{t=1}^T f_s(\pi^{(t)})\right] \right| \leq O\left(\sqrt{\frac{K_{M,q,d,p} + \log(1/\delta)}{T}}\right), \text{ or}$$
$$\left| \sum_{t=1}^T f_s(\pi^{(t)}) - \mathbb{E}\left[\sum_{t=1}^T f_s(\pi^{(t)})\right] \right| \leq \tilde{O}\left(\sqrt{T\log(1/\delta)}\right).$$

Now since $D(T, s) = \sum_{t=1}^T f_s(\pi^{(t)})$, we have for all $s$ and $\delta$, with probability at least $1 - \delta$, $\sup_{s \in L} D(T, s) \leq \sup_{s \in L} \mathbb{E}[D(T, s)] + \tilde{O}(\sqrt{T\log(1/\delta)})$. Taking expectation and setting $\delta = 1/\sqrt{T}$ implies

$$\begin{aligned} \mathbb{E}[\sup_{s \in L} D(T, s)] &\leq (1 - \delta)\left(\sup_{s \in L} \mathbb{E}[D(T, s)] + \tilde{O}(\sqrt{T\log(1/\delta)})\right) + \delta \cdot T \\ &\leq \sup_{s \in L} \mathbb{E}[D(T, s)] + \tilde{O}(\sqrt{T\log(\sqrt{T})}) + \sqrt{T}, \end{aligned}$$

which implies the desired bound. Here we have upper bounded the expected regret by $T$ in the low probability failure event where the uniform convergence does not hold. □

The above result reduces the problem of verifying dispersion to showing that the expected number of discontinuities $\mathbb{E}[D(T, s)]$ along any axis-aligned path $s$ is $\tilde{O}(\epsilon T)$, which together with Theorem 7.3 implies that the sequence of functions is $f$-point-dispersed with $f(T, \epsilon) = \tilde{O}(\epsilon T + \sqrt{T})$, which in turn implies no-regret online learning (Theorem 7.1).

### 7.3 Applications

We will now instantiate our general online learning results for concrete applications, including linkage clustering and regularized logistic regression. The key new challenge for establishing online learning guarantees is that we need to analyze the relative position of the Pfaffian structured discontinuities (in contrast, in the distributional learning setting, we only cared about the number of induced sign patterns).

#### 7.3.1 Online learning for data-driven agglomerative hierarchical clustering

We first show how to analyse disperion property of Pfaffian structured loss functions in agglomerative hierarchical clustering. Technical lemmas needed for the proof are deferred to Appendix E.

**Theorem 7.4.** *Consider an adversary choosing a sequence of clustering instances where the $t$-th instance has a symmetric distance matrix $D^{(t)} \in [0, R]^{n\times n}$ and for all $i \leq j, d_{ij}^{(t)}$ is $\kappa$-smooth. For the sub-family of $\mathcal{M}_1$ with $\alpha > \alpha_{\min}$ for $0 < \alpha_{\min} < \infty$, we have that the corresponding sequence of utility functions $u_1^{(t)}$ are $f$-point-dispersed with $f(T, \epsilon) = \tilde{O}(\epsilon T + \sqrt{T})$.*

*Proof.* **Technical overview**. By using a generalization of the Descartes' rule of signs, we first show that there is at most one positive real solution for the equation

$$(d(a_1, b_1))^\alpha + (d(a_2, b_2))^\alpha = (d(a_1', b_1'))^\alpha + (d(a_2', b_2'))^\alpha.$$

We then use $\kappa$ boundedness of the distances $d_{ij}$ to show that the probability of having a zero $\alpha^* \in I$ in any interval of width $I$ is at most $\tilde{O}(\epsilon)$. Using that we have at most $n^8$ such boundary functions, we can conclude that $\mathbb{E}[D(T, s)] = \tilde{O}(n^8\epsilon T)$ and use Theorem 7.3.

**Proof details**. As noted in the proof of Theorem 6.1, the boundaries of the piecewise-constant dual utility functions are given by

$$(d(a_1, b_1))^\alpha + (d(a_2, b_2))^\alpha = (d(a_1', b_1'))^\alpha + (d(a_2', b_2'))^\alpha, \tag{1}$$

for some (not necessarily distinct) points $a_1, b_1, a_2, b_2, a_1', b_1', a_2', b_2' \in S$.

We use the generalized Descartes' rule of signs (Jameson, 2006; Haukkanen & Tossavainen, 2011), which implies that the number of real zeros in $\alpha$ (for which boundary condition is satisfied) is at most the number of sign changes when the base of the exponents are arranged in an ascending order (since, the family $\{a^x \mid a \in \mathbb{R}_+\}$ is *Descartes admissible* on $\mathbb{R}$), to conclude that the boundary of the loss function occurs for at most one point $\alpha^* \in \mathbb{R}$ apart from $\alpha = 0$. We consider the following distinct cases (up to symmetry):

- Case $d_\beta(a_1, b_1) \geq d_\beta(a_2, b_2) \geq d_\beta(a_1', b_1') \geq d_\beta(a_2', b_2')$. The number of sign changes is one, and the conclusion is immediate.
- Case $d_\beta(a_1, b_1) \geq d_\beta(a_1', b_1') \geq d_\beta(a_2, b_2) \geq d_\beta(a_2', b_2')$. The only possibility is $d_\beta(a_1, b_1) = d_\beta(a_1', b_1')$ and $d_\beta(a_2, b_2) = d_\beta(a_2', b_2')$. But then, the condition holds for all $\alpha$ and we do not get a critical point. This corresponds to the special case of tie-breaking when merging clusters, and we assume ties are broken following some arbitrary but fixed ordering of the pair of points.
- Case $d_\beta(a_1', b_1') \geq d_\beta(a_1, b_1) \geq d_\beta(a_2, b_2) \geq d_\beta(a_2', b_2')$. The number of sign changes is two. Since $\alpha = 0$ is a solution, there is at most one $\alpha^* \in \mathbb{R} \in \backslash\{0\}$ corresponding to a critical point.

Now, let $\epsilon > 0$. Consider an interval $I = [\alpha_1, \alpha_2]$ with $\alpha_1 > \alpha_{\min}$ such that the width $\alpha_2 - \alpha_1 \leq \epsilon$. If equation (1) has a solution $\alpha^* \in I$ (guaranteed to be unique if it exists), we have that

$$d(a_1, b_1) = \left((d(a_1', b_1'))^{\alpha^*} + (d(a_2', b_2'))^{\alpha^*} - (d(a_2, b_2))^{\alpha^*}\right)^{1/\alpha^*}$$

Let $p_1$ denote the density of $d(a_1, b_1)$ which is at most $\kappa$ by assumption, and let $f(\alpha^*) := (d(a_1', b_1'))^{\alpha^*} + (d(a_2', b_2'))^{\alpha^*} - (d(a_2, b_2))^{\alpha^*}$ and $d_1(\alpha^*) := (f(\alpha^*))^{1/\alpha^*}$. We seek to upper bound $\Pr_{p_1}\{d_1(\alpha^*) \mid \alpha^* \in I, f(\alpha^*) \geq 0\}$ to get a bound on the probability that there is a critical point in $I$.

Now we consider two cases. If $f(\alpha) \leq \epsilon^\alpha$ for all $\alpha \in I$, we have that $d_1(\alpha) = f(\alpha)^{1/\alpha} \leq \epsilon$ for all $\alpha \in I$. Thus, the probability of having a critical point in $I$ is $\mathcal{O}(\kappa\epsilon)$ in this case.

Else, we have that $f(\alpha^*) > \epsilon^{\alpha^*} > 0$ for some $\alpha^* \in I$. Using Taylor series expansion for $d_1(\alpha)$ around $\alpha^*$, we have

$$d_1(\alpha^* + \epsilon) = d_1(\alpha^*) + d_1'(\alpha^*)\epsilon + \mathcal{O}(\epsilon^2).$$

Thus, the set $\{d_1(\alpha^*) \mid \alpha^* \in I, f(\alpha^*) \geq 0\}$ is contained in an interval of width at most $|d_1'(\alpha^*)|\mathcal{O}(\epsilon)$, implying a upper bound of $\kappa|d_1'(\alpha^*)|\mathcal{O}(\epsilon)$ on the probability of having a critical point in $I$.

Thus it is sufficient to give a bound on $|d_1'(\alpha^*)|$. We have

$$\begin{aligned} d_1'(\alpha^*) &= d_1(\alpha^*)\left(-\frac{1}{{\alpha^*}^2}\ln f(\alpha^*) + \frac{1}{\alpha^*}\frac{g(\alpha^*)}{f(\alpha^*)}\right) \\ &= \frac{1}{\alpha^*}\left(\frac{g(\alpha^*)}{f(\alpha^*)} - d_1(\alpha^*)\ln d_1(\alpha^*)\right), \end{aligned}$$

where

$$g(\alpha) := \ln d(a_1', b_1')(d(a_1', b_1'))^{\alpha^*} + \ln d(a_2', b_2')(d(a_2', b_2'))^{\alpha^*} - \ln d(a_2, b_2)(d(a_2, b_2))^{\alpha^*}.$$

Thus,

$$\begin{aligned} |d_1'(\alpha^*)| &= \left|\frac{1}{\alpha^*}\left(\frac{g(\alpha^*)}{f(\alpha^*)} - d_1(\alpha^*)\ln d_1(\alpha^*)\right)\right| \\ &\leq \left|\frac{1}{\alpha^*}\right| \cdot \left(\left|\frac{g(\alpha^*)}{f(\alpha^*)}\right| + |d_1(\alpha^*)\ln d_1(\alpha^*)|\right) \\ &\leq \left|\frac{1}{\alpha_{\min}}\right| \cdot \left(\left|\frac{g(\alpha^*)}{f(\alpha^*)}\right| + R\ln R\right). \end{aligned}$$

Now using Lemma E.3, we get that

$$\left|\frac{g(\alpha^*)}{f(\alpha^*)}\right| \leq \frac{1}{\alpha^*} + \ln R,$$

and thus,

$$|d_1'(\alpha^*)| \leq O\left(\frac{R\ln R}{\alpha_{\min}^2}\right).$$

Using that we have at most $n^8$ boundary functions of the form (1), we can conclude that $\mathbb{E}[D(T, s)] = \tilde{O}(\frac{R\ln R}{\alpha_{\min}^2}\kappa n^8 \epsilon T)$ and using Theorem 7.3 we can conclude that the sequence of utility functions are $f$-point-dispersed with $f(T, \epsilon) = \tilde{O}(\epsilon T + \sqrt{T})$. □

We also show how to use our tools above to establish the dispersion property for the $\mathcal{M}_3$ linkage clustgering algorithm family.

**Theorem 7.5.** *Consider an adversary choosing a sequence of clustering instances where the $t$-th instance has a symmetric distance matrix $D^{(t)} \in [0, R]^{n\times n}$ and for all $i \leq j, d_{ij}^{(t)}$ is $\kappa$-smooth. For the family of clustering algorithms $\mathcal{M}_3$, we have that the corresponding sequence of utility functions $u_3^{(t)}$ as a function of the parameter $\alpha = (\alpha_1, \ldots, \alpha_L)$ are $f$-point-dispersed with $f(T, \epsilon) = \tilde{O}(\epsilon T + \sqrt{T})$.*

*Proof.* **Technical overview**. It is sufficient to show dispersion for each $\alpha_i$ keeping the remaining parameters fixed. This is because, the definition of dispersion allows us to consider intersections of discontinuities with axis-aligned paths. WLOG, assume $\alpha_2, \ldots, \alpha_L$ are fixed. The boundary functions are given by solutions of exponential equations in $\alpha_1$ of the form

$$\frac{1}{|A||B|}\sum_{a\in A, b\in B} \Pi_{i\in[L]}(d_i(a,b))^{\alpha_i} = \frac{1}{|A'||B'|}\sum_{a'\in A', b'\in B'} \Pi_{i\in[L]}(d_i(a',b'))^{\alpha_i},$$

for $A, B, A', B' \subseteq S$. We can now use Theorem 7.3 together with Theorem 25 of Balcan & Sharma (2021) to conclude that the discontinuities of $u_3^{(t)}$ are $f$-point-dispersed with $f(T, \epsilon) = \tilde{O}(\epsilon T + \sqrt{T})$.

**Proof details**. We will show dispersion for each $\alpha_i$ keeping the remaining parameters fixed. This is sufficient because, the definition of dispersion Balcan et al. (2020b) allows us to consider discontinuities along axis-aligned paths between pairs of points $\alpha, \alpha'$ in the parameter space. WLOG, assume that $\alpha_2, \ldots, \alpha_L$ are fixed. The boundary functions are given by solutions of exponential equations in $\alpha_1$ of the form

$$\frac{1}{|A||B|}\sum_{a\in A, b\in B} \Pi_{i\in[L]}(d_i(a,b))^{\alpha_i} = \frac{1}{|A'||B'|}\sum_{a'\in A', b'\in B'} \Pi_{i\in[L]}(d_i(a',b'))^{\alpha_i},$$

for $A, B, A', B' \subseteq S$. We can rewrite this equation in the form $\sum_{j=1}^{n} a_j e^{b_j x} = 0$ where, $x = \alpha_1$, $b_j = \ln(d_1(a,b))$ for $a, b \in A \times B$ or $a, b \in A' \times B'$ and $a_j = \frac{1}{|A||B|}\Pi_{i\in\{2,\ldots,L} d_i(a,b)^{\alpha_i}$ for $a, b \in A \times B$ or $a_j = \frac{-1}{|A'||B'|}\Pi_{i\in\{2,\ldots,L\}} d_i(a',b')^{\alpha_i}$ for $a', b' \in A' \times B'$. The coefficients $a_j$ are real with magnitude at most $R^{L-1}$. By Lemma E.4, we have that $d_i(a,b)^{\alpha_i}$ is $\kappa'$-bounded for $\kappa' \leq \frac{\kappa}{\alpha_{\min}} \max\{1, R^{\frac{1}{\alpha_{\min}}-1}\}$, and therefore the coefficients $a_j$ have a $\kappa''$-bounded density for $\kappa'' \leq n^2\kappa'^{L-1} = O\left(n^2\left(\frac{\kappa R^{1/\alpha_{\min}}}{\alpha_{\min}}\right)^{L-1}\right)$ (using Lemma 8 from Balcan et al. (2018b)). Using Theorem E.5, the probability there is a discontinuity along any segment along the direction $\alpha_1$ of width $\epsilon$ is $p_1 = \tilde{O}(\epsilon)$. Thus, for any axis-aligned path $s$ between points $\alpha, \alpha' \in \mathbb{R}^L$, the expected number of discontinuities for any utility function $u_3^{(t)}$ ($t \in [T]$) is at most $Lp_1 = \tilde{O}(\epsilon)$. We can now apply Theorem 7.3 to get

$$\begin{aligned}\mathbb{E}[\sup_{s\in\mathcal{L}} D(T,s)] &\leq \sup_{s\in\mathcal{L}} \mathbb{E}[D(T,s)] + \tilde{O}(\sqrt{T\log T}) \\ &= \tilde{O}(\epsilon T) + \tilde{O}(\sqrt{T\log T}),\end{aligned}$$

where $\mathcal{L}$ denotes the set of axis-aligned paths between pairs of points $\alpha, \alpha' \in \mathbb{R}^L$. It then follows that $\mathbb{E}[\sup_{s\in\mathcal{L}} D(T,s)] = \tilde{O}(\sqrt{T})$ for $\epsilon \geq T^{-1/2}$, establishing that the sequence of utility functions $u_3^{(1)}, \ldots, u_3^{(T)}$ is $f$-point-dispersed with $f(T, \epsilon) = \tilde{O}(\epsilon T + \sqrt{T})$. □

### 7.3.2 Online learning for data-driven regularized logistic regression

We consider an online learning setting for regularized logistic regression from Section 6.3. The problem instances $P_t = (\boldsymbol{X}^{(t)}, \boldsymbol{y}^{(t)}, \boldsymbol{X}_{\text{val}}^{(t)}, \boldsymbol{y}_{\text{val}}^{(t)})$ are now presented online in a sequence of rounds $t = 1, \ldots, T$, and the online learner predicts the regularization coefficient $\lambda_t$ in each round. The regret of the learner is given by

$$R_T = \mathbb{E}\sum_{t=1}^{T} h_{\lambda_t}(P_t) - h_{\lambda^*}P_t,$$

where $\lambda^* = \arg\min_{\lambda \in [\lambda_{\min}, \lambda_{\max}]} \mathbb{E} \sum_{t=1}^{T} h_\lambda(P_t)$. Our main result is to show the existence of a no-regret learner in this setting.

**Theorem 7.6.** *Consider the online learning problem for tuning the logistic regression regularization coefficient $\lambda_t$ stated above. There exists an online learner with expected regret bounded by $\mathcal{O}(\sqrt{T \log[(\lambda_{max} - \lambda_{min})T]})$.*

*Proof.* **Technical overview**. The key idea is to use an appropriate surrogate loss function which well approximates the true loss function, but is dispersed and therefore can be learned online. We then connect the regret of the learner with respect to the surrogate loss with its regret w.r.t. the true loss.

We consider an $\epsilon$-grid of $\lambda$ values. For each round $t$, to construct the surrogate loss function, we sample a uniformly random point from each interval $[\lambda_{\min} + k\epsilon, \lambda_{\min} + (k+1)\epsilon]$ and compute the surrogate loss $h_\lambda^{(\epsilon)}(P)$ at that point, and use a linear interpolation between successive points. By Theorem D.1, this has an error of at most $\mathcal{O}(\epsilon^2)$, which implies the regret gap with the true loss is at most $\mathcal{O}(\epsilon^2 T)$ when using the surrogate function.

We show that the surrogate function is $f$-point-dispersed (Definition 4, Balcan et al. (2020b)) with $f(T, r) = \frac{rT}{\epsilon}$. Using Theorem 5 of Balcan et al. (2020b), we get that there is an online learner with regret $\mathcal{O}(\sqrt{T \log((\lambda_{\max} - \lambda_{\min})/r)} + f(T, r) + Tr + \epsilon^2 T) = \mathcal{O}(\sqrt{T \log((\lambda_{\max} - \lambda_{\min})/r)} + \frac{Tr}{\epsilon} + \epsilon^2 T)$. Setting $\epsilon = T^{-1/4}$ and $r = T^{-3/4}$, we get the claimed regret upper bound.

**Proof details**. We consider an $\epsilon$-grid of $\lambda$ values given by intervals $[\lambda_{\min} + k\epsilon, \lambda_{\min} + (k+1)\epsilon]$ for $k = 0, \ldots, \lfloor \frac{\lambda_{\max} - \lambda_{\min}}{\epsilon} \rfloor$. For each round $t$, to construct the surrogate loss function, we sample a uniformly random point $\lambda_t^{(k)}$ from each interval $[\lambda_{\min} + k\epsilon, \lambda_{\min} + (k+1)\epsilon]$ and compute the surrogate model $\hat{\beta}_{(X,y)}(\lambda)$ at that point using Algorithm 1 (2) for $\ell_1$ ($\ell_2$), and use a linear interpolation between successive points $\lambda_t^{(k)}, \lambda_t^{(k+1)}$ which are at most $2\epsilon$ apart. By Theorem D.1, we have that $\|\hat{\beta}_{(X_t, y_t)}(\lambda) - \beta^{(\epsilon)}_{(X_t, y_t)}(\lambda)\|_2 = \mathcal{O}(\epsilon^2)$ for any $\lambda \in [\lambda_{\min}, \lambda_{\max}]$, where $\beta^{(\epsilon)}_{(X_t, y_t)}(\lambda)$ is the true model (that exactly optimizes the logistic loss) for $(X_t, y_t)$. By Lemma 4.2 of Balcan et al. (2023b) we can conclude that the corresponding surrogate loss $\hat{h}_\lambda^{(\epsilon)}(P_t)$ also satisfies $||\hat{h}_\lambda^{(\epsilon)}(P_t) - h_\lambda(P_t)|| \leq \mathcal{O}(\epsilon^2)$ for any $\lambda \in [\lambda_{\min}, \lambda_{\max}]$.

This implies the regret with respect to the true loss is at most $\mathcal{O}(\epsilon^2 T)$ more than the regret when using the surrogate function. Suppose $\lambda^* = \arg\min_{\lambda \in [\lambda_{\min}, \lambda_{\max}]} \sum_{t=1}^{T} \mathbb{E}[h_\lambda(P_t)]$. We have,

$$
\begin{aligned}
R_T &= \sum_{t=1}^{T} \mathbb{E}[h_{\lambda_t}(P_t) - h_{\lambda^*}(P_t)] \\
&= \sum_{t=1}^{T} \mathbb{E}[h_{\lambda_t}(P_t) - \hat{h}_{\lambda^*}(P_t)] + \sum_{t=1}^{T} \mathbb{E}[\hat{h}_{\lambda^*}(P_t) - h_{\lambda^*}(P_t)] \\
&\leq \sum_{t=1}^{T} \mathbb{E}[h_{\lambda_t}(P_t) - \hat{h}_{\lambda^*}(P_t)] + \mathcal{O}(\epsilon^2 T) \\
&\leq \sum_{t=1}^{T} \mathbb{E}[h_{\lambda_t}(P_t) - \hat{h}_{\hat{\lambda}}(P_t)] + \mathcal{O}(\epsilon^2 T),
\end{aligned}
$$

where $\hat{\lambda} = \arg\min_{\lambda \in [\lambda_{\min}, \lambda_{\max}]} \sum_{t=1}^{T} \mathbb{E}[\hat{h}_\lambda(P_t)]$.

We next show that the surrogate function is $f$-point-dispersed (Definition 4, Balcan et al. (2020b)) with $f(T, r) = \frac{rT}{\epsilon}$. Indeed, let $0 < r < \epsilon$. Let $I = [\lambda_1, \lambda_2] \subset [\lambda_{\min}, \lambda_{\max}]$ be an interval of length $r$. Then the probability $\hat{h}_\lambda(P_t)$ has a critical point in $I$ is at most $r/\epsilon$.

Using Theorem 5 of Balcan et al. (2020b) combined with the above argument, we now get that there is an online learner with regret $\mathcal{O}(\sqrt{T\log((\lambda_{\max}-\lambda_{\min})/r)}+f(T,r)+Tr+\epsilon^2 T)=\mathcal{O}(\sqrt{T\log((\lambda_{\max}-\lambda_{\min})/r)}+\frac{Tr}{\epsilon}+\epsilon^2 T)$. Setting $\epsilon=T^{-1/4}$ and $r=T^{-3/4}$, we get the claimed regret upper bound. □

## 8 Conclusion and future directions

In this work, we introduce the Pfaffian GJ framework for the data-driven distributional learning setting, providing learning guarantees for function classes whose computations involve the broad class of Pfaffian functions. Additionally, we propose a refined Pfaffian piecewise structure for data-driven algorithm design problems and establish improved learning guarantees for problems admitting such a refined piecewise structure. We apply our framework to a variety of previously studied data-driven algorithm design problems (including hierarchical clustering, graph-based semi-supervised learning and regularized logistic regression) under natural settings, where known techniques do not yield concrete learning guarantees. By carefully analyzing the underlying Pfaffian structure for these problems, we leverage our proposed framework to establish novel statistical learning guarantees. We further study the data-driven online learning setting, where we introduce a new tool for verifying the dispersion property, applicable when the transition boundaries of the utility functions involve Pfaffian functions.

## References

Nir Ailon, Bernard Chazelle, Kenneth L Clarkson, Ding Liu, Wolfgang Mulzer, and C Seshadhri. Self-improving algorithms. *SIAM Journal on Computing*, 40(2):350–375, 2011.

Nir Ailon, Omer Leibovich, and Vineet Nair. Sparse linear networks with a fixed butterfly structure: Theory and practice, 2021.

Martin Anthony and Peter L. Bartlett. *Neural Network Learning: Theoretical Foundations*. Cambridge University Press, USA, 1st edition, 2009. ISBN 052111862X.

Peter Armitage, Geoffrey Berry, and John Nigel Scott Matthews. *Statistical methods in medical research*. John Wiley & Sons, 2008.

Pranjal Awasthi, Maria Florina Balcan, and Konstantin Voevodski. Local algorithms for interactive clustering. *Journal of Machine Learning Research*, 18(3):1–35, 2017.

Maria-Florina Balcan. Book chapter Data-Driven Algorithm Design. In *Beyond Worst Case Analysis of Algorithms, T. Roughgarden (Ed)*. Cambridge University Press, 2020.

Maria-Florina Balcan and Dravyansh Sharma. Data driven semi-supervised learning. *Advances in Neural Information Processing Systems*, 34:14782–14794, 2021.

Maria-Florina Balcan and Dravyansh Sharma. Learning accurate and interpretable decision trees. *Conference on Uncertainty in Artificial Intelligence*, 2024.

Maria-Florina Balcan, Avrim Blum, Patrick Pakyan Choi, John Lafferty, Brian Pantano, Mugizi Robert Rwebangira, and Xiaojin Zhu. Person identification in webcam images: An application of semi-supervised learning. In *ICML 2005 Workshop on Learning with Partially Classified Training Data*, volume 2, 2005.

Maria-Florina Balcan, Vaishnavh Nagarajan, Ellen Vitercik, and Colin White. Learning-theoretic foundations of algorithm configuration for combinatorial partitioning problems. In *Conference on Learning Theory*, pp. 213–274. PMLR, 2017.

Maria-Florina Balcan, Travis Dick, Tuomas Sandholm, and Ellen Vitercik. Learning to branch. In *International conference on machine learning*, pp. 344–353. PMLR, 2018a.

Maria-Florina Balcan, Travis Dick, and Ellen Vitercik. Dispersion for data-driven algorithm design, online learning, and private optimization. In *2018 IEEE 59th Annual Symposium on Foundations of Computer Science (FOCS)*, pp. 603–614. IEEE, 2018b.

Maria-Florina Balcan, Travis Dick, and Colin White. Data-driven clustering via parameterized Lloyd's families. *Advances in Neural Information Processing Systems*, 31, 2018c.

Maria-Florina Balcan, Travis Dick, and Manuel Lang. Learning to link. In *International Conference on Learning Representation*, 2020a.

Maria-Florina Balcan, Travis Dick, and Wesley Pegden. Semi-bandit optimization in the dispersed setting. In *Conference on Uncertainty in Artificial Intelligence*, pp. 909–918. PMLR, 2020b.

Maria-Florina Balcan, Tuomas Sandholm, and Ellen Vitercik. Refined bounds for algorithm configuration: The knife-edge of dual class approximability. In *International Conference on Machine Learning*, pp. 580–590. PMLR, 2020c.

Maria-Florina Balcan, Dan DeBlasio, Travis Dick, Carl Kingsford, Tuomas Sandholm, and Ellen Vitercik. How much data is sufficient to learn high-performing algorithms? generalization guarantees for data-driven algorithm design. In *Proceedings of the 53rd Annual ACM SIGACT Symposium on Theory of Computing*, pp. 919–932, 2021a.

Maria-Florina Balcan, Siddharth Prasad, Tuomas Sandholm, and Ellen Vitercik. Sample complexity of tree search configuration: Cutting planes and beyond. *Advances in Neural Information Processing Systems*, 34:4015–4027, 2021b.

Maria-Florina Balcan, Mikhail Khodak, Dravyansh Sharma, and Ameet Talwalkar. Provably tuning the ElasticNet across instances. *Advances in Neural Information Processing Systems*, 35:27769–27782, 2022a.

Maria-Florina Balcan, Siddharth Prasad, Tuomas Sandholm, and Ellen Vitercik. Improved sample complexity bounds for branch-and-cut. In *28th International Conference on Principles and Practice of Constraint Programming*, 2022b.

Maria-Florina Balcan, Siddharth Prasad, Tuomas Sandholm, and Ellen Vitercik. Structural analysis of branch-and-cut and the learnability of Gomory mixed integer cuts. *Advances in Neural Information Processing Systems*, 35:33890–33903, 2022c.

Maria-Florina Balcan, Avrim Blum, Dravyansh Sharma, and Hongyang Zhang. An analysis of robustness of non-Lipschitz networks. *Journal of Machine Learning Research*, 24(98):1–43, 2023a.

Maria-Florina Balcan, Anh Nguyen, and Dravyansh Sharma. New bounds for hyperparameter tuning of regression problems across instances. *Advances in Neural Information Processing Systems*, 36, 2023b.

Peter Bartlett, Piotr Indyk, and Tal Wagner. Generalization bounds for data-driven numerical linear algebra. In *Conference on Learning Theory*, pp. 2013–2040. PMLR, 2022.

Peter L Bartlett and Shahar Mendelson. Rademacher and gaussian complexities: Risk bounds and structural results. *Journal of Machine Learning Research*, 3(Nov):463–482, 2002.

Avrim Blum and Shuchi Chawla. Learning from labeled and unlabeled data using graph mincuts. *International Conference on Machine Learning*, 2001.

Olivier Chapelle, Bernhard Schlkopf, and Alexander Zien. *Semi-Supervised Learning*. The MIT Press, 1st edition, 2010. ISBN 0262514125.

Hongyu Cheng, Sammy Khalife, Barbara Fiedorowicz, and Amitabh Basu. Data-driven algorithm design using neural networks with applications to branch-and-cut. *arXiv preprint arXiv:2402.02328*, 2024.

Michael Chichignoud, Johannes Lederer, and Martin J Wainwright. A practical scheme and fast algorithm to tune the lasso with optimality guarantees. *Journal of Machine Learning Research*, 17(229):1–20, 2016.

Talya Eden, Piotr Indyk, Shyam Narayanan, Ronitt Rubinfeld, Sandeep Silwal, and Tal Wagner. Learning-based support estimation in sublinear time. In *International Conference on Learning Representations*, 2021.

Alberto Fernández and Sergio Gómez. Versatile linkage: a family of space-conserving strategies for agglomerative hierarchical clustering. *Journal of Classification*, 37(3):584–597, 2020.

Andrei Gabrielov. Multiplicities of Pfaffian intersections, and the łojasiewicz inequality. *Selecta Mathematica*, 1:113–127, 1995.

Andrei Gabrielov and Nicolai Vorobjov. Complexity of cylindrical decompositions of sub-pfaffian sets. *Journal of Pure and Applied Algebra*, 164(1-2):179–197, 2001.

Paul Goldberg and Mark Jerrum. Bounding the Vapnik-Chervonenkis dimension of concept classes parameterized by real numbers. In *Proceedings of the sixth annual conference on Computational learning theory*, pp. 361–369, 1993.

Rishi Gupta and Tim Roughgarden. A PAC approach to application-specific algorithm selection. In *Proceedings of the 2016 ACM Conference on Innovations in Theoretical Computer Science*, pp. 123–134, 2016.

Pentti Haukkanen and Timo Tossavainen. A generalization of Descartes' rule of signs and fundamental theorem of algebra. *Applied Mathematics and Computation*, 218(4):1203–1207, 2011.

Piotr Indyk, Ali Vakilian, and Yang Yuan. Learning-based low-rank approximations. *Advances in Neural Information Processing Systems*, 32, 2019.

Piotr Indyk, Tal Wagner, and David Woodruff. Few-shot data-driven algorithms for low rank approximation. *Advances in Neural Information Processing Systems*, 34:10678–10690, 2021.

Piotr Indyk, Frederik Mallmann-Trenn, Slobodan Mitrovic, and Ronitt Rubinfeld. Online page migration with ml advice. In *International Conference on Artificial Intelligence and Statistics*, pp. 1655–1670. PMLR, 2022.

Gareth James, Daniela Witten, Trevor Hastie, Robert Tibshirani, et al. *An introduction to statistical learning*, volume 112. Springer, 2013.

Graham JO Jameson. Counting zeros of generalised polynomials: Descartes' rule of signs and Laguerre's extensions. *The Mathematical Gazette*, 90(518):223–234, 2006.

Marek Karpinski and Angus Macintyre. Polynomial bounds for VC dimension of sigmoidal and general Pfaffian neural networks. *Journal of Computer and System Sciences*, 54(1):169–176, 1997.

Mikhail Khodak, Maria-Florina Balcan, Ameet Talwalkar, and Sergei Vassilvitskii. Learning predictions for algorithms with predictions. *Advances in Neural Information Processing Systems*, 35:3542–3555, 2022.

Askold G Khovanski. *Fewnomials*, volume 88. American Mathematical Soc., 1991.

Thomas Lavastida, Benjamin Moseley, R Ravi, and Chenyang Xu. Learnable and instance-robust predictions for online matching, flows and load balancing. *arXiv preprint arXiv:2011.11743*, 2020.

Yi Li, Honghao Lin, Simin Liu, Ali Vakilian, and David Woodruff. Learning the positions in countsketch. In *The Eleventh International Conference on Learning Representations*, 2023.

Gordon S Linoff and Michael JA Berry. *Data mining techniques: for marketing, sales, and customer relationship management*. John Wiley & Sons, 2011.

Stuart Lloyd. Least squares quantization in PCM. *IEEE transactions on information theory*, 28(2):129–137, 1982.

Ilay Luz, Meirav Galun, Haggai Maron, Ronen Basri, and Irad Yavneh. Learning algebraic multigrid using graph neural networks, 2020.

Thodoris Lykouris and Sergei Vassilvitskii. Competitive caching with machine learned advice. *Journal of the ACM (JACM)*, 68(4):1–25, 2021.

John Willard Milnor and David W Weaver. *Topology from the differentiable viewpoint*, volume 21. Princeton university press, 1997.

Michael Mitzenmacher and Sergei Vassilvitskii. Algorithms with predictions. *Communications of the ACM*, 65(7):33–35, 2022.

Mehryar Mohri, Afshin Rostamizadeh, and Ameet Talwalkar. *Foundations of machine learning*. MIT press, 2018.

Kevin P Murphy. *Machine learning: a probabilistic perspective*. MIT press, 2012.

Fionn Murtagh and Pedro Contreras. Algorithms for hierarchical clustering: an overview. *Wiley Interdisciplinary Reviews: Data Mining and Knowledge Discovery*, 2(1):86–97, 2012.

Sanjay Kumar Palei and Samir Kumar Das. Logistic regression model for prediction of roof fall risks in bord and pillar workings in coal mines: An approach. *Safety science*, 47(1):88–96, 2009.

David Pollard. *Convergence of stochastic processes*. Springer Science & Business Media, 2012.

Saharon Rosset. Following curved regularized optimization solution paths. *Advances in Neural Information Processing Systems*, 17, 2004.

Mehreen Saeed, Onaiza Maqbool, Haroon Atique Babri, Syed Zahoor Hassan, and S Mansoor Sarwar. Software clustering techniques and the use of combined algorithm. In *Seventh European Conference onSoftware Maintenance and Reengineering, 2003. Proceedings.*, pp. 301–306. IEEE, 2003.

Lou van den Dries. A generalization of the Tarski-Seidenberg theorem, and some nondefinability results. *Bulletin of the American Mathematical Society*, 15(2):189–193, 1986.

Vladimir Vapnik and Alexey Chervonenkis. Theory of pattern recognition, 1974.

Martin J Wainwright. *High-dimensional statistics: A non-asymptotic viewpoint*, volume 48. Cambridge university press, 2019.

Hugh E Warren. Lower bounds for approximation by nonlinear manifolds. *Transactions of the American Mathematical Society*, 133(1):167–178, 1968.

Alexander Wei and Fred Zhang. Optimal robustness-consistency trade-offs for learning-augmented online algorithms. *Advances in Neural Information Processing Systems*, 33:8042–8053, 2020.

James R White, Saket Navlakha, Niranjan Nagarajan, Mohammad-Reza Ghodsi, Carl Kingsford, and Mihai Pop. Alignment and clustering of phylogenetic markers-implications for microbial diversity studies. *BMC bioinformatics*, 11:1–10, 2010.

Rui Xu and Donald Wunsch. Survey of clustering algorithms. *IEEE Transactions on neural networks*, 16 (3):645–678, 2005.

Richard Zemel and Miguel Carreira-Perpiñán. Proximity graphs for clustering and manifold learning. *Advances in neural information processing systems*, 17, 2004.

Tong Zhang. Some sharp performance bounds for least squares regression with L1 regularization. *Annals of Statistics*, 2009.

Xiaojin Zhu. Semi-supervised learning with graphs. *Doctoral thesis, Carnegie Mellon University*, 2005.

Xiaojin Zhu and Zoubin Ghahramani. Learning from labeled and unlabeled data with label propagation. *ProQuest number: information to all users*, 2002.

Xiaojin Zhu and Andrew B Goldberg. Introduction to semi-supervised learning. *Synthesis lectures on artificial intelligence and machine learning*, 3(1):1–130, 2009.

Xiaojin Zhu, Zoubin Ghahramani, and John D Lafferty. Semi-supervised learning using Gaussian fields and harmonic functions. In *Proceedings of the 20th International conference on Machine learning (ICML-03)*, pp. 912–919, 2003.

# Appendix

## A Preliminaries

In this section, we first recall some additional classical notions and results on learning theory, which is also helpful in our analysis.

### A.1 Classical generalization results

For completeness, along with the definition of pseudo-dimension (Definition 1), we now give a formal definition of the VC-dimension, which is a counterpart of pseudo-dimension when the function class is binary-valued.

**Definition 11** (Shattering and VC-dimension)**.** *Let $\mathcal{U}$ is a class of binary-valued functions that take input from $\mathcal{X}$. Let $S = \{\boldsymbol{x}_1, \ldots, \boldsymbol{x}_m\} \subset \mathcal{X}$ be the set of $m$ input instances, we say that $S$ is shattered by $\mathcal{U}$ if*

$$|\{(u(\boldsymbol{x}_1), \ldots, u(\boldsymbol{x}_m) \mid u \in \mathcal{U}\}| = 2^m.$$

*The VC-dimension of $\mathcal{U}$, denoted* $\mathrm{VCdim}(\mathcal{U})$*, is the largest size of the set $S$ that can be shattered by $\mathcal{U}$.*

Rademacher complexity Bartlett & Mendelson (2002) is another classical learning-theoretic complexity measure for obtaining data-dependent learning guarantees.

**Definition 12** (Rademacher complexity, Bartlett & Mendelson (2002); Wainwright (2019))**.** *Let $\mathcal{U}$ be a real-valued function class which takes input from domain $\mathcal{U}$. Let $S = \{\boldsymbol{x}_1, \ldots, \boldsymbol{x}_m\} \sim \mathcal{D}$ be a set of $m$ input instances drawn from some problem distribution $\mathcal{D}$ over $\mathcal{X}$. Then the empirical Rademacher complexity $\mathscr{R}_S(\mathcal{U})$ of $\mathcal{U}$ with respect to $\mathcal{U}$ is defined as*

$$\hat{\mathscr{R}}_S(\mathcal{U}) = \mathbb{E}_{\boldsymbol{\sigma}}\left[\sup_{u \in \mathcal{U}} \left| \frac{1}{m} \sum_{i=1}^{m} \sigma_i f(\boldsymbol{x}_i) \right| \right].$$

*The Rademacher complexity of $\mathcal{U}$ for $n$ samples is then defined as*

$$\mathscr{R}_m(\mathcal{U}) = \mathbb{E}_{S \sim \mathcal{D}^m}[\hat{\mathscr{R}}_S(\mathcal{U})] = \mathbb{E}_{S \sim \mathcal{D}^m}\mathbb{E}_{\boldsymbol{\sigma}}\left[\sup_{u \in \mathcal{U}} \left| \frac{1}{m} \sum_{i=1}^{m} \sigma_i u(\boldsymbol{x}_i) \right| \right].$$

### A.2 Uniform convergence and PAC-learnability

We now remind classical notions in learning theory, which formalizes the learnability of a function class.

**Definition 13** (Uniform convergence)**.** *Let $\mathcal{U}$ is a real-valued function class which takes input from $\mathcal{X}$, and $\mathcal{D}$ is a distribution over $\mathcal{X}$. If for any $\epsilon > 0$, and any $\delta \in [0, 1]$, there exists $N(\epsilon, \delta)$ s.t. w.p. at least $1 - \delta$ over the draw of $m \geq N(\epsilon, \delta)$ samples $\boldsymbol{x}_1, \ldots, \boldsymbol{x}_m \sim \mathcal{D}$, we have*

$$\Delta_m = \sup_{u \in \mathcal{U}} \left| \frac{1}{m} \sum_{i=1}^{m} f(\boldsymbol{x}_i) - \mathbb{E}_{\boldsymbol{x} \sim \mathcal{D}}[f(X)] \right| \leq \epsilon,$$

*then we say that (the empirical process of) $\mathcal{F}$ uniformly converges. The quantity $\Delta_m$ is called the empirical process of function class $\mathcal{F}$.*

The following classical result demonstrates the connection between uniform convergence and learnability with an ERM learner.

**Theorem A.1** (Mohri et al. (2018))**.** *If $\mathcal{U}$ has a uniform convergence guarantee with $N(\epsilon, \delta)$ samples then it is PAC learnable with ERM and $N(\epsilon/2, \delta)$ samples.*

*Proof.* For $S = \{\boldsymbol{x}_1, \ldots, \boldsymbol{x}_m\} \subset \mathcal{X}$, let $L_S(u) = \frac{1}{m}\sum_{i=1}^m u(\boldsymbol{x}_i)$, and $L_{\mathcal{D}}(u) = \mathbb{E}_{\boldsymbol{x}\sim\mathcal{D}}[u(\boldsymbol{x})]$ for $u \in \mathcal{U}$. Since $\mathcal{U}$ is uniform convergence with $N(\epsilon, \delta)$ samples, w.p. at least $1-\delta$ for all $u \in \mathcal{U}$, we have $|L_S(u) - L_{\mathcal{D}}(u)|$ where $S$ drawn from $\mathcal{D}^m$, $m \geq N(\epsilon, \delta)$. Let $u_{\text{ERM}} \in \arg\min_{u\in\mathcal{U}} L_S(u)$ be the hypothesis outputted by the ERM learner, and $u^* \in \arg\min_{u\in\mathcal{U}} L_{\mathcal{D}}(u)$ be the best hypothesis. We have

$$L_{\mathcal{D}}(u_{ERM}) \leq L_S(u_{ERM}) + \frac{\epsilon}{2} \leq L_S(u^*) + \frac{\epsilon}{2} \leq L_{\mathcal{D}}(u^*) + \epsilon,$$

which concludes the proof. □

# B Omitted proofs from Section 4

In this section, we will present basic properties of Pfaffian chain/functions and a proof for Theorem 4.2.

## B.1 Some facts about Pfaffian functions with elementary operators

In this section, we formalize some basic properties of Pfaffian functions. Essentially, the following results say that if adding/subtracting/multiplying/dividing two Pfaffian functions from the same Pfaffian chain, we end up with a function that is also the Pfaffian function from that Pfaffian chain. Moreover, even if the two Pfaffian functions are not from the same Pfaffian chain, we can still construct a new Pfaffian chain that contains both the functions and the newly computed function as well (by simply combining the two chains).

**Fact 1** (Addition/Subtraction)**.** *Let $g$, $h$ be Pfaffian functions from the Pfaffian chain $\mathcal{C}(\boldsymbol{a}, \eta_1, \ldots, \eta_q)$ ($a \in \mathbb{R}^d$). Then we have $g(\boldsymbol{a}) \pm h(\boldsymbol{a})$ are also Pfaffian functions from the chain $\mathcal{C}$.*

*Proof.* For any $a_i$, we have $\frac{\partial}{\partial a_i}(g \pm h)(\boldsymbol{a}) = \frac{\partial}{\partial a_i} g(\boldsymbol{a}) \pm \frac{\partial}{\partial a_i} h(\boldsymbol{a})$. Since $\frac{\partial g(\boldsymbol{a})}{\partial a_i}$ and $\frac{\partial h(\boldsymbol{a})}{\partial a_i}$ are polynomial of $\boldsymbol{a}$ and $\eta_i$, $\frac{\partial}{\partial a_i}(g \pm h)(\boldsymbol{a})$ are also polynomial of $\boldsymbol{a}$ and $\eta_i$, which concludes the proof. □

**Fact 2** (Multiplication)**.** *Let $g$, $h$ be Pfaffian functions from the Pfaffian chain $\mathcal{C}(\boldsymbol{a}, \eta_1, \ldots, \eta_q)$ ($\boldsymbol{a} \in \mathbb{R}^d$) of length $q$ and Pfaffain degree $M$. Then we have $g(\boldsymbol{a})h(\boldsymbol{a})$ is a Pfaffian function from the chain $\mathcal{C}'(\boldsymbol{a}, \eta_1, \ldots, \eta_q, g, h)$.*

*Proof.* For any $a_i$, we have $\frac{\partial}{\partial a_i}(g(\boldsymbol{a})h(\boldsymbol{a})) = g\frac{\partial h(\boldsymbol{a})}{\partial a_i} + h\frac{\partial g(\boldsymbol{a})}{\partial a_i}$, which is a polynomial of $\boldsymbol{a}, \eta_1, \ldots, \eta_q, g, h$. □

**Fact 3** (Division)**.** *Let $g, h$ be Pfaffain functions from the Pfaffian chain $\mathcal{C}(\boldsymbol{a}, \eta_q, \ldots, \eta_q)$ ($\boldsymbol{a} \in \mathbb{R}^d$) of length $q$ and Pfaffian degree $M$. Assume that $h(\boldsymbol{a}) \neq 0$, then we have $\frac{g(\boldsymbol{a})}{h(\boldsymbol{a})}$ is a Pfaffian function from the Pfaffian chain $\mathcal{C}'(\boldsymbol{a}, \eta_1, \ldots, \eta_q, , \frac{1}{h}, \frac{g}{h})$.*

*Proof.* For any $a_i$, we have $\frac{\partial}{\partial a_i}\left(\frac{g(\boldsymbol{a})}{h(\boldsymbol{a})}\right) = \frac{\partial g(\boldsymbol{a})}{\partial a_i}\frac{1}{h(\boldsymbol{a})} - \frac{g(\boldsymbol{a})}{h(\boldsymbol{a})}\frac{\partial h(\boldsymbol{a})^2}{\partial a_i}$ is a polynomial of $\boldsymbol{a}, \eta_1, \ldots, \eta_q, \frac{1}{h}, \frac{g}{h}$. □

**Fact 4** (Composition)**.** *Let $h$ be a Pfaffian function from the Pfaffian chain $\mathcal{C}(\boldsymbol{a}, \eta_1, \ldots, \eta_q)$ ($\boldsymbol{a} \in \mathbb{R}^d$), and $g$ be Pfaffian function from the Pfaffain chain $\mathcal{C}'(b, \eta_1', \ldots, \eta_{q'}')$ ($b \in \mathbb{R}$). Then $g(h(\boldsymbol{a}))$ is a Pfaffian function from the Pfaffian chain $\mathcal{C}''(\boldsymbol{a}, \eta_1, \ldots, \eta_q, h, \eta_1'(h), \ldots, \eta_{q'}'(h))$.*

*Proof.* For any $a_i$, we have $\frac{\partial g(h(\boldsymbol{a}))}{\partial a_i} = \frac{\partial h(\boldsymbol{a})}{\partial a_i}\frac{\partial g(h(\boldsymbol{a}))}{\partial h(\boldsymbol{a})}$. Note that $\frac{\partial g(h(\boldsymbol{a}))}{\partial h(\boldsymbol{a})} = P(h(\boldsymbol{a}), \eta_1'(h(a)), \ldots, \eta_{q'}'(h(\boldsymbol{a}))$, where $P$ is some polynomial. Therefore, $g(h(\boldsymbol{a}))$ is a Pfaffian function from the Pfaffian chain $\mathcal{C}''(\boldsymbol{a}, \eta_1, \ldots, \eta_q, h, \eta_1'(h), \ldots, \eta_{q'}'(h))$. □

## B.2 Background for proof of Theorem 4.2

In this section, we will present the proof of the Pfaffian GJ algorithm guarantee (Theorem 4.2). To begin with, we first recall some preliminary results about a standard technique for establishing pseudo-dimension upper-bound by analyzing the solution set connected components bound.

### B.2.1 Preliminaries on the connection between pseudo-dimension and solution set connected components bound

We first introduce the notion of a *regular value*. Roughly speaking, given a smooth map $F : \mathbb{R}^d \to \mathbb{R}^r$, where $r \leq d$, a regular value $\epsilon \in \mathbb{R}^r$ is the point in the image space such that the solution of $F(a) = \epsilon$ is well-behaved.

**Definition 14** (Regular value, Milnor & Weaver (1997))**.** *Consider $C^1$ functions $f_1, \ldots, f_r : \mathbb{R}^d \to \mathbb{R}$ where $r \leq d$, $\mathcal{A} \subseteq \mathbb{R}^d$, and the (smooth) mapping $F : \mathcal{A} \to \mathbb{R}^r$ given by $F(\boldsymbol{a}) = (f_1(\boldsymbol{a}), \ldots, f_r(\boldsymbol{a}))$. Then $(\epsilon_1, \ldots, \epsilon_r) \in \mathbb{R}^r$ is a regular value of $F$ if either: (1) $F^{-1}((\epsilon_1, \ldots, \epsilon_r)) = \emptyset$, or (2) $F^{-1}((\epsilon_1, \ldots, \epsilon_r))$ is a $(d-r)$-dimensional sub-manifold of $\mathbb{R}^d$.*

It is widely known that by Sard's Lemma Milnor & Weaver (1997), the set of non-regular values of the smooth map $F$ has Lebesgue measure 0. Based on this definition, we now present the definition of the *solution set connected components bound.*

**Definition 15** (Solution set connected components bound, Karpinski & Macintyre (1997))**.** *Consider functions $\tau_1, \ldots, \tau_K : \mathcal{X} \times \mathcal{A} \to \mathbb{R}$, where $\mathcal{A} \subseteq \mathbb{R}^d$. Given $\boldsymbol{x}_1, \ldots, \boldsymbol{x}_N$, assume that $\tau_i(\boldsymbol{x}_j, \cdot) : \mathbb{R}^d \to \mathbb{R}$ is a $C^1$ function for $i \in [K]$ and $j \in [N]$. For any $F : \mathbb{R}^d \to \mathbb{R}^r$, where $F(\boldsymbol{a}) = (\Theta_1(\boldsymbol{a}), \ldots, \Theta_r(\boldsymbol{a}))$ with $\Theta_i$ chosen from the $NK$ functions $\tau_i(\boldsymbol{x}_j)$, if the number of connected components of $F^{-1}(\epsilon)$, where $\epsilon$ is a regular value, is upper bounded by $B$ independently on $x_i$, $r$, and $\epsilon$, then we say that $B$ is the solution set connected components bound.*

The solution set connected components bound offers an alternative way of analyzing VC-dimension (or pseudo-dimension) of related parameterized function classes, which is formalized in the following lemma Karpinski & Macintyre (1997). We include a high-level proof sketch for comprehensiveness.

**Lemma B.1** (Karpinski & Macintyre (1997))**.** *Consider the binary-valued function $\Phi(\boldsymbol{x}, \boldsymbol{a})$, for $\boldsymbol{x} \in \mathcal{X}$ and $\boldsymbol{a} \in \mathbb{R}^d$ constructed using the boolean operators AND and OR, and boolean predicates in one of the two forms "$\tau(\boldsymbol{x}, \boldsymbol{a}) > 0$" or "$\tau(\boldsymbol{x}, \boldsymbol{a}) = 0$". Assume that the function $\tau(\boldsymbol{x}, \boldsymbol{a})$ can be one of at most $K$ forms $(\tau_1, \ldots, \tau_K)$, where $\tau_i(\boldsymbol{x}, \cdot)$ $(i \in [K])$ is a $C^\infty$ function of $\boldsymbol{a}$ for any fixed $x$. Let $\mathscr{C}_\Phi = \{\Phi_{\boldsymbol{a}} : \mathcal{X} \to \{0, 1\} \mid \boldsymbol{x} \in \mathbb{R}^d\}$ where $\Phi_{\boldsymbol{a}} = \Phi(\cdot, \boldsymbol{a})$. Then*

$$\mathrm{VCdim}(\mathscr{C}_\Phi) \leq 2 \log_2 B + (16 + 2 \log K) d,$$

*where $B$ is the solution set connected components bound.*

*Proof Sketch.* The key idea involved in proving the following lemma is a combinatorial argument due to Warren (Theorem 1, Warren (1968)) which bounds the number of connected components induced by a collection of boundary functions by $\sum_{j=0}^{d} b_j$, where $b_j$ is the number of connected components induced by intersections of any $j$ functions. This can be combined with the solution set connected components bound $B$, to get a bound $\sum_{j=0}^{d} 2^j \binom{NK}{j} B \leq B \left(\frac{2NKe}{d}\right)^d$ on the total number of connected components. The result follows from noting $2^N \leq B \left(\frac{2NKe}{d}\right)^d$ if the $N$ instances $\boldsymbol{x}_1, \ldots, \boldsymbol{x}_N$ are to be shattered. □

We now recall a result which is especially useful for bounding the solution set connected components bound $B$ for equations related to Pfaffian functions.

**Lemma B.2** (Khovanski (1991))**.** *Let $\mathcal{C}$ be a Pfaffian chain of length $q$ and Pfaffian degree $M$, consists of functions $f_1, \ldots, f_q$ in $a \in \mathbb{R}^d$. Consider a non-singular system of equations $\Theta_1(\boldsymbol{a}) = \cdots = \Theta_r(\boldsymbol{a}) = 0$ where $r \leq d$, in which $\Theta_i(\boldsymbol{a})$ $(i \in [r])$ is a polynomial of degree at most $\Delta$ in the variable $\boldsymbol{a}$ and in the Pfaffian functions $f_1, \ldots, f_q$. Then the manifold of dimension $k = d - r$ determined by this system has at most $2^{q(q-1)} \Delta^m S^{d-r} [(r - d + 1)S - (r - d)]^q$ connected components, where $S = r(\Delta - 1) + dM + 1$.*

The following corollary is the direct consequence of Lemma B.2.

**Corollary B.3.** *Consider the setting as in Lemma B.1. Assume that for any fixed $\boldsymbol{x}$, $\tau_i(\boldsymbol{x}, \cdot)$ ($i \in [K]$) is a Pfaffian function from a Pfaffian chain $\mathcal{C}$ with length $q$ and Pfaffain degree $M$. Then*

$$B \leq 2^{dq(dq-1)/2} \Delta^d [(d^2(\Delta + M)]^{dq}.$$

The following lemma gives a connection between the number of sign patterns and number of connected components.

**Lemma B.4** (Section 1.8, Warren (1968))**.** *Given $N$ real-valued functions $h_1, \ldots, h_N$, the number of distinct sign patterns $\left|\{(sign(h_1(\boldsymbol{a})), \ldots, sign(h_N(\boldsymbol{a}))) \mid \boldsymbol{a} \in \mathbb{R}^d\}\right|$ is upper-bounded by the number of connected components $\mathbb{R}^d - \cup_{i \in [N]} \{\boldsymbol{a} \in \mathbb{R}^d \mid g_i(\boldsymbol{a}) = 0\}$.*

The following result is about the relation between the connected components and the solution set connected components.

**Lemma B.5** (Lemma 7.9, Anthony & Bartlett (2009))**.** *Let $\{f_1, \ldots, f_N\}$ be a set of differentiable functions that map from $\mathbb{R}^d \to \mathbb{R}$, with regular zero-set intersections. For each $i$, define $Z_i$ the zero-set of $f_i$: $Z_i = \{\boldsymbol{a} \in \mathbb{R}^d : f_i(\boldsymbol{a}) = 0\}$. Then*

$$CC\left(\mathbb{R}^d - \bigcup_{i \in [N]} Z_i\right) \leq \sum_{S \subseteq [N]} CC\left(\bigcap_{i \in S} Z_i\right).$$

*Combining with Definition 15, the RHS becomes $B \sum_{i=0}^{d} \binom{N}{i} \leq B \left(\frac{eN}{d}\right)^d$ for $N \geq d$.*

### B.2.2 Pfaffian formulae

We now introduce the building block of the Pfaffian GJ framework, named *Pfaffian formula*. Roughly speaking, a Pfaffian formula is a boolean formula that incorporates Pfaffian functions.

**Definition 16** (Pfaffian formulae)**.** *A Pfaffian formulae $f : \mathbb{R}^d \to \{True, False\}$ is a disjunctive normal form (DNF) formula over boolean predicates of the form $g(\boldsymbol{a}, \eta_1, \ldots, \eta_q) \geq 0$, where $g$ is a Pfaffian function of a Pfaffian chain $\mathcal{C}(\boldsymbol{a}, \eta_1, \ldots, \eta_q)$.*

The following lemma essentially claims that for any function class, if its computation can be described by a Pfaffian formula and the corresponding Pfaffian chain exhibits bounded complexities, then the function class also possesses bounded pseudo-dimension.

**Lemma B.6.** *Suppose that each algorithm $L \in \mathcal{L}$ is parameterized by $\boldsymbol{a} \in \mathbb{R}^d$. Suppose that for every $\boldsymbol{x} \in \mathcal{X}$ and $r \in \mathbb{R}$, there is a Pfaffian formula $f_{\boldsymbol{x},r}$ of a Pfaffian chain $\mathcal{C}$ with length $q$ and Pfaffian degree $M$, that given $L \in \mathcal{L}$, check whether $L(\boldsymbol{x}) > r$. Suppose that $f_{\boldsymbol{x},r}$ has at most $K$ distinct Pfaffian functions in its predicates, each of degree at most $\Delta$. Then,*

$$\text{Pdim}(\mathcal{L}) \leq d^2 q^2 + 2dq \log(\Delta + M) + 4dq \log d + 2d \log \Delta K + 16d.$$

*Proof.* This lemma is a direct consequence of Lemma B.1, and Corollary B.3. □

## C Additional details and omitted proofs for Section 5

In this section, we will present an additional comparison between our proposed framework and the general piecewise structure framework by Balcan et al. (2021a), as well as a detailed proof for Lemma 5.3.

### C.1 A detailed comparison between the piece-wise structure by Balcan et al. (2021a) and our refined Pfaffian piece-wise structure

In this section, we will do a detailed comparison between our refined Pfaffian piece-wise structure, and the piece-wise structure proposed by Balcan et al. (2021a). First, we derive concrete pseudo-dimension bounds implied by Balcan et al. (2021a) when the refined Pfaffian piece-wise structure is present. We note that this implication is not immediate and needs a careful argument to bound the learning-theoretic complexity of Pfaffian piece and boundary functions which appear in their bounds.

**Theorem C.1.** *Consider the utility function class $\mathcal{U} = \{u_{\boldsymbol{a}} : \mathcal{X} \to \mathbb{R} \mid \boldsymbol{a} \in \mathcal{A}\}$, where $\mathcal{A} \subseteq \mathbb{R}^d$. Suppose that $\mathcal{U}^*$ admits $(k_{\mathcal{F}}, k_{\mathcal{G}}, q, M, \Delta, d)$-Pfaffian piece-wise structure. Then using Theorem 5.1 by Balcan et al. Balcan et al. (2021a), we have*

$$\mathrm{Pdim}(\mathcal{U}) = \mathcal{O}((d^2q^2 + dq\log(\Delta + M) + dq\log d + d) \cdot \log[(d^2q^2 + dq\log(\Delta + M) + dq\log d + d)k_{\mathcal{G}}]).$$

*Proof.* Consider an utility function class $\mathcal{U} = \{u_{\boldsymbol{a}} : \mathcal{X} \to \mathbb{R} \mid \boldsymbol{a} \in \mathcal{A}\}$, where $\mathcal{A} \subseteq \mathbb{R}^d$, we assume that $\mathcal{U}^*$ admits $(k_{\mathcal{F}}, k_{\mathcal{G}}, q, M, \Delta, d)$-Pfaffian piece-wise structure. Then, $\mathcal{U}^*$ also admits $(\mathcal{F}, \mathcal{G}, k_{\mathcal{G}})$ piece-wise structure following Definition 7. Here, $\mathcal{H}$ is the set of Pfaffian functions of degree $\Delta$ from a Pfaffian chain of length $q$ and Pfaffian degree $M$, and $\mathcal{G}$ is the set of threshold functions which are also Pfaffian functions of degree $\Delta$ from the same Pfaffian chain of length $q$ and Pfaffian degree $M$.

The first challenge in using the framework of Balcan et al. is that it only reduces the problem of bounding the learning-theoretic complexity of the piecewise-structured utility function to that of bounding the complexity of the piece and boundary functions involved, which is non-trivial in the case of Pfaffian functions. That is, we still need to bound $\mathrm{Pdim}(\mathcal{F}^*)$ and $\mathrm{VCdim}(\mathcal{G}^*)$, where $\mathcal{F}^*$ and $\mathcal{G}^*$ are dual function classes of $\mathcal{F}$ and $\mathcal{G}$, respectively. To bound $\mathrm{VCdim}(\mathcal{G}^*)$, we first consider the set of $N$ input instances $S = \{g_1, \ldots, g_N\} \subset \mathcal{G}$, and bound the number of distinct sign patterns,

$$\Gamma_S(N) = |\{(g^*_{\boldsymbol{a}}(g_1), \ldots, g^*_{\boldsymbol{a}}(g_N)) \mid \boldsymbol{a} \in \mathcal{A}\}| = |\{(g_1(\boldsymbol{a}), \ldots, g_N(\boldsymbol{a})) \mid \boldsymbol{a} \in \mathcal{A}\}|.$$

From Lemma B.5 and B.4, and B.2, we can bound $\Gamma_S(N)$ as

$$\Gamma_S(N) = \mathcal{O}(2^{dq(dq-1)/2}\Delta^d[(d^2(\Delta + M)])^{dq}\left(\frac{eN}{d}\right)^d.$$

Solving the inequality $2^N = \mathcal{O}(2^{dq(dq-1)/2}\Delta^d[(d^2(\Delta + M)]^{dq}\left(\frac{ek}{d}\right)^d)$, we have $\mathrm{VCdim}(\mathcal{G}^*) \leq \frac{dq(dq-1)}{2} + d\log\Delta + dq\log(d^2(\Delta + M))$.

We now bound $\mathrm{Pdim}(\mathcal{F}^*)$. By definition, we have $\mathcal{F}^* = \{f^*_{\boldsymbol{a}} : \mathcal{F} \to \mathbb{R} \mid \boldsymbol{a} \in \mathcal{A}\}$. Again, to bound $\mathrm{Pdim}(\mathcal{F}^*)$, we first consider the set $S = \{f_1, \ldots, f_N\} \subset \mathcal{F}$ and a set of thresholds $T = \{r_1, \ldots, r_N\}$, and we want to bound the number of distinct sign patterns

$$\begin{aligned}\Gamma_{S,T}(N) &= |\{(\mathrm{sign}(f^*_{\boldsymbol{a}}(f_1) - r_1), \ldots, \mathrm{sign}(f^*_{\boldsymbol{a}}(f_N) - r_N)) \mid \boldsymbol{a} \in \mathcal{A}\}| \\ &= |\{(\mathrm{sign}(f_1(\boldsymbol{a}) - r_1), \ldots, \mathrm{sign}(f_N(\boldsymbol{a}) - r_N)) \mid \boldsymbol{a} \in \mathcal{A}\}|.\end{aligned}$$

Using similar argument as for $\mathcal{G}^*$, we have $\mathrm{Pdim}(\mathcal{F}^*) = \mathcal{O}(d^2q^2 + dq\log(\Delta + M) + dq\log d + d)$. Combining with Theorem 3.3 by Balcan et al. Balcan et al. (2021a), we conclude that

$$\mathrm{Pdim}(\mathcal{U}) = \mathcal{O}((d^2q^2 + dq\log(\Delta + M) + dq\log d + d)\log[(d^2q^2 + dq\log(\Delta + M) + dq\log d + d)k_{\mathcal{G}}]).$$

□

**Remark 7.** *Compared to our bounds in Theorem 5.2, Theorem C.1 (implied by Balcan et al. (2021a)) has two notable differences. First, our bound is sharper by a logarithmic factor $\mathcal{O}(\log(d^2q^2 + dq\log(\Delta + M) + dq\log d + d))$, which is a consequence of using a sharper form of the Sauer-Shelah lemma. Second, we have a dependence on a logarithmic term $k_{\mathcal{F}}$ which is asymptotically dominated by the other terms, and corresponds to better multiplicative constants than Theorem C.1.*

### C.2 Omitted proofs for Section 5.3.1

**Lemma 5.3 (restated).** *Consider a function class $\mathcal{V} = \{v_{\boldsymbol{a}} : \mathcal{X} \to \mathbb{R} \mid \boldsymbol{a} \in \mathcal{A}\}$ where $\mathcal{A} \subseteq \mathbb{R}^d$. Assume there is a partition $\mathcal{P} = \{\mathcal{A}_1, \ldots, \mathcal{A}_n\}$ of the parameter space $\mathcal{A}$ such that for any problem instance $\boldsymbol{x} \in \mathcal{X}$, the dual utility function $u_x^*$ is a Pfaffian function of degree at most $\Delta$ in region $\mathcal{A}_i$ from a Pfaffian chain $\mathcal{C}_{\mathcal{A}_i}$ of length at most $q$ and Pfaffian degree $M$. Then the pseudo-dimension of $\mathcal{V}$ is upper-bounded as follows*

$$\mathrm{Pdim}(\mathcal{V}) = O(q^2d^2 + qd\log(\Delta + M) + qd\log d + \log n).$$

*Proof.* Consider $N$ problem instances $\boldsymbol{x}_1, \ldots, \boldsymbol{x}_N$ with $N$ corresponding thresholds $\tau_1, \ldots, \tau_N$, we first want to bound the number of distinct sign patterns $\Pi_{\mathcal{V}}(N) = |\{(\mathrm{sign}(v_{\boldsymbol{a}}(\boldsymbol{x}_1) - \tau_1), \ldots, \mathrm{sign}(v_{\boldsymbol{a}}(\boldsymbol{x}_N) - \tau_N)) \mid \boldsymbol{a} \in \mathcal{A}\}|$.

Denote $\Pi_{\mathcal{V}}^{\mathcal{A}_i}(N) = |\{(\mathrm{sign}(v_{\boldsymbol{a}}(\boldsymbol{x}_1) - \tau_1), \ldots, \mathrm{sign}(v_{\boldsymbol{a}}(\boldsymbol{x}_N) - \tau_N)) \mid \boldsymbol{a} \in \mathcal{A}_i\}|$, we have $\Pi_{\mathcal{V}}(N) \leq \sum_{i=1}^n \Pi_{\mathcal{V}}^{\mathcal{A}_i}(N)$. For any $i \in [n]$, from the assumptions, Lemma 5.2 and using Sauer's Lemma, we have

$$\Pi_{\mathcal{V}}(N) \leq \left(\frac{eN}{S}\right)^S,$$

where $S = C(q^2d^2 + qd\log(\Delta + M) + qd\log d)$ for some constant $C$. Therefore $\Pi_{\mathcal{V}}(N) \leq n\left(\frac{eN}{S}\right)^S$. Solving the inequality $2^N \leq \Pi_{\mathcal{V}}(N)$, we conclude that $\mathrm{Pdim}(\mathcal{V}) = O(q^2d^2 + qd\log(\Delta + M) + qd\log d + \log n)$ as expected. □

## D Additional background and omitted proofs for Section 6

In this section, we will present the deferred proofs as well as additional for various applications in Section 6.

### D.1 Omitted proofs for Section 6.1

**Theorem 6.2.** *Let $\mathcal{H}_2$ be a class of functions*

$$\mathcal{H}_2 = \{u_2^{\alpha,\beta} \colon (S, \boldsymbol{\delta}) \mapsto u(A_2^{\alpha,\beta}(S, \boldsymbol{\delta})) \mid \alpha \in \mathbb{R} \cup \{-\infty, +\infty\}, \beta \in \Delta([L])\}$$

*mapping clustering instances $(S, \boldsymbol{\delta})$ to $[0, 1]$ by using merge functions from class $\mathcal{M}_2$ and an arbitrary merge function. Then $\mathrm{Pdim}(\mathcal{H}_2) = \mathcal{O}(n^4L^2)$.*

*Proof.* Fix the clustering instance $(S, \boldsymbol{\delta})$. Suppose $A, B \subseteq S$ and $A', B' \subseteq S$ are two candidate clusters at some merge step of the algorithm. Then $A, B$ is preferred for merging over $A', B'$ iff

$$\left(\frac{1}{|A||B|}\sum_{a\in A, b\in B}(\delta_\beta(a, b))^\alpha\right)^{1/\alpha} \leq \left(\frac{1}{|A'||B'|}\sum_{a\in A', b\in B'}(\delta_\beta(a, b))^\alpha\right)^{1/\alpha},$$

or equivalently,

$$\frac{1}{|A||B|}\sum_{a\in A, b\in B}(\delta_\beta(a, b))^\alpha \leq \frac{1}{|A'||B'|}\sum_{a\in A', b\in B'}(\delta_\beta(a, b))^\alpha.$$

For distinct choices of the point sets $A, B, A', B'$, we get at most $\binom{2^n}{2}^2 \leq 2^{4n}$ distinct boundary conditions across which the merge decision at any step of the algorithm may change.

We next show that the boundary functions constitute a Pfaffian system in $\alpha, \beta_1, \ldots, \beta_L$ and bound its complexity. For each pair of points $a, b \in S$, define $f_{a,b}(\alpha, \beta) := \frac{1}{\delta_\beta(a,b)}$, $g_{a,b}(\alpha, \beta) := \ln \delta_\beta(a, b)$ and $h_{a,b}(\alpha, \beta) := \delta_\beta(a, b)^\alpha$. Similar to the proof of Theorem 6.1, these functions form a Pfaffian chain $\mathcal{C}(\alpha, \beta, f_{a,b}, g_{a,b}, h_{a,b})$ for $a, b \in S$. We can see that $\mathcal{C}$ is of length $q = 3n^2$ and Pfaffian degree $M = 2$. The boundary conditions can all be written in terms of the functions $\{h_{a,b}\}_{a,b\in S}$, meaning $k_{\mathcal{G}} = n^8$ and degree $\Delta = 1$. Again, note that $k_{\mathcal{F}} = n+1$. Therefore, $\mathcal{H}_2^*$ admits $(n+1, n^8, 3n^2, 2, 1, L+1)$-Pfaffian piece-wise structure. Applying Theorem 5.2 now gives that $\mathrm{Pdim}(\mathcal{H}_2) = \mathcal{O}(n^4L^2 + n^2L\log L + L\log 2^{4n}) = \mathcal{O}(n^4L^2)$. □

**Theorem 6.3.** *Let $\mathcal{H}_3$ be a class of functions*

$$\mathcal{H}_3 = \{u_3^\alpha : (S, \boldsymbol{\delta}) \mapsto u(A_3^\alpha(S, \boldsymbol{\delta})) \mid \alpha_i \in \mathbb{R} \cup \{-\infty, \infty\} \setminus \{0\}\}$$

*mapping clustering instances $(S, \boldsymbol{\delta})$ to $[0, 1]$ by using merge functions from class $\mathcal{M}_3$. Then* $\mathrm{Pdim}(\mathcal{H}_3) = \mathcal{O}(n^4 L^2)$.

*Proof.* Fix the clustering instance $(S, \boldsymbol{\delta})$. Suppose $A, B \subseteq S$ and $A', B' \subseteq S$ are two candidate clusters at some merge step of the algorithm. Then $A, B$ is preferred for merging over $A', B'$ iff

$$\left(\frac{1}{|A||B|} \sum_{a \in A, b \in B} \Pi_{i \in [L]} (\delta_i(a, b))^{\alpha_i}\right)^{1/\sum_i \alpha_i} \leq \left(\frac{1}{|A'||B'|} \Pi_{i \in [L]} (\delta_i(a, b))^{\alpha_i}\right)^{1/\sum_i \alpha_i},$$

or equivalently,

$$\frac{1}{|A||B|} \sum_{a \in A, b \in B} \Pi_{i \in [L]} (\delta_i(a, b))^{\alpha_i} \leq \frac{1}{|A'||B'|} \sum_{a \in A', b \in B'} \Pi_{i \in [L]} (\delta_i(a, b))^{\alpha_i}.$$

For distinct choices of the point sets $A, B, A', B'$, we get at most $\binom{2^n}{2}^2 \leq 2^{4n}$ distinct boundary conditions across which the merge decision at any step of the algorithm may change.

We next show that the boundary functions constitute a Pfaffian system in $\alpha_1, \ldots, \alpha_L$ and bound its complexity. For each pair of points $a, b \in S$, define $h_{a,b}(\alpha_1, \ldots, \alpha_L) := \Pi_{i \in [L]} (\delta_i(a, b))^{\alpha_i}$. Note that $\frac{\partial h}{\partial \alpha_i} := \ln \delta_i(a, b) h_{a,b}(\alpha_1, \ldots, \alpha_L)$, and thus these functions form a Pfaffian chain of chain length $n^2$ and Pfaffian degree 1. The boundary conditions can be all written in terms of the functions $\{h_{a,b}\}_{a,b \in S}$, meaning that $k_{\mathcal{G}} = 2^{4n}$, and $\Delta = 1$. Again, note that $k_{\mathcal{F}} = n+1$. Therefore $\mathcal{H}_3^*$ admits $(n+1, 2^{4n}, n^2, 1, 1, L)$-Pfaffian piece-wise structure. Applying Theorem B.6 now gives that $\mathrm{Pdim}(\mathcal{H}_2) = \mathcal{O}(n^4 L^2)$. □

### D.2 Additional background and omitted proofs for Section 6.3

**Theorem D.1** (Rosset (2004))**.** *Given a problem instance $P = (X, y, X_{val}, y_{val}) \in \Pi_{m,p}$, for small enough $\epsilon$, if we use Algorithm 1 (2) to approximate the solution $\hat{\beta}_{(X,y)}(\lambda)$ of RLR under $\ell_1$ ($\ell_2$) constraint by $\beta^{(\epsilon)}_{(X,y)}(\lambda)$ then there is a uniform bound $O(\epsilon^2)$ on the error $\|\hat{\beta}_{(X,y)}(\lambda) - \beta^{(\epsilon)}_{(X,y)}(\lambda)\|_2$ for any $\lambda \in [\lambda_{\min}, \lambda_{\max}]$.*

*For any $\lambda \in [\lambda_t, \lambda_{t+1}]$, where $\lambda_k = \lambda_{\min} + k\epsilon$, the approximate solution $\beta^{(\epsilon)}(\lambda)$ is calculated by*

$$\beta^{(\epsilon)}_{(X,y)}(\lambda) = \beta^{(\epsilon)}_t - \left[\nabla^2 l\left(\beta^{(\epsilon)}_t, (X, y)\right)_{\mathcal{A}}\right]^{-1} \cdot \left[\nabla l\left(\beta^{(\epsilon)}_t, (X, y)\right)_{\mathcal{A}} + \lambda \operatorname{sgn}\left(\beta^{(\epsilon)}_t\right)_{\mathcal{A}}\right] = a_t \lambda + b_t,$$

*if we use Algorithm 1 for RLR under $\ell_1$ constraint, or*

$$\beta^{(\epsilon)}_{(X,y)}(\lambda) = \beta^{(\epsilon)}_t - \left[\nabla^2 l\left(\beta^{(\epsilon)}_t, (X, y)\right) + 2\lambda_{t+1} I\right]^{-1} \cdot \left[\nabla l\left(\beta^{(\epsilon)}_t, (X, y)\right) + 2\lambda \beta^{(\epsilon)}_t\right] = a'_t \lambda + b'_t,$$

*if we use Algorithm 2 for RLR under $\ell_2$ constraint.*

## E Additional background and omitted proofs for Section 7

We record here some fundamental results from the theory of Pfaffian functions (also known as Fewnomial theory) which will be needed in establishing our online learning results. The following result is a Pfaffian analogue of Bezout's theorem from algebraic geometry, useful in bounding the multiplicity of intersections of Pfaffian hypersurfaces.

**Theorem E.1** (Khovanski (1991); Gabrielov (1995))**.** *Consider a system of equations $g_1(\boldsymbol{x}) = \cdots = g_n(\boldsymbol{x}) = 0$ where $g_i(\boldsymbol{x}) = P_i(\boldsymbol{x}, f_1(\boldsymbol{x}), \ldots, f_q(\boldsymbol{x}))$ is a polynomial of degree at most $d_i$ in $\boldsymbol{x} \in \mathbb{R}^n$ and $f_1, \ldots, f_q$ are a sequence of functions that constitute a Pfaffian chain of length $q$ and Pfaffian degree at most $M$. Then the number of non-degenerate solutions of this system does not exceed*

$$2^{q(q-1)/2} d_1 \ldots d_n (\min\{q, n\} M + d_1 + \cdots + d_n - n + 1)^q.$$

**Algorithm 1** Approximate incremental quadratic algorithm for RLR with $\ell_1$ penalty, Rosset (2004)

Set $\beta_0^{(\epsilon)} = \hat{\beta}_{(X,y)}(\lambda_{\min})$, $t = 0$, small constant $\delta \in \mathbb{R}_{>0}$, and $\mathcal{A} = \{j \mid [\hat{\beta}_{(X,y)}(\lambda_{\min})]_j \neq 0\}$.
**while** $\lambda_t < \lambda_{\max}$ **do**
- $\lambda_{t+1} = \lambda_t + \epsilon$
- $\left(\beta_{t+1}^{(\epsilon)}\right)_{\mathcal{A}} = \left(\beta_t^{(\epsilon)}\right)_{\mathcal{A}} - \left[\nabla^2 l\left(\beta_t^{(\epsilon)}, (X,y)\right)_{\mathcal{A}}\right]^{-1} \cdot \left[\nabla l\left(\beta_t^{(\epsilon)}, (X,y)\right)_{\mathcal{A}} + \lambda_{t+1} \operatorname{sgn}\left(\beta_t^{(\epsilon)}\right)_{\mathcal{A}}\right]$
- $\left(\beta_{t+1}^{(\epsilon)}\right)_{-\mathcal{A}} = \vec{0}$
- $\mathcal{A} = \mathcal{A} \cup \{j \neq \mathcal{A} \mid \nabla l(\beta_{t+1}^{(\epsilon)}, (X,y)) > \lambda_{t+1}\}$
- $\mathcal{A} = \mathcal{A} \setminus \{j \in \mathcal{A} \mid \left|\beta_{t+1,j}^{(\epsilon)}\right| < \delta\}$
- $t = t + 1$

**Algorithm 2** Approximate incremental quadratic algorithm for RLR with $\ell_2$ penalty, Rosset (2004)

Set $\beta_0^{(\epsilon)} = \hat{\beta}_{(X,y)}(\lambda_{\min})$, $t = 0$.
**while** $\lambda_t < \lambda_{\max}$ **do**
- $\lambda_{t+1} = \lambda_t + \epsilon$
- $\beta^{(\epsilon)}(\lambda) = \beta_t^{(\epsilon)} - \left[\nabla^2 l\left(\beta_t^{(\epsilon)}, (X,y)\right) + 2\lambda_{t+1} I\right]^{-1} \cdot \left[\nabla l\left(\beta_t^{(\epsilon)}, (X,y)\right) + 2\lambda_{t+1}\beta_t^{(\epsilon)}\right]$
- $t = t + 1$

### E.1 Online learning for data-driven agglomerative hierarchical clustering

We will now present some useful lemmas for establishing Theorem 7.4. The following lemma generalizes Lemma 25 of Balcan et al. (2020b).

**Lemma E.2.** *Let $X_1, \ldots, X_n$ be a finite collection of independent random variables each having densities upper bounded by $\kappa$. The random variable $Y = \sum_{i=1}^n \beta_i X_i$ for some fixed scalars $\beta_1, \ldots, \beta_n$ with $\sum_{i=1}^n \beta_i = 1$ has density $f_Y$ satisfying $f_Y(y) \leq \kappa$ for all $y$.*

*Proof.* We proceed by induction on $n$. First consider $n = 1$. Clearly $Y = X_1$ and the conclusion follows from the assumption that $X_1$ has density upper bounded by $\kappa$.

Now suppose $n > 1$. We have $Y = \beta_1 X_1 + \beta_2 X_2 + \cdots + \beta_n X_n = \beta_1 X_1 + (1 - \beta_1)X'$, where $X' = \frac{1}{1-\beta_1}\sum_{i=2}^n \beta_i X_i$. By the inductive hypothesis, $X'$ has a density $f_{X'}$ which is upper bounded by $\kappa$. Let $f_{X_1}$ denote the density of $X_1$. Noting $X' = \frac{Y - \beta_1 X_1}{1-\beta_1}$ and using the independence of $X'$ and $X_1$, we get

$$f_Y(y) = \int_{-\infty}^{\infty} f_{X'}\left(\frac{y - \beta_1 x}{1 - \beta_1}\right) f_{X_1}(x)dx \leq \int_{-\infty}^{\infty} \kappa f_{X_1}(x)dx = \kappa.$$

This completes the induction step. □

We will now present a useful algebraic lemma for establishing Theorem 7.4.

**Lemma E.3.** *If $\alpha > 0$, $a, b, c > 0$, and $a^\alpha + b^\alpha - c^\alpha > 0$, then*

$$\frac{a^\alpha \ln a + b^\alpha \ln b - c^\alpha \ln c}{a^\alpha + b^\alpha - c^\alpha} \leq \frac{1}{\alpha} + \ln \max\{a, b, c\}.$$

*Proof.* We consider two cases. First suppose that $c > a$ and $c > b$. We have that

$$\frac{a^\alpha \ln a + b^\alpha \ln b - c^\alpha \ln c}{a^\alpha + b^\alpha - c^\alpha} \leq \frac{a^\alpha \ln c + b^\alpha \ln c - c^\alpha \ln c}{a^\alpha + b^\alpha - c^\alpha} \leq \ln c$$

in this case.

Now suppose $c \leq a$ (the case $c \leq b$ is symmetric). Observe that for $\alpha > 0$, the function $f(x) = x^\alpha \ln \frac{K}{x}$ is monotonically increasing for $x \leq Ke^{-1/\alpha}$ when $K, \alpha, x > 0$. This implies for $K = \max\{a, b\}e^{1/\alpha}$,

$$c^\alpha \ln \frac{K}{c} \leq a^\alpha \ln \frac{K}{a} \leq a^\alpha \ln \frac{K}{a} + b^\alpha \ln \frac{K}{b},$$

or, equivalently,

$$a^\alpha \ln a + b^\alpha \ln b - c^\alpha \ln c \leq \ln K(a^\alpha + b^\alpha - c^\alpha).$$

Since, $a^\alpha + b^\alpha - c^\alpha > 0$, we further get

$$\frac{a^\alpha \ln a + b^\alpha \ln b - c^\alpha \ln c}{a^\alpha + b^\alpha - c^\alpha} \leq \ln K = \frac{1}{\alpha} + \ln \max\{a, b\}.$$

□

To establish Theorem 7.5, we first present a useful lemma, and restate a useful result from Balcan & Sharma (2021).

**Lemma E.4.** *Suppose $X$ is a real-valued random variable taking values in $[0, M]$ for some $M \in \mathbb{R}^+$ and suppose its probability density is $\kappa$-bounded. Then, $Y = X^\alpha$ for $\alpha \in [\alpha_{\min}, 1]$ for some $\alpha_{\min} > 0$ takes values in $[0, M]$ with a $\kappa'$-bounded density with $\kappa' \leq \frac{\kappa}{\alpha_{\min}} \max\{1, M^{\frac{1}{\alpha_{\min}}-1}\}$.*

*Proof.* The cumulative density function for $Y$ is given by

$$\begin{aligned} F_Y(y) &= \Pr[Y \leq y] = \Pr[X \leq y^{1/\alpha}] \\ &= \int_0^{y^{1/\alpha}} f_X(x)dx, \end{aligned}$$

where $f_X(x)$ is the probability density function for $X$. Using Leibniz's rule, we can obtain the density function for $Y$ as

$$\begin{aligned} f_Y(y) &= \frac{d}{dy} F_Y(y) \\ &= \frac{d}{dy} \int_0^{y^{1/\alpha}} f_X(x)dx \\ &\leq \kappa \frac{d}{dy} y^{1/\alpha} \\ &= \frac{\kappa}{\alpha} y^{\frac{1}{\alpha}-1}. \end{aligned}$$

Now for $y \leq 1$, $y^{\frac{1}{\alpha}-1} \leq y \leq 1$ and therefore $f_Y(y) \leq \frac{\kappa}{\alpha_{\min}}$. Else, $y \leq M$, and $f_Y(y) \leq \frac{\kappa}{\alpha_{\min}} M^{\frac{1}{\alpha_{\min}}-1}$. □

We will also need the following result which is useful to establish dispersion when the discontinuities of the loss function are given by roots of an exponential equation in the parameter with random coefficients.

**Theorem E.5** (Balcan & Sharma (2021))**.** *Let $\phi(x) = \sum_{i=1}^n a_i e^{b_i x}$ be a random function, such that coefficients $a_i$ are real and of magnitude at most $R$, and distributed with joint density at most $\kappa$. Then for any interval $I$ of width at most $\epsilon$, $\Pr(\phi$ has a zero in $I) \leq \tilde{O}(\epsilon)$ (dependence on $b_i, n, \kappa, R$ suppressed).*