Avoiding Spurious Correlations: Bridging Theory and Practice

Abstract

Distribution shifts in the wild jeopardize the performance of machine learning models as they tend to pick up spurious correlations during training. Recent work [8] has characterized two specific failure modes of out-of-distribution (OOD) generalization, and we extend this theoretical framework by interpreting existing algorithms as solutions to these failure modes. We then evaluate them on different image classification datasets, and in the process surface two issues that are central to existing robustness techniques. For those that rely on group annotations, we show how the group information in standard benchmark datasets is unable to fully capture the spurious correlations present. For those that don't require group annotations, the validation set utilized for model selection still carries assumptions that are not realistic in real-world settings, and we show how this choice of shifts in validation set could impact performance of different OOD algorithms.

1 Introduction

Neural networks are commonly trained and evaluated with the assumption that the training distribution matches the test distribution. However, when this assumption does not hold because of distribution shifts in real-world deployments, machine learning models can perform in unexpected and undesirable ways [4, 12]. Previous work has shown how models can utilize different shortcuts to perform well on the task [3], a notable example of which is the presence of spurious correlations — features that correlate with the labels but are actually not causal, such as image backgrounds [11, 13, 18].

The explanation for why empirical risk minimization (ERM) approaches tend to rely on spurious correlations can be summarized by two lines of work. The first [1, 14, 16] assumes that both invariant and spurious features are only partially predictive of the label, and thus both will be used to maximize accuracy. The other line of work [5, 15, 10] demonstrates how spurious features are simpler to learn than invariant ones and thus are preferred by gradient descent (i.e. simplicity bias), even when both kinds of features are fully predictive of the labels. To provide a concrete framework for understanding OOD failures, [8] uses a series of tasks that are easy to succeed at to pinpoint fundamental mechanisms by which spurious correlations affect gradient-descent-trained linear classifiers: they induce *geometric* and *statistical* skews in the data.

Using this theoretical framework, our work characterizes existing solutions to improving OOD generalization based on the failure mode that they address, and empirically evaluate their effectiveness when they are used alone or in conjunction with another, on several standard OOD image datasets. Through this comparison, we find that there is no single solution that works best for all the datasets we examined. As the algorithms chosen for our investigation rely on the availability of group labels, we also investigate how well the official spurious features from these datasets that are widely used in existing robustness benchmarks actually reflect the spurious correlations present in the data distribution. We find that even when different subgroups are balanced (in terms of number of datapoints) by undersampling, there still exist substantial performance gaps among the groups,

38 suggesting more complicated subgroup structures that cannot be captured by a single spurious feature
39 annotation alone.

40 In addition to the ones we examine, other existing robustness methods [7, 9] that don't even require
41 group labels at training time, are often tuned with a validation set that is representative of the
42 distribution shift found at test time, or is annotated with group information. This prompts us to design
43 a new validation set that closely resembles the degree of spurious correlation found in the training set
44 instead, and explore how this affects the performance gains offered by various methods, especially in
45 comparison with using the official validation set.

46 In summary, our contributions are:

47 • We revisit some of the existing algorithms for OOD generalization that use group labels, and show
48   how they could address either the geometric or statistical skew as proposed in [8].

49 • We evaluate the effectiveness of these algorithms (by themselves and in combination with one an-
50   other), on 3 image classification datasets with varying properties (dataset sizes, degrees of spurious
51   correlations, etc.). We find that no single approach consistently yields the best performance.

52 • We also repeat these evaluations in a more realistic setting that assumes no knowledge of distribu-
53   tion shifts at test time, which is often implied in the official validation sets that come with these
54   widely-used OOD datasets.

55 • We demonstrate that downsampling these standard datasets to balance the representation of different
56   subgroups in training set is not sufficient in capturing the spurious correlations present, as some
57   groups still appear to be intrinsically harder to learn than others.

2 Experimental Setup and Background

2.1 Failure Modes and Solutions

60 For the sake of our discussion, consider a simplified binary classification setting where any datapoint
61 can be written as $(\mathbf{x}_{inv}, x_{sp})$ denoting the invariant feature (potentially high-dimensional) and a
62 spurious feature. The label y of any point is either $+1$ or -1. While the label can be perfectly
63 predicted by looking at x_{inv}, in addition we also have that the spurious feature is partially correlated
64 with the label, i.e., $\Pr_{\mathcal{D}}[x_{sp} \cdot y > 0] > 0.5$, where $\mathcal{D}$ is the data distribution. In other words, in
65 a *majority* of points, the spurious feature is positively aligned with the label and in a *minority* of
66 points, it is negatively aligned. By analyzing gradient descent on linear classifiers and its infinite-
67 time-equivalent max-margin, [8] show that there are two main kinds of failure modes by which the
68 resulting classifiers rely on the spurious feature. We briefly summarize these below.

2.1.1 Statistical skews

70 One mode of failure arises from the slow convergence rate of gradient descent (on the cross-entropy
71 loss), relative to the max-margin classifier. That is, even in datasets where the max-margin classifier
72 succeeds in using only the invariant features, finite-time (stochastic) gradient descent (SGD) still
73 relies on spurious features unless trained for an exponentially long time. This is a purely statistical
74 effect in that, in principle, it can be straightforwardly countered if we oversample the minority
75 datapoints while running GD. This is in contrast to the second type of failure mode which cannot be
76 addressed by such statistical tricks.

2.1.2 Geometric skews

78 Another kind of failure mode is one that can arise in both GD and in max-
79 margin due to certain geometric effects in the dataset. Refer to Figure 1, which
80 is taken from [8], for an illustration of the 2D setting. In particular, it is often
81 the case that the "invariant margin" (i.e., the margin of separation in the purely-
82 invariant feature subspace) of the minority group is much larger than that of
83 the majority group. This arises from a property of the invariant features: when
84 there are more uniquely sampled points, we are likely to see more difficult
85 points that make the data harder to separate. As a result of this imbalance of
86 the majority vs. minority margins, any classifier with a margin-maximizing
87 bias can be shown to make use of the spurious features. Note that a mere

Figure 1: **Geometric failure mode (from [8]).**

88 upsampling of the minority group cannot address this issue since it does not affect the number of
89 unique points and thus the margins of minority and majority groups.

2.1.3 How do different algorithms address these skews?

As already noted above, the idea of upsampling the minority can only address statistical skews. If we were to however *downsample* the *majority* (to equal the size of the minority), we would not only nullify statistical skews, we would also roughly equalize the margins in the majority and minority group and thereby nullify any geometric skews too. An alternative way to address geometric skews is to directly scale down the margins of the minority datapoints (in effect making it equal to those of the majority, so models are encouraged to separate majority and minority groups using only the invariant feature). Formally, let S_{maj} and S_{min} be the majority and minority groups respectively. Then, we seek a classifier that maximizes the following notion of margins:

$$\arg \max_{\mathbf{w}, \|\mathbf{w}\|=1} \min\left(\{c \cdot y(\mathbf{w} \cdot \mathbf{x}) | \mathbf{x} \in S_{min}\}, \{y(\mathbf{w} \cdot \mathbf{x}) | \mathbf{x} \in S_{maj}\}\right), \tag{1}$$

where c is a small multiplicative constant intended to scale down the minority margins. In the case of deep neural networks trained with cross-entropy loss, we multiply the *logits* of minority datapoints with a small constant (to be tuned) before computing the loss to achieve this effect.

Another popular algorithm to address spurious correlations is group DRO. Here the objective is to minimize the worst-case cross-entropy loss of different groups of points. This should eventually converge to the standard max-margin and therefore not address geometric skews. On the other hand, an alternative called group-adjusted DRO proposed in [13] makes the minority group's objective harder by adding a constant to its loss (we include this version in the tables of results). By doing so, we believe this mechanism should help address geometric skews as it makes all the groups equally hard to learn. However, it remains uncertain how groupDRO counters the effect of statistical skews.

2.2 Datasets

We experiment with 3 datasets that have served as popular benchmarks for OOD generalization algorithms [7, 2, 14]. They are chosen for their varying dataset sizes, degrees of spurious correlation (both natural and artificially induced), as well as levels of difficulty for learning the spurious feature:

- Colored MNIST[1]: the task is to classify the digit images into 2 classes (digits < 5 and digits $\geq$ than 5). The label is spuriously correlated with the color of the digit, which could be either "red" or "green". We modify the procedure from [1] to remove the noise introduced to the labels.
- Waterbirds [13]: the task is to classify bird images as either "landbird" or "waterbird". The label is spuriously correlated with the image background which could be either "land" or "water" places.
- CelebA [13]: the task is to classify celebrity pictures as having either "blond" or "black" hair. The label is spuriously correlated with the gender which is either "male" or "female". We modify the original setup in [13] by using only a fraction of the data from the (female, dark hair) group to keep the size of this "minority" group small.

For each dataset, we use the official group annotations that come with the datasets to split the training data into 4 groups, 2 minority and 2 majority. More details of the construction and composition of each dataset can be found in Appendix A.

3 Results

The algorithms of interest have been described and linked to the respective skews in Section 2.1.3. Refer to Appendix B for further details on hyperparameters and model choices. For upsampling (downsampling), we follow the standard practice and oversample (undersample) datapoints from each group to match the size of the biggest (smallest) group in the original dataset. Hyperparameter tuning is done based on the worst-group accuracy of the validation set, given previous work [7] which shows that worst-group test accuracies are significantly lower when average validation accuracy is used for model selection instead of worst-group accuracy.

We report worst-group test accuracy from the best performing model for each method in Table 1, and observe that no method reliably yields the best performance across all the datasets that we studied. Those that target different skews (e.g. margin scaling and upsampling, or groupDRO and upsampling) offers *complementary* performance gains when used in combination on some datasets (e.g. CelebA and ColoredMNIST) but not always (e.g. Waterbirds).

We also analyze how well the group annotations fit with the theoretical framework, by looking at the individual group validation accuracies when models are trained on downsampled datasets, an approach that is expected to get rid of most geometric and statistical skews in the original data. In

Table 1: **Comparison of models trained with different methods, tuned on the official validation set, which mirrors the distribution shift found in test set.** The table is sectioned based on the skew(s) that each approach addresses. The numbers in brackets capture the performance changes compared to the baseline (ERM). We observe that the best-performing approach is not consistent across all datasets, and methods that address complementary skews when combined sometimes yield complementary performance benefits.

Algorithm	ColoredMNIST	Waterbirds	CelebA
ERM	93.1	71.7	53.3
Upsampling	96.1 (+3.0)	86.0 (+14.3)	85.0 (+31.7)
Margin Scaling	95.2 (+2.1)	81.9 (+10.2)	57.7 (+4.4)
GroupDRO	**97.4 (+4.3)**	**90.3 (+18.6)**	87.6 (+34.3)
Downsampling	96.1 (+3.0)	87.6 (+15.9)	**88.9 (+35.6)**
Margin Scaling + Upsampling	96.2 (+3.1)	85.0 (+13.3)	87.8 (+34.5)
GroupDRO + Upsampling	96.5 (+3.4)	87.6 (+15.9)	86.7 (+33.4)

ColoredMNIST, where the spurious correlation is synthetically introduced and controlled, all groups now indeed exhibit similar performance. However, in the case of Waterbirds and CelebA, given the same number of datapoints, certain groups — which are not always the minority — appear to be harder to learn than the rest. This suggests there may be other subgroup structures beyond the official annotations that come with these two widely used OOD benchmarks.

In addition, we note that the existing validation sets from these benchmarks reflect the distribution shift at test time, which should not be expected in real-world settings. This issue is also applicable to methods that don't require group information at train time (e.g. [7, 9]). Thus, we investigate what Table 1 would look like in a more "in-the-wild" setting where we have no knowledge of future distribution shifts, and models are selected based on information related to the training distribution alone. We construct a new validation set with similar degrees of spurious correlation as the training set by subsampling from the original validation set (see Appendix A for the group breakdown), and find that the effectiveness of the robustness methods in consideration are highly sensitive to the choice of distribution shifts in the validation set (Table 2). This observation illustrates the importance of having OOD generalization techniques that do without group annotations completely.

Table 2: **Comparison of models trained with different methods, tuned on a new validation set we constructed, that follows the training group distribution instead.** We consider a more practical setting that assumes nothing about future distribution shifts: the validation set should resemble the training set in terms of group distribution. When hyperparameters are tuned on this new validation set, the relative effectiveness of each method varies substantially from that in Table 1.

Algorithm	ColoredMNIST	Waterbirds	CelebA
ERM	92.1	50.0	53.3
Upsampling	95.1 (+3.0)	83.0 (+33.0)	81.1 (+27.8)
Margin Scaling	94.6 (+2.5)	66.5 (+16.5)	56.7 (+3.4)
GroupDRO	**97.0** (+4.9)	83.5 (+33.5)	88.3 (+35.0)
Downsampling	94.0 (+1.9)	**85.1 (+35.1)**	**88.4 (+35.1)**
Margin Scaling + Upsampling	94.2 (+2.1)	77.3 (+27.3)	65.4 (+12.1)
GroupDRO + Upsampling	95.8 (+3.7)	62.5 (+12.5)	60.6 (+7.3)

4 Conclusion

Our work extends the theoretical framework in [8] and connects different techniques for boosting OOD generalization to the types of skews (i.e. geometric or statistical) induced by spurious features that they address. We look at how these methods perform in practice on 3 image classification datasets with different extents of spurious correlations. We then increase the resemblance to real-world setups further, by tuning models on a new validation set that doesn't assume any knowledge of distribution shifts at test time. In the process, we find that the best approach varies by dataset, and the structure of the validation set plays an important role in the relative effectiveness of different approaches, compared to standard ERM training. This necessitates further study into a more thorough way to evaluate existing OOD methods, even those that don't require group labels at training time. Last but not least, we also demonstrate how performances across subgroups vary substantially even when all the groups are represented equally in the training set. This presents an opportunity for future work to study group automatic structure detection, or explore other possible sources of spurious correlations that may be present in standard OOD datasets beyond the given metadata.

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Appendix

A   Dataset details

A.1   ColoredMNIST

We extract 12000 random images from the official MNIST training set [6] to create a validation set, on which hyperparameters are tuned. Following previous work [1], to construct ColoredMNIST dataset, we divide the MNIST images into 2 classes: $y = 0$ for digits 0-4 and $y = 1$ for digits 5-9, and color all images in the first class red and the second class green. With probability 0.1, we flip the color of each training image. We perform a similar procedure for validation and test sets, but with probability 0.9.

Table 3: **Group breakdown (in terms of number of images) for ColoredMNIST dataset.**

Dataset	Digit < 5, Green	Digit < 5, Red	Digit ≥ 5, Green	Digit ≥ 5, Red
Train	2454	21758	21365	2423
Validation (same as train domain)	70	621	604	69
Validation (same as test domain)	5324	621	604	5451
Test	4545	523	465	4467

A.2   Waterbirds

The dataset is constructed from placing segmented bird images from the Caltech-UCSD Birds-200-2011 dataset [17] on top of backgrounds taken from the Places dataset [19]. Each bird image is broadly classified as either waterbird or landbird, and background images are divided into land and water backgrounds, with waterbirds (landbirds) appearing more frequently on water (land) backgrounds.

Table 4: **Group breakdown (in terms of number of images) for Waterbirds dataset.**

Dataset	Landbird, Land background	Landbird, Water background	Waterbird, Land background	Waterbird, Water background
Train	3498	184	56	1057
Validation (same as train domain)	467	25	7	133
Validation (same as test domain)	467	466	133	133
Test	2255	2255	642	642

A.3   CelebA

In this dataset, the label ("blond" or "dark" hair color) is spuriously correlated with the demographic information ("male" or "female" gender), with blond females and dark-hair males appearing more frequently. We modify the group composition in [13] to make sure the infrequent associations ("dark-hair females" in particular) also have much fewer datapoints in the dataset.

Table 5: **Group breakdown (in terms of number of images) for CelebA dataset.**

Dataset	Blond, Female	Blond, Male	Dark Hair, Female	Dark Hair, Male
Train	22880	1387	4297	66874
Validation (same as train domain)	2874	174	532	8276
Validation (same as test domain)	2874	182	8535	8276
Test	2480	180	9767	7535

B   Training Details

All models are trained with stochastic gradient descent (SGD) with momentum 0.9. Specific details about architecture and training hyperparameters are deferred to the individual subsections. For margin scaling, we tune the scaling factor c for logits of minority examples to be in $[0.01, 0.05, 0.1, 0.25, 0.5, 0.75]$. Following [13], we tune the group adjustment term C in GroupDRO objective to be in $[1, 2, 3, 4, 5]$.

B.1   ColoredMNIST

For the ColoredMNIST task, we use a multi-layer perceptron that consists of 2 hidden layers with 512 neurons in each. All methods are trained with batch size 128, for 50 epochs. We tune learning rate and l_2 regularization strength with the following configurations: $[(1e-2, 1e-3), (1e-2, 1e-2), (1e-2, 1e-1), (1e-3, 1e-3), (1e-3, 1e-2), (1e-3, 1e-1)]$.

B.2   Waterbirds

All methods are trained with ResNet-50 for 300 epochs, using batch size 64. The model is initialized with weights pretrained on ImageNet. We tune over the 3 pairs of learning rate and l_2 regularization strength used by [13]: $[(1e-3, 1e-4), (1e-4, 1e-1), (1e-5, 1)]$.

B.3   CelebA

We also use ResNet-50 pretrained on ImageNet for CelebA models, with batch size 128 and 50 epochs. Similar to Waterbirds, we also use the 3 pairs of learning rate and l_2 regularization strength from previous work [13] to tune: $[(1e-4, 1e-4), (1e-4, 1e-2), (1e-5, 1e-1)]$.

C   Performance Gaps from Training on Downsampled Datasets

Figure 2: **Validation accuracies of subgroups in the downsampled datasets (rows), across different hyperparameter settings (columns) used.** While training with ColoredMNIST downsampled data results in the ideal scenario of having the same performance across different subgroups — suggesting that the skews induced by spurious correlations are completely eliminated — performance gaps between subgroups are still discernible when training on Waterbirds and CelebA downsampled datasets. We hypothesize that this is because the spurious feature (i.e. "color") is synthetically introduced and thus carefully controlled in ColoredMNIST, while the group information that comes with the other 2 datasets (and frequently used by existing OOD benchmarks) don't fully capture all sources of spurious correlations present in the data.