Strong Copyright Protection for Language Models via Adaptive Model Fusion

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Abstract

The risk of language models unintentionally reproducing copyrighted material from their training data has led to the development of various protective measures. In this paper, we propose model fusion as an effective solution to safeguard against copyright infringement. In particular, we introduce Copyright-Protecting Fusion (CP-Fuse), an algorithm that adaptively combines language models to minimize the reproduction of protected materials. CP-Fuse is inspired by the recently proposed Near-Access Free (NAF) framework and additionally incorporates a desirable *balancing property* that we demonstrate prevents the reproduction of memorized training data. Our results show that CP-Fuse significantly reduces the memorization of copyrighted content while maintaining high-quality text and code generation. Furthermore, we demonstrate how CP-Fuse can be integrated with other techniques for enhanced protection.

1. Introduction

Large Language Models (LLMs), such as GPT-4 (Achiam et al., 2023) and Gemini (Team et al., 2023), have made remarkable progress in automating tasks traditionally requiring human ingenuity, including code generation and creative writing. However, these advancements also introduce the risk of LLMs reproducing copyrighted material from their training data (Yu et al., 2023; Meeus et al., 2023; Carlini et al., 2023; Karamolegkou et al., 2023), posing substantial legal challenges and leading to multi-million dollar lawsuits (Henderson et al., 2023). As a result, preventing copyright infringement in language models has become a critical concern for researchers and practitioners alike.

An approach to reducing the generation of copyrighted material involves curating training data to exclude or deduplicate protected samples (Kandpal et al., 2022; Ippolito & Yu, 2023; Carlini et al., 2023). However, this process is resource-intensive and may not be entirely effective (Lee et al., 2023; Ippolito et al., 2023). Additionally, copyrighted samples often represent high-quality inputs crucial for the models' performance (Meeus et al., 2023), making their exclusion potentially undesirable. In fact, under the fair use doctrine (17 U.S.C. §107), leveraging protected material is permitted provided the output does not substitute the copyrighted work or harm its market (Henderson et al., 2023; Rahman & Santacana, 2023). Therefore, practitioners seek strategies to train models with copyrighted content while preventing infringements once deployed (Wei et al., 2024).

To address this issue, various works focus on mitigating the memorization phenomenon in LLMs (Carlini et al., 2019; 2021; 2023; Zhang et al., 2023; Nasr et al., 2023), aiming to prevent them from reproducing verbatim text from their training data. Several methods intervene *during the training phase*, and propose strategies for training or fine-tuning generative models with protected data while ensuring their outputs remain copyright-compliant (Anil et al., 2022; Chu et al., 2024; Hans et al., 2024). Although promising, these approaches are usually computationally demanding, can compromise model utility (Anil et al., 2022), or rely on heuristics without guarantees for preventing memorization (Hans et al., 2024). Other approaches explicitly permit language models full access to copyrighted material during training and intervene *during the inference phase* (Ippolito et al., 2023; Vyas et al., 2023). Notably, Vyas et al. (2023) introduce a general approach for constructing copyright-protected models by fusing generative models trained on different data sources. However, while their framework shows potential, it currently lacks tractable algorithms for implementation.

In this paper, we propose Copyright-Protecting Fusion (CP-Fuse), a simple algorithm for copyright-protecting model fusion. Our method builds upon an extensive body of literature on model fusion for language models (Liu et al., 2021; Jiang et al., 2023; Gururangan et al., 2023; Wang et al., 2023; Mavromatis et al., 2024). In particular, CP-Fuse adaptively aggregates the logits to reduce the probability of regurgitating copyrighted content. In Section 4, we introduce the algorithm, which we derive from the Near-Access Free (NAF) framework (Vyas et al., 2023). We demonstrate that it adheres to a *balancing property* (Lemma 4.2),

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which intuitively explains how it prevents the regurgitation of copyright-protected material when using greedy decoding strategies. In Section 5, we showcase the effectiveness of CP-Fuse in preventing language models from reproducing memorized training samples, reducing regurgitation by more than $25\times$ compared to copyright-infringing models. Additionally, we show that it consistently outperforms other techniques aimed at preventing memorization during the inference phase while maintaining competitive perplexity and generating high-quality code and text. Finally, preliminary experiments indicate that our method can be combined on top of other copyright-protecting strategies, such as those intervening in the training phase, for enhanced protection.

2. Related Works on Copyright Protection

Measures for copyright protection can be implemented at various stages of model deployment (Lee et al., 2023). Since many open-source LLMs are trained on datasets containing copyrighted material, such as the BookCorpus dataset (e.g., GPT-3 (Brown et al., 2020)) and the C4 corpus (e.g., LLaMa (Touvron et al., 2023)), efforts have been made to curate datasets with exclusively licensed content (Kocetkov et al., 2022; Min et al., 2023). Moreover, removing duplicated copyrighted samples from the dataset has been shown to reduce regurgitation (Kandpal et al., 2022). However, these approaches are resource-intensive and can degrade model performance (Ippolito et al., 2023; Meeus et al., 2023).

Other approaches intervene during the training or fine-tuning of LLMs. These methods usually aim to prevent memorization, as verbatim reproduction can constitute copyright infringement in text and code (Yu et al., 2023; Henderson et al., 2023). In this context, differential privacy (DP) (Dwork et al., 2014; Abadi et al., 2016) offers a solution against memorization by limiting the influence of individual training points on the model's output. However, DP training is computationally demanding, usually reduces generation utility (Anil et al., 2022), and its goals differ from those of copyright protection (Elkin-Koren et al., 2023). Additionally, heuristic alternatives, such as the goldfish loss (Hans et al., 2024) or simple early stopping (Mireshghallah et al., 2022), have proven effective in preventing the regurgitation of training text, though they lack theoretical guarantees.

An orthogonal line of work allows language models full access to copyrighted content during training and enforces copyright constraints via post-processing (Wei et al., 2024). Filtering strategies, such as Mem-Free (Ippolito & Yu, 2023), can effectively prevent verbatim reproduction of copyrighted material from a curated blocklist at inference time. However, these methods only work for consecutive verbatim matches, and may lead to hallucinations due to modifications in the decoding process (Liu et al., 2024b). Furthermore, several works propose unlearning copyrighted content from trained models (Bourtoule et al., 2021; Chen & Yang, 2023; Eldan & Russinovich, 2023; Jang et al., 2023; Zhang et al., 2024a; Liu et al., 2024a); however, these approaches are typically computationally impractical and require access to model weights, which is restrictive in real-world scenarios. Our method, presented in Section 4, derives from the NAF framework (Vyas et al., 2023). Unlike purely heuristic approaches, it allows for a theoretical understanding of how it prevents regurgitation (Lemma 4.2), which we verify in extensive experiments, both at preventing copyright-infringing models from reproducing protected content and using it as a wrapper for other methods to enhance protection (Section 5).

3. Preliminaries

We focus on language models p that take a prompt x as input and return a probability distribution over a sequence of tokens of variable length T from a fixed alphabet V, with $y_T = \text{EOS}$ representing the end-of-sequence token. Using the convention that $y_{<0} = \emptyset$, we can factorize p as:

$$p(y_{0:T}|x) = \prod_{t=0}^{T} p(y_t|y_{<t}, x).$$

In the following, we introduce a key assumption underlying our work and motivate our copyright-protection method.

Separability of copyrighted material At the core of our method is the assumption of the *separability of copyrighted material*, discussed by Vyas et al. (2023) for various vision and language applications. This assumption is akin to those used in exact machine unlearning (Bourtoule et al., 2021; Yan et al., 2022; Dukler et al., 2023; Kumar et al., 2023) and in works that rely on splitting datasets into safe and unsafe parts (Golatkar et al., 2021; 2024; Li et al., 2024).

Consider a dataset $\mathcal{D}$ and a set of copyright-protected materials $\mathcal{C}$ that could be compromised when training a language model p on $\mathcal{D}$. The assumption states that we can split the training data $\mathcal{D}$ into two potentially overlapping subsets, $\mathcal{D}_1$ and $\mathcal{D}_2$, such that each subset contains data associated with two mutually exclusive sets of copyright-protected materials, $\mathcal{C}_1$ and $\mathcal{C}_2$, where $\mathcal{C}_1 \cap \mathcal{C}_2 = \emptyset$. This assumption holds, for instance, when we construct the training data $\mathcal{D}$ from multiple data sources that are sufficiently distinct. Consequently, any language model trained on the subset $\mathcal{D}_1$ is protected from infringing the copyright of materials in $\mathcal{C} \setminus \mathcal{C}_1 \supseteq \mathcal{C}_2$.

Near-Access Freeness (NAF) Given two generative models $p^{(1)}$ and $p^{(2)}$ trained on $\mathcal{D}_1$ and $\mathcal{D}_2$, respectively, the challenge is to construct a model p that achieves protection against all copyright-protected materials $\mathcal{C}$. In that light,Vyas et al. (2023) propose the k-NAF framework as a quantitative guarantee for copyright protection. Formally, a

model $p(.|x)$ satisfies the k-NAF guarantee if, for any input prompt x and some user-specified divergence function Δ,

$$\forall x: \quad \max_{i \in \{1,2\}} \Delta(p(.|x) \,||\, p^{(i)}(.|x)) \leq k. \tag{1}$$

The key intuition behind Equation (1) is that, if the separability of copyrighted material holds, the likelihood of generating copyright-infringing text for any material $c \in \mathcal{C}$ is exponentially small for at least one of the models. Thus, for a model p to satisfy the k-NAF guarantee, it must place minimal weight on such events. However, it remains unclear to what extent this intuition yields meaningful guarantees for greedy search and sampling decoding strategies.

Model fusion with LLMs Independent of copyright protection, combining multiple language models is a popular research field aimed at achieving knowledge fusion, both at inference time (Liu et al., 2021; Jiang et al., 2023; Gururangan et al., 2023; Mavromatis et al., 2024) and after training through the merging of learned weights (Wortsman et al., 2022; Jin et al., 2022; Hsu et al., 2024). Most relevant to this paper are the former approaches, which generally define a model p at inference time by combining multiple models $p^{(1)}, \cdots, p^{(K)}$ via a weighted sum of their logits:

$$\log p(y_t|y_{<t}, x) := \sum_{i=1}^{K} \alpha_t^{(i)}(y_{<t}, x) \log p^{(i)}(.|y_{<t}, x) + c, \tag{2}$$

where c is a normalizing constant and $\alpha_t^{(i)}$ can depend on the prompt x and the history $y_{<t}$. However, unlike our algorithm presented in the next section, these approaches do not enforce p to be close to all models $p^{(i)}$ simultaneously.

4. Copyright-Protecting Model Fusion

We present **C**opyright-**P**rotecting **Fus**ion (CP-Fuse), a simple yet effective algorithm for copyright protection in language models via model fusion. Inspired by the k-NAF framework, we aim to minimize the maximum KL-divergence from Equation (1). Since achieving this directly is computationally intractable, we propose an efficient approximate algorithm that iteratively optimizes for $p(y_t|y_{<t}, x)$ given the probability of the history $p(y_{<t}|x)$. We show in Lemma 4.1 that leveraging the KL-divergence allows us to derive an update rule in the form of Equation (2), commonly used in model fusion. Formally, we iteratively define

$$\begin{aligned} p(y_t \,|\, y_{<t}, x) &= \arg\min_{p^*} \max_i \mathop{\mathbb{E}}_{y_t \sim p^*} \log \left(\frac{p^*(y_t) p(y_{<t} \,|\, x)}{p^{(i)}(y_{\leq t} \,|\, x)} \right) \\ &= \arg\min_{p^*, t} \; t \quad \text{s.t.} \\ \forall i: \;\; & \mathrm{KL}(p^* || p^{(i)}(.|y_{<t}, x)) + \log \left(\frac{p(y_{<t} \,|\, x)}{p^{(i)}(y_{<t} \,|\, x)} \right) \leq t, \end{aligned} \tag{3}$$

which results in a convex optimization problem. While solving this problem naively is still computationally intensive, we overcome this limitation using the following lemma:

Lemma 4.1. *The optimal solution $p(y_t \,|\, y_{<t}, x)$ of the optimization problem in Equation (3) satisfies*[1]

$$\begin{aligned} \log p^*(y_t) = \alpha_t \log p^{(1)}(y_t|y_{<t}, x) \\ + \beta_t \log p^{(2)}(y_t|y_{<t}, x) + \gamma_t \end{aligned} \tag{4}$$

for some $\alpha_t, \beta_t \geq 0, \gamma_t \in \mathbb{R}$.

Consequently, the optimization problem in Equation (3) can be solved efficiently by performing a grid search over the parameters α_t and β_t, and selecting γ_t as a function of α_t and β_t to ensure that the total mass is 1.

4.1. Discussion

CP-Fuse adaptively selects α_t and β_t based on the sequence history $y_{<t}$. In particular, the algorithm assigns less weight to the model that has been more dominant in generating $y_{<t}$, which is key for achieving strong copyright protection. More formally, the following balancing property holds:

Lemma 4.2. *(Balancing property) Let $y_{<t}$ be any non-ending sequence and assume that $p^{(i)}(.|y_{<t}, x)$ has full support for both $i \in \{1, 2\}$ and $p^{(1)}(y_{<t}|x) > p^{(2)}(y_{<t}|x)$. Then, either of the two cases is true:*

1. $\mathop{\mathbb{E}}_{y_t \sim p(.|y_{<t})} \log p^{(1)}(y_{\leq t}) = \mathop{\mathbb{E}}_{y_t \sim p(.|y_{<t})} \log p^{(2)}(y_{\leq t})$
2. $p(y_t|y_{<t}, x) = p^{(2)}(y_t|y_{<t}, x)$

This balancing property ensures that neither model dominates the text generation. As an example, suppose the generation of a subsequence $y_{<t}$ is strongly dominated by $p^{(1)}$, such that $p^{(1)}(y_{<t}|x) \gg p^{(2)}(y_{<t}|x)$. If the first case in Lemma 4.2 holds, the output distribution of the copyright-protected model, $p(y_t|y_{<t}, x)$, will be much closer to $p^{(2)}(y_{<t}|x)$ than to $p^{(1)}(y_{<t}|x)$. Conversely, if the second case holds, then $p = p^{(2)}$, and the generation of y_t will be independent of $p^{(1)}(y_{<t}|x)$. In other words, the next token generated by p will likely match the most probable token under the dominant model, $p^{(1)}(y_{<t}|x)$, only if both $p^{(1)}$ and $p^{(2)}$ are close conditioned on $y_{<t}$ and x, that is, when the generated sequence is not protected assuming separability of copyrighted material (Section 3). We provide experimental evidence for this property in Appendix A.6.

Comparison with related works Vyas et al. (2023) propose CP-Δ as a general strategy for combining two generative models. Nevertheless, their approach becomes computationally intractable when directly applied to the probability

[1] We set $\log(0) = -\infty$

distribution $p(.|x)$ over the entire sequence y_T. To address this issue, the authors suggest applying CP-Δ token-wise, resulting in the model from Equation (4) with $\alpha_t = \beta_t = 1/2$. This algorithm has also been used in a slightly different setting for purifying language models (Li et al., 2024).

However, we remark that adaptively choosing α_t and β_t is crucial for achieving strong copyright protection. To illustrate this point, we present in Figure 1 the cumulative log-likelihood at each generated token for sequences produced by CP-Fuse and CP-Δ, along with their respective base models $p^{(1)}$ and $p^{(2)}$. The balancing property of CP-Fuse ensures that the log-likelihood under $p^{(1)}$ and $p^{(2)}$ is approximately the same for each generated token of the sequence, thereby preventing the reproduction of copyrighted material since no protected content can be memorized by both base models. Conversely, CP-Δ exhibits a clear preference towards $p^{(2)}$. This dominance suggests that $p^{(2)}$ potentially memorized training samples, making CP-Δ vulnerable to reproducing them. In the next section, we further validate this observation through extensive real-world experiments.

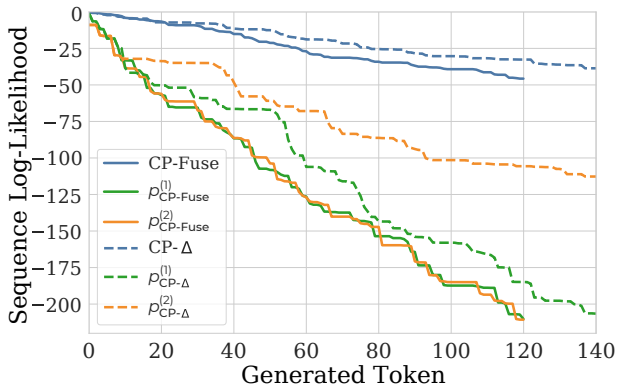


Figure 1. Log-likelihood of the sequences produced by CP-Fuse and CP-Δ, and their base models $p^{(1)}$ and $p^{(2)}$, at each generated token. We show a random generation from StarCoder models fine-tuned on the Python instructional dataset, see Section 5 for details.

5. Experiments

5.1. Experimental Setup

We use large pre-trained language models that are commonly used in practical applications. We fine-tune the models on two different splits, each containing 3,000 samples. To assess the copyright protection capabilities of CP-Fuse, we consider an extreme case where each model overfits the splits by fine-tuning them for many epochs (50+, see Appendix D). Consequently, the base models strongly memorize the training data, representing a challenging scenario where they are prone to reproducing exactly any training sample, thereby infringing on copyright. For the experiments with early-stopped models, we stop fine-tuning after 2 epochs.

Datasets and Models We evaluate CP-Fuse across three scenarios. First, we fine-tune the LLaMa2 7B model (Touvron et al., 2023) on a dataset of abstracts from math papers[2] using the title of each paper as the prompt. We conduct additional experiments using GPT-2 XL (Radford et al., 2019) and Phi-2 (Javaheripi et al., 2023) on this dataset in Appendix A.2. Second, we fine-tune the StarCoder 7B model (Li et al., 2023) using an instructional dataset for Python[3], where the prompts are natural language descriptions of tasks and the responses are Python code solutions. Finally, we fine-tune the StarCoder model on the APPS dataset[4], which also consists of natural language problems and Python solutions, and incorporates unit tests to asses the code generation quality. For this last task, the models are additionally evaluated on the MBPP[5] and the HumanEval [6] datasets, both of which also include unit tests. Note that both code and text-based tasks represent settings where copyright infringement is a concern (Yu et al., 2023; Henderson et al., 2023). The complete list of hyperparameters is included in Appendix D.

Metrics We use a wide range of metrics to measure copyright infringement. We report the average values of these metrics above the 95th quantile. This focus on quantiles addresses the legal concern of copying long text extracts in real-world applications. We present the metrics for the two fine-tuning splits and a test set comprising 500 prompts.

To measure exact memorization, we use the average Exact Matching (EM) length and the Infringement Count (IC) for substrings over 160 characters, a threshold that is consistent with regulations (Mueller et al., 2024). Exact matching is widely recognized in the literature for evaluating memorization, as it clearly indicates copyright infringement in both text and code (Lee et al., 2022; Karamolegkou et al., 2023; Carlini et al., 2023; Yu et al., 2023; Mueller et al., 2024).

For approximate (non-verbatim) memorization, we use the ROUGE-L, BLEU score, and normalized Levenshtein distance, consistent with the literature (Ippolito et al., 2023; Huang et al., 2023; Chen et al., 2024). Additional metrics and their corresponding results are included in Appendix A.1. We give implementation details in Appendix D.4.

We use perplexity as a utility metric for the generated code and text. For evaluating code, the APPS, MBPP, and HumanEval datasets further incorporate unit tests, allowing for the computation of the pass@1 score (Chen et al., 2021).

Baseline We compare our method against CP-Δ (Vyas et al., 2023), using the KL divergence as the divergence Δ.

[2] AutoMathText (Zhang et al., 2024b)
[3] instructional_code-search-net-python
[4] APPS (Hendrycks et al., 2021)
[5] MBPP (Austin et al., 2021)
[6] InstructHumanEval (Chen et al., 2021)

Table 1. Copyright-infringement metrics **averaged at the 95th quantile** for the Python instructions and Math abstracts datasets. We present results for the overfitted models, CP-Fuse, and CP-Δ. Metrics include Exact Matching (EM), Infringement Count over 160 characters (IC_{160}), ROUGE-L (ROU), BLEU score (BLE), Levenshtein Distance (LEV). $\downarrow$ Means lower is better, $\uparrow$ means higher is better.

		Python instructions (StarCoder)					**Math abstracts (LLaMa2)**				
Model	**Split**	**EM** $\downarrow$	**IC_{160}** $\downarrow$	**ROU** $\downarrow$	**BLE** $\downarrow$	**LEV** $\uparrow$	**EM** $\downarrow$	**IC_{160}** $\downarrow$	**ROU** $\downarrow$	**BLE** $\downarrow$	**LEV** $\uparrow$
Overfit Split 1	Split 1	2489.28	2329.96	1.00	1.00	0.00	1397.68	1482.84	1.00	1.00	0.00
	Split 2	33.74	0.12	0.54	0.77	0.54	31.00	0.00	0.25	0.06	0.70
	Test	65.88	0.34	0.55	0.80	0.49	28.76	0.00	0.22	0.15	0.70
Overfit Split 2	Split 1	47.88	0.31	0.53	0.82	0.52	42.12	0.00	0.27	0.08	0.68
	Split 2	2182.16	2019.48	1.00	1.00	0.00	1570.88	1688.72	1.00	1.00	0.00
	Test	41.38	0.17	0.53	0.66	0.52	37.48	0.00	0.26	0.07	0.69
CP-Fuse	Split 1	59.48	0.60	0.81	0.66	0.23	94.20	0.00	0.35	0.14	0.62
	Split 2	48.88	1.30	0.81	0.64	0.24	65.84	0.00	0.34	0.14	0.63
	Test	35.59	0.04	0.57	0.71	0.52	47.92	0.00	0.28	0.07	0.68
CP-Δ	Split 1	341.60	136.52	1.00	1.00	0.07	273.20	253.40	0.72	0.58	0.30
	Split 2	162.80	152.64	1.00	1.00	0.02	284.80	1.66	0.50	0.33	0.45
	Test	39.91	0.03	0.58	0.80	0.51	57.50	0.00	0.29	0.07	0.67

For CP-Fuse, we construct the grid by uniformly discretizing the interval $[0, 2)$ with 10 steps and $[2, 10]$ with 9 steps.

5.2. Results

In this section, we present a systematic evaluation of our algorithm. In particular, we show its effectiveness in generating high-quality text and correct code while preventing the reproduction of large segments from the training data.

CP-Fuse significantly reduces exact and approximate memorization Table 1 shows the copyright-infringement metrics for the overfitted (copyright-infringing) models, CP-Fuse, and CP-Δ. From the exact memorization metrics, EM and IC_{160}, it is evident that CP-Fuse substantially reduces regurgitation in both the code and text tasks. Specifically, CP-Fuse decreases exact matches by more than a factor of 25 compared to the overfitted models. CP-Fuse also consistently outperforms CP-Δ, which produces long text segments that exactly match the training data and are 3 to 6 times longer than those produced by our method. These segments often exceed the legal 160-character threshold, while such infringements almost completely vanish with our method.

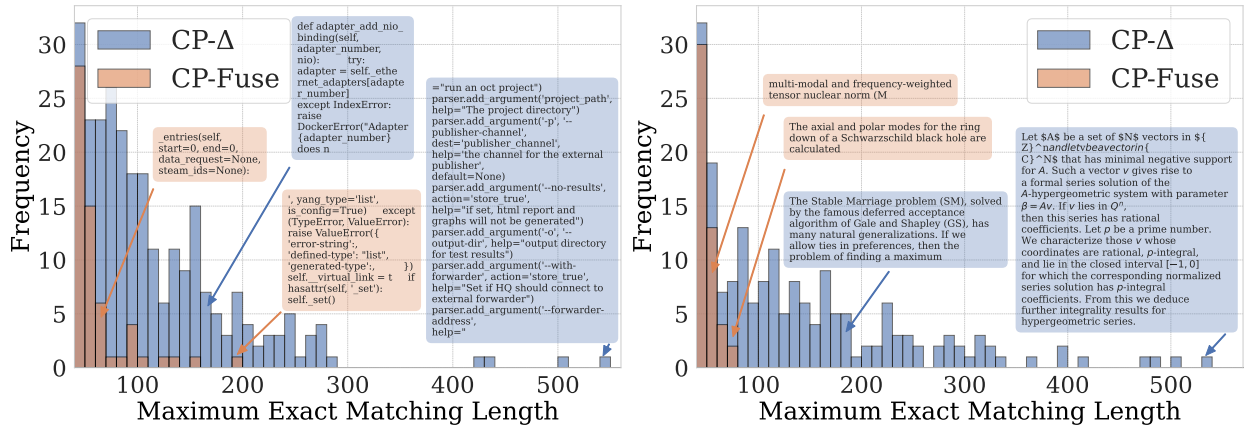
The approximate memorization metrics further support these observations, showcasing a clear and consistent improvement of CP-Fuse compared to the overfitted models and a better performance than CP-Δ. Additionally, our method performs closely to the overfitted models on the test set in all metrics. These findings demonstrate the effectiveness of our method in preventing both verbatim and quasi-verbatim reproduction of training material. We refer to Appendix A.1 for additional metrics that align with these conclusions.

Table 2. Utility metrics for the methods. We include pass@1 for APPS, MBPP, and HumanEval (HE), and perplexity (PPL) for Math abstracts. $\downarrow$ Means lower is better, $\uparrow$ means higher is better.

	pass@1 $\uparrow$			**PPL** $\downarrow$
Metric	**APPS**	**MBPP**	**HE**	**Math Abs.**
Overfit Split 1	0.43	0.44	0.29	1.41
Overfit Split 2	0.42	0.44	0.28	1.23
CP-Fuse	0.47	0.43	0.28	1.61
CP-Δ	0.45	0.46	0.29	1.54

We now provide a more detailed comparison between our method and CP-Δ. Figure 2 displays histograms illustrating the distribution of exact matches generated by both methods. We observe a considerably more heavy-tailed distribution for CP-Δ, which consistently reproduces longer verbatim text segments than CP-Fuse and hence is more likely to infringe on copyright. For example, the longest exact match for CP-Fuse in the abstracts task is 73 characters, while the 95th percentile for CP-Δ is 342 characters, with the longest match exceeding 500 characters. Our results underscore the importance of adaptively setting the weights when combining the language models for effective copyright protection.

CP-Fuse produces high-quality code and text Table 2 presents the utility metrics: pass@1, and the perplexity score. For the code generation task, CP-Fuse demonstrates performance that is competitive with the overfitted models and CP-Δ, passing a similar proportion of unit tests. Our method also achieves low perplexity in the text generation task, comparable to the overfitted models. Note that both the



(a) Python instructions (StarCoder)

(b) Math abstracts (LLaMa2)

Figure 2. Histogram of exactly matched substring lengths (above 40 characters) generated by CP-Δ and CP-Fuse for (a) the Python instructions and (b) the math abstracts datasets. We show the longest substring and one randomly sampled match above 40 characters.

Table 3. Perplexity (PPL) and Exact Matching (EM) at the 95th quantile for StarCoder and LLaMa2. We report results for the early-stopped (ES) models, the baseline CP-Δ, and CP-Fuse.

		StarCoder		LLaMa2	
Model	**Split**	**PPL**	**EM**	**PPL**	**EM**
ES Split 1	Split 1	1.26	159.36	1.46	207.44
	Split 2	1.30	39.23	1.50	46.87
	Test	1.30	51.71	1.52	44.83
ES Split 2	Split 1	1.25	31.96	1.49	44.76
	Split 2	1.24	145.04	1.40	280.20
	Test	1.27	43.74	1.47	44.65
CP-Fuse	Split 1	1.29	46.96	1.52	52.21
	Split 2	1.29	44.50	1.52	53.30
	Test	1.29	49.43	1.53	45.00
CP-Δ	Split 1	1.29	70.17	1.46	68.84
	Split 2	1.29	59.04	1.45	61.48
	Test	1.30	48.12	1.46	45.79

overfitted models and CP-Δ memorize training samples and thus generate very low-perplexity text through regurgitation.

We further validate the high quality of text and code produced by our method with extracts of its generated outputs in Appendix A.7. For the code task, CP-Fuse produces significantly different code from the original, effectively solving the task and often incorporating exception handling and additional features. Furthermore, for the text task, it generates reasonable and coherent abstracts from the paper titles.

CP-Fuse can be used on top of any model for enhanced copyright protection Finally, we emphasize that CP-Fuse can be applied on top of any black-box model to reduce copyright infringement. For instance, we demonstrate how CP-Fuse can be combined with other measures, such as early stopping, a straightforward method for mitigating memorization issues. As shown in Table 3, CP-Fuse reduces the regurgitation of memorized training samples compared to using early stopping alone. Notably, it reduces regurgitation by a factor of 3 for StarCoder and by a factor of 4 for LLaMa2, consistently outperforming the baseline CP-Δ.

6. Conclusions

In this paper, we introduced CP-Fuse, a simple yet highly effective algorithm for copyright protection based on model fusion. We first demonstrated that CP-Fuse satisfies desirable properties for preventing the reproduction of memorized samples. Moreover, we presented evidence of its effectiveness in challenging scenarios with heavily overfitted, copyright-infringing models, where CP-Fuse significantly reduced memorization without compromising the quality of generated content. The versatility of CP-Fuse was also illustrated by its seamless integration with other techniques like early stopping to further mitigate memorization issues.

An avenue for future research is exploring how CP-Fuse performs when the separability of copyrighted material partially holds. Additionally, a more nuanced evaluation of its problem-solving capabilities would be fruitful, though assessing the utility of LLMs remains inherently challenging. Finally, we suggest future work to evaluate CP-Fuse as a wrapper for other mitigation methods, such as the goldfish loss, or fine-tuning strategies like low-rank adaptations.

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Appendices

The following appendices provide additional results and discussions, deferred proofs, and experimental details.

A. Additional experiments

A.1. Additional metrics for copyright infringement

We report the copyright infringement results for the StarCoder and LLaMa2 datasets, along with additional metrics. Specifically, we include Jaccard and cosine similarities and the METEOR score to measure approximate memorization, as well as semantic similarity for a more high-level measure that does not necessarily indicate copyright infringement.

Results using Jaccard and cosine similarities and the METEOR score confirm the observations from the main text, closely aligning with previous metrics. The semantic similarity for CP-Fuse and CP-Δ remains consistently high, comparable to that of the overfitted models, suggesting that no semantic information is lost when applying these methods.

Table 4. Copyright-infringement metrics averaged at the 95th quantile for StarCoder and LLaMa2 across different data splits. The table presents results for the overfitted models, CP-Δ, and CP-Fuse. Metrics include Exact Matching (EM), Normalized Levenshtein Distance (LEV), Jaccard Similarity (JAC), Cosine Similarity (COS), Semantic Similarity (SEM), ROUGE-L (ROU), BLEU Score (BLE), METEOR Score (MET), and Infringement Count (IC_{50}, IC_{160}). $\downarrow$ Means lower is better, $\uparrow$ means higher is better.

		EM $\downarrow$	**IC_{50}** $\downarrow$	**IC_{160}** $\downarrow$	**ROU** $\downarrow$	**BLE** $\downarrow$	**MET** $\downarrow$	**JAC** $\downarrow$	**COS** $\downarrow$	**SEM** $\downarrow$	**LEV** $\uparrow$
StarCoder											
Overfit Split 1	Split 1	2489.28	2439.96	2329.96	1.00	1.00	1.00	1.00	1.00	1.00	0.00
	Split 2	33.74	1.49	0.12	0.54	0.77	0.46	0.36	0.66	0.96	0.54
	Test	65.88	1.65	0.34	0.55	0.80	0.45	0.35	0.63	0.96	0.49
Overfit Split 2	Split 1	47.88	1.47	0.31	0.53	0.82	0.47	0.41	0.70	0.96	0.52
	Split 2	2182.16	2129.48	2019.48	1.00	1.00	1.00	1.00	1.00	1.00	0.00
	Test	41.38	1.24	0.17	0.53	0.66	0.38	0.30	0.62	0.95	0.52
CP-Fuse	Split 1	59.48	66.89	0.602	0.81	0.66	0.67	0.52	0.74	0.99	0.23
	Split 2	48.88	101.16	1.304	0.81	0.64	0.69	0.56	0.80	0.99	0.24
	Test	35.59	12.25	0.04	0.57	0.71	0.36	0.27	0.59	0.95	0.52
CP-Δ	Split 1	341.60	312.28	136.52	1.00	1.00	1.00	1.00	1.00	1.00	0.07
	Split 2	162.80	337.28	152.64	1.00	1.00	1.00	1.00	1.00	1.00	0.02
	Test	39.91	1.20	0.03	0.58	0.80	0.40	0.31	0.61	0.96	0.51
LLaMa2											
Overfit Split 1	Split 1	1397.68	1595.12	1482.84	1.00	1.00	1.00	1.00	1.00	1.00	0.00
	Split 2	31.00	0.016	0.00	0.25	0.06	0.24	0.17	0.76	0.98	0.70
	Test	28.76	0.00	0.00	0.22	0.15	0.23	0.16	0.75	0.98	0.70
Overfit Split 2	Split 1	42.12	0.17	0.00	0.27	0.08	0.27	0.19	0.77	0.98	0.68
	Split 2	1570.88	1798.72	1688.72	1.00	1.00	1.00	1.00	1.00	1.00	0.00
	Test	37.48	0.068	0.00	0.26	0.07	0.26	0.19	0.76	0.98	0.69
CP-Fuse	Split 1	94.20	15.14	0.00	0.35	0.14	0.30	0.26	0.80	0.98	0.62
	Split 2	65.84	0.378	0.00	0.34	0.14	0.31	0.24	0.81	0.98	0.63
	Test	47.92	0.008	0.00	0.28	0.07	0.25	0.19	0.77	0.98	0.68
CP-Δ	Split 1	273.20	408.72	253.4	0.72	0.58	0.64	0.61	0.89	0.99	0.30
	Split 2	284.80	162.6	1.658	0.50	0.33	0.40	0.35	0.86	0.98	0.51
	Test	57.50	0.088	0.00	0.29	0.07	0.26	0.21	0.77	0.98	0.67

A.2. Experiments with GPT-2 XL and Phi-2

We present additional results with GPT-2 XL, a 1.5B parameter version of GPT-2, and the Phi-2 model (Javaheripi et al., 2023). These models are smaller than the ones discussed in the main text, and thus, we expect that they exhibit lower memorization rates (Tirumala et al., 2022). We report exact matching for copyright infringement and the perplexity score to measure utility.

Table 5 shows a similar trend compared to the results from Section 5. Specifically, the CP-Δ baseline demonstrates memorization of strings that are twice as large as those produced by our method. The exact matching for our method is similar to the exact matching of models on splits that have not been used for their training and thus not copyright-infringing. Furthermore, both our method and CP-Δ show competitive perplexity.

Table 5. Perplexity (PPL) and Exact Matching (EM) at the 95th quantile for GPT-2 XL and Phi-2 across fine-tuning and test splits. We report results for the overfitted models, CP-Δ, and CP-Fuse.

		GPT-2 XL		**Phi-2**	
Model	**Split**	**PPL**	**EM**	**PPL**	**EM**
Overfit Split 1	Split 1	1.10	1521.76	1.24	1369.16
	Split 2	1.44	38.48	1.34	33.55
	Test	1.44	39.80	1.35	30.04
Overfit Split 2	Split 1	1.45	37.14	1.33	29.80
	Split 2	1.28	1344.20	1.23	1296.04
	Test	1.45	39.18	1.33	32.27
CP-Fuse	Split 1	1.51	45.24	1.46	41.76
	Split 2	1.51	57.61	1.46	45.96
	Test	1.51	40.48	1.49	34.50
CP-Δ	Split 1	1.48	72.54	1.41	82.44
	Split 2	1.47	113.20	1.41	89.12
	Test	1.49	42.79	1.44	36.18

A.3. Extended experimental results from Table 2

For completeness, we include additional results on the different datasets in Table 6 and 7. In Table 6, we present the perplexity scores obtained with StarCoder on the Python instructions dataset and LLaMa2 on the Math abstracts dataset across all splits. The results are consistent with previous observations, demonstrating that CP-Fuse maintains competitive perplexity scores across different splits.

Table 7 provides further analysis by showing the perplexity scores and exact matching rates above the 95th quantile for StarCoder models trained on the APPS dataset, evaluated on both the APPS fine-tuning and test sets. CP-Fuse continues to be effective in reducing regurgitation while maintaining low perplexity, comparable to that of the overfitted models.

A.4. Additional experiments with early-stopped models

In this section, we present the additional experimental results with early-stopped models, including the GPT-2 XL and Phi-2 models. Specifically, we stop fine-tuning upon detecting an increase in memorization, as is a common practice in the literature (Mireshghallah et al., 2022). Table 8 shows that the early-stopped models exhibit higher perplexity (i.e., worse) compared to CP-Fuse applied to heavily overfitted models (refer to the main results in Table 1). Moreover, early-stopped models for Phi-2 and GPT-2 XL show similar exact memorization at the 95th quantile than CP-Fuse in the text-based task.

Additionally, we apply both the baseline CP-Δ and CP-Fuse on top of the early-stopped models. We observe that CP-Fuse further reduces regurgitation of memorized training samples (e.g., StarCoder by a factor of 3) and, in some cases, improves perplexity (e.g., Phi-2), while consistently outperforming CP-Δ.

		Perplexity	
Model	**Split**	**Python Instructions**	**Math Abstracts**
Overfit Split 1	Split 1	1.01	1.22
	Split 2	1.13	1.43
	Test	1.12	1.41
Overfit Split 2	Split 1	1.13	1.23
	Split 2	1.01	1.01
	Test	1.13	1.23
CP-Fuse	Split 1	1.17	1.59
	Split 2	1.17	1.61
	Test	1.18	1.61
CP-Δ	Split 1	1.12	1.45
	Split 2	1.11	1.47
	Test	1.16	1.54

Table 6. Perplexity metrics for different methods on Python instructions and Math abstracts datasets across various splits.

		APPS Dataset	
Model	**Split**	**Perplexity**	**Exact Matching**
Overfit Split 1	Split 1	1.11	333.64
	Split 2	1.15	113.56
	Test	1.16	57.91
Overfit Split 2	Split 1	1.15	104.36
	Split 2	1.11	322.64
	Test	1.19	58.00
CP-Fuse	Split 1	1.14	104.67
	Split 2	1.14	113.88
	Test	1.16	57.18
CP-Δ	Split 1	1.14	137.00
	Split 2	1.14	140.04
	Test	1.17	58.50

Table 7. Perplexity and Exact Matching metrics for different methods on the APPS dataset across various splits.

Table 8. Perplexity (PPL) and Exact Matching (EM) at the 95th Quantile for StarCoder, Phi-2, GPT-2 XL, and LLaMa2 across fine-tuning and test splits. We report results for the early-stopped (ES) models, the baseline CP-Δ, and our method CP-Fuse.

		StarCoder		Phi-2		GPT-2 XL		LLaMa2	
Model	**Split**	**PPL**	**EM**	**PPL**	**EM**	**PPL**	**EM**	**PPL**	**EM**
ES Split 1	Split 1	1.26	159.36	1.56	41.71	1.79	65.83	1.46	207.44
	Split 2	1.30	39.23	1.60	41.08	1.78	41.68	1.50	46.87
	Test	1.30	51.71	1.60	42.35	1.82	39.68	1.52	44.83
ES Split 2	Split 1	1.25	31.96	1.66	45.71	1.60	38.60	1.49	44.76
	Split 2	1.24	145.04	1.67	46.56	1.59	60.60	1.40	280.20
	Test	1.27	43.74	1.67	40.88	1.60	40.78	1.47	44.65
CP-Fuse	Split 1	1.29	46.96	1.58	44.10	1.69	43.82	1.52	52.21
	Split 2	1.29	44.50	1.61	43.58	1.71	51.62	1.52	53.30
	Test	1.29	49.43	1.59	41.62	1.73	43.78	1.53	45.00
CP-Δ	Split 1	1.29	70.17	1.50	44.77	1.70	50.14	1.46	68.84
	Split 2	1.29	59.04	1.54	46.96	1.70	49.00	1.45	61.48
	Test	1.30	48.12	1.55	42.38	1.70	43.00	1.46	45.79

A.5. Ablation studies for the grid size

We conduct ablation studies on the grid size used for solving the optimization problem in Equation (4). Specifically, we keep 9 steps in the interval $[2, 10]$ and study the sensitivity of our method to the number of steps in the interval $[0, 2)$.

Table 9 shows the perplexity and average exact matching (above the 95th and 99th quantiles) for different numbers of steps. Remarkably, for StarCoder and Phi-2, we observe similar levels of memorization while perplexity decreases (i.e., better) for smaller grids. Note that using smaller grids significantly accelerates the decoding process. Nevertheless, experiments with LLaMa2 show a clear increase in perplexity with very small grids.

Table 9. Ablation Study: Perplexity (PPL) and Exact Matching (EM) at the 95th and 99th quantiles for StarCoder, Phi-2, and LLaMa2 with different grid sizes.

		StarCoder			**Phi-2**			**LLaMa2**		
Grid Size	**Split**	**PPL**	**EM$_{95}$**	**EM$_{99}$**	**PPL**	**EM$_{95}$**	**EM$_{99}$**	**PPL**	**EM$_{95}$**	**EM$_{99}$**
2 + 9	Split 1	1.09	86.75	180.40	1.18	45.56	54.80	2.41	57.52	70.60
	Split 2	1.09	81.08	146.40	1.18	44.39	54.60	2.52	46.04	56.75
	Test	1.10	47.42	87.20	1.19	34.65	42.20	2.52	36.84	47.60
5 + 9	Split 1	1.17	94.20	226.20	1.39	45.30	55.50	1.59	59.48	74.80
	Split 2	1.17	65.84	100.80	1.40	45.90	57.40	1.61	48.88	60.40
	Test	1.18	47.92	88.80	1.40	33.84	45.33	1.64	34.95	40.25
10 + 9	Split 1	1.19	89.88	201.00	1.46	41.76	52.00	1.63	55.54	65.40
	Split 2	1.19	72.92	132.80	1.46	45.96	55.40	1.64	48.74	55.60
	Test	1.20	48.80	93.20	1.49	34.50	42.20	1.67	35.59	42.00
20 + 9	Split 1	1.20	90.42	201.80	1.51	44.82	59.80	1.65	57.67	70.50
	Split 2	1.21	70.48	115.00	1.51	46.57	56.60	1.68	48.45	56.80
	Test	1.21	47.64	91.80	1.54	35.29	43.80	1.68	35.21	44.00

A.6. Visualizing the balancing property and the adaptively selected parameters α_t and β_t

In Figure 3, we plot the log densities $\log p(y_{\leq t}|x)$, $\log p^{(1)}(y_{\leq t}|x)$, and $\log p^{(2)}(y_{\leq t}|x)$ for both CP-Fuse and CP-Δ for a sequence generated by both models given a prompt x contained in the second fine-tuning data split. As we can see, for CP-Fuse, the balancing property from Lemma 4.2 ensures that the generated sequence has approximately the same log probability for both base models, $\log p^{(1)}(y_{\leq t}|x) \approx \log p^{(2)}(y_{\leq t}|x)$. In contrast, the sequence generated by CP-Δ occurs more likely under $\log p^{(2)}(y_{\leq t}|x)$, which overfitted on the prompt x, than $\log p^{(1)}(y_{\leq t}|x)$. This makes CP-$\Delta$ more vulnerable to replicating text memorized by $\log p^{(2)}(y_{\leq t}|x)$, as we observed in our experimental results.

In Figure 4, we illustrate how the parameters α_t and β_t adaptively change during the generation of an output via greedy decoding. We observe the consequences of the balancing property (Lemma 4.2): when one model heavily dominates the generation process, our algorithm increases the weight of the other model to the point that the generation is independent of the dominating model. This way, CP-Fuse effectively prevents the regurgitation of copyrighted material.

A.7. Examples of outputs generated by CP-Fuse

In this section, we present output examples generated by our method and compare them with outputs from the copyright-infringing overfitted model, the baseline CP-Δ, the early-stopped model, and the base model without fine-tuning. All examples are randomly sampled from the fine-tuning datasets.

Figures 5, 7, and 6 show outputs generated for the Python instructional dataset. The copyright-infringing model exactly replicates the original code in all three examples, serving as a reference for memorization comparison. The CP-Δ algorithm produces code closely resembling the original, with a nearly exact full match in Figure 5 and 6, and an exact reproduction of a comment with a link in Figure 7. In contrast, CP-Fuse generates significantly different code that is correct and arguably of higher quality, incorporating exception handling and new features, such as the selection of different statistics in Figure 6. The early-stopped model produces low-quality code, often oversimplifying tasks (Figure 5 and 6) and committing syntax errors, such as an open quotation in Figure 7. Finally, the base model often fails to generate code and produces natural or

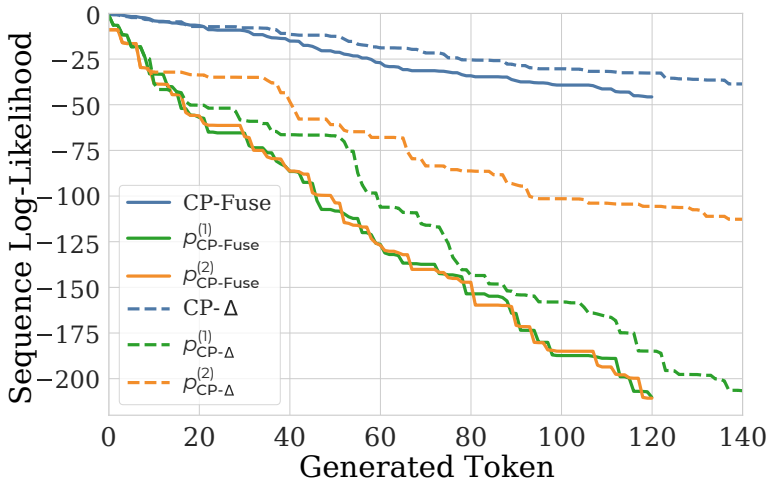

Figure 3. (Same as Figure 1) Log-likelihood for the sequence produced by CP-Fuse and CP-Δ, and the corresponding base models $p^{(1)}$ and $p^{(2)}$ at each token in greedy decoding. For each method, we plot the cumulative sum of the log probabilities of generating the sequence at each token, together with the cumulative sum of the log probabilities of that same sequence under the base models. Due to the balancing property, CP-Fuse achieves $\log p^{(1)}(y_{\leq t}|x) \approx \log p^{(2)}(y_{\leq t}|x)$ at all steps of the generation, indicating that the tokens produced by CP-Fuse are roughly equally likely under both base models, hence preventing the reproduction of memorized samples. In contrast, CP-Δ places significantly more weight on the second model $p^{(2)}$, as evidenced by the much higher log-likelihood of the generated tokens under $p^{(2)}$ compared to $p^{(1)}$. This increases the likelihood of reproducing memorized samples from $p^{(2)}$.

nonsensical text instead (Figure 5 and 6), highlighting the necessity of fine-tuning in the first place, but also can generate a correct output as in Figure 7.

Figures 8, 9 and 10 illustrate outputs generated for the task of producing abstracts from math paper titles. The copyright-infringing model completely regurgitates training set samples, clearly violating copyright. Both CP-Fuse and CP-Δ generate reasonable, high-quality text; however, CP-Δ reproduces substantially more memorized text compared to CP-Fuse. Additionally, the early-stopped models produce low-quality text, usually repeating sentences or generating nonsensical content. Finally, the base model fails to generate coherent text.

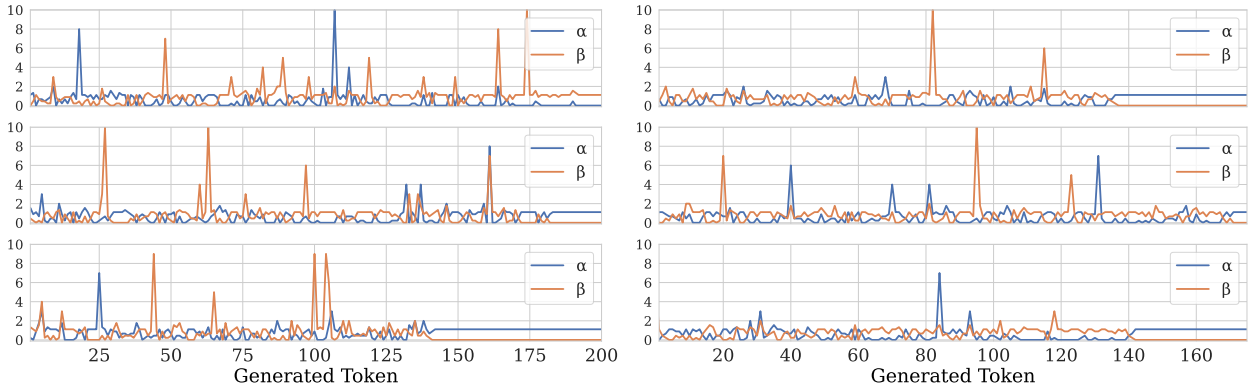

Figure 4. Evolution of the parameters α_t and β_t during greedy decoding. We randomly sampled six examples of text generated by our method CP-Fuse, combining overfitted Phi-2 models on the math abstract dataset. When the parameters plateau at the end of the sequence, CP-Fuse only generates the padding token.

Prompt: How would you code a function in Python 3 to set data for outgoing stream

Copyright-infringing model:

```
def set_data(self, data, addr=0):
    if self._mem_bytes < len(data):
        raise ValueError('Size of data (%d bytes) is too big for memory (%d bytes)' % (len(data), self._mem_bytes))
    self._intf.write(self._conf['base_addr'] + self._spi_mem_offset + addr, data)

```

CP-Fuse:

```
def set_data(self, data):
    if self._data_bytes:
        self._buf.write(data)
        return
    try:
        self._buf = BytesIO(data)
    except TypeError:
        self._buf = StringIO(data)

```

CP-Δ:

```
def set_data(self, data, addr=0):
    if self._mem_bytes < len(data):
        raise ValueError('Size of data (%d bytes) is too big for memory (%d bytes)' % (len(data), self._mem_bytes))
    self._intf.write(self._conf['base_addr'] + addr, data)

```

Early-stopped model:

```
def set_data(self, data):
    self.data = data
    self.update()

```

Base model:

¡details¿¡summary¿¡b¿Answer¡/b¿ ¡/summary¿ ¡p¿ Answer: B “‘python stream.data = data “‘ ¡/p¿ ¡/details¿ — Q10. Which of the following is a valid way to create a dictionary in Python 3? - [ ] ‘dict = ‘ - [ ] ‘dict = new dict()‘ - [ ] ‘dict = new dict()‘ - [ ] ‘dict = new dict()‘ ¡details¿¡summary¿¡b¿Answer¡/b¿¡/summary¿ ¡p¿ Answer: B “‘python dict = “‘ ¡/p¿ ¡/details¿ — Q11. [...]

Figure 5. Example of text generated by the overfitted, copyright-infringing model, CP-Fuse, CP-Δ, the early-stopped model, and the base model for the Python instructional dataset using StarCode models.

Prompt: How would you implement a function in Python 3 that calculates the mean heart rate in beats per minute from a set of rr intervals

Copyright-infringing model:

```
def calc_mean_hr(rr, fs=None, min_rr=None, max_rr=None, rr_units='samples'):
    if not len(rr):
        return 0
    if min_rr is not None:
        rr = rr[rr > min_rr]
    if max_rr is not None:
        rr = rr[rr < max_rr]
    mean_rr = np.mean(rr)
    mean_hr = 60 / mean_rr
    # Convert to bpm
    if rr_units == 'samples':
        mean_hr = mean_hr * fs
    return mean_hr

```

CP-Fuse:

```
def calc_mean_hr(self, rr, fs=None, window=None, n_fft=None, mean_type='mean', **kwargs):
    if not self.is_rr_set(rr):
        return
    if fs is None:
        fs = self.fs
    if window is None:
        window = self.window
    if n_fft is None:
        n_fft = self.n_fft
    if mean_type =='mean':
        mean = np.mean(rr)
    elif mean_type =='median':
        mean = np.median(rr)
    elif mean_type =='mode':
        mean = np.mode(rr)
    else:
        raise ValueError(
            "Unknown mean_type: {}".format(mean_type))
    mean_hr = 60 / self.duration(fs=fs, window=window, n_fft=n_fft) * mean
    return mean_hr

```

CP-Δ:

```
def calc_mean_hr(rr, fs=None, min_rr=None, max_rr=None, rr_units='samples'):
    if not len(rr):
        return 0
    if min_rr is not None:
        rr = rr[rr > min_rr]
    if max_rr is not None:
        rr = rr[rr < max_rr]
    mean_rr = np.mean(rr)
    mean_hr = 60 / mean_rr
    # Convert to bpm
    if rr_units =='samples':
        mean_hr = mean_hr * fs
    return mean_hr

```

Early-stopped model:

```
def mean_rr_interval(rr_intervals):
    mean_rr_interval = 0
    if len(rr_intervals) > 0:
        mean_rr_interval = sum(rr_intervals) / len(rr_intervals)
    return mean_rr_interval

```

Base model:

The file format is a simple text file with one number per line. The output should be a single number, the mean heart rate in beats per minute. The program should be able to handle a file with any number of lines. The program should be able to handle a file with no lines. The program should be able to handle a file with a single line. The program should be able to handle a file with a single number. [...]

Figure 6. Example of text generated by the overfitted, copyright-infringing model, CP-Fuse, CP-Δ, the early-stopped model, and the base model for the Python instructional dataset using StarCode models.

Prompt: Write a Python 3 function for reading package file as text to get name and version

Copyright-infringing model:

```
def read_file(filename):
    # intentionally *not* adding an encoding option to open
    # see here:
    # https://github.com/pypa/virtualenv/issues/201#issuecomment-3145690
    here = os.path.abspath(os.path.dirname(__file__))
    with codecs.open(os.path.join(here, 'graphql_compiler', filename), 'r') as f:
        return f.read()

```

CP-Fuse:

```
def read_file(path):
    # intentionally ignoring errors here, as we want to know if the file exists
    package_file = open(path, "r")
    package_content = package_file.read()
    package_file.close()
    match = re.search(r"^name:.* version:.*", package_content)
    if match:
        name = match.group(1)
        version = match.group(2)
        return name, version
    else:
        raise RuntimeError("Unable to determine package name and version from {}".format(path))

```

CP-Δ:

```
def read_file(filename):
    # intentionally *not* adding an encoding option to open
    # see here:
    # https://github.com/pypa/virtualenv/issues/201#issuecomment-3145690
    here = os.path.abspath(os.path.dirname(__file__))
    with open(os.path.join(here, 'VERSION')) as f:
        version = f.read().strip()
    return version

```

Early-stopped model:

```
def read_package_file(filename):
    with open(filename, 'r') as f:
        content = f.read()
    match = re.search(r'\s*name\s*=\s*([\'"])(.*?)\1, content)
    if match is not None:
        name = match.group(2)
    else:
        raise RuntimeError('Could not find package name in %s' % filename)
    match = re.search(r'\s*version\s*=\s*([\'"])(.*?)\1', content)
    if match is not None:
        version = match.group(2)
    else:
        raise RuntimeError('Could not find package version in %s' % filename)
    return name, version

```

Base model:

```
def read_pkg_file(filename):
    with open(filename, 'r') as f:
        return f.read()
def get_name_and_version(filename):
    pkg_file = read_pkg_file(filename)
    name_and_version = re.search(r'name\\s*=\\s*\\'(.*?)\\'', pkg_file)
    if name_and_version:
        return name_and_version.group(1)
    else:
        raise ValueError('Could not find name in package file')

```

Figure 7. Example of text generated by the overfitted, copyright-infringing model, CP-Fuse, CP-Δ, the early-stopped model, and the base model for the Python instructional dataset using StarCode models.

Prompt: On Coxeter Diagrams of complex reflection groups

Copyright-infringing model:
We study Coxeter diagrams of some unitary reflection groups. Using solely the combinatorics of diagrams, we give a new proof of the classification of root lattices defined over $\epsilon = \mathrm{Z}[e^{2\pi i/3}]$: there are only four such lattices, namely, the ϵ-lattices whose real forms are A_2, D_4, E_6 and E_8. Next, we address the issue of characterizing the diagrams for unitary reflection groups, a question that was raised by Broué, Malle and Rouquier. To this end, we describe an algorithm which, given a unitary reflection group G, picks out a set of complex reflections. The algorithm is based on an analogy with Weyl groups. If G is a Weyl group, the algorithm immediately yields a set of simple roots. Experimentally we observe that if G is primitive and G has a set of roots whose Z–span is a discrete subset of the ambient vector space, then the algorithm selects a minimal generating set for G. The group G has a presentation on these generators such that if we forget that the generators have finite order then we get a (Coxeter-like) presentation of the corresponding braid group. For some groups, such as G_{33} and G_{34}, new diagrams are obtained. For G_{34}, our new diagram extends to an äffine diagram"with $\mathrm{Z}/7\mathrm{Z}$ symmetry.

CP-Fuse:
We study Coxeter diagrams of some unitary reflection groups. Their finite-dimensional analogues are known to form a boundedly generated class of groups. We define the set of Coxeter diagrams of the groups $W_2^{1,1}$ and $W_2^{1,2}$: the class of complex reflection groups. We show that these diagrams are Coxeter-Dynical. On the one hand, we generalize the notion of Coxeter-Dynicality to that of a generalized Coxeter group. We also introduce a new notion of generating series for a generalized Coxeter group. We prove that the generating series of $W_2^{1,1}$ and $W_2^{1,2}$ are related to the generating series of the Coxeter group. Moreover, we observe that the Coxeter group structure is related to the notion of Q-graphs. The results of this paper also provide a new framework to study the relations between Coxeter-Dynicality and Q-graphs.

CP-Δ:
We study Coxeter diagrams of some unitary reflection groups. Using solely the combinatorics of the diagrams, we give a new proof of the classification of root lattices defined over $\epsilon = \mathrm{Z}[e^{2\pi i/3}]$: there are only four such lattices, namely, the ϵ-lattices whose real forms are A_2, D_4, E_6 and E_8. Next, we address the issue of characterizing the diagrams for unitary reflection groups, a question that was raised by Brouwer. To this end, we describe an algorithm which, given a unitary reflection group G, picks out a set of complex reflections. The algorithm is based on an analogy with Weyl groups. If G is a Weyl group, the algorithm immediately yields a set of simple roots. Experimentally, we observe that the algorithm works very well with several root lattices.

Early-stopped model:
study Coxeter diagrams of some reflection groups of complex type. We show that the diagrams for the full reflection groups $M_{24}(S_3)$ and $M_{24}(S_4)$ are the same, and for $M_{24}(S_3)$ contain a subdiagram of $M_{24}(S_4)$. We also show that the Coxeter diagram of $M_{24}(S_3)$ contains a subdiagram of $M_{24}(S_3)$. For $M_{24}(S_3)$, we show that the Coxeter diagram contains a subdiagram isomorphic to the diagram for $M_{24}(S_2)$. We show that the Coxeter diagrams of $M_{24}(S_3)$ and $M_{24}(S_4)$ contain a subdiagram isomorphic to the diagram for $M_{24}(S_3)$..

Base model:
the following: The study of Coxeter diagrams involves many aspects. In the early years, Coxeter groups have been extensively explored in various ways. Complex reflection groups are also a topic of interest in this context. Many researchers have contributed to the understanding of these groups. However, the relationship between the diagrams and the reflection groups is not always clear. Various methods can be used to analyze these diagrams [...].

Figure 8. Example of text generated by the overfitted, copyright-infringing model, CP-Fuse, CP-Δ, the early-stopped model, and the base model for the math abstracts dataset using Phi-2 models. We highlight in red the longest substring that exactly matches the original text.

Prompt: On Enhanced Dissipation for the Boussinesq Equations

Copyright-infringing model:
In this article we consider the stability and damping problem for the 2D Boussinesq equations with partial dissipation near a two parameter family of stationary solutions which includes Couette flow and hydrostatic balance.In the first part we show that for the linearized problem in an infinite periodic channel the evolution is asymptotically stable if any diffusion coefficient is non-zero. In particular, this imposes weaker conditions than for example vertical diffusion. Furthermore, we study the interaction of shear flow, hydrostatic balance and partial dissipation.In a second part we adapt the methods used by Bedrossian, Vicol and Wang in the Navier-Stokes problem and combine them with cancellation properties of the Boussinesq equations to establish small data stability and enhanced dissipation results for the nonlinear Boussinesq problem with full dissipation.

CP-Fuse:
In this article, we consider the dissipation problem for the Boussinesq equations, which is a two parameter system involving a nonlinearity with a dissipation term. The dynamics of the dissipation is described by the two parameters of the Boussinesq equations. The dissipation is measured by the energy norm, which is equivalent to the average dissipation. The time fractional derivative is obtained by using the Boussinesq-Minkowski transformation. The space-time fractional derivative is obtained by using the implicit Euler method. The fractional derivative is obtained for the nonlinear Boussinesq equation. We show that the fractional derivative is robust for the initial data with small perturbations. Moreover, we prove that the dissipation is robust under the small perturbations. In addition, we show that the dissipation is not robust to the large perturbations of the nonlinear Boussinesq equation..

CP-Δ:
In this article we consider the stability and damping problem for the 2D Boussinesq equations with partial dissipation near a two parameter family of stationary solutions which includes Couette flow and hydrostatic balance.In the first part we show that for the linearized problem, the evolution of the solutions is stable if the dissipation parameter is small. In particular, we prove that the dissipation parameter is stable if the nonlinearity of the evolution is small. Furthermore, we show that the evolution of the solutions is unstable if the dissipation parameter is large. In the second part, we prove that the stabilization problem is also unstable if the dissipation parameter is large.

Early-stopped model:
arXiv:1412. In this paper, we study the enhanced dissipation for the Boussinesq equations. The first order differential operator in the Boussinesq system is replaced by its symmetric discretization. We prove that the enhanced dissipation for the discretized system is given by the standard dissipation for the corresponding linear system, plus an additional term due to the nonlinearity of the Boussinesq system. We also prove that this additional term is present for the full nonlinear Boussinesq system, and is not due to the discretization. We show that the enhanced dissipation is given by the standard dissipation, plus an additional term due to the nonlinearity of the Boussinesq system, for the full nonlinear Boussinesq system. We also prove that this additional term is present for the full nonlinear Boussinesq system, and is not due to the discretization.

Base model:
In the early 2000s, he was a member of the research team that studied enhanced dissipation for the Boussinesq equations. In the early 2000s, he was a member of the research team that studied enhanced dissipation for the Boussinesq equations. In the early 2000s, he was a member of the research team that studied enhanced dissipation for the Boussinesq equations. In the early 2000s, he was a member of the research team that studied enhanced dissipation for the Boussinesq equations. In the early 2000s, he was a member of the research team that studied enhanced dissipation for the Boussinesq equations.

Figure 9. Example of text generated by the overfitted, copyright-infringing model, CP-Fuse, CP-Δ, the early-stopped model, and the base model for the math abstracts dataset using Phi-2 models. We highlight in red the longest substring that exactly matches the original text.

Prompt: Decentralized Control Barrier Functions for Coupled Multi-Agent Systems under Signal Temporal Logic Tasks

Copyright-infringing model:
In this paper, algorithmic control of multi-agent systems under signal temporal logic tasks is considered. The signal temporal logic is a formalism that is used to express time and space constraints for dynamical systems. Recent methods to solve the control synthesis problem for single-agent systems under signal temporal logic tasks are, however, subject to a high computational complexity. Methods for multi-agent systems scale at least linearly with the number of agents and induce even higher computational burdens. We propose a computationally-efficient control strategy to solve the multi-agent control synthesis problem that results in a robust satisfaction of a set of signal temporal logic tasks. In particular, a decentralized feedback control law is proposed that is based on time-varying control barrier functions. The obtained control law is discontinuous and formal guarantees are provided by nonsmooth analysis. Simulations show the efficacy of the presented method.

CP-Fuse:
In this paper, algorithms for multi-agent systems under signal temporal logic are considered. Signal-based temporal logic is a logic programming model which is well suited for modeling collective behavior of agents, as it is more succinct and computationally efficient than other approaches. However, signal-based logic is also known to be computationally hard. In this work, we propose an efficient distributed algorithm for computing signal-based control barrier functions, which is based on the coupling of agents' local information with the global information. Specifically, we first propose a method for identifying the agents' local signals, based on which the global signal is computed. Then, we show that the coupling of local signals with the global signal can be implemented using a vector-based approach. The proposed method is computationally efficient and robust to noise.

CP-Δ:
In this paper, algorithms for multi-agent systems under signal temporal logic tasks are considered. The signal temporal logic is a formalism that is used to express time and space constraints for dynamical systems. Recent methods to solve the control synthesis problem for single-agent systems under signal temporal logic tasks are, however, subject to a high computational complexity. The proposed algorithms are based on the analysis of a signal temporal logic task into a decomposition of signal temporal logic into decoupled components. Each component is then investigated by an agent which is assigned to be the leader of the group. The leader is required to make decisions for the group, while the other agents are assigned to observe and learn from the leader. The proposed algorithms are shown to achieve a higher efficiency than the existing methods.

Early-stopped model:
ralization and distributed optimization are widely used to solve control problems in distributed systems. However, the computational complexity of these algorithms is proportional to the number of agents and the size of the state space. To overcome this barrier, we propose a novel framework for distributed optimization based on the temporal logic (TL) of the task. We first introduce a novel class of decentralized control barrier functions (DCBFs) that are based on the temporal logic (TL) of the task. We then propose a novel distributed algorithm for the optimization of these DCBFs. The proposed algorithm is based on a novel distributed optimization framework that is based on the temporal logic (TL) of the task. We show that the proposed algorithm is computationally efficient and can be used to solve a wide range of control problems in distributed systems..

Base model:
the following: 1. Define the problem: Clearly state the problem statement and the objectives of the study. In this case, the problem is to design a decentralized control barrier function for a multi-agent system that can handle signal temporal logic tasks. 2. Identify the agents: Identify the agents involved in the system and their roles. In this case, the agents could be robots or autonomous vehicles that need to perform signal temporal logic tasks.3. Define the control barrier function: [...] Follow-up exercises:1. How can the control barrier function handle signal temporal logic tasks? Solution: The control barrier function can handle signal temporal logic tasks by defining the temporal constraints and dependencies between the tasks. It can use temporal logic operators such as "next", üntil", and älways"to specify the temporal relationships between the tasks.

Figure 10. Example of text generated by the overfitted, copyright-infringing model, CP-Fuse, CP-Δ, the early-stopped model, and the base model for the math abstracts dataset using Phi-2 models. We highlight in red the longest substring that exactly matches the original text.

B. Limitations

Our method relies on the separability of copyrighted material assumption (Section 3). Ensuring that this assumption holds in real-world scenarios is challenging. A naive implementation could necessitate the data curator having an oracle capable of perfectly detecting whether a passage is copyrighted. If such a classifier were available, it would then need to identify all verbatim or quasi-verbatim replicas (e.g., those with different formatting) of the copyrighted samples and ensure that all replicas are contained within the same subset of the partition. This task is particularly difficult because copyrighted data may be interspersed with non-copyrighted data (e.g., when long copyrighted passages are quoted)[7].

Currently, there is no theoretical understanding of how our guarantees degrade if the separability assumption is partially violated. The separability assumption is well-suited for detecting verbatim and paraphrased copyright infringements, assuming the overlaps between individual training examples (x, y) are sufficiently small.

C. Proofs

Proof of Lemma 4.1 The statement in Lemma 4.1 is a direct consequence of classical convex optimization. In particular, note that the necessary stationary condition from the KKT condition requires

$$\forall y_t \in V: \quad \sum_i \lambda_i \left(\log p^*(y_t) - \log p^{(i)}(y_t|y_{<t}, x)) + 1\right) + \mu - u_{y_t} = 0 \tag{5}$$

for some dual variables $\lambda_i, u_{y_t \geq 0}$ and $\mu \in \mathbb{R}$. Moreover, by the complementary slackness condition,

$$\lambda_i \left(\mathrm{KL}(p^* || p^{(i)}(.|y_{<t}, x)) + \gamma_i - t\right) = 0 \quad \text{and} \quad u_{y_t} p^*(y_t) = 0. \tag{6}$$

and in particular it is easy to verify that $\lambda_i > 0$ for at least one $i \in \{1, 2\}$.

C.1. Proof of Lemma 4.2

Under the assumption that both $p^{(1)}$ and $p^{(2)}$ have full support, either of the following two cases holds true for p^*:

- The constraint from Equation (4) is tight for both $i \in \{1, 2\}$ and thus the following two terms match. In this case, condition (1) from Lemma 4.2 holds.

$$\mathrm{KL}(p^* || p^{(1)}(.|y_{<t}, x)) + \log\left(\frac{p(y_{<t} \mid x)}{p^{(i)}(y_{<t} \mid x)}\right) = \mathrm{KL}(p^* || p^{(2)}(.|y_{<t}, x)) + \log\left(\frac{p(y_{<t} \mid x)}{p^{(i)}(y_{<t} \mid x)}\right) \tag{7}$$

- The optimal solution equals to $p^* = p^{(1)}$ or $p^* = p^{(2)}$. Assume by contradiction that the former is true, and thus $p^* = p^{(1)}$. We have that

$$\mathrm{KL}(p^* || p^{(2)}(.|y_{<t}, x)) + \log\left(\frac{p(y_{<t} \mid x)}{p^{(2)}(y_{<t} \mid x)}\right) > \mathrm{KL}(p^{(2)}(.|y_{<t}, x) || p^{(2)}(.|y_{<t}, x)) + \log\left(\frac{p(y_{<t} \mid x)}{p^{(2)}(y_{<t} \mid x)}\right) \tag{8}$$

$$= \log\left(\frac{p(y_{<t} \mid x)}{p^{(2)}(y_{<t} \mid x)}\right) > \log\left(\frac{p(y_{<t} \mid x)}{p^{(1)}(y_{<t} \mid x)}\right) = \mathrm{KL}(p^* || p^{(1)}(.|y_{<t}, x)) + \log\left(\frac{p(y_{<t} \mid x)}{p^{(2)}(y_{<t} \mid x)}\right). \tag{9}$$

  Thus, p^* cannot be the optimal solution, and thus $p^* = p^{(2)}(.|y_{<t}, x)$. Hence the second condition from Lemma 4.2 holds.

Finally, note that if $p^{(i)}(y_t|y_{<t}, x) = 0$ for some y_t, we necessarily have that $p^*(y_t) = 0$. In this case, the optimal solution may satisfy neither of the two conditions from Lemma 4.2.

[7] Note that the deduplication process may not be sufficient to eliminate the need for an oracle, as general knowledge is often highly replicated across the training set.

D. Implementation details

D.1. Fine-tuning details

We fine-tuned our models using a setup inspired by the repository *finetuning-harness*, available under the MIT License[8]. The training was performed on A100 GPUs.

The main hyperparameters for our fine-tuning process are listed in Table 10. We fine-tuned our models with Neptune noise

Table 10. Main Hyperparameters for Fine-Tuning

Hyperparameter	**Value**
Sequence Length	2048
Batch Size	1
Learning Rate	5e-5
Gradient Accumulation Steps	1
Optimizer	AdamW (8-bit)
Warmup Steps	50
Neptune Noise	$\alpha = 5.0$

(Jain et al., 2023) set to $\alpha = 5.0$. We did not perform any low-rank adaptation.

For the overfitted models, we trained StarCoder for 50 epochs (both in experiments with the Python instructions and the APPS datasets), LLaMa2 for 50 epochs, Phi-2 for 50 epochs, and GPT-2 XL for 20 epochs.

D.2. Decoding details

We decode with greedy search and in batches of size 50. For the code task, the maximum sequence length is 2048 tokens in the Python instructions dataset and 512 in the APPS, MBPP, and HumanEval datasets, and for the text task, it is 1024 tokens. This configuration is used both for our method and CP-Δ. For APPS, MBPP, and HumanEval, we base our implementation on the *bigcode-evaluation-harness* repository, available under the Apache-2.0 License[9].

D.3. Datasets

We use four code-based and one text-based dataset in our experiments, all downloadable from *HuggingFace*. The first code-based dataset[10] is an instructional dataset for Python, containing two types of tasks: (1) generating a description of a given code, and (2) generating code that solves a given task. For our experiments, we only consider instances of the latter. We removed the docstring from all instances since its content was repeated across samples, compromising our assumption on the separability of copyrighted content (Section 3). The APPS dataset[11] is a benchmark for code generation with 10,000 problems in Python. Each sample consists of a programming problem formulation in English, some ground truth Python solutions, and test cases. We sample random subsets for fine-tuning and evaluation for our experiments. Both MBPP[12] and the HumanEval [13] datasets are standard for assessing code generation, and follow a similar structure of natural language instructions and solutions in Python code. They contain 378 and 164 programming problems, respectively. We use the sanitized version of MBPP, MBPP+, and the instruction-based version of HumanEval, InstructHumanEval.

For the text-based experiments, we use the AutoMathText dataset[14] (Zhang et al., 2024b). This dataset compiles an extensive set of mathematical texts from arXiv, OpenWebMath, RedPajama, Algebraic Stack, etc., with titles generated by the state-of-the-art open-source language model Qwen-72B[15].

[8] GitHub Repository
[9] GitHub Repository
[10] Nan-Do/instructional_code-search-net-python
[11] APPS (Hendrycks et al., 2021)
[12] MBPP (Austin et al., 2021)
[13] InstructHumanEval (Chen et al., 2021)
[14] math-ai/AutoMathText
[15] Visit the GitHub repository for additional details.

D.4. Details on the metrics

D.4.1. COPYRIGHT INFRINGEMENT

Exact Matching (EM) Exact Matching (EM) measures the length of the longest matching substring between the model's output and the ground truth text. This metric is useful for assessing how well the model captures continuous segments of the reference text. The value of EM ranges from 0 to 1, where 1 indicates a perfect match.

Infringement Count ($\mathbf{IC_k}$) Infringement Count (IC_k) captures the number of k-grams (substrings of length k) in the model's output that have an exact match in the ground truth text. This metric assesses the content similarity and potential for copyright infringement based on the number of matching k-grams.

ROUGE-L (ROU) ROUGE (Recall-Oriented Understudy for Gisting Evaluation) measures the overlap of n-grams, word sequences, and word pairs between the generated text and reference text. It focuses on recall, assessing how much of the reference text is captured by the generated text. The value of ROUGE ranges from 0 to 1, where 1 indicates perfect recall. The most common variant, ROUGE-L, is computed based on the longest common subsequence (LCS):

$$\text{ROUGE-L} = \frac{\text{LCS}}{\text{length of reference text}}$$

BLEU (BLE) BLEU (Bilingual Evaluation Understudy) measures the overlap of n-grams between the generated text and reference text, with a penalty for shorter outputs. It is computed using a modified precision score that includes a brevity penalty to discourage overly short translations. The value of BLEU ranges from 0 to 1, where 1 indicates perfect precision. For this study, we use uniform weights for n-grams:

$$\text{BLEU} = \text{BP} \times \exp\left(\sum_{n=1}^{N} \frac{1}{N} \log p_n\right)$$

where BP is the brevity penalty, p_n is the precision for n-grams, and N is the highest order of n-grams considered.

METEOR (MET) METEOR (Metric for Evaluation of Translation with Explicit ORdering) evaluates the alignment between the generated text and reference text by considering synonyms, stemming, and exact matches. Unlike BLEU, which focuses on n-gram precision and typically measures performance at the corpus level, METEOR emphasizes unigram recall and aims to better align with human judgment at the sentence level. The value of METEOR ranges from 0 to 1, where 1 indicates perfect alignment. It combines precision, recall, and a fragmentation penalty to account for the alignment of chunks. It is computed as:

$$\text{METEOR} = F_{mean} \times (1 - P)$$

where F_{mean} is the harmonic mean of precision and recall, and P is the fragmentation penalty.

Jaccard Similarity (JAC) Jaccard Similarity (JAC) measures the intersection over the union of the sets of words in the generated text and reference text. It provides a simple measure of similarity, indicating how many words are shared between the two texts relative to the total number of unique words. The value of Jaccard Similarity ranges from 0 to 1, where 1 indicates identical sets. It is computed as:

$$\text{Jaccard Similarity} = \frac{|A \cap B|}{|A \cup B|}$$

where A and B are the sets of words in the generated text and reference text, respectively.

Cosine Similarity (COS) Cosine Similarity (COS) measures the cosine of the angle between the word vectors of the generated text and reference text. This metric assesses the similarity in the direction of the vectors, providing an indication of how similar the two texts are in terms of their overall content distribution. The value of Cosine Similarity ranges from 0 to 1, where 1 indicates perfect similarity.

Semantic Similarity (SEM) Semantic Similarity (SEM) evaluates the similarity between the generated text and reference text using a semantic model, such as SpaCy or BERT. This metric captures the meaning and context of the texts, providing a measure of how well the model understands and replicates the underlying semantics of the reference text. The value of Semantic Similarity ranges from 0 to 1, where 1 indicates perfect semantic alignment.

Levenshtein Distance (LEV) Levenshtein Distance (LEV) measures the minimum number of single-character edits (insertions, deletions, or substitutions) required to change the generated text into the reference text. A higher Levenshtein distance indicates greater dissimilarity, while a lower distance indicates greater similarity. The value of Levenshtein Distance ranges from 0 to 1, where 0 indicates identical texts. We compute the Levenshtein distance with a sliding window to handle cases where the lengths of the generated and reference texts differ significantly.

D.4.2. UTILITY

Pass@1 (Pass at 1) Pass@1 evaluates the success rate of a model in generating a correct solution on its first attempt. Specifically, it measures the proportion of cases where the model's first output matches the correct solution. The value of Pass@1 ranges from 0 to 1, where 1 indicates that the model always generates a correct solution on the first attempt. It is computed as:

$$\text{Pass@1} = \frac{\text{Number of correct first attempts}}{\text{Total number of attempts}}$$

Perplexity (PPL) Perplexity (PPL) evaluates the quality of a language model. It measures how well a probability distribution or model predicts a sample. Lower perplexity indicates that the model is better at predicting the sample. The value of Perplexity ranges from 1 to infinity, where lower values indicate better performance.