EIGENCURVE: OPTIMAL LEARNING RATE SCHEDULE FOR SGD ON QUADRATIC OBJECTIVES WITH SKEWED HESSIAN SPECTRUMS

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ABSTRACT

Learning rate schedulers have been widely adopted in training deep neural networks. Despite their practical importance, there is a discrepancy between its practice and its theoretical analysis. For instance, it is not known what schedules of SGD achieve best convergence, even for simple problems such as optimizing quadratic objectives. In this paper, we propose Eigencurve, the first family of learning rate schedules that can achieve minimax optimal convergence rates (up to a constant) for SGD on quadratic objectives when the eigenvalue distribution of the underlying Hessian matrix is skewed. The condition is quite common in practice. Experimental results show that Eigencurve can significantly outperform step decay in image classification tasks on CIFAR-10, especially when the number of epochs is small. Moreover, the theory inspires two simple learning rate schedulers for practical applications that can approximate eigencurve. For some problems, the optimal shape of the proposed schedulers resembles that of cosine decay, which sheds light to the success of cosine decay for such situations. For other situations, the proposed schedulers are superior to cosine decay.

1 INTRODUCTION

Many machine learning models can be represented as the following optimization problem:

$$\min_{w} f(w) \triangleq \frac{1}{n}\sum_{i=1}^{n} f_i(w), \tag{1.1}$$

such as logistic regression, deep neural networks. To solve the above problem, stochastic gradient descent (SGD) (Robbins & Monro, 1951) has been widely adopted due to its computation efficiency in large-scale learning problems (Bottou & Bousquet, 2008), especially for training deep neural networks.

Given the popularity of SGD in this field, different learning rate schedules have been proposed to further improve its convergence rates. Among them, the most famous and widely used ones are inverse time decay, step decay (Goffin, 1977), and cosine scheduler (Loshchilov & Hutter, 2017). The learning rates generated by the inverse time decay scheduler depends on the current iteration number inversely. Such a scheduling strategy comes from the theory of SGD on strongly convex functions, and is extended to non-convex objectives like neural networks while still achieving good performance. Step decay scheduler keeps the learning rate piecewise constant and decreases it by a factor after a given amount of epochs. It is theoretically proved in Ge et al. (2019) that when the objective is quadratic, step decay scheduler outperforms inverse time decay. Empirical results are also provided in the same work to demonstrate the better convergence property of step decay in training neural networks when compared with inverse time decay. However, even step decay is proved to be near optimal on quadratic objectives, it is *not* truly optimal. There still exists a $\log T$ gap away from the minimax optimal convergence rate, which turns out to be non-trivial in a wide range of settings and may greatly impact step decay's empirical performance. Cosine decay scheduler (Loshchilov & Hutter, 2017) generates cosine-like learning rates in the range $[0, T]$, with T being the maximum iteration. It is a heuristic scheduling strategy which relies on the observation that good performance in practice can be achieved via slowly decreasing the learning rate in the

beginning and "refining" the solution in the end with a very small learning rate. Its convergence property on smooth non-convex functions has been shown in Li et al. (2021), but the provided bound is still not tight enough to explain its success in practice.

Except cosine decay scheduler, all aforementioned learning rate schedulers have (or will have) a tight convergence bound on quadratic objectives. In fact, studying their convergence property on quadratic objective functions is quite important for understanding their behaviors in general non-convex problems. Recent studies in Neural Tangent Kernel (NTK) (Arora et al., 2019; Jacot et al., 2020) suggest that when neural networks are sufficiently wide, the gradient descent dynamic of neural networks can be approximated by NTK. In particular, when the loss function is least-square loss, neural network's inference is equivalent to kernel ridge regression with respect to the NTK in expectation. In other words, for regression tasks, the non-convex objective in neural networks resembles quadratic objectives when the network is wide enough.

The existence of $\log T$ gap in step decay's convergence analysis, which will be proven to be tight in a wide range of settings, implies that there is still room for improvement in theory. Meanwhile, the existence of cosine decay scheduler, which has no strong theoretical convergence guarantees but possesses good empirical performance in certain tasks, suggests that its convergence rate may depend on some specific properties of the objective determined by the network and dataset in practice. Hence it is natural to ask what those key properties may be, and whether it is possible to find theoretically-optimal schedulers whose empirical performance are comparable to cosine decay if those properties are available. In this paper, we offer an answer to these questions. We first derive a novel eigenvalue-distribution-based learning rate scheduler called `eigencurve` for the quadratic function. Combining with the different eigenvalue distributions of different types of networks, new neural-network-based learning rate schedulers can be generated based on our proposed paradigm, which achieve better convergence properties than step decay in Ge et al. (2019). Specifically, `eigencurve` closes the $\log T$ gap in step decay and reaches minimax optimal convergence rates if the Hessian spectrum is skewed. We summarize the main contributions of this paper as follows.

1. To the best of our knowledge, this is the first work that incorporates the eigenvalue distribution of objective function's Hessian matrix into designing learning rate schedulers. Accordingly, based on the eigenvalue distribution of the Hessian, we propose a novel eigenvalue distribution based learning rate scheduler named `eigencurve`.
2. Theoretically, `eigencurve` can achieve optimal convergence rate (up to a constant) for SGD on quadratic objectives when the eigenvalue distribution of the Hessian is skewed. Furthermore, even when the Hessian is not skewed, `eigencurve` can still achieve no worse convergence rate than the step decay schedule in Ge et al. (2019), whose convergence rate are proven to be sub-optimal in a wide range of settings.
3. Empirically, on image classification tasks, `eigencurve` achieves optimal convergence rate for several models on CIFAR-10 and ImageNet if the loss can be approximated by quadratic objectives. Moreover, it obtains much better performance than step decay on CIFAR-10, especially when the number of epochs is small.
4. Intuitively, our learning rate scheduler sheds light on the theoretical property of cosine decay and provides a perspective of understanding the reason why it can achieve good performance on image classification tasks. The same idea has been used to inspire and discover several simple families of schedules that works in practice.

Problem Setup For the theoretical analysis and the aim to derive our eigenvalue-dependent learning rate schedulers, we mainly focus on the quadratic function, that is,

$$\min_w f(w) \triangleq \mathbb{E}_\xi \left[f(w,\xi) \right], \text{ where } f(w,\xi) = \frac{1}{2} w^\top H(\xi) w - b(\xi)^\top w, \tag{1.2}$$

where ξ denotes the data sample. Hence, the Hessian of $f(w)$ is

$$H = \mathbb{E}_\xi \left[H(\xi) \right]. \tag{1.3}$$

Letting us denote $b = \mathbb{E}_\xi[b(\xi)]$, we can obtain the optima of problem (1.2)

$$w_* = H^{-1} b. \tag{1.4}$$

Given an initial iterate w_0 and the learning rate sequence $\{\eta_t\}$, the stochastic gradient update is

$$w_{t+1} = w_t - \eta_t \nabla f(w_t, \xi) = w_t - \eta_t (H(\xi) w_t - b(\xi)). \tag{1.5}$$

We denote that

$$n_t = H w_t - b - (H(\xi) w_t - b(\xi)), \quad \mu \triangleq \lambda_{\min}(H), \quad L \triangleq \lambda_{\max}(H), \quad \text{and,} \quad \kappa \triangleq L/\mu. \tag{1.6}$$

In this paper, we assume that

$$\mathbb{E}_\xi \left[n_t n_t^\top \right] \preceq \sigma^2 H. \tag{1.7}$$

The reason for this assumption is presented in Appendix G.5.

Related Work In convergence analysis, one key property that separates SGD from vanilla gradient descent is that in SGD, noise in gradients dominates. In gradient descent (GD), constant learning rate can achieve linear convergence $\mathcal{O}(c^T)$ with $0 < c < 1$ for strongly convex objectives, i.e. obtaining $f(w^{(t)}) - f(w^*) \leq \epsilon$ in $\mathcal{O}(\log(\frac{1}{\epsilon}))$ iterations. However, in SGD, $f(w^{(t)})$ cannot even be guaranteed to converge to $f(w^*)$ due to the existence of gradient noise (Bottou et al., 2018). Intuitively, this noise leads to a variance proportional to the learning rate size, so constant learning rate will always introduce a $\Omega(\eta_t) = \Omega(\eta_0)$ gap when compared with the convergence rate of GD. Fortunately, inverse time decay scheduler solves the problem by decaying the learning rate inversely proportional to the iteration number t, which achieves $\mathcal{O}(\frac{1}{T})$ convergence rate for strongly convex objectives, specifically, $\mathcal{O}(\frac{d\sigma^2}{T} \cdot \kappa)$. However, this is sub-optimal since the minimax optimal rate for SGD is $\mathcal{O}(\frac{d\sigma^2}{T})$ (Ge et al., 2019; Jain et al., 2018). Moreover, in practice, κ can be very big for large neural networks, which makes inverse time decay scheduler undesirable for those models. This is when step decay (Goffin, 1977) comes to play. Empirically, it is widely adopted in tasks such as image classification and serves as a baseline for a lot of models. Theoretically, it has been proven that step decay can achieve nearly optimal convergence rate $\mathcal{O}(\frac{d\sigma^2}{T} \cdot \log T)$ for strongly convex least square regression (Ge et al., 2019). Nevertheless, step decay is not always the best choice for image classification tasks. In practice, cosine decay (Loshchilov & Hutter, 2017) can achieve comparable or even better performance, but the reason behind this superior performance is still unknown in theory (Gotmare et al., 2018). All the aforementioned results are summarized in Table 1, along with our results in this paper. It is worth mentioning that the minimax optimal rate $\mathcal{O}(\frac{d\sigma^2}{T})$ can be achieved by iterate averaging methods (Jain et al., 2018; Bach & Moulines, 2013; Défossez & Bach, 2015; Frostig et al., 2015; Jain et al., 2016; Neu & Rosasco, 2018), but it is not a common practice to use them in training deep neural networks, so only the final iterate (Shamir, 2012) behavior of SGD is analyzed in this paper, i.e. the point right after the last iteration.

Table 1: Convergence rate of SGD with common schedulers on quadratic objectives.

Scheduler	Convergence rate of SGD in quadratic objectives
Constant	Not guaranteed to converge
Inverse Time Decay	$\Theta\left(\frac{d\sigma^2}{T} \cdot \kappa\right)$
Step Decay	$\Theta\left(\frac{d\sigma^2}{T} \cdot \log T\right)$ (Ge et al. (2019); This work - Theorem 4)
`Eigencurve`	$\mathcal{O}\left(\frac{d\sigma^2}{T}\right)$ with skewed Hessian spectrums, $\mathcal{O}\left(\frac{d\sigma^2}{T} \cdot \log \kappa\right)$ in worst case (This work - Theorem 1, Corollary 2, 3)

Paper organization: Section 2 describes the motivation of our `eigencurve` scheduler. Section 3 presents the exact form and convergence rate of the proposed `eigencurve` scheduler, along with the lower bound of step decay. Section 4 shows the experimental results. Section 5 discusses the discovery and limitation of `eigencurve` and Section 6 gives our conclusion.

2 MOTIVATION

In this section, we will give the main motivation and intuition of our `eigencurve` learning rate scheduler. We first give the scheduling strategy to achieve the optimal convergence rate in the case that the Hessian is diagonal. Then, we show that the inverse time learning rate is sub-optimal in

most cases. Comparing these two scheduling methods brings up the reason why we should design eigenvalue distribution dependent learning rate scheduler.

Letting H be a diagonal matrix $\mathrm{diag}(\lambda_1, \lambda_2, \ldots, \lambda_d)$ and reformulating Eqn. (1.5), we have

$$\begin{aligned} w_{t+1} - w_* =& w_t - w_* - \eta_t(H(\xi)w_t - b(\xi)) \\ =& w_t - w_* - \eta_t(Hw_t - b) + \eta_t\left(Hw_t - b - (H(\xi)w_t - b(\xi))\right) \\ =& w_t - w_* - \eta_t(Hw_t - b - (Hw_* - b)) + \eta_t\left(Hw_t - b - (H(\xi)w_t - b(\xi))\right) \\ =& \left(I - \eta_t H\right)(w_t - w_*) + \eta_t n_t. \end{aligned}$$

It follows,

$$\begin{aligned} \mathbb{E}\left[\lambda_j\left(w_{t+1,j} - w_{*,j}\right)^2\right] &\overset{\mathbb{E}[n_t]=0}{=} \lambda_j\left[(1-\eta_t\lambda_j)^2(w_{t,j} - w_{*,j})^2 + \eta_t^2\mathbb{E}\left\|[n_t]_j\right\|^2\right] \\ &\overset{(1.7)}{\leq} (1-\eta_t\lambda_j)^2 \cdot \lambda_j(w_{t,j} - w_{*,j})^2 + \eta_t^2\lambda_j^2\sigma^2. \end{aligned} \tag{2.1}$$

Since H is diagonal, we can set step size scheduling for each dimension separately. Letting us choose step size η_t coordinately with the step size $\eta_{t,j} = \frac{1}{\lambda_j(t+1)}$ being optimal for the j-th coordinate, then we have the following proposition.

Proposition 1. *Assume that H is diagonal matrix with eigenvalues $\lambda_1 \geq \lambda_2 \geq \ldots, \lambda_d \geq 0$ and Eqn.* (1.7) *holds. If we set step size $\eta_{t,j} = \frac{1}{\lambda_j(t+1)}$, it holds that*

$$2\mathbb{E}\left[f(w_{t+1}) - f(w_*)\right] = \mathbb{E}\left[\sum_{j=1}^{d}\lambda_j\left(w_{t+1,j} - w_{*,j}\right)^2\right] \leq \frac{\sum_{j=1}^{d}\lambda_j(w_{1,j} - w_{*,j})^2}{(t+1)^2} + \frac{t}{(t+1)^2}\cdot d\sigma^2. \tag{2.2}$$

The leading equality here is proved in Appendix G.1, with the followed inequality proved in Appendix E. From Eqn. (2.2), we can observe that choosing proper step sizes coordinately can achieve the optimal convergence rate (Ge et al., 2019; Jain et al., 2018). Instead, if the widely used inverse time scheduler $\eta_t = 1/(L + \mu t)$ is chosen, we can show that only a sub-optimal convergence rate can be obtained, especially when λ_j's vary from each other.

Proposition 2. *If we set the inverse time step size $\eta_t = \frac{1}{(L+\mu t)}$, then we have*

$$\begin{aligned} &2\mathbb{E}\left[f(w_{t+1}) - f(w_*)\right] = \mathbb{E}\left[\sum_{j=1}^{d}\lambda_j\left(w_{t+1,j} - w_{*,j}\right)^2\right] \\ &\leq \left(\frac{L+\mu}{L+\mu t}\right)^2\left(\sum_{j=1}^{d}\lambda_j(w_{1,j} - w_{*,j})^2\right) + \sum_{j=1}^{d}\left(\frac{\lambda_j^2}{2\lambda_j - \mu}\cdot\frac{1}{L+\mu t}\cdot\sigma^2 + \frac{\lambda_j^2\sigma^2}{(L+\mu t)^2}\right). \end{aligned} \tag{2.3}$$

Remark 1. *Eqn.* (2.2) *shows that if one can choose step size coordinate-wise with step size $\eta_{t,j} = \frac{1}{\lambda_j(t+1)}$, then SGD can achieve a convergence rate*

$$\mathbb{E}\left[f(w_{T+1}) - f(w_*)\right] \leq \mathcal{O}\left(\frac{d}{T}\cdot\sigma^2\right). \tag{2.4}$$

which matches the lower bound (Ge et al., 2019; Jain et al., 2018). In contrast, replacing $L = \lambda_1$ and $\mu = \lambda_d$ in Proposition 2, we can obtain that the convergence rate of SGD being

$$\mathbb{E}\left[f(w_{T+1}) - f(w_*)\right] \leq \mathcal{O}\left(\frac{1}{T}\sum_{j=1}^{d}\frac{\lambda_j}{\lambda_d}\cdot\sigma^2\right). \tag{2.5}$$

Since it holds that $\lambda_j \geq \lambda_d$, the convergence rate in Eqn. (2.4) *is better than the one in Eqn.* (2.5)*, especially when the eigenvalues of the Hessian (H matrix) decay rapidly. In fact, the upper bound in Eqn.* (2.5) *is tight for the inverse time decay scheduling (Ge et al., 2019).*

Main Intuition Though SGD with coordinately proper step sizes can obtain the optimal convergence rate, since H is commonly non-diagonal in practice, one is *not* able to choose proper step sizes coordinately. However, the diagonal case still provide an important intuition for designing eigenvalue dependent learning rate scheduling. In fact, letting $H = U\Lambda U^\top$ be the spectral decomposition of the Hessian and setting $w' = U^\top w$, then the Hessian becomes a diagonal matrix from perspective of updating w', with the variance of the stochastic gradient being unchanged since U is a unitary matrix.

Proposition 1 and 2 imply that a good learning rate scheduler should decrease the error of each coordinate. The inverse time decay scheduler is only optimal for the coordinate related to the smallest eigenvalue. That's the reason why the inverse time scheduler is sub-optimal. Thus, we should reduce the learning rate gradually such that we can run a optimal learning rate associated to λ_j to sufficiently drop the error of j-th coordinate. *Furthermore, given the total iteration T and the eigenvalue distribution of the Hessian, we should allocate the running time for each optimal learning rate associated to λ_j.*

3 Eigenvalue Dependent Step Scheduling

Just as discussed in Section 2, to obtain better convergence rate for SGD, we should consider Hessian's eigenvalue distribution and schedule the learning rate based on the distribution. In this section, we propose a novel learning rate scheduler for this task, which can be regarded as piecewise inverse time decay (see Figure 1). The method is very simple, we group eigenvalues according to their value and denote s_i to be the number of eigenvalues lie in the range $\mathcal{R}_i = [\mu \cdot 2^i, \mu \cdot 2^{i+1})$, that is,

$$s_i = \#\lambda_j \in [\mu \cdot 2^i, \mu \cdot 2^{i+1}). \tag{3.1}$$

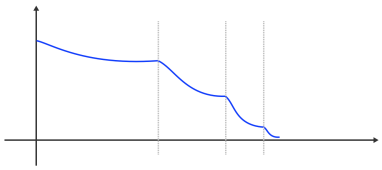

Figure 1: `Eigencurve` : piecewise inverse time decay scheduling.

Then, there are at most $I_{\max} = \log_2 \kappa$ such ranges. By the inverse time decay theory, the optimal learning rate associated to eigenvalues in the range $\mathcal{R}_i$ should be

$$\eta_t = \mathcal{O}\left(\frac{1}{2^{i-1}\mu \cdot (t - t_i)}\right), \text{ with } 0 = t_0 < t_1 < t_2 < \cdots < t_{I_{\max}} = T. \tag{3.2}$$

Our scheduling strategy is to run the optimal learning rate for eigenvalues in each $\mathcal{R}_i$ for a period to sufficiently decrease the error associated to eigenvalues in $\mathcal{R}_i$.

To make the step size sequence $\{\eta_t\}_{t=1}^T$ monotonely decreasing, we define the step sizes as

$$\eta_t = \frac{1}{L + \mu \sum_{j=1}^{i-1} \Delta_j 2^{j-1} + 2^{i-1}\mu(t - t_{i-1})} \quad \text{if} \quad t \in [t_{i-1}, t_i) \tag{3.3}$$

where

$$0 = t_0 < t_1 < t_2 < \cdots < t_{I_{\max}} = T,\ \Delta_i = t_i - t_{i-1}, \text{ and } I_{\max} = \log_2 \kappa. \tag{3.4}$$

To make the total error, that is the sum of error associated with $\mathcal{R}_i$, to be small, we should allocate Δ_i according to s_{i-1}'s. Intuitively, a large portion of eigenvalues lying in the range $\mathcal{R}_i$ should allocate a large portion of iterations. Specifically, we propose to allocate Δ_i as follows:

$$\Delta_i = \frac{\sqrt{s_{i-1}}}{\sum_{i'=0}^{I_{\max}-1} \sqrt{s_{i'}}} \cdot T, \text{ with } s_i = \#\lambda_j \in [\mu \cdot 2^i, \mu \cdot 2^{i+1}). \tag{3.5}$$

In the rest of this section, we will show that the step size scheduling according to Eqn. (3.3) and (3.5) can achieve better convergence rate than the one in Ge et al. (2019) when s_i is non-uniformly distributed. In fact, a better Δ_i allocation can be calculated using numerical optimization.

3.1 Theoretical Analysis

Lemma 1. *Let objective function $f(x)$ be quadratic and Assumption* (1.7) *hold. Running SGD for T-steps starting from w_0 and a learning rate sequence $\{\eta_t\}_{t=1}^T$ defined in Eqn.* (3.3)*, the final iterate*

w_{T+1} satisfies

$$\mathbb{E}\left[f(w_{T+1}) - f(w_*)\right] \leq (f(w_0) - f(w_*)) \cdot \frac{\kappa^2}{\Delta_1^2} + \frac{15}{2} \cdot \sigma^2 \mu \sum_{\tilde{i}=0}^{I_{\max}-1} \frac{2^{\tilde{i}+1} s_{\tilde{i}}}{L + \mu \sum_{j=1}^{\tilde{i}+1} \Delta_j 2^{j-1}}. \tag{3.6}$$

Since the bias term is a high order term, the variance term in Eqn. (3.6) dominates the error for w_{T+1}. For simplicity, instead of using numerical methods to find the optimal $\{\Delta_i\}$, we propose to use Δ_i defined in Eqn. (3.5). The value of Δ_i is linear to square root of the number of eigenvalues lying in the range $[\mu \cdot 2^{i-1}, \mu \cdot 2^i)$. Using such Δ_i, `eigencurve` has the following convergence property.

Theorem 1. *Let objective function $f(x)$ be quadratic and Assumption* (1.7) *hold. Running SGD for T-steps starting from w_0, a learning rate sequence $\{\eta_t\}_{t=1}^T$ defined in Eqn.* (3.3) *and Δ_i defined in Eqn.* (3.5)*, the final iterate w_{T+1} satisfies*

$$\mathbb{E}\left[f(w_{T+1}) - f(w_*)\right] \leq (f(w_0) - f(w_*)) \cdot \frac{\kappa^2 \cdot \left(\sum_{i=0}^{I_{\max}-1} \sqrt{s_i}\right)^2}{s_0 T^2} + \frac{15 \left(\sum_{i=0}^{I_{\max}-1} \sqrt{s_i}\right)^2}{T} \cdot \sigma^2.$$

Please refer to Appendix D, F and G for the full proof of Lemma 1 and Theorem 1. The variance term $\frac{15\left(\sum_{i=0}^{I_{\max}-1} \sqrt{s_i}\right)^2}{T} \cdot \sigma^2$ in above theorem shows that when s_i's vary largely from each other, then the variance can be close to $\mathcal{O}\left(\frac{d}{T} \cdot \sigma^2\right)$ which matches the lower bound (Ge et al., 2019). For example, letting $I_{\max} = 100$, $s_0 = 0.99d$ and $s_i = \frac{0.01}{99} d$, we can obtain that

$$\frac{\left(\sum_{i=0}^{99} \sqrt{s_i}\right)^2}{T} \cdot \sigma^2 = (\sqrt{0.99} + 99 \times \sqrt{0.01/99})^2 \cdot \frac{d}{T} \cdot \sigma^2 < \frac{4d}{T} \cdot \sigma^2.$$

We can observe that if the variance of s_i's is large, the variance term in Theorem 1 can be close to $d\sigma^2/T$. More generally, as rigorously stated in Corollary 2, `eigencurve` achieves minimax optimal convergence rate if the Hessian spectrum satisfies an extra assumption of what-we-called "power power law": the density of eigenvalue λ is exponentially decaying with increasing value of λ in log scale, i.e. $\ln(\lambda)$. This assumption comes from the observation of estimated Hessian spectrums in practice (see Figure 2), which will be further illustrated in Section 4.1.

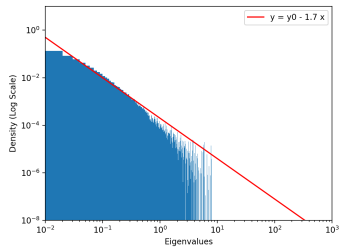

Figure 2: Power power law observed in ResNet-18 on ImageNet, both eigenvalue (x-axis) and density (y-axis) are plotted in log scale.

Corollary 2. *Given the same setting as in Theorem 1, when Hessian H's eigenvalue distribution $p(\lambda)$ satisfies "power power law", i.e.*

$$p(\lambda) = \frac{1}{Z} \cdot \exp(-\alpha(\ln(\lambda) - \ln(\mu))) = \frac{1}{Z} \cdot \left(\frac{\mu}{\lambda}\right)^\alpha \tag{3.7}$$

for some $\alpha > 1$, where $Z = \int_\mu^L (\mu/\lambda)^\alpha d\lambda$, there exists a constant $C(\alpha)$ which only depends on α, such that the final iterate w_{T+1} satisfies

$$\mathbb{E}\left[f(w_{T+1}) - f(w_*)\right] \leq \left((f(w_0) - f(w_*)) \cdot \frac{\kappa^2}{T^2} + \frac{d\sigma^2}{T}\right) \cdot C(\alpha).$$

Please refer to Appendix G.3 for the proof. As for the worst-case guarantee, it is easy to check that only when s_i's are equal to each other, that is, $s_i = d/I_{\max} = d/\log_2(\kappa)$, the variance term reaches its maximum.

Corollary 3. *Given the same setting as in Theorem 1, when $s_i = d/\log_2(\kappa)$ for all $0 \leq i \leq I_{\max} - 1$, the variance term in Theorem 1 reaches its maximum and w_{T+1} satisfies*

$$\mathbb{E}\left[f(w_{T+1}) - f(w_*)\right] \leq (f(w_0) - f(w_*)) \cdot \frac{\kappa^2 \log^2 \kappa}{T^2} + \frac{15d \cdot \log \kappa}{T} \sigma^2.$$

Remark 2. *When s_i's vary from each other, our eigenvalue dependent learning rate scheduler can achieve faster convergence rate than eigenvalue independent scheduler such as step decay which suffers from an extra $log(T)$ term (Ge et al., 2019). Only when s_i's are equal to each other, Corollary 3 shows that the bound of variance matches to lower bound up to $\log \kappa$ which is same to the one in Proposition 3 of Ge et al. (2019).*

Furthermore, we show that this $\log T$ gap between step decay and `eigencurve` certainly exists for problem instances of skewed Hessian spectrums. For simplicity, we only discuss the case where H is diagonal.

Theorem 4. *Let objective function $f(x)$ be quadratic. We run SGD for T-steps starting from w_0 and a step decay learning rate sequence $\{\eta_t\}_{t=1}^T$ defined in Algorithm 1 of Ge et al. (2019) with $\eta_1 = 1/L$. As long as **(1)** H is diagonal, **(2)** The equality in Assumption* (1.7) *holds, i.e. $\mathbb{E}_\xi \left[n_t n_t^\top\right] = \sigma^2 H$ and **(3)** $T/\log T \geq \max(\kappa, 2^{16}, 16)$, the final iterate w_{T+1} satisfies,*

$$\mathbb{E}\left[f(w_{T+1}) - f(w_*)\right] = \Omega\left(\frac{d\sigma^2}{T} \cdot \log T\right)$$

The proof is provided in Appendix G.4. Removing this extra $\log T$ term may not seem to be a big deal in theory, but experimental results suggest the opposite.

4 EXPERIMENTS

To demonstrate `eigencurve` 's practical value, empirical experiments are conducted on the task of image classification [1]. Two well-known dataset are used: CIFAR-10 (Krizhevsky et al., 2009) and ImageNet (Deng et al., 2009). For full experimental results on more datasets, please refer to Appendix A.

4.1 HESSIAN SPECTRUM'S SKEWNESS IN PRACTICE

According to estimated[2] eigenvalue distributions of Hessian on CIFAR-10 and ImageNet, as shown in Figure 3, it can be observed that all of them are highly skewed and share a similar tendency: *A large portion of small eigenvalues and a tiny portion of large eigenvalues*. This phenomenon has also been observed and explained by other researchers in the past(Sagun et al., 2017; Arjevani & Field, 2020). On top of that, when we plot both eigenvalues and density in log scale, the "power power law" arises. Therefore, if the loss surface can be approximated by quadratic objectives, then `eigencurve` has already achieved optimal convergence rate for those practical settings. The exact values of the extra constant terms are presented in Appendix A.2.

4.2 IMAGE CLASSIFICATION ON CIFAR-10 WITH EIGENCURVE SCHEDULING

This optimality in theory induces `eigencurve` 's superior performance in practice, which is demonstrated in Table 2 and Figure 4. The full set of figures are available in Appendix A.7. All models are trained with stochastic gradient descent (SGD), no momentum, batch size 128 and weight decay $wd = 0.0005$. For full details of the experiment setup, please refer to Appendix B.

4.3 INSPIRED PRACTICAL SCHEDULES WITH SIMPLE FORMS

By simplifying the form of `eigencurve` and capturing some of its key properties, two simple and practical schedules are proposed: Elastic Step Decay and Cosine-power Decay, whose empirical performance are better than or at least comparable to cosine decay. Due to page limit, we leave all the experimental results in Appendix A.4, A.5, A.6.

$$\text{Elastic Step Decay: } \eta_t = \eta_0/2^k \text{ , if } t \in \left[(1-r^k)T, (1-r^{k+1})T\right) \tag{4.1}$$

$$\text{Cosine-power Decay: } \eta_t = \eta_{\min} + (\eta_0 - \eta_{\min})\left[\frac{1}{2}(1+\cos(\frac{t}{t_{\max}}\pi))\right]^\alpha \tag{4.2}$$

[1]Code: `https://github.com/opensource12345678/why_cosine_works/tree/main`

[2]Please refer to Appendix B.2 for details of the estimation and preprocessing procedure.

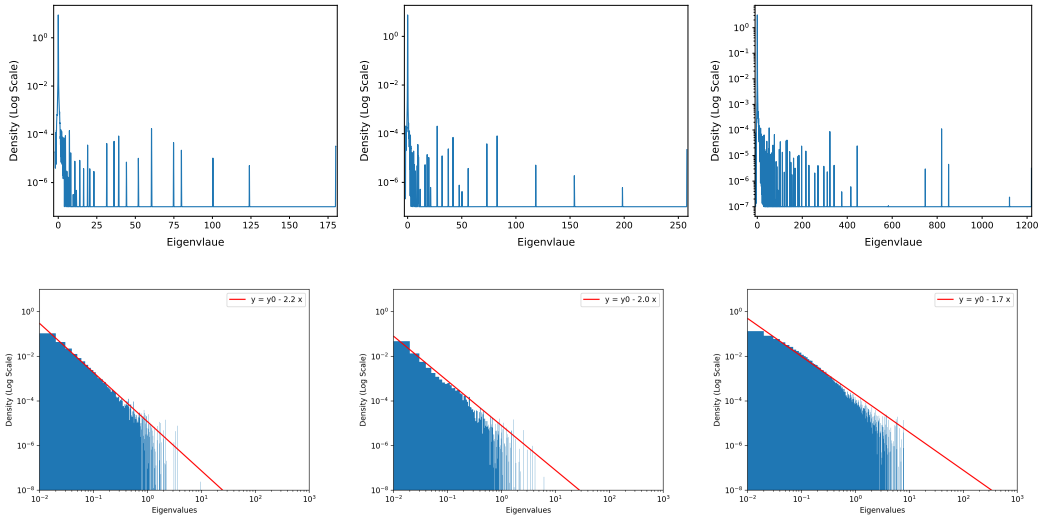

Figure 3: The estimated eigenvalue distribution of Hessian for ResNet-18 on CIFAR-10, GoogLeNet on CIFAR-10 and ResNet-18 on ImageNet respectively. Notice that the density here is all shown in log scale. First row: original scale for eigenvalues. Second row: log scale for preprocessed eigenvalues.

Table 2: CIFAR-10: training losses and test accuracy of different schedules. Step Decay denotes the scheduler proposed in Ge et al. (2019) and General Step Decay means the same type of scheduler with searched interval numbers and decay rates. "*" before a number means at least one occurrence of loss explosion among all 5 trial experiments.

#Epoch	Schedule	ResNet-18		GoogLeNet		VGG16	
		Loss	Acc(%)	Loss	Acc(%)	Loss	Acc(%)
=10	Inverse Time Decay	1.58±0.02	79.45±1.00	2.61±0.00	86.54±0.94	2.26±0.00	84.47±0.74
	Step Decay	1.82±0.04	73.77±1.48	2.59±0.02	87.04±0.48	2.42±0.45	82.98±0.27
	General Step Decay	1.52±0.02	81.99±0.35	1.93±0.03	88.32±1.32	2.14±0.42	86.79±0.36
	Cosine decay	1.42±0.01	84.23±0.07	1.94±0.00	90.56±0.31	2.03±0.00	87.99±0.13
	`Eigencurve`	**1.36±0.01**	**85.62±0.28**	**1.33±0.00**	**90.65±0.15**	**1.87±0.00**	**88.73±0.11**
=100	Inverse Time Decay	0.73±0.00	90.82±0.43	0.62±0.02	92.05±0.69	1.32±0.62	*76.24±13.77
	Step Decay	0.26±0.01	91.39±1.03	0.28±0.00	92.83±0.15	0.59±0.00	91.37±0.20
	General Step Decay	0.17±0.00	93.97±0.21	0.13±0.00	94.18±0.18	0.20±0.00	*92.36±0.46
	Cosine Decay	0.17±0.00	94.04±0.21	0.12±0.00	94.62±0.11	0.20±0.00	**93.17±0.05**
	`Eigencurve`	**0.14±0.00**	**94.05±0.18**	**0.12±0.00**	**94.75±0.15**	**0.18±0.00**	92.88±0.24

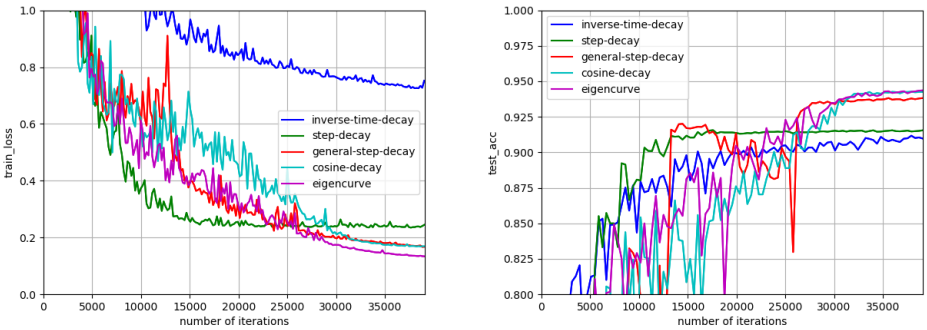

Figure 4: Example: CIFAR-10 results for ResNet-18, with #Epoch = 100. Left: training losses. Right: test accuracy. For full figures of this experiment, please refer to Appendix A.7.

5 DISCUSSION

Cosine Decay and Eigencurve For ResNet-18 on CIFAR-10 dataset, `eigencurve` scheduler presents an extremely similar learning rate curve to cosine decay, especially when the number of training epochs is set to 100, as shown in Figure 5. This directly links cosine decay to our theory: the empirically superior performance of cosine decay is very likely to stem from the utilization of the "skewness" among Hessian matrix's eigenvalues. For other situations, especially when the number of iterations is small, as shown in Table 2, `eigencurve` presents a better performance than cosine decay .

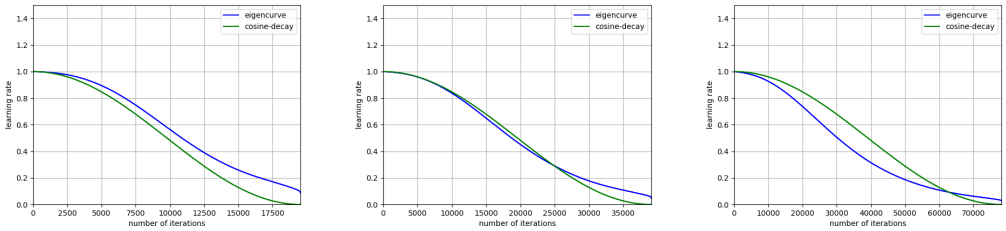

Figure 5: `Eigencurve` 's learning rate curve generated by the estimated eigenvalue distribution for ResNet-18 on CIFAR-18 after training 50/100/200 epochs. The cosine decay's learning rate curve (green) is also provided for comparison.

Sensitiveness to Hessian's Eigenvalue Distributions One limitation of `eigencurve` is that it requires a precomputed eigenvalue distribution of objective functions's Hessian matrix, which can be time-consuming for large models. This issue can be overcome by reusing the estimated eigenvalue distribution from similar settings. Further experiments on CIFAR-10 suggest the effectiveness of this approach. Please refer to Appendix A.3 for more details. This evidence suggests that `eigencurve`'s performance is not very sensitive to estimated eigenvalue distributions.

Relationship with Numerically Near-optimal Schedulers In Zhang et al. (2019), a dynamic programming algorithm was proposed to find almost optimal schedulers if the exact loss of the quadratic objective is accessible. While it is certainly the case, `eigencurve` still possesses several additional advantages over this type of approaches. First, `eigencurve` can be used to find simple-formed schedulers. Compared with schedulers numerically computed by dynamic programming, `eigencurve` provides an analytic framework, so it is able to bypass the Hessian spectrum estimation process if some useful assumptions of the Hessian spectrum can be obtained, such as "power power law". Second, `eigencurve` has a clear theoretical convergence guarantee. Dynamic programming can find almost optimal schedulers, but the convergence property of the computed scheduler is still unclear. Our work fills this gap.

6 CONCLUSION

In this paper, a novel learning rate schedule named `eigencurve` is proposed, which utilizes the "skewness" of objective's Hessian matrix's eigenvalue distribution and reaches minimax optimal convergence rates for SGD on quadratic objectives with skewed Hessian spectrums. This condition of skewed Hessian spectrums is observed and indeed satisfied in practical settings of image classification. Theoretically, `eigencurve` achieves no worse convergence guarantee than step decay for quadratic functions and reaches minimax optimal convergence rate (up to a constant) with skewed Hessian spectrums, e.g. under "power power law". Empirically, experimental results on CIFAR-10 show that `eigencurve` significantly outperforms step decay, especially when the number of epochs is small. The idea of `eigencurve` offers a possible explanation for cosine decay's effectiveness in practice and inspires two practical families of schedules with simple forms.

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A MORE EXPERIMENTAL RESULTS

A.1 RIDGE REGRESSION

We compare different types of schedulings on ridge regression

$$f(w) = \frac{1}{n}||Xw - Y||_2^2 + \alpha||w||_2^2.$$

This experiment is only an empirical proof of our theory. In fact, the optima of ridge regression has a closed form and can be directly computed with

$$w_* = \left(X^\top X + n\alpha I\right)^{-1} X^T Y.$$

Thus the optimal training loss $f(w_*)$ can be calculated accordingly. In all experiments, we use the loss gap $f(w^T) - f(w_*)$ as our performance metric.

Experiments are conducted on a4a datasets (Chang & Lin, 2011; Dua & Graff, 2017) (`https://www.csie.ntu.edu.tw/~cjlin/libsvmtools/datasets/binary.html#a4a/`), which contains $4,781$ samples and 123 features. This dataset is chosen majorly because it has a moderate number of samples and features, which enables us to compute the exact Hessian matrix $H = 2(X^\top X/n + \alpha I)$ and its corresponding eigenvalue distribution in acceptable time and space consumption.

In all of our experiments, we set $\alpha = 10^{-3}$. The model is optimized via SGD without momentum, with batch size 1, initial learning rate $\eta_0 \in \{0.1, 0.06, 0.03, 0.02, 0.01, 0.006, 0.003, 0.002, 0.001, 0.0006, 0.0003, 0.0002, 0.0001\}$ and learning rate of last iteration $\eta_{\min} \in \{0.1, 0.01, 0.001, 0.0001, 0.00001, 0,$ "UNRESTRICTED"$\}$. Here "UNRESTRICTED" denotes the case where $\eta_{\min}$ is not set, which is useful for `eigencurve`, who can decide the learning rate curve without setting $\eta_{\min}$. Given η_0 and $\eta_{\min}$, we adjust all schedulers as follows. For inverse time decay $\eta_t = \eta_0/(1 + \gamma\eta_0 t)$ and exponential decay $\eta_t = \gamma^t \eta_0$, the hyperparameter γ is computed accordingly based on η_0 and $\eta_{\min}$. For cosine decay, η_0 and $\eta_{\min}$ is directly used, with no restart adopted. For `eigencurve`, the learning rate curve is linearly scaled to match the given $\eta_{\min}$.

In addition, for `eigencurve`, we use the eigenvalue distribution of the Hessian matrix, which is directly computed via eigenvalue decomposition, as shown in Figure 6.

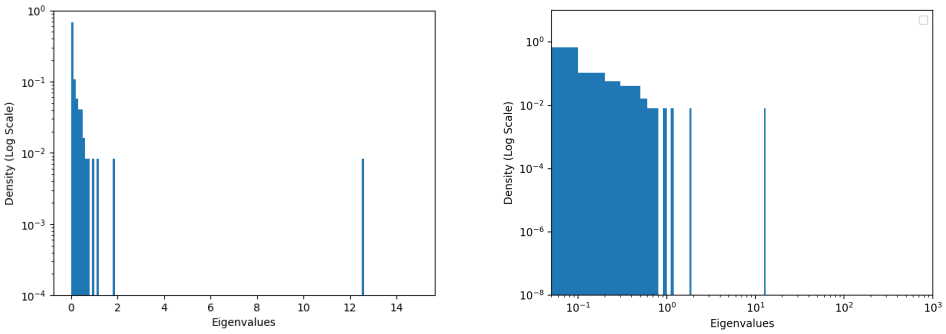

Figure 6: The eigenvalue distribution of Hessian for ridge regression on a4a. Left: original scale for eigenvalues. Right: log scale for eigenvalues. Notice that the density here is shown in log scale.

All experimental results demonstrate that `eigencurve` can obtain similar or better training losses when compared with other schedulers, as shown in Table 3.

Table 3: Ridge regression: training loss gaps of different schedules

	Training loss - optimal training loss: $f(w^T) - f(w_*)$			
Schedule	#Epoch = 1	#Epoch = 5	#Epoch = 25	#Epoch = 250
Constant	0.012230	0.004781	0.001509	0.000129
Inverse Time Decay	0.009152	0.002106	0.000777	0.000012
Exponetial Decay	0.008422	0.000792	0.000051	**0.000000**
Cosine Decay	0.008724	0.000972	0.000052	**0.000000**
`Eigencurve`	**0.008278**	**0.000540**	**0.000045**	**0.000000**

A.2 Exact Value of the Extra Term on CIFAR-10 Experiments

In Section 4.1, we have already given the qualitative evidence that shows `eigencurve` 's optimality for practical settings on CIFAR-10. Here we strengthen this argument by providing the quantitative evidence as well. The exact value of the extra term is presented in Table 4, where we assume CIFAR-10 has batch size 128, number of epochs 200 and weight decay 5×10^{-4}, while ImageNet has batch size 256, number of epochs 90 and weight decay 10^{-4}.

Table 4: Convergence rate of SGD with common schedulers given the estimated eigenvalue distribution of Hessian, assuming the objective is quadratic.

		Value of the extra term			
Scheduler	Convergence rate of SGD in quadratic functions	CIFAR-10 + ResNet18	CIFAR-10 + GoogLeNet	CIFAR-10 + VGG16	ImageNet + ResNet18
Inverse Time Decay	$\Theta\left(\frac{d\sigma^2}{T} \cdot \kappa\right)$	3.39×10^5	4.92×10^5	6.50×10^5	6.80×10^6
Step Decay	$\Theta\left(\frac{d\sigma^2}{T} \cdot \log T\right)$	16.25	16.25	16.25	18.78
`Eigencurve`	$\mathcal{O}\left(\frac{d\sigma^2}{T} \cdot \frac{\left(\sum_{i=0}^{I_{\max}-1} \sqrt{s_i}\right)^2}{d}\right)$ where $I_{\max} = \log_2 \kappa$, $s_i = \#\lambda_j \in [\mu \cdot 2^i, \mu \cdot 2^{i+1})$	**8.15**	**5.97**	**7.12**	**12.61**
Minimax optimal rate	$\Omega\left(\frac{d\sigma^2}{T}\right)$	1	1	1	1

It is worth noticing that the extra term's value of `eigencurve` is independent from the number of iterations T, since the value $(\sum_{i=0}^{I_{\max}-1} \sqrt{s_i})^2/d$ only depends on the Hessian spectrum. So basically `eigencurve` has already achieved the minimax optimal rate (up to a constant) for models and datasets listed in Table 4, if the loss landscape around the optima can be approximated by quadratic functions. For full details of the estimation process, please refer to Appendix B.

A.3 Reusing `eigencurve` for Different Models on CIFAR-10

For image classification tasks on CIFAR-10, we check the performance of reusing ResNet-18's eigenvalue distribution for other models. As shown in Table 5, experimental results demonstrate that Hessian's eigenvalue distribution of Resnet-18 on CIFAR-10 can be applied to GoogLeNet/VGG16 and still achieves good peformance. Here the experiment settings are exactly the same as Section 4.2 in main paper, except we only run one trial of experiment and use common step decay with three intervals + decay factor 10.

Table 5: CIFAR-10: training losses and test accuracy of different schedules. Here all `eigencurve` schedules are generated based on ResNet-18's Hessian spectrums

#Epoch	Schedule	GoogLeNet		VGG16	
		Loss	Acc	Loss	Acc
=10	Inverse Time Decay	2.6162	85.16%	2.2722	84.94%
	Step Decay	2.5572	88.57%	2.2535	85.16%
	Cosine Decay	1.9400	90.25%	2.0328	87.72%
	`Eigencurve` based on ResNet-18's Hessian spectrum	**1.6439**	**91.37%**	**1.8971**	**87.94%**
=100	Inverse Time Decay	0.6821	91.86%	0.6085	89.82%
	Step Decay	0.1669	94.07%	0.2334	92.81%
	Cosine Decay	0.1215	94.33%	0.2016	**93.21%**
	`Eigencurve` based on ResNet-18's Hessian spectrums	**0.1105**	**94.84%**	**0.2012**	**93.21%**

A.4 IMAGENET CLASSIFICATION WITH ELASTIC STEP DECAY

One key observation in CIFAR-10 experiments is the existence of "power power law" shown in Figure 3. Also, notice that in the form of `eigencurve` , specifically Eqn. (3.5), iteration interval length Δ_i is proportional to the square root of eigenvalue density s_i in range $[\mu \cdot 2^i, \mu \cdot 2^{i+1})$. Combining those two facts together, it suggests the length of "learning rate interval" should have lengths exponentially decreasing.

Based on this idea, Elastic Step Decay (ESD) is proposed, which has the following form,

$$\eta_t = \eta_0/2^k \text{ , if } t \in \big[(1-r^k)T, (1-r^{k+1})T\big)$$

Compared to general step decay with adjustable interval lengths, elastic step decay does not require manual adjustment for the length of each interval. Instead, they are all controlled by one hyper-parameter $r \in (0, 1)$, which decides the "shrinking speed" of interval lengths. Experiments on CIFAR-10, CIFAR-100 and ImageNet demonstrate its superiority in practice, as shown in Table 6, Table 7.

For experiments on CIFAR-10/CIFAR-100, we adopt the same settings as `eigencurve` , except we only run one trial of experiment and use common step decay with three intervals + decay factor 10. For experiments on ImageNet, we use ResNet-50 trained via SGD without momentum, batch size 256 and weight decay $wd = 10^{-4}$. Since no momentum is used, the initial learning rate is set to $\eta_0 = 1.0$ instead of $\eta_0 = 0.1$. The hyperparameters $\eta_{\min}$ is set to be 0 for cosine decay scheduler. As for the dataset, we use the common ILSVRC 2012 dataset, which contains 1000 classes, around 1.2M images for training and 50,000 images for validation. For all experiments, we search $r \in \{1/2, 1/\sqrt{2}\}$ for ESD, with other hyperparameter search and selection process being the same as `eigencurve` .

Table 6: Elastic Step Decay on CIFAR-10/CIFAR-100: test accuracy of different schedules.

#Epoch	Schedule	ResNet-18		GoogLeNet		VGG16	
		CIFAR-10	CIFAR-100	CIFAR-10	CIFAR-100	CIFAR-10	CIFAR-100
=10	Inverse Time Decay	79.22%	49.18%	85.16%	58.91%	84.94%	50.30%
	Step Decay	81.07%	53.96%	88.57%	63.21%	85.16%	46.96%
	Cosine Decay	84.58%	61.96%	90.25%	69.07%	87.72%	55.33%
	ESD	**86.25%**	**64.77%**	**91.30%**	**70.51%**	**88.72%**	**57.50%**
=100	Inverse Time Decay	90.97%	69.66%	91.86%	73.51%	89.82%	68.06%
	Step Decay	93.39%	74.06%	94.07%	77.86%	92.81%	70.05%
	Cosine Decay	93.94%	74.87%	94.33%	78.45%	93.21%	72.06%
	ESD	**94.44%**	**75.18%**	**94.84%**	**78.50%**	**93.25%**	**72.43%**

Table 7: Elastic Step Decay on ImageNet-1k: Losses and validation accuracy of different schedulings for ResNet-50 with #Epoch=90.

	Schedule	Training loss	Top-1 validation acc	Top-5 validation acc
#Epoch=90	Cosine decay	1.4712	76.67%	93.28%
	ESD ($r = 1/\sqrt{2}$)	**1.4291**	**76.93%**	**93.32%**

A.5 Language Modeling with Elastic Step Decay

More experiments on language modeling are conducted to further demonstrate Elastic Step Decay's superiority over other schedulers.

For all experiments, we follow almost the same setting in Zaremba et al. (2015), where a large regularized LSTM recurrent neural network (Hochreiter & Schmidhuber, 1997) is trained on Penn Treebank (Marcus et al., 1993) for language modeling task. The Penn Treebank dataset has a training set of 929k words, a validation set of 73k words and a test set of 82k words. SGD without momentum is adopted for training, with batch size 20 and 35 unrolling steps in LSTM.

Other details are exactly the same, except for the number of training epochs. In Zaremba et al. (2015), it uses 55 epochs to train the large regularized LSTM, which is changed to 30 epochs in our setting, since we found that the model starts overfitting after 30 epochs. We conducted hyperparameter search for all schedules, as shown in Table 8.

Table 8: Hyperparameter search for schedulers.

Scheduler	Form	Hyperparameter choices
Inverse Time Decay	$\eta_t = \frac{\eta_0}{1+\lambda\cdot\eta_0\cdot t}$	$\eta_0 \in \{10^0, 10^{-1}, 10^{-2}, 10^{-3}\}$, and set λ, so that $\eta_{\min} \in \{10^{-2}, 10^{-3}, 10^{-4}, 10^{-5}, 10^{-6}\}$
General Step Decay	$\eta_t = \eta_0 \cdot \gamma^k$, if $t \in [k, k+1) \cdot \frac{T}{K}$	$\eta_0 = 1$, $K \in \{3, 4, 5, \lfloor \log T \rfloor\}, \lfloor \log T \rfloor + 1\}$, $\gamma \in \{\frac{1}{2}, \frac{1}{5}, \frac{1}{10}\}$
Cosine Decay	$\eta_t = \eta_{\min} + \frac{1}{2}(\eta_0 - \eta_{\min})\left(1 + \cos\left(\frac{t\pi}{T}\right)\right)$	$\eta_0 \in \{10^0, 10^{-1}, 10^{-2}, 10^{-3}\}$, $\eta_{\min} \in \{10^{-2}, 10^{-3}, 10^{-4}, 0\}$
Elastic Step Decay	$\eta_t = \eta_0/2^k$, if $t \in \left[(1-r^k)T, (1-r^{k+1})T\right)$	$\eta_0 = 1$, $r \in \{2^{-1}, 2^{-1/2}, 2^{-1/3}, 2^{-1/5}, 2^{-1/20}\}$,
Baseline	$\eta_t = \begin{cases} \eta_0 & \text{for first 14 epochs} \\ \frac{\eta_0}{1.15^k} & \text{for epoch } k+14 \end{cases}$	$\eta_0 = 1$

Experimental results show that Elastic Step Decay significantly outperforms other schedulers, as shown in Table 9.

Table 9: Scheduler performance on LSTM + Penn Treebank over 5 trials.

Scheduler	Validation perplexity	Test perplexity
Inverse Time Decay	114.9±1.1	112.7±1.1
General Step Decay	82.4±0.1	79.1±0.2
Baseline (Zaremba et al., 2015)	82.2	78.4
Cosine Decay	82.4±0.4	78.5±0.4
Elastic Step Decay	**81.1±0.2**	**77.4±0.3**

A.6 IMAGE CLASSIFICATION ON IMAGENET WITH COSINE-POWER SCHEDULING

Another key observation in CIFAR-10 experiments is that `eigencurve` 's learning rate curve shape changes in a fixed tendency: *more "concave" learning rate curves for less training epochs*, which inspire the cosine-power schedule in following form.

$$\text{Cosine-power}: \eta_t = \eta_{\min} + (\eta_0 - \eta_{\min}) \left[\frac{1}{2}(1 + \cos(\frac{t}{t_{\max}}\pi)) \right]^{\alpha}$$

Results in Table 10 show the schedulings' performance with $\alpha = 0.5/1/2$, which are denoted as $\sqrt{\text{Cosine}}$/Cosine/Cosine^2 respectively. Notice that the best scheduler gradually moves from small α to larger α when the number of epochs increases. For #epoch=270, since the number of epochs is large enough to make model converge, it is reasonable that the accuracy gap between all schedulers is small.

For experiments on ImageNet, we use ResNet-18 trained via SGD without momentum, batch size 256 and weight decay $wd = 10^{-4}$. Since no momentum is used, the initial learning rate is set to $\eta_0 = 1.0$ instead of $\eta_0 = 0.1$. The hyperparameters $\eta_{\min}$ is set to be 0 for all cosine-power scheduler. As for the dataset, we use the common ILSVRC 2012 dataset, which contains 1000 classes, around 1.2M images for training and 50,000 images for validation.

Table 10: Cosine-power Decay on ImageNet: training losses and validation accuracy of different schedulings for ResNet-18.

#Epoch	Schedule	Training loss	Top-1 validation acc	Top-5 validation acc
1	**$\sqrt{\text{Cosine}}$**	**5.4007**	**30.18%**	**55.25%**
	Cosine	5.4436	26.21%	50.24%
	Cosine^2	5.4901	21.77%	44.49%
5	**$\sqrt{\text{Cosine}}$**	2.9637	**56.96%**	**80.54%**
	Cosine	**2.8308**	55.93%	79.68%
	Cosine^2	2.9248	52.38%	77.00%
30	$\sqrt{\text{Cosine}}$	2.1732	67.59%	87.89%
	Cosine	**2.0437**	**67.69%**	**88.08%**
	Cosine^2	2.0517	67.50%	87.78%
90	$\sqrt{\text{Cosine}}$	1.9056	69.85%	89.46%
	Cosine	1.7676	**70.46%**	**89.75%**
	Cosine^2	**1.7403**	70.42%	89.69%
270	$\sqrt{\text{Cosine}}$	1.7178	71.37%	90.31%
	Cosine	1.5756	**71.93%**	90.33%
	Cosine^2	**1.5250**	71.69%	**90.37%**

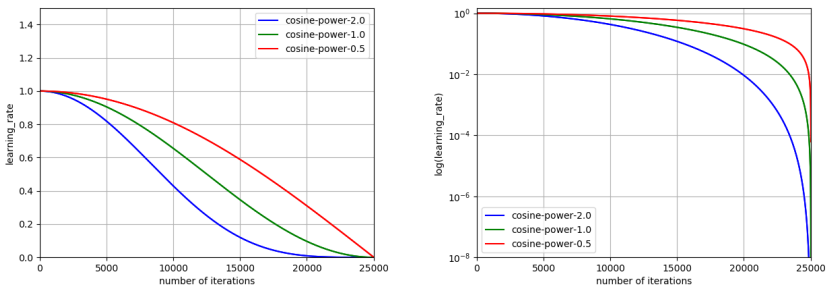

Figure 7: Learning rate curve of three cosine-power schedulers. Top: original scale; Bottom: log scale.

A.7 FULL FIGURES FOR EIGENCURVE EXPERIMENTS IN SECTION 4.2

Please refer to Figure 8, 9, 10, 11, 12 and 13.

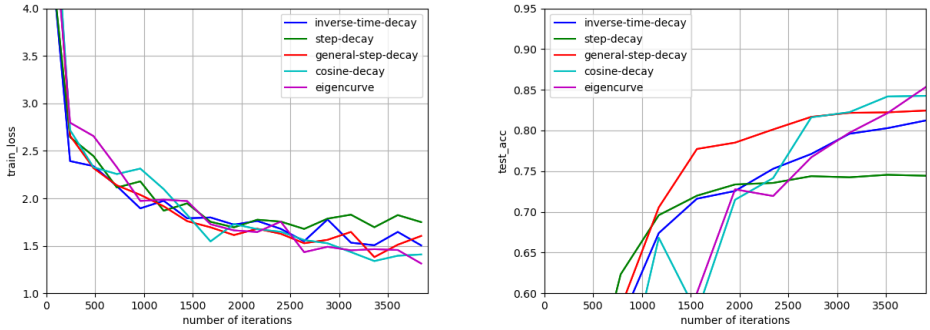

Figure 8: CIFAR-10 results for ResNet-18, with #Epoch = 10. Left: training losses. Right: test accuracy.

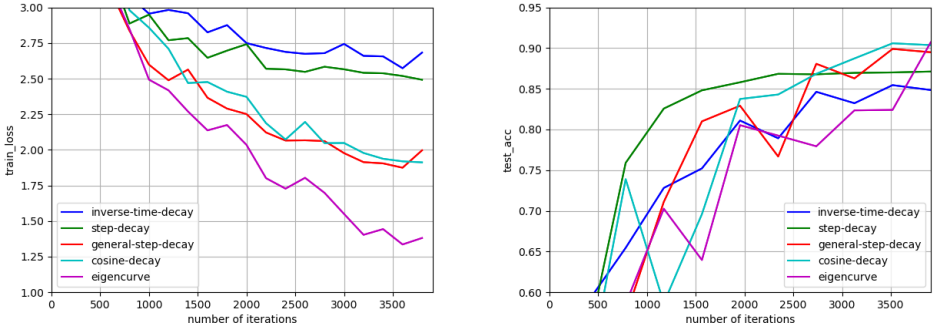

Figure 9: CIFAR-10 results for GoogLeNet, with #Epoch = 10. Left: training losses. Right: test accuracy.

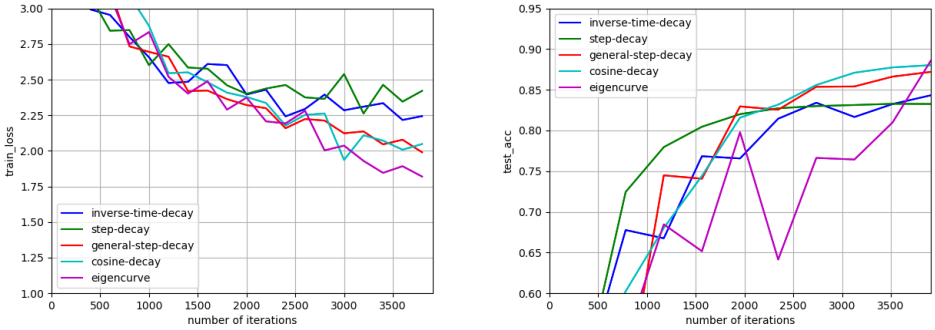

Figure 10: CIFAR-10 results for VGG16, with #Epoch = 10. Left: training losses. Right: test accuracy.

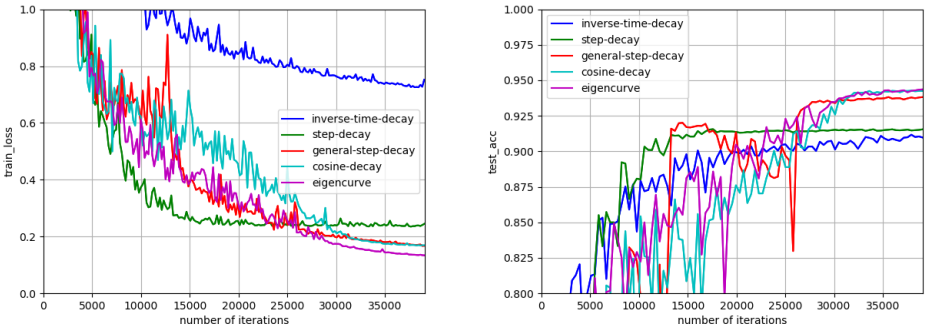

Figure 11: CIFAR-10 results for ResNet-18, with #Epoch = 100. Left: training losses. Right: test accuracy.

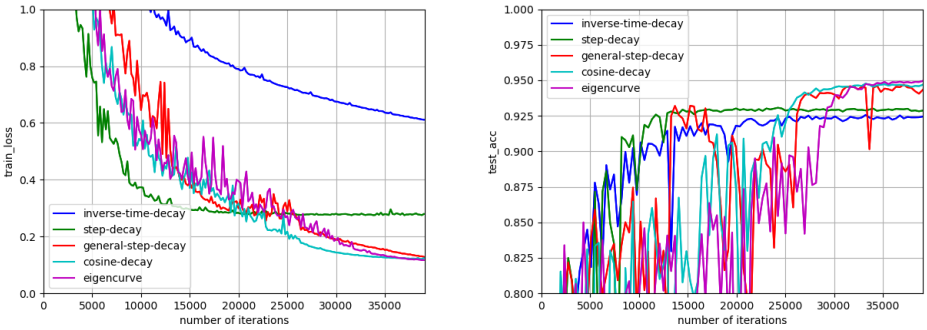

Figure 12: CIFAR-10 results for GoogLeNet, with #Epoch = 100. Left: training losses. Right: test accuracy.

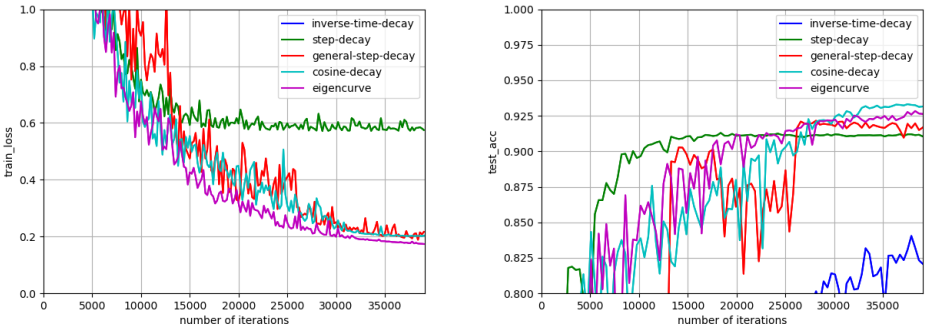

Figure 13: CIFAR-10 results for VGG16, with #Epoch = 100. Left: training losses. Right: test accuracy.

B Detailed Experimental Settings for Image Classification on CIFAR-10/CIFAR-100

B.1 Basic Settings

As mentioned in the main paper, all models are trained with stochastic gradient descent (SGD), no momentum, batch size 128 and weight decay $wd = 0.0005$. Furthermore, we perform a grid search to choose the best hyperparameters of all schedulers, with a validation set created from $5,000$

samples in the training set, i.e. one-tenth of the training set. The remaining $45,000$ samples are then used for training the model. After obtaining hyperparameters with the best validation accuracy, we train the model again with the full training set and test the trained model on test set, where 5 trials of experiments are conducted with different random seeds. The mean and standard deviation of the test results are reported.

Here the grid search explores hyperparameters $\eta_0 \in \{1.0, 0.6, 0.3, 0.2, 0.1\}$ and $\eta_{\min} \in \{0.01, 0.001, 0.0001, 0, \text{“UNRESTRICTED”}\}$, where η_0 denotes the initial learning rate and $\eta_{\min}$ stands for the learning rate of last iteration. “UNRESTRICTED” denotes the case where $\eta_{\min}$ is not set, which is useful for `eigencurve`, who can decide the learning rate curve without setting $\eta_{\min}$. Given η_0 and $\eta_{\min}$, we adjust all schedulers as follows. For inverse time decay, the hyperparameter γ is computed accordingly based on η_0 and $\eta_{\min}$. For cosine decay, η_0 and $\eta_{\min}$ is directly used, with no restart adopted. For general step decay, we search the interval number in $\{3, 4, 5, \lfloor \log T \rfloor, \lfloor \log T \rfloor + 1\}$ and decay factor in $\{2, 5, 10\}$. For step decay proposed in Ge et al. (2019), the interval number is fixed to be $\lfloor \log T \rfloor$, along with a decay factor 2. For `eigencurve`, two major modifications are made to make it more suitable for practical settings:

$$\eta_t = \frac{1/L}{1 + \frac{1}{\kappa}\sum_{j=1}^{i-1} \Delta_j 2^{j-1} + \frac{2^{i-1}}{\kappa}(t - t_{i-1})} = \frac{\boldsymbol{\eta_0}}{1 + \frac{1}{\kappa}\sum_{j=1}^{i-1} \Delta_j \boldsymbol{\beta}^{j-1} + \frac{\boldsymbol{\beta}^{i-1}}{\kappa}(t - t_{i-1})}.$$

Here we change $1/L$ to η_0 so that it is possible to adjust the initial learning rate of `eigencurve`. We also change the fixed constant 2 to a general constant $\beta > 1$, which is aimed at making the learning rate curve smoother. The learning rate curve of `eigencurve` is then linearly scaled to match the given $\eta_{\min}$.

Notice that the learning rate η_0 can be larger than $1/L$, while the loss still does not explode. There are several explanations for this phenomenon. First, in basic non-smooth analysis of GD and SGD with inverse time decay scheduler, the learning rate can be larger than $1/L$ if the gradient norm is bounded (Shamir & Zhang, 2012). Second, deep learning has a non-convex loss landscape, especially when the parameter is far away from the optima. Hence it is common to use larger learning rate at first. As long as the loss does not explode, it is okay. So we still include large learning rate η_0 in our grid search process.

B.2 Settings for Eigencurve

In addition, for our `eigencurve` scheduler, we use PyHessian (Yao et al., 2020) to generate Hessian matrix's eigenvalue distribution for all models. The whole process consists of three phases, which are illustrated as follows.

1) Training the model Almost all CNN models on CIFAR-10 have non-convex objectives, thus the Hessian's eigenvalue distributions are different for different parameters. Normally, we want the this distribution to reflect the overall tendency of most parts of the training process. According to the phenomenon demonstrated in Appendix E, figure A.11-A.17 of Yao et al. (2020), the eigenvalue distribution of ResNet's Hessian presents similar tendency after training 30 epochs, which suggests that the Hessian's eigenvalue distribution can be used after sufficient training.

In all CIFAR-10 experiments, we use the Hessian's eigenvalue distribution of models after training 180 epochs. Since the goal here is to sufficiently train the model, not to obtain good performance, common baseline settings are adopted for training. For all models used for eigenvalue distribution estimation, we adopt SGD with momentum $= 0.9$, batch size 128, weight decay $wd = 0.0005$ and initial learning rate 0.1. On top of that, we use step decay, which decays the learning rate by a factor of 10 at epoch 80 and 120. All of them are default settings of the PyHessian code (`https://github.com/amirgholami/PyHessian/blob/master/training.py`, commit: f4c3f77).

ImageNet adopts a similar setting, with training epochs being 90, SGD with momentum $= 0.9$, batch size 256, weight decay $wd = 0.0001$, inital learning rate 0.1 and step decay schedule decays learning rate by a factor of 10 at epoch 30 and 60.

2) Estimating Hessian matrix's eigenvalue distribution for the trained model After obtaining the checkpoint of a sufficiently trained model, we then run PyHessian to estimate the Hessian's

eigenvalue distribution for that checkpoint. The goal here is to obtain the Hessian's eigenvalue distribution with sufficient precision. To be more specific, the length of intervals around each estimated eigenvalue. PyHessian estimates the eigenvalue spectral density (ESD) of a model's Hessian, in other words, the output is a list of eigenvalue intervals, along with the density of each interval, where the whole density adds up to 1. Precision means the interval length here.

It is natural that the estimation precision is related to the complexity of the PyHessian algorithm, e.g. the better precision it yields, the more time and space it consumes. More specifically, the algorithm has a time complexity of $\mathcal{O}(Nn_v^2 d)$ and space complexity $\mathcal{O}(Bd + n_v d)$, where d is the number of model parameters, N is the number of samples used for estimating the ESD, B is the batch size and n_v is the iteration number of Stochastic Lanczos Quadrature used in PyHessian, which controls the estimation precision (see Algorithm 1 of Yao et al. (2020)).

In our experiments, we use $n_v = 5000$ for ResNet-18 and $n_v = 3000$ for GoogLeNet/VGG16, which gives an eigenvalue distribution estimation with precision around 10^{-5} to 10^{-4}. N and B are both set to 200 due to GPU memory constraint, i.e. we use one mini-batch to estimate the eigenvalue distribution. It turns out that this one-batch estimation is good enough and yields similar results to full dataset settings shown in Yao et al. (2020).

However, space complexity is still a bottleneck here. Due to the large number of n_v and space complexity $\mathcal{O}(Bd + n_v d)$ of PyHessian, the value of d cannot be very large. In practice, with a NVIDIA GeForce 2080 Ti GPU, which has around 11GB memory, the maximum acceptable parameter number d is around $200K - 400K$. This implies that the model has to be compressed. In our experiments, we reduce the number of channels by a factor of C for all models. For ResNet-18, $C = 16$. For GoogLeNet, $C = 4$. For VGG16, $C = 8$. Notice that those compressed models are only used for eigenvalue distribution estimation. In experiments of comparing different scheduling, we still use the original model with no compression.

One may refer to `https://github.com/opensource12345678/why_cosine_works/tree/main/eigenvalue_distribution` for generated eigenvalue distributions.

3) Generating `eigencurve` scheduler with the estimated eigenvalue distribution After obtaining the eigenvalue distribution, we do a preprocessing before plug it into our `eigencurve` scheduler.

First, we notice that there are negative eigenvalues in the final distribution. Theoretically, if the parameter is right at the optimal point, no negative eigenvalues should exist for Hessian matrix. Thus we conjecture that those negative eigenvalues are caused by the fact that the model is closed to optima w_*, but not exactly at that point. Furthermore, the estimation precision loss can be another cause. In fact, most of those negative eigenvalues are small, e.g. 98.6% of those negative eigenvalues lie in $[-0.1, 0)$, and can be generally ignored without much loss. In our case, we set them to their absolute values.

Second, for a given weight decay value wd, we need to take the implicit L2 regularization into account, since it affects the Hessian matrix as well. Therefore, for all eigenvalues after the first step, we add wd to them.

After preprocessing, we plug the eigenvalue distribution into our `eigencurve` scheduler and generates the exact form of `eigencurve`.

$$\eta_t = \frac{1/L}{1 + \frac{1}{\kappa}\sum_{j=1}^{i-1} \Delta_j 2^{j-1} + \frac{2^{i-1}}{\kappa}(t - t_{i-1})} = \frac{\boldsymbol{\eta_0}}{1 + \frac{1}{\kappa}\sum_{j=1}^{i-1} \Delta_j \boldsymbol{\beta}^{j-1} + \frac{\boldsymbol{\beta}^{i-1}}{\kappa}(t - t_{i-1})}$$

For experiments with 100 epochs, we set $\beta = 1.000005$, so that the learning rate curve is much smoother. For experiments with 10 epochs, we set $\beta = 2.0$. In our experiments, β serves as a fixed constant, not hyperparameters. So no hyperparameter search is conducted on β. One can do that in practice though, if computation resource allows.

B.3 Compute Resource and Implementation Details

All the code for results in main paper can be found in `https://github.com/opensource12345678/why_cosine_works/tree/main`, which is released under the MIT license.

All experiments on CIFAR-10/CIFAR-100 are conducted on a single NVIDIA GeForce 2080 Ti GPU, where ResNet-18/GoogLeNet/VGG16 takes around 20mins/90mins/40mins to train 100 epochs, respectively. High-precision eigenvalue distribution estimation, e.g. $n_v \geq 3000$, requires around 1-2 days to complete, but this is no longer necessary given the released results.

The ResNet-18 model is implemented in Tensorflow 2.0. We use tensorflow-gpu 2.3.1 in our code. The GoogLeNet and VGG16 model is implemented in Pytorch, specifically, 1.7.0+cu101.

B.4 License of PyHessian

According to `https://github.com/amirgholami/PyHessian/blob/master/LICENSE`, PyHessian (Yao et al., 2020) is released under the MIT License.

C Detailed Experimental Settings for Image Classification on ImageNet

One may refer to `https://www.image-net.org/download` for specific terms of access for ImageNet. The dataset can be downloaded from `https://image-net.org/challenges/LSVRC/2012/2012-downloads.php`, with training set being "Training images (Task 1 & 2)" and validation set being "Validation images (all tasks)". Notice that registration and verification of institute is required for successful download.

All experiments on ImageNet are conducted on two NVIDIA GeForce 2080 Ti GPUs with data parallelism. The ResNet-18 model takes around 2 days to train 90 epochs, about 20mins-30mins per epoch. The ResNet-18 model on ImageNet is implemented in Pytorch, specifically, 1.7.0+cu101.

D Important Propositions and Lemmas

Proposition 3. *Letting $f(x)$ be a monotonically increasing function in the range $[t_0, \tilde{t}]$, then it holds that*

$$\sum_{k=t_0}^{\tilde{t}-1} f(k) \leq \int_{t_0}^{\tilde{t}} f(x)\, dx. \tag{D.1}$$

If $f(x)$ is monotonically decreasing in the range $[t_0, \tilde{t}]$, then it holds that

$$\int_{t_0}^{\tilde{t}} f(x)\, dx \leq \sum_{k=t_0}^{\tilde{t}-1} f(k) \leq \sum_{k=t_0}^{\tilde{t}} f(k) \leq f(t_0) + \int_{t_0}^{\tilde{t}} f(x)\, dx. \tag{D.2}$$

Lemma 2. *Function $f(x) = \exp(-\alpha x)x^2$ with $0 < \alpha$ and $x \in (0, 1]$ is monotone decreasing in the range $x \in (\frac{2}{\alpha}, +\infty)$ and monotone increasing in the range $x \in [0, \frac{2}{\alpha}]$.*

Proof. We can obtain the derivative of $f(x)$ as

$$\nabla f(x) = x \exp(-\alpha x)(2 - \alpha x).$$

Thus, it holds that $\nabla f(x) \geq 0$ when $x \in [0, \frac{2}{\alpha}]$. This implies that $f(x)$ is monotone increasing when $x \in [0, \frac{2}{\alpha}]$. Similarly, we can obtain that $f(x)$ is monotone decreasing when $x \in (\frac{2}{\alpha}, +\infty)$. □

Lemma 3. *It holds that*

$$\int \exp(-\alpha x)x\, dx = -\alpha^{-1}(x \exp(-\alpha x) + \alpha^{-1} \exp(-\alpha x)). \tag{D.3}$$

Proof.

$$\int \exp(-\alpha x)x\ dx = -\alpha^{-1}\int x\ d\exp(-\alpha x) = -\alpha^{-1}(x\exp(-\alpha x) - \int \exp(-\alpha x)dx)$$
$$= -\alpha^{-1}(x\exp(-\alpha x) + \alpha^{-1}\exp(-\alpha x)).$$

□

E PROOF OF SECTION 2

Proof of Proposition 1. By iteratively applying Eqn. (2.1), we can obtain that

$$\begin{aligned}\mathbb{E}\left[\lambda_j\left(w_{t+1,j}-w_{*,j}\right)^2\right] &\overset{(2.1)}{\leq} \prod_{i=1}^{t}(1-\eta_{i,j}\lambda_j)^2\cdot\lambda_j(w_{1,j}-w_{*,j})^2 \\ &\quad + \lambda_j^2\sigma^2\cdot\sum_{k=1}^{t}\prod_{i=k+1}^{t}(1-\eta_{i,j}\lambda_j)^2\eta_{k,j}^2 \\ &= \frac{\lambda_j(w_{1,j}-w_{*,j})^2}{(t+1)^2} + \sigma^2\cdot\sum_{k=1}^{t}\frac{(k+1)^2}{(t+1)^2}\cdot\frac{1}{(k+1)^2} \\ &= \frac{\lambda_j(w_{1,j}-w_{*,j})^2}{(t+1)^2} + \frac{t}{(t+1)^2}\cdot\sigma^2.\end{aligned}$$

Summing up each coordinate, we can obtain the result. □

Proof of Proposition 2. Let us denote $\sigma_j^2 = \lambda_j^2\sigma^2$. By Eqn. (2.1), we can obtain that

$$\begin{aligned}&\mathbb{E}\left[\lambda_j\left(w_{t+1,j}-w_{*,j}\right)^2\right] \\ \leq&\Pi_{i=1}^{t}(1-\eta_{i,j}\lambda_j)^2\cdot\lambda_j(w_{1,j}-w_{*,j})^2 + \sum_{k=1}^{t}\Pi_{i=k}(1-\eta_{i,j}\lambda_j)\eta_{k,j}^2\sigma_j^2 \\ \leq&\exp\left(-2\sum_{i=1}^{t}\eta_{i,j}\lambda_j\right)\cdot\lambda_j(w_{1,j}-w_{*,j})^2 + \sum_{k=1}^{t}\exp\left(-2\sum_{i=k}^{t}\eta_{i,j}\lambda_j\right)\eta_{k,j}^2\sigma_j^2 \\ =&\exp\left(-2\lambda_j\sum_{i=1}^{t}\frac{1}{L+\mu i}\right)\cdot\lambda_j(w_{1,j}-w_{*,j})^2 + \sum_{k=1}^{t}\exp\left(-2\lambda_j\sum_{i=k}^{t}\frac{1}{L+\mu i}\right)\eta_{k,j}^2\sigma_j^2 \\ \leq&\exp\left(\frac{2\lambda_j}{\mu}\ln\left(\frac{L+\mu}{L+\mu t}\right)\right)\cdot\lambda_j(w_{1,j}-w_{*,j})^2 + \sum_{k=1}^{t}\exp\left(\frac{2\lambda_j}{\mu}\ln\left(\frac{L+\mu k}{L+\mu t}\right)\right)\cdot\frac{\sigma_j^2}{(L+\mu k)^2} \\ =&\left(\frac{L+\mu}{L+\mu t}\right)^{\frac{2\lambda_j}{\mu}}\cdot\lambda_j(w_{1,j}-w_{*,j})^2 + \sum_{k=1}^{t}\frac{(L+\mu k)^{\left(\frac{2\lambda_j}{\mu}-2\right)}}{(L+\mu t)^{\frac{2\lambda_j}{\mu}}}\cdot\sigma_j^2 \\ \leq&\left(\frac{L+\mu}{L+\mu t}\right)^{\frac{2\lambda_j}{\mu}}\cdot\lambda_j(w_{1,j}-w_{*,j})^2 + \frac{\sigma_j^2}{2\lambda_j-\mu}\frac{(L+\mu t)^{\frac{2\lambda_j}{\mu}-1}}{(L+\mu t)^{\frac{2\lambda_j}{\mu}}} + \frac{\sigma_j^2}{(L+\mu t)^2} \\ =&\left(\frac{L+\mu}{L+\mu t}\right)^{\frac{2\lambda_j}{\mu}}\cdot\lambda_j(w_{1,j}-w_{*,j})^2 + \frac{1}{2\lambda_j-\mu}\cdot\frac{1}{L+\mu t}\cdot\sigma_j^2 + \frac{\sigma_j^2}{(L+\mu t)^2}.\end{aligned}$$

The third inequality is because function $F(x) = 1/(L+\mu x)$ is monotone decreasing in the range $[1,\infty)$, and it holds that

$$\sum_{i=k}^{t}\frac{1}{L+\mu i} \geq \int_{i=k}^{t}\frac{1}{L+\mu i}\ di = \frac{1}{\mu}\ln\left(\frac{L+\mu t}{L+\mu k}\right).$$

The last inequality is because function $F(x) = (L + \mu x)^{2\lambda_j/\mu - 2}$ is monotone increasing in the range $[0, \infty)$, and it holds that

$$\begin{aligned}\sum_{k=1}^{t}(L+\mu k)^{\frac{2\lambda_j}{\mu}-2} \leq & \int_{k=1}^{t}(L+\mu k)^{\frac{2\lambda_j}{\mu}-2}dk + (L+\mu t)^{\frac{2\lambda_j}{\mu}-2} \\ =& \frac{1}{\mu\left(\frac{2\lambda_j}{\mu}-1\right)} \cdot \left((L+\mu t)^{\frac{2\lambda_j}{\mu}-1} - (L+\mu)^{\frac{2\lambda_j}{\mu}-1}\right) + (L+\mu t)^{\frac{2\lambda_j}{\mu}-2} \\ <& \frac{1}{2\lambda_j - \mu}(L+\mu t)^{\frac{2\lambda_j}{\mu}-1} + (L+\mu t)^{\frac{2\lambda_j}{\mu}-2}.\end{aligned}$$

By $\mu \leq \lambda_j$, $\sigma_j^2 = \lambda_j^2\sigma^2$, and summing up from $i = 1$ to d, we can obtain the result. □

F PRELIMINARIES

Lemma 4. *Let objective function $f(x)$ be quadratic. Running SGD for T-steps starting from w_0 and a learning rate sequence $\{\eta_t\}_{t=1}^{T}$, the final iterate w_{T+1} satisfies*

$$\begin{aligned}&\mathbb{E}\left[(w_{T+1}-w_*)^\top H(w_{T+1}-w_*)\right] \\ =&\mathbb{E}\left[(w_0-w_*)^\top \cdot P_T \dots P_0 H P_0 \dots P_T \cdot (w_0 - w_*)\right] \\ &+ \sum_{\tau=0}^{T}\mathbb{E}\left[\eta_\tau^2 n_\tau^\top \cdot P_T \dots P_{\tau+1} H P_{\tau+1} \dots P_T \cdot n_\tau\right],\end{aligned} \tag{F.1}$$

where $P_t = I - \eta_t H$.

Proof. Reformulating Eqn. (1.5), we have

$$\begin{aligned}w_{t+1} - w_* =& w_t - w_* - \eta_t(H(\xi)w_t - b(\xi)) \\ =& w_t - w_* - \eta_t(Hw_t - b) + \eta_t\left(Hw_t - b - (H(\xi)w_t - b(\xi))\right) \\ =& w_t - w_* - \eta_t(Hw_t - b - (Hw_* - b)) + \eta_t\left(Hw_t - b - (H(\xi)w_t - b(\xi))\right) \\ =& \left(I - \eta_t H\right)(w_t - w_*) + \eta_t n_t \\ =& P_t(w_t - w_*) + \eta_t n_t.\end{aligned}$$

Thus, we can obtain that

$$w_{t+1} - w_* = P_t \dots P_0(w_0 - w_*) + \sum_{\tau=0}^{t} P_t \dots P_{\tau+1}\eta_\tau n_\tau. \tag{F.2}$$

We can decompose above stochastic process associated with SGD's update into two simpler processes as follows:

$$w_{t+1}^b - w_* = P_t(w_t^b - w_*), \quad \text{and} \quad w_{t+1}^v - w_* = P_t(w_t^v - w_*) + \eta_t n_t, \text{ with } w_0^v = w_*, \tag{F.3}$$

which entails that

$$w_{t+1}^b - w_* = P_t \dots P_0(w_0^b - w_*) = P_0 \dots P_t(w_0^b - w_*) \tag{F.4}$$

$$w_{t+1}^v - w_* = \sum_{\tau=0}^{t} P_t \dots P_{\tau+1}\eta_\tau n_\tau = \sum_{\tau=0}^{t} P_{\tau+1} \dots P_t \eta_\tau n_\tau \tag{F.5}$$

$$\overset{\text{(F.2)}}{\Rightarrow} w_{t+1} - w_* = \left(w_{t+1}^b - w_*\right) + \left(w_{t+1}^v - w_*\right) \tag{F.6}$$

where the last equality in Eqn. (F.4) and Eqn. (F.5) is because the commutative property $P_t P_{t'} = (I - \eta_t H)(I - \eta_{t'} H) = (I - \eta_{t'} H)(I - \eta_t H) = P_{t'} P_t$ holds for $\forall t, t'$.

Thus, we have

$$
\begin{aligned}
&\mathbb{E}\left[(w_{T+1}-w_*)^\top H(w_{T+1}-w_*)\right] \\
\overset{\text{(F.6)}}{=}&\mathbb{E}\left[(w_{T+1}^b-w_*)^\top H(w_{T+1}^b-w_*)+2(w_{T+1}^v-w_*)^\top H(w_0^b-w_*)\right. \\
&\left.+(w_{T+1}^v-w_*)^\top H(w_{T+1}^v-w_*)\right]. \\
\overset{\text{(F.4)}}{=}&\mathbb{E}\left[(w_0^b-w_*)^\top P_T\dots P_0HP_0\dots P_T(w_0^b-w_*)+2(w_{T+1}^v-w_*)^\top HP_0\dots P_T(w_0^b-w_*)\right. \\
&\left.+(w_{T+1}^v-w_*)^\top H(w_{T+1}^v-w_*)\right] \\
\overset{\text{(F.5)}}{=}&\mathbb{E}\left[(w_0^b-w_*)^\top P_T\dots P_0HP_0\dots P_T(w_0^b-w_*)\right. \\
&+2\left(\sum_{\tau=0}^{T}P_T\dots P_{\tau+1}\eta_\tau n_\tau\right)^\top HP_0\dots P_T(w_0^b-w_*) \\
&\left.+\left(\sum_{\tau=0}^{T}P_T\dots P_{\tau+1}\eta_\tau n_\tau\right)^\top H\left(\sum_{\tau=0}^{T}P_T\dots P_{\tau+1}\eta_\tau n_\tau\right)\right] \\
\overset{\mathbb{E}[n_\tau]=0}{=}&\mathbb{E}\left[(w_0^b-w_*)^\top P_T\dots P_0HP_0\dots P_T(w_0^b-w_*)\right] \\
&+\mathbb{E}\left[\sum_{\tau=0,\tau'=0}^{T}\eta_\tau\eta_{\tau'}\cdot n_\tau^\top P_T\dots P_{\tau+1}\cdot H\cdot P_{\tau'+1}\dots P_Tn_{\tau'}\right] \\
=&\mathbb{E}\left[(w_0^b-w_*)^\top P_T\dots P_0HP_0\dots P_T(w_0^b-w_*)\right] \\
&+\sum_{\tau=0}^{T}\mathbb{E}\left[\eta_\tau^2n_\tau^\top\cdot P_T\dots P_{\tau+1}HP_{\tau+1}\dots P_T\cdot n_\tau\right],
\end{aligned}
$$

where the last equality is because when τ and τ' are different, it holds that

$$\mathbb{E}[n_\tau^\top\cdot P_T\dots P_{\tau+1}HP_{\tau+1}\dots P_T\cdot n_{\tau'}]=0$$

due to independence between n_τ and $n_{\tau'}$. □

Lemma 5. *Given the assumption that $\mathbb{E}_\xi\left[n_tn_t^\top\right]\preceq\sigma^2H$, then the variance term satisfies that*

$$\sum_{\tau=0}^{T}\mathbb{E}\left[\eta_\tau^2n_\tau^\top\cdot P_T\dots P_{\tau+1}HP_{\tau+1}\dots P_T\cdot n_\tau\right]\le\sigma^2\sum_{j=1}^{d}\lambda_j^2\sum_{k=0}^{T}\eta_k^2\prod_{i=k+1}^{T}(1-\eta_i\lambda_j)^2, \tag{F.7}$$

where $P_t=I-\eta_tH$.

Proof. Denote $A_\tau\triangleq P_T\dots P_{\tau+1}H^{\frac{1}{2}}$, then

$$A_\tau^\top=\left(P_T\dots P_{\tau+1}H^{\frac{1}{2}}\right)^\top=\left(H^{\frac{1}{2}}\right)^\top P_{\tau+1}^\top\dots P_T^\top=H^{\frac{1}{2}}P_{\tau+1}\dots P_T, \tag{F.8}$$

where the second equality is entailed by the fact that $H^{\frac{1}{2}},P_{\tau+1},\dots,P_T$ are symmetric matrices.

Therefore, we have,

$$
\begin{aligned}
&\sum_{\tau=0}^{T} \mathbb{E}\left[\eta_\tau^2 n_\tau^\top \cdot P_T \dots P_{\tau+1} H P_{\tau+1} \dots P_T \cdot n_\tau\right] \\
\overset{\text{(F.8)}}{=} &\sum_{\tau=0}^{T} \mathbb{E}\left[\eta_\tau^2 n_\tau^\top A_\tau A_\tau^\top n_\tau\right] = \sum_{\tau=0}^{T} \eta_\tau^2 \mathbb{E}\left[\mathrm{tr}\left(n_\tau^\top A_\tau A_\tau^\top n_\tau\right)\right] = \sum_{\tau=0}^{T} \eta_\tau^2 \mathbb{E}\left[\mathrm{tr}\left(A_\tau^\top n_\tau n_\tau^\top A_\tau\right)\right] \\
= &\sum_{\tau=0}^{T} \eta_\tau^2 \mathrm{tr}\left(\mathbb{E}\left[A_\tau^\top n_\tau n_\tau^\top A_\tau\right]\right) = \sum_{\tau=0}^{T} \eta_\tau^2 \mathrm{tr}\left(A_\tau^\top \mathbb{E}\left[n_\tau n_\tau^\top\right] A_\tau\right) \\
\leq &\sigma^2 \cdot \sum_{\tau=0}^{T} \eta_\tau^2 \mathrm{tr}\left(A_\tau^\top H A_\tau\right) = \sigma^2 \cdot \sum_{\tau=0}^{T} \eta_\tau^2 \mathrm{tr}\left(A_\tau A_\tau^\top H\right) \\
= &\sigma^2 \cdot \sum_{\tau=0}^{T} \eta_\tau^2 \mathrm{tr}\left(P_T \dots P_{\tau+1} H P_{\tau+1} \dots P_T H\right) \\
= &\sigma^2 \sum_{j=1}^{d} \lambda_j^2 \sum_{k=0}^{T} \eta_k^2 \prod_{i=k+1}^{T} \left(1 - \eta_i \lambda_j\right)^2,
\end{aligned}
$$

where the third and sixth equality come from the cyclic property of trace, while the first inequality is because of the condition $\mathbb{E}_\xi\left[n_t n_t^\top\right] \preceq \sigma^2 H$, where

$$
\begin{aligned}
&\forall x, \quad x^\top \mathbb{E}[n_\tau n_\tau^\top] x \leq \sigma^2 x^\top H x \\
\Rightarrow \quad &\forall z, \quad z^\top A_\tau^\top \mathbb{E}[n_\tau n_\tau^\top] A_\tau z = (A_\tau z)^\top \mathbb{E}[n_\tau n_\tau^\top](A_\tau z) \leq \sigma^2 (A_\tau z)^\top H (A_\tau z) = \sigma^2 z^\top A_\tau^\top H A_\tau z \\
\Rightarrow \quad &A_\tau^\top \mathbb{E}[n_\tau n_\tau^\top] A_\tau \preceq \sigma^2 A_\tau^\top H A_\tau \\
\Rightarrow \quad &\mathrm{tr}\left(A_\tau^\top \mathbb{E}[n_\tau n_\tau^\top] A_\tau\right) \leq \sigma^2 \mathrm{tr}\left(A_\tau^\top H A_\tau\right).
\end{aligned}
$$

□

Lemma 6. *Letting $\lambda_{\tilde{j}}$ be the smallest positive eigenvalue of H, then the bias term satisfies that*

$$
\begin{aligned}
&\mathbb{E}\left[(w_0 - w_*)^\top \cdot P_T \dots P_0 H P_0 \dots P_T \cdot (w_0 - w_*)\right] \\
\leq &(w_0 - w_*)^\top H (w_0 - w_*) \cdot \exp\left(-2\lambda_{\tilde{j}} \sum_{k=0}^{T} \eta_k\right).
\end{aligned} \tag{F.9}
$$

Proof. Letting $H = U \Lambda U^\top$ be the spectral decomposition of H and u_j be j-th column of U, we can obtain that

$$
\begin{aligned}
&\mathbb{E}\left[(w_0 - w_*)^\top \cdot P_T \dots P_0 H P_0 \dots P_T \cdot (w_0 - w_*)\right] \\
= &\sum_{j=1}^{d} \lambda_j \cdot (u_j^\top (w_0 - w_*))^2 \cdot \prod_{k=0}^{T} (1 - \eta_k \lambda_j)^2 \\
\leq &\sum_{j=1}^{d} \lambda_j \cdot (u_j^\top (w_0 - w_*))^2 \cdot \exp\left(-2\lambda_j \sum_{k=0}^{T} \eta_k\right).
\end{aligned}
$$

Since $\lambda_{\tilde{j}}$ is the smallest positive eigenvalue of H, it holds that

$$
\begin{aligned}
\sum_{j=1}^{d} \lambda_j \cdot (u_j^\top (w_0 - w_*))^2 \cdot \exp\left(-2\lambda_j \sum_{k=0}^{T} \eta_k\right) \leq &\sum_{j=1}^{d} \lambda_j \cdot (u_j^\top (w_0 - w_*))^2 \cdot \exp\left(-2\lambda_{\tilde{j}} \sum_{k=0}^{T} \eta_k\right) \\
= &(w_0 - w_*)^\top H (w_0 - w_*) \cdot \exp\left(-2\lambda_{\tilde{j}} \sum_{k=0}^{T} \eta_k\right).
\end{aligned}
$$

□

G PROOF OF THEOREMS

Lemma 7. *Let learning rate η_t is defined in Eqn.* (3.3)*. Assuming $k \in [t_{i'-1}, t_{i'}]$ with $1 \le i' \le \tilde{i} \le T$, the sequence $\{\eta_t\}_{t=0}^T$ satisfies that*

$$\sum_{t=k}^{t_{\tilde{i}+1}-1} \eta_t \ge \sum_{i=i'+1}^{\tilde{i}+1} \frac{1}{2^{i-1}\mu} \ln \frac{\alpha_i}{\alpha_{i-1}} + \frac{1}{2^{i'-1}\mu} \ln \frac{\alpha_{i'}}{\alpha_{i'-1} + 2^{i'-1}\mu(k - t_{i'-1})}, \tag{G.1}$$

where α_i is defined as

$$\alpha_i \triangleq L + \mu \sum_{j=1}^{i} \Delta_j 2^{j-1} = \frac{1}{\eta_{t_i}}. \tag{G.2}$$

Proof. First, we divide learning rates into two groups: those who are guaranteed to cover a full interval and those who may not.

$$\sum_{t=k}^{t_{\tilde{i}+1}-1} \eta_t = \sum_{t=t_{i'}}^{t_{\tilde{i}+1}-1} \eta_t + \sum_{t=k}^{t_{i'}-1} \eta_t = \sum_{i=i'+1}^{\tilde{i}+1} \sum_{t=t_{i-1}}^{t_i-1} \eta_t + \sum_{t=k}^{t_{i'}-1} \eta_t$$

Furthermore, because η_t is monotonically decreasing with respect to t, by Proposition 3, we have

$$\begin{aligned}
\sum_{t=k}^{t_{\tilde{i}+1}-1} \eta_t &\overset{\text{(D.2)}}{\ge} \sum_{i=i'+1}^{\tilde{i}+1} \int_{t_{i-1}}^{t_i} \eta_t dt + \int_k^{t_{i'}} \eta_t dt \\
&\overset{\text{(3.3)}}{=} \sum_{i=i'+1}^{\tilde{i}+1} \int_{t_{i-1}}^{t_i} \frac{1}{L + \mu \sum_{j=1}^{i-1} \Delta_j 2^{j-1} + 2^{i-1}\mu(t - t_{i-1})} dt \\
&\quad + \int_k^{t_{i'}} \frac{1}{L + \mu \sum_{j=1}^{i'-1} \Delta_j 2^{j-1} + 2^{i'-1}\mu(t - t_{i'-1})} dt \\
&= \sum_{i=i'+1}^{\tilde{i}+1} \frac{1}{2^{i-1}\mu} \ln \frac{L + \mu \sum_{j=1}^{i-1} \Delta_j 2^{j-1} + 2^{i-1}\mu(t_i - t_{i-1})}{L + \mu \sum_{j=1}^{i-1} \Delta_j 2^{j-1}} \\
&\quad + \frac{1}{2^{i'-1}\mu} \ln \frac{L + \mu \sum_{j=1}^{i'-1} \Delta_j 2^{j-1} + 2^{i'-1}\mu(t_{i'} - t_{i'-1})}{L + \mu \sum_{j=1}^{i'-1} \Delta_j 2^{j-1} + 2^{i'-1}\mu(k - t_{i'-1})} \\
&= \sum_{i=i'+1}^{\tilde{i}+1} \frac{1}{2^{i-1}\mu} \ln \frac{L + \mu \sum_{j=1}^{i} \Delta_j 2^{j-1}}{L + \mu \sum_{j=1}^{i-1} \Delta_j 2^{j-1}} \\
&\quad + \frac{1}{2^{i'-1}\mu} \ln \frac{L + \mu \sum_{j=1}^{i'} \Delta_j 2^{j-1}}{L + \mu \sum_{j=1}^{i'-1} \Delta_j 2^{j-1} + 2^{i'-1}\mu(k - t_{i'-1})} \\
&= \sum_{i=i'+1}^{\tilde{i}+1} \frac{1}{2^{i-1}\mu} \ln \frac{\alpha_i}{\alpha_{i-1}} + \frac{1}{2^{i'-1}\mu} \ln \frac{\alpha_{i'}}{\alpha_{i'-1} + 2^{i'-1}\mu(k - t_{i'-1})}.
\end{aligned}$$

□

Lemma 8. *Letting sequence $\{\alpha_i\}$ be defined in Eqn.* (G.2)*, given $1 \le \tilde{i}$, it holds that*

$$\begin{aligned}
&\sum_{i=1}^{\tilde{i}+1} \left[\prod_{j=i+1}^{\tilde{i}+1} \left(\frac{\alpha_{j-1}}{\alpha_j} \right)^{2^{\tilde{i}-j+2}} \right] \alpha_i^{-2^{\tilde{i}-i+2}} \sum_{k=t_{i-1}}^{t_i-1} (\alpha_{i-1} + 2^{i-1}\mu(k - t_{i-1}))^{2^{\tilde{i}-i+2}-2} \\
\le &2 \cdot \frac{1}{2^{\tilde{i}+1}\mu} \cdot \sum_{i=1}^{\tilde{i}+1} \left[\prod_{j=i+1}^{\tilde{i}+1} \left(\frac{\alpha_{j-1}}{\alpha_j} \right)^{2^{\tilde{i}-j+2}} \right] \left(\alpha_i^{2^{\tilde{i}-i+2}-1} - \alpha_{i-1}^{2^{\tilde{i}-i+2}-1} \right) \alpha_i^{-2^{\tilde{i}-i+2}}.
\end{aligned} \tag{G.3}$$

Proof. Notice that $g(k) := (\alpha_{i-1} + 2^{i-1}\mu(k - t_{i-1}))^{2^{\tilde{i}-i+2}-2}$ is a monotonically increasing function, we have,

$$
\begin{aligned}
&\sum_{i=1}^{\tilde{i}+1}\left[\prod_{j=i+1}^{\tilde{i}+1}\left(\frac{\alpha_{j-1}}{\alpha_j}\right)^{2^{\tilde{i}-j+2}}\right]\alpha_i^{-2^{\tilde{i}-i+2}}\sum_{k=t_{i-1}}^{t_i-1}(\alpha_{i-1}+2^{i-1}\mu(k-t_{i-1}))^{2^{\tilde{i}-i+2}-2}\\
\overset{\text{(D.1)}}{\leq}&\sum_{i=1}^{\tilde{i}+1}\left[\prod_{j=i+1}^{\tilde{i}+1}\left(\frac{\alpha_{j-1}}{\alpha_j}\right)^{2^{\tilde{i}-j+2}}\right]\alpha_i^{-2^{\tilde{i}-i+2}}\int_{t_{i-1}}^{t_i}(\alpha_{i-1}+2^{i-1}\mu(t-t_{i-1}))^{2^{\tilde{i}-i+2}-2}dt\\
=&\sum_{i=1}^{\tilde{i}+1}\left[\prod_{j=i+1}^{\tilde{i}+1}\left(\frac{\alpha_{j-1}}{\alpha_j}\right)^{2^{\tilde{i}-j+2}}\right]\alpha_i^{-2^{\tilde{i}-i+2}}((2^{\tilde{i}-i+2}-1)\cdot 2^{i-1}\mu)^{-1}\left(\alpha_i^{2^{\tilde{i}-i+2}-1}-\alpha_{i-1}^{2^{\tilde{i}-i+2}-1}\right)\\
=&\sum_{i=1}^{\tilde{i}+1}\left[\prod_{j=i+1}^{\tilde{i}+1}\left(\frac{\alpha_{j-1}}{\alpha_j}\right)^{2^{\tilde{i}-j+2}}\right]\alpha_i^{-2^{\tilde{i}-i+2}}\frac{1}{(2^{\tilde{i}+1}-2^{i-1})\mu}\left(\alpha_i^{2^{\tilde{i}-i+2}-1}-\alpha_{i-1}^{2^{\tilde{i}-i+2}-1}\right)\\
\leq&\sum_{i=1}^{\tilde{i}+1}\left[\prod_{j=i+1}^{\tilde{i}+1}\left(\frac{\alpha_{j-1}}{\alpha_j}\right)^{2^{\tilde{i}-j+2}}\right]\alpha_i^{-2^{\tilde{i}-i+2}}\frac{1}{(2^{\tilde{i}+1}-2^{\tilde{i}})\mu}\left(\alpha_i^{2^{\tilde{i}-i+2}-1}-\alpha_{i-1}^{2^{\tilde{i}-i+2}-1}\right)\\
=&\sum_{i=1}^{\tilde{i}+1}\left[\prod_{j=i+1}^{\tilde{i}+1}\left(\frac{\alpha_{j-1}}{\alpha_j}\right)^{2^{\tilde{i}-j+2}}\right]\alpha_i^{-2^{\tilde{i}-i+2}}\frac{1}{2^{\tilde{i}+1}\mu}\frac{1}{1-\frac{1}{2}}\left(\alpha_i^{2^{\tilde{i}-i+2}-1}-\alpha_{i-1}^{2^{\tilde{i}-i+2}-1}\right)\\
=&2\cdot\frac{1}{2^{\tilde{i}+1}\mu}\sum_{i=1}^{\tilde{i}+1}\left[\prod_{j=i+1}^{\tilde{i}+1}\left(\frac{\alpha_{j-1}}{\alpha_j}\right)^{2^{\tilde{i}-j+2}}\right]\alpha_i^{-2^{\tilde{i}-i+2}}\left(\alpha_i^{2^{\tilde{i}-i+2}-1}-\alpha_{i-1}^{2^{\tilde{i}-i+2}-1}\right)\\
=&2\cdot\frac{1}{2^{\tilde{i}+1}\mu}\sum_{i=1}^{\tilde{i}+1}\left[\prod_{j=i+1}^{\tilde{i}+1}\left(\frac{\alpha_{j-1}}{\alpha_j}\right)^{2^{\tilde{i}-j+2}}\right]\left(\alpha_i^{2^{\tilde{i}-i+2}-1}-\alpha_{i-1}^{2^{\tilde{i}-i+2}-1}\right)\alpha_i^{-2^{\tilde{i}-i+2}}.
\end{aligned}
$$

□

Lemma 9. *Letting $\{\alpha_i\}$ be a positive sequence, given $1 \leq \tilde{i}$, it holds that*

$$
\sum_{i=1}^{\tilde{i}+1}\left[\prod_{j=i+1}^{\tilde{i}+1}\left(\frac{\alpha_{j-1}}{\alpha_j}\right)^{2^{\tilde{i}-j+2}}\right]\left(\alpha_i^{2^{\tilde{i}-i+2}-1}-\alpha_{i-1}^{2^{\tilde{i}-i+2}-1}\right)\alpha_i^{-2^{\tilde{i}-i+2}}\leq\alpha_{\tilde{i}+1}^{-1}. \tag{G.4}
$$

Proof. First, we have

$$
\begin{aligned}
&\sum_{i=1}^{\tilde{i}+1}\left[\prod_{j=i+1}^{\tilde{i}+1}\left(\frac{\alpha_{j-1}}{\alpha_j}\right)^{2^{\tilde{i}-j+2}}\right]\left(\alpha_i^{2^{\tilde{i}-i+2}-1}-\alpha_{i-1}^{2^{\tilde{i}-i+2}-1}\right)\alpha_i^{-2^{\tilde{i}-i+2}}\\
=&\sum_{i=1}^{\tilde{i}+1}\left[\prod_{j=i+1}^{\tilde{i}+1}\left(\frac{\alpha_{j-1}}{\alpha_j}\right)^{2^{\tilde{i}-j+2}}\right]\left(\alpha_i^{-1}-\frac{\alpha_{i-1}^{2^{\tilde{i}-i+2}-1}}{\alpha_i^{2^{\tilde{i}-i+2}}}\right)\\
=&\sum_{i=1}^{\tilde{i}+1}\left[\prod_{j=i+1}^{\tilde{i}+1}\left(\frac{\alpha_{j-1}}{\alpha_j}\right)^{2^{\tilde{i}-j+2}}\right]\alpha_i^{-1}-\sum_{i=1}^{\tilde{i}+1}\left[\prod_{j=i+1}^{\tilde{i}+1}\left(\frac{\alpha_{j-1}}{\alpha_j}\right)^{2^{\tilde{i}-j+2}}\right]\left(\frac{\alpha_{i-1}^{2^{\tilde{i}-i+2}-1}}{\alpha_i^{2^{\tilde{i}-i+2}}}\right)\\
=&\alpha_{\tilde{i}+1}^{-1}+\sum_{i=1}^{\tilde{i}}\left[\prod_{j=i+1}^{\tilde{i}+1}\left(\frac{\alpha_{j-1}}{\alpha_j}\right)^{2^{\tilde{i}-j+2}}\right]\alpha_i^{-1}-\sum_{i=1}^{\tilde{i}+1}\left[\prod_{j=i+1}^{\tilde{i}+1}\left(\frac{\alpha_{j-1}}{\alpha_j}\right)^{2^{\tilde{i}-j+2}}\right]\left(\frac{\alpha_{i-1}^{2^{\tilde{i}-i+2}-1}}{\alpha_i^{2^{\tilde{i}-i+2}}}\right).
\end{aligned}
$$

Furthermore, we reformulate the term $\sum_{i=1}^{\tilde{i}} \left[\prod_{j=i+1}^{\tilde{i}+1} \left(\frac{\alpha_{j-1}}{\alpha_j} \right)^{2^{\tilde{i}-j+2}} \right] \alpha_i^{-1}$ as follows

$$\sum_{i=1}^{\tilde{i}} \left[\prod_{j=i+1}^{\tilde{i}+1} \left(\frac{\alpha_{j-1}}{\alpha_j} \right)^{2^{\tilde{i}-j+2}} \right] \alpha_i^{-1} = \sum_{i=1}^{\tilde{i}} \left[\prod_{j=i+2}^{\tilde{i}+1} \left(\frac{\alpha_{j-1}}{\alpha_j} \right)^{2^{\tilde{i}-j+2}} \right] \left(\frac{\alpha_i}{\alpha_{i+1}} \right)^{2^{\tilde{i}-i+1}} \alpha_i^{-1} \tag{G.5}$$

$$= \sum_{i=1}^{\tilde{i}} \left[\prod_{j=i+2}^{\tilde{i}+1} \left(\frac{\alpha_{j-1}}{\alpha_j} \right)^{2^{\tilde{i}-j+2}} \right] \left(\frac{\alpha_i^{2^{\tilde{i}-i+1}-1}}{\alpha_{i+1}^{2^{\tilde{i}-i+1}}} \right) \tag{G.6}$$

$$\overset{i''=i+1}{=} \sum_{i''=2}^{\tilde{i}+1} \left[\prod_{j=i''+1}^{\tilde{i}+1} \left(\frac{\alpha_{j-1}}{\alpha_j} \right)^{2^{\tilde{i}-j+2}} \right] \left(\frac{\alpha_{i''-1}^{2^{\tilde{i}-i''+2}-1}}{\alpha_{i''}^{2^{\tilde{i}-i''+2}}} \right) \tag{G.7}$$

$$\overset{i=i''}{=} \sum_{i=2}^{\tilde{i}+1} \left[\prod_{j=i+1}^{\tilde{i}+1} \left(\frac{\alpha_{j-1}}{\alpha_j} \right)^{2^{\tilde{i}-j+2}} \right] \left(\frac{\alpha_{i-1}^{2^{\tilde{i}-i+2}-1}}{\alpha_i^{2^{\tilde{i}-i+2}}} \right). \tag{G.8}$$

Combining above results, we can obtain that

$$\begin{aligned}
&\sum_{i=1}^{\tilde{i}+1} \left[\prod_{j=i+1}^{\tilde{i}+1} \left(\frac{\alpha_{j-1}}{\alpha_j} \right)^{2^{\tilde{i}-j+2}} \right] \left(\alpha_i^{2^{\tilde{i}-i+2}-1} - \alpha_{i-1}^{2^{\tilde{i}-i+2}-1} \right) \alpha_i^{-2^{\tilde{i}-i+2}} \\
=&\alpha_{\tilde{i}+1}^{-1} + \sum_{i=2}^{\tilde{i}+1} \left[\prod_{j=i+1}^{\tilde{i}+1} \left(\frac{\alpha_{j-1}}{\alpha_j} \right)^{2^{\tilde{i}-j+2}} \right] \left(\frac{\alpha_{i-1}^{2^{\tilde{i}-i+2}-1}}{\alpha_i^{2^{\tilde{i}-i+2}}} \right) \\
&- \sum_{i=1}^{\tilde{i}+1} \left[\prod_{j=i+1}^{\tilde{i}+1} \left(\frac{\alpha_{j-1}}{\alpha_j} \right)^{2^{\tilde{i}-j+2}} \right] \left(\frac{\alpha_{i-1}^{2^{\tilde{i}-i+2}-1}}{\alpha_i^{2^{\tilde{i}-i+2}}} \right) \\
=&\alpha_{\tilde{i}+1}^{-1} - \left[\prod_{j=2}^{\tilde{i}+1} \left(\frac{\alpha_{j-1}}{\alpha_j} \right)^{2^{\tilde{i}-j+2}} \right] \left(\frac{\alpha_0^{2^{\tilde{i}+1}-1}}{\alpha_1^{2^{\tilde{i}+1}}} \right) \\
\leq&\alpha_{\tilde{i}+1}^{-1}.
\end{aligned}$$

□

Lemma 10. *Letting us denote* $v_{t+1,j} \triangleq \sum_{k=0}^{t} \eta_k^2 \prod_{i=k+1}^{t} (1 - \eta_i \lambda_j)^2$ *with* η_i *defined in Eqn.* (3.3)*, for* $1 \leq t \leq t'$*, it holds that*

$$v_{t',j} \leq \max(v_{t,j}, \eta_t / \lambda_j). \tag{G.9}$$

Proof. If $v_{t+1,j} \leq \max(v_{t,j}, \eta_t/\lambda_j)$ holds for $\forall t \geq 1$, then it naturally follows that

$$\begin{aligned}
v_{t',j} \leq& \max\left(v_{t'-1,j}, \frac{\eta_{t'-1}}{\lambda_j} \right) \leq \max\left(v_{t'-2,j}, \frac{\eta_{t'-2}}{\lambda_j}, \frac{\eta_{t'-1}}{\lambda_j}) \right) \\
\leq& \dots \\
\leq& \max\left(v_{t,j}, \frac{\eta_t}{\lambda_j}, \dots \frac{\eta_{t'-2}}{\lambda_j}, \frac{\eta_{t'-1}}{\lambda_j} \right) \\
=& \max\left(v_{t,j}, \frac{\eta_t}{\lambda_j} \right)
\end{aligned}$$

where the last equality is entailed by the fact that $t \leq t'$ and η_t defined in Eqn. (3.3) is monotonically decreasing. We then prove $v_{t+1,j} \leq \max(v_{t,j}, \eta_t/\lambda_j)$ holds for $\forall t \geq 1$.

For $\forall t \geq 1$, we have

$$\begin{aligned} v_{t+1,j} =& \sum_{k=0}^{t} \eta_k^2 \prod_{i=k+1}^{t} (1-\eta_i\lambda_j)^2 \\ =& \eta_t^2 + \sum_{k=0}^{t-1} \eta_k^2 \prod_{i=k+1}^{t} (1-\eta_i\lambda_j)^2 \\ =& \eta_t^2 + (1-\eta_t\lambda_j)^2 \sum_{k=0}^{t-1} \eta_k^2 \prod_{i=k+1}^{t-1} (1-\eta_i\lambda_j)^2 \\ =& \eta_t^2 + (1-\eta_t\lambda_j)^2 v_{t,j} \end{aligned} \tag{G.10}$$

1) If $v_{t+1,j} \leq v_{t,j}$, then it naturally follows $v_{t+1,j} \leq \max(v_{t,j}, \eta_t/\lambda_j)$.

2) If $v_{t+1,j} > v_{t,j}$, denote $a \triangleq (1-\eta_t\lambda_j)^2, b \triangleq \eta_t^2$, we have $v_{t+1,j} = av_{t,j} + b$, where $a \in [0,1)$ and $b \geq 0$. It follows,

$$\begin{aligned} & v_{t+1,j} > v_{t,j} \\ \Rightarrow \quad & av_{t,j} + b > v_{t,j} \\ \Rightarrow \quad & v_{t,j} < \frac{b}{1-a} \\ \Rightarrow \quad & v_{t+1,j} = av_{t,j} + b < a \cdot \frac{b}{1-a} + b = \frac{b}{1-a} \end{aligned}$$

Therefore,

$$v_{t+1,j} < \frac{b}{1-a} = \frac{\eta_t^2}{1-(1-\eta_t\lambda_j)^2} < \frac{\eta_t^2}{1-(1-\eta_t\lambda_j)} = \frac{\eta_t}{\lambda_j} \leq \max\left(v_{t,j}, \frac{\eta_t}{\lambda_j}\right)$$

where the second inequality is entailed by the fact that $1-\eta_t\lambda_j \in [0,1)$.

□

Lemma 11. *Letting $v_{t,j}$ be defined as Lemma 10 and index $\tilde{i}$ satisfy $\lambda_j \in [\mu \cdot 2^{\tilde{i}}, \mu \cdot 2^{\tilde{i}+1})$, then $v_{\tilde{i}+1,j}$ has the following property*

$$v_{t_{\tilde{i}+1},j} \leq 15 \cdot \frac{\eta_{t_{\tilde{i}+1}}}{\lambda_j}. \tag{G.11}$$

Proof. By the fact that $(1-x) \leq \exp(-x)$, we have

$$v_{t+1,j} \leq \sum_{k=0}^{t} \exp\left(-2 \sum_{t'=k+1}^{t} \eta_{t'}\lambda_j\right) \eta_k^2.$$

Setting $t = t_{\tilde{i}+1} - 1$ in above equation, we have

$$v_{t_{\tilde{i}+1},j} \leq \sum_{k=0}^{t_{\tilde{i}+1}-1} \exp\left(-2 \sum_{t'=k+1}^{t_{\tilde{i}+1}-1} \eta_{t'}\lambda_j\right) \eta_k^2. \tag{G.12}$$

Now we bound the variance term. First, we have

$$\begin{aligned}\sum_{k=0}^{t_{\tilde{i}+1}-1}\exp\left(-2\sum_{t=k+1}^{t_{\tilde{i}+1}-1}\eta_t\lambda_j\right)\eta_k^2 &= \sum_{k=0}^{t_{\tilde{i}+1}-1}\exp\left(-2\sum_{t=k}^{t_{\tilde{i}+1}-1}\eta_t\lambda_j\right)\exp(2\eta_k\lambda_j)\eta_k^2\\ &\le \sum_{k=0}^{t_{\tilde{i}+1}-1}\exp\left(-2\sum_{t=k}^{t_{\tilde{i}+1}-1}\eta_t\lambda_j\right)\exp\left(\frac{2\lambda_j}{L}\right)\eta_k^2\\ &\le \exp(2)\cdot\sum_{k=0}^{t_{\tilde{i}+1}-1}\exp\left(-2\sum_{t=k}^{t_{\tilde{i}+1}-1}\eta_t\lambda_j\right)\eta_k^2,\end{aligned}$$

where the first inequality is because $\eta_k \le 1/L$. Hence, we can obtain

$$\begin{aligned}&\sum_{k=0}^{t_{\tilde{i}+1}-1}\exp\left(-2\sum_{t=k+1}^{t_{\tilde{i}+1}-1}\eta_t\lambda_j\right)\eta_k^2\\ \le&\exp(2)\cdot\sum_{k=0}^{t_{\tilde{i}+1}-1}\exp\left(-2\sum_{t=k}^{t_{\tilde{i}+1}-1}\eta_t\lambda_j\right)\eta_k^2\\ =&\exp(2)\cdot\sum_{i=1}^{\tilde{i}+1}\sum_{k=t_{i-1}}^{t_i-1}\exp\left(-2\sum_{t=k}^{t_{\tilde{i}+1}-1}\eta_t\lambda_j\right)\eta_k^2.\end{aligned}$$

Furthermore, combining with Eqn. (G.1) and the condition $\lambda_j \in [\mu\cdot 2^{\tilde{i}}, \mu\cdot 2^{\tilde{i}+1})$, we can obtain

$$\begin{aligned}&\sum_{i=1}^{\tilde{i}+1}\sum_{k=t_{i-1}}^{t_i-1}\exp\left(-2\sum_{t=k}^{t_{\tilde{i}+1}-1}\eta_t\lambda_j\right)\eta_k^2 \le \sum_{i=1}^{\tilde{i}+1}\sum_{k=t_{i-1}}^{t_i-1}\exp\left(-2\sum_{t=k}^{t_{\tilde{i}+1}-1}\eta_t\mu\cdot 2^{\tilde{i}}\right)\eta_k^2\\ \overset{\text{(G.1)}}{\le}&\sum_{i=1}^{\tilde{i}+1}\sum_{k=t_{i-1}}^{t_i-1}\exp\left(-2\sum_{j=i+1}^{\tilde{i}+1}2^{\tilde{i}-j+1}\ln\frac{\alpha_j}{\alpha_{j-1}}-2\cdot 2^{\tilde{i}-i+1}\ln\frac{\alpha_i}{\alpha_{i-1}+2^{i-1}\mu(k-t_{i-1})}\right)\eta_k^2\\ =&\sum_{i=1}^{\tilde{i}+1}\sum_{k=t_{i-1}}^{t_i-1}\exp\left(\sum_{j=i+1}^{\tilde{i}+1}2^{\tilde{i}-j+2}\ln\frac{\alpha_{j-1}}{\alpha_j}+2^{\tilde{i}-i+2}\ln\frac{\alpha_{i-1}+2^{i-1}\mu(k-t_{i-1})}{\alpha_i}\right)\eta_k^2\\ =&\sum_{i=1}^{\tilde{i}+1}\sum_{k=t_{i-1}}^{t_i-1}\left[\prod_{j=i+1}^{\tilde{i}+1}\left(\frac{\alpha_{j-1}}{\alpha_j}\right)^{2^{\tilde{i}-j+2}}\right]\cdot\left(\frac{\alpha_{i-1}+2^{i-1}\mu(k-t_{i-1})}{\alpha_i}\right)^{2^{\tilde{i}-i+2}}\eta_k^2\\ =&\sum_{i=1}^{\tilde{i}+1}\left[\prod_{j=i+1}^{\tilde{i}+1}\left(\frac{\alpha_{j-1}}{\alpha_j}\right)^{2^{\tilde{i}-j+2}}\right]\sum_{k=t_{i-1}}^{t_i-1}\left(\frac{\alpha_{i-1}+2^{i-1}\mu(k-t_{i-1})}{\alpha_i}\right)^{2^{\tilde{i}-i+2}}\eta_k^2\\ \overset{\text{(3.3)}}{=}&\sum_{i=1}^{\tilde{i}+1}\left[\prod_{j=i+1}^{\tilde{i}+1}\left(\frac{\alpha_{j-1}}{\alpha_j}\right)^{2^{\tilde{i}-j+2}}\right]\\ &\cdot\sum_{k=t_{i-1}}^{t_i-1}\left(\frac{\alpha_{i-1}+2^{i-1}\mu(k-t_{i-1})}{\alpha_i}\right)^{2^{\tilde{i}-i+2}}\left(L+\mu\sum_{j=1}^{i-1}\Delta_j 2^{j-1}+2^{i-1}\mu(k-t_{i-1})\right)^{-2}\\ \overset{\text{(G.2)}}{=}&\sum_{i=1}^{\tilde{i}+1}\left[\prod_{j=i+1}^{\tilde{i}+1}\left(\frac{\alpha_{j-1}}{\alpha_j}\right)^{2^{\tilde{i}-j+2}}\right]\\ &\cdot\sum_{k=t_{i-1}}^{t_i-1}\left(\frac{\alpha_{i-1}+2^{i-1}\mu(k-t_{i-1})}{\alpha_i}\right)^{2^{\tilde{i}-i+2}}\left(\alpha_{i-1}+2^{i-1}\mu(k-t_{i-1})\right)^{-2}\end{aligned}$$

$$
\begin{aligned}
&= \sum_{i=1}^{\tilde{i}+1} \left[\prod_{j=i+1}^{\tilde{i}+1} \left(\frac{\alpha_{j-1}}{\alpha_j} \right)^{2^{\tilde{i}-j+2}} \right] \alpha_i^{-2^{\tilde{i}-i+2}} \\
&\quad \cdot \sum_{k=t_{i-1}}^{t_i-1} \left(\alpha_{i-1} + 2^{i-1}\mu(k-t_{i-1})\right)^{2^{\tilde{i}-i+2}} \left(\alpha_{i-1} + 2^{i-1}\mu(k-t_{i-1})\right)^{-2} \\
&= \sum_{i=1}^{\tilde{i}+1} \left[\prod_{j=i+1}^{\tilde{i}+1} \left(\frac{\alpha_{j-1}}{\alpha_j} \right)^{2^{\tilde{i}-j+2}} \right] \alpha_i^{-2^{\tilde{i}-i+2}} \sum_{k=t_{i-1}}^{t_i-1} \left(\alpha_{i-1} + 2^{i-1}\mu(k-t_{i-1})\right)^{2^{\tilde{i}-i+2}-2} \\
&\overset{\text{(G.3)}}{\leq} 2 \cdot \frac{1}{2^{\tilde{i}+1}\mu} \cdot \sum_{i=1}^{\tilde{i}+1} \left[\prod_{j=i+1}^{\tilde{i}+1} \left(\frac{\alpha_{j-1}}{\alpha_j} \right)^{2^{\tilde{i}-j+2}} \right] \left(\alpha_i^{2^{\tilde{i}-i+2}-1} - \alpha_{i-1}^{2^{\tilde{i}-i+2}-1} \right) \alpha_i^{-2^{\tilde{i}-i+2}} \\
&\overset{\text{(G.4)}}{\leq} 2 \cdot \frac{1}{2^{\tilde{i}+1}\mu} \cdot \alpha_{\tilde{i}+1}^{-1} \leq 2 \cdot \frac{\eta_{t_{\tilde{i}+1}}}{\lambda_j},
\end{aligned}
$$

where the last inequality is because of the condition $\lambda_j \in [\mu \cdot 2^{\tilde{i}}, \mu \cdot 2^{\tilde{i}+1})$ and the definition of α_i.

Therefore, we have

$$
v_{t_{\tilde{i}+1},j} \leq 2\exp(2) \cdot \frac{\eta_{t_{\tilde{i}+1}}}{\lambda_j} \leq 15 \cdot \frac{\eta_{t_{\tilde{i}+1}}}{\lambda_j}.
$$

□

Lemma 12. *Let objective function $f(x)$ be quadratic and Assumption* (1.7) *hold. Running SGD for T-steps starting from w_0 and a learning rate sequence $\{\eta_t\}_{t=1}^T$ defined in Eqn.* (3.3)*, the final iterate w_{T+1} satisfies*

$$
\begin{aligned}
\mathbb{E}\left[(w_{T+1} - w_*)^\top H (w_{T+1} - w_*)\right] \leq & (w_0 - w_*)^\top H (w_0 - w_*) \cdot \exp\left(-2\mu \sum_{k=0}^{T} \eta_k \right) \\
& + 15\sigma^2\mu \sum_{\tilde{i}=0}^{I_{\max}-1} \frac{2^{\tilde{i}+1} s_{\tilde{i}}}{L + \mu \sum_{j=1}^{\tilde{i}+1} \Delta_j 2^{j-1}}.
\end{aligned}
$$

Proof. The target of this lemma is to obtain the explicit form to bound the variance term. By the definition of $v_{t+1,j}$ in Lemma 10, we can obtain that

$$
\begin{aligned}
& \sum_{\tau=0}^{T} \mathbb{E}\left[\eta_\tau^2 n_\tau^\top \cdot P_T \dots P_{\tau+1} H P_{\tau+1} \dots P_T \cdot n_\tau\right] \\
\overset{\text{(F.7)}}{\leq} & \sigma^2 \sum_{j=1}^{d} \lambda_j^2 \cdot v_{T+1,j} \\
\overset{\text{(G.9)}}{\leq} & \sigma^2 \sum_{j=1}^{d} \lambda_j^2 \cdot \max\left(v_{t_{\tilde{i}+1}+1,j}, \frac{\eta_{t_{\tilde{i}+1}+1}}{\lambda_j} \right) \\
\overset{\text{(G.11)}}{\leq} & \sigma^2 \sum_{j=1}^{d} \lambda_j^2 \cdot \max\left(15 \cdot \frac{\eta_{t_{\tilde{i}+1}+1}}{\lambda_j}, \frac{\eta_{t_{\tilde{i}+1}+1}}{\lambda_j} \right) \\
= & 15\sigma^2 \sum_{j=1}^{d} \lambda_j \cdot \eta_{t_{\tilde{i}+1}+1} \leq 15\sigma^2 \sum_{j=1}^{d} \lambda_j \cdot \eta_{t_{\tilde{i}+1}} \leq 15\sigma^2\mu \sum_{\tilde{i}=0}^{I_{\max}-1} 2^{\tilde{i}+1} s_{\tilde{i}} \cdot \eta_{t_{\tilde{i}+1}},
\end{aligned}
$$

where the last inequality is because $\lambda_j \in [2^{\tilde{i}}\mu,\ 2^{\tilde{i}+1}\mu)$ and there are $s_{\tilde{i}}$ such λ_j's lie in this range. By Eqn. (3.3), we have

$$
\eta_{t_{\tilde{i}+1}} = \frac{1}{L + \mu \sum_{j=1}^{\tilde{i}+1} \Delta_j 2^{j-1}}. \tag{G.13}
$$

Therefore, we have

$$\sum_{\tau=0}^{T} \mathbb{E}\left[\eta_\tau^2 n_\tau^\top \cdot P_T \dots P_{\tau+1} H P_{\tau+1} \dots P_T \cdot n_\tau\right] \leq 15\sigma^2\mu \sum_{\tilde{i}=0}^{I_{\max}-1} \frac{2^{\tilde{i}+1} s_{\tilde{i}}}{L + \mu \sum_{j=1}^{\tilde{i}+1} \Delta_j 2^{j-1}}. \tag{G.14}$$

Combining with Lemma 4 and Lemma 6, we can obtain that

$$\begin{aligned}\mathbb{E}\left[(w_{T+1} - w_*)^\top H (w_{T+1} - w_*)\right] \leq & (w_0 - w_*)^\top H (w_0 - w_*) \cdot \exp\left(-2\mu \sum_{k=0}^{T} \eta_k\right) \\ & + 15\sigma^2\mu \sum_{\tilde{i}=0}^{I_{\max}-1} \frac{2^{\tilde{i}+1} s_{\tilde{i}}}{L + \mu \sum_{j=1}^{\tilde{i}+1} \Delta_j 2^{j-1}}.\end{aligned}$$

□

Lemma 13. *For $\forall t \geq 0$, the learning rate sequence $\{\eta_t\}_{t=1}^T$ defined in Eqn.* (3.3) *satisfies*

$$\eta_t \leq \frac{1}{L + \mu t} \tag{G.15}$$

Proof. For $\forall t \geq 0$, there $\exists i \geq 1$, where $t \in [t_{i-1}, t_i)$. Given the form defined in Eqn. (3.3), we have,

$$\begin{aligned}\eta_t =& \frac{1}{L + \mu \sum_{j=1}^{i-1} \Delta_j 2^{j-1} + 2^{i-1}\mu(t - t_{i-1})} \\ \leq& \frac{1}{L + \mu \sum_{j=1}^{i-1} \Delta_j + \mu(t - t_{i-1})} \\ \overset{(3.4)}{=}& \frac{1}{L + \mu \sum_{j=1}^{i-1} (t_j - t_{j-1}) + \mu(t - t_{i-1})} \\ =& \frac{1}{L + \mu(t_{i-1} - t_0) + \mu(t - t_{i-1})} \\ =& \frac{1}{L + \mu(t - t_0)} \\ =& \frac{1}{L + \mu t}\end{aligned}$$

□

Lemma 14. *Let objective function $f(x)$ be quadratic and Assumption* (1.7) *hold. Running SGD for T-steps starting from w_0 and a learning rate sequence $\{\eta_t\}_{t=1}^T$ defined in Eqn.* (3.3)*, the final iterate w_{T+1} satisfies*

$$\begin{aligned}\mathbb{E}\left[(w_{T+1} - w_*)^\top H (w_{T+1} - w_*)\right] \leq & (w_0 - w_*)^\top H (w_0 - w_*) \cdot \frac{\kappa^2}{\Delta_1^2} \\ & + 15\sigma^2\mu \sum_{\tilde{i}=0}^{I_{\max}-1} \frac{2^{\tilde{i}+1} s_{\tilde{i}}}{L + \mu \sum_{j=1}^{\tilde{i}+1} \Delta_j 2^{j-1}}.\end{aligned}$$

Proof. The target of this lemma is to obtain the explicit form to bound the bias term.

First, by Eqn. (G.1) and the condition $\lambda_j \in [\mu \cdot 2^{\tilde{i}}, \mu \cdot 2^{\tilde{i}+1})$, we have

$$\begin{aligned}\exp\left(-2\lambda_j \sum_{k=0}^{T} \eta_k\right) \leq & \exp\left(-2 \sum_{k=0}^{t_{\tilde{i}+1}-1} \eta_k \lambda_j\right) \leq \exp\left(-2 \sum_{i=1}^{\tilde{i}+1} \frac{1}{2^{i-1}\mu} \ln \frac{\alpha_i}{\alpha_{i-1}} \lambda_j\right) \\ \leq & \exp\left(-\sum_{i=1}^{\tilde{i}+1} 2^{\tilde{i}-i+2} \ln \frac{\alpha_i}{\alpha_{i-1}}\right) = \prod_{i=1}^{\tilde{i}+1} \left(\frac{\alpha_{i-1}}{\alpha_i}\right)^{2^{\tilde{i}-i+2}} \\ \leq & \prod_{i=1}^{\tilde{i}+1} \left(\frac{\alpha_{i-1}}{\alpha_i}\right)^2 = \left(\frac{\alpha_1}{\alpha_{\tilde{i}+1}}\right)^2 = L^2 \cdot \eta_{t_{\tilde{i}+1}}^2\end{aligned} \tag{G.16}$$

For $\lambda_j = \mu$, since $\mu \in [\mu \cdot 2^{\tilde{i}}, \mu \cdot 2^{\tilde{i}+1})$ for $\tilde{i} = 0$, it follows,

$$\exp\left(-2\mu \sum_{k=0}^{T} \eta_k\right) \leq L^2 \cdot \eta_{t_1}^2 \overset{\text{(G.15)}}{\leq} \left(\frac{L}{L+\mu t_1}\right)^2 \overset{\text{(3.4)}}{=} \left(\frac{L}{L+\mu\Delta_1}\right)^2 \leq \left(\frac{L}{\mu\Delta_1}\right)^2 = \frac{\kappa^2}{\Delta_1^2} \tag{G.17}$$

Combining with Lemma 12, we obtain that,

$$\begin{aligned}\mathbb{E}\left[(w_{T+1}-w_*)^\top H (w_{T+1}-w_*)\right] \leq & (w_0-w_*)^\top H (w_0-w_*) \cdot \frac{\kappa^2}{\Delta_1^2} \\ & + 15\sigma^2\mu \sum_{\tilde{i}=0}^{I_{\max}-1} \frac{2^{\tilde{i}+1} s_{\tilde{i}}}{L + \mu \sum_{j=1}^{\tilde{i}+1} \Delta_j 2^{j-1}}.\end{aligned}$$

□

G.1 Proof of Lemma 1

Lemma 1. *Let objective function $f(x)$ be quadratic and Assumption* (1.7) *hold. Running SGD for T-steps starting from w_0 and a learning rate sequence $\{\eta_t\}_{t=1}^T$ defined in Eqn.* (3.3)*, the final iterate w_{T+1} satisfies*

$$\mathbb{E}\left[f(w_{T+1}) - f(w_*)\right] \leq (f(w_0) - f(w_*)) \cdot \frac{\kappa^2}{\Delta_1^2} + \frac{15}{2} \cdot \sigma^2 \mu \sum_{\tilde{i}=0}^{I_{\max}-1} \frac{2^{\tilde{i}+1} s_{\tilde{i}}}{L + \mu \sum_{j=1}^{\tilde{i}+1} \Delta_j 2^{j-1}}. \tag{3.6}$$

Proof. For $\forall t \geq 0$, we have

$$\begin{aligned}f(w_t) - f(w_*) \overset{\text{(1.2)}}{=} & \mathbb{E}\left[\frac{1}{2} w_t^\top H(\xi) w_t - b(\xi)^\top w_t\right] - \mathbb{E}\left[\frac{1}{2} w_*^\top H(\xi) w_* - b(\xi)^\top w_*\right] \\ = & \left(\frac{1}{2} w_t^\top \mathbb{E}[H(\xi)] w_t - \mathbb{E}[b(\xi)]^\top w_t\right) - \left(\frac{1}{2} w_*^\top \mathbb{E}[H(\xi)] w_* - \mathbb{E}[b(\xi)]^\top w_*\right) \\ = & \left(\frac{1}{2} w_t^\top H w_t - b^\top w_t\right) - \left(\frac{1}{2} w_*^\top H w_* - b^\top w_*\right) \\ \overset{\text{(1.4)}}{=} & \left(\frac{1}{2} w_t^\top H w_t - b^\top w_t\right) - \left(\frac{1}{2} b^\top \left(H^\top\right)^{-1} b - b^\top H^{-1} b\right) \\ = & \left(\frac{1}{2} w_t^\top H w_t - b^\top w_t\right) - \left(\frac{1}{2} b^\top H^{-1} b - b^\top H^{-1} b\right) \\ = & \frac{1}{2} w_t^\top H w_t - b^\top w_t + \frac{1}{2} b^\top H^{-1} b \\ = & \frac{1}{2} w_t^\top H w_t - \frac{1}{2} b^\top w_t - \frac{1}{2} b^\top w_t + \frac{1}{2} b^\top H^{-1} b\end{aligned}$$

$$
\begin{aligned}
=&\frac{1}{2}w_t^\top H w_t - \frac{1}{2}w_t^\top b - \frac{1}{2}b^\top w_t + \frac{1}{2}b^\top H^{-1} b \\
=&\frac{1}{2}w_t^\top H w_t - \frac{1}{2}w_t^\top H w_* - \frac{1}{2}w_*^\top H w_t + \frac{1}{2}w_*^\top H w_* \\
=&\frac{1}{2}(w_t - w_*)^\top H (w_t - w_*),
\end{aligned}
$$

where the 5th equality is entailed by the fact that $H^\top = H$ is a symmetric matrix, and the 9th equality uses both $H^\top = H$ and Eqn 1.4.

Combine the above result with Lemma 14, we obtain that

$$
\mathbb{E}\left[f(w_{T+1}) - f(w_*)\right] \leq (f(w_0) - f(w_*)) \cdot \frac{\kappa^2}{\Delta_1^2} + \frac{15}{2} \cdot \sigma^2 \mu \sum_{\tilde{i}=0}^{I_{\max}-1} \frac{2^{\tilde{i}+1} s_{\tilde{i}}}{L + \mu \sum_{j=1}^{\tilde{i}+1} \Delta_j 2^{j-1}}.
$$

□

G.2 Proof of Theorem 1

Theorem 1. *Let objective function $f(x)$ be quadratic and Assumption* (1.7) *hold. Running SGD for T-steps starting from w_0, a learning rate sequence $\{\eta_t\}_{t=1}^T$ defined in Eqn.* (3.3) *and Δ_i defined in Eqn.* (3.5)*, the final iterate w_{T+1} satisfies*

$$
\mathbb{E}\left[f(w_{T+1}) - f(w_*)\right] \leq (f(w_0) - f(w_*)) \cdot \frac{\kappa^2 \cdot \left(\sum_{i=0}^{I_{\max}-1} \sqrt{s_i}\right)^2}{s_0 T^2} + \frac{15 \left(\sum_{i=0}^{I_{\max}-1} \sqrt{s_i}\right)^2}{T} \cdot \sigma^2.
$$

Proof. We have

$$
\begin{aligned}
\mu \cdot \sum_{\tilde{i}=0}^{I_{\max}-1} \frac{2^{\tilde{i}+1} s_{\tilde{i}}}{L + \mu \sum_{j=1}^{\tilde{i}+1} \Delta_j 2^{j-1}} <& \mu \cdot \sum_{\tilde{i}=0}^{I_{\max}-1} \frac{2^{\tilde{i}+1} s_{\tilde{i}}}{\mu 2^{\tilde{i}} \Delta_{\tilde{i}+1}} \overset{(3.5)}{=} 2 \sum_{\tilde{i}=0}^{I_{\max}-1} \frac{s_{\tilde{i}}}{\frac{\sqrt{s_{\tilde{i}}}}{\sum_{i=0}^{I_{\max}-1} \sqrt{s_i}} \cdot T} \\
=& \frac{2}{T} \cdot \sum_{i=0}^{I_{\max}-1} \sqrt{s_i} \cdot \sum_{\tilde{i}=0}^{I_{\max}-1} \sqrt{s_{\tilde{i}}} = \frac{2 \left(\sum_{i=0}^{I_{\max}-1} \sqrt{s_i}\right)^2}{T}.
\end{aligned}
$$

Combining with Lemma 1 and the definition of Δ_1, we can obtain that

$$
\mathbb{E}\left[f(w_{T+1}) - f(w_*)\right] \leq (f(w_0) - f(w_*)) \cdot \frac{\kappa^2 \cdot \left(\sum_{i=0}^{I_{\max}-1} \sqrt{s_i}\right)^2}{s_0 T^2} + \frac{15 \left(\sum_{i=0}^{I_{\max}-1} \sqrt{s_i}\right)^2}{T} \cdot \sigma^2.
$$

□

G.3 Proof of Corollary 2

Corollary 2. *Given the same setting as in Theorem 1, when Hessian H's eigenvalue distribution $p(\lambda)$ satisfies "power power law", i.e.*

$$
p(\lambda) = \frac{1}{Z} \cdot \exp(-\alpha(\ln(\lambda) - \ln(\mu))) = \frac{1}{Z} \cdot \left(\frac{\mu}{\lambda}\right)^\alpha \tag{3.7}
$$

for some $\alpha > 1$, where $Z = \int_\mu^L (\mu/\lambda)^\alpha d\lambda$, there exists a constant $C(\alpha)$ which only depends on α, such that the final iterate w_{T+1} satisfies

$$
\mathbb{E}\left[f(w_{T+1}) - f(w_*)\right] \leq \left((f(w_0) - f(w_*)) \cdot \frac{\kappa^2}{T^2} + \frac{d\sigma^2}{T}\right) \cdot C(\alpha).
$$

Proof. According to Theorem 1,

$$
\begin{aligned}
&\mathbb{E}\left[f(w_{T+1}) - f(w_*)\right] \\
\leq &(f(w_0) - f(w_*)) \cdot \frac{\kappa^2 \cdot \left(\sum_{i=0}^{I_{\max}-1} \sqrt{s_i}\right)^2}{s_0 T^2} + \frac{15\left(\sum_{i=0}^{I_{\max}-1} \sqrt{s_i}\right)^2}{T} \cdot \sigma^2 \\
= &(f(w_0) - f(w_*)) \cdot \frac{\kappa^2}{T^2} \cdot \frac{\left(\sum_{i=0}^{I_{\max}-1} \sqrt{s_i}\right)^2}{s_0} + \frac{d\sigma^2}{T} \cdot \frac{15\left(\sum_{i=0}^{I_{\max}-1} \sqrt{s_i}\right)^2}{d}.
\end{aligned}
$$

The key terms here are $C_1 \triangleq \left(\sum_{i=0}^{I_{\max}-1} \sqrt{s_i}\right)^2 / s_0$ and $C_2 \triangleq 15\left(\sum_{i=0}^{I_{\max}-1} \sqrt{s_i}\right)^2 / d$. As long as we can bound both terms with a constant $C(\alpha)$, the corollary will be directly proved.

1) If $\kappa < 2$, then there is only one interval with $s_0 = d$. By setting $C(\alpha) = \max(C_1, C_2) = 15$, this completes the proof.

2) If $\kappa \geq 2$, then bounding C_1 and C_2 be done by computing the value of s_i under power power law. For all interval i except the last interval, we have,

$$
\begin{aligned}
\frac{s_i}{d} &\overset{(3.1)}{=} \#\lambda_j \in [\mu \cdot 2^i, \mu \cdot 2^{i+1}) = \int_{\mu \cdot 2^i}^{\mu \cdot 2^{i+1}} p(\lambda) d\lambda \\
&\overset{(3.7)}{=} \int_{\mu \cdot 2^i}^{\mu \cdot 2^{i+1}} \frac{1}{Z} \cdot \left(\frac{\mu}{\lambda}\right)^\alpha d\lambda = \frac{1}{Z} \cdot \mu^\alpha \cdot \int_{\mu \cdot 2^i}^{\mu \cdot 2^{i+1}} \lambda^{-\alpha} d\lambda \\
&= \left(\int_\mu^L \left(\frac{\mu}{\lambda}\right)^\alpha d\lambda\right)^{-1} \cdot \mu^\alpha \cdot \int_{\mu \cdot 2^i}^{\mu \cdot 2^{i+1}} \lambda^{-\alpha} d\lambda = \left(\int_\mu^L \lambda^{-\alpha} d\lambda\right)^{-1} \cdot \int_{\mu \cdot 2^i}^{\mu \cdot 2^{i+1}} \lambda^{-\alpha} d\lambda \\
&= \left(\frac{\lambda^{1-\alpha}}{1-\alpha}\Big|_\mu^L\right)^{-1} \cdot \left(\frac{\lambda^{1-\alpha}}{1-\alpha}\Big|_{\mu \cdot 2^i}^{\mu \cdot 2^{i+1}}\right) = \left(\lambda^{1-\alpha}\Big|_\mu^L\right)^{-1} \cdot \left(\lambda^{1-\alpha}\Big|_{\mu \cdot 2^i}^{\mu \cdot 2^{i+1}}\right) \\
&= \left(L^{1-\alpha} - \mu^{1-\alpha}\right)^{-1} \cdot \left(\mu^{1-\alpha} \cdot \left(2^{i+1}\right)^{1-\alpha} - \mu^{1-\alpha} \cdot \left(2^i\right)^{1-\alpha}\right) \\
&= \frac{\mu^{1-\alpha} \cdot \left(2^{i+1}\right)^{1-\alpha} - \mu^{1-\alpha} \cdot \left(2^i\right)^{1-\alpha}}{L^{1-\alpha} - \mu^{1-\alpha}} = \frac{\left(2^{i+1}\right)^{1-\alpha} - \left(2^i\right)^{1-\alpha}}{\kappa^{1-\alpha} - 1} \\
&= 2^{i(1-\alpha)} \cdot \frac{2^{1-\alpha} - 1}{\kappa^{1-\alpha} - 1}
\end{aligned}
$$

Therefore, we have

$$
s_i = d \cdot 2^{i(1-\alpha)} \cdot \frac{2^{1-\alpha} - 1}{\kappa^{1-\alpha} - 1} = d \cdot \frac{2^{1-\alpha} - 1}{\kappa^{1-\alpha} - 1} \cdot 2^{i(1-\alpha)} \tag{G.18}
$$

holds for all interval i except the last interval $i' = I_{\max} - 1 = \log_2 \kappa - 1 > 0$. This last interval may not completely covers $[\mu \cdot 2^{i'}, \mu \cdot 2^{i'+1})$ due to the boundary truncated by L, but we still have

$$
s_{i'} \leq d \cdot \frac{2^{1-\alpha} - 1}{\kappa^{1-\alpha} - 1} \cdot 2^{i'(1-\alpha)}
$$

It follows,

$$\begin{aligned}
\left(\sum_{i=0}^{I_{\max}-1}\sqrt{s_i}\right)^2 \leq & d\cdot\frac{2^{1-\alpha}-1}{\kappa^{1-\alpha}-1}\cdot\left(\sum_{i=0}^{I_{\max}-1}\sqrt{2^{i(1-\alpha)}}\right)^2 = d\cdot\frac{2^{1-\alpha}-1}{\kappa^{1-\alpha}-1}\cdot\left(\sum_{i=0}^{I_{\max}-1}2^{i(1-\alpha)/2}\right)^2 \\
= & d\cdot\frac{2^{1-\alpha}-1}{\kappa^{1-\alpha}-1}\cdot\left(\sum_{i=0}^{I_{\max}-1}\left(\frac{1}{2}\right)^{i(\alpha-1)/2}\right)^2 \\
\leq & d\cdot\frac{2^{1-\alpha}-1}{\kappa^{1-\alpha}-1}\cdot\left(\sum_{i=0}^{\infty}\left(\frac{1}{2}\right)^{i(\alpha-1)/2}\right)^2 = d\cdot\frac{2^{1-\alpha}-1}{\kappa^{1-\alpha}-1}\cdot\left(\sum_{i=0}^{\infty}\left(\frac{1}{2^{(\alpha-1)/2}}\right)^{i}\right)^2 \\
= & d\cdot\frac{2^{1-\alpha}-1}{\kappa^{1-\alpha}-1}\cdot\left(\frac{1}{1-\frac{1}{2^{(\alpha-1)/2}}}\right)^2 = d\cdot\frac{2^{1-\alpha}-1}{\kappa^{1-\alpha}-1}\cdot\left(\frac{1}{1-2^{(1-\alpha)/2}}\right)^2.
\end{aligned}$$

Thus,

$$\begin{aligned}
C_1 = & \frac{\left(\sum_{i=0}^{I_{\max}-1}\sqrt{s_i}\right)^2}{s_0} \leq \frac{d\cdot\frac{2^{1-\alpha}-1}{\kappa^{1-\alpha}-1}\cdot\left(\frac{1}{1-2^{(1-\alpha)/2}}\right)^2}{d\cdot\frac{2^{1-\alpha}-1}{\kappa^{1-\alpha}-1}\cdot 2^{0(1-\alpha)}} = \left(\frac{1}{1-2^{(1-\alpha)/2}}\right)^2 \\
C_2 = & \frac{15\left(\sum_{i=0}^{I_{\max}-1}\sqrt{s_i}\right)^2}{d} \leq \frac{15}{d}\cdot d\cdot\frac{2^{1-\alpha}-1}{\kappa^{1-\alpha}-1}\cdot\left(\frac{1}{1-2^{(1-\alpha)/2}}\right)^2 \\
= & 15\cdot\frac{1-\left(\frac{1}{2}\right)^{\alpha-1}}{1-\left(\frac{1}{\kappa}\right)^{\alpha-1}}\cdot\left(\frac{1}{1-2^{(1-\alpha)/2}}\right)^2 \\
\leq & 15\cdot\left(\frac{1}{1-2^{(1-\alpha)/2}}\right)^2.
\end{aligned}$$

Here the last inequality for C_2 is entailed by $\kappa \geq 2$ and $\alpha > 1$.

By setting $C(\alpha) = \max(C_1, C_2) = 15\cdot\left(\frac{1}{1-2^{(1-\alpha)/2}}\right)^2$, we obtain

$$\begin{aligned}
& \mathbb{E}\left[f(w_{T+1}) - f(w_*)\right] \\
\leq & (f(w_0) - f(w_*))\cdot\frac{\kappa^2}{T^2}\cdot\frac{\left(\sum_{i=0}^{I_{\max}-1}\sqrt{s_i}\right)^2}{s_0} + \frac{d\sigma^2}{T}\cdot\frac{15\left(\sum_{i=0}^{I_{\max}-1}\sqrt{s_i}\right)^2}{d}. \\
= & (f(w_0) - f(w_*))\cdot\frac{\kappa^2}{T^2}\cdot C_1 + \frac{d\sigma^2}{T}\cdot C_2 \\
\leq & \left((f(w_0) - f(w_*))\cdot\frac{\kappa^2}{T^2} + \frac{d\sigma^2}{T}\right)\cdot C(\alpha).
\end{aligned}$$

□

G.4 Proof of Theorem 4

Theorem 4. *Let objective function $f(x)$ be quadratic. We run SGD for T-steps starting from w_0 and a step decay learning rate sequence $\{\eta_t\}_{t=1}^T$ defined in Algorithm 1 of Ge et al. (2019) with $\eta_1 = 1/L$. As long as **(1)** H is diagonal, **(2)** The equality in Assumption (1.7) holds, i.e. $\mathbb{E}_\xi\left[n_t n_t^\top\right] = \sigma^2 H$ and **(3)** $T/\log T \geq \max(\kappa, 2^{16}, 16)$, the final iterate w_{T+1} satisfies,*

$$\mathbb{E}\left[f(w_{T+1}) - f(w_*)\right] = \Omega\left(\frac{d\sigma^2}{T}\cdot\log T\right)$$

Proof. In Ge et al. (2019), step decay has following learning rate sequence:

$$\eta_t = \frac{1}{2^\ell L} \quad \text{if } t \in \left[1 + \frac{T}{\log T} \cdot \ell, \frac{T}{\log T} \cdot (\ell + 1)\right], \tag{G.19}$$

where $\ell = 0, 1, \ldots, \log T - 1$. We first translate the general notations to diagonal cases so that the idea of the proof can be clearer.

Since $f(x)$ is quadratic, according to the proof in Lemma 1,

$$f(w_{T+1}) - f(w_*) = \frac{1}{2}(w_{T+1} - w_*)^\top H (w_{T+1} - w_*)$$

Furthermore, according to Lemma 4, where $P_t = I - \eta_t H$,

$$\begin{aligned}
&\mathbb{E}\left[(w_{T+1} - w_*)^\top H (w_{T+1} - w_*)\right] \\
=&\mathbb{E}\left[(w_0 - w_*)^\top \cdot P_T \ldots P_0 H P_0 \ldots P_T \cdot (w_0 - w_*)\right] \\
&+ \sum_{\tau=0}^{T} \mathbb{E}\left[\eta_\tau^2 n_\tau^\top \cdot P_T \ldots P_{\tau+1} H P_{\tau+1} \ldots P_T \cdot n_\tau\right] \\
\geq& \sum_{\tau=0}^{T} \mathbb{E}\left[\eta_\tau^2 n_\tau^\top \cdot P_T \ldots P_{\tau+1} H P_{\tau+1} \ldots P_T \cdot n_\tau\right] \\
=& \sum_{\tau=0}^{T} \eta_\tau^2 \prod_{k=\tau+1}^{T} \sum_{j=1}^{d} \lambda_j (1 - \eta_k \lambda_j)^2 \mathbb{E}\left[n_{\tau,j}^2\right] \\
=& \sum_{\tau=0}^{T} \eta_\tau^2 \prod_{k=\tau+1}^{T} \sum_{j=1}^{d} \lambda_j (1 - \eta_k \lambda_j)^2 \cdot \lambda_j \sigma^2 \\
=& \sigma^2 \sum_{j=1}^{d} \lambda_j^2 \sum_{\tau=0}^{T} \eta_\tau^2 \prod_{k=\tau+1}^{T} (1 - \eta_k \lambda_j)^2
\end{aligned}$$

Here the second equality is entailed by the fact that H and P_t are diagonal, and the third equality comes from $\mathbb{E}_\xi\left[n_t n_t^\top\right] = \sigma^2 H$. Thus, by denoting $v_j \triangleq \sum_{\tau=0}^{T} \eta_\tau^2 \prod_{k=\tau+1}^{T} (1 - \eta_k \lambda_j)^2$, we have,

$$\mathbb{E}\left[f(w_{T+1} - f(w_*)\right] \geq \frac{\sigma^2}{2} \sum_{j=1}^{d} \lambda_j^2 \sum_{\tau=0}^{T} \eta_\tau^2 \prod_{k=\tau+1}^{T} (1 - \eta_k \lambda_j)^2 = \frac{\sigma^2}{2} \sum_{j=1}^{d} \lambda_j^2 v_j \tag{G.20}$$

For each dimension λ_j, step decay's bottleneck actually occurs at the first interval ℓ that satisfies

$$2^\ell \geq \frac{\lambda_j}{L} \cdot \frac{8T}{\log T} \tag{G.21}$$

We first show that interval ℓ is well-defined for any dimension j.

Since we assume $T/\log T \geq \kappa$, i.e. $1/\kappa \geq \log T/T$, it follows

$$\begin{aligned}
& 2^\ell \geq \frac{\lambda_j}{L} \cdot \frac{8T}{\log T} \geq \frac{\mu}{L} \cdot \frac{8T}{\log T} = \frac{1}{\kappa} \cdot \frac{8T}{\log T} \geq \frac{\log T}{T} \cdot \frac{8T}{\log T} = 8 \\
\implies & \ell \geq 3
\end{aligned}$$

Since interval ℓ is the first interval satisifies Eqn. (G.21), we also have

$$2^\ell < \frac{\lambda_j}{L} \cdot \frac{16T}{\log T}, \tag{G.22}$$

which follows,

$$\begin{aligned}
& 2^\ell < \frac{\lambda_j}{L} \cdot \frac{16T}{\log T} \leq \frac{16T}{\log T} \leq T \\
\implies & \ell < \log T
\end{aligned}$$

The last inequality is because $T \geq T/\log T \geq 2^{16} \Rightarrow \log T \geq 16$. Since $T \geq 16 \Rightarrow \log T \geq 4 > 3$, thus such ℓ is guaranteed to be well-defined. Back to our main analysis, by focusing on interval ℓ only, we have,

$$
\begin{aligned}
v_j =& \sum_{\tau=0}^{T} \eta_\tau^2 \prod_{k=\tau+1}^{T} (1-\eta_k\lambda_j)^2 \geq \sum_{\tau=\ell\cdot\frac{T}{\log T}+1}^{(\ell+1)\cdot\frac{T}{\log T}} \eta_\tau^2 \prod_{k=\tau+1}^{T} (1-\eta_k\lambda_j)^2 \\
\geq& \sum_{\tau=\ell\cdot\frac{T}{\log T}+1}^{(\ell+1)\cdot\frac{T}{\log T}} \eta_\tau^2 \prod_{k=\ell\cdot\frac{T}{\log T}+1}^{T} (1-\eta_k\lambda_j)^2 = \sum_{\tau=\ell\cdot\frac{T}{\log T}+1}^{(\ell+1)\cdot\frac{T}{\log T}} \left(\frac{1}{L2^\ell}\right)^2 \prod_{k=\ell\cdot\frac{T}{\log T}+1}^{T} (1-\eta_k\lambda_j)^2 \\
=& \frac{T}{\log T}\cdot\left(\frac{1}{L2^\ell}\right)^2 \prod_{k=\ell\cdot\frac{T}{\log T}+1}^{T} (1-\eta_k\lambda_j)^2 \\
\overset{\text{(G.22)}}{>}& \frac{T}{\log T}\cdot\left(\frac{1}{L\cdot\frac{\lambda_j}{L}\cdot\frac{16T}{\log T}}\right)^2 \prod_{k=\ell\cdot\frac{T}{\log T}+1}^{T} (1-\eta_k\lambda_j)^2 \\
=& \frac{1}{256}\cdot\frac{\log T}{T}\cdot\frac{1}{\lambda_j^2}\cdot \prod_{k=\ell\cdot\frac{T}{\log T}+1}^{T} (1-\eta_k\lambda_j)^2 \\
\geq& \frac{1}{256}\cdot\frac{\log T}{T}\cdot\frac{1}{\lambda_j^2}\cdot\left(1-\sum_{k=\ell\cdot\frac{T}{\log T}+1}^{T} 2\eta_k\lambda_j\right) = \frac{1}{256}\cdot\frac{\log T}{T}\cdot\frac{1}{\lambda_j^2}\cdot\left(1-2\lambda_j\sum_{k=\ell\cdot\frac{T}{\log T}+1}^{T}\eta_k\right) \\
=& \frac{1}{256}\cdot\frac{\log T}{T}\cdot\frac{1}{\lambda_j^2}\cdot\left(1-2\lambda_j\sum_{i=\ell}^{\log T-1}\sum_{k=i\cdot\frac{T}{\log T}+1}^{(i+1)\cdot\frac{T}{\log T}}\eta_k\right) \\
=& \frac{1}{256}\cdot\frac{\log T}{T}\cdot\frac{1}{\lambda_j^2}\cdot\left(1-2\lambda_j\sum_{i=\ell}^{\log T-1}\sum_{k=i\cdot\frac{T}{\log T}+1}^{(i+1)\cdot\frac{T}{\log T}}\frac{1}{L2^i}\right) \\
=& \frac{1}{256}\cdot\frac{\log T}{T}\cdot\frac{1}{\lambda_j^2}\cdot\left(1-2\lambda_j\sum_{i=\ell}^{\log T-1}\frac{T}{\log T}\cdot\frac{1}{L2^i}\right) \\
\geq& \frac{1}{256}\cdot\frac{\log T}{T}\cdot\frac{1}{\lambda_j^2}\cdot\left(1-2\lambda_j\cdot\frac{T}{\log T}\cdot\frac{1}{L2^{\ell-1}}\right) \\
\overset{\text{(G.21)}}{\geq}& \frac{1}{256}\cdot\frac{\log T}{T}\cdot\frac{1}{\lambda_j^2}\cdot\left(1-4\lambda_j\cdot\frac{T}{\log T}\cdot\frac{1}{L\cdot\frac{\lambda_j}{L}\cdot\frac{8T}{\log T}}\right) \\
=& \frac{1}{256}\cdot\frac{\log T}{T}\cdot\frac{1}{\lambda_j^2}\cdot\frac{1}{2} \\
=& \frac{1}{512}\cdot\frac{\log T}{T}\cdot\frac{1}{\lambda_j^2}
\end{aligned}
$$

Here the first inequality is obtained by focusing variance generated in interval ℓ only. The second inequality utilizes $\tau + 1 \geq \ell \cdot T/\log T$. The fourth inequality is entailed by $(1-a_1)(1-a_2) = 1 - a_1 - a_2 + a_1a_2 \geq 1 - a_1 - a_2$ for $\forall a_1, a_2 \in [0,1]$, where by mathematical induction, we can extend this inequality for more terms $\prod_{i=1}^n (1-a_i) \geq 1 - \sum_{i=1}^n a_i$ as long as $\sum_{i=1}^n a_i \leq 1$. The fifth inequality comes from $\sum_{i=\ell}^{\log T-1} 1/2^i \leq \sum_{i=\ell}^{\infty} 1/2^i = 1/2^{\ell-1}$.

By combining with Eqn. (G.20), we have

$$\mathbb{E}\left[f(w_{T+1}-f(w_*)\right] \geq \frac{\sigma^2}{2}\sum_{j=1}^{d}\lambda_j^2 v_j \geq \frac{\sigma^2}{2}\sum_{j=1}^{d}\lambda_j^2\cdot\left(\frac{1}{512}\cdot\frac{\log T}{T}\cdot\frac{1}{\lambda_j^2}\right) = \frac{1}{1024}\cdot\frac{d\sigma^2}{T}\cdot\log T$$
$$= \Omega\left(\frac{d\sigma^2}{T}\cdot\log T\right)$$

□

G.5 THE REASON OF USING ASSUMPTION (1.7)

In all of our analysis, we employ assumption (1.7)

$$\mathbb{E}_\xi\left[n_t n_t^\top\right] \preceq \sigma^2 H \quad \text{where } n_t = Hw_t - b - (H(\xi)w_t - b(\xi))$$

which is the same as the one in Appendix C, Theorem 13 of Ge et al. (2019). This key theorem is the major difference between our work and Ge et al. (2019), which directly entails its main theorem by instantiating σ with specific values in its assumptions.

On the other hand, it is possible to use the assumptions in Ge et al. (2019); Bach & Moulines (2013); Jain et al. (2016) instead of our assumption (1.7) for least square regression:

$$\min_w f(w) \quad \text{where } f(w) \triangleq \frac{1}{2}\mathbb{E}_{(x,y)\sim\mathcal{D}}\left[(y-w^\top x)^2\right] \tag{G.23}$$

$$y = w_*^\top x + \epsilon \text{ with } \epsilon \text{ satisfying } \mathbb{E}_{(x,y)\sim\mathcal{D}}\left[\epsilon^2 xx^\top\right] \preceq \sigma^2 H \text{ for } \forall(x,y)\sim\mathcal{D} \tag{G.24}$$

$$\mathbb{E}\left[||x||^2 xx^\top\right] \preceq R^2 H \tag{G.25}$$

By combining our Lemma 1 and assumption (1.7) with Lemma 5, Lemma 8 and Lemma 9 in Ge et al. (2019), one can obtain similar results in this paper with their assumptions. For simplicity, we just use assumption (1.7) here.