MaskTune: Mitigating Spurious Correlations by Forcing to Explore

Abstract

A fundamental challenge of over-parameterized deep learning models is learning meaningful data representations that yield good performance on a downstream task without over-fitting spurious input features. This work proposes *MaskTune*, a masking strategy that prevents over-reliance on spurious (or a limited number of) features. *MaskTune* forces the trained model to explore new features during a single epoch finetuning by masking previously discovered features. *MaskTune*, unlike earlier approaches for mitigating shortcut learning, does not require any supervision, such as annotating spurious features or labels for subgroup samples in a dataset. Our empirical results on biased MNIST, CelebA, Waterbirds, and ImagenNet-9L datasets show that *MaskTune* is effective on tasks that often suffer from the existence of spurious correlations. Finally, we show that *MaskTune* outperforms or achieves similar performance to the competing methods when applied to the selective classification task.

1 Introduction

Spurious correlations are coincidental feature associations formed between a subset of the input and target variables, which may be caused by factors such as data selection bias (Torralba & Efros, 2011; Jabri et al., 2016). The presence of spurious correlations in training data can cause over-parameterized deep neural networks to fail, often drastically, when such correlations do not hold in test data (Sagawa et al., 2019) or when encountering domain shift (Arjovsky et al., 2019). Consider the classification problem of cows and camels (Beery et al., 2018), where most of the images of cows vs. camels are captured on green fields vs. desert backgrounds due to selection bias (and perhaps the nature of the problem that camels are often in the desert). A model trained on such data may rely on the background as the key discriminative feature between cows and camels, thus failing on images of cows on non-green backgrounds or camels on non-desert backgrounds.

In over-parameterized regimes, there are often several solutions with almost identical loss values, and the optimizer (e.g., SGD) typically selects a low-capacity one (Wilson et al., 2017). In the presence of spurious correlations, the optimizer chooses to leverage them as they generally demand less capacity than the expected semantic cues of interest, e.g., relying on the local color or texture of grass instead of the elaborate visual features that give a cow its appearance (Bruna & Mallat, 2013; Bruna et al., 2015; Brendel & Bethge, 2019).

In previous work, a supervised loss function has been employed to reduce the effect of spurious correlations (Sagawa et al., 2019). However, identifying and annotating the spurious correlations in a large dataset as a training signal is impractical. Other works have attempted to force models to discard context and background (as spurious features) through input morphing using perceptual similarities (Taghanaki et al., 2021) or learning casual variables (Javed et al., 2020). Discarding context and background, however, is incompatible with the human visual system that relies on

Figure 1: An illustration of how *MaskTune* works. *MaskTune* generates a new set of masked samples by obstructing the features discovered by a model fully trained via empirical risk minimization (ERM). The ERM model is then fine-tuned for only one epoch using the masked version of the original training data to force new feature exploration. The features highlighted in yellow, black, and red correspond to features discovered by ERM, the masked features, and the newly discovered features by *MaskTune*, respectively.

contextual information when detecting and recognizing objects (Palmer, 1975; Biederman et al., 1982; Chun & Jiang, 1998; Henderson & Hollingworth, 1999; Torralba, 2003). In addition, spurious features may appear on the object itself (e.g., facial attributes). Thus discarding the context and background may be a futile strategy in these cases (Khani & Liang, 2021).

In mission-critical applications, relying on a small number of input features may increase the risk of failure. Recent approaches either use uncertainty estimation (Geifman & El-Yaniv, 2017) or equip models with a "rejection" option (Geifman & El-Yaniv, 2019) to reduce such risks.

Instead of requiring contextual and background information to be discarded or relying on a limited number of features, we propose a single-epoch finetuning technique called *MaskTune* that prevents a model from learning only the "first" simplest mapping (potentially spurious correlations) from the input to the corresponding target variable. Our method forces the model training to explore other input variables by concealing (masking) the ones that have already been deemed discriminatory. As we finetune the model with a new set of masked samples, we cause the training to escape its myopic and greedy capacity-preserving feature-seeking approach and encourage exploring and leveraging more input variables. In other words, as the previous clues are hidden, the model is constrained to find alternative loss-minimizing input-target mappings. *MaskTune* conceals the first clues discovered by a fully trained model, whether they are spurious or not. This forces the model to investigate and leverage new complementary discriminatory input features. A model relying upon a broader array of complementary features (some may be spurious while others are not) is expected to be more robust to test data missing a subset of these features. We then show how our approach can be used for selective classification, which is a way of providing models with a rejection option.

Figure 1 visualizes how *MaskTune* works via a schematic of the cow-on-grass scenario. Even in the absence of spurious correlations, models tend to focus on the shortest path (e.g., ears or skin texture of a cow), which can prevent models from generalizing to scenarios where those specific parts are missing. However, the object is still recognizable from the remaining parts. As an alternative, *MaskTune* generates a diverse set of partially masked training examples, forcing the model to investigate a wider area of the input features landscape, e.g., new pixels.

To the best of our knowledge, this is the first work to present a finetuning technique using masked data to overcome spurious correlations. Our contributions are summarized as follows:

1. We propose *MaskTune*, a new technique to reduce the effect of spurious correlations or over-reliance on a limited number of input features without any supervision such as object location or data subgroup labels.

2. We show that *MaskTune* leads to learning a model that does not rely solely on the initially discovered features.

3. We show how our method can be applied to selective classification tasks.

4. We empirically verify the robustness of the learned representations to spurious correlations on a variety of datasets.

2 Method

Setup. We consider the supervised learning setting with inputs $x \in \mathcal{X} \subset \mathbb{R}^d$ and corresponding labels $y \in \mathcal{Y} = \{1, \dots, k\}$. We assume having access to samples $\mathcal{D}^0 = \{(x_i, y_i)\}_{i=1}^n$ drawn from an unknown underlying distribution $p_{data}(x, y)$.

Our goal is to learn the parameters $\theta \in \Theta$ of a prediction model $m_\theta : \mathcal{X} \to \mathcal{Y}$ that obtains low classification error w.r.t some loss function (e.g., cross entropy) $\ell : \Theta \times (\mathcal{X} \times \mathcal{Y}) \to \mathbb{R}$. Specifically, we minimize:

$$\mathcal{L}(\theta) = \mathbb{E}_{x,y \sim p_{\text{data}}(x,y)}[\ell(m_\theta(x), y)] \approx \frac{1}{n} \sum_{i=1}^n \ell(m_\theta(x_i), y_i) \tag{1}$$

where n is the number of training data.

Besides having good prediction accuracy, we aim to develop a model which does not solely rely on spurious or a limited number of input features. We propose to mask the input training data to create a new set. We then finetune a fully trained model with the new masked data to reduce over-reliance on spurious or a limited number of features.

Input Masking. A key ingredient of our approach is a masking function $\mathcal{G}$ that is applied offline (i.e., after full training). The goal here is to construct a new masked dataset by concealing the most discriminative features in the input discovered by a model after full training. This should encourage the model to investigate new features with the masked training set during finetuning. As for $\mathcal{G}$, we adopt the xGradCAM (Selvaraju et al., 2017), which was originally designed for a visual explanation of deep models by creating rough localization maps based on the gradient of the model loss w.r.t. the output of a desired model layer. Given an input image of size $H \times W \times C$, xGradCAM outputs a localization map $\mathcal{A}$ of size $H \times W \times 1$, which shows the contribution of each pixel of the input image in predicting the most probable class, i.e., it calculates the loss by choosing the class with highest logit value (not the true label) as the target class. After acquiring the localization map, for each sample (x_i, y_i), where $x_i \in X$ and $y_i \in Y$, we mask the locations with the most contribution as:

$$\hat{x}_i = \mathcal{T}(\mathcal{A}_{x_i}; \tau) \odot x_i; \quad \mathcal{A}_{x_i} = \mathcal{G}(m_\theta(x_i), y_i) \tag{2}$$

where $\mathcal{T}$ refers to a thresholding function by the threshold factor τ (i.e., $\mathcal{T} = \mathbb{1}_{\mathcal{A}_{x_i} \leq \tau}$), and $\odot$ denotes element-wise multiplication. As the resolution of $\mathcal{A}$ is typically coarser than that of the input data, $\mathcal{T}(\mathcal{A}_{x_i})$ is up-sampled to the size of the input.

Procedurally, we first learn model $m_\theta^{\text{initial}}$ using original unmasked training data $\mathcal{D}^{\text{initial}}$. Then we use $m_\theta^{\text{initial}}$, $\mathcal{G}$ and $\mathcal{T}$ to create the masked set $\mathcal{D}^{\text{masked}}$. Finally, the fully trained predictor $m_\theta^{\text{initial}}$ is tuned using $\mathcal{D}^{\text{masked}}$ to obtain m_θ^{final}.

As for the masking step, any explainability approach can be applied (note that some may have more computational complexity, such as ScoreCAM (Wang et al., 2020)). We use xGradCAM (Selvaraju et al., 2017) as it is fast and produces relatively denser heat-maps than other methods (Srinivas & Fleuret, 2019; Selvaraju et al., 2017; Wang et al., 2020).

2.1 *MaskTune* in Over-parameterized Regimes

Consider the overparametrized regime, in which the model family has sufficient complexity to fully fit the training data. It has been shown that deep neural nets are overparametrized and can fit completely random data (Zhang et al., 2021). The generalization ability of deep neural nets are still not clear, but there are some speculation that connect the deep network generalization to their tendency of choosing simple functions that fit the training data (Valle-Perez et al., 2018; Arpit et al., 2017). However, this simplicity bias can causes side effects such as their poor performance with respect to adversarial examples (Raghunathan et al., 2019) or to distribution shifts (Khani & Liang, 2021; Shah et al., 2020). Here we study the effect of masking input features on complexity of a model in situation where indeed the training procedure chooses the lowest complex model that fit training data. We show that

in this case masking will result in learning a more complex model that discovers new features as the previous ones are blocked.

Formally, let $\mathcal{C}$ denote a function that measures model complexity and assume that the masking function $\mathcal{T}$ (as described in 2) only returns binary values, i.e., an indicator function that only keeps some features and zeros out the rest. We show that if training procedure returns the lowest complex model then masking results in a more complex model.

Proposition 1. *Consider an optimizing procedure that finds $\min \mathcal{C}(m_\theta), s.t., \ell(m_\theta) = 0$ as defined in 1. Let masking function $\mathcal{T}$ return binary values. If both models m_θ and $m_\theta^{initial}$ fit training data (i.e., zero loss) then we have $\mathcal{C}(m_\theta^{final}) \geq \mathcal{C}(m_\theta^{initial})$.*

Proof. Note that both models belong to the model family ($m_\theta^{\text{initial}}, m_\theta^{\text{final}} \in \Theta$), and they both fit the training data. In the first step, training procedure chooses $m_\theta^{\text{initial}}$ over m_θ^{final}; therefore according to our assumption $\mathcal{C}(m_\theta^{\text{final}}) \geq \mathcal{C}(m_\theta^{\text{initial}})$. $\square$

2.2 Adapting *MaskTune* for Selective Classification

A further disadvantage of relying on a limited number of features is the model's inability to know when it does not know. Let's go back to the cow-camel classification example; if cows only appear on the grass in the training set then it is unclear which of the grass or the cow refers to the "cow" label. A model that only relies on the grass feature can confidently make a wrong prediction when some other object appear in the grass in the test time. We need the model to predict only if both cow and grass appear in the picture and *abstain* otherwise.

One method used in the literature to address this issue is selective classification (Geifman & El-Yaniv, 2019, 2017), which allows a network to reject a sample if it is not confident in its prediction. Selective classification is essential in mission-critical applications such as autonomous driving, medical diagnostics, and robotics as they need to defer the prediction to human if they are uncertain about the prediction. We now demonstrate how to adapt *MaskTune* to be used for the selective classification problem.

In order to make a more reliable prediction, we ensemble the original model ($m_\theta^{\text{initial}}$) and *MaskTune* ($m_\theta^{\text{final}}$) and only predict if both models agree. As a result, if there exist two sets of features that can predict the label, our method predicts if both of them predict the same label (e.g., grass and cow in Figure 1).

To get an intuition on the performance of *MaskTune* for selective classification, similar to Khani et al. (2016) we analyze the noiseless overparametrized linear regression. We show that *MaskTune* adaptation, explained above, abstains in the presence of covariate shift, thus leading to a more reliable prediction.

In particular, we show that *MaskTune* only predicts if the relationship between masked and unmasked features in training data holds in the test time. For example, if features describing "cow" are predictable of "grass" in training data (i.e., they always co-occur) then we only predict if they co-occur in the test data as well. Formally, let s denote the masked feature after the first round and z denote the rest of the $d-1$ features. As we are in the overparametrized regime s can be predicted from z, let β be the min-norm solution for predicting s from z, i.e., $s = \beta z$ for training data. We now show that both models agree with each other for a new test set if $s = \beta z$ in the test time as well. In other words, there is not covariate shift between s and z.

Proposition 2. *Let $S \in \mathbb{R}^n$ be the concatenation, across all n training samples, of a single masked scalar feature, out of d possible features, and $Z \in \mathbb{R}^{n \times (d-1)}$ be the remaining $d-1$ features. Let the model family Θ be the linear functions, and the optimization function chooses the min L_2-norm solution that fits the training data. The models trained with and without S agree on the predicted output for a new test set (z, s), iff $s = (Z^\top (ZZ^T)^{-1}S)^\top z$.*

The full proof is in the appendix. Note that $(Z^\top (ZZ^T)^{-1}S)$ is the min-norm solution for predicting s from z in the training data. This proposition states that the models agree only if the relation between the masked feature (s) and remaining features (z) in training holds in the test data as well.

In practice, we need to trade off between the coverage and precision. Therefore, instead of a hard threshold and predicting if both models agree, we ensemble $m_\theta^{\text{initial}}$ and m_θ^{final} by multiplying their

Figure 2: Left: Test accuracy on the original and biased MNIST datasets. *MaskTune* outperforms other methods on both the original and and biased test sets. Right: xGradCAM visualizations before and after applying *MaskTune*. *MaskTune* enforces exploring more input features, which leads to more robust predictions. Here the spurious feature is the blue square on the top left corner.

probabilities and we find the desired threshold for abstaining in the validation set in order to achieve the coverage goal (see Section 3 for details).

3   Experimental Results

We evaluate our *MaskTune* method on two main applications: a) classification with spurious correlations—we expect *MaskTune* to prevent such correlations by identifying and masking them and b) selective classification where the ability to abstain is critical—we expect *MaskTune* to improve reliability by forcing a model to investigate additional variables in the input and learn more complex relationships. In each experiment, we compare our method to relevant baselines and competing methods.

3.1   Classification with Spurious Features

MNIST with Colored Squares on the Corners: As a warm-up, we test the ability of our method to distinguish between two MNIST digit groups (0-4 and 5-9) in the presence of spurious features. We construct a dataset such that a classifier would achieve poor accuracy by relying on spurious input features. We place 99% and 1% of all digits labelled "0-4" and "5-9" in the training set on a background with a small blue square on the top left corner, respectively, and keep the remaining data intact. We use two test sets during testing: the original raw MNIST test set and a biassed test set. To create the biased test set we place all of the digits from the group "5-9" on a background with a small blue square (representing spurious features) on the top left corner and keep all of the digits from the group "0-4" unchanged (i.e., we don't add any squares to their background and use the original images). Figure 2 demonstrates the performance of the ERM, RandMask, and our *MaskTune* on both original and biased test sets. The RandMask method is similar to *MaskTune*, but masks a *randomly* chosen area of the input image. As shown in Figure 2, *MaskTune* outperforms other methods by a large margin on both the test sets. As demonstrated in Figure 2 (right), *MaskTune* forces the model to explore more features, as opposed to the ERM, which only looks into the spurious feature (the blue square).

Classification with Spurious Features in Subgroups.   In this experiment, we leverage the CelebA (Liu et al., 2015) and the Waterbirds (Sagawa et al., 2019) datasets. In the CelebA dataset, there is a high correlation between features gender={male, female} and hair_color={blond, dark}, meaning that the feature gender is used as a proxy to predict the hair_color. In other words, an ERM would assign the label dark to male images since the majority of male images have dark hair, and there are only 1,387 (0.85%) blond males in the training set of size 162,770. To balance the accuracy of predictions on different subgroups of data, the existing methods (Sagawa et al., 2019) use privileged subgroup information, i.e., wrong predictions of an ERM on the worst group (blond males) can be penalized during training. Some other approaches (Levy et al., 2020; Nam et al., 2020; Pezeshki et al., 2021; Liu et al., 2021; Taghanaki et al., 2021) use such information during model

| Input | ERM | *MaskTune* | | Input | ERM | *MaskTune* |

Figure 3: Activation visualizations of ERM and *MaskTune* for CelebA (left) and Waterbirds (right) samples. *MaskTune* enforces exploring new features. As demonstrated, after applying *MaskTune*, the task-relevant input signals (hair colour and bird features) are emphasised.

selection (labeled validation set). However, it is impractical to recognize "all" subgroups in a dataset and label them. On the other hand, our *MaskTune* uses group information neither during training nor during model selection. In Table 1, we compare our *MaskTune* to both these groups of methods. *MaskTune* achieves comparable performance to the methods which use group level supervision while significantly outperforming (78% vs. 55% classification accuracy) the methods that do not use any supervision on the worst-group accuracy.

Table 1: Results from the CelebA dataset using ResNet-50. Our method outperforms competing fully unsupervised methods.

Method	Train supervision	Model-selection supervision	Worst-group accuracy	Avgerage accuracy
Group DRO (Sagawa et al., 2019)	Yes	Yes	**88.3**	91.8
CVaR DRO (Levy et al., 2020)	No	Yes	64.4	82.5
LfF (Nam et al., 2020)	No	Yes	77.2	85.1
SD (Pezeshki et al., 2021)	No	Yes	**83.2**±**2.0**	91.6±0.6
JTT (Liu et al., 2021)	No	Yes	81.1	88.0
CIM (Taghanaki et al., 2021)	No	Yes	81.3	89.2
ERM Sagawa et al. (2019)	No	No	47.2	95.6
CVaR DRO (Levy et al., 2020)	No	No	36.1	82.5
LfF (Nam et al., 2020)	No	No	24.4	85.1
JTT Liu et al. (2021)	No	No	40.6	88.0
DivDis (Lee et al., 2022)	No	No	55.0	90.8
MaskTune (ours)	No	No	**78.0**±**1.2**	91.3±0.1

In Figure 3, we highlight the important input features for predicting hair color. As shown, the ERM model leverages gender features while *MaskTune* forces to investigating other features as well.

We discovered and fixed two problems with the Waterbirds dataset: a) Because the background images in the Places dataset (Zhou et al., 2017) may already contain bird images, multiple birds may appear in an image after overlaying the segmented bird images from the Caltech-UCSD Birds-200-2011 (CUB) dataset (Wah et al., 2011). For example, the label of an image may be "landbird", but the image contains both land and water birds. Such images were removed from the dataset. b) Because the names of the species are similar, some land birds have been mislabeled as waterbirds. After addressing these issues, the ERM model's worst-group accuracy increased from 60% which is reported in (Sagawa et al., 2019) to 82%. We repeated the group-DRO method and ERM experiments on the corrected waterbirds dataset and reported the results in Table 2. As demonstrated, our method (without any group supervision) achieves similar accuracy to the group-DRO that benefits from full supervision. In Figure 3, we visualized feature importance before and after applying our *MaskTune*.

Table 2: Results from the Waterbirds dataset using ResNet-50. Our method significantly improves ERM's worst-group accuracy without supervision.

Method	Train Supervision	Model-selection supervision	Worst-group accuracy	Avgerage accuracy
GroupDRO (Sagawa et al., 2019)	Yes	Yes	**89.3±3.1**	94.4±0.7
ERM	No	No	80.8±1.3	94.0±0.2
MaskTune	No	No	**86.4±1.9**	93.0±0.7

The Background Challenge. As a further step, we evaluated *MaskTune* on the Background Challenge data (Xiao et al., 2020) to see if the positive observations from the MNIST experiment apply to a more realistic scenario. The Background Challenge is a publicly available dataset that consists of ImageNet-9 (Deng et al., 2009) test sets with various levels of foreground and background signals. It is intended to assess how much deep classifiers rely on spurious features for image classification. We used two configurations to compare *MaskTune*'s performance: Only FG, in which the background is completely removed, Mixed-same, in which the foreground is placed on different background from the same class, and Mixed-rand, where the foreground is overlaid onto a random background.

As shown in Table 3, *MaskTune* outperforms the baseline ResNet-50's performance by 2.5% on the Only-FG test set and 1.2% on Mixed-same, showing that *MaskTune* does not rely much on the background and uses both background and foreground for prediction. These results show that our technique helps to learn task-relevant features without depending on nuisance signal sources.

Table 3: Results from the Background Challenge on ImageNet-9 using ResNet-50. Our method outperforms the baselines on both Mixed-same and Only FG test sets.

Method	Original	Mixed-same	Mixed-rand	Only-FG
Baseline (Xiao et al., 2020)	96.3	89.8	75.6	85.6
CIM (Taghanaki et al., 2021)	**97.7**	89.8	**81.1**	-
SIN (Sauer & Geiger, 2021)	89.2	73.1	63.7	-
INSIN (Sauer & Geiger, 2021)	94.7	85.9	78.5	-
INCGN (Sauer & Geiger, 2021)	94.2	83.4	80.1	-
MaskTune (Ours)	95.6	**91.1**	78.6	**88.1**

3.2 Selective Classification

For selective classification task, we evaluated our *MaskTune* on three datasets: CIFAR-10 (Krizhevsky et al., 2009), SVHN (Netzer et al., 2011), and Cats vs. Dogs (Geifman & El-Yaniv, 2019), with coverage values of {90%, 95%, 100%}. For example 90% coverage means abstaining 10% of the samples.

Given input image j and the original (O) and finetuned (M) models, let their respective inference-time prediction probabilities for class i be P_{ij}^M and P_{ij}^O. Then *MaskTune* does not abstain and declares the class i^* as the predicted class, if and only if $P_{ij}^M \cdot P_{ij}^O > \gamma$, where γ is a threshold that allows for controlling the target coverage. To find the proper γ for achieving the targeted coverage, we iterate over the validation set and find a threshold that, if applied to the validation set, would give the desired

coverage, then use the found threshold in the test time (i.e., if our target coverage is 90%, we seek for a threshold which if we apply for abstention on the validation set, we will abstain predicting 10% of validation data). Note that the probabilities of the two models are multiplied to ensure that as the value of either probability decreases, the possibility of abstention increases.

We compare our method to the other selective classification approaches such as Softmax Response (SR) (Geifman & El-Yaniv, 2019), SelectiveNet (SN) (Geifman & El-Yaniv, 2019), Deep Gamblers (DG) (Liu et al., 2019), and One-sided Prediction (OSP) (Gangrade et al., 2021). Like the OSP, we first split the training data into train and validation sets. After training, we search for the abstention threshold on the validation set, then use it at the test time. As seen in Table 4, *MaskTune* outperforms all prior techniques on all three datasets on 95% and 100% coverage rates. For results on more coverage rates refer to Appendix A.

Table 4: Selective clssification results on CIFAR-10, SVHN, and Cats vs. Dogs datasets for different coverage values.

Dataset	Target Coverage	SR		SN		DG		OSP		MaskTune	
		Cov.	Error	Cov.	Error	Cov.	Error	Cov.	Error	Cov.	Error
Cifar-10	100%	99.99	9.58	100	11.07	100	10.81	100	9.74	99.97	**8.67**
	95%	95.2	8.74	94.7	8.34	95.1	8.21	95.1	6.98	95.04	**6.34**
	90%	90.5	6.52	89.6	6.45	90.1	6.14	90.0	4.67	89.74	**4.52**
SVHN	100%	99.97	3.86	100	4.27	100	4.03	100	4.27	100	**3.51**
	95%	95.1	1.86	95.1	2.53	95.0	2.05	95.1	1.83	95.21	**1.58**
	90%	90.0	1.04	90.1	1.31	90.0	1.06	90.1	1.01	89.25	**0.84**
Cats vs. Dogs	100%	100	5.72	100	7.36	100	6.16	100	5.93	99.98	**4.68**
	95%	95.0	3.46	95.2	5.1	95.1	4.28	95.1	2.97	94.86	**2.83**
	90%	90.0	2.28	90.2	3.3	90.0	2.5	90.0	**1.74**	90.68	1.83

4 Implementation Details

Classification with Spurious Features. For all of the datasets in Section 3.1, we use SGD with a momentum of 0.9 and weight decay of 1e-4. For biased MNIST, we used a simple convolutional neural network with four convolutional layers and a linear head. We trained this model with a batch size of 128 for 100 epochs with a learning rate of 0.01. We decreased the learning rate by a factor of 0.5 every 25 epochs. In the case of Background Challenge, we trained an ImageNet pre-trained ResNet50 with a batch size of 1024 for 100 epochs decaying the learning rate by 0.1 after every 30 epochs. For the CelebA dataset, we trained an ImageNet pre-trained ResNet50 with a batch size of 512 for 20 epochs with a learning rate of 1e-4.

Selective Classification. For all the datasets in Section 3.2, we trained a ResNet32 from scratch. For CIFAR-10, we used SGD with a momentum of 0.9, weight decay of 1e-4, learning rate of 0.1, and batch size of 128. We trained it for 300 epochs and halved the learning rate every 25 epochs. For SVHN, we used the same hyperparameters as CIFAR-10 with only two differences: the weight decay and batch size were 5e-4 and 1024, respectively. For Cats vs. Dogs dataset, we used Adam optimizer with a weight decay of 1e-4 and a learning rate of 0.001. We trained the model for 200 epochs with a batch size of 128 and dropped the learning rate by a factor of 0.1 on epoch 50.

Masking Threshold. Our goal is to mask the most important features, i.e., the core of the heat maps generated by the explainability methods. Masking a few input variables has almost no effect on the model's behavior, whereas large masks may destroy useful signals in the input, resulting in very low training accuracy. To reduce the search space of the masking threshold τ across all tasks, we experimented with $\tau = \{\mu_i, \mu_i + \sigma_i, \mu_i + 2\sigma_i, \mu_i + 3\sigma_i\}$ where μ_i and σ_i represent mean and standard deviation over the heatmap values for training sample x_i. We found $\mu_i + 2\sigma_i$ works best as μ_i and $\mu_i + \sigma_i$ remove a large portion of the input while $\mu_i + 3\sigma_i$ removes very few variables.

Hardware. We used two multi-GPU machines for all the experiments: a) 8 NVIDIA V100 Tensor Core GPUs with 32 GB of memory each, 728 GB RAM, b) 4 NVIDIA Quadro RTX 5000 with 16 GB memory each, and 128 GB RAM.

5 Related Work

In the following, we review the related works which have attempted to mitigate the effect of spurious correlation in training deep models. We also discuss previous methods that use attention-based online masking and how our method differs.

Robustness to Spurious Correlations. Distributionally robust optimization (DRO) (Ben-Tal et al., 2013; Gao et al., 2017; Duchi et al., 2021) has been proposed to improve generalization to worst cases (minority distributions) in a dataset. However, the DRO objective leads to disproportionate attention to the worst cases, even if they are implausible. To address this issue, Sagawa et al. (2019) proposed to leverage subgroup information during optimization. Although this method reduces the likelihood of the worst-case failure, it is based on prior solid information (i.e., subgroup labels), which is not always available. Several efforts have been made to reduce the subgroup-level supervision. Sohoni et al. (2020) proposed a clustering-based method for obtaining sub-group information to be used in DRO setup. However, determining the number of clusters (sub-groups) in a dataset is not trivial since a small number may still dismiss minor subgroups while a large number may lower overall accuracy. Yaghoobzadeh et al. (2019) proposed measuring sample accuracy throughout training to discover forgettable instances, then fine-tuning models using such samples to increase model resilience against spurious correlations. Chen et al. (2020) demonstrated that self-training can also help decrease the effect of spurious features, but only if the source classifier is very accurate and there are not too many isolated sub-groups in the data. Liu et al. (2021) discovered that training a model twice helps it become resistant to spurious correlation. However, if a model reaches high classification accuracy in the first run, this technique is no longer useful since there is not enough misclassified data to retrain the model. *MaskTune*, on the other hand, employs an orthogonal approach to learn robust representations through gradient-based masking and fine-tuning and does not require subgroup-level labels during training or model selection.

Online Attention-based Masking. A large number of studies suggest using attention-based (soft) masks to eliminate irrelevant information from input data during training (Sharma et al., 2015; Wang et al., 2017; Xu et al., 2015; Zheng et al., 2017). Although these methods increase overall classification accuracy, they are incapable of disregarding spurious correlations since attention may be on an area of the input where the spurious correlations are dominant during training. For concentrating attention only on the foreground, Li et al. (2018) developed a guided attention model. Their technique, however, needs additional annotations of object locations/masks. Nonetheless, none of these methods aimed to reduce the effects of spurious correlations. Even with complete supervision (i.e., masking the whole background), spurious correlations might still occur in the foreground. *MaskTune*, on the other hand, produces masks from a fully trained model and uses them for a single epoch fine-tuning. *MaskTune* does not require any additional supervision, such as object location annotations.

6 Conclusion

In this work, we considered the problem of preventing models from learning spurious correlations. We introduced a new fine-tuning technique that is designed explicitly for spurious correlations. It enforces a model to explore more variables in the input and map them to the same target. Through experiments and theoretical analysis on classification with nuisance background information which typically suffers from the presence of spurious correlations in the data, we showed that models trained with *MaskTune* outperform previous relevant methods. We also showed that *MaskTune* helps to improve the accuracy significantly in selective classification tasks. Adapting *MaskTune* for non-image data, such as sentiment analysis, can be an intriguing future work. Another area for future work is *how* best to identify and use the most effective masked samples (rather than all) when fine-tuning the final model, perhaps using uncertainty information or active learning.

References

Martin Arjovsky, Léon Bottou, Ishaan Gulrajani, and David Lopez-Paz. Invariant risk minimization. *arXiv preprint arXiv:1907.02893*, 2019.

Devansh Arpit, Stanisław Jastrzębski, Nicolas Ballas, David Krueger, Emmanuel Bengio, Maxinder S Kanwal, Tegan Maharaj, Asja Fischer, Aaron Courville, Yoshua Bengio, et al. A closer look at memorization in deep networks. In *International conference on machine learning*, pp. 233–242. PMLR, 2017.

Sara Beery, Grant Van Horn, and Pietro Perona. Recognition in terra incognita. In *Proceedings of the European conference on computer vision (ECCV)*, pp. 456–473, 2018.

Aharon Ben-Tal, Dick Den Hertog, Anja De Waegenaere, Bertrand Melenberg, and Gijs Rennen. Robust solutions of optimization problems affected by uncertain probabilities. *Management Science*, 59(2):341–357, 2013.

Irving Biederman, Robert J Mezzanotte, and Jan C Rabinowitz. Scene perception: Detecting and judging objects undergoing relational violations. *Cognitive psychology*, 14(2):143–177, 1982.

Wieland Brendel and Matthias Bethge. Approximating cnns with bag-of-local-features models works surprisingly well on imagenet. *arXiv preprint arXiv:1904.00760*, 2019.

Joan Bruna and Stéphane Mallat. Invariant scattering convolution networks. *IEEE transactions on pattern analysis and machine intelligence*, 35(8):1872–1886, 2013.

Joan Bruna, Stéphane Mallat, Emmanuel Bacry, and Jean-François Muzy. Intermittent process analysis with scattering moments. *The Annals of Statistics*, 43(1):323–351, 2015.

Yining Chen, Colin Wei, Ananya Kumar, and Tengyu Ma. Self-training avoids using spurious features under domain shift. *arXiv preprint arXiv:2006.10032*, 2020.

Marvin M Chun and Yuhong Jiang. Contextual cueing: Implicit learning and memory of visual context guides spatial attention. *Cognitive psychology*, 36(1):28–71, 1998.

Jia Deng, Wei Dong, Richard Socher, Li-Jia Li, Kai Li, and Li Fei-Fei. Imagenet: A large-scale hierarchical image database. In *2009 IEEE conference on computer vision and pattern recognition*, pp. 248–255. Ieee, 2009.

John C Duchi, Peter W Glynn, and Hongseok Namkoong. Statistics of robust optimization: A generalized empirical likelihood approach. *Mathematics of Operations Research*, 2021.

Aditya Gangrade, Anil Kag, and Venkatesh Saligrama. Selective classification via one-sided prediction. In *International Conference on Artificial Intelligence and Statistics*, pp. 2179–2187. PMLR, 2021.

Rui Gao, Xi Chen, and Anton J Kleywegt. Wasserstein distributional robustness and regularization in statistical learning. *arXiv e-prints*, pp. arXiv–1712, 2017.

Yonatan Geifman and Ran El-Yaniv. Selective classification for deep neural networks. *arXiv preprint arXiv:1705.08500*, 2017.

Yonatan Geifman and Ran El-Yaniv. Selectivenet: A deep neural network with an integrated reject option. In *International Conference on Machine Learning*, pp. 2151–2159. PMLR, 2019.

John M Henderson and Andrew Hollingworth. High-level scene perception. *Annual review of psychology*, 50(1):243–271, 1999.

Allan Jabri, Armand Joulin, and Laurens Van Der Maaten. Revisiting visual question answering baselines. In *European conference on computer vision*, pp. 727–739. Springer, 2016.

Khurram Javed, Martha White, and Yoshua Bengio. Learning causal models online. *arXiv preprint arXiv:2006.07461*, 2020.

Fereshte Khani and Percy Liang. Removing spurious features can hurt accuracy and affect groups disproportionately. In *Proceedings of the 2021 ACM Conference on Fairness, Accountability, and Transparency*, pp. 196–205, 2021.

Fereshte Khani, Martin Rinard, and Percy Liang. Unanimous prediction for 100% precision with application to learning semantic mappings. *arXiv preprint arXiv:1606.06368*, 2016.

Alex Krizhevsky, Geoffrey Hinton, et al. Learning multiple layers of features from tiny images. 2009.

Yoonho Lee, Huaxiu Yao, and Chelsea Finn. Diversify and disambiguate: Learning from underspeci-fied data. *arXiv preprint arXiv:2202.03418*, 2022.

Daniel Levy, Yair Carmon, John C Duchi, and Aaron Sidford. Large-scale methods for distributionally robust optimization. *Advances in Neural Information Processing Systems*, 33:8847–8860, 2020.

Kunpeng Li, Ziyan Wu, Kuan-Chuan Peng, Jan Ernst, and Yun Fu. Tell me where to look: Guided attention inference network. In *Proceedings of the IEEE Conference on Computer Vision and Pattern Recognition*, pp. 9215–9223, 2018.

Evan Z Liu, Behzad Haghgoo, Annie S Chen, Aditi Raghunathan, Pang Wei Koh, Shiori Sagawa, Percy Liang, and Chelsea Finn. Just train twice: Improving group robustness without training group information. In *International Conference on Machine Learning*, pp. 6781–6792. PMLR, 2021.

Ziwei Liu, Ping Luo, Xiaogang Wang, and Xiaoou Tang. Deep learning face attributes in the wild. In *Proceedings of the IEEE international conference on computer vision*, pp. 3730–3738, 2015.

Ziyin Liu, Zhikang Wang, Paul Pu Liang, Russ R Salakhutdinov, Louis-Philippe Morency, and Masahito Ueda. Deep gamblers: Learning to abstain with portfolio theory. *Advances in Neural Information Processing Systems*, 32:10623–10633, 2019.

Junhyun Nam, Hyuntak Cha, Sungsoo Ahn, Jaeho Lee, and Jinwoo Shin. Learning from failure: De-biasing classifier from biased classifier. *Advances in Neural Information Processing Systems*, 33:20673–20684, 2020.

Yuval Netzer, Tao Wang, Adam Coates, Alessandro Bissacco, Bo Wu, and Andrew Y Ng. Reading digits in natural images with unsupervised feature learning. 2011.

tephen E Palmer. The effects of contextual scenes on the identification of objects. *Memory & cognition*, 3:519–526, 1975.

Mohammad Pezeshki, Oumar Kaba, Yoshua Bengio, Aaron C Courville, Doina Precup, and Guil-laume Lajoie. Gradient starvation: A learning proclivity in neural networks. *Advances in Neural Information Processing Systems*, 34, 2021.

Aditi Raghunathan, Sang Michael Xie, Fanny Yang, John C Duchi, and Percy Liang. Adversarial training can hurt generalization. *arXiv preprint arXiv:1906.06032*, 2019.

Shiori Sagawa, Pang Wei Koh, Tatsunori B Hashimoto, and Percy Liang. Distributionally robust neural networks for group shifts: On the importance of regularization for worst-case generalization. *arXiv preprint arXiv:1911.08731*, 2019.

Axel Sauer and Andreas Geiger. Counterfactual generative networks. *arXiv preprint arXiv:2101.06046*, 2021.

Ramprasaath R Selvaraju, Michael Cogswell, Abhishek Das, Ramakrishna Vedantam, Devi Parikh, and Dhruv Batra. Grad-cam: Visual explanations from deep networks via gradient-based local-ization. In *Proceedings of the IEEE international conference on computer vision*, pp. 618–626, 2017.

Harshay Shah, Kaustav Tamuly, Aditi Raghunathan, Prateek Jain, and Praneeth Netrapalli. The pitfalls of simplicity bias in neural networks. *Advances in Neural Information Processing Systems*, 33:9573–9585, 2020.

Shikhar Sharma, Ryan Kiros, and Ruslan Salakhutdinov. Action recognition using visual attention. *arXiv preprint arXiv:1511.04119*, 2015.

Nimit S Sohoni, Jared A Dunnmon, Geoffrey Angus, Albert Gu, and Christopher Ré. No subclass left behind: Fine-grained robustness in coarse-grained classification problems. *arXiv preprint arXiv:2011.12945*, 2020.

Suraj Srinivas and François Fleuret. Full-gradient representation for neural network visualization. *Advances in neural information processing systems*, 32, 2019.

Saeid Asgari Taghanaki, Kristy Choi, Amir Khasahmadi, and Anirudh Goyal. Robust representation learning via perceptual similarity metrics. *arXiv preprint arXiv:2106.06620*, 2021.

Antonio Torralba. Contextual priming for object detection. *International journal of computer vision*, 53(2):169–191, 2003.

Antonio Torralba and Alexei A Efros. Unbiased look at dataset bias. In *CVPR 2011*, pp. 1521–1528. IEEE, 2011.

Guillermo Valle-Perez, Chico Q Camargo, and Ard A Louis. Deep learning generalizes because the parameter-function map is biased towards simple functions. *arXiv preprint arXiv:1805.08522*, 2018.

Catherine Wah, Steve Branson, Peter Welinder, Pietro Perona, and Serge Belongie. The caltech-ucsd birds-200-2011 dataset. 2011.

Fei Wang, Mengqing Jiang, Chen Qian, Shuo Yang, Cheng Li, Honggang Zhang, Xiaogang Wang, and Xiaoou Tang. Residual attention network for image classification. In *Proceedings of the IEEE conference on computer vision and pattern recognition*, pp. 3156–3164, 2017.

Haofan Wang, Zifan Wang, Mengnan Du, Fan Yang, Zijian Zhang, Sirui Ding, Piotr Mardziel, and Xia Hu. Score-cam: Score-weighted visual explanations for convolutional neural networks. In *Proceedings of the IEEE/CVF conference on computer vision and pattern recognition workshops*, pp. 24–25, 2020.

Ashia C Wilson, Rebecca Roelofs, Mitchell Stern, Nathan Srebro, and Benjamin Recht. The marginal value of adaptive gradient methods in machine learning. *arXiv preprint arXiv:1705.08292*, 2017.

Kai Xiao, Logan Engstrom, Andrew Ilyas, and Aleksander Madry. Noise or signal: The role of image backgrounds in object recognition. *arXiv preprint arXiv:2006.09994*, 2020.

Kelvin Xu, Jimmy Ba, Ryan Kiros, Kyunghyun Cho, Aaron Courville, Ruslan Salakhudinov, Rich Zemel, and Yoshua Bengio. Show, attend and tell: Neural image caption generation with visual attention. In *International conference on machine learning*, pp. 2048–2057. PMLR, 2015.

Yadollah Yaghoobzadeh, Soroush Mehri, Remi Tachet, Timothy J Hazen, and Alessandro Sordoni. Increasing robustness to spurious correlations using forgettable examples. *arXiv preprint arXiv:1911.03861*, 2019.

Chiyuan Zhang, Samy Bengio, Moritz Hardt, Benjamin Recht, and Oriol Vinyals. Understanding deep learning (still) requires rethinking generalization. *Communications of the ACM*, 64(3):107–115, 2021.

Heliang Zheng, Jianlong Fu, Tao Mei, and Jiebo Luo. Learning multi-attention convolutional neural network for fine-grained image recognition. In *Proceedings of the IEEE international conference on computer vision*, pp. 5209–5217, 2017.

Bolei Zhou, Agata Lapedriza, Aditya Khosla, Aude Oliva, and Antonio Torralba. Places: A 10 million image database for scene recognition. *IEEE transactions on pattern analysis and machine intelligence*, 40(6):1452–1464, 2017.

A Appendix

A.1 More experimental results

Selective classification. In table 5 the results of the selective classification is depicted for the *MaskTune* for different coverages. We have run every experiment three times and reported the mean and std for each.

B Missing proofs

Proposition 2. *Let $S \in \mathbb{R}^n$ be the concatenation, across all n training samples, of a single masked scalar feature, out of d possible features, and $Z \in \mathbb{R}^{n \times (d-1)}$ be the remaining $d - 1$ features. Let the model family Θ be the linear functions, and the optimization function chooses the min L_2-norm solution that fits the training data. The models trained with and without S agree on the predicted output for a new test set (z, s), iff $s = (Z^\top (ZZ^T)^{-1}S)^\top z$.*

Proof. Let $Y \in \mathbb{R}^d$ be the targets in training data. Let $\hat{\theta}^{+s}$ denote the recovered coefficient for the first $d - 1$ features and $\hat{w}$ be the coefficient for the feature s.

Table 5: Selective clssification results on CIFAR-10, SVHN, and Cats vs. Dogs datasets for different coverage values.

Dataset	Target Coverage	MaskTune Cov.	Error
Cifar-10	100%	99.99±0.02	8.96±0.48
	95%	94.86±0.18	6.54±0.39
	90%	89.73±0.22	4.74±0.31
	85%	84.46±0.07	3.23±0.20
	80%	79.03±0.44	2.13±0.11
SVHN	100%	100.0±0.0	3.68±0.16
	95%	95.19±0.09	1.84±0.23
	90%	89.55±0.26	0.96±0.11
	85%	83.72±0.71	0.57±0.04
	80%	77.81±0.75	0.45±0.05
Cats vs. Dogs	100%	99.98±0.0	4.83±0.17
	95%	95.01±0.14	2.96±0.15
	90%	90.78±0.16	1.94±0.18
	85%	86.33±0.61	1.24±0.21
	80%	81.98±0.47	0.89±0.2

The parameters after the first round can be obtained by the following optimization problem.

$$\hat{\theta}^{+s}, \hat{w} = \arg\min_{\theta,w} \|\theta\|_2^2 + w^2 \tag{3}$$

$$s.t. \quad Z\theta + Sw = Y, \tag{4}$$

where $\hat{w}$ denotes the weight associate with the feature s.

Recall that we assumed that after training the first model we mask the feature s. The parameters for the second model that does not use feature s can be obtained by solving the following optimization problem, where $\hat{\theta}^{-s}$ denote the recovered coefficients.

$$\hat{\theta}^{-s} = \arg\min_{\theta} \|\theta\|_2^2 \tag{5}$$

$$s.t. \quad Z\theta = Y, \tag{6}$$

The minimum norm solution in the first round is:

$$\theta^{+s} = Z^\top (ZZ^\top)^{-1}(Y - S\hat{w}) \tag{7}$$

The min-norm solution for the second round is:

$$\theta^{-s} = Z^\top (ZZ^\top)^{-1}Y \tag{8}$$

Now we show that for a new test set $(z^\star, s^\star)$, the models m^1 and m^0 predict the same if there is no covariate shift between z and s. We are assuming that $\hat{w}$ is not zero meaning that the first model is using the feature s.

$$(Z^\top (ZZ^\top)^{-1}Y)^\top z^\star = (Z^\top (ZZ^\top)^{-1}(Y - S\hat{w}))^\top z^\star + \hat{w}s^\star \tag{9}$$

$$(Z^\top (ZZ^\top)^{-1}S\hat{w}))^\top z^\star = \hat{w}s^\star \tag{10}$$

$$(Z^\top (ZZ^\top)^{-1}S))^\top z^\star = s^\star \tag{11}$$

$\square$